

## EasyBuilder Pro

Ver. 6.09.01

### **Table of Contents**

1.	Easy	Build	er Pro Installation and Startup Guide	1-1
	1.1.	Insta	llation Requirements	1-2
	1.2.	Step	s to Install EasyBuilder Pro	1-3
	1.3.	Soft	ware Update Reminder	1-7
2.	Utili <sup>.</sup>	ty Ma	nager	2-1
	2.1.	Ove	view	2-2
	2.2.	Desi	gn	2-3
	2.3.	Anal	ysis & Testing	2-4
	2.4.	Publ	ish	2-6
	2.4	.1.	Download (PC->HMI)	2-7
	2.4	.2.	Upload (HMI->PC)	2-9
	2.4	.3.	Build Download Data for SD/USB Disk	2-10
	2.4	.4.	Steps to Download Project to HMI via USB Disk or SD Card	2-10
	2.5.	Maiı	ntenance	2-11
	2.6.	Data	Conversion	2-13
3.	Crea	te an	EasyBuilder Pro Project	3-1
	3.1.	Ove	view	3-2
	3.2.	Crea	te a New Project File	3-2
	3.3.	Save	and Compile the Project File	3-4
	3.4.	Com	pile and Quick Compile	3-5
	3.5.	Run	On-Line or Off-Line Simulation	3-6
	3.6.	cMT	Viewer	3-6
	3.7.	Dow	nload the Project File to HMI	3-7
	3.7	.1.	Configure in EasyBuilder Pro	3-7
	3.7	.2.	Use HMI Name	3-10
	3.7	.3.	Use USB cable	3-12
	3.7	.4.	Use USB Drive or SD Card	3-12
	3.8.	Uplo	ad the Project File from HMI	3-14
4.	. Hardware Settings			4-1
	4.1.	Ove	view	4-2
	4.2.	I/O I	Ports	4-2
	4.3.	LED	Indicators	4-2
	4.4.	Syste	em Reset	4-3
	4.5.	Syste	em Toolbar	4-4
	4.5	.1.	System Setting	4-4
	4.5	.2.	System Information	4-12
5.	Syste	em Pa	arameter Settings	5-1



	5.1.	Ove	rview	5-2
	5.2.	Dev	ice	5-2
	5.2	2.1.	How to Control a Local PLC	5-2
	5.2	2.2.	How to Control a Remote Device	5-7
	5.2	2.3.	How to Control a Remote HMI	5-9
	5.3.	Mo	del	5-11
	5.4.	Ger	eral	5-15
	5.5.	Syst	em Setting	5-22
	5.6.	Ren	note	5-25
	5.7.	Sec	urity	5-26
	5.7	'.1.	General Mode	5-27
	5.7	'.2.	Enhanced Security Mode	5-27
	5.8.	Exte	ended Memory	5-29
	5.9.	Prin	ter / Backup Server	5-33
	5.10.	Tim	e Sync./DST	5-34
	5.11.	e-N	ail	5-36
	5.12.	Cell	ular Data Network	5-38
	5.13.	FTP		5-40
6.	. Window Operations		Operations	6-1
	6.1. Overview.		rview	6-2
	6.2.	Wir	dow Types	6-2
	6.2.1.		Base Window	6-2
	6.2	2.2.	Fast Selection Window	6-2
	6.2	2.3.	Common Window	6-3
	6.2	2.4.	System Message Window	6-3
	6.3.	Cre	ate, Set, and Delete a Window	6-4
	6.3	8.1.	Creating and Setting a Window	6-5
	6.3.2.		Open, Close, and Delete a Window	6-7
	6.4.	Wir	dow Transparency	6-8
	6.5.	Edit	ing Tips	6-10
	6.5	5.1.	Non-display Area, Select Tool, and Hand Tool	6-10
	6.5.2.		Ruler	6-11
	6.5.3.		Quick Copy	6-13
7.	Evei	nt Lo	g	7-1
	7.1.		rview	
	7.2.	Eve	nt Log Management	7-2
	7.2	2.1.	eMT, iE, XE, mTV, iP Series	7-3
	7.2	2.2.	cMT, cMT X Series	7-4



	7.2	.3.	Excel Editing	7-8
	7.2	.4.	Quick View of Errors	7-9
	7.3.	Crea	iting a New Event Log	7-9
8.	Data	Sam	pling	8-1
	8.1.	Ove	rview	8-2
	8.2. Data		a Sampling Management	8-2
	8.3.	Crea	iting a New Data Sampling	8-2
	8.3	.1.	Demonstration of Auto. stop	8-11
	8.3	.2.	Customized File Handling	8-12
	8.4.	Synd	chronizing cMT Viewer data and Saving to External Device or Database	8-15
	8.5.	Che	cking History Data of a Specific Date / File on cMT Viewer	8-15
9.	Obje	ct G	eneral Properties	9-1
	9.1.	Ove	rview	9-2
	9.2.	Sele	cting PLC and Setting Read/Write Address	9-2
	9.3.	Usin	g Shape Library and Picture Library	9-3
	9.3	.1.	Picture	9-3
	9.3	.2.	Shape	9-4
	9.3	.3.	Shape manager	9-6
	9.4. Sett		ing Label Text	9-7
	9.5. Adj		ısting Profile Size	9-9
	9.6.	Ove	rlapping Objects (cMT / cMT X Series)	9-10
	9.6.1.		Enable Touch Area	9-10
	9.6	.2.	Find Overlapping Objects	9-11
	9.6.3.		Convert to Combo Button	9-11
10	). User	Pass	sword and Object Security	10-1
	10.1.	Ove	rview	10-2
	10.2.	Use	r Password and Operable Object Classes	10-2
	10.	2.1.	General Mode	10-2
	10.	2.2.	Enhanced Security Mode	10-3
	10.	2.3.	LDAP Mode	10-4
	10.	2.4.	Remote HMI Mode	10-5
	10.3. Enh		anced Security Mode and Control Address	10-6
	10.	3.1.	Control Address Settings	10-6
	10.	3.2.	Commands	10-7
	10.	3.3.	Command Execution Results	10-9
	10.4.	Enha	anced Security Mode Usage	10-10
	10.	4.1.	Importing User Accounts	10-10
	10.	4.2.	Login with USB Security Key	10-11



10.4.	3. Login / Logout Automatically with USB Security Key	10-13
10.4.	4. Enhanced Security Mode with Option List Object	10-14
10.4.	5. LDAP Mode	10-14
10.4.	6. Remote HMI Mode	10-21
10.4.	7. Login / Logout with Plugins	10-22
10.5. O	bject Security Settings	10-24
10.5.	1. Security Tab	10-24
10.5.	2. Enable/Disable	10-25
10.5.	3. User Restriction	10-27
10.6. E	xample of Object Security Settings	10-29
10.7. P	rotecting Password Settings from Unauthorized Editing	10-32
10.8. B	ulk Changing of Security Settings of Multiple Objects	10-33
11. Index I	Register	11-1
11.1. O	verview	11-2
11.2. E	xamples of Index Register	11-3
11.3. E	xamples of Using Tag-Based PLC and Index Registers	11-5
12. Keybo	ard Design and Usage	12-1
12.1. O	verview	12-2
12.2. S	teps to Design a Popup Keyboard	12-2
12.3. S	teps to Design a Keyboard with Direct Window	12-5
12.4. S	teps to Design a Fixed Keyboard on Screen	12-6
12.5. S	teps to Design a Unicode Keyboard	12-7
13. Object	S	13-1
13.1. B	it Lamp	13-3
13.1.	1. Overview	13-3
13.1.	2. Configuration	13-3
13.2. W	/ord Lamp	13-5
13.2.	1. Overview	13-5
13.2.	2. Configuration	13-5
13.3. S	et Bit	13-10
13.3.	1. Overview	13-10
13.3.	2. Configuration	13-10
13.4. S	et Word	13-13
13.4.	1. Overview	13-13
13.4.	2. Configuration	13-13
13.5. F	unction Key	13-23
13.5.	1. Overview	13-23
13.5.	2. Configuration	13-23



13.6. Toggle Switch	13-30
13.6.1. Overview	13-30
13.6.2. Configuration	13-30
13.7. Multi-State Switch	13-33
13.7.1. Overview	13-33
13.7.2. Configuration	13-33
13.8. Slider	13-37
13.8.1. Overview	13-37
13.8.2. Configuration	13-37
13.8.3. Combo Setting	13-40
13.9. Numeric	13-44
13.9.1. Overview	13-44
13.9.2. Configuration	13-44
13.10. ASCII	13-63
13.10.1. Overview	13-63
13.10.2. Configuration	13-63
13.11. Indirect Window	13-67
13.11.1. Overview	13-67
13.11.2. Configuration	13-67
13.12. Direct Window	13-75
13.12.1. Overview	13-75
13.12.2. Configuration	13-75
13.13. Moving / Rotating Shape	13-81
13.13.1. Overview	13-81
13.13.2. Configuration	13-81
13.14. Animation	13-87
13.14.1. Overview	13-87
13.14.2. Configuration	
13.15. Bar Graph	13-91
13.15.1. Overview	
13.15.2. Configuration	13-91
13.15.3. Combo Setting	13-97
13.16. Meter Display	
13.16.1. Overview	
13.16.2. Configuration	
13.17. Trend Display	
13.17.1. Overview	
13 17 2 Configuration	13-108



-	13.18. History Data Display	13-131
	13.18.1. Overview	13-131
	13.18.2. Configuration	13-131
-	13.19. Data Block Display	13-140
	13.19.1. Overview	13-140
	13.19.2. Configuration	13-140
-	13.20. XY Plot	13-149
	13.20.1. Overview	13-149
	13.20.2. Configuration	13-149
-	13.21. Alarm Bar and Alarm Display	13-156
	13.21.1. Overview	13-156
	13.21.2. Configuration	13-156
-	13.22. Event Display	13-165
	13.22.1. Overview	13-165
	13.22.2. Configuration	13-165
-	13.23. Data Transfer	13-179
	13.23.1. Data Transfer (Per-page)	13-179
	13.23.2. Data Transfer (Global): Time-based	13-182
	13.23.3. Data Transfer (Global): Bit Trigger	13-185
-	13.24. Backup	13-187
	13.24.1. Overview	13-187
	13.24.2. Configuration	13-187
-	13.25. Media Player	13-195
	13.25.1. Overview	13-195
	13.25.2. Configuration	13-195
-	13.26. BACnet Schedule	13-201
	13.26.1. Overview	13-201
	13.26.2. Configuration	13-201
-	13.27. PLC Control	13-205
	13.27.1. Overview	13-205
	13.27.2. Configuration	13-205
-	13.28. Scheduler	13-212
	13.28.1. Overview	13-212
	13.28.2. Configuration	13-212
•	13.29. Option List	
	13.29.1. Overview	
	13.29.2. Configuration	
	13 30 Timer	13-230



	13.30.1. Overview	13-230
	13.30.2. Configuration	13-230
1	3.31. Video In	13-235
	13.31.1. Overview	13-235
	13.31.2. Configuration	13-235
1	3.32. System Message	13-242
	13.32.1. Overview	13-242
	13.32.2. Configuration	13-242
1	3.33. Recipe View	13-244
	13.33.1. Overview	13-244
	13.33.2. Configuration	13-244
1	3.34. Flow Block	13-252
	13.34.1. Overview	13-252
	13.34.2. Configuration	13-252
1	3.35. Operation Log	13-257
	13.35.1. Operation Log Settings	13-257
	13.35.2. Operation Log View	13-262
	13.35.3. Operation Log Printing	13-265
1	3.36. Combo Button	13-271
	13.36.1. Overview	13-271
	13.36.2. Configuration	13-271
1	3.37. Circular Trend Display	13-279
	13.37.1. Overview	13-279
	13.37.2. Configuration	13-279
1	3.38. Picture View	13-289
	13.38.1. Overview	13-289
	13.38.2. Configuration	13-289
1	3.39. File Browser	13-292
	13.39.1. Overview	13-292
	13.39.2. Configuration	13-292
1	3.40. Import/Export	13-296
	13.40.1. Overview	13-296
	13.40.2. Configuration	13-296
1	3.41. Pie Chart	13-301
	13.41.1. Overview	
	13.41.2. Configuration	13-301
	13.41.3. Combo Setting	
1	2.42 Parcodo	12 206



13.42.1. 2D Barcode Display	13-306
13.42.2. Push Notification Barcode Display	13-307
13.42.3. Barcode Scanner (Android Camera)	13-310
13.43. String Table	13-316
13.43.1. Overview	13-316
13.43.2. Configuration	13-316
13.44. Database	13-318
13.44.1. Database Server	13-318
13.44.2. SQL Query	13-326
13.44.3. SQL Query Result Viewer	13-334
13.45. Dynamic Scale	13-336
13.45.1. Overview	13-336
13.45.2. Configuration	13-336
13.46. Dynamic Drawing	13-339
13.46.1. Overview	13-339
13.46.2. Configuration	13-339
13.47. PDF Reader	13-345
13.47.1. Overview	13-345
13.47.2. Configuration	13-345
13.48. Table	13-347
13.48.1. Overview	13-347
13.48.2. Configuration	13-347
13.49. VNC Viewer	13-349
13.49.1. Overview	13-349
13.49.2. Configuration	13-349
13.50. Contacts Editor	13-354
13.50.1. Overview	13-354
13.50.2. Configuration	13-354
13.51. Event Bar Chart	13-357
13.51.1. Overview	13-357
13.51.2. Configuration	13-357
13.52. Action Trigger	13-363
13.52.1. Overview	
13.52.2. Configuration	13-363
13.53. Calendar	
13.53.1. Overview	
13.53.2. Configuration	
13.54. Touch Gesture	



13.54.1. Overview	13-372
13.54.2. Configuration	13-372
13.55. PLC Web Browser	13-374
13.55.1. Overview	13-374
13.55.2. Configuration	13-374
13.55.3. Notes on PLC Web Browser	13-376
13.56. Condition	13-378
13.56.1. Overview	13-378
13.56.2. Configuration	13-378
13.57. FTP Server	13-382
13.57.1. Overview	13-382
13.57.2. Configuration	13-382
13.58. Date/Time	13-385
13.58.1. Overview	13-385
13.58.2. Configuration	13-385
13.59. Template	13-387
13.59.1. Template Window	13-387
13.59.2. Template	13-388
14. Shape Library and Picture Library	14-1
14.1. Overview	14-2
14.2. Building Shape Library	14-2
14.2.1. Shape manager	14-2
14.2.2. Steps to Build Shape Library	14-4
14.3. Building Picture Library	14-9
14.3.1. Picture manager	14-9
14.3.2. Steps to Build Picture Library	14-11
14.3.3. Steps to Import Picture by Pasting	14-13
14.4. Immediate Modification and Preview	14-15
14.4.1. Replacing a Picture	14-16
14.4.2. Replacing a Color	14-16
14.4.3. Extended Features	14-18
14.4.4. Docking a Window	14-19
15. Label Tag Library and Multi-Language	15-1
15.1. Overview	15-2
15.2. Label Tag Library Manager	15-2
15.3. Steps to create Label Tag Library	15-3
15.4. Using Label Tag Library	15-4
15.5. Selecting Language & Font	15-5



15	.5.1.	Language	15-5
15	.5.2.	Non-ASCII Fonts	15-6
15	.5.3.	Font Management	15-8
15	.5.4.	Font Mapping	15-8
15	.5.5.	Complete font file download	15-9
15.6.	Sett	ings of Multi-Language	15-10
16. Add	ress <sup>-</sup>	Tag Library	16-1
16.1.	Ove	rview	16-2
16.2.	Buil	ding Address Tag Library	16-2
16.3.	Usir	ng Address Tag Library	16-5
17. Trar	nsferr	ing Recipe Data	17-1
17.1.	Ove	rview	17-2
17.2.	Step	os to Update Recipe Data with Ethernet or USB Cable	17-2
17.3.	Step	os to Update Recipe Data with SD Card or USB Disk	17-3
17.4.	Trar	nsferring Recipe Data	17-4
17.5.	Savi	ng Recipe Data Automatically	17-5
18. Mad	cro Re	eference	18-1
18.1.	Ove	rview	18-2
18.2.	Inst	ructions to use the Macro Editor	18-2
18.3.	Con	figuration	18-7
18.4.	Synt	tax	18-8
18	.4.1.	Constants and Variables	18-8
18	.4.2.	Operators	18-11
18.5.	Stat	ement	18-14
18	.5.1.	Definition Statement	18-14
18	.5.2.	Assignment Statement	18-14
18	.5.3.	Logical Statements	18-14
18	.5.4.	Selective Statements	18-16
18	.5.5.	Iterative Statements	18-17
18.6.	Fun	ction Blocks	18-19
18.7.	Buil	t-In Function Block	18-22
18	.7.1.	Table of Functions	18-22
18	.7.2.	Device	18-26
18	.7.3.	Free Protocol	18-36
18	.7.4.	Process Control	18-41
18	.7.5.	Data Operation	18-42
18	.7.6.	Data Type Conversion	18-47
18	.7.7.	String Operation	18-57



18.	3.7.8. Mathematics	18-80
18.	3.7.9. Statistics	18-86
18.	3.7.10. Recipe Database	18-88
18.	3.7.11. Data/Event Log	18-90
18	3.7.12. Checksum	18-94
18.	3.7.13. Miscellaneous	18-97
18.8.	How to Create and Execute a Macro	18-99
18.	3.8.1. How to Create a Macro	18-99
18.	3.8.2. Execute a Macro	18-104
18.9.	User Defined Macro Function	18-104
18.	3.9.1. Import Function Library File	18-105
18.	3.9.2. How to Use Macro Function Library	18-106
18.	3.9.3. Function Library Management Interface	18-108
18.10.	. Some Notes about Using the Macro	18-117
18.11.	. Use the Free Protocol to Control a Device	18-117
18.12.	. Compiler Error Message	18-122
18.13.	. Sample Macro Code	18-128
18.14.	. Macro TRACE Function	18-133
18.15.	. Example of String Operation Functions	18-138
18.16.	. Macro Password Protection	18-145
18.17.	. Reading / Writing CAN bus Address Using Variable	18-147
19. Con	nfigure HMI as a MODBUS Server	19-1
19.1.	Overview	19-2
19.2.	Steps to Create a MODBUS Server	19-2
19.3.	Steps to Access a MODBUS Server	19-4
19.4.	Changing MODBUS Server Station Number Online	19-7
19.5.	MODBUS Address Type	19-7
20. Hov	w to Connect a Barcode Scanner	20-1
20.1.	Overview	20-2
20.2.	Steps to Connect a Barcode Scanner	20-2
20.3.	CDC/POS Mode	20-6
21. Ethe	ernet Communication and Multi-HMI Connection	21-1
21.1.	Overview	21-2
21.2.	HMI to HMI Communication	21-2
21.3.	PC to HMI Communication	21-3
21.4.	Operating the PLC Connected with Other HMI	21-4
21	4.1. Settings of eMT / iE / XE / mTV / iP Series	21-4
21	4.2. Settings of cMT / cMT X Series models	21-5



22	. Syst	em R	egisters	22-1
	22.1.	Ovei	rview	22-3
	22.2.	The	Address Ranges of Local HMI	22-4
	22	.2.1.	Bits	22-4
	22	.2.2.	Words	22-4
	22.3.	Syste	em Registers	22-5
	22	.3.1.	HMI Time	22-5
	22	.3.2.	HMI Operation	22-7
	22	.3.3.	Touch Position	22-8
	22	.3.4.	Local HMI Network Information	22-9
	22	.3.5.	Project File Information	22-11
	22	.3.6.	Storage Space Management	22-12
	22	.3.7.	Recipe and Extended Memory	22-13
	22	.3.8.	Data Sampling	22-16
	22	.3.9.	Event Log	22-18
	22	.3.10.	Station Number Variables	22-21
	22	.3.11.	Index Registers	22-22
	22	.3.12.	MODBUS Server Communication	22-24
	22	.3.13.	Communication Parameter Settings	22-25
	22	.3.14.	Communication Status and Control with Device (COM)	22-29
	22	.3.15.	Communication Status and Control with Device (Ethernet)	22-31
	22	.3.16.	Communication Status and Control with Device (USB)	22-41
	22	.3.17.	Communication Status and Control with Device (CAN Bus)	22-42
	22	.3.18.	Communication Status and Control with Remote HMI	22-43
	22	.3.19.	Communication Status and Control with Remote Device	22-58
	22	.3.20.	Local/Remote Operation Restrictions	22-60
	22	.3.21.	Communication Error Codes	22-61
	22	.3.22.	Driver ID	22-63
	22	.3.23.	DLT645 Controller	22-63
	22	.3.24.	[Device No Response] Window Control	22-63
	22	.3.25.	[Fast Selection] Window Control	22-64
	22	.3.26.	EasyAccess	22-64
	22	.3.27.	EasyAccess 2.0	22-64
	22	.3.28.	Remote Print/Backup Server	22-65
	22	.3.29.	Pass-Through Settings	22-66
	22	.3.30.	VNC Control	22-68
	22	.3.31.	Project Key and HMI Key	22-68
	22	.3.32.	USB Security Key	22-69



22	.3.33. User Name and Password	22-69
22	.3.34. Macro	22-71
22	.3.35. Input Object Function	22-73
22	.3.36. Time Sync./Daylight Saving Time	22-73
22	.3.37. Cellular Data Network	22-75
22	.3.38. WiFi Setting	22-76
22	.3.39. OPC UA Server	22-78
22	.3.40. e-Mail	22-79
22	.3.41. cMT Viewer and Diagnoser	22-81
22	.3.42. CODESYS Information	22-83
22	.3.43. Miscellaneous	22-84
23. HM	l Supported Printers	23-1
23.1.	The Supported Printer Types	23-2
23.2.	Steps to Add a New Printer and Start Printing	23-5
23.3.	Installing Network Printer on cMT / cMT X HMI	23-7
23.4.	Installing PPD File on cMT / cMT X HMI	23-10
23.5.	CUPS Printing Support	23-12
24. Rec	ipe Editor	24-1
24.1.	Overview	24-2
24.2.	Recipe / Extended Memory Editor Setting	24-2
24.3.	Recipe Database Settings	24-4
24	.3.1. Definition	24-4
24	.3.2. Transfer	24-6
24	.3.3. Data	24-7
24	.3.4. System Registers	24-9
25. Easy	yConverter	25-1
25.1.	Overview	25-2
25.2.	Converting Data Log File to Excel File	25-2
25.3.	Converting Event Log File to Excel File	25-4
25.4.	Converting Operation Log File to Excel File	25-7
25.5.	Converting Multiple Files	25-8
25.6.	Scaling Function	25-9
25.7.	Batch File	25-10
25.8.	Examination of Historical Data Integrity	25-14
26. Easy	yPrinter	
26.1.	Overview	26-2
26.2.	Using EasyPrinter as a Printer Server	26-3
26	.2.1. Setup Procedure in EasyPrinter	26-3



26.2.2.	Setup Procedure in EasyBuilder Pro	26-4
26.3. Usir	ng EasyPrinter as a Backup Sever	26-6
26.3.1.	Setup Procedure in EasyPrinter	26-6
26.3.2.	Setup Procedure in EasyBuilder Pro	26-7
26.4. Easy	Printer Operation Guide	26-10
26.4.1.	EasyPrinter Managing Window	26-10
26.4.2.	Operation Guide	26-11
26.5. Con	vert Batch File	26-15
26.5.1.	The Default Value of Convert Batch File	26-16
26.5.2.	Specialized Criteria	26-17
26.5.3.	The Format of a Convert Batch File	26-17
26.5.4.	The Order of Examining Criterion	26-18
27. Simulation	on in EasySimulator / cMT Viewer	27-1
27.1. Easy	Simulator	27-2
27.1.1.	Overview	27-2
27.1.2.	Steps to setup EasySimulator	27-2
27.2. cMT	Viewer	27-3
27.2.1.	Overview	27-3
27.2.2.	Steps to setup cMT Viewer	27-3
28. EasySyste	emSetting	28-1
28.1. Easy	SystemSetting	28-2
28.2. Con	figuring EasySystemSetting	28-5
29. Pass-thro	ough	29-1
29.1. Ove	rview	29-2
29.2. Seri	al Pass Through Ethernet Mode	29-2
29.2.1.	Steps to Install Virtual Serial Port Driver	29-2
29.2.2.	Steps to Change the Virtual Serial Port Number	29-3
29.2.3.	Steps to Uninstall the Virtual Serial Port	29-3
29.2.4.	Steps to Update Virtual Serial Port Driver	29-4
29.2.5.	Settings of Ethernet mode	29-5
29.3. Seri	al Pass-Through COM Port Mode	29-7
29.3.1.	Settings of COM Port Mode	29-7
29.3.2.	Using Utility Manager	29-7
29.3.3.	Using System Registers	29-9
	s-through Control	
	JENS S7-200 PPI and S7-300 MPI Pass-through Settings	
	EasyBuilder Pro Settings	
	S7-200 PPI Connection	



29.5.3. S7-300 MPI Connection	29-11
29.5.4. Registers of SIEMENS Pass-through	29-14
29.6. Ethernet Pass-Through	29-15
30. Project Protection	30-1
30.1. Overview	30-2
30.2. EXOB/CXOB Password	30-2
30.3. Decompilation is Prohibited	30-3
30.4. Disable HMI Upload Function	30-3
30.5. Project Key	30-3
30.6. MTP File Password	30-4
31. cMT Diagnoser	31-1
31.1. Overview	31-2
31.2. How to Start Diagnoser	31-2
31.3. cMT Diagnoser User Interface	31-4
31.3.1. Object Settings	31-4
31.3.2. Device Settings	31-7
31.3.3. Packet Settings	31-7
31.3.4. Macro Settings	31-9
31.3.5. MQTT Settings	31-16
31.3.6. OPC UA Settings	31-18
31.3.7. JS Settings	31-19
31.4. Additional Notes	31-19
32. FTP Server Application	32-1
32.1. Overview	32-2
32.2. Steps to Log in FTP Server	32-2
32.3. Backup History Data and Update Recipe Data	32-3
33. EasyDiagnoser	33-1
33.1. Overview	33-2
33.2. Configuration	33-2
33.3. EasyDiagnoser Settings	33-3
33.3.1. Main Menu	33-3
33.3.2. Activity Area	33-4
33.3.3. Polling Packages	33-6
33.3.4. Devices	33-8
33.3.5. Output (Macro debug)	33-8
33.4. Error Code	33-9
33.5. Window Adjustment	33-10
34 Control Taken (cMT / cMT X)	34-1



	34.1.	Ove	rview	34-2
	34.2.	Conf	figuration	34-2
	34.3.	Dem	nonstration	34-4
35	. Easy	Wato	:h	35-1
	35.1.	Ove	rview	35-2
	35.2.	Conf	figuration	35-2
	35.	2.1.	Basic Functions	35-2
	35.	2.2.	Quick Selection Tools	35-3
	35.3.	Mor	nitor Settings	35-4
	35.	3.1.	Adding a Monitor	35-4
	35.	3.2.	Monitor Settings	35-4
	35.	3.3.	Steps to Add a New Monitor	35-5
	35.4.	Mac	ro Settings	35-9
	35.	4.1.	Adding a Macro	35-9
	35.	4.2.	Macro Settings	35-9
	35.	4.3.	Steps to Add a New Macro	35-9
	35.5.	НМІ	Manager	35-10
	35	5.1.	Opening HMI Setting	35-10
	35	5.2.	HMI Manager	35-11
	35.6.	Obje	ect List	35-12
	35.	6.1.	Object List Columns	35-12
	35.	6.2.	Editing Object List	35-13
36	. Adm	inisti	rator Tools	36-1
	36.1.	Ove	rview	36-2
	36.2.	User	Accounts	36-2
	36.	2.1.	User Accounts Settings	36-2
	36.	2.2.	Steps to Set User Accounts	36-4
	36.	2.3.	Steps to Import Accounts Using EasyBuilder Pro	36-5
	36.3.	USB	Security Key	36-6
	36.	3.1.	USB Security Key Settings	36-6
	36.	3.2.	Steps to Set USB Security Key	36-7
	36.	3.3.	Steps to Set USB Security Key Using EasyBuilder Pro	36-8
	36.4.	e-M	ail SMTP Server Settings	36-9
	36.	4.1.	Steps to set e-Mail SMTP Server Settings	36-9
	36.5.	e-M	ail Contacts	36-10
	36.	5.1.	e-Mail Contacts Settings	36-10
	36.	5.2.	Steps to set e-Mail Contacts	36-11
	36.	5.3.	Steps to Import e-Mail Settings and Contacts Using EasyBuilder Pro	36-13



37. MODBUS Gateway	37-1
37.1. Overview	
37.2. Steps to Create an Address Mapping Table	
37.3. Notes about Configuring Address Mapping	
38. EasyDownload	
38.1. Overview	
38.2. Configuration	38-2
39. Data Security	
39.1. Overview	39-2
39.2. Configuration	39-2
39.2.1. Word address settings	39-3
39.2.2. Bit address settings	39-5
40. Web Streaming	40-1
40.1. Overview	40-2
40.2. Configuration	40-2
40.3. Operation	40-2
40.4. Applicable Models	40-3
41. Energy	41-1
41.1. Energy Demand Setting	41-2
41.1.1. Overview	41-2
41.1.2. Configuration	41-2
41.2. Energy Demand Display	41-6
41.2.1. Overview	41-6
41.2.2. Configuration	41-6
42. IIoT	42-1
42.1. MQTT	42-2
42.1.1. Overview	42-2
42.1.2. Configuration	42-2
42.2. OPC UA Server	42-30
42.2.1. Overview	42-30
42.2.2. Configuration	42-30
42.2.3. Device Statistics	42-42
42.2.4. Limitation	42-43
43. JS Object and JS Library	43-1
43.1. Overview	43-2
43.1.1. Usage Suggestions	43-2
43.1.2. Hardware and Software Requirements	43-2
43.1.3. Warning	43-2



#### EasyBuilder Pro User Manual

43.	1.4.	JS Object SDK	43-2
43.2.	JS Ob	pject	43-3
43.3.	JS Re	source	43-6
43.4.	Dem	onstrations	43-8
43.	4.1.	Mimic a [Toggle Switch] object	43-8
43.	4.2.	Examples of JS Resource Usage	43-17
43.5.	Limit	ations	43-21
43.6.	How	a JS object operates behind the scenes	43-21
Appendix	A.	Comparison of HMI Software Features	A-1
Appendix	В.	cMT Viewer Limitations	B-1
Appendix	C.	PC Simulation Limitations	C-1
Appendix	D.	Notes on the Use of 64-bit Data Type	D-1

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# 1. EasyBuilder Pro Installation and Startup Guide

This chapter explains how to install EasyBuilder Pro.

1.1.	Installation Requirements	1-2
1.2.	Steps to Install EasyBuilder Pro	1-3
13	Software Undate Reminder	1-7



### 1.1. Installation Requirements

#### Software:

Visit Weintek Labs, Inc.'s website at <a href="http://www.weintek.com">http://www.weintek.com</a> and download the installation package which include the following languages: Simplified Chinese, Traditional Chinese, English, Japanese, German, Italian, Korean, Spanish, Russian, French, Polish, and Turkish. The latest updates can be downloaded too.

### **Operating System:**

Windows® 7 SP1 (32bit / 64bit)

Windows® 8 (32bit / 64bit)

Windows® 8.1 (32bit / 64bit)

Windows® 10 (32bit / 64bit)

Windows® 11 (32bit / 64bit)

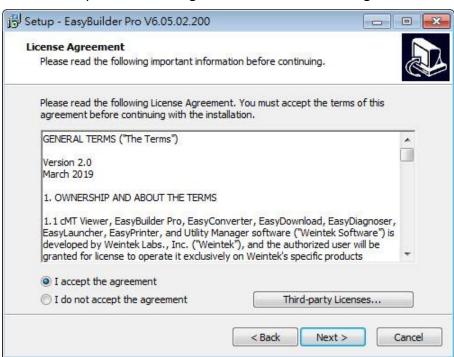


### 1.2. Steps to Install EasyBuilder Pro

1. Click [Install] and select the language for the installation process, and then click [Next].

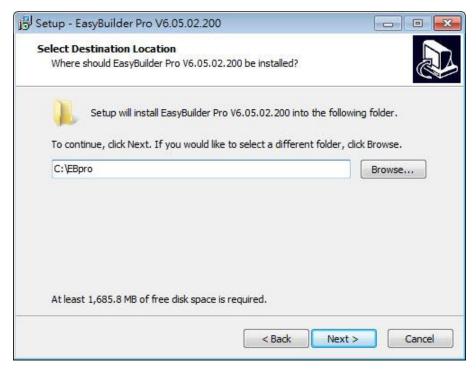


- 2. If there is a previous version of EasyBuilder Pro on the PC, please remove it before installation.
- Please read and accept the License Agreement before continuing.

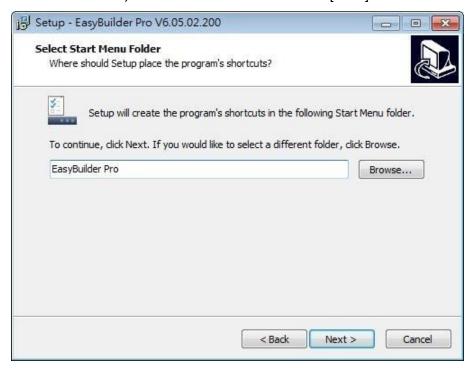


Select a folder for EasyBuilder Pro installation, or use the default folder. Click [Next].





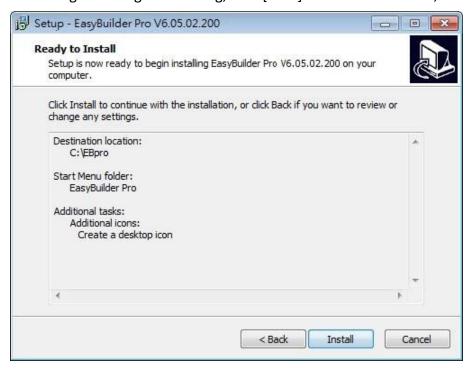
Select a start menu folder, or use the default folder. Click [Next].



6. Select additional tasks, for example: [Create a desktop icon]. Click [Next].

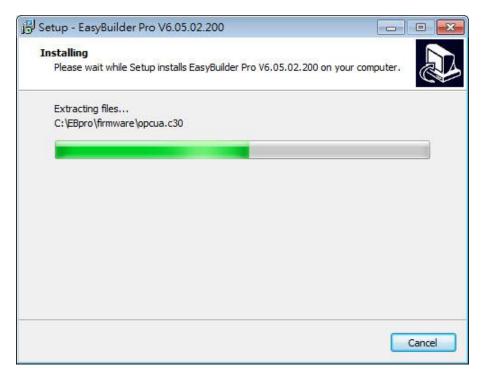


Confirm all setting. To change the setting, click [Back]. To start installation, click [Install].



8. Installation in progress.





Click [Finish] to complete the installation.



10. The EasyBuilder shortcut can be found in [Start] » [All Programs] » [EasyBuilder Pro].

The description of each item in EasyBuilder Pro menu:

Installed file	Description
Administrator Tools	Saves User Accounts, USB Security Key, e-Mail SMTP
	Server Setting, e-Mail Contacts to an external device
	(USB drive or SD card) so that the data become



	portable and can be imported to HMI.
cMT Viewer	Supports access to cMT / cMT X Series HMI via
	network, for operating cMT / cMT X Series HMI on
	PC.
Easy Access	Supports access to remote HMI by connecting
	EasyAccess server over Internet.
EasyBuilder Pro	EasyBuilder Pro project editor.
EasyConverter	Conversion tool for Data Sampling and Event Log.
EasyDiagnoser	Monitoring and debugging tool operated on HMI.
EasyPrinter	Allows exporting data to a remote server on PC via
	Ethernet, realizing remote printing / backup.
EasySimulator	Executes simulation.
EasySystemSetting	Allows updating hardware system settings by using
	SD card or USB drive.
EasyWatch	An easy to use debugging and remote monitoring
	tool running on PC that allows monitoring or setting
	HMI and PLC addresses and executing macro.
Recipe Editor	Tool for setting the format of Recipe data. Users can
	open Recipe data or the data in the External
	Memory.
Release Note	Software release notes.
UtilityManagerEx	EasyBuilder Pro management tool.

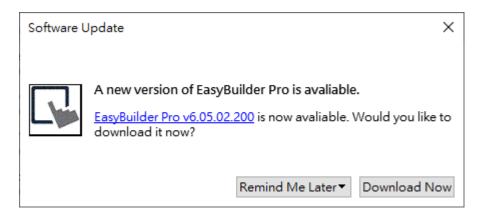


Certain HMI supports downloading/uploading projects via USB cable. After installing EasyBuilder Pro, the USB driver will be automatically installed. A message saying "Windows can't verify the publisher of this driver" may show, please continue anyway. After installing the USB driver, open [Computer Management] » [Device Manager] to check if installation succeeded.

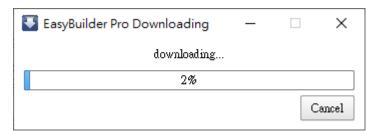
### 1.3. Software Update Reminder

After launching EasyBuilder Pro, the system will check whether the latest version has been installed, and show a reminder dialog if there is a newer version.





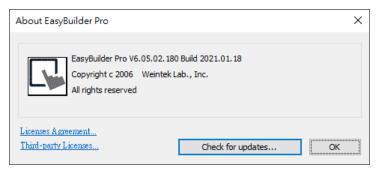
After clicking [Download Now], the latest version of EasyBuilder Pro will be downloaded to a temporary folder, and a progress bar is shown as below. After download, please follow the steps explained in the previous section to install EasyBuilder Pro.





In [File] » [Preferences] » [Misc] an option can be selected to receive a notification when a new version of EasyBuilder Pro is available.

Users can open File » About in EasyBuilder Pro to see current version and check for updates.





### 2. Utility Manager

This chapter explains how to use Utility Manager.

2.1.	Overview	2-2
2.2.	Design	<b>2</b> -3
2.3.	Analysis & Testing	2-4
2.4.	Publish	2-6
2.5.	Maintenance	2-11
2.6	Data Conversion	2-13



### 2.1. Overview

After installing EasyBuilder Pro, double click [UtilityManagerEx] shortcut on the desktop to start. Utility Manager is for launching several utilities and it is a stand-alone program. Please select a model first and note that certain features may not work as expected if an incorrect model is selected.



Utilities	Description
	Minimize Utility Manager window.
×	Close Utility Manager.
<b>(4)</b>	Add the frequently used utilities to the toolbar at the bottom of the
	window.
Run	Run the selected utility on the toolbar.
Edit	Delete the selected utility on the toolbar.



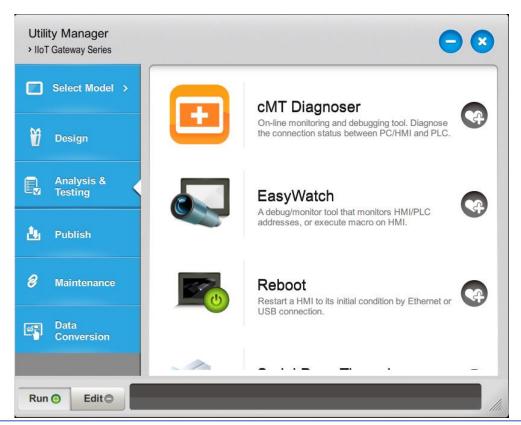
### 2.2. Design



Utilities	Description
EasyBuilder Pro	Launch EasyBuilder Pro to edit projects.
EasyAddressViewer Review the address ranges and formats of supported PLCs.	
Simulation	Simulate an HMI on PC by running On-line Simulation or Off-line
	Simulation. Please select an .exob / .cxob file as source first.
	Off-line simulation: Simulate project operation on PC without
	connecting any devices.
	On-line simulation: Simulate project operation on PC and PLCs are
	directly connected with PC.
	Note
	When using [On-line simulation] on PC, if the target device is a
	local PLC (the PLC directly connected to PC), there is a
	one-hour simulation limit.



### 2.3. Analysis & Testing



Utilities	Description
cMT Diagnoser	A diagnostic tool that can monitor data and status of all objects in
	the current window when it is connected to a cMT Series HMI,
	show the status of individual communication packet, show
	communication status with MQTT server, and debug macros.
	See "31 cMT Diagnoser".
EasyDiagnoser	Diagnoses the connection status between eMT/iE/XE/mTV HMI and
	PLC.
	See "33 EasyDiagnoser".
EasyWatch	See "33 EasyDiagnoser".  Allows users to monitor or configure HMI or PLC address values via
EasyWatch	, ·
EasyWatch	Allows users to monitor or configure HMI or PLC address values via
EasyWatch Reboot HMI	Allows users to monitor or configure HMI or PLC address values via Ethernet on PC.
	Allows users to monitor or configure HMI or PLC address values via Ethernet on PC.  See "35 EasyWatch".

applications to connect to PLC via HMI.

The Serial Pass-Through feature provides two modes: Ethernet and COM port.

Before using [Ethernet] mode, please check if virtual serial port driver has been installed.



### Ethernet Pass-Through

When PC and PLC are respectively connected to different Ethernet ports of a Dual-port HMI, this feature allows running the application on PC to control PLC through HMI. This feature is only supported on cMT / cMT X Series models.



Pass-through feature allows the PC application to connect PLC via HMI. In this case, the HMI works like a converter.





### 2.4. Publish



Utilities	Description
Download	Downloads project file to HMI via Ethernet or USB cable.
Upload	Uploads files on HMI to PC via Ethernet or USB cable.
<b>Build Download</b>	Builds the data to be downloaded to HMI in an SD card / USB drive.
Data for SD/USB	For cMT / cMT X Series, the data needs to be built in EasyBuilder
Disk	Pro.

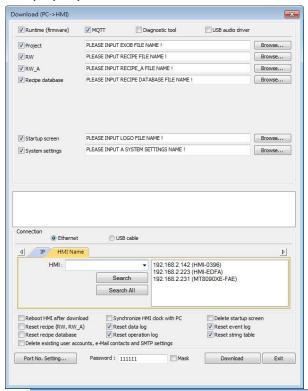


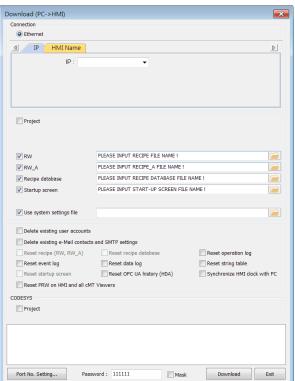
### 2.4.1. Download (PC->HMI)

Download files to HMI via Ethernet or USB cable.

### eMT, iE, XE, mTV Series







Setting	Description
Project	Select an .exob or .cxob project file. For a cMT /
	cMT X project, the Project Checksum will be
	shown under the directory of the project for
	users to check whether the project file has been
	tempered with.
Runtime (firmware)	Update HMI kernel programs. The firmware
	must be downloaded at the first time
	downloading data to HMI.
MQTT	If MQTT is used in the project and HMI is the
	broker, this checkbox must be selected before
	download.
Diagnostic tool	Enable the diagnostic tool to send diagnostic
	data to the developers when an error occurs for
	quick troubleshooting.
<b>USB Audio Driver</b>	Enable audio output on HMI so it can
	immediately emit a sound when a USB sound
	card and a speaker are connected.



RW / RW_A	Select an .rcp recipe file.
Recipe database	Select a .db file of Recipe Database.
Startup screen	Download a .bmp file to the HMI, which will be
	displayed after the HMI is started, and then the
	downloaded project is loaded. Please note that
	when downloading a project to a cMT / cMT X
	model, it is not possible to select both Project
	and Startup Screen in the download window.
Use system settings file	Select a .conf system settings file.
Reboot HMI after download	Automatically reboot after download.
Port No. Setting	Select the port by which to download the
	project file via Ethernet.
Synchronize HMI clock with PC	Synchronize HMI time with PC time when
With PC	downloading project file.
Reset recipe / recipe database / event log / data log / operation log / string table / OPC UA history (HDA) / startup screen / Delete existing user accounts, e-Mail contacts and SMTP settings	Erase the selected files on HMI before download.
CODESYS	Use Utility Manager to download CODESYS boot
	project.

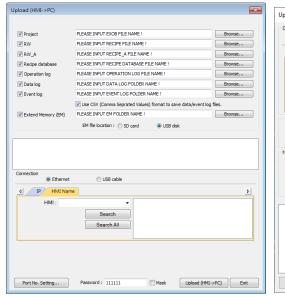


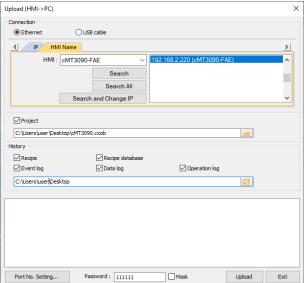
### 2.4.2. **Upload (HMI->PC)**

Upload files from HMI to PC via Ethernet or USB cable. Click [Browse] and assign the file path before uploading.

eMT, iE, XE, mTV Series







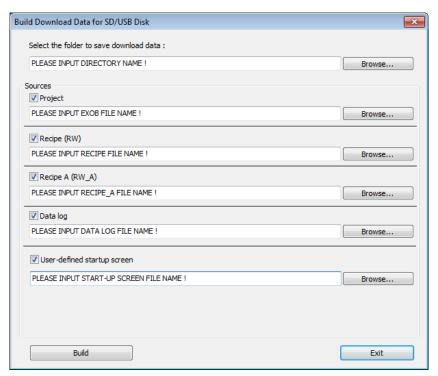
Setting	Description
Event log	Upload the .evt file on HMI to PC.
Extended Memory	Upload the .emi file saved in SD card or USB disk
(EM)	to PC.

For information about [Project], [RW / RW\_A], [Recipe database] or [Data log], see "2.4.1 Download" in this chapter.



- The file will be uploaded to PC in .exob / .cxob format. Please decompile it into editable .emtp / .cmtp file first and open the .emtp / .cmtp file in EasyBuilder Pro.
- To upload the historical files saved in the external device, please use FTP. See "32 FTP Server Application" for more information.

#### 2.4.3. Build Download Data for SD/USB Disk



- 1. Insert an external device (SD card or USB drive) to PC.
- 2. Designate the directory to save data.
- 3. Browse for the directory of the source files.
- 4. Click [Build] to create download file.

Files will then be saved to the inserted device for users to download to HMI without having to use a USB cable or Ethernet.

#### 2.4.4. Steps to Download Project to HMI via USB Disk or SD Card

To download data in a folder (e.g. a folder named "123" (K:\123)) in a USB disk.

- 1. Insert USB (in which the project is saved) to HMI.
- In [Download / Upload] dialog box select [Download].
- 3. Enter Download Password.
- In [Download Settings] dialog box, select [Download project files] and [Download history files].
- 5. Press [OK].
- 6. In [Pick a Directory] dialog box, select directory: usbdisk\disk\_a\_1\123.
- 7. Press [OK].

Project will then be updated.



If history data is downloaded but not the project file, please reboot HMI to update files.



#### 2.5. Maintenance

Options in this tab may vary according to model.



Utilities	Description			
Administrator Tools	Allows saving the data of [User Accounts], [USB Security Key],			
	[e-Mail SMTP Server Settings], and [e-Mail Contacts] to USB.			
	See "36 Administrator Tools".			
cMT Viewer	cMT Viewer can connect to a cMT / cMT X Series model. PC is the			
	display terminal for cMT / cMT X project.			
cMT-iV5/cMT-iV6	Undates oNAT iVE /iVE runtime (firmware) or OS			
Firmware Update	Updates cMT-iV5/iV6 runtime (firmware) or OS.			
cMT-Server OS	Undates oNT CVD/CVD 200 OC			
Update	Updates cMT-SVR/SVR-200 OS.			
cMT-Gateway/CTRL	Undates oMT Cataway/CTDL OS			
OS Update	Updates cMT-Gateway/CTRL OS.			
CODESYS Firmware	Undates CODESVS firmware on SMT HMI			
Upgrade	Updates CODESYS firmware on cMT HMI.			
SSL/TLS Certificate	Ungrades the built in expired SSI/TIS cortificate on HMI			
Upgrade	Upgrades the built-in expired SSL/TLS certificate on HMI.			



HMI Information Collector	Obtains a file with diagnostic information from HMI.
EasyPrinter / Backup Server	Runs remote backup/printer server on PC.
Data/Event log Information	Connects with HMI via USB cable or Ethernet to check the number of history files on HMI. This feature is not supported on cMT / cMT X Series.
	Data/Event Log File Information

Supports access to remote HMI by connecting EasyAccess server over Internet. You can find more information at: <a href="https://www.ihmi.net">www.ihmi.net</a>



EasyAccess 1.0

■ HMI Information Collector is available only on cMT / cMT X Series models, and the applicable OS version is 20210705 or later.



#### 2.6. Data Conversion



Utilities	Description	
Recipe Database	Edits recipe data.	
Editor	Click the icon to download the document about Recipe	
	Database.	
Easy Converter	Reads HMI-generated data logs, event logs, and operation logs and	
	converts the files to Excel (.xlsx) format.	
	See "25 EasyConverter".	
Recipe Editor	Creates new recipe data to be used on HMI and modifies the	
	existing recipe data.	
	See "24 Recipe Editor".	



## 3. Create an EasyBuilder Pro Project

This chapter explains the basic steps to create an EasyBuilder Pro project.

3.1.	Overview	3-2
3.2.	Create a New Project File	3-2
3.3.	Save and Compile the Project File	3-4
3.4.	Compile and Quick Compile	3-5
	Run On-Line or Off-Line Simulation	
3.6.	cMT Viewer	3-6
3.7.	Download the Project File to HMI	3-7
	Upload the Project File from HMI	



#### 3.1. Overview

The following is the process of creating a project.

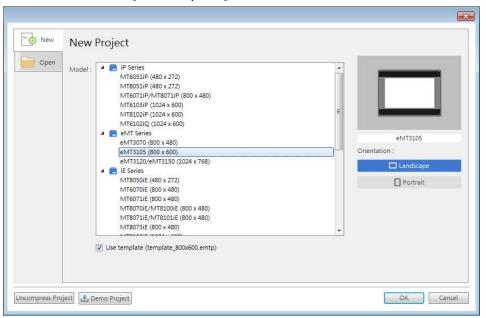
- 1. Create a new project file.
- 2. Save and compile the project file.
- 3. Run On-line or Off-line simulation.
- 4. Download the project file to HMI.

The following describes each process.

Click the icon to watch the demonstration film. Please confirm your internet connection before playing the film.

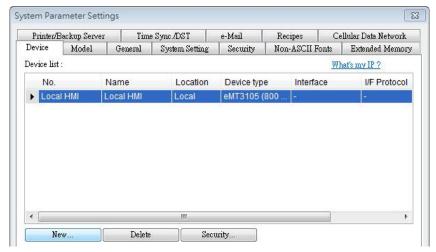
#### 3.2. Create a New Project File

- 1. Launch EasyBuilder Pro and open a new project file.
- 2. Select a model and select [Use template] check box.

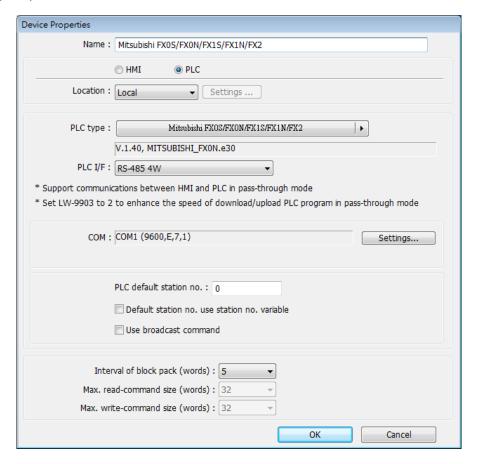


3. Click [New] button in the Device tab and select a device.





Configure parameters.

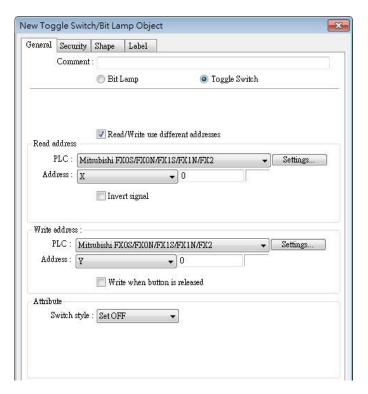


A new device is added to the [Device List].

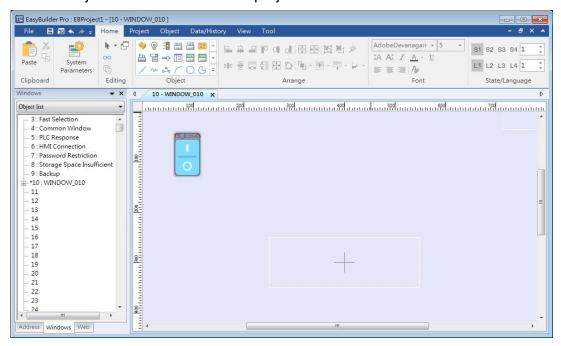


6. Create an object, for example, a Toggle Switch, and then set the address.





7. Place the object in the edit window. A project is now created.



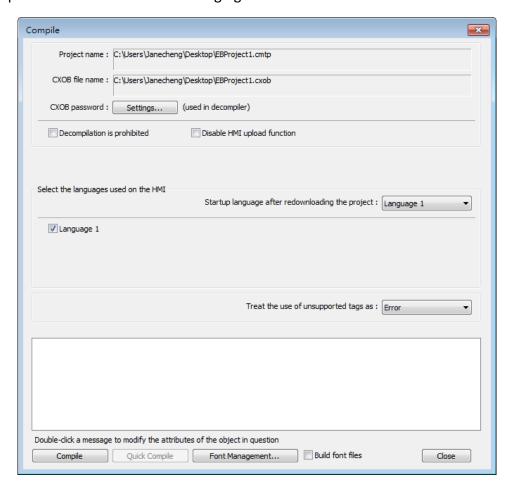
#### 3.3. Save and Compile the Project File

- 1. In EasyBuilder Pro toolbar click [File] » [Save] to save the .emtp file.
- 2. In EasyBuilder Pro toolbar click [Project] » [Compile] to compile .emtp file as .exob file, which could be downloaded to HMI. This also checks if the project can run correctly.





- For cMT / cMT X Series models, the project file extension is .cmtp, and the compiled file extension is .cxob.
- 3. To use multiple languages, all languages must be configured in Label Tag Library first. When downloading the project to HMI, select the needed languages only. A successful compilation is shown in the following figure.



#### 3.4. Compile and Quick Compile

The [Compile] and [Quick Compile] modes can be selected in the Compile window. To compile a relatively large file in which only a few windows are modified, the Quick Compile mode can be used to save compilation time.

#### Compile:

Compile the whole project file.

#### Quick Compile:

Only compile the modified window or event log. When one of the records in the event log is changed, the whole event log will be compiled.





- If the project file is compiled for the first time, the Quick Compile mode is not supported.
- In a project file, when its system settings, picture library, sound library, or label library is modified, then Quick Compile mode is not supported for the first compilation after modification.
- The whole project file must be compiled before it is downloaded to HMI.
- Utility Manager does not support the project file compiled using Quick Compile mode. To download a project file using Utility Manager, please compile the whole project file first.

#### 3.5. Run On-Line or Off-Line Simulation

Off-line simulation: Simulate project operation on PC without the need for connecting any device.

On-line simulation: Simulate project operation on PC without downloading the project to HMI. The PLC is connected to PC, please set correct parameters.



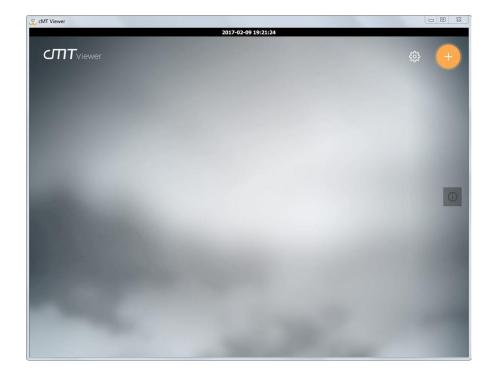
- (iE/XE/eMT Series) When using On-line Simulation on PC, if the target device is the PLC directly connected to PC, there is a 10-minute simulation limit.
- (cMT/cMT X Series) When using On-line Simulation on PC, the monitoring time is limited to one hour and a prompt window pops up every 15 minutes.

#### 3.6. cMT Viewer

This program connects to cMT Series models via network. To run this program, execute cMTViewer.exe under installation directory. Or, in EasyBuilder Pro toolbar, click [Tools] » [cMT Viewer].

Click the icon to watch the demonstration film. Please confirm your internet connection before playing the film.





#### 3.7. Download the Project File to HMI

The following explains four ways to download the project file to HMI.



- For cMT-SVR, only the way described in 3.6.1 is available.
- When download project file to HMI using mini USB cable, please do not connect PLC simultaneously, in order to avoid noise from PLC interfering with HMI.
- Click the icon to watch the demonstration film. Please confirm your internet connection before playing the film.

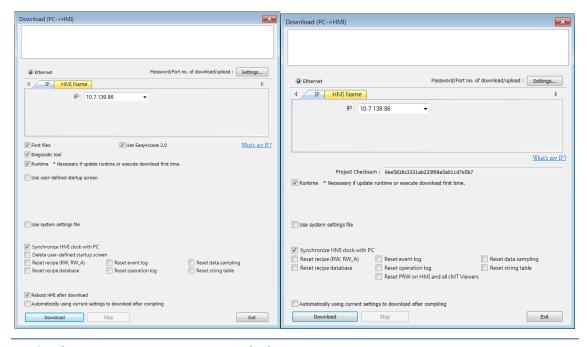
#### 3.7.1. Configure in EasyBuilder Pro

- In EasyBuilder Pro toolbar, click [Project] » [Download]. Make sure that all the settings are correct.
- 2. Select [Ethernet], set password and HMI IP.



#### eMT, iE, XE, mTV Series

#### cMT, cMT X Series



Setting	Description
Font files	Download the font used in the project to HMI.
Runtime	Select the check box to update the HMI kernel
	programs. If this is the first time downloading file or
	EasyBuilder Pro version is updated, please download
	the firmware before downloading files to HMI.
EasyAccess 2.0	Download EasyAccess 2.0 driver to HMI. (This option
	is available only for MT8000iE models. For other
	models, EasyAccess 2.0 will be automatically
	downloaded.)
Use user-defined startup screen	Download the specified .bmp image file to the HMI
	as the startup screen. For cMT/cMT X HMI, please
	see chapter 5.4 General Settings in this user manual
	for more information on updating the startup screen
	on the HMI.
Use system settings file	Download the system settings file to update
ille	hardware settings.
Synchronize HMI	Synchronize HMI time with PC time when
clock with PC	downloading project file.
Delete existing user	Select the check box to delete existing user
accounts, e-Mail contacts and SMTP	accounts, e-Mail contacts or SMTP settings before
settings	downloading the project. This setting is only
	effective when one of the following settings is

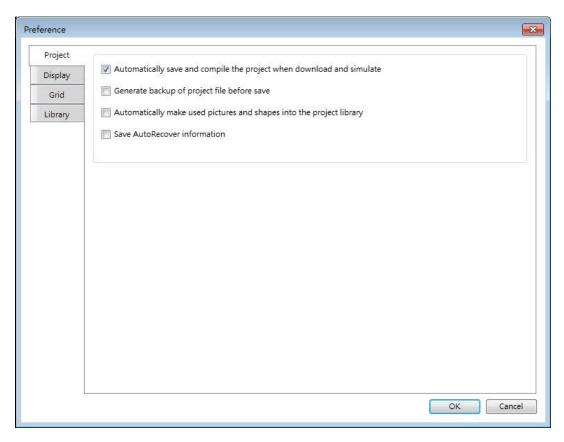


	enabled:
	1. [System Parameters] » [Security] » [Enhanced
	security mode] » [Use existing user accounts on
	HMI first (if existed), Othrewise, use settings
	below].
	2. [System Parameter s] » [e-Mail] » [Use existing
	user accounts on HMI first (if existed),
	Othrewise, use settings below].
Reset recipe/ event log/ data sampling/ recipe database/ operation log/ string table/ user-defined startup screen	The selected files will be erased before downloading.
Reboot HMI after download	HMI will reboot after the downloading process is
	done.
Automatically using current	The system will compile the project and download it
settings to	to the latest target HMI. The way to enable this
download after compiling	function is described in the following part.

[Automatically using current settings to download after compiling]
If this check box is selected, EasyBuilder Pro will compile the project and download it to the latest target HMI.

- 1. In EasyBuilder Pro toolbar, click [File] » [Preferences].
- 2. Select [Automatic save and compile when download and simulate] check box.

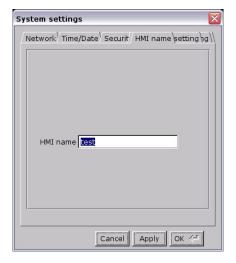




- 3. In EasyBuilder Pro toolbar, click [Save] and then [Download].
- 4. In the dialog box, select [Automatically using current settings to download after compiling] check box.
- Click [Download].
- 6. When finished, next time when [Download] is clicked, EasyBuilder Pro will automatically compile and download the project to the latest target HMI.

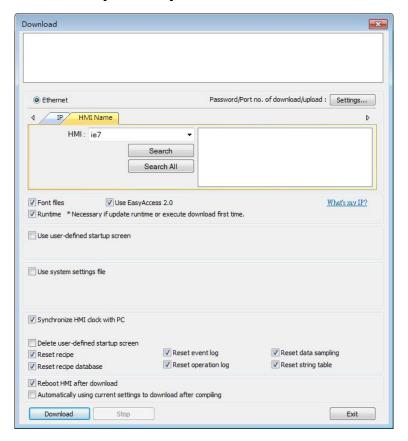
#### 3.7.2. Use HMI Name

1. Go to [System settings] on HMI and then set HMI name first.



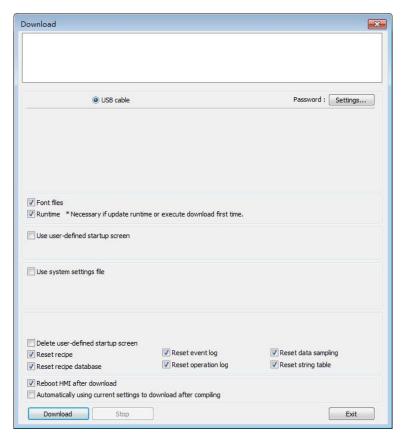


On PC, select the HMI name and start downloading. To use [Search], enter the HMI name first to search for the HMI. [Search all] searches for all HMIs in the same subnet network.





#### 3.7.3. Use USB cable



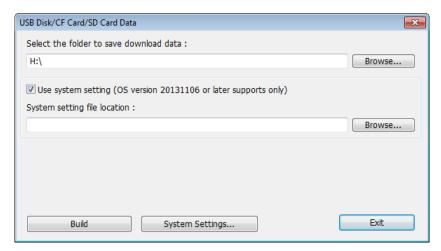
Select USB cable to download project to HMI. The way of setting is same as "3.6.1 Configure in EasyBuilder Pro". Before downloading via USB cable, please make sure the USB driver is installed. Go to [Computer Management] » [Device Manager] to check if USB driver is installed. If it is not installed, please refer to installation steps to install manually.

#### 3.7.4. Use USB Drive or SD Card

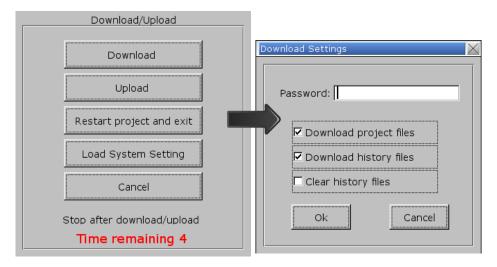
The following explains how to download project file by using USB drive or SD card.

On EasyBuilder Pro toolbar click [Project] » [Build for SD card / USB disk download].
 Browse for the project file and then click [Build], the file for download will be generated in the connected external device.

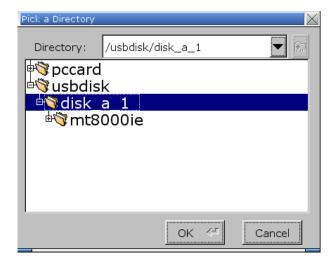




- 2. Insert an external device to HMI.
- 3. Select [Download] on HMI and enter password.



**4.** After password is confirmed, it will show the directories in the external device. (pccard: SD Card; usbdisk: USB Drive)



5. Select the directory that contains project, and then click [OK] to start downloading.

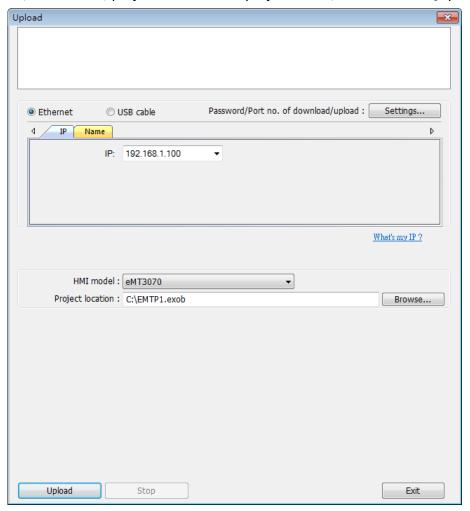




- Please select the parent directory of the generated files when downloading. For the structure above, please select disk\_a\_1, not mt8000ie.
- You may click [System Settings] to save the hardware settings configured in EasyBuilder Pro into SD card or USB disk, and then download the settings file to HMI. See "4 Hardware Settings" for more information.
- Click the icon to watch the demonstration film. Please confirm your internet connection before playing the film.

#### 3.8. Upload the Project File from HMI

- 1. On EasyBuilder Pro toolbar click [File] » [Upload].
- 2. Set HMI IP, HMI model, project location and project name, and then click [Upload].





## 4. Hardware Settings

This chapter explains HMI settings.

4.1.	Overview	4-2
4.2.	I/O Ports	4-2
4.3.	LED Indicators	4-2
4.4.	System Reset	4-3
4.5.	System Toolbar	4-4



#### 4.1. Overview

This chapter discusses the HMI settings.

#### 4.2. I/O Ports

The I/O ports may vary between models; please see the datasheet for more information. The I/O Ports include:

- SD card slot: Allows downloading / uploading project file, including recipe data, event log, data log...etc. and also allows recording history data and data backup.
- COM Port: Connects PLC or other peripheral devices. The type of serial port include: RS-232, RS-485 2W, RS-485 4W, and CAN Bus.
- Ethernet: Allows downloading / uploading project file, including recipe data, event log, data log...etc. Connects to Ethernet devices, such as PLC, laptop.
- USB Host: Supports USB devices, such as mouse, keyboard, USB disk, printer, or barcode device.
- USB Client: Allows downloading / uploading project file, including recipe data, event log, data log...etc. and also allows recording history data and data backup.

For the first time operating HMI, please complete the following system settings. When finished, the project files designed using EasyBuilder Pro can be used on HMI.

#### 4.3. LED Indicators

The LED indicators on the HMI indicate:

Models: MT8121XE, MT8150XE, MT8121iE, MT8150iE

	LED	Description
	PWR (Orange)	Indicates power status.
	CPU (Green)	Blinks when read/write Flash Memory.
	COM (Blue)	Indicates COM port communication status, blinks
		during communication. When communication is
		good, it may stay on. (Not including network
		communication)
Oth	er Models:	
	LED	Description
	PWR (Orange)	Indicates power status.

Indicates CPU status. If it blinks or goes out, there



CPU (Green)

	may be a CPU error.
COM (Blue/Red)	Indicates communication status, blinks during
	communication. When communication is good, it
	may stay on.

#### 4.4. System Reset

Certain HMI models are equipped with a reset button and a set of DIP switches. When using the DIP switches to change modes, the corresponding functions will be triggered. If system password is lost or forgotten, see the following steps to restore factory default.

- 1. Flip DIP Switch 1 to ON and the rest to OFF, and then reboot HMI. HMI will switch to touch screen calibration mode.
- 2. A "+" sign appears on the screen, touch the center of the sign, after all 5 signs are touched, "+" disappears and the touch screen parameters will be stored in HMI system.
- 3. After calibration, confirm to restore the default password, select [Yes].
- 4. Confirm to restore the default password again by typing [yes] and clicking [OK]. The project files and history records stored in HMI will all be removed. (The default Local Password is 111111. However, other passwords, such as Download/Upload passwords have to be reset.)

The following lists the DIP switch settings of different models. Please see the relevant installation instruction.

### cMT / cMT X / eMT / iE Dip Switch



SW1	SW2	SW3	SW4	Mode
ON	OFF	OFF	OFF	Touch Screen Calibration Mode
OFF	ON	OFF	OFF	Hide HMI System Setting Bar
OFF	OFF	ON	OFF	Boot Loader Mode
OFF	OFF	OFF	ON	Reserved
OFF	OFF	OFF	OFF	Normal



The state of DIP Switch 4 on each unit may be different. If it should be ON when out from factory, the Dip Switch 4 would be set ON and cut off. If it should be OFF, the Dip Switch 4 would be set OFF but the switch is not cut.

SW1	SW2	Mode
ON	ON	Restore factory default
ON	OFF	Hide system setting bar



mTV Dip Switch

OFF	ON	Boot loader mode
OFF	OFF	Normal mode



cMT-SVR

Dip Switch



SW1	SW2	Mode
ON	ON	Restore factory default
ON	OFF	Restore Ethernet IP Settings
OFF	ON	Boot loader mode
OFF	OFF	Normal mode

#### 4.5. System Toolbar

After rebooting HMI, you can set the system with [System Toolbar] at the bottom of the screen. Normally, this bar is hidden automatically. Only by touching the arrow icon at the bottom-right corner of the screen will the System Toolbar pop up. From left to right the icons are: System Settings, System Information, Text Keyboard, and Number Keyboard.



How to hide HMI System Setting Toolbar:

- When [DIP Switch 2] is set ON, the system setting toolbar is disabled. When set OFF; the system setting toolbar is enabled. Please restart HMI to enable/disable the toolbar.
- For mTV Series, flip DIP Switch 1 to ON to hide system setting toolbar.
- System register [LB-9020] can also enable/disable system setting toolbar. When [LB-9020] is set ON, the toolbar is displayed, and set OFF to hide the toolbar.

#### 4.5.1. System Setting

#### cMT/cMT X Series

Set or modify system parameters. Confirm password for security first. The factory default password is 111111.









#### **CODESYS**

Enter the activation code to activate CODESYS.

#### General

General settings including FTP settings. [Direction]

Set screen orientation mode to landscape or portrait by selecting degrees from 0 / 90 / 180 / 270.

[Brightness]

Adjust screen brightness.

[Popup download window]

When enabled, the download window can pop up.

[Show Start button]

When enabled, the Start button is displayed.

[Show mouse cursor]

When enabled, the mouse cursor is displayed.

#### Network

Download project file to HMI via Ethernet. The IP address of the target device (HMI) must be correctly set. Users can choose from obtaining an IP address automatically or entering an IP address manually. To use Email or EasyAccess 2.0, please set DNS correctly. For models with two Ethernet ports, please associate two IP addresses with different domains to avoid network conflict.

[Enable Bridge Mode]



For dual Ethernet port models, bridge mode can be enabled to allow LAN1 and LAN2 to be in the same network segment, achieving the function of a switch.



#### Time/Date

Set HMI local date and time.



#### **HMI** name

Set the HMI name for identification when downloading / uploading a project.



#### **Clear History**

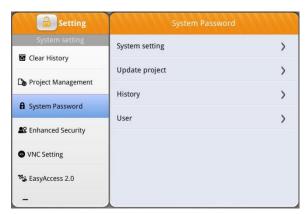
Clear historical data stored in HMI.





#### **Project Management**

HMI can be rebooted by clicking the Restart button.



#### System Password

By default the password is 111111.
User-defined passwords can be used after verification.



#### **Enhanced Security**

Add or delete user accounts and manage user privileges.



#### **VNC Setting**

When enabled, VNC can be used to monitor a remote HMI over an Ethernet network.

[Start VNC]

Allows connections from VNC Client devices.

[VNC multi connection]

Allows multiple VNC Client devices to connect. Connecting multiple VNC Client devices simultaneously may affect the communication speed of the HMI.





# Setting System setting Printer name Not installed URI URI Install network printer \*\* OS Upgrade Reset options Printer





#### EasyAccess 2.0

Activate EasyAccess 2.0 service.

Click the icon to download the demo project. Please confirm your internet connection before downloading the demo project.

#### **Printer**

Please see Chapter 23.3 in EasyBuilder Pro user manual for more information on installing printers.

#### **OS Upgrade**

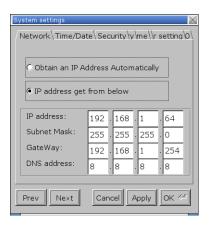
Select an OS file saved in an SD card or USB disk to upgrade OS. When OS is upgrading, please do not cut off HMI power. For more information on upgrade steps or notes, see the OS upgrade manual of the model in use.

#### **Reset options**

Restore HMI to factory settings.



#### eMT/iE/XE/mTV Series









#### Network

When downloading project file to HMI via Ethernet, set the correct IP of the target HMI. You can obtain an IP address automatically or enter the IP address manually. To use Email and EasyAccess2.0, please set correct DNS address. For models with two Ethernet ports, please associate two IP addresses with different domains to avoid network conflict.

#### Time / Date

Set HMI local time and date.

#### Security

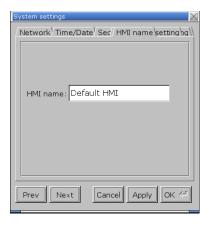
Password protection, the default is 111111. Please click the buttons to set the passwords, and finish password confirmation.

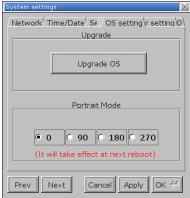
[Password for entering system][Password for uploading project][Password for downloading project][Password for uploading history data]

#### History

Clears history data in HMI.









#### **HMI** name

Set HMI name to be used when download/upload project.

#### **OS** setting

[Upgrade OS]

Upgrade firmware. Please do not turn off or unplug HMI during OS upgrade process. For more details, see the instruction about OS upgrade of the model used.

[Portrait Mode]

Set screen orientation mode. After changing the mode, reconnect HMI to power supply, for the setting to take effect. That is, disconnect all power from HMI, and then connect again. If portrait mode is used (90 or 270 degree), the project must be designed for portrait mode, otherwise it cannot be correctly displayed.

#### **VNC** server setting

Remote HMI monitoring and controlling via Ethernet.

[Start VNC single-connection]

Allows connection with one VNC client.

[Start VNC multi-connection]

Allows connection with multiple VNC clients.

Connecting more VNC clients may slow down the communication speed.

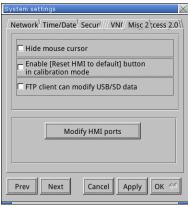
Please see the settings steps in the later part.

Click the icon to watch the demonstration film.

Please confirm your internet connection before playing the film.









#### Misc 1

Rotary switch for adjusting LCD brightness.

[Popup download window]

If selected, after inserting USB disk or SD card to HMI, the Upload / Download dialog box shows.

[Restart after download/upload]

If selected, restarts HMI automatically after uploading / downloading project.

#### Misc 2

[Hide mouse cursor]

If selected, the mouse cursor will be hidden.
[Enable [Reset HMI to default] button in calibration mode]

If selected, when the operator presses and holds anywhere on the screen for more than 2 seconds during HMI startup, the touch screen calibration mode will start. After calibration, [Reset HMI to default] option shows.

[FTP client can modify USB/SD data]
If selected, USB/SD data can be modified using FTP.
[Modify HMI ports]

Change the port number for Upload/Download and FTP.

#### EasyAccess 2.0

Activate EasyAccess 2.0 service.

Click the icon to download the demo project.

Please confirm your internet connection before downloading the demo project.

The following steps explain how to set VNC server.

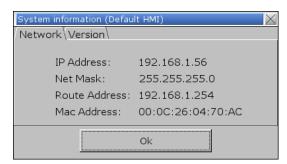
- 1. Enable HMI VNC server, set password.
- 2. Install Java IE or VNC Viewer on PC.
- Enter remote HMI IP in Internet Browser. Or, in VNC Viewer enter remote HMI IP and password.



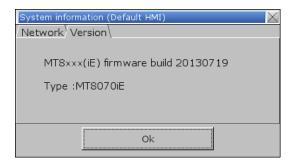


#### 4.5.2. System Information

Network: Displays network information & HMI IP address.



Version: Displays HMI firmware version and model type.





## 5. System Parameter Settings

This chapter introduces the system parameter settings.

5.1.	Overview	5-2
5.2.	Device	5-2
5.3.	Model	5-11
5.4.	General	5-15
5.5.	System Setting	5-22
5.6.	Remote	5-25
5.7.	Security	5-26
5.8.	Extended Memory	5-29
5.9.	Printer / Backup Server	5-33
5.10.	Time Sync./DST	5-34
5.11.	e-Mail	5-36
5.12.	Cellular Data Network	5-38
5.13.	FTP	5-40



System Parameter Settings 5-2

#### 5.1. Overview

Launch EasyBuilder Pro, in the main menu select [Home] » [System Parameters] to open the [System Parameter Settings] dialog box. System Parameter Settings are divided into several tabs, these tabs will be introduced respectively in this chapter.

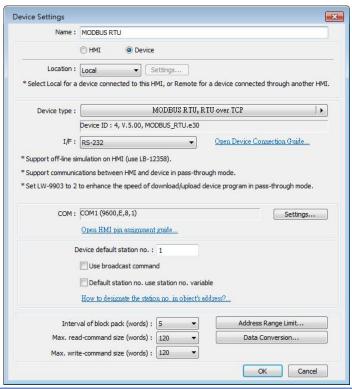
#### 5.2. Device

Parameters in this tab determine the attributes of each device connected with HMI. The device can be a Local / Remote HMI / PLC. A default device "Local HMI" exists when creating a new project. This device is the HMI that will be updated and programmed.

#### 5.2.1. How to Control a Local PLC



"Local Device" is a device connected to the local HMI. To control/connect a Local Device, add this type of device first. Click [System Parameters] » [New] to open [Device Properties] dialog box. For example, when connecting MODBUS RTU as a Local Device:

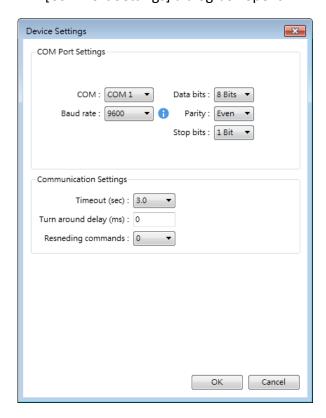






HMI / Device	In this example a device is used, so select [Device].
Location	Select [Local] or [Remote]. In this example the device is
	connected to the Local HMI, so select [Local].
Device type	Select the type of the device.
I/F	The available interface: [RS-232], [RS-485 2W], [RS-485
	4W], [Ethernet], [USB], and [CAN Bus].

 If the interface used is [RS-232], [RS-485 2W], or [RS-485 4W], configure communication parameters by clicking [Device Properties] » [Settings] and then [Com Port Settings] dialog box opens.



#### **Timeout**

If the communication has been disconnected for more than preset time limit configured in [Timeout] (in sec), Window No. 5 will pop up and show "Device No Response" message.

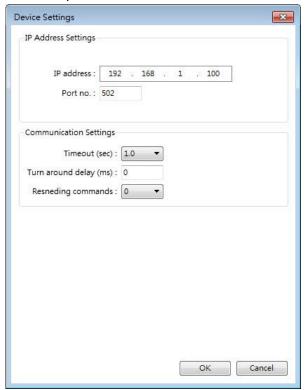
#### Turn around delay

While sending the next command to the device, HMI will delay the sending according to the time interval set in [Turn around delay]. This may influence the efficiency of the communication between HMI and the device. Default value is "0".



Note: If the device used is SIEMENS S7-200 Series, it is recommended to assign "5" to [Turn around delay] and "30" to [Send ACK delay].

 If the interface used is [Ethernet], click [Device Properties] » [Settings] and the [IP Address Settings] dialog box opens. Please set correct device IP address and port number.



- If the interface is [USB], no further setting is required. Please check the settings in [Device Properties].
- If the interface is [CAN (Controller Area Network)
   Bus], please see "Device Connection Guide" for "CANopen" and import the .eds device file.

Device default station no.

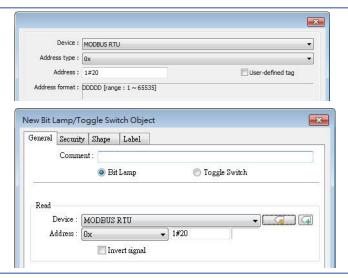
Set the default station number for device address if the device station number is not included in the address.

Device station no. can be set in its address. The address

format: ABC#Addr

ABC stands for device station number and ranges from 0 to 255. Addr stands for device address. And the "#" sign separates the station number and the address. As shown in the following figure, the data is read from device station number 1, and address 0x-20.





Default station no. use station no. variable

Use the station number variables as the default device station number. Select one from LW-10000 to LW-10015 (var0 to var15) as the station number variables. If the station no. is not specified in device address, the station number will be determined by the station no. variable. For example, if var3 is set for default station no:



The followings demonstrate some examples:

The device station number is "5".



 The device station number is determined by var7 (LW-10007)



 Device address is set to "111", since device station no. is not specified, and the default station no. is var3, the device station no. is determined by var3 (LW-10003).





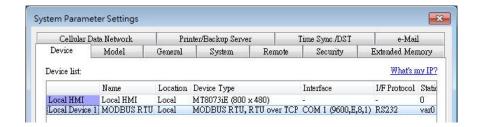
Click the icon to download the demo project. Please



	confirm your internet connection before downloading the demo project.
Use broadcast command	When [Use broadcast command] check box is selected, please fill in [Broadcast station no.] according to the broadcast station number defined by the device. When HMI sends a broadcast command to the station number set here, the device will only receive the command and not reply to HMI.  PLC default station no. use station no. variable Use broadcast command Broadcast station no.: 255  As shown in the following figure:
	Read address PLC name: MODBUS RTU Address: 4x  V 255#200  When HMI sends a command to address 255#200, all the devices will receive this command and will not reply.  Only devices that support broadcast command can use this feature.
Interval of block pack (words)	If the interval between read addresses of different commands is less than this value, the commands can be combined to one. The combining function is disabled if this value is set to "0".  For example, the interval value is set to "5", to read 1 word from LW-3 and 2 words from LW-6 respectively (read from LW-6 to LW-7), since the interval of addresses between LW-3 and LW-6 is less than 5, these two commands can be combined to one. The result is to read 5 consecutive words from LW-3 to LW-7.  Note: The maximum size of command combination data must be less than [Max. read-command size].
Max. read - command size (words)	The maximum data size to read from the device at one time. Unit: word
Max. write - command size (words)	The maximum data size to write to the device at one time. Unit: word.

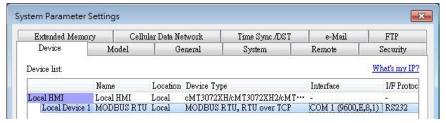
After all settings are completed, a new device named "Local Device 1" is added to the [Device list].





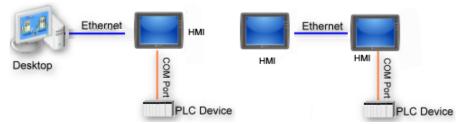


When using a cMT / cMT X Series model, select "Local HMI" in [System Parameter Settings] dialog box and then click [New Device] to add a "Local Device 1" under "Local HMI".



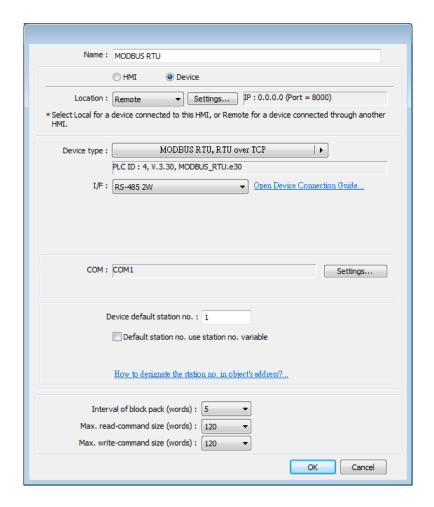
Click the icon to watch the demonstration film. Please confirm your internet connection before playing the film.

### 5.2.2. How to Control a Remote Device



"Remote Device" is a device being connected to a remote HMI. To control a remote device, add this type of device first. Please click [System Parameters] » [New] to open [Device Properties] dialog box. For example, use MODBUS RTU as the Remote Device:



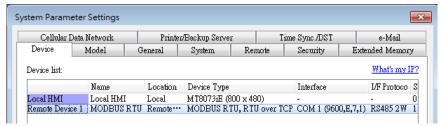


Setting	Description	
HMI or Device	In this example, a device is used, so select [Device].	
Location	Select [Local] or [Remote]. In this example the device is connected to Remote HMI, so select [Remote]. Set the IP address and port number of the Remote HMI by clicking [Settings] next to [Remote].	
	IP Address Settings  © Ethernet © COM port (use master-slave protocol)  IP address: 192 . 168 . 1 . 10  Port no.: 8000  OK Cancel	
Device Type	Select the type of the device.	
I/F	The interface used for Remote Device. If the remote device uses a COM port, select [RS-232], [RS-485 2W], or [RS485 4W].	



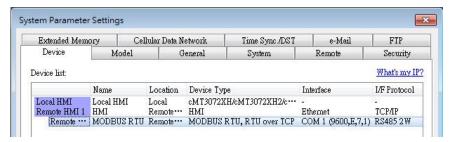
СОМ	Set the correct COM port used by the Remote Device.
Device	
default	Set the station number of Remote Device.
station no.	

After all settings are completed, a new device named "Remote Device 1" is added to the [Device list].





■ When using a cMT / cMT X Series model, select the defined "Remote HMI 1" in [System Parameters] dialog box and then click [New Device] to add a "Remote PLC 1" under "Remote HMI 1".



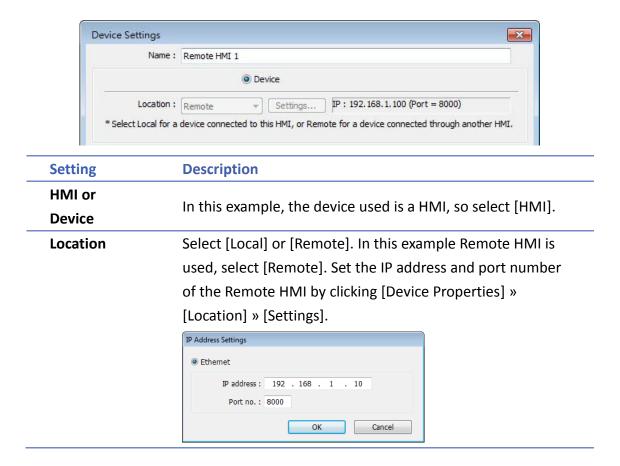
Click the icon to watch the demonstration film. Please confirm your internet connection before playing the film.

### 5.2.3. How to Control a Remote HMI

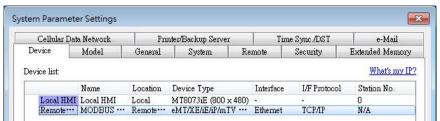


"Remote HMI" is the HMI other than "Local HMI", and PC is also a "Remote HMI". To control a Remote HMI, add this type of device first. Click [System Parameters] » [New] to open [Device Properties] dialog box as shown in the following figure:



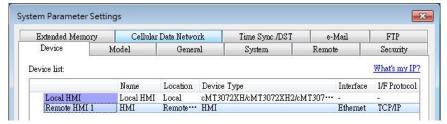


After all settings are completed, a new device named "Remote HMI 1" is added to the [Device list].





When using a cMT / cMT X Series model, in [Device list] click [New HMI] to add a "Remote HMI 1".

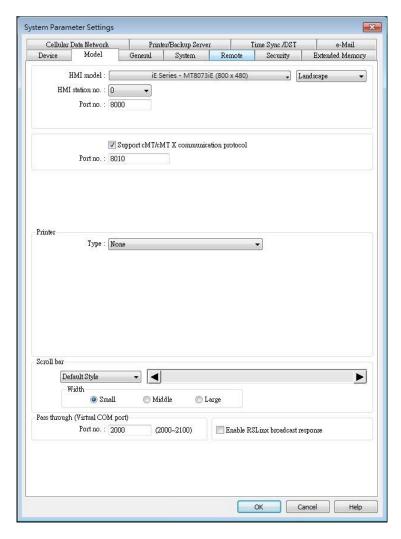


Click the icon to watch the demonstration film. Please confirm your internet connection before playing the film.



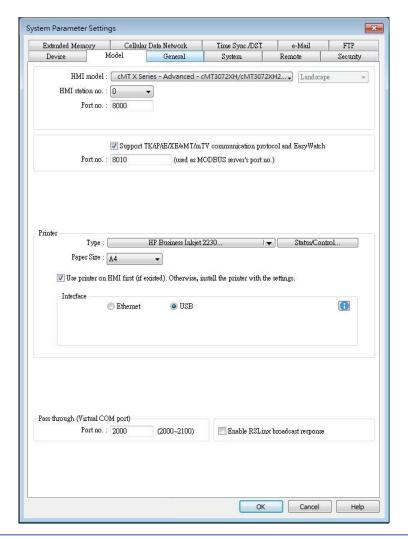
# 5.3. Model

Configure the [HMI model], [Timer], [Printer] and [Scroll bar] settings, and more. eMT, iE, XE, mTV Series





# cMT, cMT X Series



# Setting

### **Description**

# **HMI** model

Select an HMI model.

The [Resize pop-up windows / objects] dialog box will pop up when changing to a model with a different resolution. Select required adjustment and click [OK]. In most cases, select all options.



# Landscape/Portrait

Change the orientation of the project.



HMI station no.	Set the station number of current HMI. The default value is "0".	
Port no.	Set the port number of current HMI. The default value is "8000".	
Support cMT communication protocol	Supports communication with cMT / cMT X Series models. cMT / cMT X Series project file should use the same communication port.	
Printer (eMT,	Туре	
iE, XE, mTV	A printer can be connected with the HMI. The HP PCL Series	
Series)	printer is connected through USB interface while other printers through a COM port.  For more information, see "23 HMI Supported"	
	Printers".  If the printer is connected through [COM], configure the parameters correctly. If the printer type is [SP-M, D, E, F], the [pixels of width] has to be set accurately, i.e. the set pixel(s) cannot exceed printer's default setting, or the HMI will fail to print data.	
Printer (cMT,	The printer driver can be installed on HMI.	

# Printer (cMT, cMT X Series)

# Type

Select printer type.

# **Status address**

Shows printer status.

LW-n	Status
0	Printer driver is not installed yet.
1	Installing printer driver.
2	Printer is ready.
3	Printer is printing.
4	Print job is canceled.
LW-n+1	Error
0	None
1	Printer is not found.
2	Unknown error.

# **Control address**

Updates printer connection parameters.

LW-n	Command
0	None
1	Update connection parameters.
2	Restart printer driver.



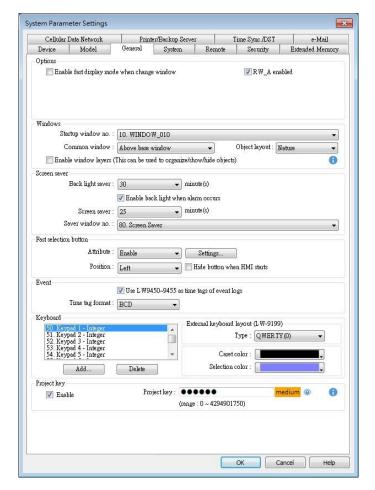
	LW-n+1	1/0
	0	Ethernet
	1	USB
	LW-n+2	IP address (Total: 4 words)
	LW-n+6	Port (Default port number: 9100)
	Please note	e that using only the ppd file for a printer may
	not be able	e to run the printer since the corresponding
	driver is ab	sent. Using tested models is recommended.
Scroll bar	Set the wid	th of Scroll Bar, when the size of the object is too
	small to dis	splay the contents, a scroll bar is displayed in the
	object. This	s feature can be applied to objects that allow
	scrolling, su	uch as Alarm Display, Event Display, History Data
	Display, an	d Option List.
Pass through		
(Virtual COM	Set the por	rt number for Pass-through communication.
port)		



# 5.4. General

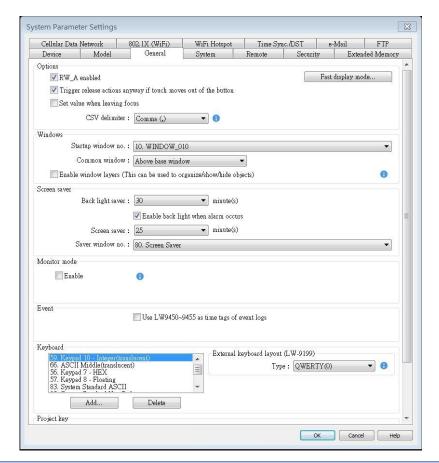
Configure the properties related to screen display.

# eMT, iE, XE, mTV Series





### cMT, cMT X Series



# Setting

# **Description**

### **Options**

### Fast display mode

In this mode, selected objects will cache the most recently read data and display it quickly after window is changed, achieving a faster display speed.

Controllable objects: Objects that allow variable input, such as Toggle Switch, Numeric Input.

Uncontrollable objects: Objects that only display states, such as Bit Lamp, Word Lamp.

The objects that support the fast display mode include: Bit Lamp, Word Lamp, ASCII, Numeric, Function Key, Option List, Direct / Indirect Window, Bar Graph, Meter Display, Animation, Moving / Rotating Shape, PDF Reader, Picture View, Energy Demand Display.

### RW A enabled

Enable or disable recipe data RW\_A. Enable this, the objects can then control RW A .The size of RW A is 64K.

Trigger release action anyway if touch moves out of the button. (cMT / cMT X Series)

With this option selected, releasing the finger after



touching the button and then sliding the finger out of the button area is still considered as button release; its release action(s) will be triggered.

### Set value when leaving focus (cMT / cMT X Series)

With this option selected, values will be written upon leaving the input mode of an object (e.g. Numeric object), even if not by pressing the ENTER key. For example, data entry for the current numerical object is considered completed and value is written when one selects another object to enter value. An alert message shows when an invalid value is entered.



- 1. Values will not be retained after pressing the ESC key to leave.
- 2. When the system keyboard is used, values will be directly written after closing the keyboard.
- 3. With [Input order] enabled, the sequential input is performed after leaving the object by pressing the ENTER key. The sequential input will be stopped if another object is touched during the input process.

### CSV delimiter (cMT / cMT X Series)

Save the CSV file generated from Backup or Import/Export with Comma (,) or Semicolon (;) delimiter.

### Windows

### Startup window no.

Designate the window shown when start up HMI.

# **Common window**

The objects in the common window (Window No. 4) will be shown in each base window. This determines that the objects in common window are placed above or below the objects in the base window.

### **Object layout**

If [Control] mode is selected, when operating HMI, [Animation] and [Moving Shape] objects will be displayed above other kinds of objects neglecting the sequence that the objects are created. If [Nature] mode is selected, the display will follow the sequence that the objects are created, the first created will be displayed first.

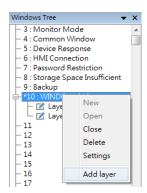
# Enable window layers (This can be used to organize/show/hide objects)

With this option selected, layers within a window can be created in the window tree.



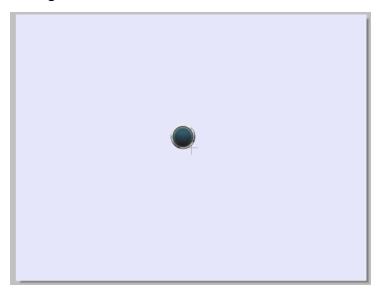
At most 10 layers can be added to a window.

As shown in the following figure, right-click on a window number and then select [Add layer].



The following is an example of creating a layered window: Place a Bit Lamp object in Layer 1 and a Numeric object in layer 2.

Selecting Layer 1 shows only the Bit Lamp object in the editing window.

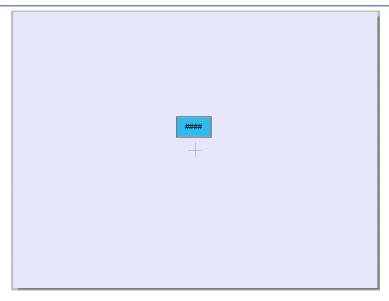


Selecting Layer 2 shows only the Numeric object in the editing window.

```
+10: WINDOW_010

| Super 1 (Bottom)
| BL_0 (LB-0) (Bottom)
| Layer 2
| NE_0 (LW-0)
```





Selecting window 10 shows all objects.



### Screen saver

# **Back light saver**

If the screen is left untouched and reaches the time limit set here, the back light will be turned off. The setting unit is minute. Back light will be on again once the screen is touched. If [none] is set, the back light will always be on.

### Screen saver

If the screen is left untouched and reaches the time limit set here, the current screen will automatically switch to a window assigned in [Saver window no.]. The setting unit is minute. If [none] is set, this feature is disabled.



### Saver window no.

Specify a window to be displayed when HMI goes to screen saver mode.

Note: In a saver window, the [Return to previous window] option of a Function Key can be used to wake up HMI from screen saver mode; therefore, please avoid editing the project in the way shown as the example below, to prevent the HMI from going to screen saver mode repeatedly. Example: A Function Key used to "Return to previous window" is placed in Window no. 11, and the HMI goes into screen saver mode when Window no. 11 is displayed. In this case, the HMI can wake up from screen saver mode when any point on its screen is touched, and Window no. 11 will be displayed again. At this moment, if the Function Key in Window no. 11 is touched, the HMI goes into screen saver mode again.

Solution: 1. When a Function Key with "Return to previous window" selected is placed in the saver window, please use "Change full-screen window" for all other windows.

2. When "Change full-screen window" is used for the saver window to change to a specific window (e.g., home page), please make sure that "Return to previous window" is not used in this destination window. The "Return to previous window" option can still be used for other windows.

# Fast selection buttons

This setting is applicable for eMT, iE, XE, mTV, and iP Series. Setting the attributes for fast selection button for Window No. 3. To use the fast selection button, create Window No. 3 first.

### **Attribute**

Enable or disable fast selection window. Select [Enable] and click [Settings] to set the attributes, including color and text of the button.

# **Position**

Select the button position on the screen. If [Left] is chosen, the button will show at bottom left side of the screen; if [Right] is chosen, the button will show at the bottom right side of the screen.

### **Settings**

Set the shape and label font of the Fast Selection Button.

# **Hide button when HMI starts**

The Fast Selection Button will be hidden, calling it out requires system registers LB-9013~LB-9015.



Monitor	This setting is applicable for cMT / cMT X Series.
Mode	Window no. 3 in the project is monitored in this mode in
	cMT Viewer. The user can select up to 50 cMT / cMT X
	Series HMIs to monitor in cMT Viewer, and in 3x3 or 5x4 tile view.
Event	Use LW9450~9455 as time tags of event logs
	When this option is selected, Event Log will use the
	following time tags to show the time that the event is
	triggered.
	LW-9450: time tag of event log – second (range: $0^{\sim}59$ )
	LW-9451: time tag of event log – minute (range: 0~59)
	LW-9452: time tag of event log – hour (range: $0^2$ 23)
	LW-9453: time tag of event log – day (range: $1^{\sim}31$ )
	LW-9454: time tag of event log – month (range: $1^{\sim}12$ )
	LW-9455: time tag of event log – year (range: 1970~2037)
	Please note that the system will not be able to use these
	time tags when one of them exceeds acceptable range.
	Click the icon to download the demo project. Please
	confirm your internet connection before downloading the
	demo project.
Keyboard	The window number in which the keyboard is placed.
	When using Numeric Input or ASCII Input objects, the type
	of keyboards can be selected. Up to 32 keyboards can be
	added. To design a keyboard, a window should be
	designated for creating it. Press [add] after creating and
	add the window to the list.
	See "12 Keyboard Design and Usage".
	External keyboard layout
	The available USB keyboard layouts are QWERTY, AZERTY,
	and Cyrillic. System register LW-9199 allows switching
	keyboard layouts on HMI.
	Caret color / Select color
	This setting is applicable for eMT, iE, XE, mTV, and iP Series.
	Set the color of caret that appears when entering data in
	Numeric Input and ASCII Input objects or change the
	selection color.
Project	Projects can be restricted to be executed by a specific HMI.
protection	See "30 Project Protection".
Update	This setting is only available on cMT / cMT X Series.
startup	Default
screen on	If an image is already used as startup screen on the HMI,
НМІ	the image will be cleared when this mode is selected.

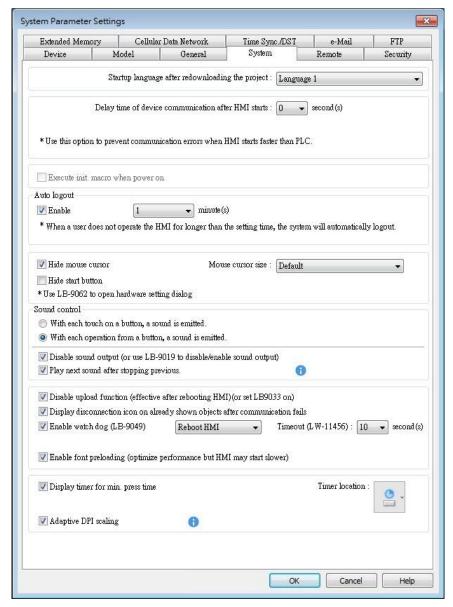


# **Customized**

A .bmp file can be selected as startup screen.

# 5.5. System Setting

[System Setting] is used to configure different features of EasyBuilder Pro.



Some features are duplicated from system registers, such as, [Hide system setting bar (LB-9020)], [Hide mouse cursor (LB-9018)], [Disable buzzer (LB-9019)], and [Disable upload function (LB-9033)]. Users can also set these features via system tag.

To select a system tag, select [Address] » [System tag] check box when adding a new object and then select the [Address Type].

To browse all the system tags, Select [Project] » [Tag] » [System] from the main menu of EasyBuilder Pro.



Cotting	Description
Setting	Description
Startup language after	Set the language to use when HMI starts after
redownloading the	the project is re-downloaded.
project	
Delay time of device	Certain PLC models need relatively longer
communication after	startup time. In order to prevent
HMI starts	communication error that occurs when HMI
	attempts to communicate with a PLC that has
	not yet started, a delay time can be set.  Include delaying the execution of all init.
	Macros when HMI starts.
	With this option selected, the macros that
	have [Execute one time when HMI starts]
	enabled will also be delayed.
Execute init. MACRO	Designate the macro to be executed when HMI
when power on	power on.
Auto logout	If leaving HMI untouched for longer than the
	set time, the objects protected by security
	classes will not be able to operate. The user ID
	and password must be entered again to unlock
	it.
Hide system setting bar /	Hide the system setting bar from HMI screen.
Start Button	
Hide mouse cursor	Hide the mouse cursor in HMI screen.
Mouse cursor size	Set mouse cursor size.
Sound control	With each touch on a button, a sound is
	emitted: With sound enabled in object
	settings, a sound is emitted when the object is touched.
	With Each operation from a button, a sound is
	emitted: When sound is enabled in object
	settings and the [Min. press time] is specified,
	there may be a time gap between touching the
	object and the action of the object. With this
	option selected, the sound is emitted when
	the object actions.
	Disable sound output: Mute HMI. (Not
	including the sound played when tapping
	system setting button on HMI.)
	Play next sound after stopping previous:

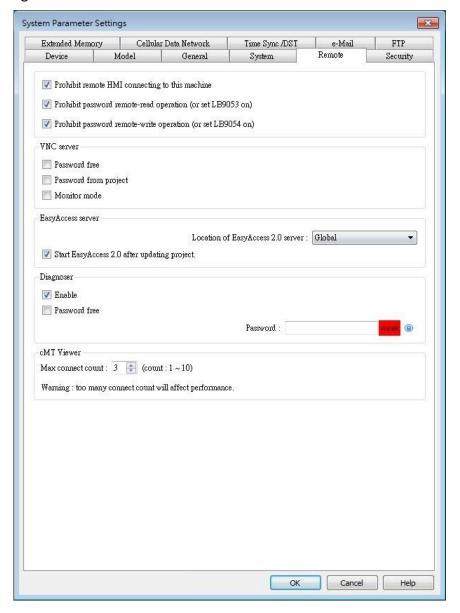


	LANT LANTYC : LAND :
	(cMT / cMT X Series only) When the next
	sound is triggered at the time the current
	sound is playing, the current sound will stop, and the next sound will start.
Disable unless function	
Disable upload function	Disable HMI to upload project.
(effective after rebooting	
HMI) (or set LB9033 ON)	
Use a disconnection icon	If selected, a disconnection icon is
or relative objects when	displayed on relevant objects
device communication	when failing to communicate with
fails	the device.
	This icon will be shown in the
	lower right corner of the
	object.
	This icon will only show for
Fueble wetch de :	disconnection after successful connection.
Enable watch dog	Watchdog automatically reboots the system
(LB-9049)	after the HMI stops functioning for a specified
Fuchle fout westerding	period of time.
Enable font preloading	(cMT / cMT X Series only) With this option selected, the speed of
(optimize performance	With this option selected, the speed of
but HMI may start	changing windows that contain more texts is optimized. Please note that using this feature
slower)	may slow down HMI boot time.
Display timer for min.	(cMT / cMT X Series only)
• •	With this option selected, a countdown timer
press time	is shown when an object with min. press time
	set is being pressed.
Adaptive DPI scaling	With this option selected, the system will
	automatically adjust text size, position, and the
	spacing between Y axes based on the screen
	DPI of the connected device.
	This setting is applicable to Trend Display,
	Circular Trend Display, Mail Contact Editor,
	Option List, Media Player, Alarm Display, and
	Event Display.
	If this option is disabled, certain length-based
	configurations may not accurately reflect on
	different screens.



# 5.6. Remote

Parameters in this tab configure remote connections. Certain functions can be carried out using system registers.



Setting	Description
Prohibit remote HMI connecting to this machine	Prohibit the connection with a remote HMI or cMT Viewer. The remote HMI will not be able to control the local HMI.
Prohibit password remote-read operation (or set LB9053 ON)	Prohibit Remote HMI to read Local HMI's project password and user password.



Prohibit password remote-write operation	Prohibit Remote HMI to write to Local HMI's project password and user password.
(or set LB9054 ON)	
VNC Server	If [Password free] check box is selected, the client can connect with HMI via VNC without entering the password.  If [Monitor mode] check box is selected, the HMI connected via VNC can only be monitored but not controlled.
	If [Password from project] check box is
	selected, set the password for VNC login.
Easy Access server	Location of EasyAccess 2.0 server:  Current location includes Global and China.  Click the icon to watch the demonstration film. Please confirm your internet connection before playing the film.
Diagnoser	Enable
	When selected, cMT Viewer will allow diagnostic operations when connecting to a cMT / cMT X model. System register LB-12656 can also be used to control Diagnoser.  Password free Enabling Disgnoser will not require password login. System Register LB-12657 can also be used to set whether a password is required.  Password Enter the password for logging in Diagnoser. System register LW-11756 (4 words) can also be used to set this password.
cMT Viewer	Max connect count
	Allows specifying the allowable number of cMT Viewer connections for a local cMT / cMT X HMI.

# 5.7. Security

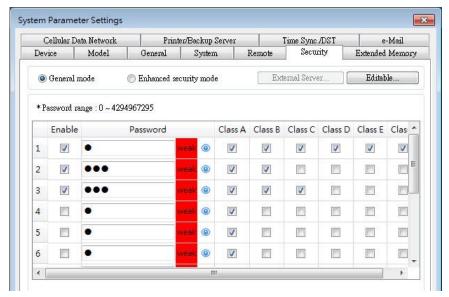
Parameters in this tab configure the user passwords and security classes. There are two authentication modes: General Mode and Enhanced Security Mode.



For more information, see "10 Security".



### 5.7.1. General Mode



Up to 12 sets of user and password are available. Password should be one non-negative integer. Once the password is entered, the objects that the user can operate are classified.

There are six security classes available: A to F.

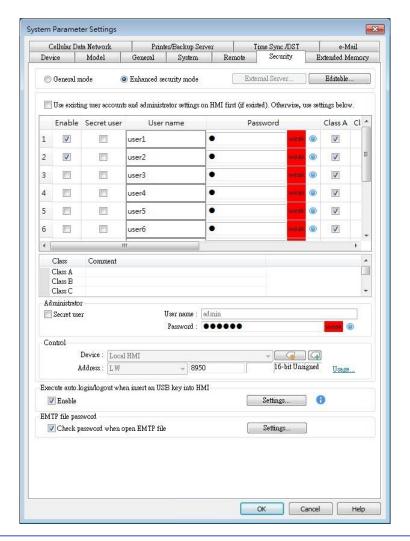
If [None] is selected for an object, every user can access this object.

For example, when the security class of User No. 3 is set as the preceding figure, User No. 3 could only access objects of classes A, B, C and "none".

# 5.7.2. Enhanced Security Mode

At most 11 users can be set here. An [Administrator] user is provided in this mode. An [Administrator] has all privileges and can operate all object classes. User passwords must be alphanumeric, and each user can have up to 12 classes: A to L.





# Setting

# **Description**

### **Editable**

Determines whether other users can change the password settings or see passwords.



# **Enable read-only**

Under this mode, the settings can be viewed but not changed.

# Mask password

Passwords are masked by asterisks (\*).

# Select operable classes for each user

When [Use existing user accounts on HMI] check box is selected, the user accounts existing on HMI will not be erased after downloading the project file to HMI.



Administrator	Default administrator account, cannot be deleted, has all privileges, and cannot be changed. Enhanced Security Mode can be used with Option List object. It displays the account names and privileges. If [Secret user] is checked, the account names and privileges will be hidden in Option List.
Control address	An address for users to manage the accounts directly on HMI.
Project password	When this password is enabled, it has to be entered before editing the project file.  Select [Enable] and then click [Settings] to set the password.
Execute auto. Login/logout when insert an USB key into HMI	This feature allows automatic login / logout using an USB security key. The login / logout status will be written into a designated address. Insert the USB disk to HMI to log in, and remove the USB disk to log out. The result codes of login / logout: 0x00: No action, 0x01: Login succeeds, 0x04: Login fails, 0x08: Logout

# **5.8. Extended Memory**

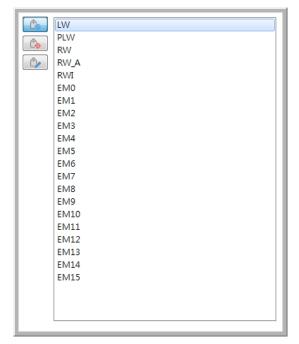
Parameters in this tab determine the location of the extended memory.





Extended Memory is numbered from EM0 to EM15. It works in a way similar to other device types (i.e. LW or RW address). Users can simply select from EM0 to EM15 in the [Address] setting while creating a new object. Maximum allowable data size for each Extended Memory is 2G words.





Data in the extended memory is saved as a file into [SD card] or [USB disk]. By default, the files in [EM0] to [EM15] are with the file names "em0.emi" to "em15.emi" respectively, although users are free to change the file names. To open these files and edit the data in the extended memory, RecipeEditor.exe may be used.

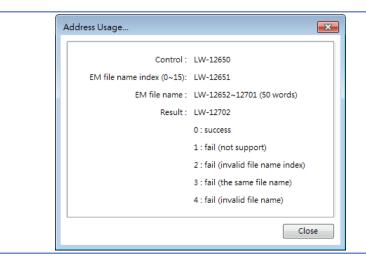
Data in the extended memory will not be erased when HMI power is cut, which means data in the extended memory remains the same as before power off when HMI is started again. This is a behavior similar to recipe data (RW, RW\_A).

When the device used as extended memory does not exist, reading the data in the extended memory will get "0", and writing data to the extended memory will display "Device no response" message on HMI.

Cutting HMI power is not necessary for inserting or removing the external device to or from HMI, making it easy for users to immediately update or obtain data in the extended memory.

Setting	Description
Enable dynamic	With this option selected, the file names of
file name	EM0~EM15 can be changed dynamically. Select "EM
	file name index (0~15)", enter "EM file name", set
	"Control" to 1, and then see the "Result". After
	successfully changing the file name, the new file name
	will immediately be the data source of EM address.
	Please note that after changing the EM file name
	dynamically, the new file name is retained after
	rebooting HMI, which may be different from the file
	name specified in the project file.



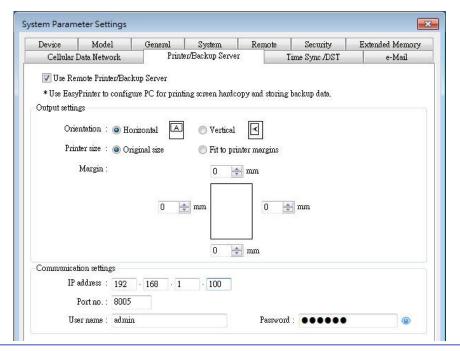


Click the icon to watch the demonstration film. Please confirm your internet connection before playing the film.



# 5.9. Printer / Backup Server

Configure remote printer / backup server. This feature is not supported on cMT / cMT X Series HMI.



Setting	Description
Output	Orientation
settings	Set how will words or pictures be printed out, [horizontal]
	or [vertical].
	Printer size
	Set to print out in [Original size] or to [Fit to printer
	margins].
	Margin
	Set the top, bottom, right and left margin width.
Communication	IP address
settings	Assign the IP address of the printer via network.
	[Port], [User name], [Password]
	Specify the data to log in server.
	Port can be set from 1 to 65535.
	Maximum length of user name or password is 12
	characters.



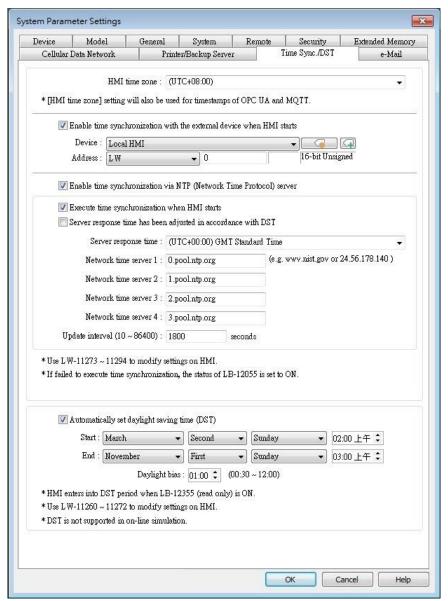
For more information, see "26 EasyPrinter".

Click the icon to download the demo project. Please confirm your internet connection before downloading the demo project.



# 5.10. Time Sync./DST

Configure HMI time synchronization and daylight saving time.



Setting	Description
HMI time zone	Select HMI time zone.
<b>Enable time</b>	Automatically synchronizes HMI time with the designated
synchronization	source address when HMI starts. As shown in the settings
with the external	above, the time source is set to D address of the device
device when HMI	Mitsubishi FX5U, so 6 consecutive word addresses starting
starts	from D-0 will be the source addresses and each of them
	should contain time information as follows:
	D-0 → Second (range: 0~59)



	D-1 → Minute (range: 0~59)
	D-2 $\rightarrow$ Hour (range: 0~23)
	D-3 $\rightarrow$ Day (range: 1~31)
	D-4 $\rightarrow$ Month (range: 1~12)
	D-5 → Year (range: 1970~2037)
Enable time	Execute time synchronization when HMI starts
synchronization	Automatically synchronizes HMI time with the designated
via NTP (Network	NTP server when HMI starts.
Time Protocol)	Server response time
server	Select NTP server time zone.
	Network time server
	Provides four fields to fill in Network Time Servers for user's
	device. If the synchronization with server 1 fails, the system
	will try to synchronize with server 2, and so on. If HMI time
	cannot synchronize with any of the Network Time Servers,
	the system register LB-12055 will change to ON status.
	Update interval
	The frequency of synchronization, the range is from 10 to
	86400 seconds.
Automatically set	Start / End
daylight saving	Set the start/end of Daylight Saving Time.
time (DST)	The option [Last] may refer to the 5 <sup>th</sup> or 6 <sup>th</sup> week depending
	on the selected month.
	Daylight bias
	Set the time zone's offset during DST.



- When DST ends, and the time falls back, the Trend Display object in Real-time mode will stop refreshing for the overlapping hour(s) when it just going back to standard time. However, historical data will not be affected.
- When DST ends, adjusting HMI time (manually or by network) back to the DST period will not be effective to the system. The system register LB-12355 stays OFF.
- When DST ends, and the time falls back, the system will not start DST for the overlapping hour(s). The system register LB-12355 stays OFF.
- Before DST starts, adjusting HMI time (manually or by network) into the DST period will start DST. The system register LB-12355 will be set ON. The HMI time will be the specified time without adding the offset.
- During DST, adjusting HMI time (manually or by network) to a time that is not within DST period will end DST. The system Register LB-12355 will be set OFF. The HMI time will be the specified time without subtracting the offset.



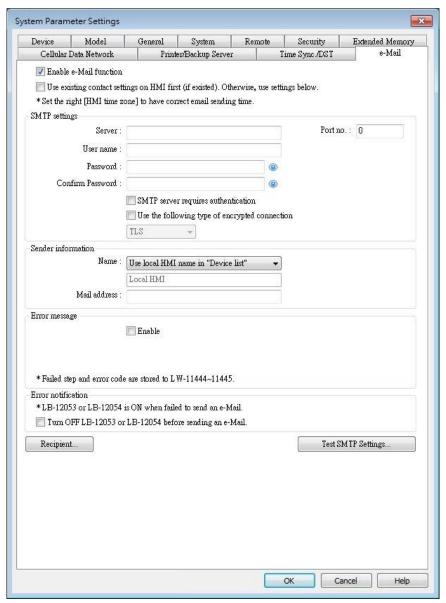
This feature does not yet support the DST in Southern Hemisphere.

For more information on system registers relevant to DST, see "22 System Registers".

### 5.11. e-Mail

Select [Enable e-Mail function] check box to configure the parameters.

When [Use existing contact settings on HMI] check box is selected, the system will use the contact settings in HMI after downloading the project to HMI, or use the following settings when no contact is found in HMI.



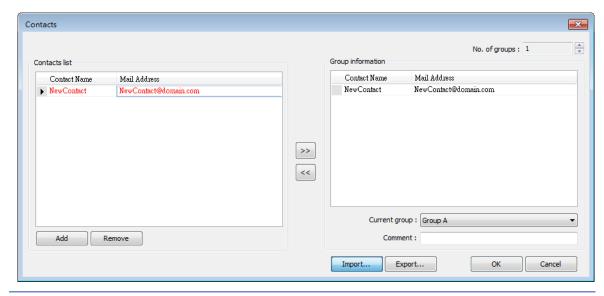
Setting	Description
SMTP Settings	Server: Set SMTP Server.
	Port: Set communication port.



	User name: Set e-mail address.
	Password: Set e-mail password.
	Confirm Password: Confirm e-mail password.
	SMTP server requires authentication:
	Decide whether Secure Password Authentication is needed
	when log in e-mail.
	Use the following type of encrypted connection:
	Decide whether an encrypted connection (TLS, SSL) is
	required when sending e-mails. Please note that TLS
	support is limited to TLS 1.0.
Sender	Name:
Information	Enter the sender name or use the local HMI name in the
	device list, or the name specified using system register
	LW-10884 (HMI name).
	Mail Address:
	Setting e-mail address.
Error message	When an error occurs in email delivery, the error message
	sent from SMTP server can be shown in the designated
	address.
	For more information on system registers relevant to
	mail delivery, see "22 System Registers".
Error	Turn OFF LB-12053 or LB-12054 before send an e-Mail
notification	When enabled, system registers LB-12053 or LB-12054 will
	be turned off before sending e-mail, otherwise, when an
	error occurs in email delivery, the register remains ON.
Test SMTP	Verify SMTP settings in advance by sending a test email to
Settings	the specified e-mail address.
	-

Click [Recipients] to open the following dialog to edit contacts:





Setting	Description
Contact list	Add or remove contacts from the list.
Group	Group up contacts.
Information	No. of groups:
	Set no. of contact groups, according to the number, the
	groups are named from A to P and up to 16 groups can be
	set.
	Current group:
	Displays the group that includes the contacts above.
	Comment:
	Enter a description for the current group.



For more information on sending Event Log, see "7 Event Log".



For more information on e-mail related system registers, see "22.3.40 e-Mail".

Lick the icon to watch the demonstration film. Please confirm your internet connection before playing the film.

Click the icon to download the demo project. Please confirm your internet connection before downloading the demo project.

#### 5.12. **Cellular Data Network**

This tab is for setting cellular data. Cellular data network settings may differ from one model to another.

Applicable models:

cMT X Series models

cMT-SVR (OS ver. 20151127 or later)

cMT3071/cMT3072/cMT3090/cMT3103/cMT3151 (OS ver. 20180723 or later)

cMT-HDM/cMT-FHD/cMT-FHDX (OS ver. 20190130 or later)



# MT8051iP/MT8071iP/MT8102iP (OS ver. 20201007 or later)

Attaching a 3G/4G USB dongle to the USB port enables the cMT-SVR to connect to 3G/4G networks.



Setting	Description
Use existing contact	If this check box is selected, the cellular data currently
settings on HMI	in HMI will be used. When no specific settings are required, generally, [PIN code] is "0000", [APN] is "internet", and [Username], [Password], [Dial number]
	are optional.

# The relevant registers:

LW-11297:	(16 words): PIN code of SIM card (cellular network)
LW-11313:	(16 words): Access Point Name (cellular network)
LW-11329:	(16 words): username (cellular network)
LW-11345:	(16 words): password (cellular network)
LW-11361:	(16 words): dial number (cellular network)
LW-11377:	(16bit): stop (set 0)/start (set 1) connection (cellular
	network)
LW-11378:	(16bit): last error code (0:success, 1:incorrect PIN code,
	2:no SIM, 3:no device, 4:puk locked, 5:other) (cellular
	network)
LW-11379:	(16bit): connection status (0:no device, 1:disconnect,
	2:connecting, 3:connected) (cellular network)

# **USB Tethering**

By connecting an Android® mobile phone with HMI using a micro USB cable, or any USB data cable that is compatible with the phone, the internet connection of the phone can be shared with HMI. On the Android mobile phone please enable USB Tethering.





When successfully connected, the following registers can be used to monitor and control the connection status.

LW-11380: (16bit): stop (set 0)/start (set 1) connection (USB

tethering)

LW-11381: (16bit): connection status (0:no device, 1:disconnect,

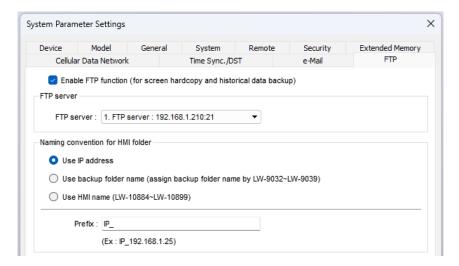
2:connected, 3:fail, 4:OS not support, 5:HMI not

support) (USB tethering)

Click the icon to download the demo project. Please confirm your internet connection before downloading the demo project.

### 5.13. FTP

This tab is for configuring FTP connection parameters. With [Enable FTP function] selected, backup files (screen hardcopy or historical data) can be transferred to FTP server on PC from HMI, in order to achieve the same effect as using EasyPrinter. This feature is only supported on cMT / cMT X Series models.

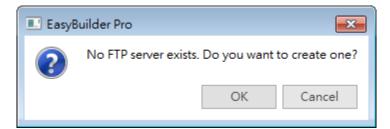




Setting	Description
Enable FTP	With this option selected, backup files (screen hardcopy or
Function	historical data) can be transferred to FTP server.
FTP Server	FTP server's information.
Naming	Use IP address, backup folder name, or HMI name to name
Convention for	the HMI folder.
HMI Folder	<b>Prefix:</b> Add a prefix to the beginning of the folder name.



When FTP function is enabled with no FTP server exists in the project, the FTP Server settings page in Data / History tab will be opened for configuration of FTP connection parameters.





# 6. Window Operations

This chapter describes different types of windows and how to create, set and delete a window.

6.1.	Overview	6-2
6.2.	Window Types	6-2
6.3.	Create, Set, and Delete a Window	6-4
6.4.	Window Transparency	6-8
6.5.	Editing Tips	6-10



# 6.1. Overview

A window is a basic element in a project. With a window, all kinds of information like objects, pictures, and texts can be displayed on HMI screen. In total, 1997 windows numbered from 3 ~ 1999 in EasyBuilder Pro can be built and edited.

# 6.2. Window Types

There are 4 types of windows, each with different functions and usages:

- Base Window
- Fast Selection Window
- Common Window
- System Message Window

#### 6.2.1. Base Window

The most frequently used window, except for main screen, it can also be:

- A background of other windows.
- A keyboard window.
- A pop-up window of Function Key object.
- A pop-up window of Direct Window and Indirect Window objects.
- A screen saver.



Base Window should be in same size as the HMI screen. Therefore, the resolution of the base window should be set to the resolution of HMI.

#### 6.2.2. Fast Selection Window

Window no. 3 is the default Fast Selection Window. This window can co-exist with base window. Generally, it is used to place the frequently-used buttons on the lower-left side or the lower-right side on the screen. Please create window no. 3 first, and set the relevant properties in [System Parameter Settings] » [General] tab. Apart from showing or hiding fast selection window with the button on the screen, there are system registers to do so:

[LB-9013] hide (set ON)/show (set OFF) Fast Selection window

[LB-9014] hide (set ON)/show (set OFF) Fast Selection button

[LB-9015] hide (set ON)/show (set OFF) Fast Selection window/button



cMT / cMT X Series does not support Fast Selection Window.

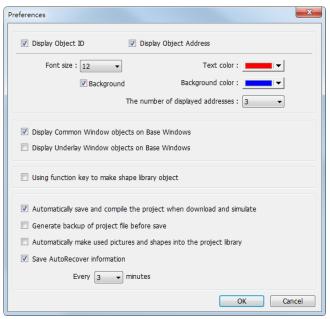


#### 6.2.3. Common Window

Window no. 4 is the default Common Window. Objects in this window will be displayed in other base windows, not including pop-up windows. Therefore, the common objects in different windows are often placed in common window.

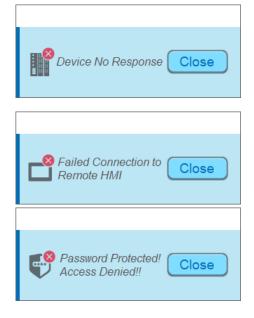
When operating HMI, select [Function Key] » [Change common window] to change the source of common window.

In menu [File] » [Preferences] » [Display] select whether or not to [Display Common Window objects on Base Windows] when editing a project. This can avoid overlapping objects in base window with objects in common window.



# 6.2.4. System Message Window

Windows No. 5, 6, 7, 8 are the default System Message Windows:



#### Window No. 5: Device No Response

When the communication between device and HMI is disconnected, this message window will pop up automatically right on the base window currently opened. This window can be disabled by system registers.

### Window No. 6: HMI Connection

When failing to connect HMI with a remote HMI, this message window will pop up automatically.

#### Window No. 7: Password Restriction

When attempting to control an object without authorization, this window may pop up as a warning depending on the settings of the object.





# **Window No.8: Storage Space Insufficient**

When HMI flash memory, USB disk or SD card run out of storage space, this message window will pop up automatically. (When the memory space is under 4 MB)

The following system registers can be used to check the free memory space in HMI, USB disk, or SD card:

[LW-9072] HMI current free space (K bytes)

[LW-9074] SD current free space (K bytes)

[LW-9076] USB disk current free space (K bytes)

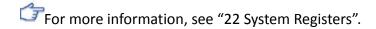
To check if there is sufficient storage in the devices, the following system registers can be used.

These addresses will set ON when the space is under 4 MB.

[LB-9035] HMI free space insufficiency alarm (when ON)

[LB-9036] SD card free space insufficiency alarm (when ON)

[LB-9037] USB disk free space insufficiency alarm (when ON)



The text shown in windows no.  $5 \sim 8$  can be edited for easier reference.



- For eMT/iE/XE/mTV models, a screen can display up to 24 pop-up windows simultaneous including System Message Window, Direct Window and Indirect Window. For cMT/cMT X Series, the number of pop-up windows is not limited.
- The system does not allow opening the same window (including overlay windows) with two Direct / Indirect Windows in one base window.
- Windows no. 3 to 9 are used by the system only, and windows no. 10 to 1999 can be edited based on actual usage.

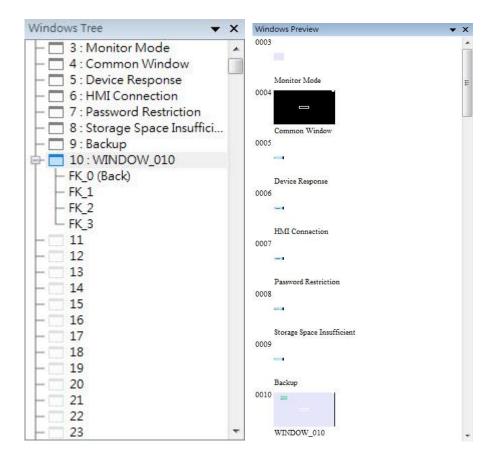
# 6.3. Create, Set, and Delete a Window

Check the existing windows in [Windows Tree].

[Windows Tree] displays window numbers and window names. Opened windows are marked with icon. Press the (+) sign to see the object ID, address and description of the objects used in this window.

[Window preview] displays the thumbnails of windows.

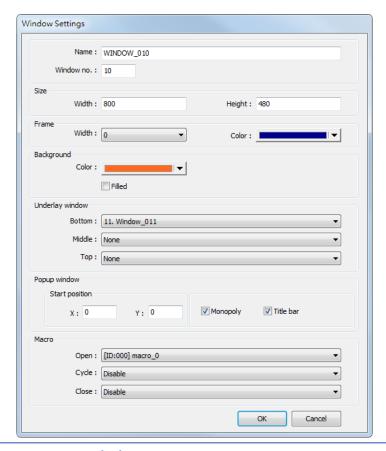




# 6.3.1. Creating and Setting a Window

In windows tree right click on a window number then select [New].





Setting	Description
Name	The name appears on the title bar and also in windows tree.
Window no.	Can be 3 to 1999.
Size	Set the window size in accordance with the HMI resolution.
Underlay	Underlay Window can be seen as an extra Common
window	Window. When designing the project, some commonly
	used objects are used in some windows but not all. These
	objects can be placed in underlay window.
	Each base window can set three underlay windows as
	background, from [Bottom] to [Top]. The objects in underlay
	windows are displayed in this order in base window.
Pop-up	Base window can also be used as a pop-up window. Use [X]
window	and [Y] to set the coordinates indicating where in the screen
	will this base window pop up. The origin of the coordinates
	is the upper-left corner of the window.
Monopoly	If the option is selected, when the base window pops up, no
	operations of other pop-up windows and background
	windows are allowed until the monopoly window is closed.
	If a base window is used as a keyboard window, "Monopoly"
	is automatically enabled.
Title bar	If the option is selected, a title bar appears on a system
	message window. This feature is only available for system

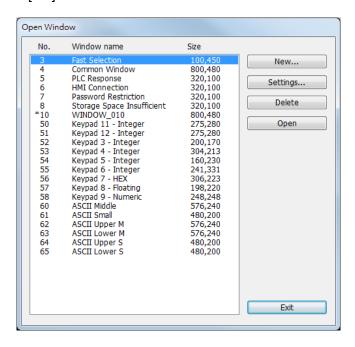


	message windows no. 5 to no. 8.
Macro	Select the macro to be executed when the window opens or
	closes, or the macro to be executed periodically (each 500
	ms).
	Please build the macro in advance.



- The objects in underlay window cannot be edited from the base window that displays them. To edit those objects, please open the underlay window where they are located.
- When the window number of the underlay window used by the base window is identical to the pop-up window, the pop-up window is disabled.
- When base window and pop-up window use the same underlay window, the objects in the underlay window cannot be displayed in pop-up window.
- Click the icon to watch the demonstration film. Please confirm your internet connection before playing the film.

Or, from the main menu click [View] » [Open Window] and then click [New] and select the type of the window and click [OK].



Ways to call up [Window Settings] dialog:

- Right click on the window number in the windows tree and select [Settings].
- In [View] » [Open Window] select the window then click [Settings].
- In the window, right click when no object is selected, and select [Attribute].

#### 6.3.2. Open, Close, and Delete a Window

The ways to open an existing window:

Double click on the window number in the windows tree.



In the windows tree, select the window number, right click, and then select [Open].

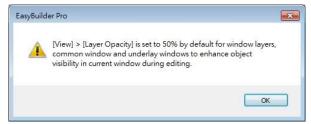
• In [View] » [Open Window] select the window number and then click [Open].

The ways to close or delete an existing window:

- In the windows tree, select the window number; right click, and then select [Close] or [Delete].
- In [View] » [Open Window] select the window number and then click [Delete].

# 6.4. Window Transparency

The Opacity setting in the View tab is used to adjust transparency effect of the common window, overlay windows, and window layers.



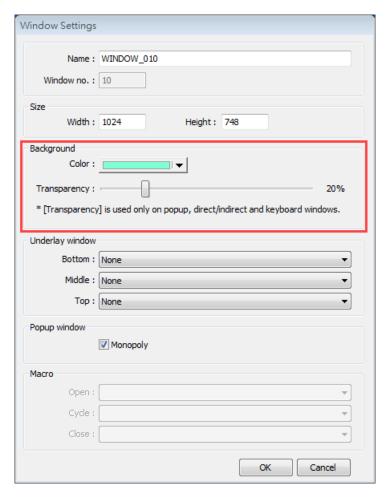
As shown in the following screenshots, greater Opacity makes the object in the relevant window more visible.



Additionally, the cMT / cMT X Series models support setting window transparency. This setting is applicable for popup windows, Direct / Indirect Windows, and keyboard windows. The settings dialog box and the effect are shown in the following screenshots. Greater transparency

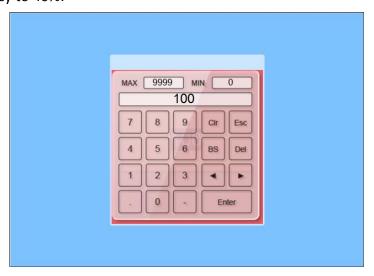


can make the object on the base window more visible when it is covered by the popup window.



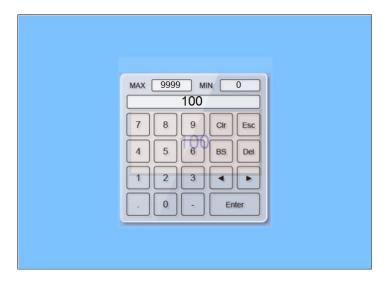
# **Example**

Setting transparency to 40%:



Setting transparency to 90%:





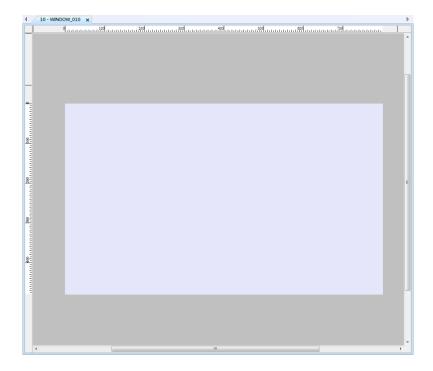
# 6.5. Editing Tips

EasyBuilder Pro provides a user-friendly interface with which users can easily edit projects. The following are some editing tips.

# 6.5.1. Non-display Area, Select Tool, and Hand Tool

As shown in the following screenshot, two areas can be found in the editing window: editing area and non-display area. The non-display area refers to the area outside the editing area (the one in the middle). Objects placed in the non-display area will not be visible on HMI, and communication with devices continues. The invisible objects such as Meter, Time-based Data Transfer, or Text objects used for comments can be placed in this area to avoid overlapping with other objects in the editing area, which adds difficulty to project editing. The objects placed in the non-display area remain effective.







# **Select Tool**

Clicking this icon in the toolbar changes the cursor to the Select Tool. Select a single object by clicking it, or select multiple objects by clicking on an empty part of the editing screen and then drag a box around the objects.



#### **Hand Tool**

Clicking this icon in the toolbar changes the cursor to the Hand Tool. The Hand Tool allows moving through the project screen by simply left clicking the mouse and dragging anywhere.

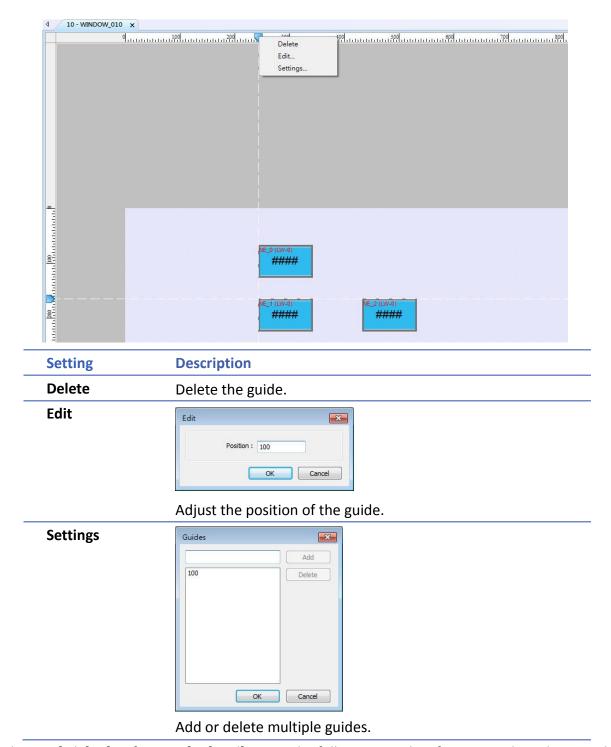
9 409 509 509 509 509 509

# 6.5.2. Ruler

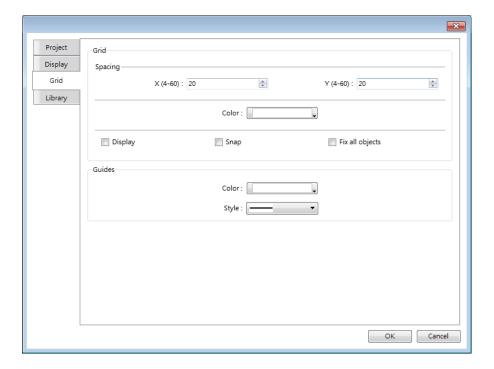


Selecting [View] » [Ruler] adds rulers to the top and left of the editing screen. Guides can be added from the ruler by right click on the ruler. Objects will automatically snap to the guides when moved or resized.



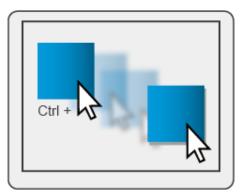


Selecting [File] » [Preferences] » [Grid] opens the following window for setting the color or style of the Guides.



# 6.5.3. Quick Copy

Quick copy can be carried out by pressing and holding Ctrl key on the keyboard while an object is selected, and then drag the cursor to a new location where the object will be created.





# 7. Event Log

This chapter explains how to set and use Event Log.

7.1.	Overview	7-2
7.2.	Event Log Management	7-2
7.3.	Creating a New Event Log	7-9



# 7.1. Overview

The following are the basic steps to use Event Log:

- 1. Define event content and trigger condition.
- 2. Trigger event according to the condition.
- 3. Save the event log to the specified device.
- 4. View the process of event by using the relevant objects.

This chapter will explain how to set and use Event Log.

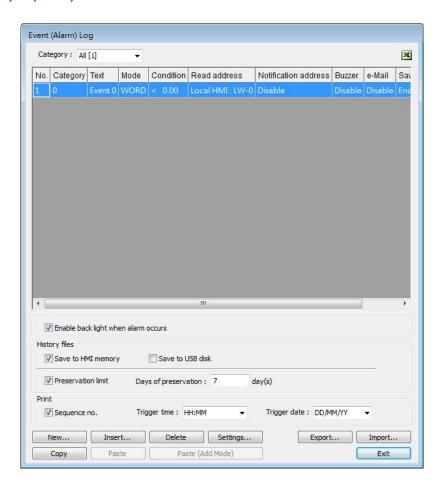
Click the icon to watch the demonstration film. Please confirm your internet connection before playing the film.

# 7.2. Event Log Management

Firstly, define the event content then use Alarm Bar , Alarm Display , Event Display objects to view the process of the whole event from triggering—waiting to be processed—return to normal. The upper limit for the number of event logs is 10000.



# 7.2.1. eMT, iE, XE, mTV, iP Series

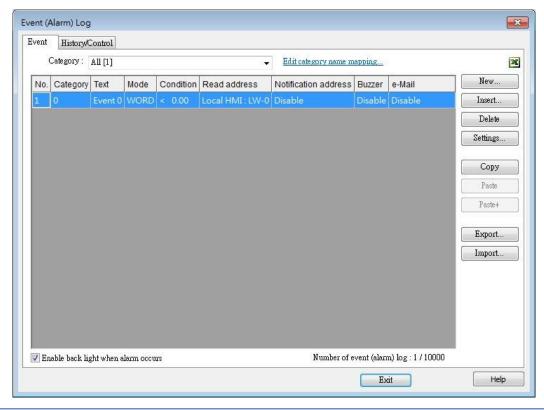


Setting	Description
Category	Classifies events by dividing them into 0 $^{\sim}$ 255 categories.
	Select one category to add or view event log. In the bracket
	"[]", it shows the number of events are in this category.
History	Saves event log files to the specified location. Once an event
files	occurs, the HMI immediately saves the history file. When
	executing On-line or Off-line Simulation on PC, the files will
	be saved in the HMI_memory / SD_card / USB folder under
	the installation directory.
	Preservation limit
	This setting determines the maximum number of Event Log
	files to be preserved in HMI memory. This does not include
	the file generated today. That is, if [Days of preservation] is
	set to 2; the two latest files excluding the file generated today
	will be kept. The files that are not within the range will be
	deleted automatically for saving the storage space.



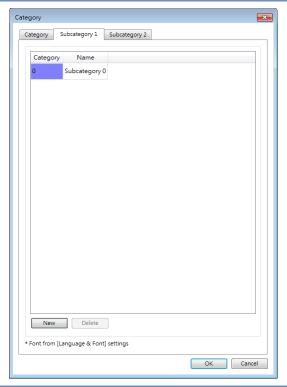
Print	In [System Parameter Settings] » [Model], select a printer and
	set the printing format.
Сору	Copy the selected item.
Paste	Overwrites the selected item with the new items. A message
	window will pop up to confirm this operation.
Paste	Annondo os a novu entru
(Add Mode)	Appends as a new entry.

# 7.2.2. cMT, cMT X Series

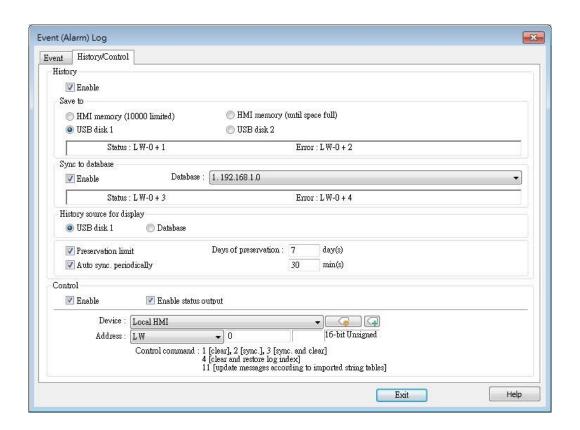


Setting	Description
Category	Classifies events by dividing them into 0 $^{\sim}$ 255 categories.
	Select one category to add or view event log. The number of
	events in this category is shown in the bracket "[]".
	Edit category name mapping Opens a category name table
	which allows editing corresponding category names.
	Subcategories can also be added in this table in addition to
	the exiting categories. The maximum allowable number of
	entries in each subcategory is 256 (0 $^{\sim}$ 255) entries.





Сору	Copies the selected item.
Paste	Overwrites the selected items with the clipboard contents.
	A message window will pop up to confirm this operation.
Paste +	Appends the clipboard contents to the end of the list.





Setting	Description
History	Saves the Event Log data to HMI memory (10000 limited or
	until space full), SD card, USB disk, or database (by
	synchronizing Event Log file to database server).
	The rules of saving the data are:
	When [HMI memory (10000 limited)] is selected, and
	the number of events reaches 10000, the system will
	delete the earliest 1000 events on HMI and keep on
	saving the data to HMI memory
	When [HMI memory (until space full)] is selected, the
	system will keep on saving the data to HMI memory
	without deleting the earlier events. In this case the data
	may not be synchronized to database.
	When USB disk or SD card is selected, and the number of
	events reaches 10000, the system will automatically save
	the data to the external device and delete the earliest
	1000 events on HMI.
	To synchronize the data to database server, select a
	database that has been configured before.
	If the external device already contains some events, the
	new data is appended without overwriting the original
	data each time in synchronization.
	When the external device is removed from HMI, or HMI
	is disconnected from database server, if the connection
	is recovered before the number of events exceeds 9000,
	the events occur during disconnection will be saved to
	HMI. If the number of events exceeds 9000 during
	disconnection, the earlier data will be deleted, and
	cannot be synchronized by recovering connection.
History	Event Log displays the history data read from the designated
source for	
display	source.
Preservation	This setting determines the maximum number of Event Log
limit	files to be preserved in HMI memory. This does not include
	the file generated today. That is, if [Days of preservation] is
	set to 2; the two latest files excluding the file generated today
	will be kept. The files that are not within the range will be
	deleted automatically. The system checks the time of the files



	and deletes earlier files only during synchronization.
Auto sync.	Data will be automatically synchronized to the designated
periodically	external device in the specified time interval, regardless of
	the rules explained above.
	Unit: Minute(s)
	Range: 1~1440
Control	If select [Enable] check boxes under both [Control address]

# address

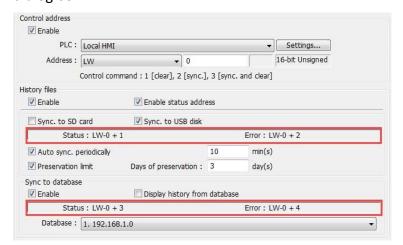
and [History files], entering a specific value in the control address sends the corresponding command.

Value	Command
1	Clear the event log on HMI
2	Synchronize event log to the external device
3	Synchronize event log to the external device and then
	clear the event log on HMI
4	Use the history data stored in USB disk / SD card /
	database after changing HMI
6	Free unused storage space reserved for event logs
	(*.db). This command can be used when historical data
	is saved to HMI memory (until space full).
11	Update event log message contents by reading a new
	String Table

If none of these values is entered, the system will synchronize data in the same rules as [History] setting.

# **Status Error**

When LW-n is used as the control address, the four consecutive addresses following LW-n (LW-n+1~LW-n+4) will show status and error, please see the prompt in the settings dialog box.



Value	Status address: LW-n+1 and LW-n+3
0	Disconnected from external device or database
1	Connecting with external device or database
2	Connected with external device or database



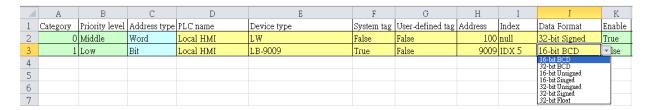
3	Storing records into the archive. When this is done, the
	value returns to 2.
Value	Error address: LW-n+2 and LW-n+4
0	None
1	Unknown error
2	Failed to connect with external device or database
3	Access denied
4	Wrong database name
5	Inconsistent data format
6	Failed to open table
7	Failed to create table
8	Failed to write table
9	Failed to open database
10	Database is corrupted



- Before removing SD card / USB disk, or disconnecting from database server, please synchronize event log data by using control address.
- When monitoring multiple HMIs by using cMT Viewer, the Start Button on the current HMI screen may flash to indicate that an error has occurred on another HMI that is also being monitored, reminding the user to switch HMI and check the event.

# 7.2.3. Excel Editing

Click on the Excel icon in Event Log setting dialog box to open the Excel template for a reference of editing. This template is under the installation directory, the file name is EventLogExample.xls. This template includes the ready-made dropdown lists and validation mechanism.





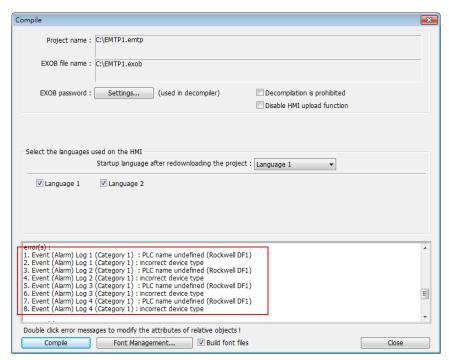
- [System tag] and [User-defined tag] cannot be set to true simultaneously, otherwise, the system will view the User-defined tag to be a System tag, and [User-defined tag] to be false. If setting [Device type] to [User-defined tag], please set [System tag] to false.
- When setting [User-defined tag] to true, if the system compares the [Device type] with the user-defined tag in the system, and no suitable tag is found, the system will set the [User-defined tag] in event log to false
- [Color] format is R:G:B, each should be an integer form 0 to 255.



Before importing Label Library / Sound Library, please make sure the library names exist in the system.

# 7.2.4. Quick View of Errors

When compiling the project, the errors in Event Log will be displayed in the Compile window. To open Event Log and view the errors, double click on the item in the Compile window.

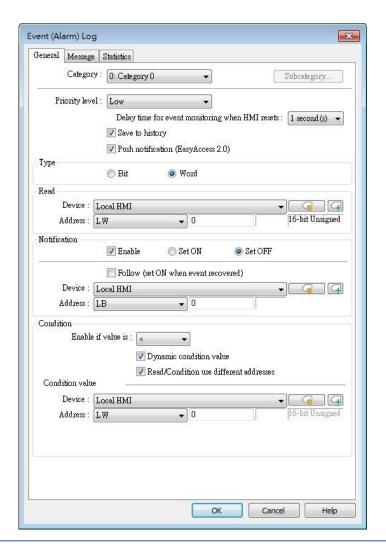


# 7.3. Creating a New Event Log

# **General Tab**

Click [New] in the [Event (Alarm) Log] dialog box.



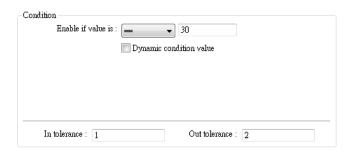


Setting	Description	
Category	Select event category, the range is from 0 to 255.	
Subcategory	Add this Event Log into the subcategories in the category	
	name mapping table.	
	Subcategory	
	-Subcategory 1	
	☐ Enable  ☐ Subcategory 0  ☐ Usubcategory 0	
	Subcategory 2  ☑ Enable 0: Subcategory 0  ▼	
	OK Cancel	
Priority	Events in Alarm Bar / Alarm Display are ordered by priority	
level	level first and then by time.	
Save to	In Event Log main settings, if [Save to HMI memory] check	
history	box under [History files] group box is selected, selecting [Save	
•	to history] here determines whether each separate event	
	should be saved as historical file.	
Push	When an event occurs, EasyAccess 2.0 push notifications can	
	be sent to iOS®/Android® devices.	



notification	
(EasyAccess 2.0)	
Delay time for event monitoring when HMI resets	This feature is used to set the delay time of Event Log after HMI reboot, in order to avoid false alarm that occurs upon HMI reboot due to uninitialized values. This feature is often used with [Dynamic condition value]. The delay time only occurs once upon HMI reboot.
Read address	The system reads data from this address to check if the event matches the trigger condition.
Notification	When enabled, the system will set the specified address ON or OFF when the event is triggered.  Follow
	The notification bit will reset to its original state once the alarm condition returns to normal. For example, when the alarm is triggered, the state of the notification bit turns ON. When the alarm condition returns to normal, and [Follow] check box is selected, the state of the notification bit turns OFF.
Condition	When [Bit] is selected, Event Log will detect the state of a Bit address.  When [Word] is selected, Event Log will detect the value of a Word address to check if it is greater than, less than, or equals to a specified value. See Example 1 and Example 2.  Dynamic condition value
	Allows online change of the comparison value for trigger condition when the condition is a Word address type. If [Read/Condition use different addresses] is not selected, the source of condition value will be the next consecutive address from [Read address].  Read/Condition use different addresses  Allows selecting the Word address type to be the source of condition value.

# Example 1





The setting above indicates:

When [Read address] value is greater than or equals to 29 (= 30 - 1)

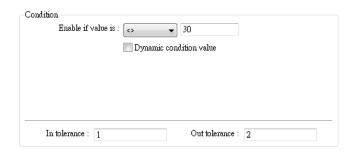
Or less than or equals to 31 (= 30 + 1), the event will be triggered. The trigger condition:

29 ≤ [Read address] value ≤ 31

After the event is triggered, when [Read address] value is greater than 32 = 30 + 2 or less than 28 = 30 - 2 the system will return to normal condition:

[Read address] value < 28 or [Read address] value > 32

# **Example 2**



The setting above indicates:

When [Read address] value is less than 29 (= 30 - 1)

or greater than 31 (= 30 + 1), the event will be triggered. The trigger condition:

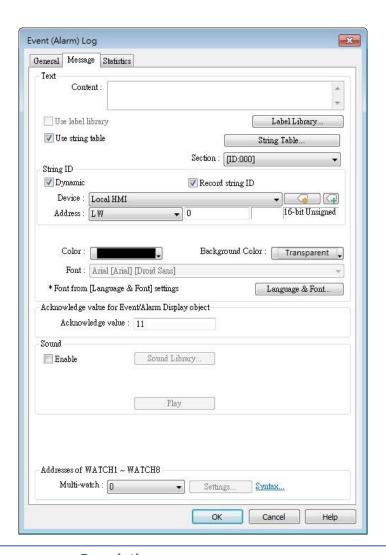
[Read address] value < 29 or [Read address] value > 31

After the event is triggered, when [Read address] value is greater than or equals to 28 (= 30 - 2) or less than or equals to 32 (= 30 + 2) the system will return to normal condition:

28 ≤ [Read address] value ≤ 32



# **Message Tab**



Setting	Description
Content	The text content displayed in [Alarm Bar], [Alarm Display],
	and [Event Display] objects. Use the formats in the
	following two examples of WATCH addresses to use
	register data in content. The content in Label Tag Library
	and String Table can be used in the Event Log message.
String ID	[Event Display] and [Alarm Display] objects display
	messages according to the String ID in the designated
	register.
	Record String ID
	With this option selected, when an event occurs, the
	string's ID number will be recorded. Message of the event
	triggered before can be retained.
Font / Color / Background	The font / color / background color can be set respectively



#### color

for each event. The font and color settings determine how [Alarm Bar] shows the text, while The font, color, and background color settings determine how [Alarm Display] and [Event Display] show the text. These settings are not available in the [Event Display] under History mode.

# Write value for Event/Alarm Display object

When an event in the [Event Display] or [Alarm Display] object is acknowledged, the acknowledge value is written to the specified [Acknowledge] address. This feature can be used with an Indirect Window object's read address so that when the acknowledge value is written, a window pops up as a prompt about how to handle the alarm. As illustrated below, when an event is selected and the acknowledge value is set to 11, window 11 will pop up, displaying the alarm handling prompt.



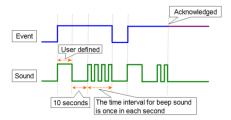
Click the icon to download the demo project. Please confirm your internet connection before downloading the demo project.

# Sound



If enabled, the selected sound will be played when an event is triggered. Continuous beep can also be enabled, which only stops when the event is acknowledged or recovered.

For continuous beep, a delay time can be set between triggering the alarm and the start of beeping.

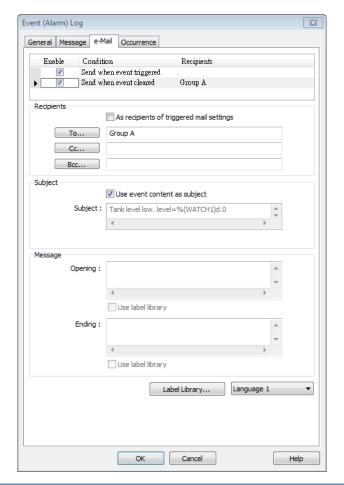




	Click the icon to download the demo project. Please
	confirm your internet connection before downloading the
	demo project.
Address of WATCH 1 ~ 8	Users can set how the value is displayed in the designated
WAICH 1 6	watch address when an event occurs. Up to 8 watch
	addresses can be used simultaneously. Click [Syntax] to
	see how to use the syntax to embed device data in the
	content of an event log displayed in the watch address.
	Click the icon to download the demo project. Please
	confirm your internet connection before downloading the
	demo project.

# e-Mail Tab

Please enable this function in [System Parameter Settings] » [e-Mail] first.



Setting	Description
Recipients	Select the [To], [Cc], and [Bcc] recipients.
Subject	Enter the subject of the e-mail.
Message	Enter the [Opening] and [Ending] content of an e-mail.



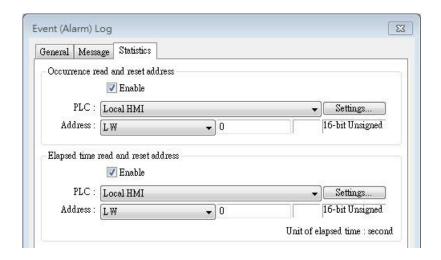
Attach	If the [Contains a screenshot of window] check box is selected, the screenshot of the selected window will be
	attached.



The priority level of an event determines its importance in e-mail delivery.

<b>Event Priority Level</b>	Email Importance
Emergency	High
High / Normal	Normal
Low	Low

#### **Statistics Tab**



Setting	Description
Occurrence	If enabled, the number of occurrence of the event after
read and reset	HMI startup will be written to the designated word
address	address. The word address can be read / written.
Elapsed time	If enabled, from an event occurs to its recovery, the
read and reset	elapsed time (in seconds) will be written to the
address	designated word address. The word address can be read / written.

Click the icon to download the demo project. Please confirm your internet connection before downloading the demo project.

# **Security Tab**

With security settings enabled, an address and a condition can be set so that an event is recorded only when the state of the specified address meets the preset condition.





Setting	Description
Use register	With this option enabled, an event will be recorded only
status/value	when the state of the specified address meets the preset condition.



- When an event is triggered with the security settings enabled, the event can be acknowledged on Event Display or Alarm Display even when the security settings are disabled after the event is triggered.
- With security settings enabled, the event's address will not communicate with the device if the preset condition is not met.



# 8. Data Sampling

This chapter explains how to set and use Data Sampling.

8.1.	Overview	8-2
8.2.	Data Sampling Management	8-2
8.3.	Creating a New Data Sampling	8-2
8.4.	Synchronizing cMT Viewer data and Saving to External Device	8-15
8.5.	Checking History Data of a Specific Date on cMT Viewer	8-15



Data Sampling 8-2

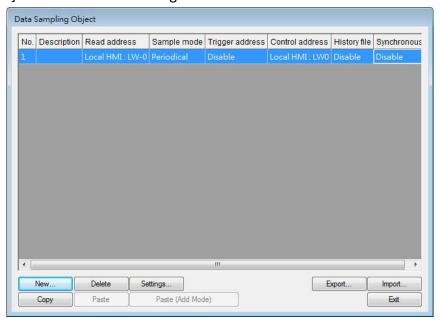
# 8.1. Overview

After defining how the data is sampled, by sampling time, address, or data length, the sampled data can be saved to the designated location, such as HMI memory, SD card, or USB disk. Trend Display and History Data Display objects can be used to display sampling records.

# 8.2. Data Sampling Management

Create a new Data Sampling object first by the following steps:

- 1. From the menu select [Data/History] and click [Data Sampling].
- 2. Click [New] to finish relevant settings.



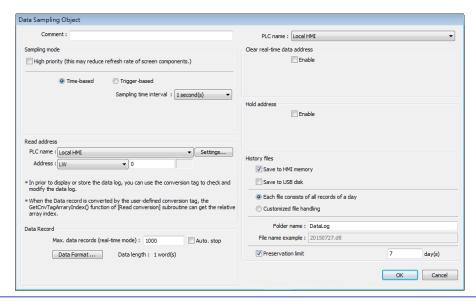
# 8.3. Creating a New Data Sampling

The following introduces how to set a new Data Sampling.

eMT, iE, XE, mTV, iP Series



Data Sampling 8-3



## **Setting**

## **Description**

## Sampling mode

# **High priority**

Data sampling processes with this feature enabled will be prioritized. Please note that too many priorities can slow down update rate of other objects.

#### Time-based

Samples data in a fixed frequency. The [Sampling time interval] can be set from "0.1 second(s) to 120 mins".

#### **Trigger-based**

Triggers data sampling by the status of a designated bit address.

Mode Conditions to trigger Data Sampling:

[OFF -> ON] Triggers sampling when the status of the address changes from OFF to ON.

[ON -> OFF] Triggers sampling when the status of the address changes from ON to OFF.

[OFF <-> ON] Triggers sampling when the status of the address changes.

# Set ON/OFF after triggered

If selected, after triggering Data Sampling, the system will set the designated bit address back to ON/OFF state.

#### Read address

Specify an address to be the source of Data Sampling. To convert a data record, please use a user-defined conversion tag that allows [Read conversion]. For array addresses, the GetCnvTagArrayIndex function can get the relative array index and then calculate.



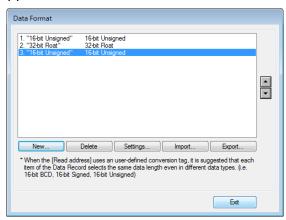
**Data Sampling** 8-4

# **Data Record** (Real-time)

In Real-time Mode, when [Auto. stop] is not selected, the max. number of data records can be saved on HMI is 86400. When the number of records exceeds 86400, the earliest data will be deleted.

#### **Data Format**

Data of different formats in consecutive registers can be sampled. For example, setting: LW-0 (16-bit Unsigned), LW-1 (32-bit Float), and LW-3 (16-bit Unsigned). The upper limit for the number of records is 1000.



#### Auto. stop

Data sampling will automatically stop when the number of records reaches [Max. data records].



See "8.3.1 Demonstration of Auto. stop".

# Clear real-time data address

Set when the bit address status changes from [OFF -> ON] or [ON -> OFF], clear the sampled data in Trend Display Real-time Mode. The number of data records returns zero but the data records that are already saved as history files will not be cleared.

#### **Hold address**

If the status of the designated address is set ON or OFF, sampling will be paused until the status of the designated address returns.

# **History files**

# Save to HMI memory

Saves Data Sampling to HMI every 10 seconds. Or, use system register [LB-9034] to force storing data. See details on the restrictions of using LB-9034 in the Note below.

# Save to SD card / USB disk

Saves Data Sampling to the specified external device.

Each file consists of all records of a day



Data Sampling 8-5

	The data sampling file will be saved on a daily basis into
	the specified folder, and the file name will be
	yyyymmdd.dtl, indicating the date of the file.
	Folder name
	Specify Data Sampling file name which must be all in
	ASCII characters. The folder name will be written as:
	[Storage Location] \ [Folder Name] \ [File Name]
	Preservation limit
	Determines the number of data sampling files to be
	preserved. Please note that the current .dtl file is not
	included in this limit. That is, if this limit is set to 2, apart
	from the current file, two latest files will be preserved.
Customized file	This feature can be used to customize naming and
handling	management of data sampling files (*dtl).
	See "8.3.2 Customized File Handling".

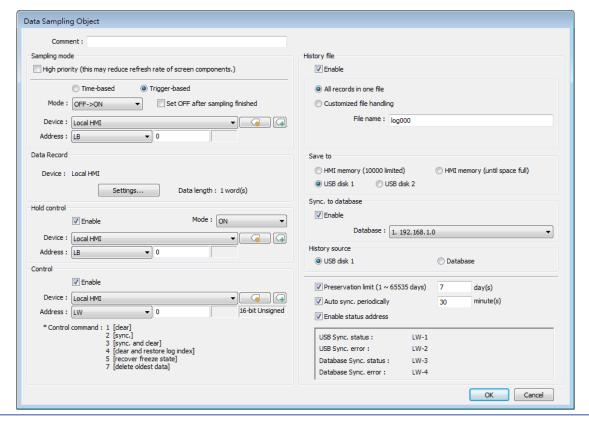


- A Data Sampling may include more than one type of records. Data Sampling can retrieve different types of records at the same time. For example, if define three types of data, 4 words in total, the system retrieves a 4-word data each time from the designated address to be the content in one Data Sampling.
- When using [Each file consists of all records of a day] and set [Preservation limit] to 2 files, the data of yesterday and the day before yesterday will be kept. Data that is not built in this period will be deleted to prevent the storage space from running out.
- When using [Customized file handling] and set [Preservation limit] to 2 files, not only the currently sampled file, another 2 newest files (3 files in total) will be kept. The rest of the data will be deleted to prevent the storage space from running out.
- When running simulation on PC, all data sampling will be saved to the datalog folder in C:\EBPro\[Storage Location]\datalog. If you change the data format of data sampling, delete the previous data records in the installation directory to prevent the system from reading the old records.
- When saving files to USB disk or SD card, the capacity of a FAT32 folder depends on the length of the file names. Fewer files can be saved when the file names are longer.
- When using LB-9034, the shortest interval between two successful executions is 2 seconds.
   That is, after LB-9034 is triggered, it can be effective again 2 seconds later.
  - Click the icon to watch the demonstration film. Please confirm your internet connection before playing the film.

# cMT, cMT X Series

The settings are almost similar to eMT, iE, XE, mTV, iP Series. The following highlights the settings that are different.





# **Setting**

# **Description**

#### **Data Record**

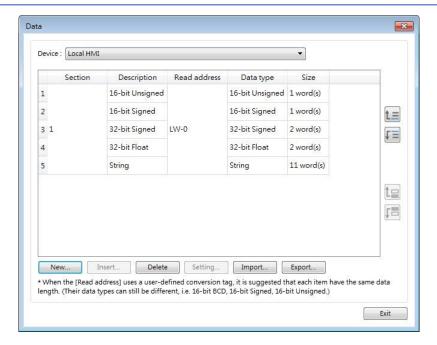
Data of different formats can be sampled. The upper limit for the number of records is 1000. Click the [Settings...] button to set the read addresses of different data types. For selected PLC drivers, sampling addresses of different sections is possible. For the drivers that can only sample contiguous addresses, simply set the data types. The display format settings may be used by Trend Displays and History Data Displays which are set to display the sampled data.

# **Next contiguous address**

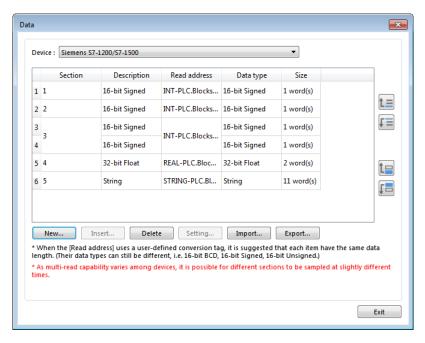
With this option selected when adding a new item, simply set the data type and it will be put into the same section as the previous read address. The following setting aims to read LW-0~LW-17 at a time.



Data Sampling 8-7

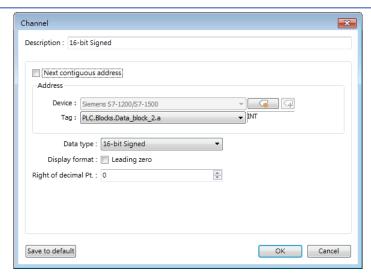


When [Next contiguous address] option is **not** selected, multiple addresses can be read at a time.



Click [New] and de-select [Next contiguous address] option. The address setting shows, and a different address can be selected.

Data Sampling 8-8



Please note that when contiguous address setting is used for a tag-based PLC driver, only one-dimensional arrays are supported.

## Control address

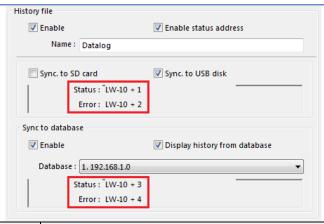
Entering a value in the control address sends the corresponding command.

Value	Command
1	Clear the sampled data in HMI.
2	Synchronize data to the external device / database.
3	Synchronize data to the external device / database
	and then clear the sampled data in HMI.
4	Use the history data stored in USB disk / SD card /
	database after changing HMI.
5	As data sampling stops when HMI storage is full, this
	command allows restarting of data sampling when
	there's free space.
6	Free up memory space reserved for data logs (*.db).
	This command can be used when historical data is
	saved to HMI memory (until space full).
7	Delete the oldest data (*.db).

# Status & Error address

When LW-n is used as the control address, the four consecutive addresses following LW-n (LW-n+1~LW-n+4) will show status and error, please see the prompt in the settings dialog box.





Value	Status address: LW-n+1 and LW-n+3	
0	Disconnected from external device or database	
1	Connecting with external device or database	
2	Connected with external device or database	
3	Storing records into the archive. When this is done,	
	the value returns to 2.	
Value	Error address: LW-n+2 and LW-n+4	
0	None	
1	Unknown error	
2	Failed to connect with external device or database	
3	Access denied	
4	Wrong database name	
5	Inconsistent data format	
6	Failed to open table	
7	Failed to create table	
8	Failed to write table	
9	Failed to open database	
10	Database is corrupted	
11	The Row ID from the external device is inconsistent	
	with the internal Row ID.	

#### **History files**

History data can be saved to HMI memory (10000 limited or until space full), USB disk, SD card, and Database (by synchronizing history data to database server.).

The rules of saving the data are:

 When [Save to HMI memory (10000 limited)] is selected and the sampled data reaches 10000 records, the system will delete the earliest 1000 records and keep on saving data to HMI memory.

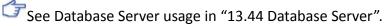


Data Sampling 8-10

 When [Save to HMI memory (until space full)] is selected, the system will keep on saving data to HMI memory, in this case, the data may not be synchronized to database server. When the HMI memory storage is full, the system will delete the earliest 1000 records and keep on saving data to HMI memory.

- When USB disk or SD card is selected, and the number of records reaches 10000, the system will automatically save the sampled data to the external device and delete the earliest 1000 records on HMI.
- To synchronize the data to database server, select a database that has been configured before.

See synchronization rules in "8.4 Synchronizing cMT Viewer data and Saving to External Device".



# Customized file handling

This feature can be used to customize naming and management of data sampling files (\*db). The current \*db file is saved in HMI memory. Please note the following two points when Sync. Destination is USB disk / SD card:

- When \*db file name changes, the \*.db file with the former name will be synchronized to USB disk / SD card.
- 2. If a new \*db file is generated when there's no existing USB disk / SD card on HMI, the earlier \*db file will be deleted. For example, if 20161218.db is the current file, when 20161219.db is generated and no external device is inserted to HMI, and then 20161218.db will be deleted. When [Customized file handling] is used, enabling [Sync. to database] is not possible.



## Auto sync. periodically

Data will be automatically synchronized to the designated external device in the specified time interval, regardless of the rules explained above. Please note that the timer will reset when a control address is used.

See "8.4 Synchronizing cMT Viewer data and Saving to External Device or Database Server".



All record in	When Sync. Destination is USB disk / SD card, the
one file	preservation limit is 1 to 65535 days.
Customized file	When Sync. Destination is USB disk / SD card, the
handling	preservation limit is 1 to 65535 files.
	When Sync. Destination is HMI memory, the preservation
	limit is 1 to 1000 files.
History source	Data can be read from USB disk, SD card, or Database.

#### 8.3.1. Demonstration of Auto. stop

This feature depends on the arrangement of different objects and modes. (Set [Max. data records] to n.)

Object	[Auto. stop] not selected	[Auto. stop] selected
Trend Display- Real time	Deletes the earlier records and displays the latest number of records (n) in Trend Display. See the following figure.	Stops after reaching the specified number of data records (n).
Trend Display- Historical	Keeps on sampling data and displays all history data in Trend Display.	Stops after reaching the specified number of data records (n).
History Data Display	Keeps on sampling data and displays all history data in History Data Display.	Stops after reaching the specified number of data records (n).
Data Sampling	Keeps on sampling new data.	Stops after reaching the specified number of data records (n).

The figure illustrates how the data is sampled in Trend Display – Real Time mode when [Auto. stop check] box is not selected. Set the number of data records to 10, when the 11<sup>th</sup> data is generated, the earliest record is deleted and the newest record is added.

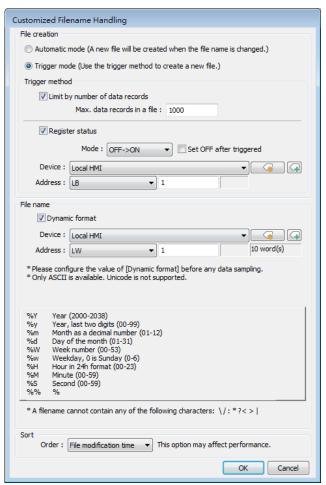


Data Sampling 8-12

Record Number	Data	Not selecting [Auto. stop]
1	101	102
2	102	103
3	103	104
4	104	105
5	105	106
6	106	107
7	107	108
8	108	109
9	109	110
10	110	111
11	111	

#### 8.3.2. Customized File Handling

This feature can be used to customize naming and management of data sampling files (\*.dtl, \*db).





Data Sampling 8-13

Setting	Description
File creation	Automatic mode
	A new file will be created when the name of an existing
	file is changed.
	Trigger mode
	A new file will be created according to the [Trigger
	method] settings.
Trigger method	Limit by number of data records
	A new file will be created when the number of data
	sampling records reaches the specified "Max. data
	records in a file"
	Register status
	A new file will be created when the status of a designated
	bit address meets the specified condition. The condition
	is specified in Mode field.
	Set ON/OFF after triggered
	If selected, after the new file is created, the system will
	set the designated bit address back to ON/OFF state.
	Following HMI reboot, generate and write to a new file
	only after trigger condition has been met.
	When the trigger condition has not been met following
	HMI reboot and therefore no new file is generated, the
	new data will be written to the last file generated before
	HMI is rebooted. Downloading a new project to HMI is
	the same as rebooting HMI.
	the same as resouting min
File name	The file name can be an alphanumeric name, and certain
File name	The file name can be an alphanumeric name, and certain
File name	The file name can be an alphanumeric name, and certain
File name	The file name can be an alphanumeric name, and certain half-width symbols are allowed. The file name can also be
File name	The file name can be an alphanumeric name, and certain half-width symbols are allowed. The file name can also be specified by a file name syntax.
File name	The file name can be an alphanumeric name, and certain half-width symbols are allowed. The file name can also be specified by a file name syntax.  Dynamic format
File name	The file name can be an alphanumeric name, and certain half-width symbols are allowed. The file name can also be specified by a file name syntax.  Dynamic format  The file names can be set by a designated word address,
File name	The file name can be an alphanumeric name, and certain half-width symbols are allowed. The file name can also be specified by a file name syntax.  Dynamic format  The file names can be set by a designated word address, or by a file name syntax indicating the current system
File name	The file name can be an alphanumeric name, and certain half-width symbols are allowed. The file name can also be specified by a file name syntax.  Dynamic format  The file names can be set by a designated word address, or by a file name syntax indicating the current system time. The file name syntax can be specified by selecting
File name	The file name can be an alphanumeric name, and certain half-width symbols are allowed. The file name can also be specified by a file name syntax.  Dynamic format  The file names can be set by a designated word address, or by a file name syntax indicating the current system time. The file name syntax can be specified by selecting time buttons or entering the syntax in Format field. The length limit is from 1 to 25.
File name	The file name can be an alphanumeric name, and certain half-width symbols are allowed. The file name can also be specified by a file name syntax.  Dynamic format  The file names can be set by a designated word address, or by a file name syntax indicating the current system time. The file name syntax can be specified by selecting time buttons or entering the syntax in Format field. The
File name	The file name can be an alphanumeric name, and certain half-width symbols are allowed. The file name can also be specified by a file name syntax.  Dynamic format  The file names can be set by a designated word address, or by a file name syntax indicating the current system time. The file name syntax can be specified by selecting time buttons or entering the syntax in Format field. The length limit is from 1 to 25.  The following half-width characters are not allowed:



and backup logic.

#### File name

Files are sorted by their filenames in descending order.

#### File modification time

Files are sorted by the actual timestamps of the contents. (Because the system has to check the content of the files, this option may affect performance negatively.)

#### Example:

Consider the case where files have been generated in this order: filename\_05--> filename\_04--> filename\_03--> filename\_02--> filename\_01. The earliest file is filename\_05 and the latest file is filename\_01. With preservation limit set to 5 files, the two sorting methods yield different results when the 6<sup>th</sup> file is generated:

Sorted by Filename: filename\_05 is seen as the latest file; therefore, filename\_01 will be deleted.

Sorted by File Modification Time: filename\_01 is seen as the latest file; therefore, filename\_05 will be deleted. Note on naming convention:

When File Name is selected as the sorting method and the filenames are: filename\_1, filename\_2, and filename\_10, filename\_2 will be seen as the latest file, followed by filename\_10 and filename\_1. To make filename\_10 the latest file, please zero-pad the numbers and name the files to: filename\_01, filename\_02, and filename\_10.



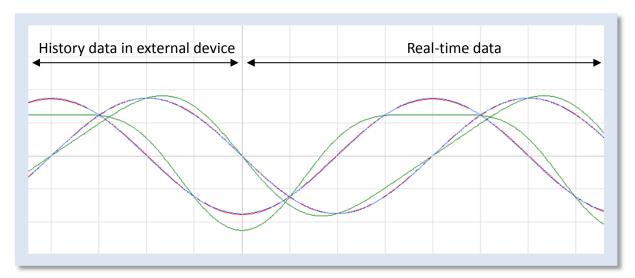
- If both [Limit by number of data records] and [Dynamic format] check boxes are selected, before startup HMI, please enter the name in the designated register for Dynamic Format, otherwise, it is impossible the reach the "Max. data records in a file", and the data sampling file will not be generated.
- When a new file is generated, the system will first detect if the filename already exists. If the file name does exist, the newly sampled data will be appended to the existing file.

Click the icon to download the demo project. Please confirm your internet connection before downloading the demo project.



Data Sampling 8-15

#### 8.4. Synchronizing cMT Viewer data and Saving to External Device or Database



For other series, when displaying the sampled data in Trend Display object, it is necessary to select from Real-time mode or History mode and the two modes cannot simultaneously be displayed in one object.

cMT / cMT X Series allows displaying history data and at the same time updates real-time data in one Trend Display or History Data Display object. The data saved in the external device can be updated.

The rule of synchronizing the data saved in the external device:

- 1. When the sampled data reaches 10000 records, HMI will automatically save data to the external device and deletes the earliest 1000 records in HMI.
- 2. If the external device is removed from HMI and inserted back again at the time when the sampled data is under 9000 records, the data generated during the time the external device is removed is saved in HMI and is not cleared. If the data exceeds 9000 records during the time the external device is removed, the earlier data is cleared and cannot be synchronized even to insert the external device back to the HMI.
- 3. If there already exists sampled data in the external device, the new data is appended without overwriting the original data each time in synchronization.

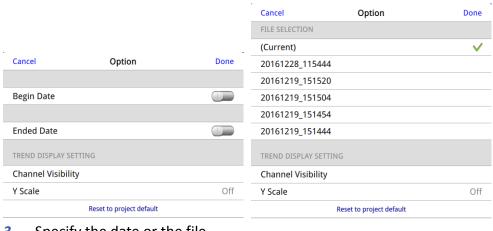
#### 8.5. Checking History Data of a Specific Date / File on cMT Viewer.

To check the history data, see the following steps (Use Trend Display object as example).

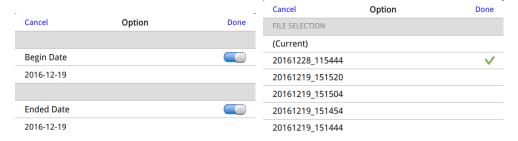
- 1. Tap the icon in the upper-right corner of the Trend Display object.
- 2. The following dialog box appears.



8-16 **Data Sampling** 



Specify the date or the file. 3.



Tap [Done] button to finish setting.



# 9. Object General Properties

This chapter explains the basic settings of an object.

9.1.	Overview	9-2
9.2.	Selecting PLC and Setting Read/Write Address	9-2
9.3.	Using Shape Library and Picture Library	9-3
9.4.	Setting Label Text	9-7
9.5.	Adjusting Profile Size	9-9
9.6.	Overlapping Objects (cMT / cMT X Series)	9-10



#### 9.1. Overview

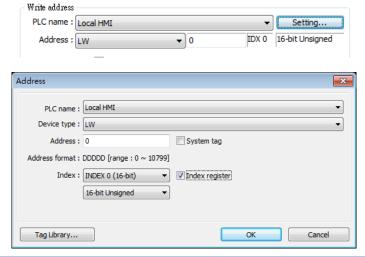
The basic steps to create an object:

- Selecting the PLC device and setting the read/write address.
- 2. Using Shape Library and Picture Library.
- 3. Setting label text.
- 4. Adjusting profile size.

This chapter explains the basic settings of an object.

## 9.2. Selecting PLC and Setting Read/Write Address

Most objects read data from PLC devices, so a properly configured PLC address is needed. Select the PLC to control at [PLC name] which comes from [System Parameters Settings] » [Device List].



Setting	Description
PLC name	Select the PLC type.
Device type	Different PLCs have different device types.
Address	Set the read/write address.
System tag	Address tags include [System Tag] and [User-defined Tag].
	This option allows users to use [System Tag]. [System Tag]
	consists of the preserved addresses by system for
	particular purposes. The address tags include bit registers
	or word registers (LB or LW).
	After selecting [System tag], not only will the [Device type]
	field display the chosen tag, but [Address] field will also
	display the chosen register.

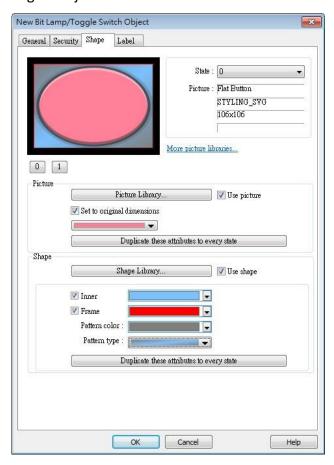


**Index register** Select this check box to use the [Index Register].

- For more information about System Tag, see "22 System Reserved Words and Bits".
- For more information about Index Register, see "11 Index Register".
- For more information about Tag Library, see "16 Address Tag Library".

### 9.3. Using Shape Library and Picture Library

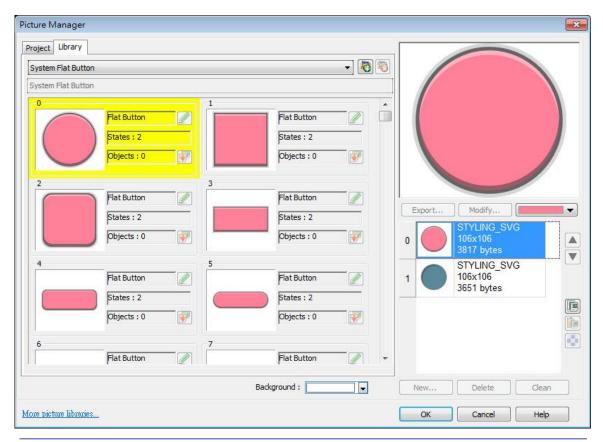
In the settings dialog box of certain objects, "Shape" tab can be found. In this tab, Shape Library and Picture Library can be used to add visual effects on objects. Select Shape tab to use the libraries when creating an object.



#### **9.3.1.** Picture

Select [Use picture] and then click [Picture Library] button to open Picture Manager window and select a picture from the window.



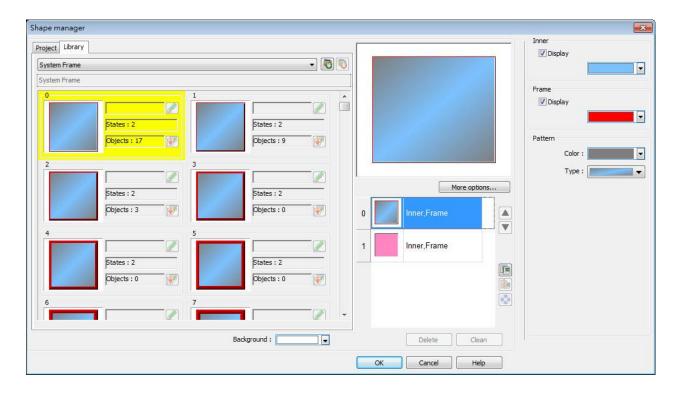


Setting	Description
Picture	Click [Picture Library] button in Picture group box to open
Library	Picture Manager window.
Set to original dimensions	When this checkbox is selected, EasyBuilder will return the picture to its original size to eliminate the redrawing step.
Duplicate these	This button is available only when a system picture is used.
attributes to	Clicking this button will duplicate the attributes of the
every state	current picture to other states.

#### 9.3.2. Shape

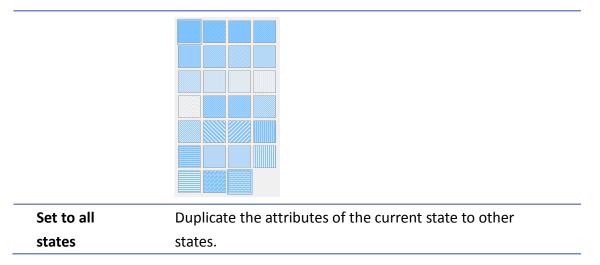
Select [Use shape] and then click [Shape Library] button to open Shape Manager window and select a shape from the window.





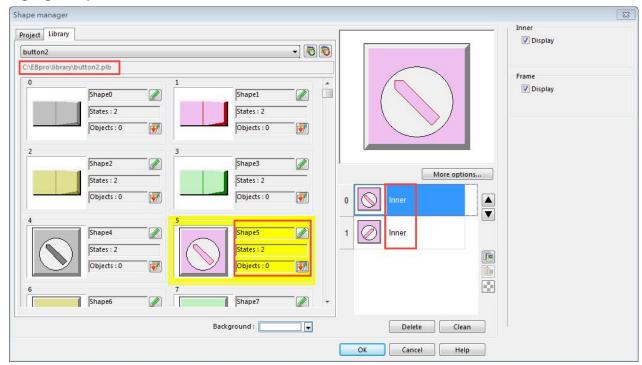
Setting	Description
Inner	Select [Display] to show the inner color of the shape and
	select a color as the inner color by clicking the drop-down
	button.
	Default
	Recent
	Custom
Frame	Select [Display] to show the frame color of the shape and
	select a color as the frame color by clicking the drop-down
	button.
Pattern color	Click the drop-down button to select a color for the
	interior pattern of the shape.
Pattern type	Click the drop-down button to select a pattern.





#### 9.3.3. Shape manager

In Picture Manager and Shape Manager windows, the currently selected picture / shape is highlighted yellow as shown below.



The information about the selected picture / shape:

Directory The directory from which EasyBuilder searches for the pictures / shapes.

Shape5 Name of the shape.

States: 2 Number of states of the shape.

Objects: 1 This shape is used by 0 object in the project.

Inner The state 0 and state 1 of this shape contain only "inner" but not "frame."

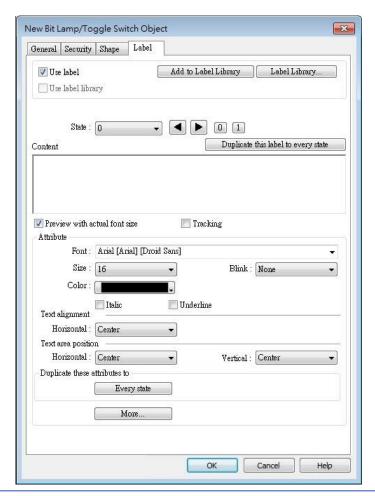


For more information, see "14 Shape Library and Picture Library".



Object General Properties 9-7

## 9.4. Setting Label Text



Setting	Description
Use label	Use a label for the object.
	Add to Label Library
	Add a new label containing the content for all states to the
	Label Library.
Use label library	Use a label from the Label Library.
<b>Label Library</b>	View all the labels in the Label Library.
	For more information, see "15 Label Tag Library and Multi
	Language".
Content	Set the content of the label. If [Use label library] is
	selected, the content in the Label Library can be used.
Duplicate this	
label to every	Copy the content of the current state to all states.
state	
Tracking	With this option selected, changing the position of the



	text in one state will also change the text position in othe states.	
Font	Select a font from the list. EasyBuilder Pro supports Windows True-type fonts.	
Size	Select a font size.	
Color	Select a font color.	
Blink	Specify the way the text blinks. Choose [None] to disable	
	this feature or set the blinking interval to [1 second] or	
	[0.5 seconds].	
Italic	Use Italic font. Italic Label	
Underline	Use Underline font. <u>Underline Label</u>	
Text Alignment	Multiline text is aligned within the label outline.	
	Relow are the corresponding shortcut keys.	
	[Left] [Center] [Right]	
	111 111 111 222222 22222 22222 33333333 333333333 33333333	
Text area	Multiline text is aligned within the object outline.	
position	Below are the corresponding shortcut keys.	
	→ → → → → L1 L2 L3 L4    ← Left Alignment  →   Right Alignment  →   Right Alignment	
	Horizontal Vertical	
Duplicate these		
attributes to	Copy the attributes of the current state to all states.	
every state		
More	Convert labels to bitmap images (Use bitmap font)	
	Convert the label text into bitmap format. This setting is	
	only available for non-cMT models.	
	ON = OFF (use state 0)	
	The content displayed will not change due to state.	
	Movement:	
	Direction	



Set the direction of the marquee effect. The directions include: [No movement], [Left], [Right], [Up], [Down].

#### **Continuous**

Specify how the marquee effect is displayed.

If this option is not selected, the next text appears only when the previous text disappears completely.



If this option is selected, the text will be displayed continuously.



#### **Speed**

Adjust the speed of the text movement.



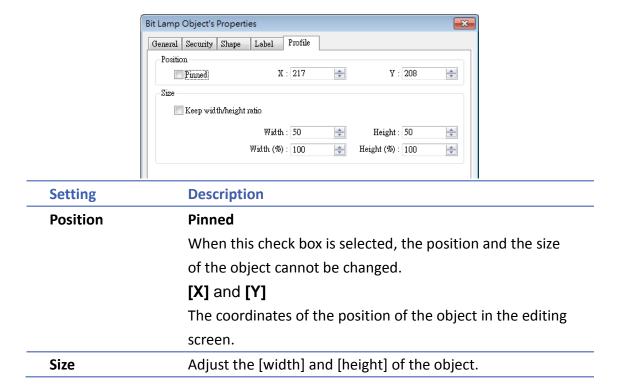
- When Text/Comment object is used with Comment enabled, the text used as comment will not appear on HMI.
- When the texts of the fonts used in the editing window and on the HMI screen are not properly aligned vertically, it is possible to correct it with the FontRules.xml file in "%appdata%\Weintek\EasyBuilder" folder.

By adding the names of the fonts in question into the FontRules.xml file, their vertical metrics can be adjusted in advance to avoid the misalignment problem.

#### 9.5. Adjusting Profile Size

When an object is created and placed in the editing screen, double click it and select the [Profile] tab to adjust the position and size of the object.



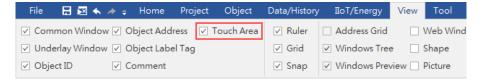


#### 9.6. Overlapping Objects (cMT / cMT X Series)

The following explains the ways to find the overlapping objects and convert them into a single Combo Button. After conversion, the general settings of the Combo Button will follow the settings of the frontmost object.

#### 9.6.1. Enable Touch Area

Open View tab and select [Touch Area].



2. All the touchable objects in the proejct will be highlighted in yellow, the overlapping areas will be highlighted in pink, and the objects that are not touchable will remain the same.

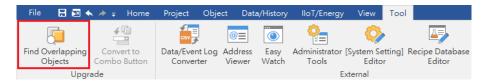




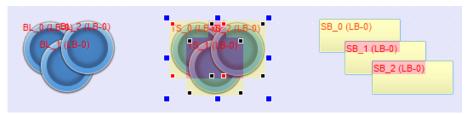
Object General Properties 9-11

#### 9.6.2. Find Overlapping Objects

 Open Tool tab and click [Find Overlapping Objects] to find all the touchable overlapping objects in the project.



2. At the first time clicking [Find Overlapping Objects], the system will find the first group of overlapping objects in the current window. To search for the next group, click this button again. When all the overlapping objects in the current window are found, the system will start searching for overlapping objects in the next window, and then open the window in which overlapping objects are found.



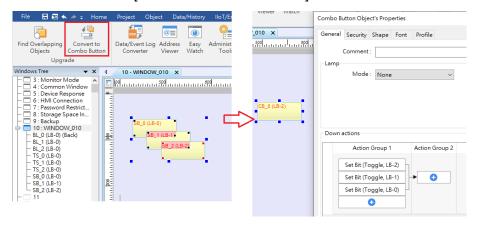


All layers of a window must be editable before clicking [Find Overlapping Objects].

#### 9.6.3. Convert to Combo Button

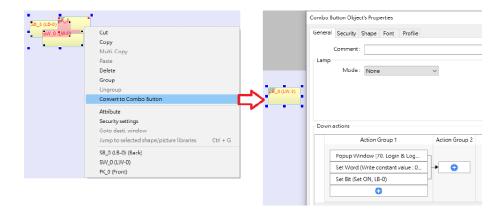
When the overlapping objects found are Set Bit, Toggle Switch, Set Word, Multi-State Switch and Function Key, they can be converted to a single Combo Button by the following ways.

Way 1. Open Tool tab and click [Convert to Combo Button].

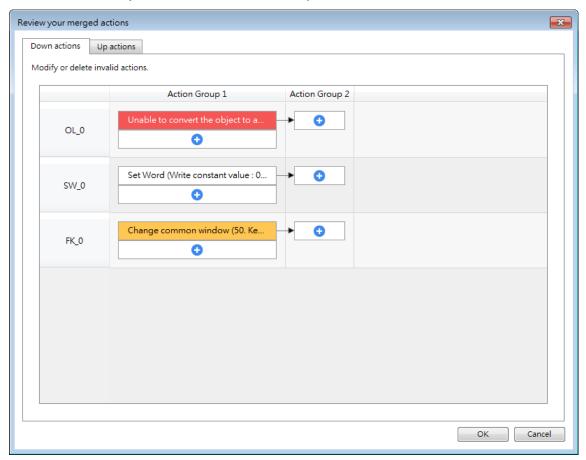


Way 2. Select the overlapping objects together, click the right mouse button, and then select [Conver to Combo Button].





After [Convert to Combo Button] is clicked, a review window shows for users to review the actions that can be triggered by the Combo Button. Actions that are not highlighted can be merged; actions that are highlighted in yellow will be automatically adjusted to meet merging condition; and actions that are highlighted in red cannot be merged. The user can move the mouse cursor to the yellow or red area to see explanations.



## Note

The Comment of the generated Combo Button will follow the setting of the frontmost object that has a Comment.



Object General Properties 9-13

The Security settings of the generated Combo Button will follow the settings of the frontmost object. If the Security settings of the objects layers down are different from the frontmost object, an alert is shown after conversion.

- The Sound settings of the generated Combo Button will follow the settings of the frontmost object that has Sound settings. If the Sound settings of the objects layers down are different from the frontmost object, an alert is shown after conversion.
- The Picture or Shape, and the Label settings of the generated Combo Button will follow the settings of the frontmost object that has these settings. When there's no object using a picture or a shape, the Combo Button will follow the Label settings of the backmost object that is mergeable.
- The generated Combo Button will have the Vibration setting enabled if any of the overlapping objects has Vibration setting enabled.
- The generated Combo Button will follow the Operation Log settings of the overlapping object that uses Operation Log. When Operation Log is used for multiple overlapping objects, an alert is shown after conversion.



# 10. User Password and Object Security

This chapter discusses the protection for operations provided by setting up user passwords and security classes.

10.1.	Overview	10-2
10.2.	User Password and Operable Object Classes	10-2
10.3.	Enhanced Security Mode and Control Address	10-6
10.4.	Enhanced Security Mode Usage	. 10-10
10.5.	Object Security Settings	. 10-24
10.6.	Example of Object Security Settings	. 10-29
10.7.	Protecting Password Settings from Unauthorized Editing	. 10-32
10.8.	Bulk Changing of Security Settings of Multiple Objects	. 10-33



#### 10.1. Overview

This chapter discusses the protection for operations provided by setting up user passwords and security classes. Authentication modes are:

- General Mode
- Enhanced Security Mode

In addition, cMT / cMT X series allows the use of LDAP protocols for user authentication.

To set up the protection system, please:

- 1. Set user password and operable classes.
- 2. Set object class for objects.

An object belongs only to one security class. Setting the object class to "None" means any user can operate this object.

#### 10.2. User Password and Operable Object Classes

The security parameters can be found in [System Parameter Settings] » [Security].

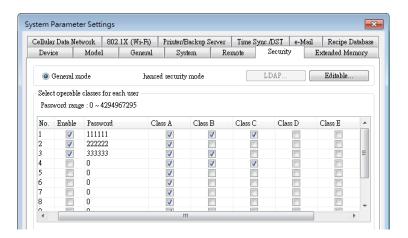
#### 10.2.1. General Mode

Up to 12 sets of user and password are available. A password should be one non-negative integer. There are six security classes: A to F.

Once the password is entered, the objects that the user can operate are classified. As shown below, "User 1" can only operate objects with class A or class C.



General Mode is not used for cMT / cMT X Series.





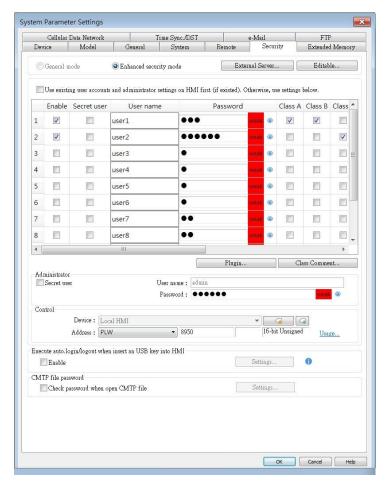


Click the icon to download the demo project. Please confirm your internet connection before downloading the demo project.

#### 10.2.2. **Enhanced Security Mode**

Up to 11 users can be set here. In addition, [Administrator] setting is provided. Administrator has all privileges and can operate all object classes. A username can contain Chinese characters, letters, and numbers, and a password can only contain letters and numbers. Each user can have up to 12 operable classes: A to L. (Up to 127 users can be set in Administrator Tools. Please see "10.4 Enhanced Security Mode Usage" for more details.)

Enhanced Security Mode provides a [Control address] for users to manage the accounts directly on HMI. Please see "10.3 Enhanced Security Mode and Control Address" for more details. Alternatively, use USB Security Key to log in automatically. Insert the USB disk in which the key is saved to log in. Please see "10.4.3 Login / Logout Automatically with USB Security Key" for more details. Login can also be achieved using fingerprint or RFID. Upon successful fingerprint recognition or RFID card scanning, the linked account will be automatically logged in, see "10.4.7 Login / Logout with Plugins" for more details.







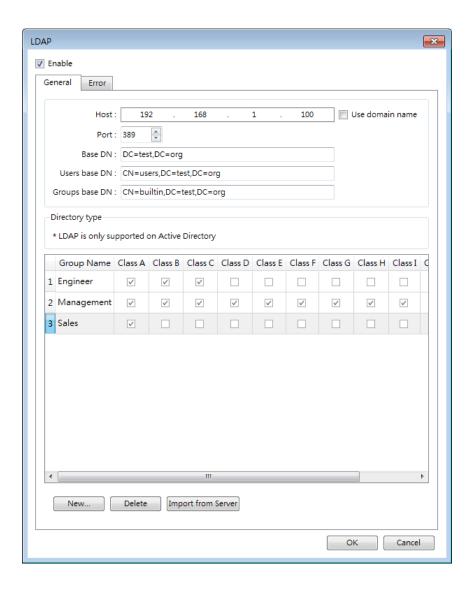
- In Enhanced Security Mode on a cMT / cMT X model, the Control Address can only be assigned to a word register of Local HMI. Please note that security features will work only on HMI when the control address is LW. Remote login on cMT Viewer will not be possible.
- EasyAccess 2.0's HMI Viewer on a eMT/iE/XE/mTV model doesn't support Enhance Security Mode, please use VNC Viewer instead.
- Usernames that contain Chinese characters cannot be changed by using EasyWeb or HMI system settings; they can only be edited in EasyBuilder Pro.

Click the icon to download the demo project. Please confirm your internet connection before downloading the demo project.

#### 10.2.3. LDAP Mode

LDAP (Lightweight Directory Access Protocol) enables applications to access Directory server providing database-like data structure, and here, the primary use of LDAP is to enable centralized user account management. When using LDAP mode, user account management is up to the Directory server, with HMI validating user login via the LDAP protocol. To have LDAP set up on HMI, users only need to provide necessary information about the directory server and set the operable classes for each group, without the need for managing username/password for each user.

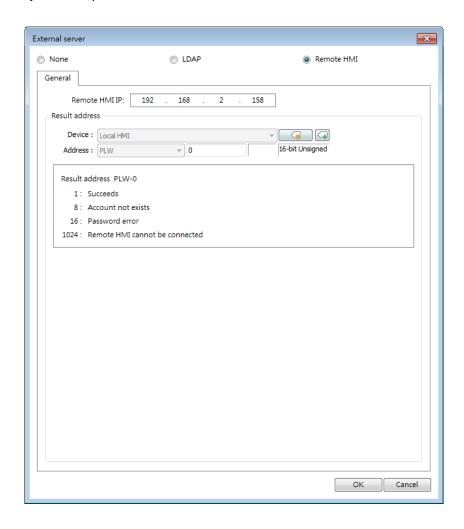




#### 10.2.4. Remote HMI Mode

In this mode, user accounts can be managed on a remote HMI, instead of the local HMI. The accounts on a remote HMI can be used to log in the local HMI; therefore, managing the accounts on the local HMI is not necessary.





## 10.3. Enhanced Security Mode and Control Address

The Control Address is used for login and account management. The Control Address can only be assigned to LW register on Local HMI, and 20 consecutive registers will be used. To log in using Control Address, please select to log in by [user name] or [user index].

Please set [user name] and [password] in [System Parameter Settings] » [Security] » [Enhanced security mode] in advance.

#### 10.3.1. Control Address Settings

When control address is set to LW-n, where n is an arbitrary number, the following addresses will be designated:

Address	Tag Name	Description
LW-n (1 word)	command	Commands to be executed: Login, Logout, Add/Setting/Delete Accounts, etc.
LW-n + 1 (1 word)	command execution result	Displays the result of command execution.
LW-n + 2 (1 word)	user index	The index of accounts (used with Option



		List Object).
LW-n + 3 (1 word)	user privilege	Binary value. Level A = bit0, Level B = bit1,
LW-n + 4 (8 words)	user name	Account name (Case-sensitive and only allows Chinese characters, letters and numbers).
LW-n + 12 (8 words)	password	Account password (Case-sensitive and only allows letters, numbers, or special characters).

After setting the [Control address], the relevant addresses can be found in [Address Tag Library] » [User-defined tags]. For example, setting [Control address] to LW-0: (UAC stands for User Account Control)

LW-0  $\rightarrow$  [UAC command]

LW-1 → [UAC command execution result]

LW-2  $\rightarrow$  [UAC user index]

LW-3 → [UAC user privilege]

LW-4  $\sim$  LW-11  $\rightarrow$  [UAC user name]

LW-12 ~ LW-20 → [UAC password]



- In Enhanced Security Mode on a cMT / cMT X model, the Control Address can only be assigned to a word register of Local HMI. Please note that security features will work only on HMI when the control address is LW. Remote login on cMT Viewer will not be possible.
- EasyAccess 2.0's HMI Viewer on a eMT/iE/XE/mTV model doesn't support Enhance Security Mode, please use VNC Viewer instead.

#### **10.3.2.** Commands

Setting different values in LW-n [command] enables different commands:

Set Value	Command	Corresponding Address
1	Log in by user name	Set [user name] and [password] first. After entering the user name and password, the system will check if they are valid in [System Parameter Settings] » [Security] » [Enhanced security mode].
2	Log in by user index	Set [user index] and [password] first. Please refer to 10.4.4 Enhanced Security Mode with Option List Object.
3	Log out	
4	Change the password of current logged-in user	Set [user name] and [password] first. Please fill in the original password in [user name] and new password in [password].
5	Add an account	Set [user name], [password] and [user



		privilege] first.
6	Add a temporary account (minutes)	Set [user name], [password], [user privilege], and [user index] first. [user index] is for specifying a time period (in minutes), within this period the account is valid. If 0 is specified, this account stays valid until the HMI is powered off.
7	Delete an existing account by user name	Set [user name] first.
8	Delete an existing account by user index	Set [user index] first.
9	Setting the privilege of an existing account by user name	Set [user name] and [user privilege] first.
10	Setting the privilege of an existing account by user index	Set [user index] and [user privilege] first.
11	Setting the password of an existing account by user name	Set [user name] and [password] first.
12	Setting the password of an existing account by user index	Set [user index] and [password] first.
13	Read the privilege of an existing account by user name	Set [user name] first. If the command succeeds, [user privilege] can be displayed.
14	Read the privilege of an existing account by user index	Set [user index] first. If the command succeeds, [user privilege] can be displayed.
15	Add a temporary account (days)	Set [user name], [password], [user privilege], and [user index] first. [user index] is for specifying a time period (number of days), within this period the account is valid. If 0 is specified, this account stays valid until the HMI is powered off.
16	Add an expiring account (minutes)	Set [user name], [password], [user privilege], and [user index] first. [user index] is for specifying a time period (in minutes), within this period the account is valid. 0 is an invalid value for this setting.
17	Add an expiring account (days)	Set [user name], [password], [user privilege], and [user index] first. [user index] is for specifying a time period (number of days), within this period the account is valid. 0 is an invalid value for this setting.



18	Remaining minutes for user name	Set [user name] first. If succeeded, the remaining time (in minutes) will be displayed in [user index].
19	Remaining minutes for user index	Set [user index] first. If succeeded, the remaining time (in minutes) will be displayed in [user index].
20	Remaining days for user name	Set [user name] first. If succeeded, the remaining time (number of days) will be displayed in [user index].
21	Remaining days for user index	Set [user index] first. If succeeded, the remaining time (number of days) will be displayed in [user index].



- Add a temporary account / expiring account: The difference between temporary accounts and expiring accounts is that temporary accounts are not stored in the system and will be invalid after HMI is turned off. Both temporary accounts and expiring accounts will be automatically deleted when they are expired.
- Delete the existing account: The currently logged in account cannot be deleted.
- Offline/Online Simulation: Simulate using the account settings in the program. Any modifications of the account during simulation will not be reserved for next simulation.
- admin: Default administrator account, cannot be deleted, has all privileges and cannot be changed.
- System Register PLW-10754: Displays current user name. (Only available for cMT / cMT X Series)
- The [user privilege] address does not display the privileges assigned to current user account, please use system register LW-9222 to display the privileges.
- LDAP mode does not support login with [user index].
- Click the icon to watch the demonstration film. Please confirm your internet connection before playing the film.

#### 10.3.3. Command Execution Results

After the command is executed, the system will store the result code to control address LW-n +

1. The listed result codes below are shown in hexadecimal format.

<b>Result Codes</b>	Command execution result
(0x001)	Succeeds
(0x002)	Invalid command
(0x004)	Account exists (when adding a new account)
(0x008)	Account not exists
(0x010)	Password error
(0x020)	Deny command



(0x040)	Invalid name
(0x080)	Invalid password character exists
(0x100)	Invalid import data
(0x200)	Out of validity range (when log in by USB Security Key). The [Effective Time] can be set in Administrator Tools.

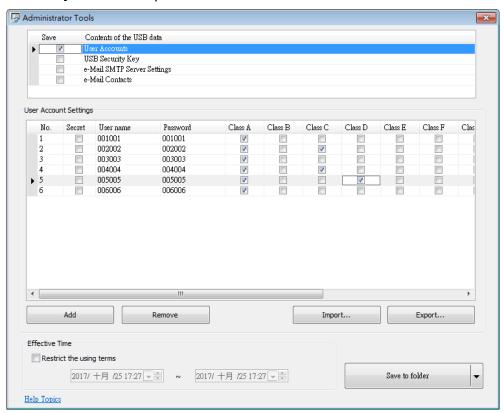


Users can add a new event in Event (Alarm) Log, and designate the [Read address] to LW-n + 1 [command execution result]. Open [Message] tab » [Text] » [Content] and specify the message to be displayed in Event Display Object for showing command execution result.

#### 10.4. **Enhanced Security Mode Usage**

#### 10.4.1. **Importing User Accounts**

The user accounts can be set using other tools we provide, apart from the settings in [System Parameter Settings] » [Security] tab. Administrator Tools can also be used to set user accounts. Administrator Tools can be found in the installation directory. After the program starts, select the [User Accounts] check box. Up to 127 accounts can be added.

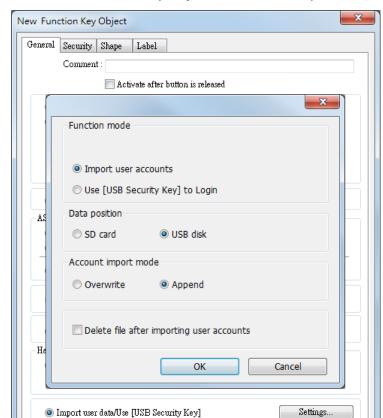




For more information, see "36 Administrator Tools".

The added accounts can be stored in USB disk or SD card and imported in HMI by a Function





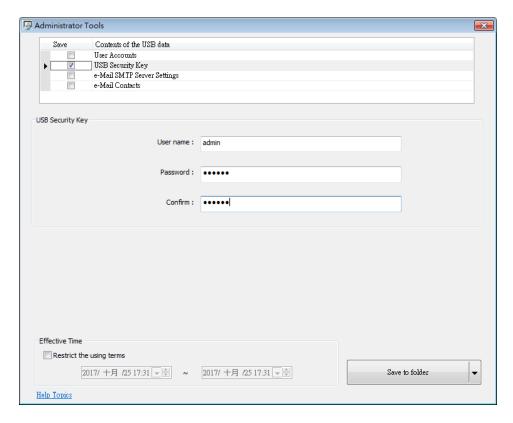
Key Object. To do so, create a Function Key Object, and select [Import user accounts].

When finished, insert the external device to HMI, and press Function Key to import accounts. If [Overwrite] is selected, the existing accounts will be overwritten with new accounts and automatically log out after importing. If select [Delete file after importing user accounts] check box, the system will delete the account data saved in the external device after importing. If the [Effective Time] in Administrator Tools is specified, the importing can only be done in the time limit specified. The imported accounts will not be deleted by system when the effective time ends.

#### 10.4.2. Login with USB Security Key

Instead of entering user name and password to login, a key can be used to do so. In EasyBuilder Pro installation directory, launch Administrator Tools, select [USB Security Key] check box. The account information uses the predefined data in [System Parameter Settings] » [Security].



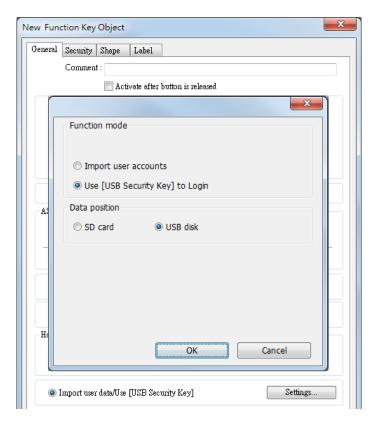




- Please note that the user accounts used for USB Security Key must already exist in HMI.
- For more information, see "36 Administrator Tools".

USB Security Key can be stored in USB disk or SD card, and create a Function Key to log in by USB Security Key as shown below:

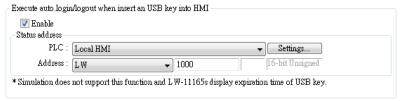




When finished, insert the external device to HMI, and press Function Key to log in using USB Security Key. If the [Effective Time] in Administrator Tools is specified, the login can only be done in the time limit specified. The system will log out automatically when the key expires.

#### 10.4.3. Login / Logout Automatically with USB Security Key

As shown below, in [System Parameter Settings] » [Security], select [Enable] check box for [Execute auto. login/logout when insert an USB key into HMI].



This function allows automatic login / logout using an USB security key. Insert the USB disk in which the key is saved to HMI to log in, and remove the USB disk to log out. The login / logout status will be written into a designated address, the result codes of login / logout:

0x00: No Action

0x01: Login Succeeds

0x04: Login Fails

0x08: Login Succeeds

0x10: Logout Fails



For more information about USB Security Key, see "36 Administrator Tools".



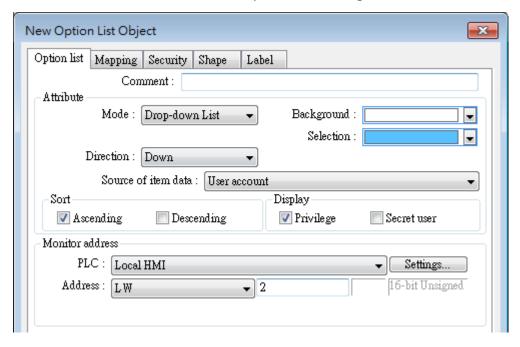


- When Auto Login / Logout is enabled, log in by [Function Key] object is not possible, but it is still possible to log in / out with a designated control address.
- This function does not support On-line / Off-line simulation.
- Only the USB Security Key saved in USB disk is valid.

Click the icon to download the demo project that explains how to use USB Security Key to log in / out. Please confirm your internet connection before downloading the demo project.

#### 10.4.4. Enhanced Security Mode with Option List Object

Enhanced Security Mode uses Control Address LW-n + 2 as account index. With Option List Object, account names and privileges can be displayed. Users can select whether or not to display the account privileges and secret users in Option List. Secret users are set to be hidden in [System Parameter Settings] » [Security] » [Enhanced Security Mode]; their account names will be hidden in Option List if [Secret user] check box is not selected. If the control address is set to LW-0, the monitor address for index of Option List is designated to LW-2.

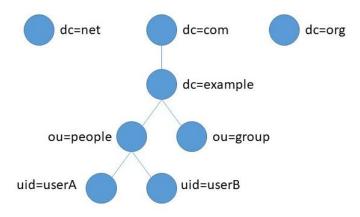


#### 10.4.5. LDAP Mode

LDAP (Lightweight Directory Access Protocol) enables applications to access Directory server providing database-like data structure, and here, the primary use of LDAP is to enable centralized user account management. When using LDAP mode, user account management is up to the Directory server, with HMI validating user login via the LDAP protocol. To have LDAP



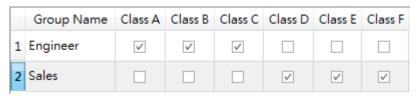
set up on HMI, users only need to provide necessary information about the directory server and set the operable classes for each group, without the need for managing username/password for each user.



The control addresses used by LDAP Mode are the same as the control addresses used by Enhanced Security Mode. Please see chapter 10.3 in this user manual for more information on the control address. Please note that obtaining LDAP user name using Option List object is not possible; therefore, [Log in by user index] is not supported.



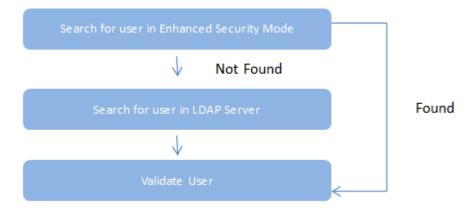
A user may be a member of multiple groups; in this case, the user has permission to operate all classes assigned for all the groups the user is in. As shown in the following figure, if a user is a member of both Engineer and Sales groups, the user can operate classes A~F.



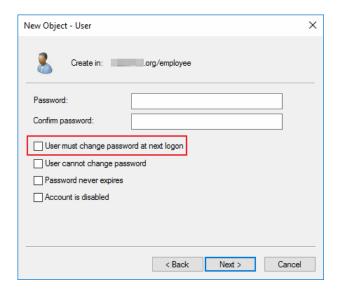
The credentials in the list in Enhanced Security Mode can also be managed and validated in LDAP mode. Please note that when a username exists in the lists of both modes, the system will only validate user using Enhanced Security Mode. As shown in the following figure, in the case where username Angela exists in the user list in both LDAP server and Enhanced Security Mode, the HMI will validate user under Enhanced Security Mode.

LDAP Server			Enhanced Security Mode			
Name	Type	No.	Enable	Secret user	User name	Password
遇 Angela	User	1	<b>V</b>		Angela	1
_		2	1		Gina	2
Bella	User	3	<b>V</b>		Helen	3
遇 Cindy	User					
Bora	User					
Elly	User					
Fanny	User					





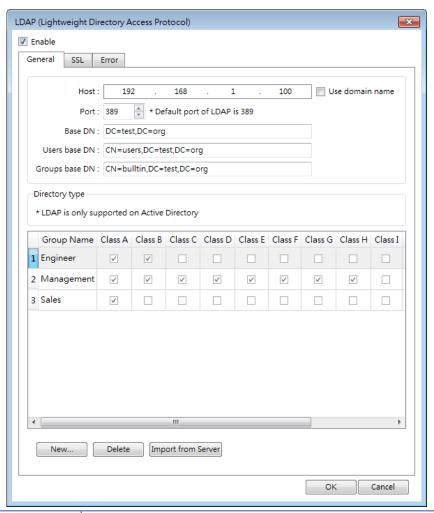
- LDAP Mode does not support login with [user index].
- LDAP is only supported on Active Directory.
- HMI cannot change user's password; therefore, when adding a new user in LDAP server, please do not select [User must change password next logon].



### **10.4.5.1.** General Tab

Set LDAP server and operable classes for each group.



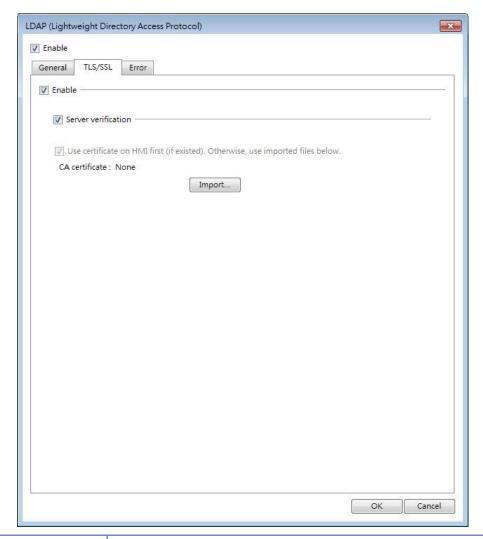


Setting	Description	
Host	Set the IP address of the host or use domain name.	
Port	By default the port number is:	
	LDAP: 389	
	LDAPS: 636	
Base DN	LDAP server's domain name (DN).	
User base DN	Organizational units (OU) that hold users.	
Group base DN	Organizational units (OU) that hold groups.	
New	Add a new group.	
Delete	Delete a group.	
Import from	Log in LDAP server using user credentials to import all	
Server	allowable groups.	
Group Name	Select the operable classes for each group. The group	
and Class	name can be 64 words in maximum, case-sensitive, and	
	allows letters / numbers / symbols / Unicode.	



### 10.4.5.2. TLS/SSL Tab

Enable settings in this tab for LDAPS (LDAP over SSL) connection with the AD server.

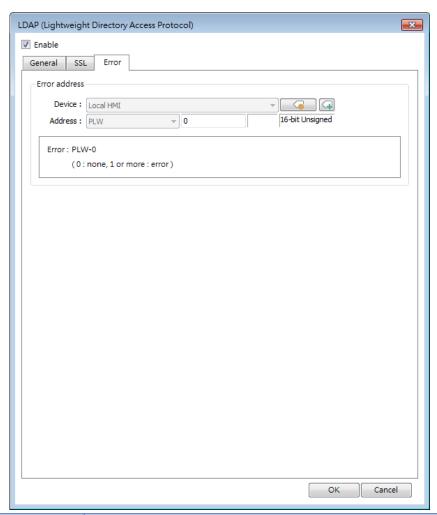


Setting	Description
Enable	Enable TLS/SSL security for secured LDAP
	communication.
Server	When establishing connection, the HMI will verify
verification	whether the certificate supplied by the server matches
	the one stored on HMI.
Use certificate	Use surrent certificate on HMI or import a new
on HMI (if	Use current certificate on HMI or import a new certificate.
existed)	Certificate.

### 10.4.5.3. Error Tab

When LDAP server cannot be connected, an error code shows in the designated address.





Setting	Description		
Error address	The res	ult of login is output to this address.	
	Value	Description	
	0	No error	
	1	Error on LDAP server or no password is	
		entered.	
	2	Unknown error	
	257	Remote LDAP server cannot be connected.	
	258	Wrong username or password.	
	259	Verification failed	
	512	Unknown TLS	
	513	Domain name does not match CN.	



## 10.4.5.4. LDAP Settings (Import from Server)

Get group information from LDAP server.



Setting	Description		
Username	Log in LDAP Server using username.		
Password	Log in LDAP Server using pa	ssword.	
Fetch all	Fetch all groups of the DN in	n LDAP server.	
groups	Error Message	Description	
	Can't contact LDAP server	LDAP server cannot be	
		connected.	
	Invalid Credentials	Wrong username or	
		password used for login	
		LDAP server.	
	Unknown Error on LDAP server or no		
		password is entered.	



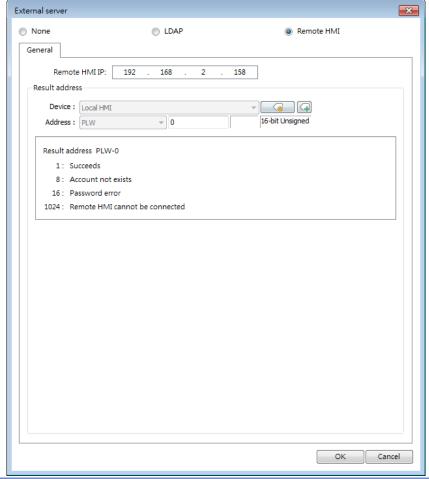
The maximum number of groups allowable in LDAP mode is 128 groups. When importing from LDAP server, the system will check the number of groups in LDAP server first, exceeding 128 groups will result in unsuccessful import.



Importing duplicate group name will not clear the operable classes of that group.

### 10.4.6. Remote HMI Mode

In this mode, user accounts can be managed on a remote HMI, instead of the local HMI. The accounts on a remote HMI can be used to log in the local HMI; therefore, managing the accounts on the local HMI is not necessary.



Setting	Description	
Remote HMI IP	The IP address of the remote HMI that holds the user	
	accounts.	
Result address	When an error occurs while trying to authenticate the	
	account or connect to the remote HMI, the	
	corresponding error code will be output to the	
	designated result address.	



The accounts can be authenticated via both local and remote HMI. When the same account exists on both local and remote HMI, the authentication is done via the local HMI, instead of the remote HMI. As shown below, user Angela will be authenticated via local

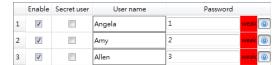


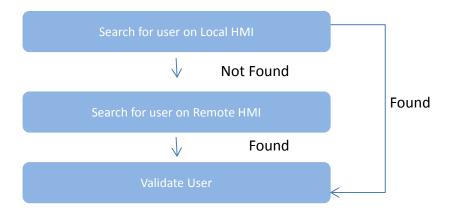
HMI.

# Accounts on Remote HMI



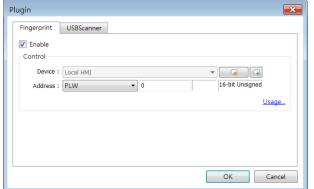
#### Accounts on Local HMI

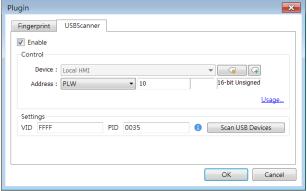




### 10.4.7. Login / Logout with Plugins

After enabling the plugin, users have the option to log in either through a fingerprint recognition device for accounts linked to fingerprints or via a USB scanner for accounts linked to RFID cards or barcodes.





When configuring the USB scanner, to prevent interference from other USB devices during login, it's necessary to first set the VID and PID of the USB scanner. After clicking [Scan USB Devices], the system will prompt a message "Please insert your USB Device". Once the USB scanner is inserted into the PC, the system will obtain a unique VID and PID for the USB scanner. Click [Save], and the system will automatically incorporate this VID and PID into the settings.

### **Control Address Settings**

When control address is set to PLW-n, where n is an arbitrary number, the following addresses



## will be designated:

Address	Tag Name	Description
PLW-n (1 word)	Command	Commands to be executed: Login, Add Fingerprint / RFID Card, Remove Fingerprint / RFID Card, etc.
PLW-n + 1 (1 word)	Result	Displays the result of command execution.
PLW-n + 2 (1 word)	Status	The initialization status of the plugin server.
PLW-n + 3 (1word)	Error	The error code from the device server.

### **Commands**

Setting different values in PLW-n [command] enables different commands:

	<u> </u>	
Set Value	Command	Corresponding Address
1	Log in by fingerprint / RFID / barcode	
2	Add fingerprint / RFID / barcode by user name	Set [user name] first.
3	Add fingerprint / RFID / barcode by user index	Set [user index] first. Please refer to 10.4.4 Enhanced Security Mode with Option List Object.
4	Remove fingerprint / RFID / barcode by user name	Set [user name] first.
5	Remove fingerprint / RFID / barcode by user index	Set [user index] first.
6	Remove all fingerprints / RFID / barcodes	

## **Command Execution Results**

After the command is executed, the system will store the result code at control address PLW-n

+ 1.

<b>Result Codes</b>	Command execution result
0	Succeeds
1	Unknown error
6	Canceled
101	Account not linked
115	Authentication failed
Others	System error



#### **Error Codes**

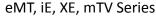
When the plugin server initializes, the system will store the result code at control address PLW-n + 3.

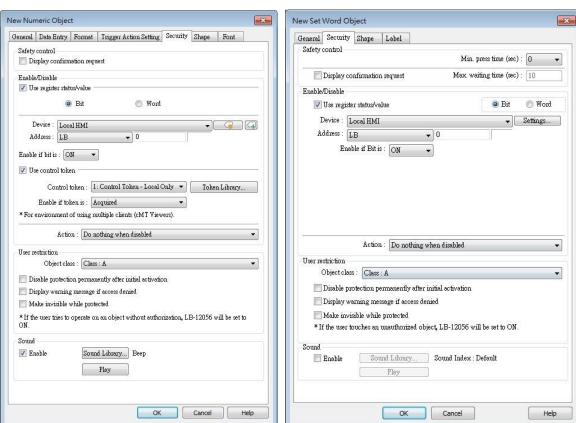
Error Codes	Command execution result
0	Initialization succeeds
1	Unknown error
2 or more	System error

# 10.5. Object Security Settings

Settings in the Security tab allow users to configure conditions so that the object is operable when the condition is met. The sound emitted when operating the object can be selected.

cMT, cMT X Series





### 10.5.1. Security Tab

Setting	Description
Min. press	Press and hold the object for longer than the [Min. press



time (sec)	time] set here to activate the object.
Display	After pressing the object, a dialog appears for operation
confirmation	confirmation. If the response to this dialog comes later
request	than the set [Max. waiting time (sec)], this dialog disappears automatically and the operation will be canceled.
	Please confirm the operation  OK Cancel

### 10.5.2. Enable/Disable

When [Use register status/value] or [Use control token] is selected, whether the object is operable is determined by the status of the designated address or acquisition the control token, respectively. As shown in the following figure, only when LB-0 is in OFF state and "2: Control Token" is acquired will this object be operable.



The following table describes the action this object will take when it's token is not acquired.

Setting	Description
Do nothing	When the control token is not acquired, the object is
when disabled	displayed.
Hide when	When the control token is not acquired, the object is
disabled	hidden.
Grayed label	When the control token is not acquired, the label of the
when disabled	object turns gray.
	toggle



## 10.5.2.1. Use Register Status/Value

When selected, the status of the designated bit/word address determines whether the object is operable.

Setting	Description
Bit	
DIL	The object is operable when the designated bit is in
	On/Off state.
Word	When [Use Register Status/Value] and [Word] are both
	selected, the status of a designated word address
	determines whether the object is operable.
	Enable if value is: >, <, ==, <>, >=,<=
	When the value in the word address reaches the
	condition specified here, the object is operable.
	<b>Tolerance:</b> This setting is available for <> and ==.
	<>: The object will be operable when:
	value in address > [value in address + tolerance]
	or
	value in address < [value in address - tolerance]
	==: The object will be operable when:
	value in address is between [value in address + tolerance]
	and [value in address - tolerance] (including value in
	address ± tolerance)
	For example:
	✓ Use register status/value ⑤ Bit ⑥ Word
	Device : Local HMI   ▼ Settings
	Address: LW 0 16-bit Unsigned
	Enable if value is :   Tolerance : 1
	When the value in the designated word address is
	between 9~11, the object is operable.
	Please note that [Word] option is only available for Set
	Word and Numeric objects.

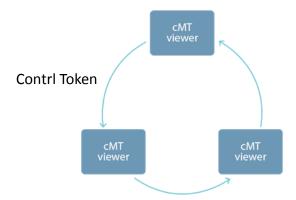


Word objects supported on cMT/cMT X Series include: Set Word, Numeric, ASCII, Combo Button

Word objects supported on iE/XE/eMT/mTV Series include: Set Word, Numeric.



### 10.5.2.2. Control Token



One cMT / cMT X HMI can be simultaneously controlled by multiple cMT Viewer clients. To ensure system safety by preventing an object to be controlled by multiple clients simultaneously, a control token can be set. Only one cMT Viewer client can acquire the control token at a time, and only the cMT Viewer client that acquires control token can operate the object. The rest of the clients can acquire the token one by one when the token is not occupied.

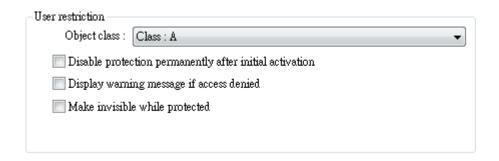
The applicable objects include: Combo Button, Numeric, ASCII, Direct Window, and Indirect Window.

Setting	Description
Control Token	Select a control token for the object.
Token Library	Add/delete control token.
	For more information, please see "Chapter 34 Control
	Token" in this user manual.
Enable if Token is	When [acquired] is selected, only the device that
	obtains the control token can operate the object.
	When [unacquired] is selected, only the devices that
	do not obtain the control token can operate the
	object.

### 10.5.3. User Restriction

Set the security class of the object to be operated by an authorized user.





Setting	Description
Object class	"None" means any user can operate this object. Only account "admin" can operate "Administrator" object class.
Disable	Once the permitted class of the user matches that of the
protection	object, the system will stop checking the security class
permanently	permanently, that means, any user can operate this
after initial	object freely after it is unlocked.
activation	
Display	When an unauthorized user attempts to operate the
warning	object, a warning dialog (Window no. 7) appears. The
message if	content of the message in the dialog can be modified.
access denied	
Make invisible	When the user's privilege does not match the object
while	class, the object will be hidden.
protected	



# 10.6. Example of Object Security Settings

The following shows an example of setting object security class:

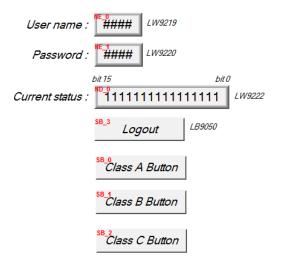
Create a project, go to [System Parameter Settings] » [Security] » [General] to enable 3
users:

User 1 = Operable class: A

User 2 = Operable class: A, B

User 3 = Operable class: A, B, C

2. Design Window no. 10 as shown:



Create two [Numeric Input] objects:

[LW-9219] User no.  $(1^{-12})$ , Length = 1word

[LW-9220] For entering user password. Length = 2 words

Create a [Numeric Display] object:

[LW-9222] Displays the operable object class of current user. (16-bit Binary)

Create a [Set Bit] object

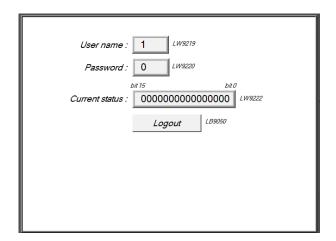
[LB-9050] logout

Create three [Set Bit] objects:

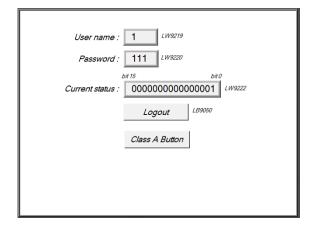
Each set to different classes but all select [Made invisible while protected].

**3.** After setting, please save and compile the project and execute off-line simulation. The below shows how it works when simulating.



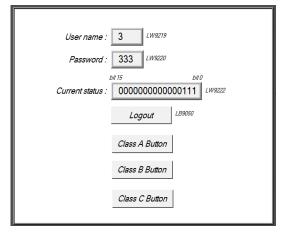


Before entering the password, it displays "0000000000000000000, which means that the user operable object class is "None". [Class A Button] ~ [Class C Button] objects are classified from "A" to "C" and selected [Made invisible while protected]; therefore they are hidden at this moment.



Enter User 1 password "111". Since User 1 is only allowed to operate class A objects, [Class A Button] object appears for

operating. [LW-9222] bit 0 turns to "1" means that user can operate class A objects.



Enter User 3 password "333".

Since User 3 is allowed to operate class A, B,
C objects, [LW-9222] bit 0 ~ bit 2 turns to "1",
means that user can operate class A ~ C

objects.

User name: 3 LW9219

Password: 333 LW9220

bit 15 bit 0

Current status: 0000000000000000 LW9222

Logout LB9050

Click [Logout] button to log out, the system will return to the initial state, and current user can only operate class "None" objects.



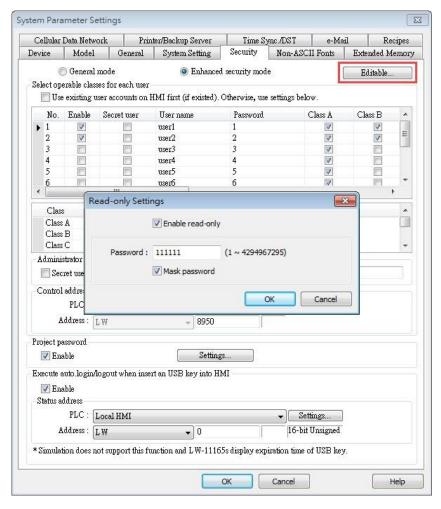


- Password input: If the password is incorrect, [LB-9060] will be ON; if the password is correct, [LB-9060] will be OFF. All user passwords (User 1 to User 12) can be obtained from system registers [LW-9500] ~ [LW-9522], 24 words in total.
- Changing password directly on HMI: When [LB-9061] is set ON, the system will read data in [LW-9500] ~ [LW-9522] to update user password. The new password will be used in future operations. Please note that the user operable object classes will not be changed due to the change of password.



# 10.7. Protecting Password Settings from Unauthorized Editing

Before sending the project to others who may edit the project afterwards, it is recommended to click [Editable] button in Security settings tab to open read-only mode. This mode can protect password settings from unauthorized editing.



When [Enable read-only] is selected, a password will be required for changing security settings in the project.

When [Mask password] is selected, passwords will be masked by asterisks (\*).

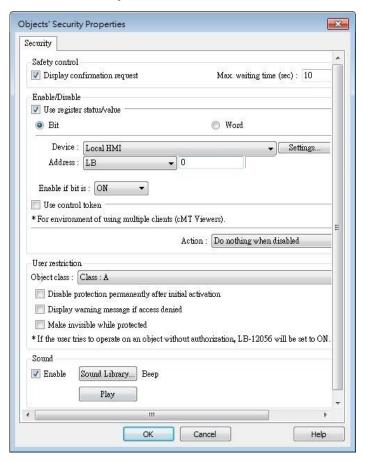


The protected projects cannot be decrypted since they are encrypted by users, therefore, please remember your password.



# 10.8. Bulk Changing of Security Settings of Multiple Objects

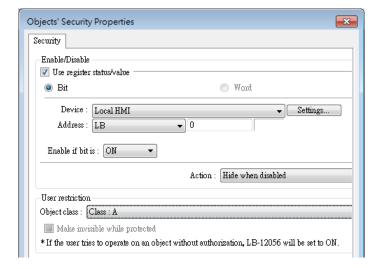
Selecting multiple objects in a group and then selecting [Security settings] in the right-click menu can open an Objects' Security Properties window that allows users to change the security settings of all the selected objects at a time.





When the selected objects have different security settings pages, Objects' Security Properties will automatically adjust and show the settings that users are allowed to change. The rest of the settings will be hidden or greyed out. The following is a window that shows when selecting a Bit Lamp and a Numeric object.







# 11.Index Register

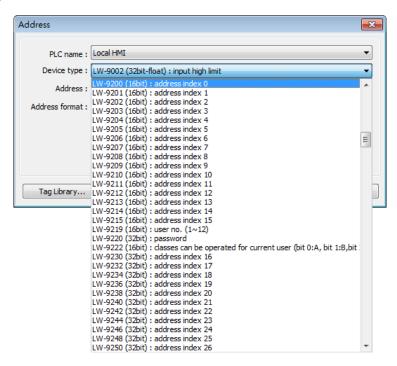
This chapter explains how to use Index Register.

11.1.	Overview	11-2
11.2.	Examples of Index Register	11-3
11.3.	Examples of Using Tag-Based PLC and Index Registers	11-5



## 11.1. Overview

EasyBuilder Pro provides Index Registers for changing addresses flexibly. With Index Registers, user can change the object's read/write address directly on HMI without changing its settings. There are 32 Index Registers, divided into 16-bit and 32-bit. cMT / cMT X models offer 32 Private Index Registers, also divided into 16-bit and 32-bit.



The corresponding address of 16-bit Index Register 0 to 15: LW-9200 (16bit) to LW-9215 (16bit) The maximum offset range is 65536 words.

The corresponding address of 32-bit Index Register 16 to 31: LW-9230 (32bit) to LW-9260 (32bit)

The maximum offset range is 4294967296 words.

The corresponding address of 16-bit Private Index Register 0 to 15: PLW-9200 (16bit) to PLW-9215 (16bit)

The maximum offset range is 65536 words.

The corresponding address of 32-bit Private Index Register 16 to 31: PLW-9230 (32bit) to PLW-9260 (32bit)

The maximum offset range is 4294967296 words.

When using [Index register], the address is designated by the following equation:

The constant set in [Address] + the value in the chosen Index Register.

The way to use Private Index Registers is the same as that of Index Registers. The difference is



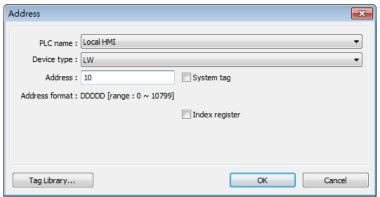
that Private Index Registers work for objects in cMT Viewer app, which runs independently on each client device; therefore, operations in this app will not make the HMI show the same screen.



- Index Registers work for the **Word** registers. For **Bit** registers, adding 1 to the value in the Index Register, the offset is 16 bits.
- Index Registers do not work for PLB and PLW registers.

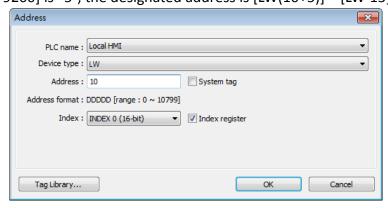
# 11.2. Examples of Index Register

The following explains the way to designate the register while Index Register is used. If **not** selecting [Index register] check box and set address to [LW-10]. The system will directly read / write LW-10.



If select [Index register] check box and set [Index] to [INDEX 0 (16-bit)], the system will read / write [LW(10 + value in Index Register 0)].

If the data in [LW-9200] is "5", the designated address is [LW(10+5)] = [LW-15].



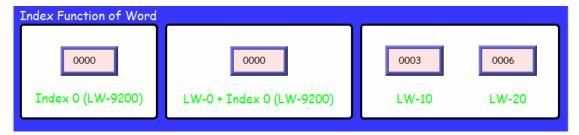
Here's a demo project shown as an example:



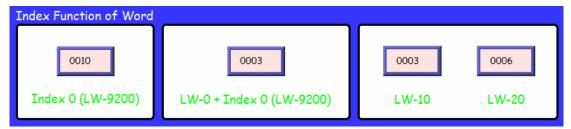


# **Example 1**

The following shows an example of using a Word register and select [Index register]. If the value in [LW-0] is 0, in [LW-10] is 3, and in [LW-20] is 6, the result is:



If the value in Index 0 (LW-9200) is 0, then [LW0 + Index 0] = read [LW-0].



If the value in Index 0 (LW-9200) is 10, then [LW0 + Index 0] = read [LW-10] = 3.

## **Example 2**

The following shows an example of using a Bit register and select [Index register].

If the state of [LB-16] is ON, and the state of [LB-32] is OFF.

Since 1 Word equals to 16 Bit, adding 1 in Index Register, the offset is 16 bits.





If Index 6 (LW-9206) is set to 1, then switch [LB-0 + Index6] reads LB-16 which is in ON state.



If Index 6 (LW-9206) is set to 2, then switch [LB-0 + Index6] reads LB-32 which is in OFF state.



- When using Index Registers for Bit register, the offset is 16 bits. For example, if the Bit register is LB-0, and set the value in Index Register to 1, then LB-16 will be activated. If set the value in Index Register to 2, then LB-32 will be activated.
- Click the icon to download the demo project. Please confirm your internet connection.

# 11.3. Examples of Using Tag-Based PLC and Index Registers

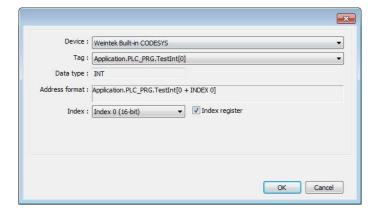
Index Registers only support one-dimensional array variables.

### **Example 1: INT**

If [Index register] is enabled and [Index] is set to [Index 0 (16-bit)], the system will read / write "Application.PLC PRG.TestInt[0 + value in Index Register 0]".

If the data in [LW-9200] is "5", the actual address is "Application.PLC PRG.TestInt[5]".

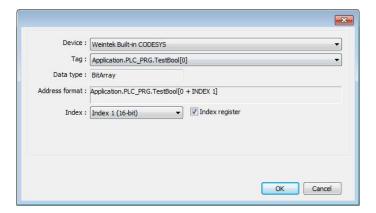




# **Example 2: Bit**

If [Index register] is enabled and [Index] is set to [Index 1 (16-bit)], the system will read / write "Application.PLC\_PRG.TestBool[0 + value in Index Register 1]".

If the data in [LW-9201] is "7", the designated address is "Application.PLC\_PRG.TestBool[7]".



Note that, unlike its non-tag counterpart, the 16-bit offset is not necessary for Bit array tags.



# 12. Keyboard Design and Usage

This chapter explains how to design and use keyboard in EasyBuilder Pro.

12.1.	Overview	. 12-2
12.2.	Steps to Design a Popup Keyboard	. 12-2
12.3.	Steps to Design a Keyboard with Direct Window	. 12-5
12.4.	Steps to Design a Fixed Keyboard on Screen	. 12-6
12.5.	Steps to Design a Unicode Keyboard	. 12-7



## 12.1. Overview

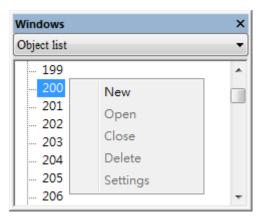
Numeric Input and ASCII Input objects need keyboard as an input tool. Both numeric keyboard and ASCII keyboard are created with Function Key object. Apart from the keyboards provided by EasyBuilder Pro, you can create the keyboard if needed. System keyboard is available on cMT / cMT X Series models.

The types of the keyboards are:

- Popup Keyboard (with or without title bar)
- Fixed Keyboard
- Unicode Keyboard
- System Keyboard (available on cMT / cMT X models)

# 12.2. Steps to Design a Popup Keyboard

1. Create and open a window for the new keyboard. For example, set to "window no. 200".

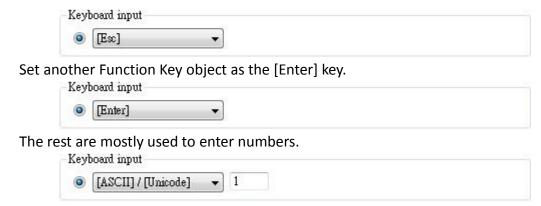


2. Adjust the height and width of "window no. 200" and create a variety of Function Key objects in [ASCII/Unicode mode].



Set one of the Function Key objects as the [Esc] key.





3. Select a suitable picture for each Function Key object.

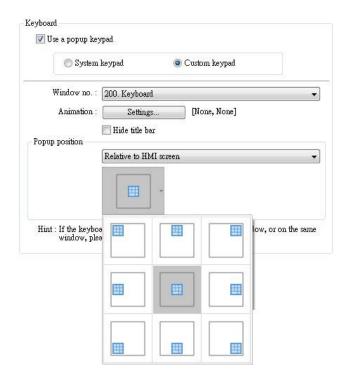


4. Select [System Parameter Settings] » [General] » [Keyboard] » [Add] to add "window no. 200". Up to 32 keyboards can be added.

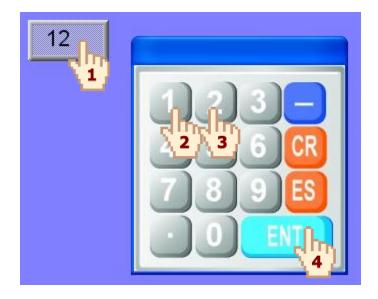


5. After the keyboard window is added, when you create Numerical Input and ASCII Input objects, "200. Keyboard" can be found in [Data Entry] » [Keyboard] » [Window no.]. The [Popup position] is for designating the display position of the keyboard on the HMI screen. The system divides the screen into 9 areas.



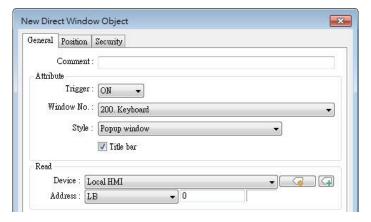


6. Select "200.Keyboard". When you press Numerical Input or ASCII Input objects on the screen, "window no. 200" will pop up. You can press the keys on the keyboard to enter data.

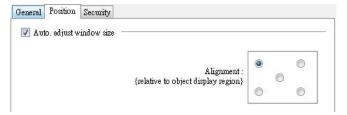


# 12.3. Steps to Design a Keyboard with Direct Window

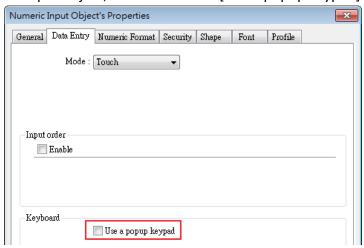
Create a Direct Window object and set a read address to activate it.
 In [General] » [Attribute] select [Title bar] and the correct [Window No.].



2. Open the [Position] tab and select [Auto. adjust window size].



**3.** Create a Numeric Input object, and don't select [Use a popup keypad] check box.



4. Create a Set Bit object, set address to [LB-0] and set [Set style] to [Set ON]. Overlay it on the Numeric Input object. Pressing the Numeric Input object will open the keyboard window.





5. Add Set Bit objects on the [Enter] and [ESC] Function Key objects respectively. Set address to [LB-0] and [Set style] to [Set OFF]. In this way when pressing either [Enter] or [ESC] key will close the keyboard window.

# 12.4. Steps to Design a Fixed Keyboard on Screen

You can also place a fixed keyboard on the screen instead of popup keyboard or Direct Window. This type of keyboard can't be moved or closed.

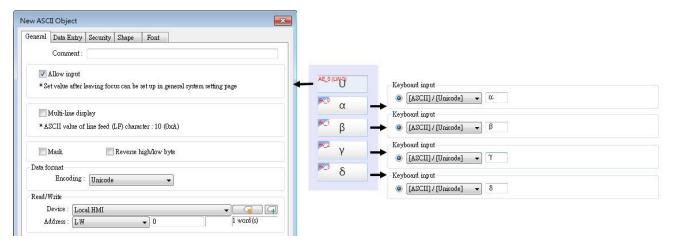
- 1. Create a Numeric Input object, in [Data Entry] » [Keyboard] don't select [Use a popup keypad] check box.
- 2. Use Function Key objects to design the keyboard and place it on the screen.
- 3. Press the Numeric Input object and enter a value with Function Key objects directly.



# 12.5. Steps to Design a Unicode Keyboard

The following steps explain how to create a Unicode keyboard with Function Key objects.

- 1. Place an ASCII Input object on the window and select [Unicode].
- 2. Create Function Key objects as shown in the following figure. A simple UNICODE keyboard is created.





You can group up the elements of the designed keyboard and save to Group Library for future use.

Click the icon to download the demo project. Please confirm your internet connection before downloading the demo project.



# 13. Objects

This chapter explains how to use different objects.

13.1.	Bit Lamp	13-3
13.2.	Word Lamp	13-5
13.3.	Set Bit	13-10
13.4.	Set Word	13-13
13.5.	Function Key	13-23
13.6.	Toggle Switch	13-30
13.7.	Multi-State Switch	13-33
13.8.	Slider	13-37
13.9.	Numeric	13-44
13.10.	ASCII	13-63
13.11.	Indirect Window	13-67
13.12.	Direct Window	13-75
13.13.	Moving / Rotating Shape	13-81
13.14.	Animation	13-87
13.15.	Bar Graph	13-91
13.16.	Meter Display	13-100
13.17.	Trend Display	13-108
13.18.	History Data Display	13-131
13.19.	Data Block Display	13-140
13.20.	XY Plot	13-149
13.21.	Alarm Bar and Alarm Display	13-156
13.22.	Event Display	13-165
13.23.	Data Transfer	13-179
13.24.	Backup	13-187
13.25.	Media Player	13-195
13.26.	BACnet Schedule	13-201
13.27.	PLC Control	13-205
13.28.	Scheduler	13-212
13.29.	Option List	13-222
13.30.	Timer	13-230
13.31.	Video In	13-235
13.32.	System Message	13-242



12 22	Recipe View	2//
	·	
	Flow Block 13-7	
13.35.	Operation Log	257
13.36.	Combo Button	271
13.37.	Circular Trend Display	279
13.38.	Picture View	289
13.39.	File Browser	292
13.40.	Import/Export	296
13.41.	Pie Chart	301
13.42.	Barcode	306
13.43.	String Table	316
13.44.	Database	318
13.45.	Dynamic Scale	336
13.46.	Dynamic Drawing	339
13.47.	PDF Reader	345
13.48.	Table	347
13.49.	VNC Viewer	349
13.50.	Contacts Editor	354
13.51.	Event Bar Chart	357
13.52.	Action Trigger	363
13.53.	Calendar13-	370
13.54.	Touch Gesture	372
13.55.	PLC Web Browser	374
13.56.	Condition	378
13.57.	FTP Server	382
13.58.	Date/Time	385
13.59.	Template 13-	387



Objects 13-3

# **13.1.** Bit Lamp

### **13.1.1.** Overview

Bit Lamp object displays the state of a designated bit address. If the bit state is OFF, the State 0 shape will be displayed. If the bit state is ON, the State 1 shape will be displayed.

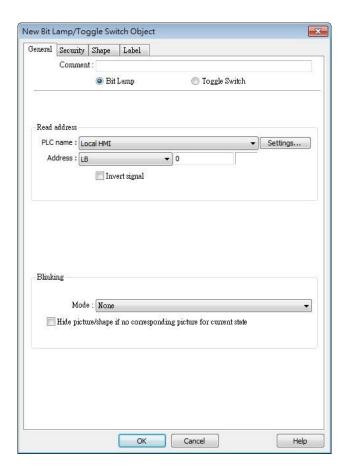


## 13.1.2. Configuration



Click [Object] » [Bit Lamp] icon on the toolbar to open a Bit Lamp object property dialog box. Set up the properties, press OK button, and a new Bit Lamp object will be created.

#### **General Tab**





Setting	Description		
Comment	User can describe the information of the object.  Bit Lamp / Toggle Switch		
	Switch between Bit Lamp and Toggle Switch features.		
Read address	Click [Setting] to select the [PLC name], [Address], [Device type],		
	[System tag], [Index register] of the bit device that controls the [Bit		
	Lamp] object. Users can also set address in [General] tab while		
	adding a new object.		
	Invert signal		
	Reverses the display of ON / OFF states. For example, if [Invert		
	signal] check box is selected, when the designated bit is OFF, the		
	object displays ON state.		
Blinking	The appearance of the object may alternate between states when		
	the bit is ON or OFF.		
	Mode:		
	None		
	No blinking.		
	Alternating image on state 0		
	The appearance of the object alternates between State 0 and 1		
	when the bit is OFF.		
	Alternating image on state 1		
	The appearance of the object alternates between State 0 and 1		
	when the bit is ON.		
	Blinking on state 0		
	The State 0 appearance of the object will blink when the bit is OFF.		
	Blinking on state 1		
	The State 1 appearance of the object will blink when the bit is ON.		
	Hide picture/shape if no corresponding picture for current state		
	If selected, when there are not enough pictures to represent all the		
	states, hides the picture. Otherwise, displays the last state.		



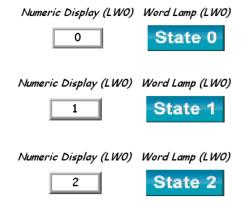
■ In [Label] tab, if select [ON=OFF (use state 0)] check box, both state 0 and 1 follow the settings of state 0.



## 13.2. Word Lamp

### 13.2.1. Overview

Word Lamp object displays the state according to the value of a designated word register. Up to 256 states are available. When the value of the register is 0, State 0 appearance of the object is displayed, and with the register value being 1 the object displays State 1, and so on.



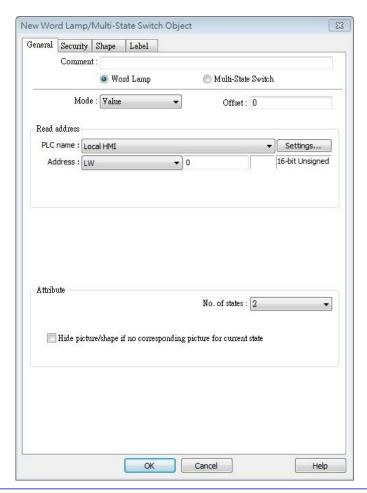
## 13.2.2. Configuration



Click [Object] » [Word Lamp] icon on the toolbar to open a Word Lamp object property dialog box. Set up the properties, press OK button, and a new Word Lamp object will be created.

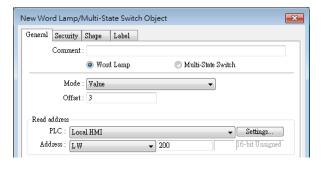


## **General Tab**



Setting	Description	
Comment	User can describe the information of the object.	
	Word Lamp / Multi-State Switch	
	Switch between Word Lamp and Multi-State Switch features.	
Mode / Offset	Word Lamp object offers the following three modes:	
	Value	
	The state is displayed according to the value in the designated word	
	address and plus the [Offset].	
	As shown below, if the value within LW-200 is 3, since the offset is	
	set to 3, the shape of state 0 is displayed. (value 3 - offset 3)	





## **LSB**

Convert the value from decimal to binary. The least significant active bit in a binary data word selects the state displayed.

Decimal	Binary	Displayed state	
0	000000000000000000000000000000000000000	State = 0 when all bits are 0	
1	0000000000000001	The lowest non-zero bit is bit 0, state = 1.	
2	00000000000000000010	The lowest non-zero bit is bit 1, state = 2.	
3	0000000000000011	The lowest non-zero bit is bit 0, state = 1.	
4	0000000000000100	The lowest non-zero bit is bit 2, state = 3.	
7	0000000000000111	The lowest non-zero bit is bit 0, state = 1.	
8	000000000001000	The lowest non-zero bit is bit 3, state = 4.	
16	000000000010000	The lowest non-zero bit is bit 4, state = 5.	
32	000000000100000	The lowest non-zero bit is bit 5, state = 6.	
64	000000001000000	The lowest non-zero bit is bit 6, state = 7.	
128	000000010000000	The lowest non-zero bit is bit 7, state = 8.	
256	000000100000000	The lowest non-zero bit is bit 8, state = 9.	
512	0000001000000000	The lowest non-zero bit is bit 9, state = 10.	
1024	0000010000000000	The lowest non-zero bit is bit 10, state = 11.	
2048	0000100000000000	The lowest non-zero bit is bit 11, state = 12.	
4096	00010000000000000	The lowest non-zero bit is bit 12, state = 13.	
8192	0010000000000000	The lowest non-zero bit is bit 13, state = 14.	
16384	01000000000000000	The lowest non-zero bit is bit 14, state = 15.	
32768	10000000000000000	The lowest non-zero bit is bit 15, state = 16.	

## **Bit combination**

Lamp state depends on the states of bit combinations, where PLC 1



represents the least significant bit (LSB), PLC 2 represents the next LSB, and so on. Maximum number of bit is 4, for a total of 16 states. Changing [No. of states] in Attribute group box changes the number of read addresses.



#### Change state by time

The state displayed changes on a time basis. The frequency can be set.

#### **Read address**

Click [Setting] to select the [PLC name], [Address], [Device type], [System tag], [Index register] of the word device that controls the [Word Lamp] object. Users can also set address in [General] tab while adding a new object.

#### **Attribute**

## No. of states

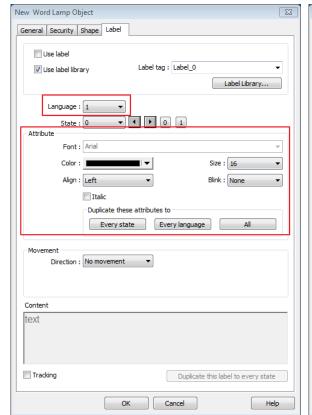
The number of states is utilized by the object. The state is numbered from 0, so the number of states minus 1 will be the state number. If the value within the word register is  $\geq$  [No. of states] defined in Attribute, the highest state will be displayed. If the number of states is set to 8, the valid states will be 0, 1, 2, ..., 7. In this case if the word value is 8 or higher, the system will display the state 7 shape.

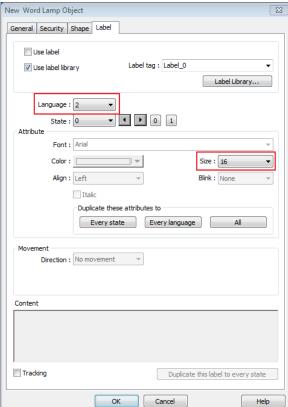
Hide picture/shape if no corresponding picture for current state If selected, when there are not enough pictures to represent all the states, hides the picture. Otherwise, displays the last state.



■ In [Label] tab, Language 1 determines the relevant settings of the font. For Language 2~8, only the font size can be changed and other settings follow Language 1.









## 13.3. Set Bit

#### **13.3.1.** Overview

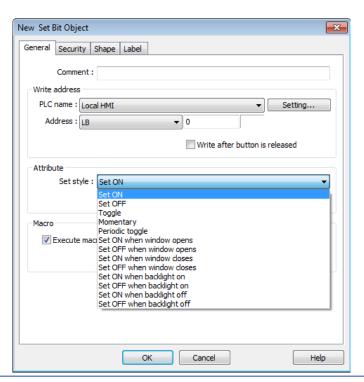
The Set Bit object provides two operation modes: manual or automatic. Manual mode can trigger a designated bit address to change the state between ON and OFF when the object is touched. In automatic mode, the bit is automatically activated when a pre-defined condition occurs; touching the button will not be effective.

#### 13.3.2. Configuration



Click [Object] » [Set Bit] icon on the toolbar to open a Set Bit object property dialog box. Set up the properties, press OK button, and a new Set Bit object will be created.

#### **General Tab**



#### Setting

#### **Description**

#### Write address

Click [Setting] to select the [PLC name], [Address], [Device type], [System tag], [Index register] of the bit device that controls the Set Bit object. Users can also set address in [General] tab while adding a new object.

Write after button is released



13-11 Objects

If this function is selected, the action is delayed till button is	
released; otherwise, the action is executed once the button is	S
pressed. This function does not work with momentary buttor	١S.

Mode / Offset	Set style	Description	
Wode / Offset	Set ON	Set ON the designated bit of the device.	
	Set OFF	Set OFF the designated bit of the device.	
	Toggle	Alternates the bit state each time pressed.	
	Momentary	Holds the bit ON only while button is pressed.	
	Periodical toggle	Set a designated bit ON and OFF at a set time interval. Time interval can be selected; the range is from 0.1 to 25.5 seconds.	
	Set ON when window opens	Set ON the bit within the window when the window opens.	
	Set OFF when window opens	Set OFF the bit within the window when the window opens.	
	Set ON when window closes	Set ON the bit within the window when the window closes.	
	Set OFF when window closes	Set OFF the bit within the window when the window closes.	
	Set ON when backlight on (N/A for cMT-SVR)	Set the bit ON when the backlight is turned ON.	
	Set OFF when backlight on (N/A for cMT-SVR)	Set the bit OFF when the backlight is turned ON.	
	Set ON when backlight off (N/A for cMT-SVR)	Set the bit ON when the backlight is turned OFF.	
	Set OFF when backlight off (N/A for cMT-SVR)	Set the bit OFF when the backlight is turned OFF.	
Macro	Set Bit object can t	rigger the start of a Macro routine when the	
	Macro has been cre	eated in advance.	
	For more infor	mation, see "18 Macro References".	

# **Note**

In [Label] tab, if select [ON=OFF (use state 0)] check box, both state 0 and 1 follow the settings of state 0.

or at both of the changes of state.



 Using address types other than PLB or PLW\_Bit for Set Bit objects with [Periodic Toggle] attribute is not supported by cMT-SVR.

- The Set Style setting in the General tab determines which settings are available in the Security tab. When the Set Style is [Set ON / OFF when window opens], there will be no settings available in the Security tab.
- When [Execute macro] is selected, the sequence in which the object's write operation and the macro execution is determined by the HMI runtime. In order to exactly arrange the write operation and the macro execution in the desired way, specify the sequence by configuring a Combo Button instead.



## 13.4. Set Word

#### **13.4.1.** Overview

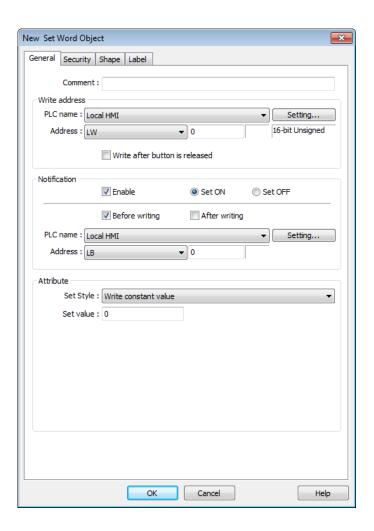
The Set Word object provides two operation modes: manual or automatic. Manual mode can change the value in a designated word address when the object is touched. In automatic mode, the word register is automatically activated when a pre-defined condition occurs; touching the button will not be effective.

## 13.4.2. Configuration



Click [Object] » [Set Word] icon on the toolbar to open a Set Word object property dialog box. Set up the properties, press OK button, and a new Set Word object will be created.

#### **General Tab**





Setting	Description		
Write address	Click [Setting] to select the [PLC name], [Address], [Device type],		
	[System tag], [Index register] of the word device that controls the		
	Set Word object. Users can also set address in [General] tab while		
	adding a new object.		
	Write after button is released		
	If this function is selected, the action is delayed till button is		
	released; otherwise, the action is executed once the button is		
	pressed.		
Notification	If this check box is selected, it will notify a designated bit address		
	(setting ON or OFF).		
	Before writing / After writing		
	Set the state of the designated bit address before or after the		
	manual operation.		
Attribute	Set Style		
	Select the button action from the drop down list, see Example 2.		
	Dynamic limits		
	Set the [Bottom limit] and [Upper limit] by a designated register,		
	see Example 1.		

## **Example 1**

Set the [Bottom limit] and [Upper limit] by a designated register. When Dynamic Address is LW-n, where n is an arbitrary number, the rule of setting Upper / Bottom limit is:

Content	16-bit	32-bit	64-bit (cMT / cMT X only)
Dynamic address	LW-n	LW-n	LW-n
Bottom limit	LW-n	LW-n	LW-n
Upper limit	LW-n+1	LW-n+2	LW-n+4
When Dynamic Address is	LW-100, the rule	e of setting Uppe	r / Bottom limit is:
Content	16-bit	32-bit	64-bit (cMT / cMT X only)
Dynamic address	LW-100	LW-100	LW-100
Bottom limit	LW-100	LW-100	LW-100
Upper limit	LW-101	LW-102	LW-104

## **Example 2**

The available button actions are:

## Write constant value

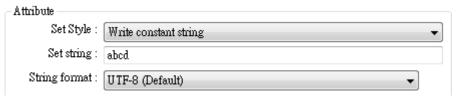
Write a preset value. Each time the button is pressed, the value in [Set value] is written to the designated register. Data format is as set by the [Write address] above; it can be 16-bit BCD, 32-bit BCD, ...64-bit Double. In the following figure, when the button is pressed, the number 12 is written to the designated register.





## Write constant string (cMT / cMT X only)

Write a preset string. Each time the button is pressed, the string in [Set string] is written to the designated register. The string format can be: UTF-8, Unicode, Latin-1...etc. In the following figure, when the button is pressed, the string "abcd" is written to the designated register.



## Increment value (JOG+)

Increase value in register by a set amount in [Inc. value], each time when the button is pressed, up to the [Upper limit]. As shown below, each button press increases the value in the register by 1 until the value is 10.



#### Decrement Value (JOG-)

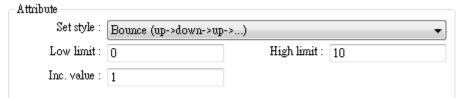
Decrease value in register by a set amount in [Dec. value], each time when the button is pressed, down to the [Bottom limit]. As shown below, each button press decreases the value in the register by 1 until the value is 0.



#### Bounce (up->down->up) (cMT / cMT X only)

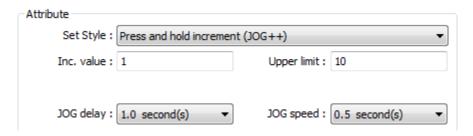
Each time when the button is pressed, the value in the register is increased by the [Inc. value] until the [High limit] is reached, and then the value is decreased by the [Inc. value], each time when the button is pressed, down to the [Low limit]. As shown below, the system will increase the value in the register by 1 each time when the button is pressed, until the value is 10, and then decrease the value by 1 each time when the button is pressed, until the value is 0, and then increase the value again.





## Press and hold increment (JOG++)

When the button is held longer than a set time in [JOG delay], it will increase the value in a register by a set amount :[Inc. value] at a set rate :[JOG speed], to the [Upper limit]. As shown below, when the button is pressed, it increases the value in the designated register by 1. When the button is held longer than 1 second, it increases the value in register by 1 every 0.5 second, till the value is 10.



## Press and hold increment (JOG--)

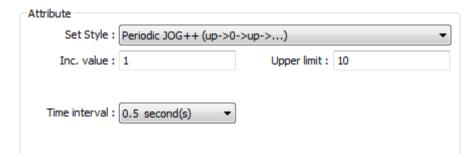
When the button is held longer than a set time in [JOG delay], it will decrease the value in a register by a set amount: [Dec. value] at a set rate: [JOG speed], to the [Bottom limit]. As shown below, when the button is pressed, it decreases the value in the designated register by 1. When the button is held longer than 1 second, it decreases the value in register by 1 every 0.5 second, till the value is 0.

Attribute			
Set Style :	Press and hold decrement (JOG)		
Dec. value :	1	Bottom limit :	0
JOG delay :	1.0 second(s) ▼	JOG speed :	0.5 second(s) ▼

#### Periodic JOG++

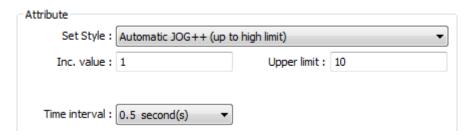
This automatic function increases the value in the register by a set amount: [Inc. value], at a set rate: [Time interval], to the [Upper limit]. As shown below, the system will automatically increase the value in the register by 1 every 0.5 second, till the value is 10. Then the value returns to 0 and add 1 every 0.5 second again.





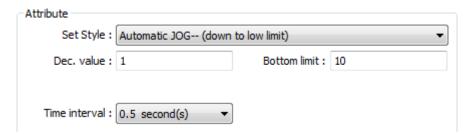
#### Automatic JOG++

This automatic function increases the value in the register by a set amount: [Inc. value], at a set rate: [Time interval], to the [Upper limit].then holds this value. As shown below, the system will automatically increase the value in the register by 1 every 0.5 second, till the value is 10, and then stop.



#### Automatic JOG--

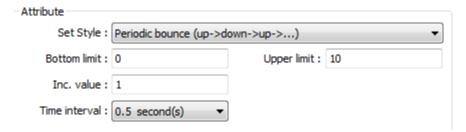
This automatic function decreases the value in the register by a set amount: [Dec. value], at a set rate: [Time interval], to the [Bottom limit].then holds this value. As shown below, the system will automatically increase the value in the register by 1 every 0.5 second, till the value is 10, and then stop.



#### Periodic bounce

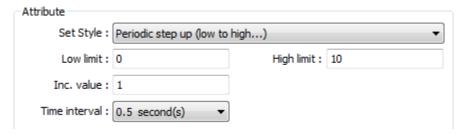
Increases the word address value to the [Upper limit] by a [Inc. value] at a set rate in [Time interval], then decreases to the [Bottom limit] by the same value at the same rate. As shown below, the system will increase the value in the designated register by 1 every 0.5 second, till the value is 10, and then decrease the value by 1 every 0.5 second till the value is 0 whenever the screen is active.





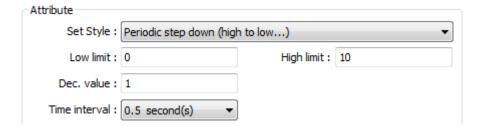
## Periodic step up

Step up to the [High limit] by [Inc. value] at a set rate in [Time interval], then reset immediately to the [Low limit]. The action repeats whenever the screen is active. As shown below, the system will increase the value in the designated register by 1 every 0.5 second, till the value is 10, and then reset to 0 and increase again, and the action repeats.



## Periodic step down

Step down to the [Low limit] by [Dec. value] at a set rate in [Time interval], then reset immediately to the [High limit]. The action repeats whenever the screen is active. As shown below, the system will decrease the value in the designated register by 1 every 0.5 second, till the value is 0, and then reset to 10 and decrease again, and the action repeats.



#### Set when window opens / Set when window closes

Automatic function occurs whenever the screen is active. The value entered in [Set value] is set into the word address when the action occurs. If [Set value] is set to 5, when the window opens / closes, the system enters 5 into the designated register.

- Set when backlight on / Set when backlight off (Not supported on cMT-SVR)

  Automatic function occurs whenever the backlight is active. The value entered in [Set value] is set into the word address when the action occurs. If [Set value] is set to 5, when the backlight turns ON / OFF, the system sets 5 into the designated register.
- Cyclic JOG+

Each time when the button is pressed, increases the word address value to the [Upper limit] by



[Inc. value] then reset to the [Bottom limit]. As shown below, each time when pressing the button, the system will increase the value in the designated register by 1, till the value is 10, and then reset to 0 and increase again by pressing the button.



## Cyclic JOG-

Each time when the button is pressed, decrease the word address value to the [Bottom limit] by [Dec. value] then reset to the [Upper limit]. As shown below, each time when pressing the button, the system will decrease the value in the designated register by 1, till the value is 0, and then reset to 10 and decrease again by pressing the button.



## Cyclic JOG++

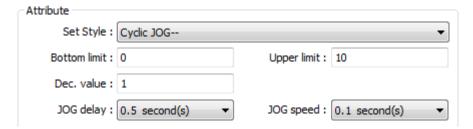
When the button is held longer than a set time in [JOG delay], it increases the value in a register by a set amount in [Inc. value] at a set rate in [JOG speed], to the [Upper limit], then reset to the [Bottom limit]. As shown below, when the button is held longer than 0.5 second, increase the value in the designated register by 1 every 0.1 second, till the value is 10, and then reset to 0 and increase again by holding the button.



## Cyclic JOG- -

When the button is held longer than a set time in [JOG delay], decrease the value in a register by a set amount in [Dec. value] at a set rate in [JOG speed], to the [Bottom limit], then reset to the [Upper limit]. As shown below, when the button is held longer than 0.5 second, decrease the value in the designated register by 1 every 0.1 second, till the value is 0, and then reset to 10 and decrease again by holding the button.





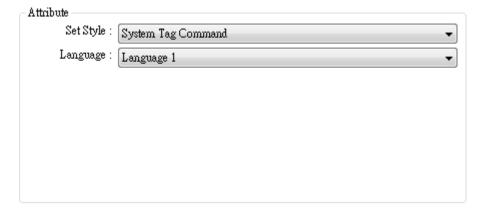
## Object Control Command (cMT / cMT X only)

Listed for selection are commands (with their corresponding command values) available for the control address of various functions. For a given function, with write address set to its control address, Set Word writes the command value and achieves function control.



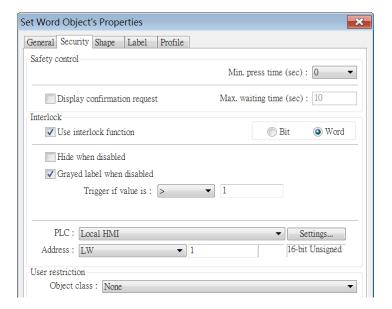
## System Tag Command (cMT / cMT X only)

When a system tag is set as write address, for example, LW-9134: Language Mode, the commands relating to the system tag can be selected.



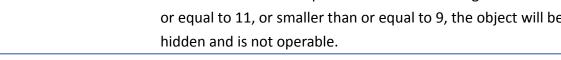


## **Security Tab**





Setting	Description
Interlock	Use interlock function
	When this option is enabled and [Word] is selected, whether
	the object is operable depends on the condition of a word
	address specified in [Trigger if value is:]. In the settings above,
	the object is operable only when the value in LW-1 is greater
	than 1.
	Hide when disabled
	The object is hidden when the specified condition does not
	occur in the specified word address.
	Grayed label when disabled
	The label of the object turns gray when the specified condition
	does not occur in the specified word address.
	button
	Trigger if value is:
	This setting is for specifying a trigger condition. The available
	options are: >, <, ==, <>, >=, and <=. A tolerance value can be
	set for conditions == and <>.
	For example:
	☑ Hide when disabled
	Grayed label when disabled
	Trigger if value is : ==
	Tolerance : 1
	When the value is the specified word address is greater than
	or equal to 11, or smaller than or equal to 9, the object will be





Using address types other than PLW for Set Word objects with automatic attributes such as [Periodic set up], [Periodic set down], [Automatic JOG++], [Automatic JOG--], and [Periodic JOG++]...etc, is not supported by cMT-SVR.



## 13.5. Function Key

#### 13.5.1. Overview

The Function Key object can be used for several tasks, such as switching between windows, keypad design, Macro execution, screen hardcopy, and setting USB security key.

Function Keys with [Screen hardcopy] or [Import user data/Use [USB Security Key]] selected do not work remotely on cMT Viewer.

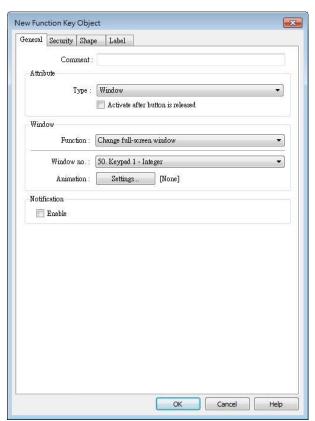
## 13.5.2. Configuration



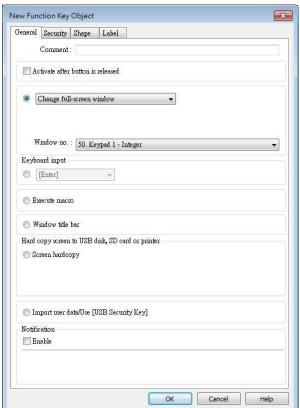
Click [Object] » [Function Key] icon on the toolbar to open a Function Key object property dialog box. Set up the properties, press OK button, and a new Function Key object will be created.

### **General Tab**

cMT / cMT X Series



eMT, iE, XE, mTV Series

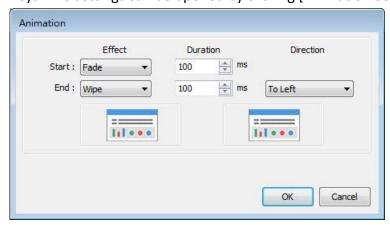




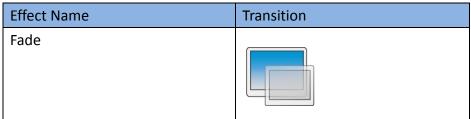
Setting	Description		
Activate	If this function is selected, the action is delayed till button is		
after button	released; otherwise, the action is executed once the button is		
is released	pressed.		
Change	Change full-screen window: Change to another base window.		
window	Change common window: Change common window.		
	Display popup window: A pop-up window displays in the base		
	window. If [Close this popup window when parent window is closed]		
	check box is selected, the pop up window will be closed when		
	change the base window to another window. Otherwise, a function		
	key in the pop up window is needed to close it.		



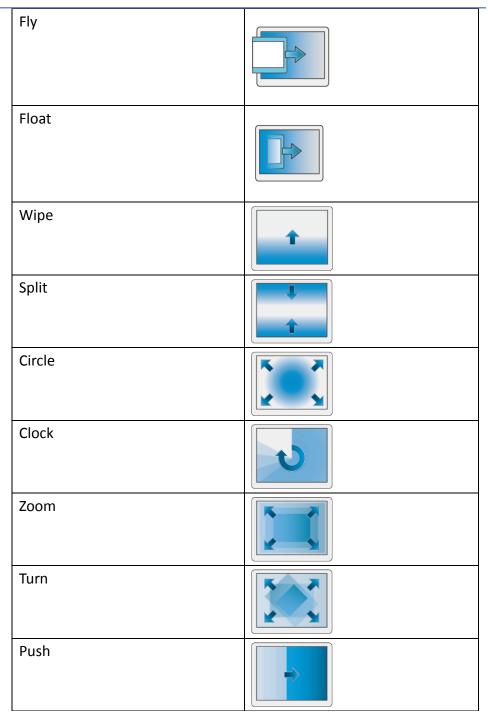
(cMT / cMT X Series) Animation Setting: cMT / cMT X Series allows using transition effects for opening popup windows using Function Keys. The settings can be opened by clicking [Animation Setting].



The effects are shown below. Different effects may be used for Start (window appears) and End (window disappears).







[Duration] specifies how many milliseconds (ms) a transition effect takes to complete.

[Direction] The direction of the transition.

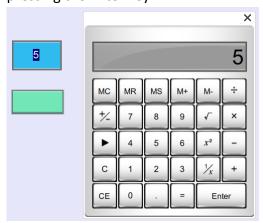
**Return to previous window:** If this is selected, the Function Key will change from the current screen to the previous one displayed. For example, when window no. 10 is changed to window no. 20, press the function key to return to window no. 10. This function is only available for base window.

Close window: Close any active pop-up windows, message windows

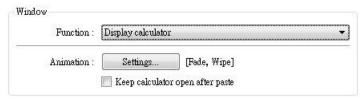


included.

**Display calculator window(cMT / cMT X Series):** If this option is selected, clicking this Function Key can open a calculator with an unchangeable appearance. This calculator allows operators to do simple calculation and enter the result to a destination object by pressing the Enter key.



Selecting this option opens [Keep calculation open after paste] checkbox, which keeps the calculator displayed after the value is entered to the object.



Click the icon to watch the demonstration film. Please confirm your internet connection before playing the film.

## Keyboard Input

Configures the button as a keypad key, and the character it enters, via [Numeric] or [ASCII] objects.

**Enter:** Same as the keyboard's "Enter" function.

**Backspace:** Same as the keyboard's "Backspace" function.

**Clear**: Clear the value in the word register.

**Esc:** Same as the [Close window] function; it is used to close the keyboard window.

**Delete:** Same as the keyboard's "Delete" function, deletes the number or character on the right side of the text cursor.

**Left:** Same as the keyboard's " $\leftarrow$ " key moves the text cursor to the left side of the previous number or character.

**Right:** Same as the keyboard's " $\rightarrow$ " key moves the text cursor to the left side of the next number or character.

Line feed: Move the cursor down to the next line.



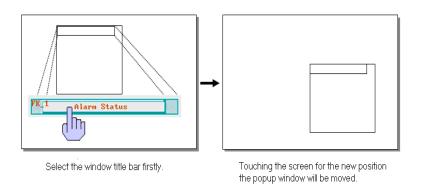
> Inc: Increment by 1. **Dec:** Decrement by 1. **ASCII/UNICODE:** Specify the character to be entered by this key. Select this check box to execute one of the Macros from the drop down list that has already been configured by users. For more information, see "18 Macro References". Macro: [ID:000] macro\_0 Execute macro

## Window title bar

**Execute** 

Macro

Function Key defined can be used to move a pop-up window which has no [window title bar] to a preferred position on screen. Select the pop-up window and then click on a preferred position, the window will be moved.



Click the icon to download the demo project. Please confirm

your internet connection before downloading the demo project.

Hard copy screen to USB disk, SD card or printer

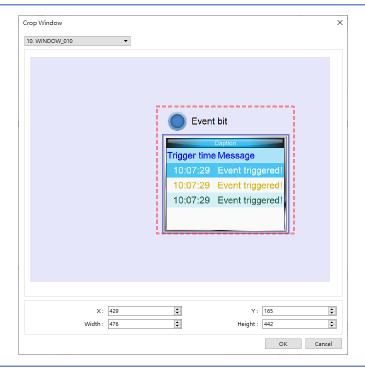
Print the current window. Before using this function, choose a printer model in [System Parameter Settings] » [Model] » [Printer].

If a monochrome printer is used, selecting [grayscale] can provide a better print result, but the text may not be clearly printed. To improve text printing, avoid using [grayscale].



### **Crop window**

This option can be selected for taking a cropped screenshot.



Acknowledge all events (alarms) (cMT / cMT X

Acknowledge all events once by pressing the Function Key.

Import user data / Use [USB Security Key]

Series)

A Function Key can be used to import the e-mail contacts or user accounts set, also, to log in using USB Security Key.



#### **Data Position**

Select the external device to store data from [SD card] or [USB disk].

## **Account import mode**

If [Overwrite] is selected, the existing accounts will be overwritten with new accounts in the external device after importing. If [Append] is selected, HMI will append more accounts while the old accounts



	still exist.
	Please note that when [Append] is selected, the accounts that
	already exist in the project cannot be imported.
	Delete file after importing user accounts
	If select this check box, the system will delete the account data saved
	in the external device after importing, this can prevent the account
	data from leaking out.
Notification	If this selection is enabled, it will notify a designated bit address to
	set ON or OFF, each time the button is pressed.



[Overwrite] is the only option when importing the e-mail contacts. This means that all existing contacts will be removed first, and then the new contacts are added.

For more information, see "6 Window Operations", "12 Keypad Design and Usage", "36 Administrator Tools".



## 13.6. Toggle Switch

#### **13.6.1.** Overview

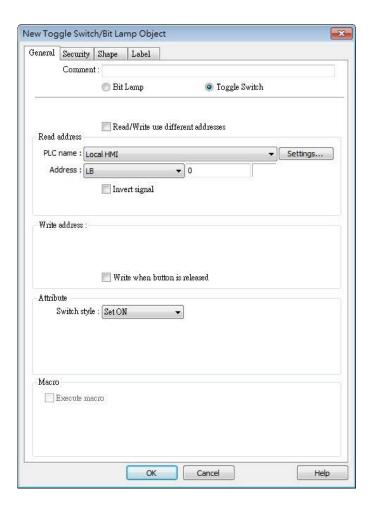
Toggle Switch object is a combination of Bit Lamp object and Set Bit object. The appearance of the object is controlled by the ON / OFF state of the read bit address. As well, pressing the button sets the value in the bit address according to the settings.

## 13.6.2. Configuration



Click [Object] » [Toggle Switch] icon on the toolbar to open a Toggle Switch object property dialog. Set up the properties, press OK button, and a new Toggle Switch object will be created.

#### **General Tab**





Setting	Description		
Comment	User can describe the information of the object.  Bit Lamp / Toggle Switch		
	Switch between	Bit Lamp and Toggle Switch features.	
Read/Write			
use different	Different addres	ses can be used to read data and write data.	
addresses			
Read address	Click [Setting] to	select the [PLC name], [Address], [Device type],	
	[System tag], [Index register] of the bit device that controls the		
	[Toggle Switch]	object. Users can also set address in [General] tab	
	while adding a n	ew object.	
	Invert signal		
	Reverses the display of ON / OFF states. For example, if [Invert		
	signal] check box is selected, when the designated bit is OFF, the		
	object displays ON state.		
	When [Read/Write use different addresses] option is not selected,		
	the title of this group box will be "Read/Write address".		
Write address	Click [Setting] to select the [PLC name], [Address], [Device type],		
	[System tag], [Index register] of the bit device that controls the		
	[Toggle Switch] object. Users can also set address in [General] tab		
	while adding a new object. The address can be the same or		
	different from [Read address].		
	Write after butt	on is released	
		s selected, the action is delayed till button is	
	,	vise, the action is executed once the button is	
	•	nction does not work with momentary buttons.	
Attribute	Set style Set ON	Description  Cat ON the designated bit of the design	
	Set OFF	Set ON the designated bit of the device.	
	Toggle	Set OFF the designated bit of the device.	
	Momentary	Alternates the bit state each time pressed.	
	ivioinentary	Holds the bit ON only while button is	
		pressed.	
Macro		pject can trigger the start of a Macro routine when	
	the Macro has b	een created in advance.	
	For more in	formation, see "18 Macro References".	





■ When [Execute macro] is selected, the sequence in which the object's write operation and the macro execution is determined by the HMI runtime. In order to exactly arrange the write operation and the macro execution in the desired way, specify the sequence by configuring a Combo Button instead.



## 13.7. Multi-State Switch

#### 13.7.1. Overview

Multi-state Switch object is a combination of Word Lamp object and Set Word object. The appearance of the object is controlled by the value of the read word address. As well, pressing the button sets the value in the word address according to the settings.

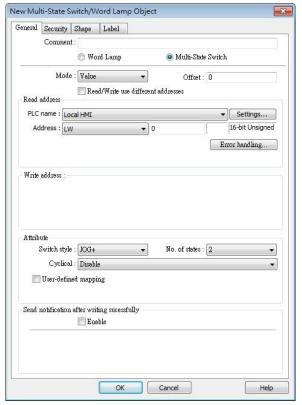
## 13.7.2. Configuration



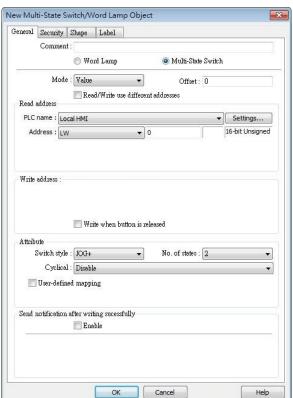
Click [Object] » [Multi-State Switch] icon on the toolbar to open a Multi-State Switch object property dialog box. Set up the properties, press OK button, and a new Multi-State Switch object will be created.

#### **General Tab**

## cMT / cMT X Series



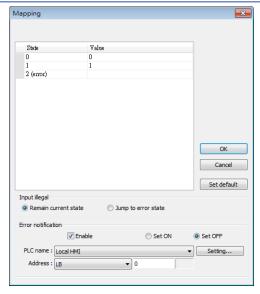
eMT, iE, XE, mTV Series





Setting	Description			
Comment	User can describe the information of the object.  Word Lamp / Multi-State Switch			
	Switch between Word Lamp and Multi-State Switch features.			
Model /	Different modes can be selected: [Value], [LSB].			
Offset	For more information, see "13.2 Word Lamp".			
Read/Write				
use different	Different addresses can be used to read data and write data.			
addresses				
Read address	Click [Setting] to select the [PLC name], [Address], [Device type],			
	[System tag], [Index register] of the word device that controls the			
	Multi-state Switch object. Users can also set address in [General]			
	tab while adding a new object.			
	When [Read/Write use different addresses] option is not selected,			
	the title of this group box will be "Read/Write address".			
Write address	Click [Setting] to select the [PLC name], [Address], [Device type],			
	[System tag], [Index register] of the word device that controls the			
	Multi-state Switch object. Users can also set address in [General]			
	tab while adding a new object.			
	Write after button is released			
	If this function is selected, the action is delayed till button is			
	released; otherwise, the action is executed once the button is			
	pressed.			
Attribute	Switch style			
	Select the object's operation mode, see Example 1.			
	User-defined mapping			
	The value placed in the write register of each selection, the action			
	taken when an illegal value is entered, and error notification to a			
	designated bit address can be set.			





#### Remain current state

If an illegal value is entered, Multi-state Switch will remain at the current state.

### Jump to error state

If an illegal value is entered, Multi-state Switch will jump to the error state.

#### **Error notification**

If an illegal value is entered, automatically set the value placed in the designated register.

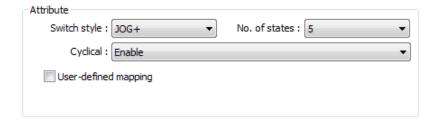
Send			
notification	After the system successfully writes data to PLC, the designated bit		
after writing	address will be set On/Off.		
successfully			
Error handling	The action taken when an illegal value is entered or notify a		
(cMT / cMT X	designated bit address. This is similar to [User-defined mapping];		
Series)	the difference is the value corresponding to each state need not to		
	be preset.		

## **Example 1**

#### JOG+

Increase the value of a designated register by 1 each time when pressing the button, till the value equals to [No. of states]. A cyclic action can be enabled. As shown below, each time when pressing the button, the state number will add 1 start from state 0, till state 4 ([no. of state]-1), and returns to 0 and step up again.





#### JOG-

Decrease the value of the designated register by 1 each time when pressing the button, till the value equals to 0. A cyclic action can be enabled. As shown below, each time when pressing the button, the state number will minus 1 start from state 4 ([no. of state]-1), till state 0, and returns to state 4 and step down again.





## 13.8. Slider

### 13.8.1. Overview

Slider object is used to change the value in a designated word register address by moving the slide on the screen.

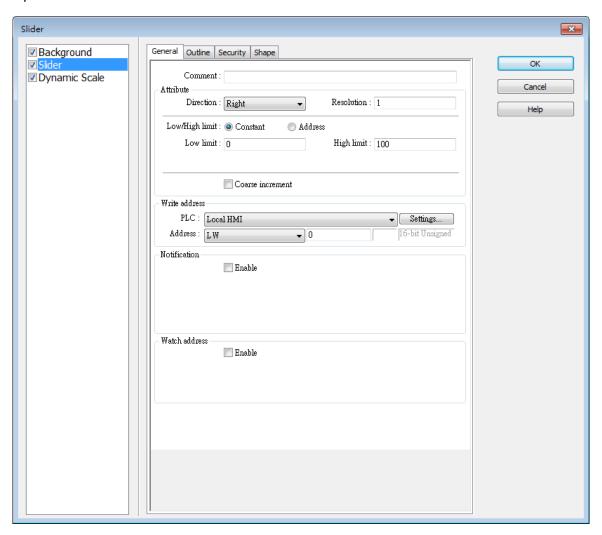
## 13.8.2. Configuration



Click [Object] » [Slider] icon on the toolbar to open a Slider object property dialog box. Set up the properties, press OK button, and a new Slider object will be created.

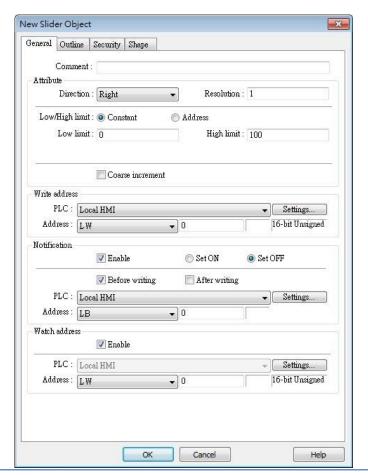
## **General Tab**

## cMT / cMT X





eMT, iE, XE, mTV



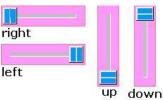
## **Setting**

## **Description**

#### **Attribute**

#### **Direction**

Select the direction of the slider. (Right, Up, Left, Down)



#### Resolution

Sets the value change in the word register for each step of the Slider. For example, if set to 10, the register value changes by 10 points for each increment or decrement on the Slider.

#### Constant

Sets the range of the Slider. For example, If set [Low limit] to 5, and [High limit] to 100, the Slider will enter values between 5 and 100.

#### **Address**

Set the [Low/High limit] by a designated register, see Example 1.

#### **Coarse increment**

Apart from moving the roller to change the value as in [Resolution],



if this option is selected, the word value will increase / decrease by		
the [Increment] value each time the object is touched.		
Click [Setting] to select the [Device], [Address], [Device type],		
[System tag], [Index register] of the word device that controls the		
Slider object. Users can also set address in [General] tab while		
adding a new object.		
If enabled, the state of a designated bit address will be set to ON or		
OFF before or after writing.		
Click [Setting] to select the [Device], [Address], [Device type],		
[System tag], [Index register] of the bit device that controls the		
notification settings. Users can also set address in [General] tab		
while adding a new object.		
[Before writing] / [After writing]		
Change the state of a designated bit register before, or after the		
slider is slid.		
Shaci is sha.		
When moving the roller, the new value written to the word register		

## Example 1

Set the low or high limit by a designated register. When write address is LW-n, where n is an arbitrary number, the rule of setting limits is:

Content	16-bit	32-bit	64-bit (cMT / cMT X only)
Address	LW-n	LW-n	LW-n
Low limit	LW-n	LW-n	LW-n
High limit	LW-n+1	LW-n+2	LW-n+4

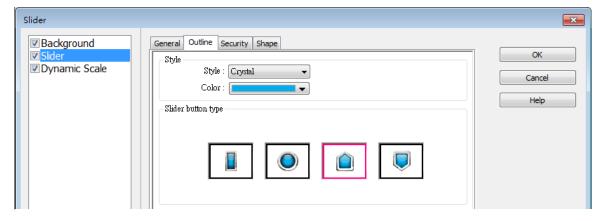
When address is LW-100, the rule of setting limits is:

Content	16-bit	32-bit	64-bit (cMT / cMT X only)
Address	LW-100	LW-100	LW-100
Low limit	LW-100	LW-100	LW-100
High limit	LW-101	LW-102	LW-104

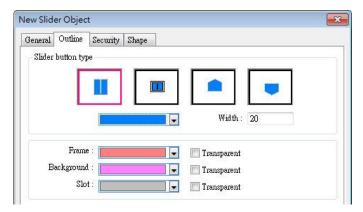
## **Outline Tab**

cMT / cMT X Seires





eMT, iE, XE, mTV Seires



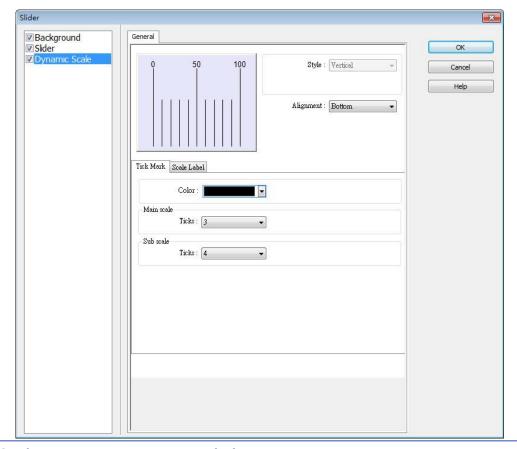
Setting	Description		
Slider button type (cMT / cMT X)	Select slider button type, by default, a picture selected from the Picture Library can be the slider button.		
Slider button type (eMT, iE, XE, mTV)	Four default styles are offered, and the width and color of the Frame, Background, Slot can be set.  Slider button type  Slot		
	Frame Background		

# 13.8.3. Combo Setting

cMT / cMT X Series HMI support combo setting for Slider, which allows setting of multiple related objects at a time. Slider can be set with Background and Dynamic Scale.



# **Background**



# **Setting**

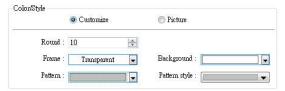
# Description

# Margin

Specify the space between the background edge and the objects.

# Color/Style

#### Customize



Select a suitable background pattern and color.

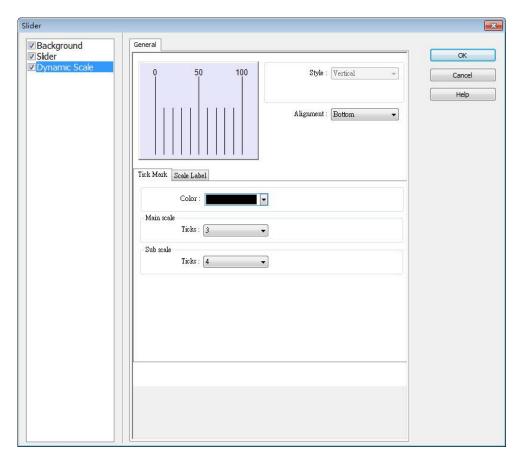
#### **Picture**



Use the default picture or choose a picture from Picture Library.

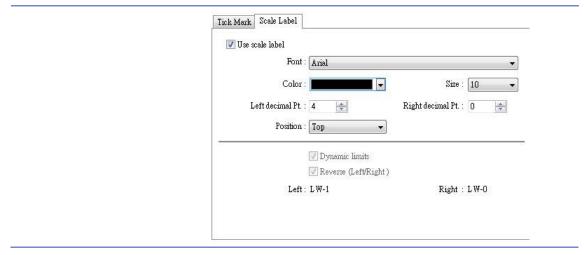


# **Dynamic Scale**



Setting	Description		
Style	The scale style will follow the Slider.		
Alignment	The position of the scale bar along the Slider.		
Tick Mark	Configure the number of tick marks for main and		
	sub scales, and the color of tick marks.		
Scale Label	Configure the font, font color, font size and other		
	attributes of scale label.		
	In Slider settings if [Address] is selected for		
	Low/High limit, then Scale Label's [Dynamic limits]		
	will be set automatically.		
	In Slider settings if [Left] is selected for Direction,		
	then Scale Label's [Reverse (Left/Right)] will be set		
	automatically.		







# 13.9. Numeric

#### **13.9.1.** Overview

Numeric object can be used to input or display the value of a designated word register.

# 13.9.2. Configuration

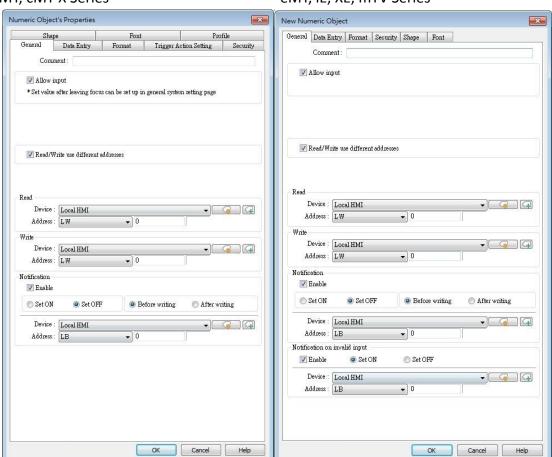


Click [Object] » [Numeric] icon on the toolbar to open a Numeric object property dialog box. Set up the properties, press OK button, and a new Numeric object will be created.

#### **General Tab**

#### cMT, cMT X Series

eMT, iE, XE, mTV Series



Setting	Description		
Allow input	If selected, the input features and relevant settings are enabled.		
Read / Write	Different addresses can be used to read data and write data.		

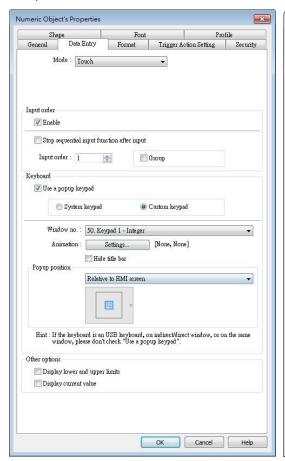


use different address			
Read address	Click [Setting] to select the [Device], [Address], [Device type],		
	[System tag], [Index register] of the word device that displays the		
	value. Users can also select a tag defined in Address Tag Library.		
	When [Read/Write use different addresses] option is not selected,		
	the title of this group box will be "Read/Write address".		
Write address	Select the [Device], [Device type], [Address] of the word device		
	that system writes to.		
Notification	With notification enabled, the state of the designated bit address		
	can be set on / off, before / after writing.		
	Notification works differently comparing cMT / cMT X Series with		
	eMT/iE/XE/mTV Series.		
	cMT/cMT X Series: Trigger the object to open a keyboard window »		
	Notification before writing » Enter a value and press ENTER » Start		
	writing operation » Notification after writing.		
	eMT/iE/XE/mTV Series:		
	Trigger the object to open a keyboard window » Enter a value and		
	press ENTER » Notification before writing » Start writing operation		
	» Notification after writing.		
Notification	If an illegal value is entered, automatically set the state of a		
on invalid input	designated register.		



#### **Data Entry Tab**

# cMT, cMT X



eMT, iE, XE, mTV Series



Setting	Description			
Mode	Touch			
	Used when data entry is initiated by touching the screen object.			
	Bit control			
	Used when data entry is enabled by turning ON a designated bit,			
	and entry ends when the bit goes OFF.			
Input control	Specify a bit address that enables or ends data entry. The order of			
	data entry is specified in [Input order] and an external USB			
	keyboard is needed for data entry. For cMT-SVR, use cMT Viewer's			
	keyboard.			
Input order	Perform continuous input by setting [Input order] and [Group].			
	The criterion of searching the next input object:			
	<ul> <li>The range of [Input order]: 1 ~ 511, range of [Group]: 1 ~ 15.</li> </ul>			
	<ul><li>If [Group] is not selected, its input order is 0.</li></ul>			
	<ul> <li>The system only searches for the objects within the same</li> </ul>			



Group.

 The lower number of order is entered before the higher number of order.

 For multiple objects within the same group and with the same input order, the object placed in the lower layer is entered first.

Click the icon to download the demo project. Please confirm

your internet connection before downloading the demo project.

#### **Keyboard**

#### Use a popup keypad

If selected: A pre-designed pop-up keypad can be chosen by selecting a check box and selecting the relative position on the HMI screen. When data entry is enabled, the pop-up keypad displays in the selected position, and closed when data entry ends.

If not selected: When data entry is enabled, the pop-up keypad is not displayed. Users may:

- Create a custom design on the same screen window.
- Use a USB keyboard.

#### System keypad

cMT / cMT X Series model has its own system keypad, select this checkbox to use the system keypad, or select [Custom keypad] to set up a customized keypad.

#### **Animation Setting**

When using a cMT / cMT X Series model with [Custom keypad] selected, the transition effect of the keypad window can be selected.



See Chapter 13.5 Function Key in this manual for the list of effects.

#### Hide title bar

Use a keypad without the title bar.

#### Popup position

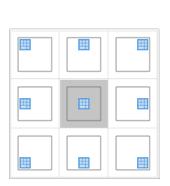
When using a cMT / cMT X Series model with [Custom keypad] selected, the position where the keypad pops up can be selected.

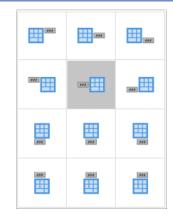
The position can either be relative to HMI screen or relative to object.

Relative to HMI screen

Relative to object







#### Restart the keypad if input value is out of range

When entering data, if the value entered is not within the valid range, the system will automatically restart the keypad.

# Other options (For cMT / cMT X Series)

# Display lower and upper limits

If selected, when entering a value, the range is displayed near the object.

# Display previous value

If selected, when entering a value, the value before update is displayed near the object.



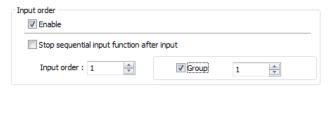
To create a keyboard in current window, see "12 Keypad Design and Usage".

Click the icon to watch the demonstration film. Please confirm your internet connection before playing the film.

# **Example 1**

This example demonstrates how to use [Input Order] and [Group] to perform continuous input in several Numeric objects. After entering data in one object, entry will be passed to the next input order object which is in the same group.

Create three Numeric objects, and set [Input order] to 1, 2, and 3 respectively. Include
the three objects in [Group 1] as shown in the following figure.
LW-0

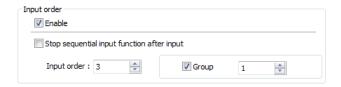


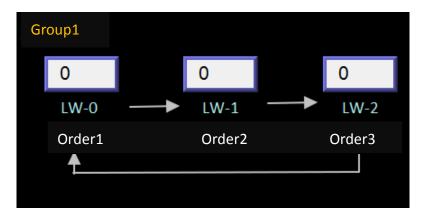
LW-1





LW-2



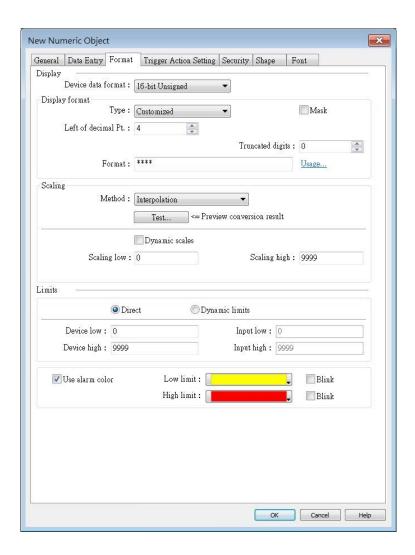


2. When finish entering data in the last object, to end data entry of all objects, please select [Stop sequential input function after input] check box.





#### **Format Tab**



Setting	Description		
Device Data	Set the data format of a designated word register. Options include:		
Format	BCD, Binary, Unsigned, Signed, HEX, and Float. 16-bit uses 1 word		
	where 32-bit uses two words.		
	Mask		
	If selected, any values entered will be hidden by displaying them as		
	asterisks "*".		
Display	Default		
format	General Numeric formats.		
	Customized		
	Each "*" sign represents each integer digit, and each "#" sign		
	represents each fraction digit that will be displayed in the Numeric		
	object. Float and Double formats are only supported on cMT / cMT		
	X models.		



Apart from "\*" signs, extra texts can be entered in the [Format] field, for example: kg. The available alignment options are: [Left], [Center], [Right], [Leading zero].

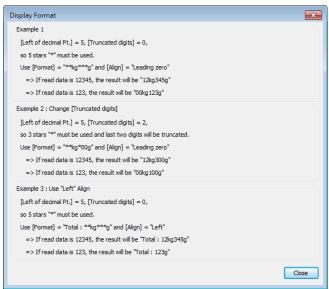
The numeric value represented by "\*" sign will be displayed from the highest digit to the lowest in the Numeric object.

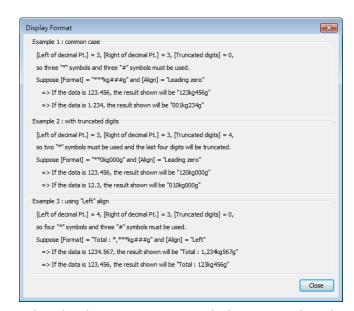
#### **Truncated digits**

Specify the number of digits to be truncated, from the lowest digit to the highest.

The number of "\*" signs = [Left of decimal Pt.] - [Truncated digits] - [Right of decimal Pt.].

The number of "#" signs = [Right of decimal Pt.] - [Truncated digits]. Please see the following examples:





When leading zero is not used, the text enclosed in two "\*" signs



	will not show, for example:			
	[Left of decimal Pt.] = 5, [Truncated digits] = 0, and Display Format			
	is "Total=**kg***g"			
	If the data read is 255, the result would be: "Total=255g"			
	If the data read is 1000, the result would be: "Total=1kg000g"			
	Scientific Notation (cMT / cMT X Series)			
	Express numerical data using scientific notation; for example,			
	number 100 is displayed as 1e+2. Scientific notation is not available			
	for device data formats: BCD, HEX, or Binary.			
Number of	Left of decimal Pt.			
digits	The number of digits before the decimal point.			
	Right of decimal Pt.			
	The number of digits after the decimal point.			
Scaling	Interpolation			
	If this check box is selected, [Engineering low] and [Engineering			
	high] boxes appear. Values entered in these boxes correspond to			
	the display range required. The setting also requires [Input low]			
	and [Input high] in the limits section. See Example 2.			
	Test: Preview the result of Interpolation. See Example 2.			
	Dynamic scales: Set the [Engineering low] and [Engineering high]			
	by a designated register. See Example 4.			
	Macro subroutine			
	The value read from or written to the register can be computed by			
	macro subroutines selected in [Read conversion] and [Write			
	conversion]. The macro subroutines should be defined in Macro			
	Function Library. To use this feature, see "13.9.2.1 The rule of using			
	Macro subroutine".			
Limits	This section enables users to apply display limits to the values in			
	the input register and set the display color to be used when the			
	register value falls outside the specified limits.			
	·			
	Direct			
	<b>Direct</b> Set the limits by entering values in [Device low] and [Device high].			
	Set the limits by entering values in [Device low] and [Device high].			
	Set the limits by entering values in [Device low] and [Device high]. If the value entered is outside the limits, the value in the register			
	Set the limits by entering values in [Device low] and [Device high]. If the value entered is outside the limits, the value in the register cannot be changed.			
	Set the limits by entering values in [Device low] and [Device high]. If the value entered is outside the limits, the value in the register cannot be changed.  Dynamic limits			
	Set the limits by entering values in [Device low] and [Device high]. If the value entered is outside the limits, the value in the register cannot be changed.			

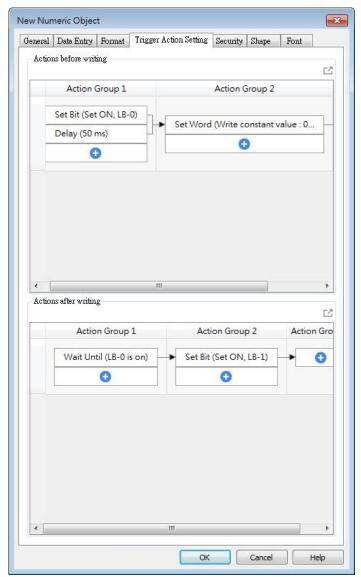


	selected, it's possible to set the high and low limits by specifying		
	different addresses. If the scaling method used is interpolation,		
	both high and low limit addresses are required.		
Use alarm	Low limit		
color	When the value in the register is outside the [Low limit], the object		
	displays digits by using the set color.		
	High limit		
	When the value in the register is outside the [High limit], the object		
	displays digits by using the set color.		
	Blink		
	When the value in the register is outside either limit, the digits		
	flash.		

# **Trigger Action Setting (cMT / cMT X)**

Actions executed before/after writing can be classified into action groups. The groups are put in sequence. The actions within the same group are executed at the same time. When all the actions within the same group are completed, the actions in the next group are then executed. Compared to the Notification actions selected in General tab, Trigger Action Setting offers more flexible combination of actions. For more details about these settings, please also see Action Trigger in Chapter 13.





Setting	Description		
Actions	The predefined action groups will be executed once the write		
before writing	operation starts, and will not wait for it to be completed.		
Actions after	The predefined action groups will be executed when the write		
writing	operation is completed.		

# 13.9.2.1. The rule of using Macro Subroutine

• There must be a return value and exactly one parameter.

# Examples:

```
sub char test (short a) // (Correct)
sub test (char a) // (Incorrect, no return value.)
sub char test (char a, char b) // (Incorrect, two parameters.)
```



• Use the Macro data type that corresponds to the object's data format.

The mapping is as follows:

Macro Data Type	Numeric Object Data Format		
short	16-bit Signed		
Int	32-bit Signed		
unsigned short	16-bit BCD, 16-bit HEX, 16-bit Binary, 16-bit Unsigned		
unsigned int	32-bit BCD, 32-bit HEX, 32-bit Binary, 32-bit Unsigned		
float	32-bit Float		
long	64-bit Signed (cMT / cMT X only)		
unsigned long	64-bit Unsigned (cMT / cMT X only)		
double	64-bit Double (cMT / cMT X only)		

For example, if the data format of the numeric object is 16-bit Unsigned, only the corresponding Macro data type: unsigned short, is available.

#### **Examples:**

sub char test(unsigned short a) // (Correct)
sub char test(char a) // (Incorrect)

Supports only the local HMI address.

#### Examples:

GetData(var, "Local HMI", LB, 0, 1) // (Correct)
GetData(var, "MODBUS RTU", 0x, 0, 1) // (Incorrect)

The following system defined functions are unable to be invoked:

ASYNC\_TRIG\_MACRO, SYNC\_TRIG\_MACRO, DELAY, FindDataSamplingDate, FindDataSamplingIndex, FindEventLogDate, FindEventLogIndex, INPORT, INPORT2, OUTPORT, PURGE, TRACE

The following statements are not supported:

For-Next, While-Wend

#### **Example 2**

If [Interpolation] is selected, the scaling equation is as the following:

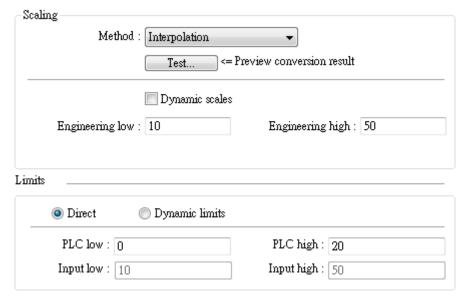
If A indicates the original data and B indicates the displayed data:

B = [Engineering low] + (A - [PLC low]) × Ratio

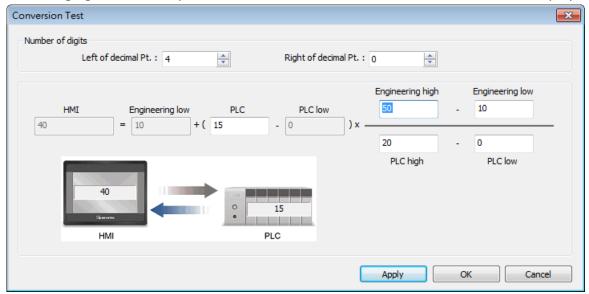
where, Ratio = ([Engineering high] - [Engineering low]) / ([PLC high] - [PLC low])

As shown below, the original data is 15, after conversion, 40 will be displayed.





Click [Test] button to preview the result of Interpolation. Enter a value in [PLC] field as shown in the following figure, for example, enter value 15, and the result, which is 40, will be displayed.

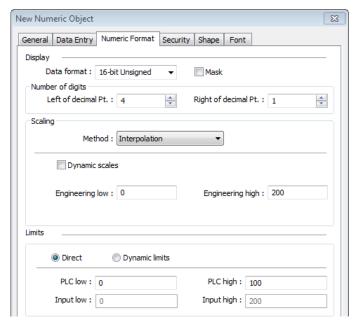


# **Example 3**

If the numeric format selected is not Float and decimal point is used, the decimal place of the converted result will not be adjusted automatically, please adjust [Engineering high] to correctly place the decimal point of the result gained in [Interpolation] mode. Please see the illustration below.

1. Create two Numeric objects, set [Right of decimal Pt.] to 1 and select [Interpolation] method for one of the objects as shown in the following figure.

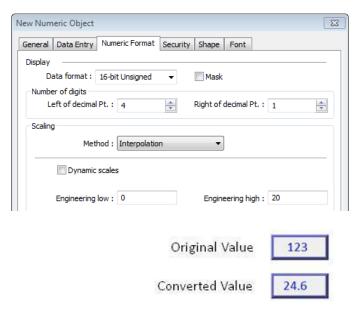




2. Enter value "123", the object set to [Interpolation] displays "246.0" instead of "24.6".



**3.** To move the decimal point one place to the left, adjust [Engineering high] as shown in the following figure.



# **Example 4**

If [Interpolation] is selected, set the [Engineering low] and [Engineering high] by a designated register. When Dynamic Address is LW-n, where n is an arbitrary number, the rule of setting [Engineering low] and [Engineering high] is:



Content	16-bit	32-bit	64-bit (cMT / cMT X only)
Dynamic address	LW-n	LW-n	LW-n
<b>Engineering low</b>	LW-n	LW-n	LW-n
<b>Engineering high</b>	LW-n+1	LW-n+2	LW-n+4
When address is LW-100,	the rule of settin	g limits is:	
Content	16-bit	32-bit	64-bit (cMT / cMT X only)
Dynamic address	LW-100	LW-100	LW-100
<b>Engineering low</b>	LW-100	LW-100	LW-100
Engineering high	LW-101	LW-102	LW-104

# **Example 5**

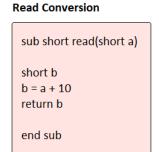
Set the limits by a designated register. When [Address] is LW-n and [Use consecutive addresses] is selected, the rule of setting limits is:

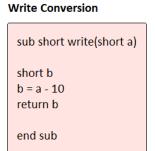
3 selected, the raie of	secting mines is.		
Content	16-bit	32-bit	<b>64-bit</b> (cMT / cMT X only)
Address	LW-n	LW-n	LW-n
Low limit	LW-n	LW-n	LW-n
High limit	LW-n+1	LW-n+2	LW-n+4
When address is LW-1	00, the rule of settin	g limits is:	
Content	16-bit	32-bit	64-bit (cMT / cMT X only)
Address	LW-100	LW-100	LW-100
Low limit	LW-100	LW-100	LW-100
High limit	LW-101	LW-102	LW-104

# **Example 6**

The following demonstrates how to use [Macro subroutine] for scaling when configuring Numeric object.

The following two macros are used, one for [Read conversion] and one for [Write conversion].



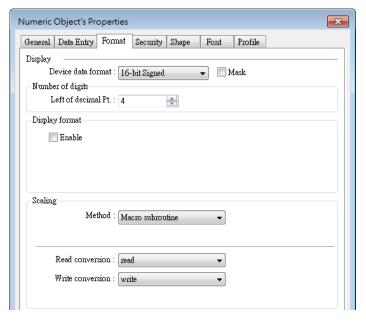


 Create two Numeric objects: NE\_0 and NE\_1 and use the same control address. Select [Macro subroutine] for NE\_1.

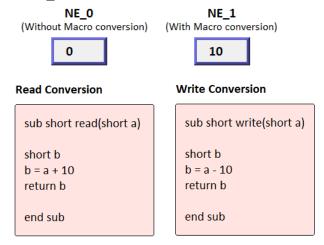




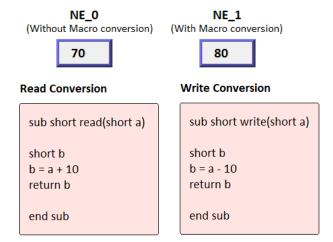




2. Enter 0 in NE\_0 then NE\_1 will execute [Read conversion]. The value gained will be 10.



3. Enter 80 in NE\_1, [Write conversion] is executed and the value gained will be 70. NE\_0 displays 70.





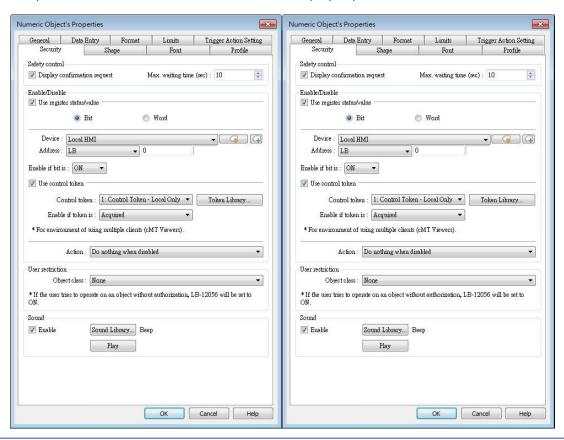


If executing [Read conversion] and [Write conversion] by the same numeric object, the value entered in this object is computed by the Macro subroutine of [Write conversion] first, and then the result is computed by the Macro subroutine of [Read conversion]. In Example 5, if the subroutine of [Write conversion] is set to b=a-20, then entering 80 in NE\_1 will get 60 after [Write conversion] and then the object displays 70 after [Read conversion].

## **Security Tab**

cMT, cMT X

eMT, iE, XE, mTV Series



Setting	Description	
Safety control	Displays a confirmation request window before executing a command.	
Enable/Disable	Use register status / value	
	With this option selected, whether an object is operable	
	depends on whether the specified condition occurs in the	
	designated address.	
	Use control token	
	With this option selected, whether an object is operable	
	depends on whether a control token is acquired or	
	unacquired.	



#### **Action modes:**

# Do nothing when disabled

The object is not operable, and its status remains unchanged when the specified condition does not occur in the designated address.

#### Hide when disabled

The object is hidden when the specified condition does not occur in the designated address.

### Grayed label when disabled

The value in the object turns gray when the specified condition does not occur in the designated address.



User restriction	Set the security class of the object to be operated by an authorized user.
Sound	When enabled, the selected sound will be played when the
	object is touched.

#### **Font Tab**



Setting	Description	
Color	When the value is within the limits, display digits using color set in	



	this tab.
Align	Left: Align the number to the left.
	Center: Align the number to the center.
	Right: Align the number to the right.
	Leading zero: The number is preceded with leading zeros when the
	number of digits is less than that set.
	Left 66
	Center 66
	Right 66
	Leading zero 0066
Size	Set the font size.



# 13.10. ASCII

#### 13.10.1. Overview

ASCII object can be used to input or display ASCII or UNICODE characters held in designated word registers.

## 13.10.2. Configuration

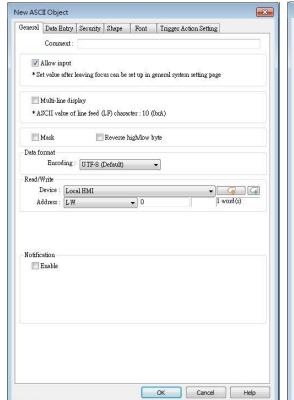


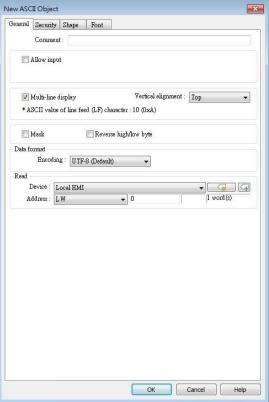
Click [Object] » [ASCII] icon on the toolbar to open an ASCII object property dialog box. Set up the properties, press OK button, and a new ASCII object will be created.

#### **General Tab**



eMT, iE, XE, mTV Series



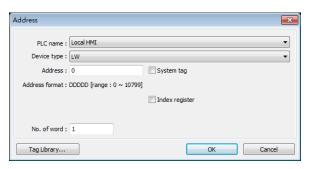


Setting	Description	
Allow input	If selected, the input features and relevant settings are enabled.	
Multi-line	If selected, the ASCII object can display multi-lined text. If a line	
display	feed character LF (0xA) is used in the string, a newline will be	
	created.	



Vertical	When [Multi-line display] is enabled, the method to vertically align	
alignment	multiple lines of text can be selected.	
Mask	If selected, any values entered will be masked by asterisks (*)	
Reverse	Normally an ASCII code is displayed in "high byte", "low byte"	
high/low byte	order. Reverse selection makes the system display ASCII characters	
	in "low byte", "high byte" order.	
	ABCD BADC  The left object is in normal form, and another is high/low byte reversed.	
Data format	Select encoding from UTF-8 (default), Unicode, or Latin-1.	
	Data format  Encoding: Latin-1	
Read address	Click [Setting] to select the [PLC name], [Address], [Device type],	

Click [Setting] to select the [PLC name], [Address], [Device type], [System tag], [Index register] of the word device that displays characters. Users can select a defined address tag from Address Tag Library, or set address in [General] tab while adding a new object.



#### No. of words

Select the maximum number of words to be displayed.

cMT / cMT X Series: max. 160 words eMT/XE/mTV/iP: max. 64 words

#### **Notification**

With notification enabled, the state of the designated bit address can be set on / off, before / after writing.

Notification works differently comparing cMT/cMT X Series with eMT/iE/XE/mTV Series.

**cMT/cMT X Series:** Trigger the object to open a keyboard window » Notification before writing » Enter a value and press ENTER » Start writing operation » Notification after writing.

#### eMT/iE/XE/mTV Series:

Trigger the object to open a keyboard window » Enter a value and press ENTER » Notification before writing » Start writing operation



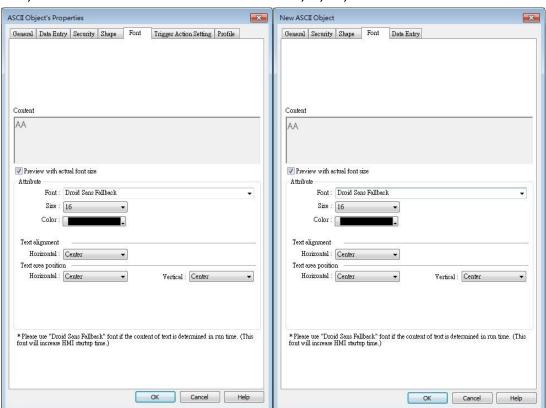
# » Notification after writing.



A UNICODE character uses 1 word, and an ASCII character uses 1 byte. Therefore 1 word can be used as 1 UNICODE character or 2 ASCII characters. (1 word equals to 2 bytes)

#### **Font Tab**



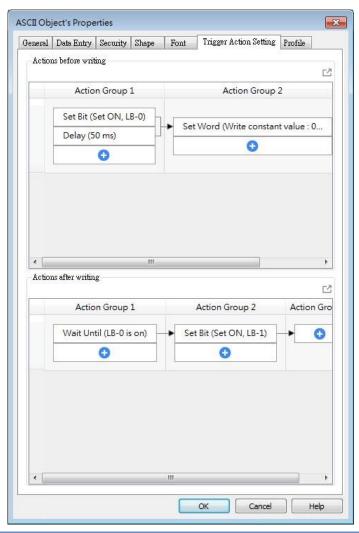


Setting	Description		
Attribute	The font, size, color, and alignment can be set.		
Text	Multiline text is aligned within the label outline. The method to		
Alignment	align multiple lines of text can be selected.		
Text area	Multiline text is aligned within the object outline.		
position	The label outline is highlighted by red dotted line and the object		
	outline is highlighted by blue dotted line. Please note that this		
	feature is ineffective when [Multi-line display] is enabled in General		
	tab.		
	When object is selected. When text is selected.		
	AAAA AAAA		



#### Trigger Action Setting (cMT / cMT X)

Actions executed before/after writing can be classified into action groups. The groups are put in sequence. The actions within the same group are executed at the same time. When all the actions within the same group are completed, the actions in the next group are then executed. Compared to the Notification actions selected in General tab, Trigger Action Setting offers more flexible combination of actions. For more details about these settings, please also see Action Trigger in Chapter 13.



Setting	Description	
Actions	The predefined action groups will be executed once the write	
before writing	operation starts, and will not wait for it to be completed.	
Actions after	The predefined action groups will be executed when the write	
writing	operation is completed.	



#### 13.11. Indirect Window

#### 13.11.1. Overview

Indirect Window object opens or closes a pop-up window assigned by a designated word register. There are two ways to use Indirect Window object: The first is to use the profile of Indirect Window object, and let the pop-up window be resized and displayed in the defined profile; the second is to automatically resize the window according to the size of the pop-up window to be displayed. To close the pop-up window, assign 0 to the designated word register. The difference between Direct Window and Indirect Window is that Direct Window is controlled by a bit register, while Indirect Window is controlled by a word register.

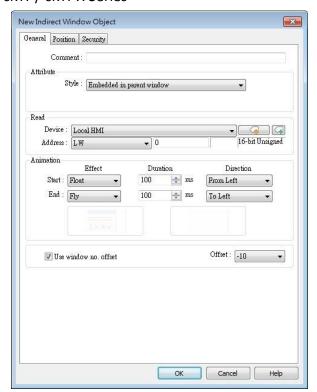
### 13.11.2. Configuration



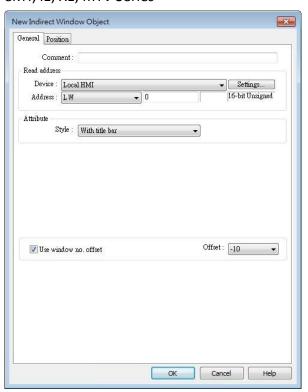
Click [Object] » [Embed Window] » [Indirect Window] icon on the toolbar to open the object property dialog box. Set up the properties, press OK button, and a new Indirect Window object will be created.

#### **General Tab**

#### cMT / cMT X Series

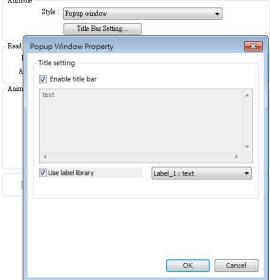


eMT, iE, XE, mTV Series





# Setting **Description** Style This setting is available only on cMT / cMT X Series. When a base window contains an underlay window, this setting determines the display style of an Indirect Window placed in the underlay window. Please see Example 2 below. **Embedded in parent window** The Indirect Window is displayed in its parent window. When an Indirect Window is placed in an underlay window, the Indirect Window is displayed in the underlay window when it is called in the base window. Popup window The Indirect Window is displayed in the base window. When an Indirect Window is placed in an underlay window, the Indirect Window is displayed in the base window when it is called in the base window. **Title Bar Setting** When [Enable title bar] is selected, a field shows for entering the caption in the title bar. The caption can be selected from Label Tag Library. Attribute Style : Popup window Title Bar Setting × Popup Window Property Title setting Enable title bar



#### **Read address**

Click [Setting] to select the [PLC name], [Address], [Device type], [System tag], [Index register] of the word device that controls the pop-up window. Users can also set address in [General] tab while adding a new object.

#### **Attribute**

# Style

Set the display style of the pop-up window. There are two styles:

No title bar

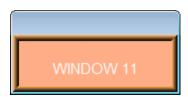


The pop-up window has no title bar and cannot be dragged.



• With title bar

The pop-up window has a title bar that can be dragged to move the window.



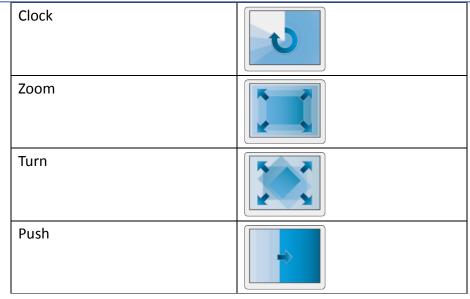
Animation (cMT / cMT X Series)

#### **Effect**

Different effects may be used for Start (window appears) and End (window disappears).

Effect Name	Transition
Fade	
Fly	
Float	
Wipe	
Split	1
Circle	





# **Duration**

Specifies how many milliseconds (ms) a transition effect takes to complete.

#### Direction

The direction of the transition.

# Use window no. offset

Sets the offset of the window number for selecting the pop-up window. The window number of the pop-up window is calculated by the value in the word register added to the offset. For example, assume the value in the register is 20 and offset is 5, the pop-up window number will be 25.

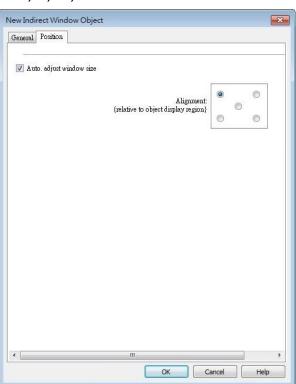


#### **Position**

# cMT / cMT X Series



eMT, iE, XE, mTV Series



#### Setting

#### Description

# Auto. adjust window size

Automatically resizes the Indirect Window and align the pop-up window to the preset region.

#### **Alignment**

Sets a reference point of the pop-up window from one of the five positions on the screen; for example, if the lower-right region is selected, the lower-right corner of the pop-up window is aligned to the lower-right region of the Indirect Window. See Example 1.

# Dynamic position

With this option selected, the position of the window on the screen can be changed dynamically by the values in the designated address.

#### **Enable shift window animation**

With this option selected, the window changes position with transition effect.

# **Example 1**

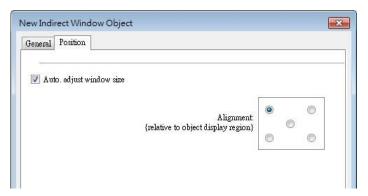
Here is an example of using Indirect Window. The setting is shown in the following figure, set the address to LW-0 which assigns the window number. Create window no. 11 and 12 first.

1. Create an Indirect Window object, set address to LW-0, and select [Auto. adjust window

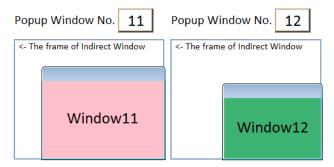


size].

2. Select the region where the window is to be displayed.



- 3. Enter value 11 in LW-0, the pop-up window displayed is window no. 11.
- 4. Enter value 12 in LW-0, the pop-up window displayed is window no. 12.
- 5. Enter value 0 in LW-0, the pop-up window is closed.

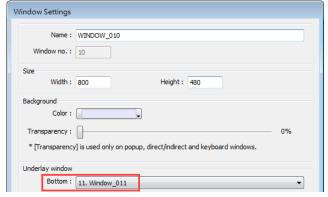


To close the pop-up window, apart from entering 0 in the designated word register, another way is to place a Function Key object in the pop-up window, and set the key to [Close window].

# Example 2

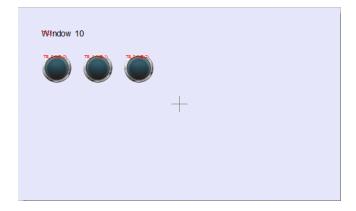
Here is an example showing the difference between these two styles: [Embedded in parent window] and [Popup window]. The style setting determines how an Indirect Window placed in an underlay window is displayed when it is called in the base window.

1. Add two base windows: Window no. 10 and Window no. 11. Add an underlay window in Window no. 10 and set Window no. 11 as the underlay window.

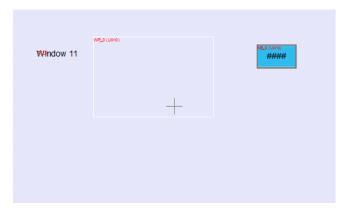


2. Create several objects in Window no. 10.



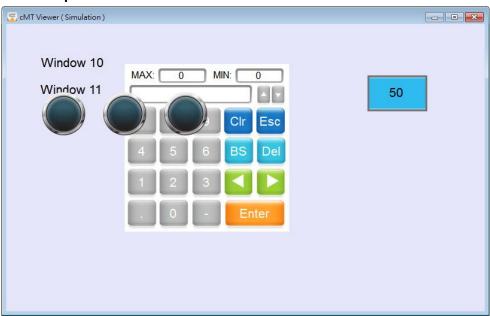


3. In Window no. 11 create an Indirect Window object and a Numeric Input object. Set both read addresses to LW-0.



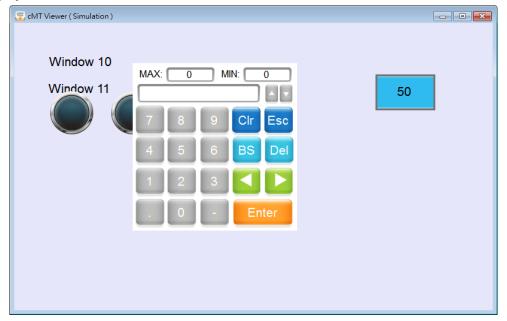
**4.** By entering a window number in the Numeric Input object, the Indirect Window is displayed according to the selected style.

# **Embedded in parent window**





#### Popup window



# Note

- For eMT/iE/XE/mTV models, a screen can display up to 24 pop-up windows simultaneous including System Message Window, Direct Window and Indirect Window. For cMT / cMT X Series, the number of pop-up windows is not limited.
- The system does not allow opening the same window with two Direct (or Indirect) windows in one base window.
- If the pop up window has monopoly property enabled, then when the window pops up, all background windows may not be operated until the monopolizing window has been closed.
- Click the icon to watch the demonstration film. Please confirm your internet connection before playing the film.



## 13.12. Direct Window

#### 13.12.1. Overview

Direct Window object opens or closes a pop-up window assigned by a designated bit register. When the state of the bit register changes, the pop-up window appears at the predefined location. The display area for the pop-up window is limited by the size of predefined location. Returning the state of the bit register closes the pop-up window. The difference between Direct Window and Indirect Window is that Direct Window is controlled by a bit register, while Indirect Window is controlled by a word register.

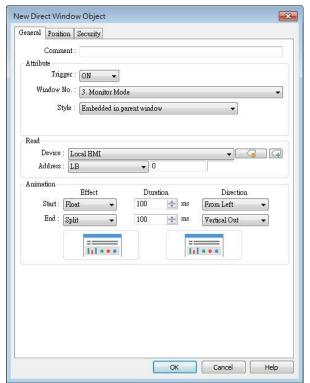
#### 13.12.2. Configuration



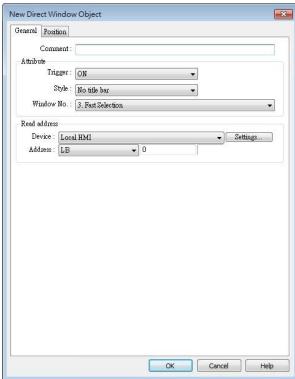
Click [Object] » [Embed Window] » [Direct Window] icon on the toolbar to open a Direct Window object property dialog box. Set up the properties, press OK button, and a new Direct Window object will be created.

#### **General Tab**

cMT / cMT X Series



eMT, iE, XE, mTV Series





# Setting **Description** Style This setting is available only on cMT / cMT X Series. When a base window contains an underlay window, this setting determines the display style of a Direct Window placed in the underlay window. Please see Example 2 in Chapter 13.11 in this manual. **Embedded in parent window** The Direct Window is displayed in its parent window. When a Direct Window is placed in an underlay window, the Direct Window is displayed in the underlay window when it is called in the base window. Popup window The Direct Window is displayed in the base window. When a Direct Window is placed in an underlay window, the Direct Window is displayed in the base window when it is called in the base window. **Title Bar Setting** When [Enable title bar] is selected, a field shows for entering the caption in the title bar. The caption can be selected from Label Tag Library. Trigger: ON Window No.: 3. Monitor Mode Style : Popup window Title Bar Setting. Popup Window Property Title setting ▼ Enable title bar Ani ✓ Use label library Label 1: text **Read address** Click [Setting] to select the [PLC name], [Address], [Device type], [System tag], [Index register] of the bit device that controls the pop-up window. Users can also set address in [General] tab while adding a new object. **Attribute** Style Set the display style of the pop-up window. There are two styles: No title bar

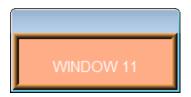
The pop-up window has no title bar and cannot be dragged.





With title bar

The pop-up window has a title bar that can be dragged to move the window.



# Window no.

Set the pop-up window number.

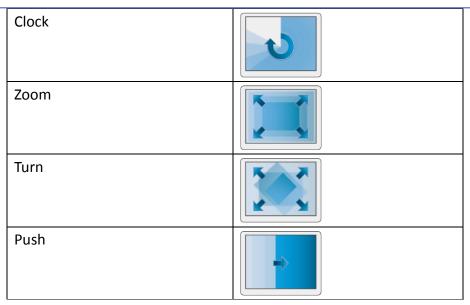
# Animation (cMT / cMT X Series)

### **Effect**

Different effects may be used for Start (window appears) and End (window disappears).

Effect Name	Transition
Fade	
Fly	
Float	
Wipe	
Split	
Circle	





# **Duration**

Specifies how many milliseconds (ms) a transition effect takes to complete.

# Direction

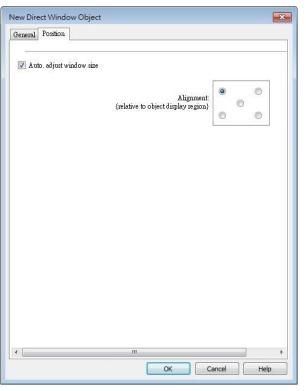
The direction of the transition.

# **Position**

# cMT / cMT X Series



eMT, iE, XE, mTV Series



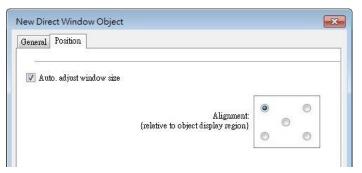


Setting	Description
Auto. adjust	Automatically resizes the Direct Window and align the pop-up
window size	window to the preset region.
	Alignment
	Sets a reference point of the pop-up window from one of the five
	positions on the screen; for example, if the lower-right region is
	selected, the lower-right corner of the pop-up window is aligned to
	the lower-right region of the Direct Window. See Example 1.
Dynamic	With this option selected, the position of the window on the screen
position	can be changed dynamically by the values in the designated
	address.
	Enable shift window animation
	With this option selected, the window changes position with
	transition effect.

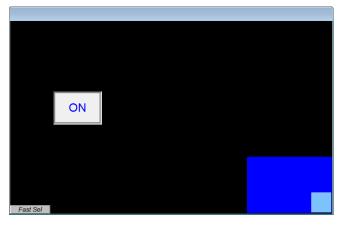
# **Example 1**

Create window no. 11 which can be controlled by a Toggle Switch with address LB-0.

- 1. Create a Direct Window object and set read address to LB-0.
- 2. In this example, the reference point for alignment is set to the lower-right region.



3. When LB-0's state is ON, window no. 11 will show.



4. When LB-0's state is OFF, window no. 11 will be hidden.







- For eMT/iE/XE/mTV models, a screen can display up to 24 pop-up windows simultaneous including System Message Window, Direct Window and Indirect Window. For cMT / cMT X Series, the number of pop-up windows is not limited.
- The system does not allow opening the same window with two Direct (or Indirect) Windows in one base window.
- If the pop up window has monopoly property enabled, then when the window pops up, all background windows may not be operated until the monopolizing window has been closed.
- Click the icon to watch the demonstration film. Please confirm your internet connection before playing the film.



# 13.13. Moving / Rotating Shape

# 13.13.1. Overview

Moving / Rotating Shape is an object that changes its state, moves, and/or rotates according to the user-defined parameters. The state, moving distance, and rotation direction/angle are determined by values in consecutive registers.

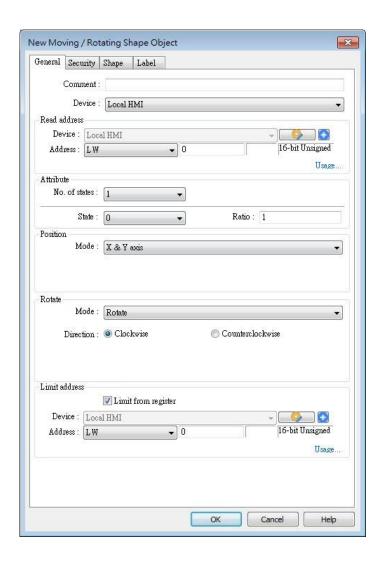
# 13.13.2. Configuration



Click [Object] » [Animation] » [Moving / Rotating Shape] icon on the toolbar to create the object, set up the properties, press OK button, and a new Moving / Rotating Shape object will be created.



# **General Tab**



Setting	Description		
Read address	Click [Setting] to configure the [Device], [Device type], [Address],		
	[System tag], or [Index register] of the word devices that control		
	the display of object's state and moving distance. Users can also set		
	the address in [General] tab while adding a new object.		
Attribute	Select the object's movement mode and range. See "13.13.2.1		
	Illustration of Modes" in the following part.		
Display ratio	The size of shape in different states can be set individually as		
	shown in the following figure.		
	Ratio: 1 Ratio: 1.2 Ratio: 1.4 Ratio: 1.6		
	State 0 State 1 State 2 State 3		
Rotate	Select Clockwise or Counterclockwise for Direction and define the		



	angle range (unit in degree) within which the object may rotate.
	The allowable range is 0~360 degrees, and the Max. angle should
	be greater than Min. angle.
	For more information please see "13.13.2.2 Rotation Modes".
Limit address	The object's moving range can be set by adjusting the data in the
	designated register, see Example 1.

# **Example 1**

Supposed that the object's moving range is limited by register LW-n, the addresses in the following table are used to limit the moving / rotating range.

Data format	16-bit	32-bit	64-bit (cMT / cMT X only)
Position - [Min. X] address	LW-n	LW-n	LW-n
Position - [Max. X] address	LW-n+1	LW-n+2	LW-n+4
Position - [Min. Y] address	LW-n+2	LW-n+4	LW-n+8
Position - [Max. Y] address	LW-n+3	LW-n+6	LW-n+12
Rotate – Input Low	LW-n+4	LW-n+8	LW-n+16
Rotate – Input High	LW-n+5	LW-n+10	LW-n+20
Rotate – Scaling Low	LW-n+6	LW-n+12	LW-n+24
Rotate – Scaling High	LW-n+7	LW-n+14	LW-n+28

# 13.13.2.1. Illustration of Modes

Available modes are: (Assume Read Address is LW-n)

X axis only

The object is only allowed to move along the X-axis. The moving distance ranges from [Min. X] to [Max. X].



Data format	16-bit	32-bit	64-bit (cMT / cMT X only)
Object state	LW-n	LW-n	LW-n
Moving distance on X-axis	LW-n+1	LW-n+2	LW-n+4

Y axis only

The object is only allowed to move along the Y-axis. The moving distance ranges from [Min. Y] to [Max. Y].





Data format	16-bit	32-bit	64-bit (cMT / cMT X only)
Object state	LW-n	LW-n	LW-n
Moving distance on Y-axis	LW-n+1	LW-n+2	LW-n+4

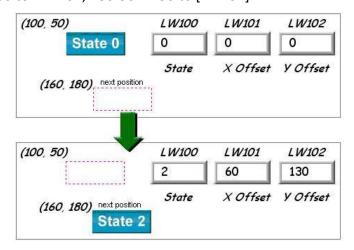
#### X & Y axis

The object is allowed to move along the X-axis and Y-axis. The moving range in X and Y directions is defined by [Min. X], [Max. X] and [Min. Y], [Max. Y] respectively.



Data format	16-bit	32-bit	64-bit (cMT / cMT X only)
Object state	LW-n	LW-n	LW-n
Moving distance on X-axis	LW-n+1	LW-n+2	LW-n+4
Moving distance on Y-axis	LW-n+2	LW-n+4	LW-n+8

For example, if the object's read address is LW-100 and the data format is [16-bit Unsigned], LW-100 is used to control the object's state, LW-101 is used to control the object's moving distance on the X-axis, and LW-102 is used to control the object's moving distance on the Y-axis. The following figure shows that the object's read address is LW-100 and initial position is (100, 50). To move the object to the position (160,180) and change its state to State 2, assign 2 to LW-100, 160-100 = 60 to LW-101, 180-50 = 130 to [LW102].





# X axis w/ scaling

The object moves in X-axis only with scaling. Suppose that the value of the designated register is DATA, the system uses the following equation to calculate the moving distance on the X-axis.

$$\label{eq:Displacement} \begin{aligned} & \text{Displacement=(Data-[Input low])} \times \frac{\text{[Scaling high]-[Scaling low]}}{\text{[Input high]-[Input low]}} \end{aligned}$$

Data format	16-bit	32-bit	64-bit (cMT / cMT X only)
Object state	LW-n	LW-n	LW-n
Moving distance on X-axis	LW-n+1	LW-n+2	LW-n+4

Y axis w/ scaling

The object is for Y axis movement with scale, and the equation to calculate the moving distance on the Y-axis is the same as the one in [X axis w/ scaling].

Data format	16-bit	32-bit	64-bit (cMT / cMT X only)
Object state	LW-n	LW-n	LW-n
Moving distance on Y-axis	LW-n+1	LW-n+2	LW-n+4

X axis w/ reverse scaling

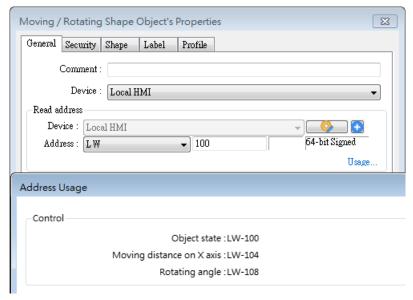
This works in the way as [X axis w/ scaling], but the moving direction is in reverse.

Y axis w/ reverse scaling

This works in the way as [Y axis w/ scaling], but the moving direction is in reverse.

#### 13.13.2.2. Rotation Modes

The addresses that control the moving / rotating shape are consecutive addresses starting from Read Address (LW-n), and they may vary depending on the selected mode. Please click [Usage...] to open the window that shows the control addresses relating to rotation parameters.



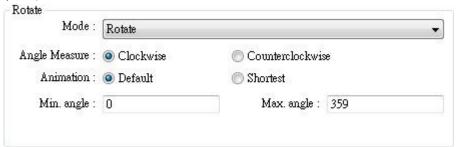


# Rotate

Select rotating direction from clockwise or counterclockwise and set the Min. and Max. angle range.

When rotation animation is enabled, two modes can be selected: Default and Shortest. e.g. When the angle measure is set to clockwise and the rotating angle is changed from 10 degrees to 350 degrees, these two modes give different results:

Default: rotates 340 degrees clockwise (linear interpolation between the two numbers) Shortest: rotates 20 degrees counterclockwise (in the direction that produces the shortest animation path)



Rotate w/ scaling

Select rotating direction from clockwise or counterclockwise. The angle of rotation is calculated by the formula as shown below.

$$\label{eq:angle of Rotation} Angle of Rotation = (Data-[Input low]) \times \frac{[Scaling high]-[Scaling low]}{[Input high]-[Input low]}$$

Rotate w/ reverse scaling
 Similar to [Rotate w/ scaling] but reverses the object from clockwise to counterclockwise and vice versa.



# 13.14. Animation

### 13.14.1. Overview

Animation object is defined by a pre-defined point set and states. Animation object will then move to a given point in a given state defined by designated registers. The object state and position depend on current value of two consecutive registers. The first register controls the state of the object and the second register controls the position along the predefined path.

# 13.14.2. Configuration

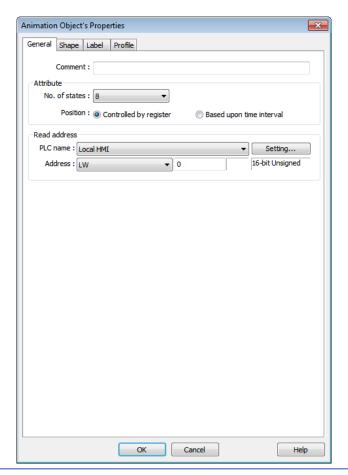


Click [Object] » [Animation] » [Animation] icon on the toolbar. First, create the pre-defined path. Move the mouse to each moving position, and click the left button to define positions one by one. When it is done, right click on the screen, set up the properties, press OK button, and a new Animation object will be created.



To change the object's attributes, double click on the object to open Animation Object's Properties dialog box.

#### **General Tab**



# **Setting**

#### **Description**

# Attribute

# No. of states

Configure the number of states for this object.

# Controlled by register

Use the designated registers to control the object's state and position. See Example 1.

# Based upon time interval

The object's state and position will change from time to time. [Time interval attributes] is used to set the time interval for states and positions.



**Position speed:** The speed of movement. The unit is 0.1 second. Supposed that [Speed] is set to 10, the object's position will change each second.



Image state change: Determines how state changes, either [Position dependent] or [Time-based]. If [Position dependent] is selected, the object state will change when position changes. If [Time-based] is selected, the object position will change based on [Position speed] and the object state will change based on [Image update time].

**Backward cycle:** Assumed the object has four positions: position 0, position 1, position 2, and position 3, and [Backward cycle] is not selected. When the object moves to the last position (position 3), the next position will be back to the initial position 0, and repeat. The moving path is shown as follows:

position  $0 \rightarrow$  position  $1 \rightarrow$  position  $2 \rightarrow$  position  $3 \rightarrow$  position  $0 \rightarrow$  position  $1 \rightarrow$  position 2...

If [Backward cycle] is selected, when the object moves to the last position (position 3), it will move backwards to position 2, position 1 and then the initial position 0, and start over again. The moving path is shown as follows.

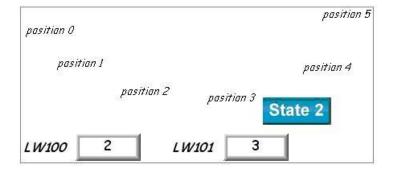
position  $0 \rightarrow$  position  $1 \rightarrow$  position  $2 \rightarrow$  position  $3 \rightarrow$  position  $2 \rightarrow$  position  $1 \rightarrow$  position 0...

# **Example 1**

The object's state and position are determined by the registers, and the addresses must be configured correctly, as in the following table:

Data format	16-bit	32-bit	64-bit (cMT / cMT X only)
Object state	LW-n	LW-n	LW-n
Object position	LW-n+1	LW-n+2	LW-n+4

For example, if the designated register is LW-100 and the data format is [16-bit Unsigned], then LW-100 represents object's state, LW-101 represents position. In the picture below, LW-100 = 2, LW-101 = 3, so the object's state is 2 and position is 3.





# **Profile Tab**



Setting	Description
Shape rectangle size	Set the size of the shape.
Trajectory	Set the position of each point on the moving path.



Since multiple pictures might be used by an [Animation] object, [Set to original dimension] will not return all pictures to the original size.

# 13.15. Bar Graph

# 13.15.1. Overview

Bar Graph object displays data as a bar graph for visualization.

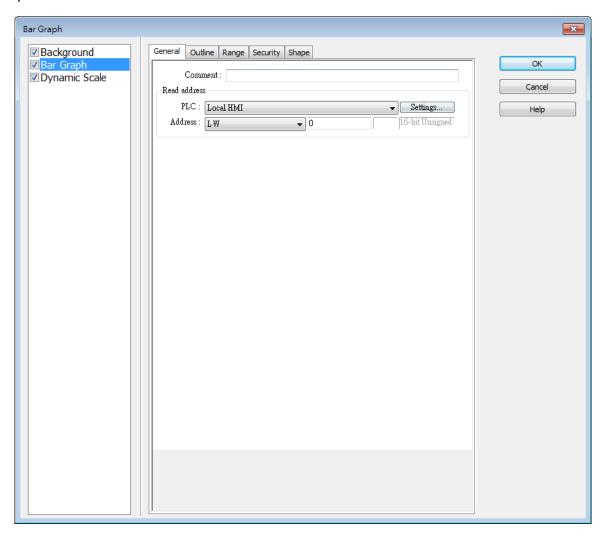
# 13.15.2. Configuration



Click [Object] » [Chart] » [Bar Graph] icon on the toolbar to open Bar Graph dialog box. Select properties, click OK button, a new Bar Graph object is created.

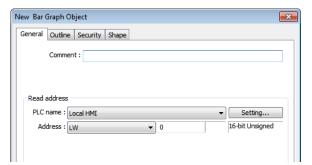
### **General Tab**

# cMT / cMT X





eMT, iE, XE, mTV

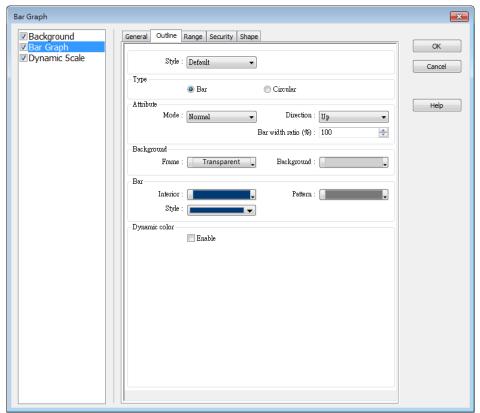


Setting	Description	
Read address	Click [Setting] to Select the [Device], [Device type], [Address],	
	[System tag], and [Index register] of the word devices that controls	
	how the bar graph displays.	

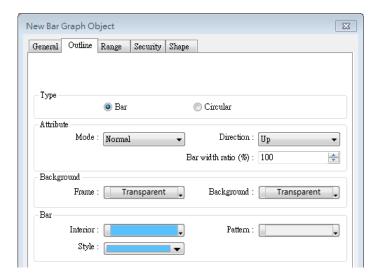


# **Outline Tab**

# cMT / cMT X



eMT, iE, XE, mTV



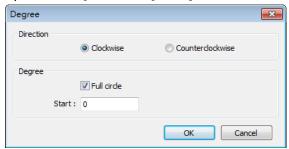
Setting	Description	
Туре	Choose either [Bar] or [Circular].	
Attribute	Mode	
	Choose either [Normal] or [Offset]. If [Offset] is selected, an	
	original value [Origin] must be entered for reference.	



# **Direction / Degree**

Bar: Determine the bar graph direction. Available options are [Up], [Down], [Right], and [Left].

Circular: Determine the circular bar graph direction. Available options are [Clockwise] and [Counter clockwise].

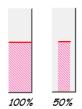


If [Full circle] is selected, set the start degree.

If [Full circle] is not selected, set the start and end degree.

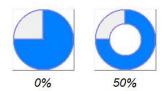
# Bar width ratio (%)

The ratio of bar to object width. The figure below shows two ratios, 100% and 50%.



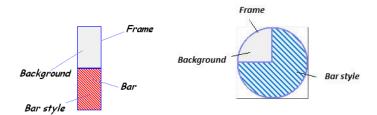
# Hole Radius (%)

The ratio of the radius of the hole to the radius of the whole circular bar graph. The figure below shows two ratios, 0% and 50%.



# Color/Style

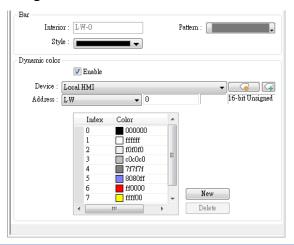
Set the bar's frame and background color, bar style, and bar color. See the picture below.



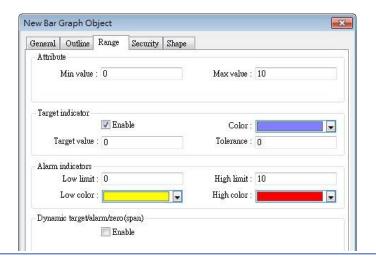


# Dynamic color

(For cMT / cMT X Series models only) With this option selected, the interior color of the bar is determined by the value in the designated address.



# **Range Tab**



Setting	Description	
Zero / Span	The percentage of filling can be calculated by the formula, see	
	Example 1.	
Target	When the register value meets the condition, the color of filled	
indicator	area will change to the target color, see Example 2.	
Alarm	If the register value is larger than [High limit], the color of filled	
indicators	area will change to [High color]. If the register value is smaller than	
	[Low limit], the color will change to [Low color].	
	Please note that when [Dynamic color] is enabled, the Target	
	indicator and Alarm indicator settings will not be present and their	
	colors are determined by the designated addresses.	
Dynamic	When [Enable] is selected, the [Low limit] and [High limit] of [Alarm	
taget/alarm	indicator] and the [Target Value] of [Target indicator] will use	



/zero(span)	designated registers, which is shown in their respective fields see
	Example 3.

# **Example 1**

The percentage of filling can be calculated by the following formula:

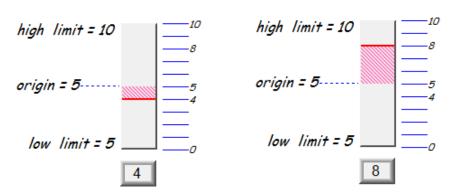
Percentage of filling = 
$$\frac{\text{Register value} - [\text{Zero}]}{[\text{Span}] - [\text{Zero}]} \times 100\%$$

Assume [Offset] is selected. If (Register value – [Zero]) is greater than 0, the bar will fill up from [Origin]. If (Register value – Zero) is less than 0, the bar will be drawn below [Origin].

For example, [Origin] is 5, [Span] is 10, and [Zero] is 0.

For different value in read address, it will display as below:

If the value at read address is 4: If the value at read address is 8:

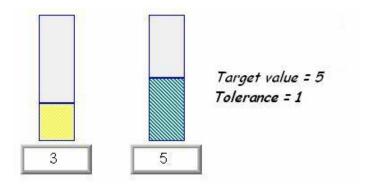


# **Example 2**

When the register value meets the following condition, the color of filled area will change to the target color.

[Target Value] - [Tolerance] ≤ Register value ≤ [Target Value] + [Tolerance]

Assume [Target Value] is 5 and [Tolerance] is 1. As shown below, if the register value is equal to or larger than 4 (=5-1) and equal to or less than 6 (=5+1), the filled area's color of the bar will change to the target color.



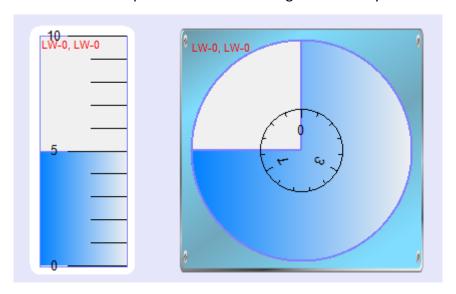
# **Example 3**

If [Dynamic target/alarm] is enabled, [Low limit] and [High limit] of [Alarm indicator] are defined by designated registers as shown in the following table. Furthermore, if [Dynamic zero/span] is used, [Zero], [Span] and [Origin] will be defined by designated registers. Assume the address is LW-n, the limits are:

Data format	16-bit	32-bit	64-bit (cMT / cMT X only)
Alarm Low Limit	LW-n	LW-n	LW-n
Alarm High Limit	LW-n+1	LW-n+2	LW-n+4
Target	LW-n+2	LW-n+4	LW-n+8
Zero	LW-n+3	LW-n+6	LW-n+12
Span	LW-n+4	LW-n+8	LW-n+16
Origin	LW-n+5	LW-n+10	LW-n+20

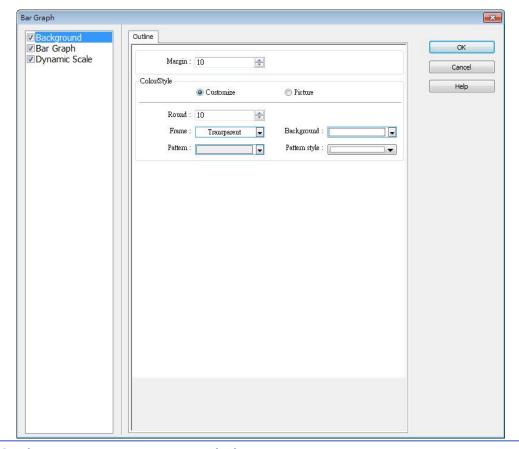
# 13.15.3. Combo Setting

cMT / cMT X Series HMI support combo setting for Bar Graph, which allows setting of multiple related objects at a time. Bar Graph can be set with Background and Dynamic Scale.





# **Background**



# **Setting**

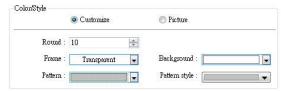
# **Description**

# Margin

Specify the space between the background edge and the objects.

# Color/Style

# Customize



Select a suitable background pattern and color.

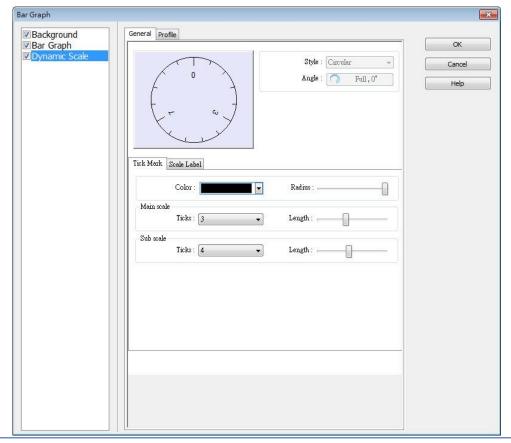
#### **Picture**



Use the default picture or choose a picture from Picture Library.



# **Dynamic Scale**



Setting	Description
Style	The scale style will follow the bar type.
Tick Mark	Configure the number of tick marks for main and
	sub scales. If the style is circular, the radius and tick
	mark length can be specified.
Scale Label	Configure the font, font color, font size and other
	attributes of scale label.



# 13.16. Meter Display

# 13.16.1. Overview

Meter Display object displays the value of word register with a meter.

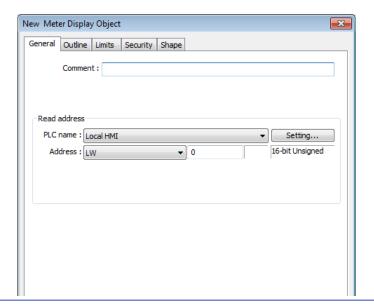
# 13.16.2. Configuration



Click [Object] » [Chart] » [Meter Display] icon on the toolbar to open the Meter Display dialog box. Set the object's attributes and then click OK to create a new Meter Display object.

# **13.16.2.1. eMT, iE, XE, mTV Series**

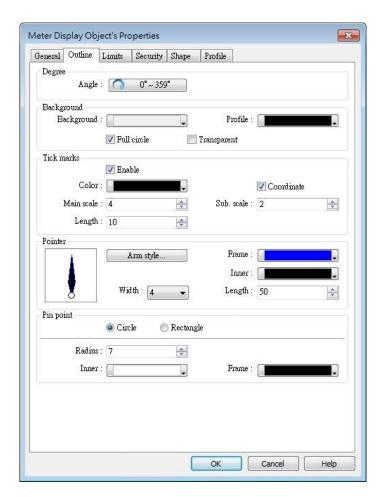
# **General Tab**

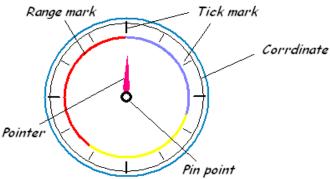


Setting	Description
Read address	Click [Setting] to select the [Device], [Device type], [Address],
	[System tag], and [Index register] of the word devices that controls
	the Meter Display object.



#### **Outline Tab**

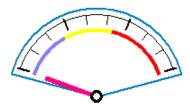




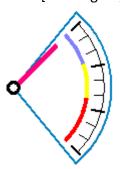
# Degree Set the pointer to go around the meter clockwise or counterclockwise. Sets the object's start degree and end degree measured clockwise from the 12 o'clock position. The angle range is 0 to 360 degrees. The following shows meters of different settings.



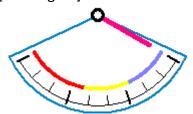
• [Start degree] =  $290^{\circ}$ [End degree] =  $70^{\circ}$ 



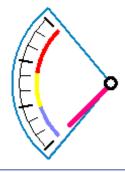
• [Start degree] =  $40^{\circ}$ [End degree] =  $140^{\circ}$ 



• [Start degree] =  $120^{\circ}$ [End degree] =  $240^{\circ}$ 



[Start degree] =  $225^{\circ}$ [End degree] =  $315^{\circ}$ 

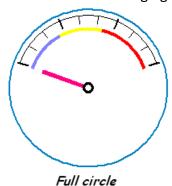


# **Background**

Sets the object's background color and profile color.

#### **Full circle**

When selected, the object will display the whole circle. Otherwise, the object will only display a partial circle in the defined degree range, as shown in the following figure.



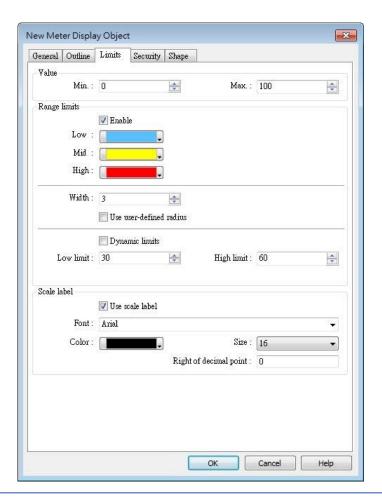


# **Transparent**

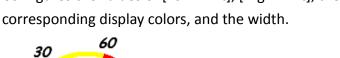
When selected, the object will not display the background and profile color.

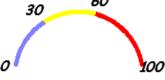
Tick marks	Configures the number of tick mark and color.
Pointer	Configures pointer's style, length, width, and color.
Pin point	Configures the style, radius, and color of the pin point.

#### **Limits Tab**



# Value Sets the object's display range. Meter Display object will use the value of [Zero] and [Span] and the value of register to calculate the pointer's position. See Example 1. Range limits Configures the values of [Low limit], [High limit], their





# Use user-defined radius Configures the radius to display range limits. For example, set to 80: Set to 30:



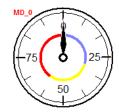


# **Dynamic Limits**

The low limit and high limit are set by registers. See Example 2.

# Scale label

Select the attribute of scale label on Meter Display.





# **Example 1: Pointer position calculation**

Set object's display range. Meter Display object will use the value of [Zero] and [Span] and the value of register to calculate the pointer's position. For example, supposed that [Zero] is 0, [Span] is 100, when the value of register is 30, [Start degree] is 0, and [End degree] is 360, then the degree indicated by the pointer is:

 ${ (30 - [Zero]) / ([Span] - [Zero]) } * ([End degree] - [Start degree]) = {(30 - 0) / (100 - 0)} * (360 - 0) = 108$ 

Pointer will be pointing at 108 degrees.

# **Example 2: Dynamic Limits**

The low limit and high limit are set by the register.

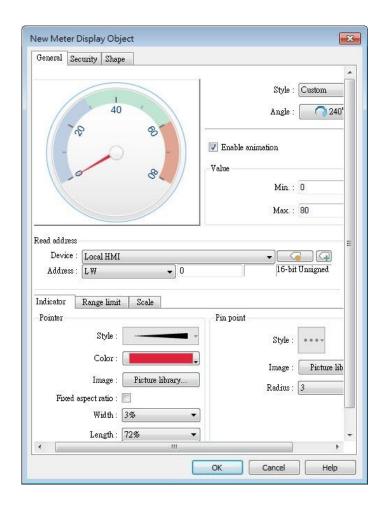
Suppose the address is LW-n, the following table shows the read address of low limit and high limit:

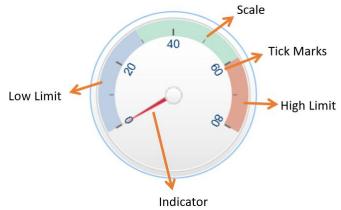
Content	16-bit	32-bit	64-bit (cMT / cMT X only)
Low limit	LW-n	LW-n	LW-n
High limit	LW-n+1	LW-n+2	LW-n+4
For instance, when ad	dress is LW-100, the i	rule of setting lir	mits is:
Content	16-bit	32-bit	64-bit (cMT / cMT X only)
Low limit	LW-100	LW-100	LW-100
High limit	LW-101	LW-102	LW-104



# 13.16.2.2. **cMT / cMT X Series**

# **General Tab**





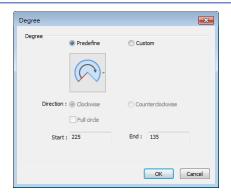


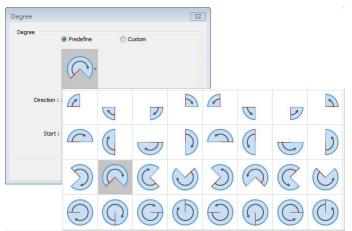
Setting	Description		
Style	Select a style from the drop-down list. Available options include: [Custom], [Style 1], [Style 2], and [Classical]. If [Custom] is selected, properties such as the width / length of the pointer or the radius of the pin point, etc must also be manually set.		
	The following background-related settings are available using [Style 1], [Style 2], or [Classical]:		
	Color		
	Sets the color of the background picture of meter.		
	Outline		
	The following is the outline of Style 1 when [Full circle], [Half		
	circle], or [Quarter circle] is selected.		
	40 60 80 100 RS		
	The following is the outline of Style 2 when [Full circle], [Half circle], or [Quarter circle] is selected.		
	Rotation		
	Rotates the background picture clockwise according to the angles		
	set.		
Angle	Direction		
	Sets the range to label the scale, using twelve o'clock direction as the $0^\circ$ reference.		
	Degree		
	Available options include: [Predefined] and [Custom]. With		
	[Predefine] selected, pick from the thumbnails configure directions		

and angle ranges with ease.



13-107 Objects





# **Full circle**

If selected, the full circle is drawn according to the selected direction and the start angle. The limits are determined by the

	direction and the start angle. The limits are determined by the
	value set in [Minimum] and [Maximum] field under [Value].
Enable	If selected, the pointer slides to the designated position when the
animation	read value changes; if not selected, the pointer directly points to
	the designated position when the read value changes.
Value	Sets the lower and upper limits of the meter.
Read address	Displays the value in meter according to the value in the designated
	word register.
Indicator	Sets the style of pointer and pin point. If [Custom] is selected, the
	direction of the pointer must points upward to correctly display.
Range limit	Sets the colors to indicate different ranges.
	Dynamic limits
	The low limit and high limit are decided by the register. See
	Example 2 in the previous section.
Scale	Sets the number of main and sub scale, the color of tick marks and
	scale label.

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# 13.17. Trend Display

# 13.17.1. Overview

Trend display objects draw curves of the data recorded by Data Sampling object.

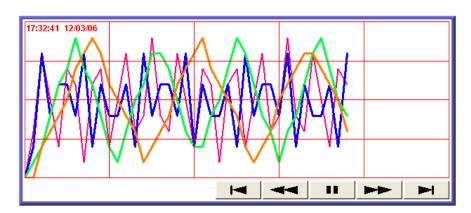
# 13.17.2. Configuration



Click [Data/History] » [Trend Display] icon on the toolbar to open a Trend Display object property dialog box. Set up the properties, press OK button, and a new Trend Display object will be created.

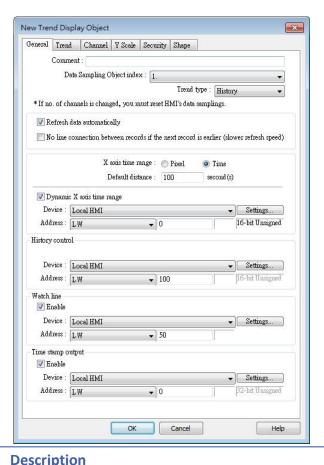
# **13.17.2.1. eMT, iE, XE, mTV Series**

#### **General Tab**



Button	Description
<b>⊢</b> ◀	Go to the earliest sampling data.
44	Go to the previous time interval.
11	Click to stop auto-scrolling. When the new sampling data is
	generated, the display does not scroll, nor is the new data outside
	the display range displayed.
<b>-</b>	Click to start auto-scrolling. The display scrolls as the new sampling
	data is generated.
<b> </b>	Go to the next time interval.
<b>►</b> I	Go to the latest sampling data.





Setting	Description
Data	
Sampling	Select a Data Sampling object as the source data.
Object index	
Refresh data	In history mode, when this option is selected, Trend Display will be
automatically	automatically refreshed every 10 seconds. If this option is not
	selected, Trend Display can only be refreshed by changing window.
No line connection between records if the next record is earlier	When HMI time is adjusted to an earlier time, and data sampling
	keeps going on, selecting this option can prevent the system from
	drawing a line to connect the gap between current trend curve
	(earlier in time axis) and former trend curve (later in time axis). This
	can slow down refresh speed.
Trend type	Select the mode of data source, either [Real-time] or [History].
	Real-time
	In this mode, the display object shows all sampled data since the
	HMI started. The maximum number of records that can be sampled
	is set in [Max.data records] (Real-time mode) of the Data Sampling
	object. When the sampling data exceed this setting, the earlier
	data will be deleted. To show older data, use [History] mode.
	[Hold control]: Suspends the update of Trend Display. However, it



does not stop the sampling process of Data Sampling object.

# History

In this mode, the data comes from the history data files stored on HMI. The history data files are sorted by dates, and each is given an index. The system uses [History control] to select the history data files that are created on different dates.

The system sorts the history data of sampling data by date; the latest file is record 0 (typically the data sampled today), the second latest file is record 1, and so on. If the value of designated register in [History control] is n, the Trend Display object will display data record n.

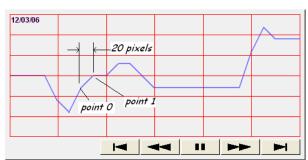
Here is an example to explain [History control]. If the designated register is LW-0, and the sampling data files available are pressure\_20061120.dtl, pressure\_20061123.dtl, pressure\_2006127.dtl, and pressure\_20061203.dtl, and it is 2006/12/3 today, based on the value of LW-0, the sampling data file which will be selected by [Trend Display] is shown as follows:

Value of LW-0	Selected sampling history data
0	pressure_20061203.dtl
1	pressure_20061127.dtl
2	pressure_20061123.dtl
3	pressure_20061120.dtl

If use with Option List object and select data source as [Dates of historical data], the history data will be sorted by date and displayed in Option List object, see "13.29 Option List".

**Pixel** 

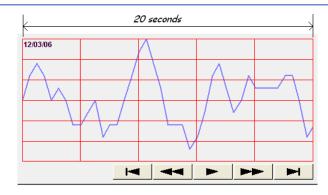
[Distance] is used to set the distance between two sampling points, as shown in the following figure.



Time

[Distance] is used to set the X-axis in unit of time, as shown in the following figure.





Select [Time] for [X axis time range] and go to [Trend] » [Grid] and enable [Time scale]. Please refer to [Time scale] in the later section.

Dynamic distance between data samples/ Dynamic X axis time range Designate a 32-bit word register for adjusting the distance between two sampling points (select Pixel), or the time unit represented by X-axis (select Time). If no value is entered, the default value will be used.

Refresh data automatically

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If selected, every time when opening the window on which the Trend Display object in history mode is placed, the display is automatically refreshed every 10 seconds. Please note that:

- The refresh status can be observed from the control button of Trend Display object.
  - Showing button: The automatic refresh feature is enabled.
  - Showing button: The automatic refresh feature is disabled.
- When scrolling to the previous data, the automatic refresh feature is disabled, the button is shown.
- If [Refresh data automatically] check box is selected, when change back to the window, the display is refreshed, ignoring the control buttons. For example, select [Refresh data automatically], and scroll to the previous data, the automatic refresh feature is disabled. In this case, changing to another window and then change back will still refresh the display.
- If [Refresh data automatically] check box is not selected when building the project, the feature can still be enabled by pressing button on HMI. In this case, the automatic refresh feature is disabled, that is, even when change back to the current window, the display will not be refreshed.

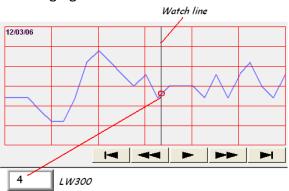


#### **Hold control**

When the register is set ON, suspend the update of Trend Display. It does not stop the sampling process of Data Sampling object. This setting is available only in Real-time mode.

#### Watch line

Use the [Watch line] function to display a "watch line" when user touches the Trend Display object. It will also export the sampling data at the position of watch line to the designated word device and use Numeric objects to display the results, as shown in the following figure.



[Watch line] can also export sampling data with multiple channels. The system will consecutively write each channel to the specified address and the following addresses, in the same order as in [Data Sampling] object. The address assigned to [Watch line] is the start address, and sampling data for each channel will be exported to the word devices starting from "start address." If the data format of each channel is different, the corresponding address of each channel is arranged from the first to the last. If the watch register is LW-300, watch function will export each channel's data to the following addresses:

Register	Channel	Data format
LW-300	0	16-bit Unsigned (1 word)
LW-301	W-301 1 32-bit Unsigned (2 words	
LW-303 2 32-bit float (2 words)		32-bit float (2 words)
LW-305	3	16-bit Signed (1 word)



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## Time stamp output

Time stamp output

Suppose the address is set to LW-n, then:

If enabled, the system will use the time of the first sampling data as "time origin", and write the time stamp of the most recent sampled



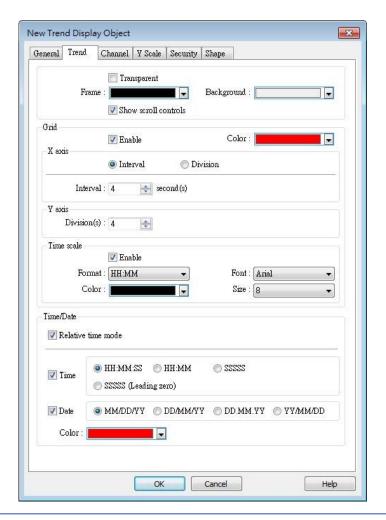
data (relative to "time origin") to [LW-n+2].

When clicking on the curve, the time stamp of the closest sampled point will be written to [LW-n].

Clear real-time data address (Data Sampling object) will clear the time origin as well.

Time stamp is recorded in seconds.

#### **Trend Tab**



Setting	Description
Transparent /	
Frame /	Select the color of frame and background.
Background	
Show scroll	Enable or disable the scroll control as shown in the following figure.
controls	
Grid	Set the number of dividing lines and the line color. The number of divisions depends on the setting in General tab » [Distance



between data samples] / [X axis time range].

#### X-axis interval

The number of vertical grid lines.

Select [Distance between data samples] in General tab:

Select how many sampling points will be included between two vertical grid lines.

Select [X axis time range] in General tab:

Select the time range between two vertical grid lines.

#### X-axis division

The number of vertical grid lines.

#### Y-axis division

The number of horizontal grid lines.

#### Time scale

Select [Time] / [Date] check box to display the time scale along the x axis.



#### Font / Color / Size

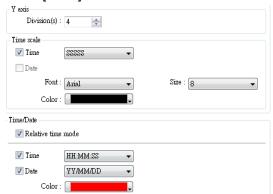
Select the font, font color, and font size of the time scale.

The default font size is 8.

#### Time / Date

#### Relative time mode

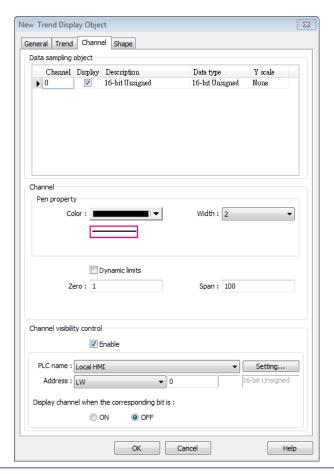
When this mode is selected, the time of the earliest sampling data will be the start time from which to count a relative time. This mode works with time scale [SSSSSS] and under this mode, time scale [Date] cannot be used.





The time of the latest sampling data will be marked on the top left corner of the object. This group box is used to set the time / date display format and font color.

#### **Channel Tab**



#### Setting Description

Y scale

Set Y-axis to be Main Axis or Aux. Axis. See "Y Scale Tab" for more information.



#### Channel

Configure each sampling line's format and color.

#### **Dynamic limits**

Not selected:

[Zero] and [Span] are used to set the low limit and high limit of sampling data. If the low limit is 50 and the high limit is 100 for one sampling line, [Zero] and [Span] must be set as [50] and [100], so that all the sampling data can be displayed in the trend display object.

Selected



> The low limit and the high limit are read from the designated word devices, as shown below. When address is LW-n, the register's address:

Data Format	16-bit	32-bit	64-bit (cMT / cMT X only)
Low limit	LW-n	LW-n	LW-n
High Limit	LW-n+1	LW-n+2	LW-n+4

For example, if LW-100 is used here, the low limit and the high limit will be read from:

Data Format	16-bit	32-bit	64-bit
			(cMT / cMT X
			only)
Low limit	LW-100	LW-100	LW-100
High Limit	LW-101	LW-102	LW-104

A typical usage of this is to zoom in and zoom out of Trend Display. (Not available for cMT / cMT X Series). See Example 1.

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Channel visibility control

If [Enable] is selected, the bits of the assigned word register will be used to show/hide each channel. The first bit controls the first channel, and the second bit controls the second channel, and so on. For example, suppose there are 5 channels and LW-0 is used, channels which will be shown given the states of the control bits are:

Channel	<b>Control Bit</b>	State	Displayed
1	LW_bit-000	OFF	YES
2	LW_bit-001	ON	NO
3	LW_bit-002	ON	NO
4	LW_bit-003	OFF	YES
5	LW bit-004	OFF	YES

Note on using this feature: Each control bits are not reserved for the channel. If a particular channel is not displayed, the control bit is assigned to the next displayed channel. For example, if the third channel of the 5 channels is not displayed, only 4 channels will be displayed in Trend Display, and the used control bits will only be: LW bit-000~003.



Click the icon to download the demo project. Please confirm

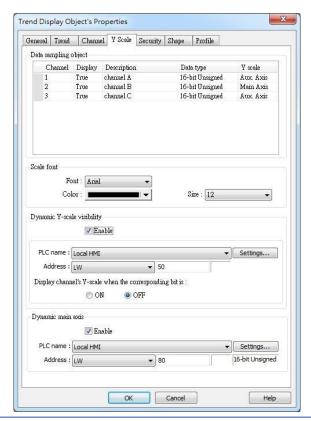


your internet connection before downloading the demo project.



- A Trend Display can display up to 64 channels simultaneously.
- A Trend Display can only display channels with serial number ≤ 256; therefore, channels with serial number greater than 256 cannot be selected.

#### **Y Scale Tab**



Setting	Description
Y scale	Show whether Y-axis is Main Axis or Aux. Axis.
	Y-axis will not be displayed when [none] is selected for Y scale in
	Data Sampling Object group box. At most 32 Y axes can be
	displayed, including one main axis and multiple aux. axes.
Scale font	Select the font, font color, and font size of the scale.
Dynamic	To show or hide Y-scale. If the control address is LW-50, then the
Y-scale visibility	first axis is controlled by LW_Bit 5000, and the second axis is
Visibility	controlled by LW_Bit 5001, and so on.
Dynamic	To change the main axis. If writing 1 into LW-80, the main axis will
main axis	be Channel 1; if writing 2 into LW-80, the main axis will be Channel,
	and so on.





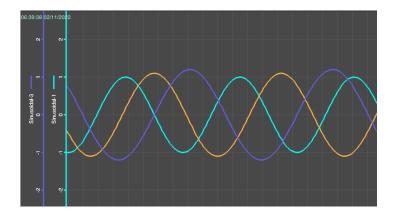
A Trend Display on an eMT/iE/XE/mTV model can display 6MB of data in maximum.

Click the icon to watch the demonstration film. Please confirm your internet connection before playing the film.

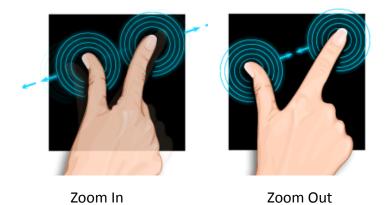
Click the icon to download the demo project. Please confirm your internet connection before downloading the demo project.

#### 13.17.2.2. **cMT**, **cMT** X Series

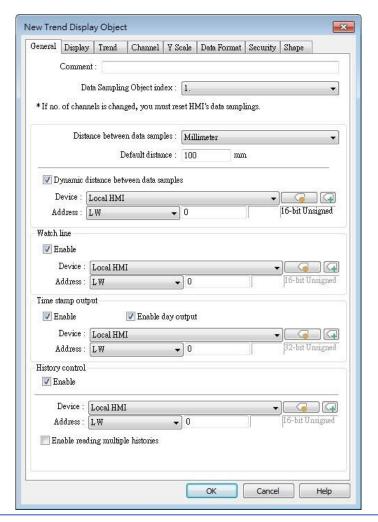
#### **General Tab**



The Trend Display on cMT / cMT X Series combines Real-time mode and History mode. Drag left to scroll the Trend Display to view history data and drag right to view the latest sampling data. Pinch two fingers together to zoom out Trend Display or spread them apart to zoom in.



For more information about how sampling data is saved, see "8 Data Sampling".



Setting	Description
Data Sampling Object index	Select a [Data Sampling] object as the source data.
Millimeter	Same as eMT, iE, XE mTV Series. The upper limit is 500 mm.
Time	Same as eMT, iE, XE mTV Series.
Pixel	Same as eMT, iE, XE mTV Series. The upper limit is 1920 pixels.
Dynamic distance between data samples	Same as eMT, iE, XE mTV Series.
Watch line	Same as eMT, iE, XE mTV Series.
Time stamp output	When enabled, the number of seconds passed from the first sampling data can be calculated.  Suppose the address is set to LW-n, then:  [LW-n]: The number of seconds passed from the first sampling data to the closest sampled point.  [LW-n+2]: The number of seconds passed from the first sampling



data to the most recent sampling data.

## **Enable day output**

With this option selected, the number of days passed since 1970/1/1 can be calculated.

Suppose the address is set to LW-n, then:

[LW-n+4]: The number of days passed since 1970/1/1 to the closest sampled point.

[LW-n+6]: The number of days passed since 1970/1/1 to the most recent sampling data.

## History Control

Same as eMT, iE, XE mTV Series.

#### **Enable reading multiple histories:**

In the following two modes, days are calculated backward.

#### **Number of days**

Suppose the address is set to LW-n, then:

[LW-n]: The start day index from which to calculate number of days.

0: today, 1: yesterday, and so on.

[LW-n+2]: The total number of days before the start day.

#### Specific days

Suppose the address is set to LW-n, then:

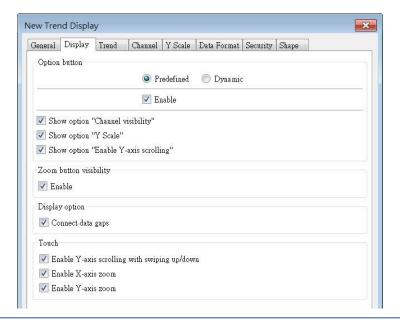
[LW-n]: The start day index from which to calculate number of days.

0: today, 1: yesterday, and so on.

[LW-n+2]: The end day index, the specified value must be greater than that of the start day index. For example, if start is 4 and end is 7, the specified days will be 4 days before to 7 days before.



#### **Display Tab**



### **Setting**

#### **Description**

## **Option** button visibility (cMT Series)

Show or hide the option button of the object.

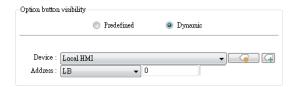


#### **Predefined**

Select [Enable] to show the option button.

#### **Dynamic**

Choose a bit address to control option button visibility.



#### Show option "Channel visibility"

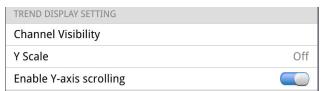
With this option selected, the [Channel Visibility] setting will be displayed.

#### Show option "Y Scale"

With this option selected, the [Y Scale] setting will be displayed.

#### Show option "Enable Y-axis scrolling"

With this option selected, the [Enable Y-axis scrolling] setting will be displayed.

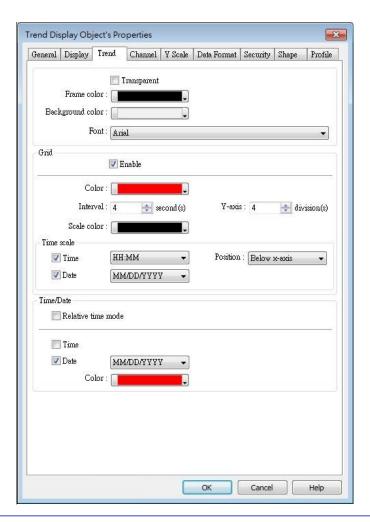




Zoom button visibility	Show or hide the zoom button of the object.		
Display	Show custom file name		
option	This option appears when [Customized file handling] is selected in		
	Data Sampling. With this option selected, the customized file name		
	is shown as caption in Trend Display.		
	Connect data gaps		
	Data sampling stops when PLC is disconnected, and after PLC is		
	reconnected, the trend curve of the disconnected period is plotted		
	with a gap. With this option selected, the system will draw a line to		
	connect the gap between the former trend curve (before		
	disconnected period) and the current trend curve (after		
	disconnected period).		
Touch	Disable Y-axis scrolling with swiping up/down		
	With this option selected, dragging the object with your finger will		
	only scroll X-axis range while Y-axis remains being placed in the		
	middle of the object even if it is zoomed in/out.		
	Disable X axis zoom		
	With this option selected, dragging the object with your finger will		
	only scroll Y-axis range.		
	Disable Y axis zoom		
	With this option selected, dragging the object with your finger will		
	only scroll X-axis range.		



#### **Trend Tab**

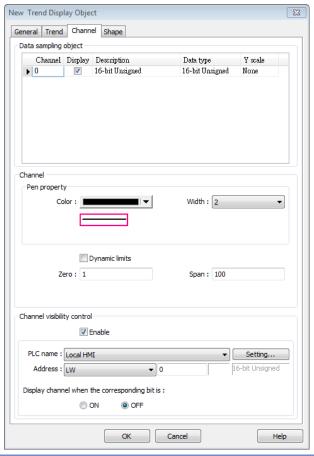


Setting	Description
Transparent /	
Frame /	Select the color of frame and background.
Background	
Grid	Set the number of dividing lines and the line color. The number of
	divisions depends on the setting in General tab » [Distance
	between data samples] / [X axis time range].
	X-axis interval
	The number of vertical grid lines.
	<ul><li>Select [Distance between data samples] in General tab:</li></ul>
	Select how many sampling points will be included between two
	vertical grid lines.
	<ul><li>Select [X axis time range] in General tab:</li></ul>
	Select the time range between two vertical grid lines.
	X-axis division



	The number of vertical grid lines.	
	Y-axis division	
	The number of horizontal grid lines.	
Time scale	Select [Time] / [Date] check box to display the time scale along the	
	x axis. The position of the time scale can be selected.	
	The default font size is 8.	
Time / Date	Relative time mode	
	When this mode is selected, the time of the earliest sampling data	
	will be the start time from which to count a relative time. This	
	mode works with time scale [SSSSSS] and under this mode, time	
	scale [Date] cannot be used.	
	The time of latest sampling data will be marked on the top left	
	corner of the object. This group box is used to set the time / date	
	display format and font color.	

#### **Channel Tab**



Setting	Description
Y scale	Set Y-axis to be Main Axis or Aux. Axis. See "Y Scale Tab" for more
	information. At most 32 Y axes can be displayed, including one



main axis and multiple aux. axes.

Channel	Display	Description	Data type	Y scale
1	Troe	cheanel A	16-bit Unnigned	Avec Axis
2	Troe	cheunel B	16-bit Unrigned	Main Axis
3	Troe	cheunel C	16-bit Unnigned	Avex. Axis

#### Channel

Configure each sampling line's format and color.

#### **Dynamic limits**

#### Not selected:

[Zero] and [Span] are used to set the low limit and high limit of sampling data. If the low limit is 50 and the high limit is 100 for one sampling line, [Zero] and [Span] must be set as [50] and [100], so that all the sampling data can be displayed in the trend display object.

#### Selected

The low limit and the high limit are read from the designated word devices, as shown below. When address is LW-n, the register's address:

Data Format	16-bit	32-bit	64-bit (cMT / cMT X only)
Low limit	LW-n	LW-n	LW-n
High Limit	LW-n+1	LW-n+2	LW-n+4

For example, if LW-100 is used here, the low limit and the high limit will be read from:

Data Format	16-bit	32-bit	<b>64-bit</b> (cMT / cMT X only)
Low limit	LW-100	LW-100	LW-100
High Limit	LW-101	LW-102	LW-104

# Channel visibility control

If [Enable] is selected, the bits of the assigned word register will be used to show/hide each channel. The first bit controls the first channel, and the second bit controls the second channel, and so on. For example, suppose there are 5 channels and LW-0 is used, channels which will be shown given the states of the control bits are:

Channel	<b>Control Bit</b>	State	Displayed
1	LW_bit-000	OFF	YES
2	LW_bit-001	ON	NO
3	LW_bit-002	ON	NO
4	LW_bit-003	OFF	YES



5 LW\_bit-004 OFF YES

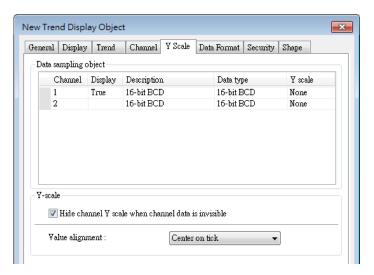
Note on using this feature: Each control bits are not reserved for the channel. If a particular channel is not displayed, the control bit is assigned to the next displayed channel. For example, if the third channel of the 5 channels is not displayed, only 4 channels will be displayed in Trend Display, and the used control bits will only be: LW\_bit-000~003.



- A Trend Display can display up to 64 channels simultaneously.
- A Trend Display can only display channels with serial number ≤ 256; therefore, channels with serial number greater than 256 cannot be selected.



#### **Y Scale Tab**



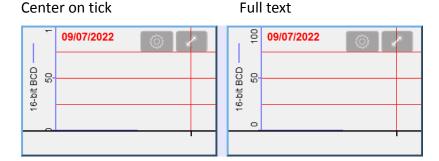
The scale along the Y axis of a specific channel can be displayed. To enable Y Scale, [Grid] should first be enabled in [Trend] tab.

# should first be enabled in [Trend] tab. Setting Description Y Scale Hide channel Y scale when channel data is invisible

This option is selected by default. With this option selected, whether channel Y scale is shown or hidden is determined by the settings in Channel Visibility Control.

#### Value alignment

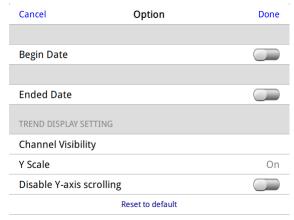
Set the alignment of Y axis tick values.



Y Scale can be configured on the in cMT Viewer as shown in the following steps.

- 1. Tap the button on the upper right corner of Trend Display object.
- 2. Tap [Trend Display Setting] » [Y Scale].

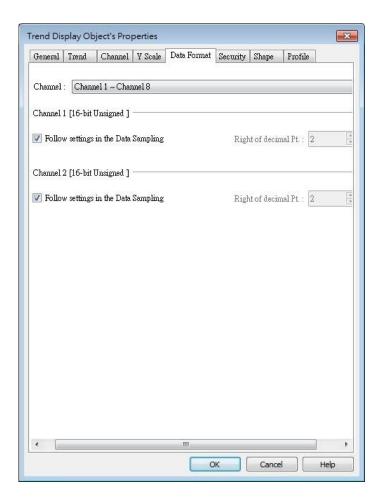




3. Set channel visibility.



#### **Data Format Tab**





Setting	Description				
Follow					
settings in the	Health of Disha of decimal Duller Wise to Date Consulting				
Data	Use the [Right of decimal Pt.] setting in Data Sampling.				
Sampling					
Right of	The number in this field determines the number of decimal places				
decimal Pt	of the value displayed; for example, when 1 is entered in this field,				
	and the original value obtained by Data Sampling is 45, then 4.5				
	will be displayed in Trend Display as a result.				

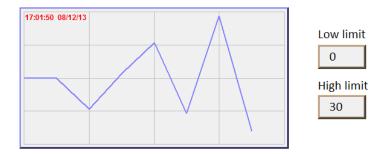
## **Example 1**

The example explains how to zoom in or zoom out Trend Display. The feature described is not available for cMT / cMT X Series.

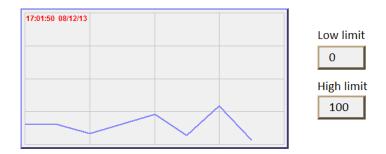
In Channel tab select [Dynamic limits] check box. If the [Address] is set to LW-n, then LW-n controls the low limit where LW-n+1 controls the high limit.



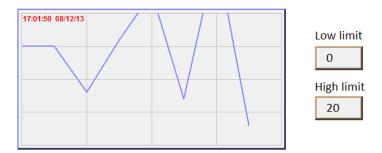
Set [Address] to LW-0 and create two Numeric objects for entering the low / high limit. The address that controls the low limit is LW-0; the address that controls the high limit is LW-1. Let's suppose the data is between 0 and 30; set the [Low limit] to 0 and the [High limit] to 30, the trend curve is displayed as shown in the following figure.



To zoom out the Trend Display, enter a value greater than 30 in [High limit] as shown in the following figure.



To zoom in the Trend Display, enter a value less than 30 in [High limit] as shown in the following figure.



Click the icon to download the demo project. Please confirm your internet connection before downloading the demo project.

## 13.18. History Data Display

#### 13.18.1. Overview

History Data Display object displays data stored by Data Sampling object. It differs from Trend Display in that History Data Display object uses a table to display data. The following is an example of a history data display object.

No.	Time	Date	Ch.0	Ch.1	Ch.2▲
3577		16/09/07	0	0	0
3576	21:52	16/09/07	0	0	0
3575	21:52	16/09/07	0	0	0
3574	21:52	16/09/07	0	0	0
		16/09/07	0	0	0
		16/09/07	0	0	0
3571	21:52	16/09/07	0	0	0
3570	21:52	16/09/07	0	0	0
3569		16/09/07	0	0	0
3568	21.52	16/00/07	0	n	<u>∩</u> _▼
1					

A History Data Display on an eMT/iE/XE/mTV model can display 6MB of data in maximum. The data will not be displayed after exceeding the limit.

#### 13.18.2. Configuration



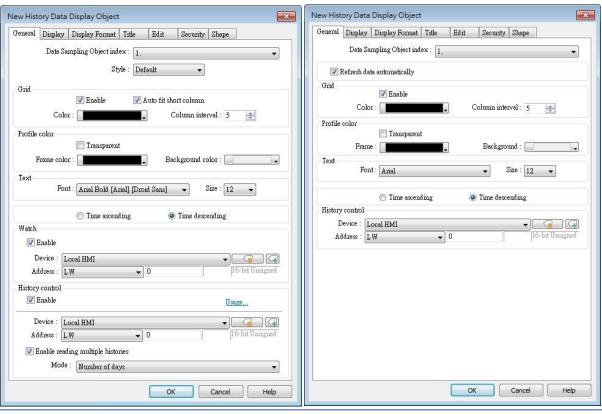
Click [Data/History] » [History Data Display] icon on the toolbar to open a History Data Display object property dialog box. Set up the properties, press OK button, and a new History Data Display object will be created.



#### **General Tab**

#### cMT, cMT X

eMT, iE, XE, mTV



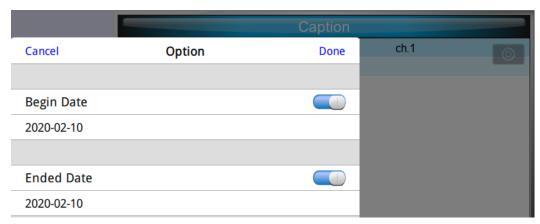
3					
Setting	Description				
Data Sampling object index	Select a Data Sampling object as the source data.				
Refresh Data	The system will refresh data every 10 seconds. When this option is				
Automatically	not selected, data can be freshed only by changing windows.				
Style	Select History Data Display object's style.				
	Shows grids between rows and columns.				
	Color				
	Change the color of grids.				
	Column interval				
	Change the width of each column. The figures below are the				
	examples.				
Grid	No.   Time   Date   Ch.0   Ch.1   Ch.2				



Profile color	Change the color of frame and background. Use [Transparent] to			
Trome color	hide frames and background.			
Text	Change the font and font size.			
	Time ascending			
Time / Date	Put earliest data at the top and the latest data at the bottom.			
Time / Date	Time descending			
	Put the latest data at the top and the earliest data at the bottom.			
History	The history files are sorted by date and each file is given an index.			
History Control	The latest one is assigned index 0 (in most cases: today), the			
(eMT, iE, XE,	second latest file is assigned index 1, and so on. [History Control] is			
mTV Series)	used to specify the history data to be shown.			
Watch (cMT /	By tapping on a record in History Data Display object, data in the			
cMT X Series)	selected row can be output to the designated addresses.			
History	Same as eMT, iE, XE mTV Series.			
Control (cMT	Enable reading multiple histories:			
/ cMT X Series)	In the following two modes, days are calculated backward.			
Jeries,	Number of days			
	Suppose the address is set to LW-n, then:			
	[LW-n]: The start day index from which to calculate number of days			
	0: today, 1: yesterday, and so on.			
	[LW-n+2]: The total number of days before the start day.			
	Specific days			
	Suppose the address is set to LW-n, then:			
	[LW-n]: The start day index from which to calculate number of days			
	0: today, 1: yesterday, and so on.			
	[LW-n+2]: The end day index, the specified value must be greater			
	than that of the start day index. e.g. start: 4, end: 7, the specified			
	days will be 4 days before to 7 days before.			



■ When using cMT / cMT X Series, use the gear icon in the upper-right corner of History Data Display object in cMT Viewer to select the date and display the data.



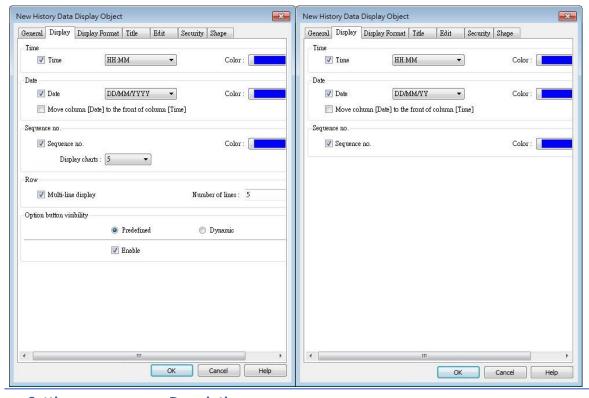
Click the icon to watch the demonstration film. Please confirm your internet connection before playing the film.



#### **Display Tab**

#### cMT, cMT X

eMT, iE, XE, mTV



Description	
Enable or disable showing the time and date and configure its	
format and color.	
Move column [Date] to the front of column [Time]	
Swap the position of column [Date] and column [Time].	
Show the sequence number of all records.	
Multi-line display	
Display a specified number of lines of data. Data will be displayed	
as specified regardless of the actual number of lines of data.	

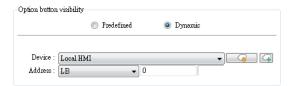
Show or hide the option button



#### **Predefined**

Option button visibility (cMT / cMT X Series) Select [Enable] to show the option button.

#### **Dynamic**

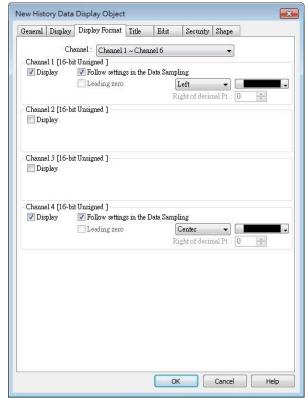


Designate a bit address to control option button visibility.

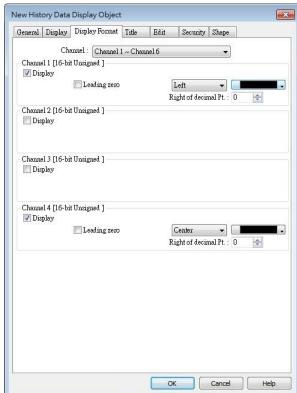


#### **Data Format Tab**

## cMT / cMT X Series



eMT, iE, XE, mTV Series

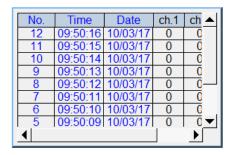


#### **Setting**

#### Description

#### Channel

Each History Data Display object can display up to 64 channels. Check [Display] to select the channels to be shown on the screen. In the figure above, there are 4 channels (channel 1 to channel 4) in the Data Sampling object, and only Ch.1 and Ch.4 are selected. The data formats are shown next to channel name. The data format of each channel is decided by the corresponding Data Sampling objects. The result is shown below:

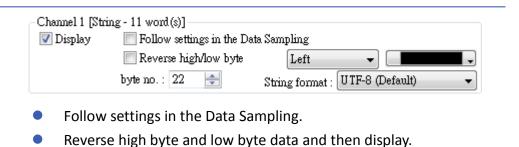


When using cMT / cMT X models, Data Sampling's Data Format settings can be applied to History Data Display object.

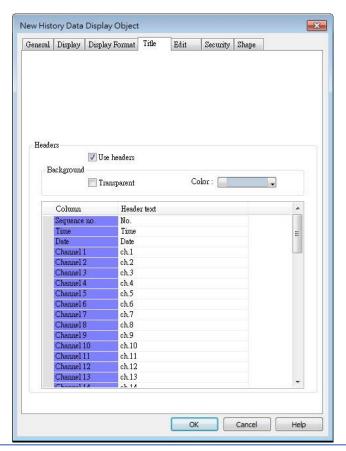
Two display modes are available when displaying [String] format in

History Data Display object:



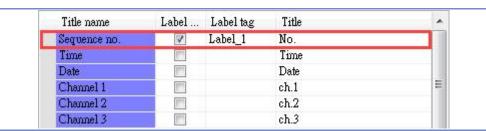


#### **Title Tab**



## 



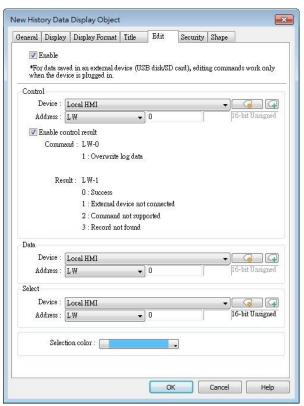




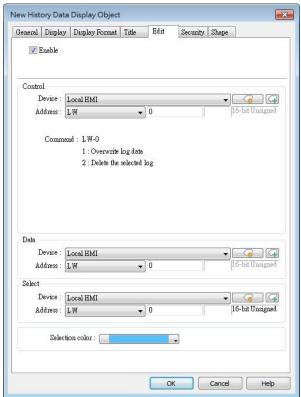
After running simulation on PC, to run simulation again using the same project that contains some changed data, please find the HMI\_memory, SD\_card, or usb1 folder in EasyBuilder Pro installation, and then delete the old data sampling records in it, to prevent the system from reading old data in the second simulation.

#### **Edit Tab**

#### cMT / cMT X Series



eMT, iE, XE, mTV Series



#### **Setting**

#### **Description**

## Control address

LW-n: Command

Value	Description
1	The data in Data Address will
	overwrite the data in data log.
2	The selected data log will be deleted.

LW-n+1: Result (cMT / cMT X Series)



	Value	Description		
	0	The command is executed		
		successfully.		
	1	The external device is not connected.		
	2	The command is not supported.		
	3	The record cannot be found.		
Data address	The syste	em will start reading row by row from the selected one in		
	History Data Display, and change the data log accordingly.			
	Please note that the settings in this address must be identical to			
	that in Data Sampling.			
Select address	By changing the value in Select Address, the corresponding row in			
auuress	History Data Display can be selected.			
	Please note that:			
	1. Whe	n the value in Select Address is 0, no row will be selected,		
	and t	he value in Data Address will stay the same as that of the		
	previously selected row number.			
	2. Whe	2. When the value in Select Address exceeds the total number of		
	rows in History Data Display, the last row (the one with largest			
	row i	number) will be selected.		



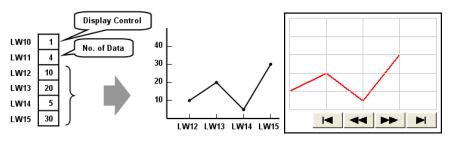
- When an external device is used to save data log, removing the external device will make Edit function ineffective. Editing can keep on when the external device is inserted again and the system starts reading historical data.
- Click the icon to watch the demonstration film. Please confirm your internet connection before playing the film.



## 13.19. Data Block Display

#### 13.19.1. Overview

Data Block is a combination of several word devices with continuous address, where the X axis of Data Block Display object represents the address and the numbers on the Y axis represent the data values in the corresponding address. Data Block Display object can display multiple data blocks. For example, it can display two data blocks LW-12~LW-15 and RW-12~RW-15 in trend curves simultaneously. It is very useful to observe and compare the difference of trend curves.



The display result

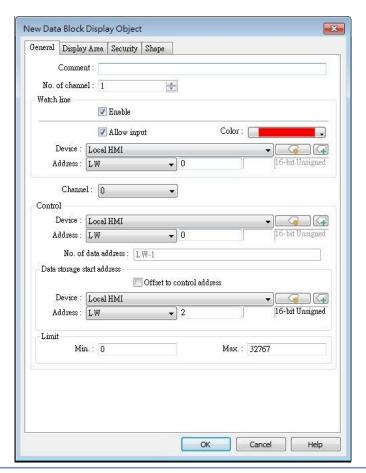
#### 13.19.2. Configuration



Click the [Object] » [Chart] » [Data Block Display] icon on the toolbar to open the property dialog box. Set up the properties, press OK button, and a new Data Block Display object will be created.



#### **General Tab**



Setting	Description
Comment	Description of the object.
No. of	Set the no of channel for this object. Each channel represents one
channel	data block. The maximal number of channels is 12.
Watch Line	If enabled, when user touches the [Data Block Display] object, it will display a vertical cursor line on it, and store the data on the line to the designated registers. See Example 1.  Allow input (cMT / cMT X Series)  With this checkbox selected, entering a value in the specified address for watch line can move the verticle watch line to the desired position.
Channel	Select the channel to be configured.
Control	Specify the control address also the data source.
address	Control address is used to control and clear the drawn curve. After executing the operation below, the system will reset the control word to zero.  Enter "0" = No action (default)  Enter "1" = Draw (Without clear first)  Enter "2" = Clear



Enter	"2"	= F	₽₽S	raw
LIILEI	J	- 1	١cu	ıavv

#### No. of data address

If control address is LW-n, then LW-n+1 stores the number of word devices in each data block, i.e. the number of data. The maximum value is 1024.

#### Data storage start address

If [Offset to start address] is enabled, the [Offset value storage address] will be set as [Control address] + 2.

If select 16-bit data format, the address for each data will be start address, start address + 1, start address + 2 and so on.

If select 32-bit data format, the address for each data will be start address, start address + 2, start address + 4 and so on.

For more information about control address, see Example 2 to 5.

Limit

Set the minimum and maximum limit for the curve.



■ Without clearing the drawn lines, Data Block Display can be drawn a number of times by entering value 1 in the control address repeatedly. The way to calculate the maximum number of times is: 32 divided by the number of channels.

1 channel → 32 times

2 channels → 16 times

16 channels → 2 times

#### **Example 1**

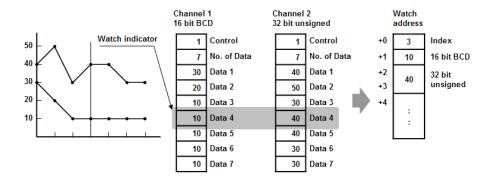
#### How to use watch (Cursor Line) feature

Use "Watch" function to check the value of any point of the curve. When the user touches [Data Block] object, it will display a "cursor line", and the system will write the index and value of that data on the cursor line to the designated address.

Data Format	Index Value	Channel 1 Value	Channel 2 Value
16-bit	Address	Address + 1	Address + 2
32-bit	Address	Address + 2	Address + 4
64-bit (cMT/	Address	Address + 4	Address + 8
cMT X only)	Address		

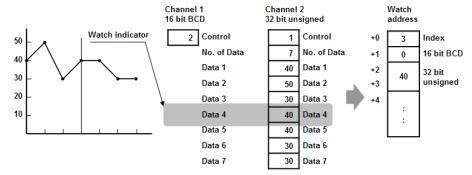
When watch address is set to LW-n, the value written into LW-n represents the channel index number to be called up. (Start form 0)



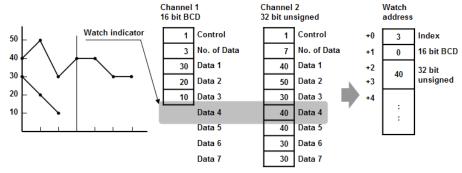




- [Data Index] is a 16 bit unsigned integer. When the designated register of cursor line is 32 bit device, it will be stored in the bit 0-15.
- If the channel to be viewed has no data, "0" will be displayed, as shown below. In the example, there is no data in channel 1, when the cursor points at Data 4, "0" will be displayed as shown below.



If there is less data in Channel 1, "0" will be displayed, as shown below.

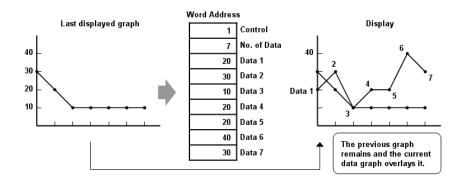


## **Example 2**

#### How to show a data block

- 1. Write the number of data to [No. of data address], i.e. "Control address+1"
- 2. Store the data consecutively beginning at [Data storage start address].
- 3. Write "1" to [Control address] to draw the curve without cleaning the plot. All previous curves will not be erased.
- 4. The system will write "0" to [Control address] after marking the plot.





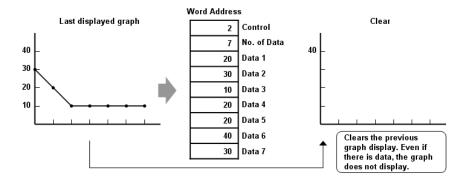


Do not change the content of [Control address], [No. of data address] and [Data storage start address] between step 3 and step 4 above as doing so might cause error for the trend curve plot.

## **Example 3**

#### How to clear the graph

- 1. Write "2" to [Control address], all the trend curves will be cleared.
- 2. The system will write "0" to [Control address] after the trend curve is cleared.

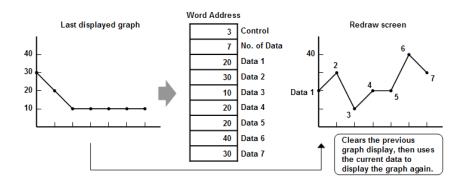


## **Example 4**

#### How to clear the previous trend curve and display new one

- 1. Write the number of data to [No. of data address], i.e. "control address+1"
- 2. Store the data consecutively beginning at [Data storage start address].
- **3.** Write "3" to [Control address], the previous trend curves will be cleared and the new content in data block will be plotted on the screen.
- 4. The system will write "0" to [Control address] after the trend curve has been plotted.





## **Example 5**

#### How to use offset mode

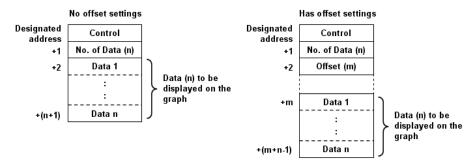
If [Offset to start address] is selected, [Control address], [No. of data address], and [Offset value storage address] will use 3 consecutive addresses.

For example, assume the total number of channels is 3 (start from 0 to 2), and the [Control address] are LW-0, LW-100, and LW-200, respectively. Then, the other addresses will be set as follows: (In the example, format 16-bit Unsigned is used and [Offset value storage address] are all m).



Item	Channel 0	Channel 1	Channel 2
<b>Control Address</b>	LW-0	LW-100	LW-200
No. of data	LW-1	LW-101	LW-201
address			
Offset value	LW-2 (=m)	LW-102 (=m)	LW-202 (=m)
storage address			
Data 1	LW-0+m	LW-100+m	LW-200+m
Data 2	LW-1+m	LW-101+m	LW-201+m

The following figure on the left shows the result when offset mode is not used while the figure on the right shows the result when offset mode is used.





When [Control address] is set to LW-n, [No. of data address] and [Offset value storage address] are as follows:

<u> </u>			
Data Type	16-bit	32-bit	64-bit (cMT / cMT
			X only)
Control address	LW-n	LW-n	LW-n
No. of data address	LW-n+1	LW-n+2	LW-n+4
Offset value storage address	LW-n+2	LW-n+4	LW-n+8

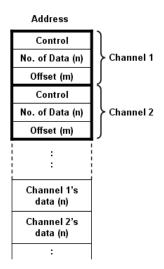
If the control registers are 32-bit devices, only bit 0-15 will be used for control purpose, bit 16-31 will be ignored. (as illustrated below)

	32 bit device				
3	1 16	15 0			
+0	0	Control			
+1	0	No. of Data			
+2	0	Offset			

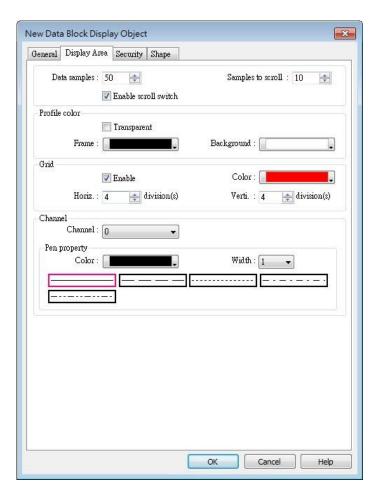
- When the value in [Control address] is not zero, the system will read [No. on data address] and [Offset value storage address].
- It is recommended to use [Offset to start address] for data block display with multiple



channels and the same device type. As shown in the following figure, The control words of channel 1 is located from LW-n, the control words of channel 2 is located from LW-n+3, and so on.



#### **Display Area**



Setting	Description
Description	Data samples



	Configure the maximal number of data samples (points) to be		
	,		
	displayed.		
	Samples to scroll		
	Configure the number of data samples being scrolled.		
	Enable scroll switch		
	Clicking displays the previous or next data point.		
	Clicking displays the first or the last data point.		
Profile	Set the color of the frame and background of the object.		
	Transparent		
	Hides the background. Color selection will not be available.		
Grid	Set the number of horizontal and vertical divisions shown by grid.		
Channel	Set the color, width and style of each curve.		

Click the icon to download the demo project. Please confirm your internet connection before downloading the demo project.



#### 13.20. XY Plot

#### 13.20.1. Overview

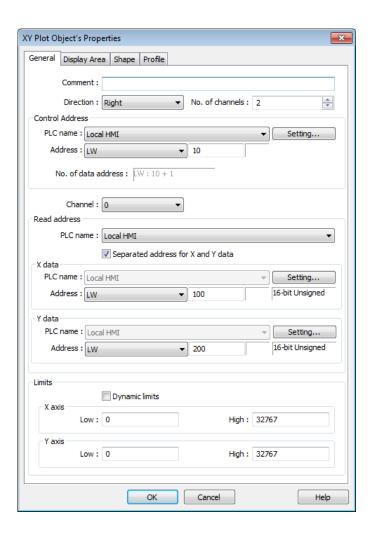
XY Plot object is used to display values for two variables (x,y) for a set of data, where the data comes from word registers. Up to 16 channels can be displayed simultaneously. This object facilitates data observation and analysis. Additionally, negative numbers can be displayed as well.

#### 13.20.2. Configuration



Click [Object] » [Chart] » [XY Plot] icon on the toolbar to open a [XY Plot] object property dialog box.

#### **General Tab**





Setting	Description			
Direction	There are four selections, right, left, up or down.			
	Right direction    Right direction	Left  Left direction  Y	Up  Up direction  ×  origin → γ	Down  origin → Y  X  Down direction
No. of channels	Set the number	of channels for c	bservation.	
Control address	[Control addres commands to X LW-n+1 I contro	s] is LW-n, assign Y plot according t Is the number of	nnels simultaneou ing values to LW-n to the table below data points plotte will be reset to 0.	will issue . Meanwhile,
	Control Valu		will be reset to 0.	
	LW-n 1	(The plotte	on XY curve. ed points are kept. Y curves. n plots new XY cur	
	LW-n+1 Ar	' I ( ONTROIS TR	ne number of data	points plotted.
	No. of data add Controls the nu 1023 points.		nts. Each channel o	can plot up to
Channel	Select a channel to configure.			
Read Address	designate a read The format of the depends on wh	d address. ne data register b ether [Separated	urce of [X data] an locks used for the address for X and	display channels Y data] and/or
D	<u> </u>		ed. See Example 1	•
Dynamic limits	The Low and Higand High limits percentage.	are used for calcu	et by entering con	
		cted (See Exampl an be created by	e 3) changing the Low	/ High Limits.

#### **Example 1**

The format of the data register blocks used for the display channels depends on whether [Separated address for X and Y data] has been selected, and if [Dynamic limits] has been selected. The following explains the situations where 16-bit register is used:

• If [Separated address for X and Y data] is **not** selected, and set [Read address] to LW-n:

	Select [Dynam	Select [Dynamic limits]		Dynamic limits]
	X data	Y data	X data	Y data
Low Limit	LW-n	LW-n+2	Constant	Constant
High Limit	LW-n+1	LW-n+3	Constant	Constant
1 <sup>st</sup> data	LW-n+4	LW-n+5	LW-n+0	LW-n+1
2 <sup>nd</sup> data	LW-n+6	LW-n+7	LW-n+2	LW-n+3
3 <sup>rd</sup> data	LW-n+8	LW-n+9	LW-n+4	LW-n+5
4 <sup>th</sup> data	LW-n+10	LW-n+11	LW-n+6	LW-n+7

 If [Separated address for X and Y data] is selected, and set [X data] to LW-m, [Y data] to LW-n:

	Select [Dynamic limits]		Not select [Dynamic limits	
	X data	Y data	X data	Y data
Low Limit	LW-m+0	LW-n+0	Constant	Constant
High Limit	LW-m+1	LW-n+1	Constant	Constant
1 <sup>st</sup> data	LW-m+2	LW-n+2	LW-m+0	LW-n+0
2 <sup>nd</sup> data	LW-m+3	LW-n+3	LW-m+1	LW-n+1
3 <sup>rd</sup> data	LW-m+4	LW-n+4	LW-m+2	LW-n+2
4 <sup>th</sup> data	LW-m+5	LW-n+5	LW-m+3	LW-n+3

#### **Example 2**

When [Dynamic limits] is not selected, the Low and High limits can be set. The Low and High limits are used for calculating X and Y range in percentage.

$$Scale (\%) = \frac{Read Address Value - Low Limit}{High Limit - Low Lmit}$$

If [Separated address for X and Y data] is **not** selected and the address is LW-n, the corresponding limits are retrieved from the addresses as shown in the following table.

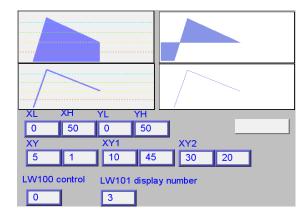
Data format	16-bit	32-bit	64-bit (cMT / cMT X only)
X axis low limit	LW-n	LW-n	LW-n
X axis high limit	LW-n+1	LW-n+2	LW-n+4
Y axis low limit	LW-n+2	LW-n+4	LW-n+8
Y axis high limit	LW-n+3	LW-n+6	LW-n+12



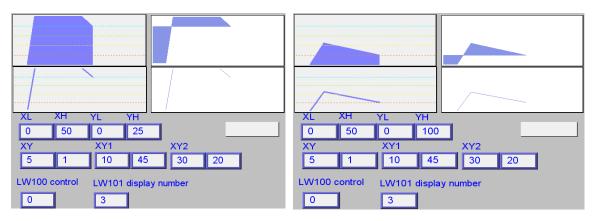
#### **Example 3**

If **[Dynamic limits]** is selected, a zoom effect can be created by changing the setting of Low / High Limits.

In the following example, XL=X low limit, XH=X high limit, YL=Y low limit, YH=Y high limit, and XY, XY1, XY2 are three XY data. When changing the high limits of X and Y axis, the result is shown below:

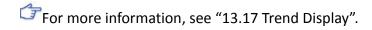


Original



Change the high limit of Y axis to 25. (zoom in)

Change the high limit of Y axis to 100 (zoom out)

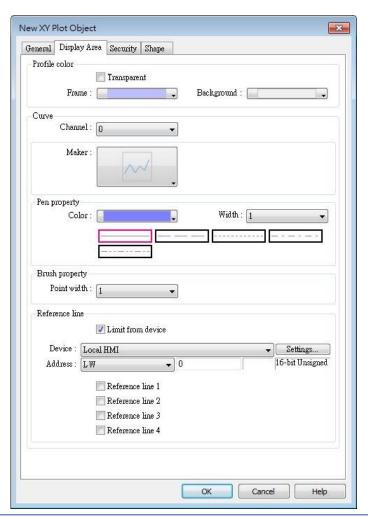




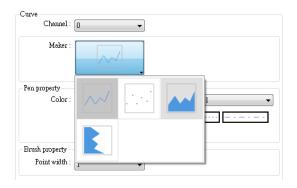
- X and Y data can be set to different formats. For example: If X data uses 16-bit unsigned, Y data uses 32-bit signed, please note the address setting.
- When using a Tag PLC, such as AB tag PLC, X and Y must be in the same format. When using different formats a warning will be shown.



#### **Display Area Tab**



Setting	Description
Profile color	Select the color of the frame and the background, or select
	[Transparent] check box to hide the frame and background.
Curve	For each channel select the properties of color, width, and line
	style.
Maker	Select the style of XY Plot. For eMT/iE/XE/mTV series, there are
	four different types of XY plot as shown below:





For cMT / cMT X Series, , there are six different types of XY plot as shown below:



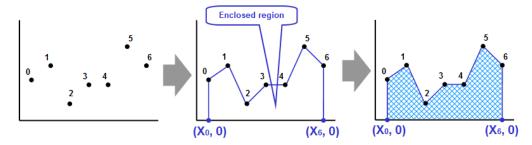
See Example 4.

Pen property	Select color, width and style for the line in XY plot.
Brush	Coloct point width
property	Select point width.
Reference line	Up to 4 horizontal reference lines can be shown on the graph. Fill in
	high, low limits and Y axis percentage values. Different colors can
	be selected for each reference line.
	If [Limit from PLC] is selected, designate a register to be the read
	address of reference line.

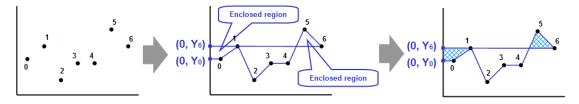
#### **Example 4**

The curve shown in the following figure is drawn with 7 points numbered from P0 to P6. The steps the system draws the X-axis Projection are:

- 1. Calculates the two points in X-axis  $(X_0, 0)$  and  $(X_6, 0)$ .
- 2. Link all the points in the order of  $(X_0, 0)$ , P0... P6,  $(X_6, 0)$  and returns to  $(X_0, 0)$  at last.
- 3. Fill out all enclosed areas.



Similarly for Y-axis projection:







Without clearing the drawn points, XY Plot can be drawn a number of times by entering value 1 in the control address repeatedly. The way to calculate the maximum number of times is: 32 divided by the number of channels.

1 channel → 32 times

2 channels → 16 times

16 channels → 2 times



#### 13.21. Alarm Bar and Alarm Display

#### 13.21.1. Overview

Alarm Bar and Alarm Display objects are used to display alarm messages which are defined in Event (Alarm) Log objects. When the trigger conditions are met, events or alarms will be displayed as they occur in chronological order in Alarm Bar or Alarm Display object.

Alarm Bar scrolls all alarm messages in one single display line, whereas Alarm Display shows alarm messages in multiple lines.

For more information, see "7 Event Log".

```
1 (When LW 1 >= 10) 13:21:06 Event 0 (when LW0
```

Alarm Bar - Displays alarm messages in one scrolling line.

Alarm Display – Displays alarm messages in multiple lines.

#### 13.21.2. Configuration



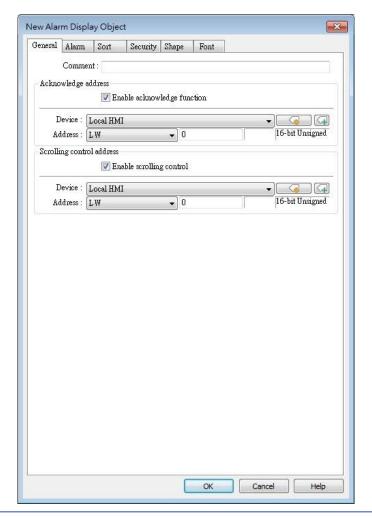


Click [Data/History] » [Alarm Display] or [Alarm Bar] icon on the toolbar to open the object property dialog box. Set up the properties, press OK button, and a new object will be created.

#### **General Tab**

The difference between these two objects is that Alarm Display allows an [Acknowledge address] and a [Scrolling control address] to be set.





#### **Setting**

#### Description

# Enable acknowledge function

If selected, the [Acknowledge value] selected for the associated event, specified in Alarm (Event) Log » Message tab will be written to the [Acknowledge address] designated in Alarm Display. For more information, see "7 Event Log".



# Scrolling control address

If enabled, the value in the designated control address indicates the number of lines to be scrolled down. The minimal value is 0, which indicates the first line. Please note that with this address enabled, the horizontal and vertical scroll bars will not be available on the object; please make sure that the width of the object is enough for completely showing the content.



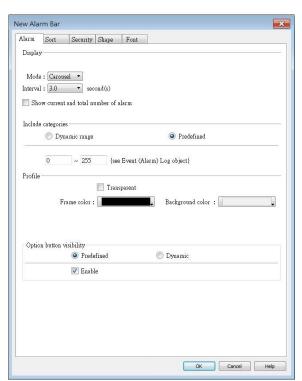
■ When using a cMT / cMT X Series model, press and hold the event on the screen to



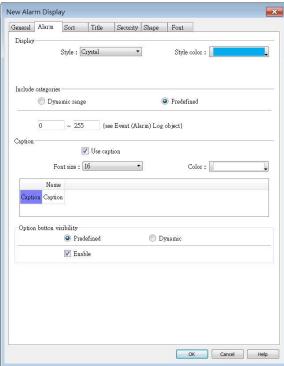
- acknowledge an event; drag a finger on the screen to scroll.
- When using a cMT / cMT X Series model, a default minimal row height exists in Alarm Display objects that have enabled Acknowledge function. The minimal row height prevents the rows to be touch by mistake. On a small-sized HMI, the row height may be slightly taller when Acknowledge function is enabled.

#### **Alarm Tab**

#### Alarm Bar



#### Alarm Display

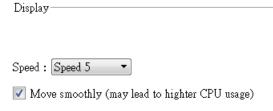


#### Setting Description

#### **Display**

Display settings are only available for Alarm Bar.

#### iP/iE/XE/eMT/mTV Series

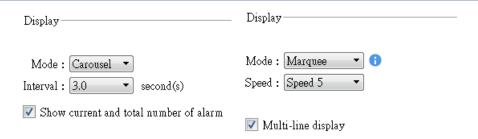


When [Move smoothly] option is selected, the message will move along the Alarm Bar object more smoothly. Please note that enabling this may lead to high CPU loading.

#### cMT / cMT X Series

The available modes are [Carousel] and [Marquee].





When [Carousel] mode is selected, the option to display the current and total alarm count and set the interval in seconds can be enabled.



When [Marquee] mode is selected, the speed of text movement in the Alarm Bar object can be adjusted. Enabling multi-line display allows the event content to be shown in multiple lines within the Alarm Bar object. Please consider the performance impact when using this mode.

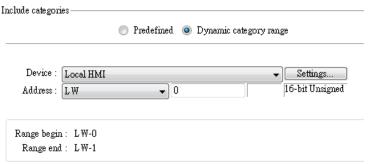
## Include categories

Events in the selected category will be displayed. The categories are set in Event (Alarm) Log object.

For example, if the category is set to "2 to 4" here, only events in categories 2, 3, 4 will be displayed. For more information, see "7 Event Log".

#### cMT / cMT X Series

Dynamic Category Range is an option available only for cMT Series models. With this option selected, an address can be designated for dynamically selecting event categories to be displayed.



#### Caption

Caption settings are only available for Alarm Display on cMT / cMT X Series.





Option
button
visibility (cMT
/ cMT X
Series)

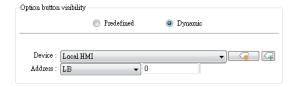
Show or hide the option button



#### **Predefined**

Select [Enable] to show the option button.

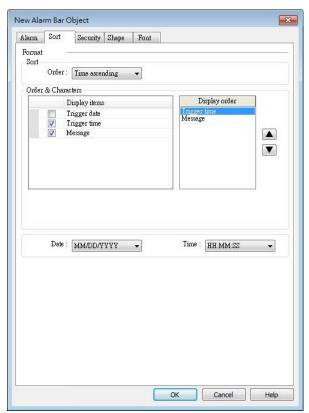
#### **Dynamic**



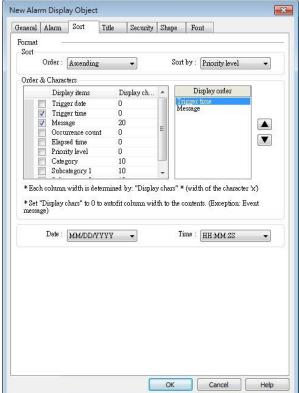
Designate a bit address to control option button visibility.

#### **Sort Tab**

#### Alarm Bar



#### Alarm Display



Setting Description

Order (Alarm Time ascending

**Bar)** Latest event is placed last in the list (the bottom).



	Time descending
	Latest event is placed first in the list (the top).
Order (Alarm	Sort by:
Display)	Ascending – Priority Level (cMT / cMT X Series)
	Event with highest priority level is placed last in the list (the
	bottom).
	Descending – Priority Level (cMT / cMT X Series)
	Event with highest priority level is placed first in the list (the top).
	Ascending – Occurrence Count
	Event with highest occurrence count is placed last in the list (the
	bottom).
	Descending – Occurrence Count
	Event with highest occurrence count is placed first in the list (the
	top).
	Ascending - Time
	Latest event is placed last in the list (the bottom).
	Descending - Time
	Latest event is placed first in the list (the top).
Display order	Select the items to be displayed and use the up and down arrow
	buttons to adjust the display order of the alarms.
Date	Displays the date tag with each alarm message. The four formats of
	date tag:
	MM/DD/YY、DD/MM/YY、DD/MM/YY、YY/MM/DD
Time	Displays the time tag with each alarm message. The four formats of
	time tag:
	HH:MM:SS、HH:MM、DD:HH:MM、HH



#### **Title Tab**

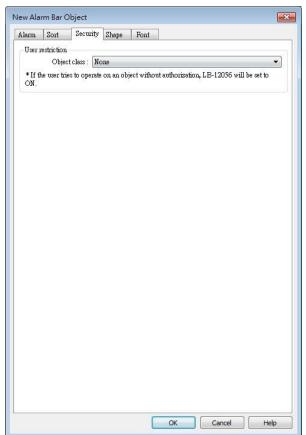


Title settings are available on cMT Series. With [Use headers] selected, the text color and column headers can be configured.

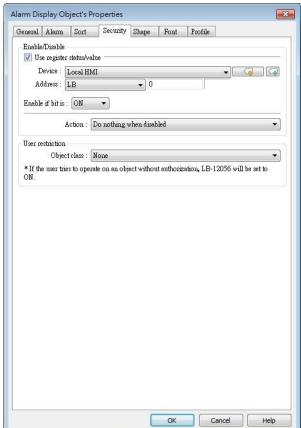


#### **Security Tab**

#### Alarm Bar



#### Alarm Display



#### **Setting**

#### **Description**

#### Interlock

When [Use interlock function] check box is selected, whether the object is operable is determined by the state of a designated Bit address. As shown in the above settings, if LB-0 is ON, the object is operable.

#### Hide when disabled

When the designated Bit is OFF, the object will be hidden.

### User restriction

Set the security class of the object to be operated by an authorized user.

#### **Object class**

"None" means any user can operate this object. Only account "admin" can operate "Administrator" object class.

#### Make invisible while protected

When the user's privilege does not match the object class, the object will be hidden.

When this check box is deselected in Alarm Display

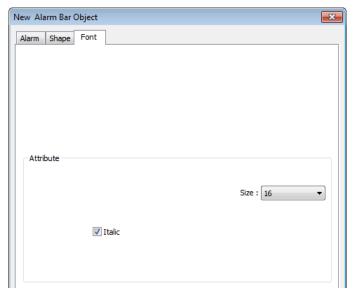


object settings, the unauthorized user can see the Alarm Display object, but cannot trigger the object or make any change.

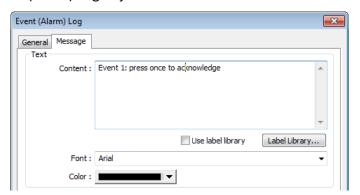
This check box is greyed out in Alarm Bar object settings.

#### **Font Tab**

Set the font size or select [Italic].



The font, color, and content of the alarm messages displayed in Alarm Bar and Alarm Display objects are set in Alarm (Event) Log object:



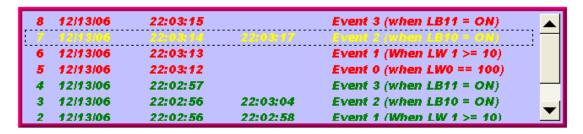
Click the icon to download the demo project. Please confirm your internet connection before downloading the demo project.

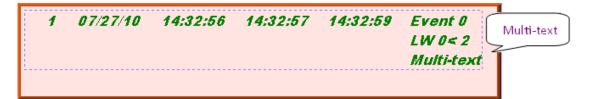


#### 13.22. Event Display

#### 13.22.1. Overview

The Event Display object displays events from the Event (Alarm) Log that meet the specified trigger conditions. These displayed events can be sorted based on time, occurrence count, or priority level. The Event Display object provides information about the events, including the trigger date / time, acknowledge time, recovered time, message, occurrence count, elapsed time, priority level, category, and subcategory. Furthermore, it is capable of displaying multi-lined messages as well.





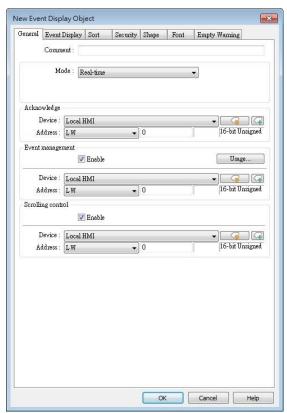
#### 13.22.2. Configuration

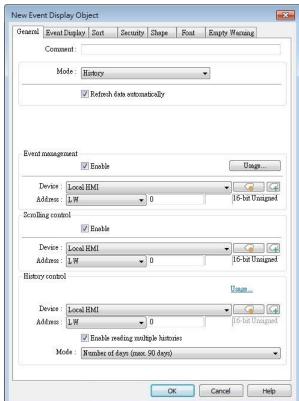


Click [Data/History] »[Event Display] icon on the toolbar to open an Event Display object property dialog box. Set up the properties, press OK button, and a new Event Display object will be created.

#### **General Tab**

#### 13.22.2.1. **eMT, iE, XE, mTV Series**





#### Setting

#### **Description**

#### Mode

The available modes are: [Real-time] and [History].

- Real-time
   All the events triggered since HMI starts up are displayed.
- History

The system reads the event log in HMI memory and displays them. The content can be updated by changing window. In case when the trend display shows history data from today, the display will refresh once per second.

#### **Acknowledge**

When in Real-time mode and an event is acknowledged by touching an active display line, the [Acknowledge value] specified in Event (Alarm) Log object, Message tab, is output to the [Acknowledge address] of Event Display object. For more information, see "7 Event Log".



## History Control

When in History mode and if:

[Enable reading multiple histories] is not selected



The history files are sorted by date and each file is given an index. The latest one is assigned index 0 (in most cases: today), the second latest file is assigned index 1, and so on. The history control address is used to specify the history file to be displayed.

If control address is LW-100, and four files exist with dates: EL\_20100720.evt, EL\_20100723.evt, EL\_20100727.evt, and EL\_20100803.evt.

The index value given to each file is shown below:

Value in LW-100	The corresponding file
0	EL 20100803.evt
1	EL 20100727.evt
2	_
2	EL_20100723.evt
3	EL_20100720.evt

#### [Enable reading multiple histories] is selected

Displays a list of events triggered in multiple days. The display range is formed by two consecutive addresses. Please note that the history control address is defined differently in "Number of days" mode and in "Index of the last history" mode.

#### **Number of days**

Suppose the history control address is set to LW-n, then:

[LW-n]: The start day index (which is expressed as the number of days before today. 0: today, 1: yesterday, and so on.)

[LW-n+1]: The total number of days to display. The days are calculated backward from the start day.

Example: If today were 2010/6/10, and LW-n = 1, LW-n+1 = 3, then the data range will start from 1 day before today, which is 20100609 (yesterday), and include data for 3 days:  $20100607^220100609$ .

👺 EL_20100604	No.4	1 KB	EVT
FEL_20100605	No.3	6 KB	EVT
EL_20100608	No.2	17 KB	EVT
👺 EL_20100609	No.1	4 KB	EVT
ES ET 50100610	No.0	12 KB	EVT

#### Index of the last history

Suppose the history control address is set to LW-n, then:

[LW-n]: The index value of the file to start. 0: the latest file, 1: the second latest file, and so on.

[LW-n+1]: The index value of the file to end. The specified value must be greater than that of the start index.

Example: If LW-n = 1 and LW-n+1 = 3, then file No.1, No.2, No.3 will be displayed.

👺 EL_20100604	No.4	1 KB	EVT
EL_20100605	No.3	6 KB	EVT
EL_20100608	No.2	17 KB	EVT
SEL_20100609	No.1	4 KB	EVT
SPEL_20100610	No.0	12 KB	EVT

The maximum size of data that can be displayed is 4MB. Data exceeding the limit will not be displayed.



The following shows how data will be displayed according to data size.

5 history data, each is 0.5MB → Data displayed: 8 x 0.5MB

5 history data, each is 1MB → Data displayed: 4 x 1MB

5 history data, each is 1.5MB → Data displayed:

2 x 1.5MB+1 x 1MB (partial)

Click the icon to download the demo project. Please confirm your internet connection before downloading the demo project.

## Event management

#### **Enable event management**

If this check box is selected, writing a specific value into register LW-n and LW-n+1, where n is an arbitrary number, will control [Event Display] object with different commands as shown below:

1 / 1		
Address	Value	Command
LW-n	0	Display all events.
	1	Hide [Confirmed] events.
	2	Hide [Recovered] events.
	3	Hide [Confirmed] or [Recovered] events.
	4	Hide [Confirmed] and [Recovered] events.
LW-n+1	1	In real-time mode, delete a single selected
		event.

## Scrolling control

If enabled, the value in the designated control address indicates the number of lines to be scrolled down. The minimal value is 0, which indicates the first line.

In the following figure, there are 10 events recorded in the object, and value 3 is set at the control address. The upper event object displays the events in time ascending order, and begins at the 4<sup>th</sup> event; on the other hand, the lower one displays the events in time descending order, and begins at the 7<sup>th</sup> event.

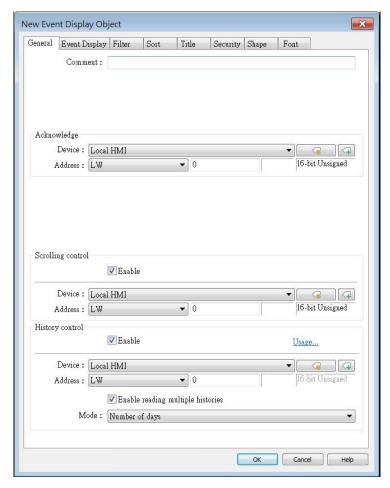


If [Scrolling control address] is enabled, the scroll bar cannot be used for scrolling, but still shows the relative position of the content. If the control address holds a value that is larger than the total number of lines, the display will stroll to the end. Please note that with this address enabled, the horizontal and vertical scroll bars will not be available on the object; please make sure that the width of the object is enough for completely showing the content.



Click the icon to watch the demonstration film. Please confirm your internet connection before playing the film.

#### 13.22.2.2. cMT, cMT X Series



For cMT / cMT X models, only events with "save to history" option selected in the Event (Alarm) Log settings can be displayed in the Event Display object. The events that are not set to be saved in the history can be displayed using the Alarm Bar or Alarm Display object.

# Acknowledge When an event is acknowledged, the value specified in the Acknowledge Value field under the Message tab of the Event (Alarm) Log settings will be outputted to the Acknowledge address of the Event Display object. For more information, see "7 Event Log". Acknowledge value for Event/Alarm Display object Acknowledge value: 11 Scrolling If enabled, the value in the designated control address indicates the number of lines to be scrolled down. The minimal value is 0, which indicates the first line.



#### History Control

[Enable reading multiple histories] is not selected

The history files are sorted by date and each file is given an index which is expressed as the number of days before today. 0: today, 1: yesterday, and so on. The history control address is used to specify the history file to be displayed.

• [Enable reading multiple histories] is selected

Displays a list of events triggered in multiple days. The display range is formed by two consecutive addresses. Please note that the history control address is defined differently in "Number of days" mode and in "Specific days" mode.

#### **Number of days**

Suppose the history control address is set to LW-n, then:

[LW-n]: The start day index (which is expressed as the number of days before today. 0: today, 1: yesterday, and so on.)

[LW-n+1]: The total number of days to display. The days are calculated backward from the start day.

#### **Specific days**

Suppose the history control address is set to LW-n, then:

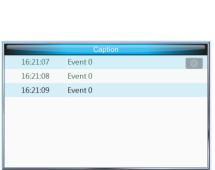
[LW-n]: The start day index. 0: today, 1: yesterday, and so on.

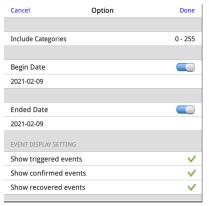
[LW-n+1]: The end day index. The specified value must be greater than that of the start day index.

Example: When start = 4 and end = 7, the specified days will be 4 days before to 7 days before.

For cMT / cMT X Series, all the events that occurred are displayed and updated in real-time.

Press the Option Button in the upper-right corner of the object and set the start and end date. If the dates are not set specifically, all the events are displayed.





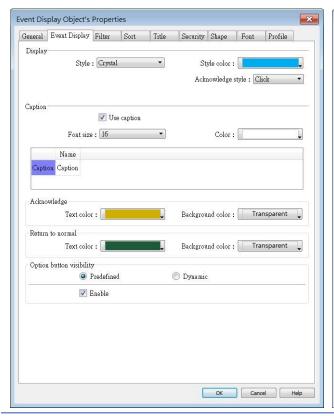




#### **Event Display Tab**

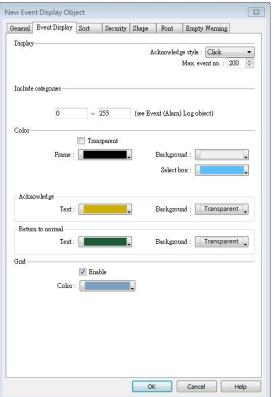
**Setting** 

#### cMT / cMT X Series



**Description** 

eMT, iE, XE, mTV Series



#### Include Events in the selected category will be displayed. The categories are set in Event (Alarm) Log object. categories For example, if the category is set to 2 to 4 here, only events in categories 2, 3, 4 will be displayed. For more information, see "7 Event Log". **Acknowledge** Select [Click] or [Double Click] to acknowledge each single event. When an event occurs the user can tap the event line once or twice style to acknowledge the new event. When acknowledged, the text color of the event will change to the selected color, and the acknowledge value associated with that event will be sent to the register designated in [Acknowledge address]. If the address is set to LW-100, and the acknowledge value is set to 31, when user acknowledges the event, value 31 is written to LW-100. This can be used in conjunction with Indirect Window object so that when an event is acknowledged, the corresponding message window is displayed. Max. event The maximum number of events to be displayed in this Event Display no. (eMT, iE, object. When the number of the displayed events equals to the set

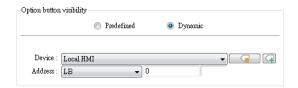
maximum number, the new coming event will overwrite the latest



XE, mTV

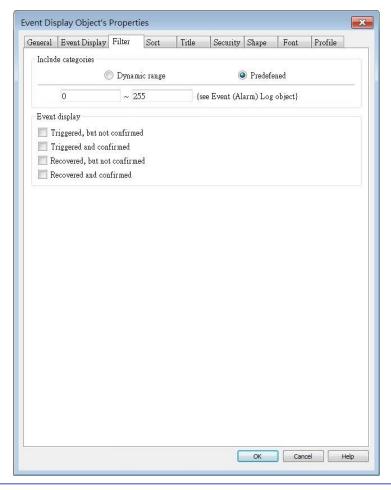
Series)	event.
Color	Different colors indicate different event states, such as acknowledged,
	returns to normal, or selected. The system draws a highlight box
	around the latest selected event.
	Acknowledge  6 13:12:19
	5 13:12:18 Event 2 (when LB10 = ON)
	3 13:12:15 Event 2 (when LB10 = ON)
	2 13:12:14
	Sequence no. Return to normal Select box
	History background (eMT, iE, XE, mTV)
	When using Event Display object and select History mode, the
	background color of the history record can be customized.
	New Event Display Object
	General Event Display   Security   Shape   Font   Empty Warning
	Color —
	Transparent  Frame: ■■■■■■■■■■■■■■■■■■■■■■■■■■■■■■■■■■■■
	History background : ■■■■■■■■■■■■■■■■■■■■■■■■■■■■■■■■■■■
	18:45:43 Event 0
Grid	Displays a grid of rows and columns in the object. The color of the
	grid lines can be selected.
	Auto fit short column (cMT / cMT X Series Default style)
	The column width automatically adjusts to the size of the content.
Caption (cMT	
/ cMT X	Available styles are: Default, Crystal, and Flat.  With [Use caption] enabled, the fort size, color, and name of the
•	With [Use caption] enabled, the font size, color, and name of the caption can be specified for Recipe View object.
Series)	caption can be specified for Necipe view object.
Option button	Show or hide the option button .
visibility (cMT	Predefined
/ cMT X Series)	Select [Enable] to show the option button.
Series)	· · · · · · · · · · · · · · · · · · ·





Designate a bit address to control option button visibility.

#### Filter Tab (cMT / cMT X Series)

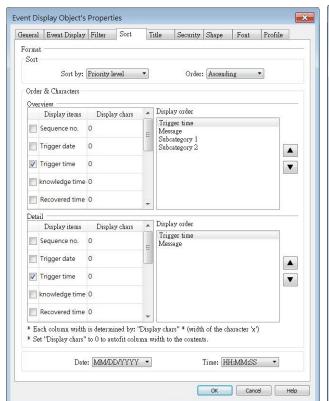


Setting	Description
Include	Events in the selected category will be displayed. The categories are
categories	set in Event (Alarm) Log object. For example: if the category is set
	to 2 to 4 here, only events in categories 2, 3, 4 will be displayed. For
	more information, see "7 Event Log".
	When [Dynamic range] is selected, the object can dynamically filter
	the displayed event categories based on the value in the specified
	register.

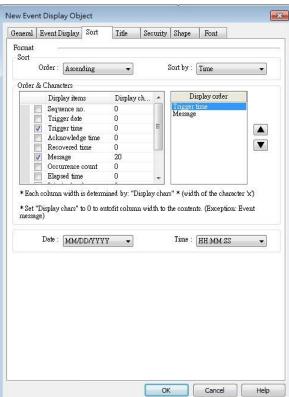


#### **Sort Tab**

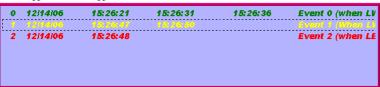
#### cMT, cMT X Series



#### eMT, iE, XE, mTV Series



trigger date trigger time notification time return to normal time



#### Setting

#### **Description**

#### Order

#### Sort by:

#### Ascending – Priority Level (cMT / cMT X Series)

Events on the Overview page are grouped and sorted by priority level, with the group of events with highest priority level placed last in the list (the bottom). On the Detail page, all events in the group are displayed in a time descending order, with the latest event placed first in the list (the top).

#### Descending – Priority Level (cMT / cMT X Series)

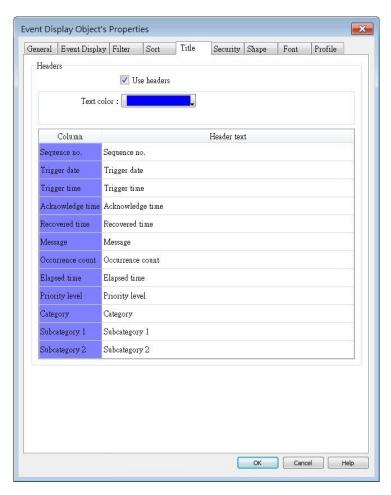
Events on the Overview page are grouped and sorted by priority level, with the group of events with highest priority level placed first in the list (the top). On the Detail page, all events in the group are displayed in a time descending order, with the latest event



	placed first in the list (the top).
	Ascending – Occurrence Count
	eMT, iE, XE, mTV Series: Event with highest occurrence count is
	placed last in the list (the bottom).
	cMT, cMT X Series: On the Overview page, the group of events with
	the highest occurrence count is placed last in the list (the bottom).
	On the Detail page, all events in the group are displayed in a time
	descending order, with the latest event placed first in the list (the
	top).
	Descending – Occurrence Count
	eMT, iE, XE, mTV Series: Event with highest occurrence count is
	placed first in the list (the top).
	cMT, cMT X Series: On the Overview page, the group of events with
	the highest occurrence count is placed first in the list (the top). On
	the Detail page, all events in the group are displayed in a time
	descending order, with the latest event placed first in the list (the
	top).
	Ascending - Time
	Latest event is placed last in the list (the bottom).
	Descending - Time
	Latest event is placed first in the list (the top).
Display order	Select the items to be displayed and use the up and down arrow
	buttons to adjust the display order of the events.
Date	Displays the date tag with each event message. The four formats of
	date tag: MM/DD/YY、DD/MM/YY、DD/MM/YY、YY/MM/DD
Time	Displays the time tag with each event message. The four formats of
	time tag: HH:MM:SS、HH:MM、DD:HH:MM、HH



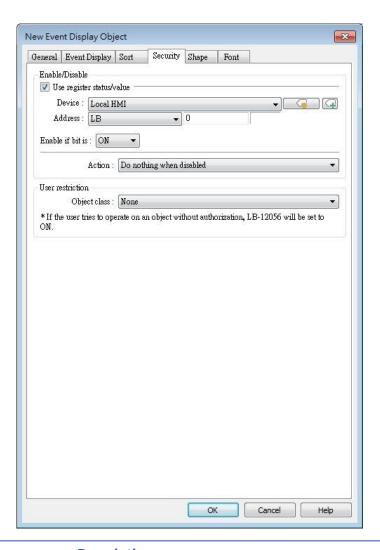
#### **Title Tab**



Title settings are available on cMT / cMT X Series. With [Use headers] selected, the text color and column headers can be configured.



#### **Security Tab**



Setting	Description
Interlock	When [Use interlock function] check box is selected,
	whether the object is operable is determined by the
	state of a designated Bit address. As shown in the above
	settings, if LB-0 is ON, the object is operable.
	Hide when disabled
	When the designated Bit is OFF, the object will be
	hidden.
User	Set the security class of the object to be operated by an
restriction	authorized user.
	Object class
	"None" means any user can operate this object. Only
	account "admin" can operate "Administrator" object
	class.



#### Make invisible while protected

When the user's privilege does not match the object class, the object will be hidden.

When this check box is deselected, the unauthorized user can see the Event Display object, but cannot trigger the object or make any change.

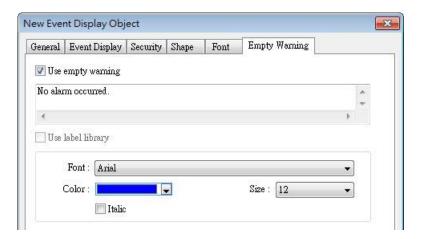
#### **Font Tab**

In Real-time mode: Users may select Italic font and set the font size. The font is displayed according to the setting in Event Log object.

In History mode: Users may select Italic font and set the font size, font and color, or tick the [Font from label library] check box.



#### **Empty Warning**



When [Use empty warning] is enabled, the text displayed when no event has occurred can be specified. This feature is not supported on cMT / cMT X Series models.

Click the icon to download the demo project. Please confirm your internet connection before downloading the demo project.



#### 13.23. Data Transfer

#### 13.23.1. Data Transfer (Per-page)

#### 13.23.1.1. Overview

Data Transfer (Per-page) object can transfer values from the source address to the destination address when the window in which this object is placed opens. The data transfer operation can be activated by manually pressing the object or by detecting the change of state of the designated bit.



When Data Transfer (Per-page) object in Bit-Trigger mode is placed in the common window, it activates data transfer operation once the specified condition is met, regardless of the current base window.

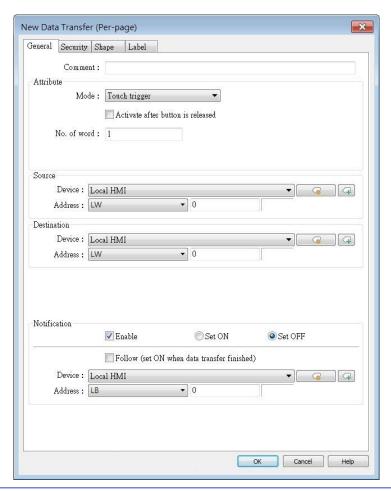
#### 13.23.1.2. Configuration



Click [Object] » [Data Transfer] » [Data Transfer (Per-page)] icon on the toolbar to open the property dialog box. Set up the properties, press OK button, and a new Data Transfer (Per-page) object will be created.



#### **General Tab**



Setting	Description
Source	Data Transfer abiast reads the data from [Course Address]
address	Data Transfer object reads the data from [Source Address].
Destination	Data Transfer shipst united the data to [Destination Address]
address	Data Transfer object writes the data to [Destination Address].
Attribute	No. of word
	Enter the number of words to be transferred. Unit: word.
	Mode
	Touch trigger
	Press the object to activate data transfer operation.
	External trigger
	The data transfer operation is activated when the state of the
	designated bit address changes.
	There is a further selection to make of whether the data transfer
	operation is activated after OFF to ON, ON to OFF transition, or at
	both of the changes of state.



Trigger address	Specify a bit address for [External trigger] mode.
Notification	When enabled, the system will set the designated address ON or OFF when it's ready for data transfer.  Follow
	The notification bit will reset to its original state once the system finishes data transfer.



#### 13.23.2. Data Transfer (Global): Time-based

#### 13.23.2.1. Overview

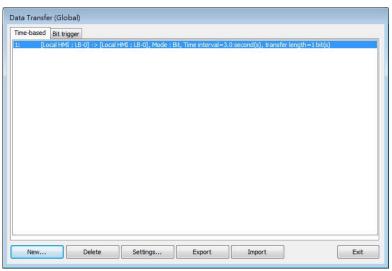
Data Transfer (Global) object in Time-based mode can transfer data from the source address to the destination address based on a time schedule.

#### 13.23.2.2. Configuration

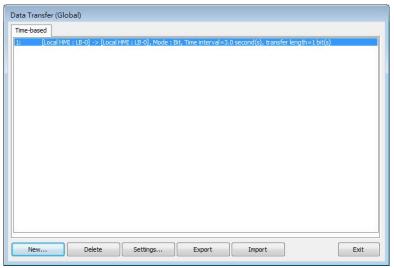


Click [Object] » [Data Transfer] » [Data Transfer (Global)] icon on the toolbar and open the Time-based tab. Click [New] and set up the properties, press OK button, and a new Data Transfer (Global) object will be created. Please note that the data should be imported / exported separately in Time-based mode and Bit Trigger mode of Data Transfer (Global).

#### cMT / cMT X Series



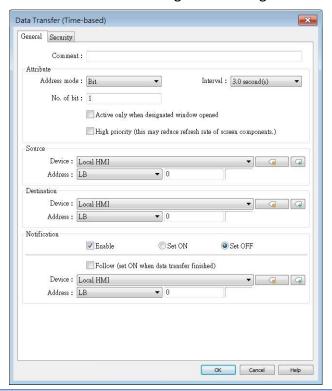
#### eMT, iE, XE, mTV Series





#### **General Tab**

Click the [New] button in the Data Transfer management dialog box.



#### **Setting**

#### Description

#### Attribute

#### Address mode

Select the data type to be transferred from [Bit] or [Word].

#### No. of bit /No. of word

When [Bit] is selected in [Address mode], set the number of bits transferred each time when data transfer is triggered.

When [Word] is selected in [Address mode], set the number of words transferred each time when data transfer is triggered.

#### Interval

Select the time interval of data transfer; for example, when 3 seconds is set, the system will transfer data every 3 seconds. Specifying a shorter time interval or a greater amount of data to transfer may decrease overall system performance; therefore, a longer time interval or a smaller amount of data to transfer is recommended.

When a short interval is inevitable, please at least set an interval longer than the time needed for data transfer operation; for example, when the data transfer operation takes 2 seconds, the interval must be longer than 2 seconds.



	Activate only when designated window opened		
	Data Transfer object transfers data only when the designated		
	window is opened.		
	High priority		
	Assign a higher priority level for this data transfer. Please note that		
	this could result in a reduced screen refresh rate.		
Source	Data Transfer object reads the data from [Source Address].		
address			
Destination	Data Transfer object writes the data to [Destination Address].		
address			
Notification	When enabled, the system will set the designated address ON or		
	OFF when it's ready for data transfer.		
	Follow		
	The notification bit will reset to its original state once the system		
	finishes data transfer.		



# 13.23.3. Data Transfer (Global): Bit Trigger

# 13.23.3.1. Overview

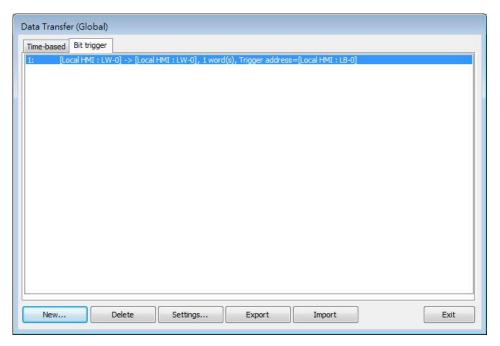
Data Transfer (Global) object in Bit Trigger mode transfers data from the source address to the destination address when HMI detects that the state of the designated bit address changes. This feature is not supported on eMT, iE, XE, mTV models.

# 13.23.3.2. Operation



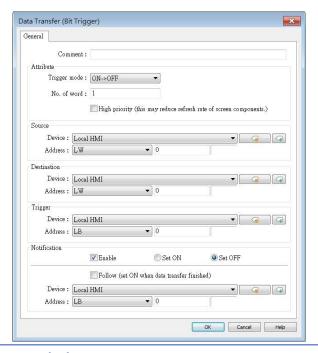
Click [Object] » [Data Transfer] » [Data Transfer (Global)] icon on the toolbar and open the Bit Trigger tab. Click [New] and set up the properties, press OK button, and a new Data Transfer (Global) object will be created. Please note that the data should be imported / exported separately in Time-based mode and Bit Trigger mode of Data Transfer (Global).

# cMT / cMT X Series





#### **General Tab**



Setting	Description	
Attribute	Trigger mode	
	Trigger data transfer when the state of the designated register	
	changes from OFF to ON, ON to OFF, or at both of the changes of	
	state.	
	No. of word	
	Set the number of words transferred each time when data transfer	
	is triggered.	
	High priority	
	Assign a higher priority level for this data transfer. Please note that	
	this could result in a reduced screen refresh rate.	
Source	Data Transfer object reads the data from [Course Address]	
address	Data Transfer object reads the data from [Source Address].	
Destination	Deta Transfer chiest writes the data to [Destination Address]	
address	Data Transfer object writes the data to [Destination Address].	
Trigger	Set the address used to control data transfer and select the trigger	
address	mode.	
Notification	When enabled, the system will set the designated address ON or	
	OFF when it's ready for data transfer.	
	Follow	
	The notification bit will reset to its original state once the system	
	finishes data transfer.	



# 13.24. Backup

#### 13.24.1. Overview

Backup (Trigger-based) object and Backup (Global) object can transmit recipe data (RW, RW\_A), event log, recipe database, sampling data, and operation log to an external device (SD card, USB disk), in a specified time range or format. For example, when the event log is saved in a SD card, a USB disk can be inserted when HMI power is still ON, and use Backup object to copy the data into USB disk from SD card, and then remove USB disk without turning off HMI power. The data saved in USB disk can be used on PC for analyzing. When the system is backing up, the state of system register [LB-9039] is set ON. With [e-Mail] option, information can be sent to configured email contacts.

Backup (Trigger-based) object is triggered by pressing the object on the screen while Backup (Global) object runs in the background regardless of screens being viewed. Backup (Global) object is available only on cMT / cMT X Series models.

## 13.24.2. Configuration





On the toolbar click [Object] » [File Operation] to find [Backup (Trigger-based)] and [Backup (Global) objects.

Open [Backup (Trigger-based)] object property dialog box, set up the properties, press OK button, and a new Backup (Trigger-based) object will be created.

When using a cMT / cMT X Series model, [Backup (Global)] object is available. Open [Backup (Global)] object managing dialog box, click [New] to open the object property dialog box, set up the properties, press OK button, and a new Backup (Global) object will be created.



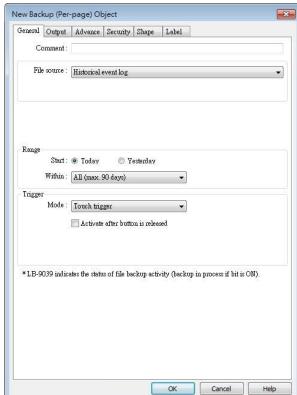
#### **General Tab**

# Backup (Trigger-based)

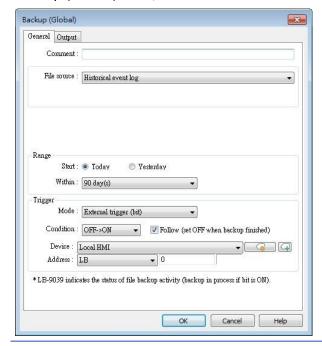
cMT / cMT X Series



eMT, iE, XE, mTV Series



Backup (Global) cMT / cMT X Series



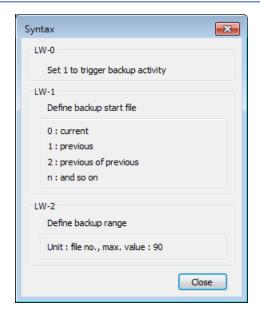
Setting Description

Source [RW], [RW\_A], [Recipe database], [Historical event log],



	[Historical data sampling], [Operation log], [SQL Query]
	Select one from the above for the source. When backing up
	[Historical data sampling], use [Data Sampling object index] to
	select the one to back up.
	Options other than RW, RW_A will be available only when they are
	used in the project file.
Event	This groupbox will be available only when backing up a historical
category	event log in CSV format. Two options can be found in this group
range	box: All and Partial. Selecting partial and entering "3, 5, 8" in the
	field will backup events in categories 3, 5, and 8. Selecting partial
	and entering "3-8" will backup events in categories 3 to 8.
Range	Historical data sampling
	Select a number of files. For example, if [Start] is set to [Current],
	and [Within] is set to [5 file(s)], the latest five files in memory will
	be backed up.
	Historical eventlog
	Select a number of days. For example, if [Start] is set to [Yesterday],
	and [Within] is set to [2 day(s)], the files obtained yesterday and
	the day before yesterday will be backed up. Select [All] to save all
	files, and the maximum is 90 days.
Trigger	Mode
	There are three ways to activate Backup function.
	Touch trigger
	Touch the Backup object to activate backup operation.
	External trigger (bit)
	Register a bit device to trigger the backup operation.
	Select whether the backup operation is activated after Off to ON,
	ON to OFF transition, or at both of the changes of state.
	Click the icon to download the demo project. Please confirm
	your internet connection before downloading the demo project.
	External trigger (word)
	Users can specify the number of days to backup data using [Trigger
	address]. [Trigger address] usage (suppose LW-n is used):
	LW-n: Will start to back up when the value changes from 0 to 1.
	LW-n+1: The start date of backup.
	LW-n+2: The number of days for backup. (The maximum: 90 days).





On cMT-SVR, Backup (Trigger-based) object only supports [Touch trigger] mode but not [External trigger (bit)] and [External trigger (word)] modes.

Click the icon to download the demo project. Please confirm your internet connection before downloading the demo project.

# Trigger address

When the state of the designated register is set ON, the backup operation is activated. When the backup operation is done, the state of the designated register is set OFF.



- All history files should have been saved in memory, either HMI memory, USB disk or SD card. Otherwise, the Backup object will not work.
- The maximum number of days for backup is 90 days.
- When saving files to USB disk or SD card, the capacity of a FAT32 folder depends on the length of the file names. Fewer files can be saved when the file names are longer.

For cMT / cMT X Series, see "7 Event Log" and "8 Data Sampling" that explain the mechanism of synchronizing data to external device.

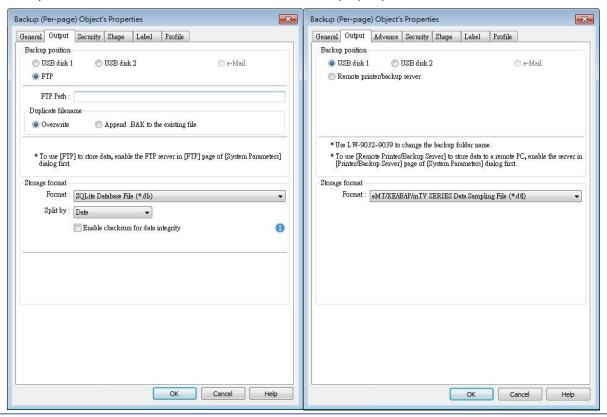
Click the icon to download the demo project. Please confirm your internet connection before downloading the demo project.



#### **Output Tab**

# cMT / cMT X Series

#### eMT, iE, XE, mTV Series



#### **Setting**

# **Description**

# Backup position

Select the destination where the source files will be saved to.

#### SD card / USB disk

The external device connected to HMI.

Remote printer/backup server (eMT, iE, XE, mTV Series)

This option is available when [System Parameters] » [Printer/Backup Server] » [Use Remote Printer/Backup Server] is selected.

Please note that [Operation log] backup can only be saved to Remote printer/backup server. To save into a SD card or USB drive, use the control address of Operation Log object.



# E-mail

To send backup using e-mail, go to [System Parameters] » [e-Mail] tab to configure first, and then open Backup object's e-Mail tab to configure the recipient address, subject, and message.

FTP (cMT, cMT X Series)

To save backup to an FTP server, go to [System Parameters] » [FTP] tab to enable the FTP function first, and then open Backup object's



Output tab to set the FTP path and the way to handle duplicate filenames.

#### Save format

Select the desired format to back up the file.

#### eMT, iE, XE, mTV Series:

- HMI Event Log File (.evt) / HMI Data Log File (.dtl)
- Comma Separated Values (.csv)

The [Event] column is included in the backup file to indicate the type of the event.

	Α	В	С	D	Е
1	Event	Category	Date	Time	Message
3	0	1	2013/7/4	16:12:11	Event A
3	2	1	2013/7/4	16:12:12	Event A
4	0	0	2013/7/4	16:12:33	Event B
5	2	0	2013/7/4	16:12:36	Event B
6	0	0	2013/7/4	16:12:37	Event B
7	1	0	2013/7/4	16:12:37	Event B
8	2	0	2013/7/4	16:12:39	Event B
9	0	0	2013/7/4	16:12:40	Event B

0 = Event is triggered

1 = Event is acknowledged

2 = Event returns to normal

EasyConverter can be used to easily convert HMI Event Log File (.evt) and HMI Data Log File (.dtl) to .xls or .csv format.

SQLite Database File (.db)

#### cMT / cMT X Series:

- SQLite Database File (.db) (Only for backup to e-mail)
- Comma Separated Values (.csv)

## Split by

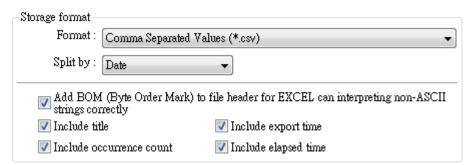
No split	Backup all historical data to the same file.	
Date	Files are separated according to the date of	
	historical data.	
	When [Customized file handling] is used in	
	Data Sampling, the backup files are	
	separated in the same way they are by the	
	rules of customized file handing.	
Number of rows	Files are separated according to the number	
	of rows set.	

# Add BOM (Byte Order Mark) to file header for EXCEL can interpreting non-ASCII strings correctly.

To back up history logs in .csv format, open the csv file in EXCEL. The BOM (Byte Order Mark) can be added to the file header so that the .csv file containing non-ASCII strings can directly be opened in EXCEL. The title, export time, occurrence count, and elapsed time can



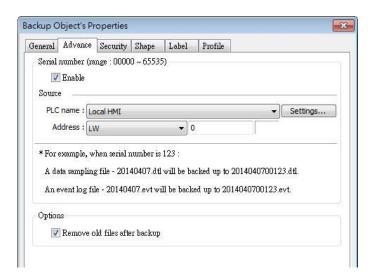
be included or omitted in the backed-up .csv file.



# **Enable checksum for data integrity**

This option is provided for using Backup object to generate a backup file with checksum. EasyConverter can then be used to examine data integrity.

# Advance Tab (eMT, iE, XE, mTV)



# **Setting**

# **Description**

#### Serial number

If enabled, when backing up history files, a user-defined, 5-digit serial number can be appended to the end of the file name of the history data backup.

The serial number is determined by the value in the designated source address. After backup, the value of this LW address will automatically increment by 1.

The range of the serial number is  $0^{\sim}65535$ 

For example, if the serial number is 123, the appended 5 digits will be 00123.

A data sampling file -20140407.dtl will be backed up as 2014040700123.dtl.

An event log file -20140407.evt will be backed up as 2014040700123.evt.



Options	Remove old files after backup
	If selected, the old history files will be removed after backup.



cMT / cMT X Series does not support Advance settings.

# e-Mail Tab



Setting	Description
Add .txt	
extension to	If selected, when sending backup data as an email attachment, the
the filename	filename extension .txt will be added to the file name. This
to skip the	prevents the mail server or anti-virus software from blocking
anti-virus	emails.
detection	
Recipients,	
Subject,	Back up the email address of the recipients, the subject of the email, and the message content.
Message	eman, and the message content.



# 13.25. Media Player

#### 13.25.1. Overview

Media Player object plays video files on HMI. It can, for example, be useful in providing better instructions onsite to facilitate maintenance.

This object does not work remotely on cMT Viewer.

# 13.25.2. Configuration

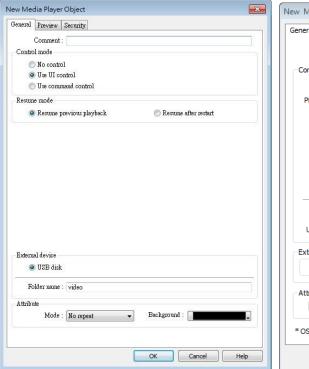


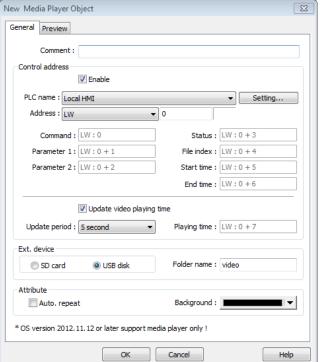
Click [Object] » [Media Player] icon on the toolbar to open a Media Player object property dialog box. Set up the properties, press OK button, and a new Media Player object will be created.

#### **General Tab**

cMT / cMT X (excluding cMT-SVR)







Setting	Description	
Control mode	No control: Disable manual control by user. Video playback starts	
	as soon as the window opens.	



	Use UI control: Use built-in user interface to control media playback.  Use command control: Use control addresses to control media		
Resume	playback.  Defines where to resume video playback when changing back to a		
	window with media player. Options include <b>Resume previous</b>		
mode	playback and Resume after restart.		
Control	Selected		
address	<ul><li>Designate a word register to control the object operations.</li><li>Not selected</li></ul>		
	No manual control. Video will be played automatically when the		
	designated window opens.		
	Command (control address + 0)		
	Enter a value in the Command register to designate which action is executed.		
	Parameter 1 (control address + 1)		
	Enter a value in Parameter 1 associated with each command action		
	Parameter 2 (control address + 2)		
	Enter a value in Parameter 2 associated with each command action		
	Status (control address + 3)		
	Indicates the status or errors.		
	File index (control address + 4)		
	The file number in the designated folder. It is recommended to file		
	the video name with a number.		
	Start time (control address + 5)		
	The start time of the video (second). 0, normally.		
	End time (control address + 6)		
	The end time of the video (second). (The time length of the video)		
	Update video playing time		
	If enabled, the elapsed playing time of video will be written into		
	[Playing time] register at a rate set by [Update period] in seconds.		
	Update period		
	Update period of [Playing time], range from 1 to 60 (second).		
	Playing time (control address + 7)		
	The elapsed playing time of video (Second). Normally between		
	start time and end time.		
Ext. device	Play video files in SD card / USB disk.		
	Folder name		
	The folder name of video files stored in SD card or USB disk. Files		
	must be stored in root directory. Subdirectories won't be accepted.		
	(For example, "example\ex" is an invalid directory.)		
	[Folder name] cannot be empty, must be alpha-numeric, and all in		



	ASCII character.
Attribute	Auto. repeat
	When finish playing all the video files, replay from the first file.
	Ex: Video 1 > Video 2 > Video 1 > Video 2
	Background
	The background color of the object.



The data format for control address is 16-bit Unsigned or 16-bit Signed. If using 32-bit Unsigned or 32-bit Signed, only the previous 16 bits will be effective.

#### **Control command**

The following are the settings of different commands.

# Play index file

[Command] = 1

[Parameter 1] = file index

[Parameter 2] = ignore (set 0)



- Files are stored with file names in ascending order.
- If the file cannot be found, [Status] bit 8 is set ON.
- Please stop the playing video before switching to another.

# Play previous file

[Command] = 2

[Parameter 1] = ignore (set 0)

[Parameter 2] = ignore (set 0)



- If [File index] is zero, the same file is replayed.
- If the file cannot be found, [Status] bit 8 is set ON.

# Play next file

[Command] = 3

[Parameter 1] = ignore (set 0)

[Parameter 2] = ignore (set 0)

- If there are no more files, the index 0 file is played.
- If the file cannot be found, [Status] bit 8 is set ON.
- Pause / Play Switch



```
[Command] = 4

[Parameter 1] = ignore (set 0)

[Parameter 2] = ignore (set 0)
```

# Stop playing and close file

```
[Command] = 5
[Parameter 1] = ignore (set 0)
[Parameter 2] = ignore (set 0)
```

# Start playing from the designated time

```
[Command] = 6
[Parameter 1] = target time (second)
[Parameter 2] = ignore (set 0)
```



Parameter 1 (target time) must be less than the ending of time or it plays the last second.

## Forward

```
[Command] = 7
[Parameter 1] = target time (second)
[Parameter 2] = ignore (set 0)
```



- Going forward to the designated second in [Parameter 1]. If the video is paused, the forwarding action will be started by playing.
- When the designed time is later than the end time, it plays the last second.

#### Backward

```
[Command] = 8
[Parameter 1] = target time (second)
[Parameter 2] = ignore (set 0)
```



- Going Backward to the designated second in [Parameter 1], if the video is paused, the backward action will be started by playing.
- When the designed time is earlier than the beginning time, it plays from beginning.

# Adjust volume

```
[Command] = 9

[Parameter 1] = volume (0 \sim 128)
```



[Parameter 2] = ignore (set 0)



- Default volume is 128.
- Set video display size

[Command] = 10

[Parameter 1] = display size  $(0 \sim 16)$ 

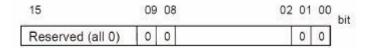
[Parameter 2] = ignore (set 0)



- [Parameter 1 = 0] : Fit video image to object size.
- Parameter  $1 = 1 \sim 16$ ]: Magnification from 25%  $\sim 400\%$  in 25% increments where 1 = 25%, 2 = 50%, 3 = 75% and so on.

# Status (control address + 3)

When playing a video the system sets [File Open (bit00)] and [File Playing (bit01)] to ON. If the file cannot be found, or an invalid command is entered, the Command Error bit 08 is set ON. If the file format is not supported, or a disk I/O error occurs, during playback, the File Error bit 09 is set ON.



00: File Opened / Closed (0 = closed, 1 = opened)

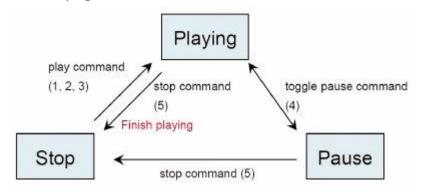
01: File Playing (0 = not playing, 1 = playing)

08: Command Error (0 = accepted, 1 = incorrect)

09: File Error (0 = accepted, 1 = incorrect)



■ The figure shows the status value associated with each state:



[Command], [Parameter 1], and [Parameter 2] are write addresses. All others are read



only.

#### **Preview Tab**

Users can test whether the video format is supported by using the preview function.



Setting	Description		
Forward << /			
Backward >>	Go forward or backward of the video. (in minutes)		
Play / Pause	Select to start playing video or pausing.		
Stop	Stop playing and close the video file. To test another video, please		
	stop playing the current video first.		
Load	Select a video to preview.		



- Only one video file can be played at one time.
- If [control address] is not enabled and [Auto. repeat] is not selected, after finish playing the first file, the system will stop playing and close the video file.
- If [control address] is not enabled, the system will find the first file in the designated folder and start to play (in ascending order of the file name).
- If the file can be previewed, the format is supported. If the video image quality is poor, please adjust the resolution.
- The supported formats: mpeg4, xvid, flv...etc.
- The recommended frame rate for videos is 30fps.

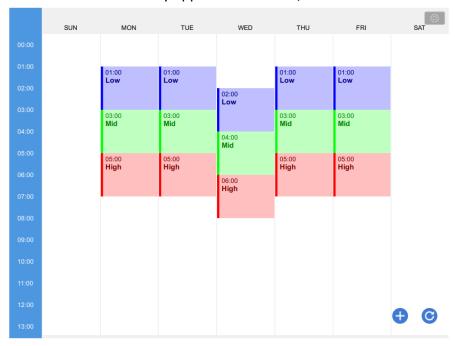
Click the icon to download the demo project. Please confirm your internet connection before downloading the demo project.



# 13.26. BACnet Schedule

#### 13.26.1. Overview

BACnet Schedule helps visualize and access schedule data (Schedule) in BACnet IP controller with a graphical UI. This feature is only applicable for cMT / cMT X Series HMI.



# 13.26.2. Configuration

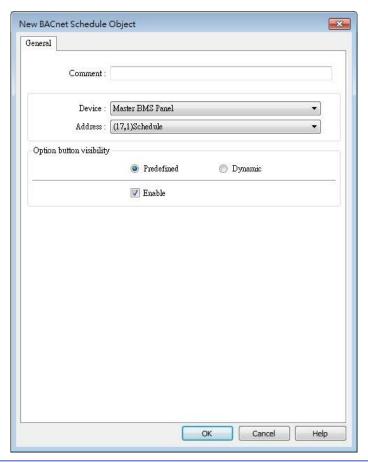


Add BACnet/IP driver into the device list in System Parameter Settings and check whether a Scudule is contained in the scanned BACnet/IP device or the imported tag file.

Click [Object] » [Time Related] »[BACnet Schedule] icon on the toolbar to open the BACnet Schedule property dialog box. Configure the parameters and then click OK, a BACnet Schedule object is created.



# **General Tab**

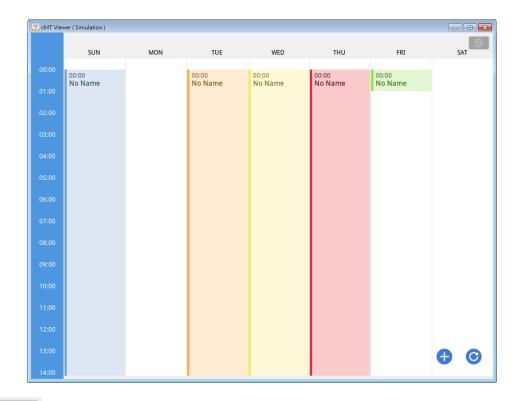


Setting	Description	
Device	Select the BACnet/IP device to be read.	
Address	Select the address tag of the Schedule to be read.	
Option button visibility (cMT	Show or hide the option button .	
/ cMT X	Predefined	
Series)	Select [Enable] to show the option button.	
,	Dynamic	
	Option button visibility  Predefined  Device: Local HMI  Address: LB  Designate a bit address to control option button visibility.	

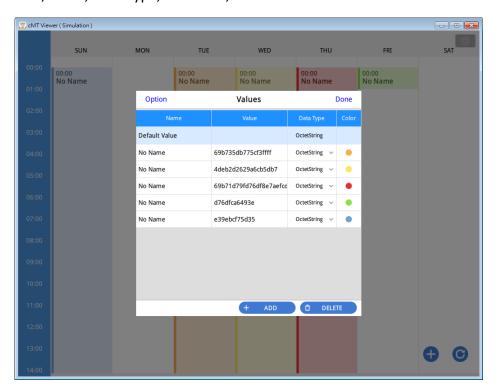
# Example 1

After downloading the project to HMI, the HMI will automatically read the schedule settings in the BACnet IP device as shown below.



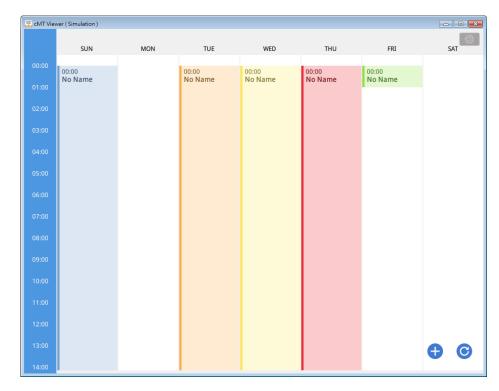


Click and then select Value Editor to configure the Values table containing these columns: Name, Value, Data Type, and Color, as shown below.



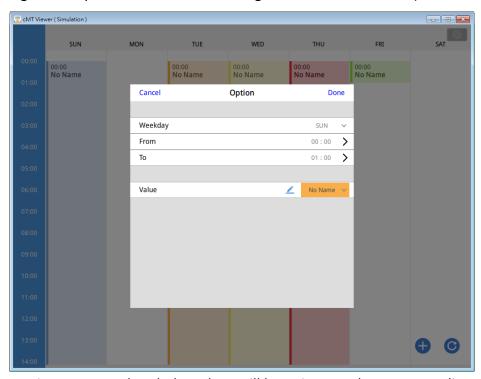
Click to add a schedule setting. Click to refresh schedule data by reading from the BACnet device.





As shown in the following screenshot, in a schedule settings window, the Weekday, start time (From), end time (To), and Value should be configured. Value can be selected from the value

table. (Clicking open Value Editor for editing the value table as well.)



After the time settings are completed, the values will be written to the corresponding schedule tags in BACnet device.



# 13.27. PLC Control

#### 13.27.1. Overview

PLC Control object can execute commands when it is triggered.

# 13.27.2. Configuration

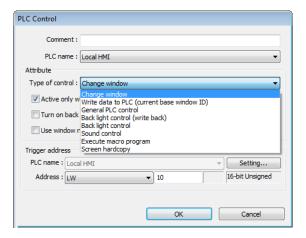


Click [Object] » [PLC Control] icon on the toolbar to open the PLC Control Object management dialog box. To add a PLC Control object, click [New], set up the properties, press OK button and a new PLC Control object will be created.

```
| 1: [Local HMI: LB-8999] => Sound control: OFF->ON, PLC no response (67 k)
| 2: [Local HMI: LW-100] => Change window (clear data after window changed)
| 3: [Local HMI: LW-110] => Seneral PLC control
| 4: [Local HMI: LW-120] => General PLC control
| 5: [Local HMI: LW-120] => Change window (clear data after window changed)
| 6: [Local HMI: LB-10] => Execute macro program: [ID:000] macro 0 (OFF->ON) (active on Window 4)

| New... | Delete | Settings... | Exit
```

Click [New] and the following dialog box appears. See "13.27.2.1 Type of Control".





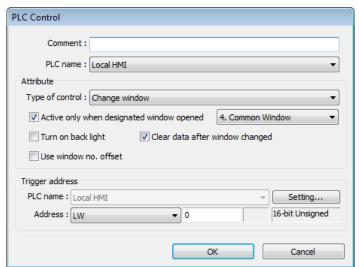
- The [General PLC Control] option is not available for cMT / cMT X Series.
- Triggering [Screen hardcopy] in cMT Viewer will result in files being saved into the USB disk / SD card connected to the cMT / cMT X HMI. Likewise, the [Back light control] option in cMT Viewer will control the backlight of the HMI itself.



Selecting [Change window] or [General PLC Control] as [Type of control] will require more than one trigger word (consecutive). Using a user-defined tag PLC will require declaring an array datatype.

# **13.27.2.1.** Type of Control

Change window



Setting	Description	
Active only when		
designated	Allow this operation only if a particular screen is displayed.	
window opened		
Turn on back light	The backlight is turned ON when the window is changed.	
Clear data after	Reset the value at trigger address to zero when the window	
window changed	object is changed. If [Use window no. offset] is selected, this	
	option will only show when a negative offset is used.	
Use window no.	Select the check box and select a window offset, the new	
offset	window no. to change to will be the value in [Trigger address]	
	plus the offset. For example, if [Trigger address] is LW-0 and	
	offset is set to -10. When the value in LW-0 is 25, the system	
	will change to window no. 15 (25-10=15). The range of the	
	offset is -1024 to 1024.	



If [LB-9017] is set ON, the write-back function will be disabled, the new window number is not written back into a designated address.

Place a valid window number in the designated trigger address to change the base screen to the new window number. The new window number is written back into the designated



address.

For example, if current window is window no. 10, and [Trigger address] is set to LW-0, When LW-0 is changed to 11, the system will change the current window to window no. 11, and then write 11 to LW-1.

Click the icon to watch the demonstration film. Please confirm your internet connection before playing the film.

When the window is changed, the new window number is written back into the address that is calculated by [Trigger address] and the data format, as shown in following table.

Data Format	Trigger address	Write address
16-bit BCD	Address	Address + 1
32-bit BCD	Address	Address + 2
16-bit Unsigned	Address	Address + 1
16-bit Signed	Address	Address + 1
32-bit Unsigned	Address	Address + 2
32-bit Signed	Address	Address + 2
64-bit Unsigned	Address	Address + 4
64-bit Signed	Address	Address + 4

Click the icon to download the demo project. Please confirm your internet connection before downloading the demo project.

# Write data to PLC (current base window)

Each time the base window is changed, the new window number will be written into the [Trigger address]. If [Use window no. offset] is selected, the window number of the base window plus the window number offset will be written into the [Trigger address].

# General PLC Control (eMT, iE, XE, mTV)

Transfer word data blocks from PLC to HMI, and vise-versa, and the transfer direction is controlled by the value in the [Trigger address].

Value in	Action
[Trigger address]	
1	Transfer data from PLC register → HMI RW register
2	Transfer data from PLC register → HMI LW register
3	Transfer data from HMI RW register → PLC register
4	Transfer data from HMI LW register → PLC register



Four consecutive word registers are used as described in the following table:

Address	Purpose	Description
[Trigger	Determine the	The valid values are listed in the
address]	direction of data	above table. When a new control
	transfer	code is written into the register,
		HMI will start to transfer. After data
		transfer is finished, the value will
		be set to 0.
[Trigger	The size of data	The unit is word.
address] +1	to transfer.	
[Trigger	Offset to the	Assume the value is "n", where n is
address] +2	start address of	an arbitrary number, the start
	PLC register	address of PLC register is [Trigger
		address $+ 4 + n$ ].
		Take an OMRON PLC as an
		example:
		If [Trigger address] uses DM-100,
		[Trigger address + 2] will be
		DM-102. If the value in DM-102 is
		5, the start address of data source
		would be DM-109 (100 + 4 + 5 =
		109).
[Trigger	Offset to the	Take OMRON PLC as an example:
address] +3	start address of	If set [Trigger address] to DM-100,
	LW or RW	[Trigger address + 3] will be
	memory in HMI	DM-103. If the value in DM-103 is
		100, the start address of memory
		in HMI is RW-100 or LW-100.

# **Example 1**

To use PLC Control object to transfer 16 words data in OMRON PLC, starting from address DM-100, to the HMI address, starting from RW-200. The setting is shown below:

- 1. Firstly, create a PLC Control object, set [Type of control] to [General PLC control], and set [Trigger address] to DM-10, that is, to use the four sequential registers start from DM-10 to control data transfer.
- Confirm the data size and the offset addresses.Set DM-11 to 16, since the number of words to transfer is 16 words.Set DM-12 to 86, which indicates the address of data source is DM-100 (100=10+4+86).



Set DM-13 to 200, which indicates the destination address is RW-200.

3. Set DM-10 according to the direction of data transfer.
If set DM-10 to 1, the data will be transferred from PLC to HMI RW register,
If set DM-10 to 3, the data will be transferred from HMI RW register to PLC.

# Back light control (write back)

When [Trigger address] is turned ON, HMI backlight will be turned ON/OFF and [Trigger address] will be turned OFF. Any touch on the screen will turn the backlight on.

# Back light control

When [Trigger address] is turned ON, HMI backlight will turn ON/OFF and the state of [Trigger address] will not be changed.

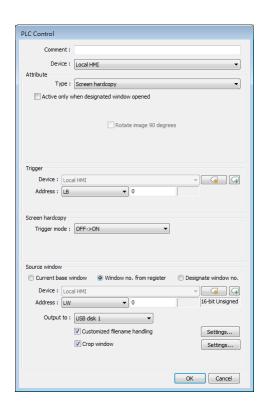
# Sound control

When the state of the designated [Trigger address] changes, the HMI will play the sound selected from the sound library. There is a further selection determines whether the sound is played after Off to ON, ON to OFF transition, or at both of the changes of state.

# Execute macro program

Select a pre-defined Macro from the drop-down list. When the state of the designated [Trigger address] changes, the selected Macro is executed. There is a further selection determines whether the Macro is executed after Off to ON, ON to OFF transition, or at both of the changes of state. If select [Always active when ON], the macro will be executed repeatedly. (The shortest time interval between runs is 0.5 second.)

# Screen hardcopy





When the state of the designated [Trigger address] changes, print the selected screen. If select [SD card] or [USB disk] as [Printer], a "hardcopy" folder will be generated in the selected external device for saving the printed screen in JPG format. The name of the JPG files starts from yyyymmdd\_0000.

To print the screen using a printer, go to System Parameter Settings » Model tab and set the printer.

To print the screen using a remote printer, go to System Parameter Settings » Printer/Backup Server tab and configure the parameters.

There are three options to specify the source window for hardcopy:

#### **Current base window**

Print the base window currently opened.

# Window no. from register

Print the window designated by the value in a designated word address.

# Designate window no.

Directly select a window to be printed.

# **Customized File Handling**

This feature can be used to customize naming of the folders and the JPG files.

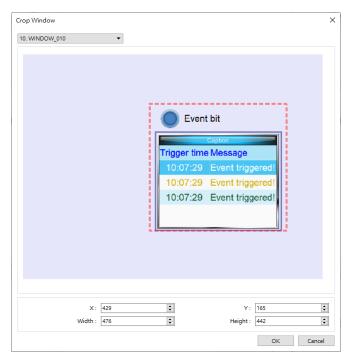
	-
Setting	Description
Folder name	The folder name can be an alphanumeric name, and
	certain half-width symbols are allowed:
	!@#\$%^&()_+{}`-=;',.
	The folder name can also be specified by a naming syntax.
	Dynamic format
	The folder names can be set by a designated word
	address, or by a naming syntax indicating the current
	system time. The syntax can be specified by selecting
	time buttons or entering the syntax in Format field. The
	length limit is from 1 to 25.
	Note: Up to 10 layers of folders can be created. The
	exceeding layers will be ignored.
File name	The way to specify a file name is similar to specifying a
	folder name.
	Note: If the file name already exists, the system will add
	"_0001" to the file name as a serial number. The numbers
	of the later files add up until "_9999". The files after
	"_9999" will be ignored.
	For example, if the three file names exist: "A.jpg",
	"A_0001.jpg", "A_0003.jpg". When trigger screen



hardcopy with the same file name, the coming files will be named in this order: "A\_0002.jpg", "A\_0004.jpg", "A\_0005.jpg", and so on.

# **Crop window**

With this option selected, taking a cropped screenshot is possible.





- A background printing procedure is performed when the printed window is not the current base window.
- If the hard-copied window is a background window, its [Direct Window] and [Indirect Window] objects will not be printed.
- When using a dynamic format name, the system will use a "\_" sign as a substitute for invalid symbols.
- When using a dynamic format name, if screen hardcopy is triggered without specifying the format first, the system will save the file in the default directory, which is: hardcopy\yymmdd\_0000.JPG
- On cMT / cMT X models, a triggered bit address is reset to its original state automatically, whereas on eMT/iP/iE/mTV models, the state of a triggered bit address is retained.
- Click the icon to download the demo project. Please confirm your internet connection before downloading the demo project.



# 13.28. Scheduler

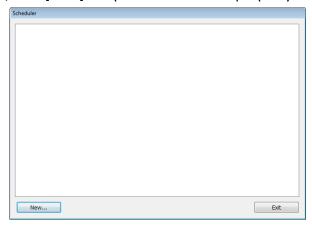
#### 13.28.1. Overview

Scheduler object turns bits ON/OFF, or writes values to word registers at designated start times. It works on a weekly basis.

# 13.28.2. Configuration



Click [Object] » [Time-related] » [Scheduler] icon on the toolbar to open the Scheduler management dialog box, click [New] to open the Scheduler property setting dialog box.

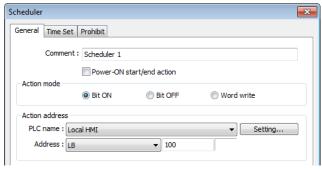


The following two demonstrations explain the usage of Scheduler.

# **Example 1**

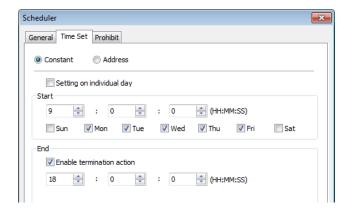
A motor is scheduled to power - ON at 9:00 and power - OFF at 18:00, Monday to Friday. We are using LB-100 to control the motor state. LB-100 will be set ON at 9:00 and OFF at 18:00.

- Click the Scheduler icon on the toolbar to open the Scheduler management dialog box, click [New].
- 2. In [General] tab, select [Bit ON] in [Action mode] and set [Action address] to LB-100.



3. In [Time Set] tab, select [Constant].





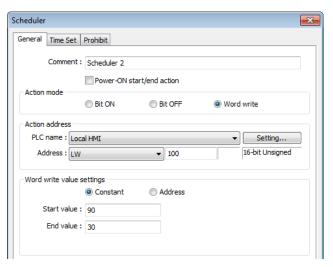
**4.** Enter [Start] time as 9:00:00 and select Monday to Friday. Do not select [Setting on individual day].

- 5. Enter [End] time as 18:00:00 and select [Enable termination action] check box.
- Click [OK], a new Scheduler object will be created on the [Scheduler] list.

# **Example 2**

A thermal heater is scheduled to heat up to 90°C at 08:00 and cool down to 30°C at 17:00, Monday to Friday. LW-100 is used to store the set point value.

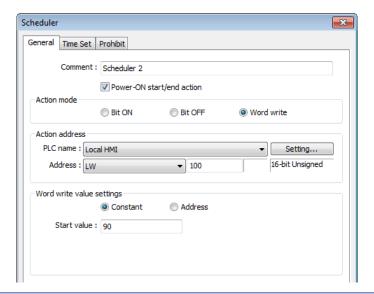
- Click the Scheduler icon on the toolbar to open the Scheduler management dialog box, click [New].
- 2. In [General] tab, select [Word write] in [Action mode] and set [Action address] to LW-100.
- 3. Select [Constant] for [Word write value settings] and enter 90 in [Start value].



- 4. In [Time set] tab select [Constant].
- 5. Enter [Start] time as 8:00:00 and select Monday to Friday. Do not select [Setting on individual day].
- 6. Enter [End] time as 17:00:00 and select [Enable termination action] check box.
- 7. Return to [General] tab and enter 30 in [End value].
- 8. Click [OK], a new schedule object will be created on the [Scheduler] list.



#### **General Tab**



# Setting

# Power ON start/end action

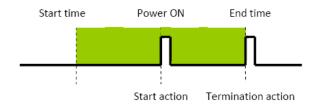
# **Description**

Execute the defined action when the HMI is powered ON.

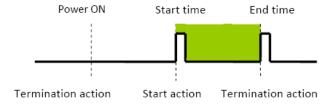
#### Enabled

When HMI is powered ON within the scheduled time range, the start action will be performed automatically. When HMI is powered ON outside the scheduled time range, the termination action will be executed.

#### Inside scheduled range



# Outside scheduled range



#### Disabled

When the HMI is powered ON at a time later than the start time, the start action will not be performed, but the termination action will be performed. When the termination action is not defined, the scheduled range is not recognized and no action is performed.



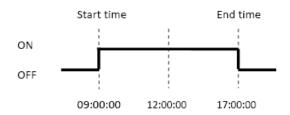
# **Action mode**

Choose the action to do at the given time.

#### Bit ON

At the start time, set the designated bit ON. At the end time, set the designated bit OFF.

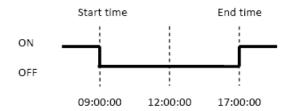
Example: Start time: 09:00:00 End time: 17:00:00



#### **Bit OFF**

At the start time, set the designated bit OFF. At the end time, set the designated bit ON.

Example: Start time: 09:00:00 End time: 17:00:00



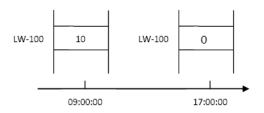
#### **Word write**

The [Write start value] entered here is transferred to the designated [Action address] word register at the start time. At end time, the [Write end value] entered here is written to the [Action address]. The valued can be entered manually or be set by using [Address] mode. In [Address] mode, the value in the specified address is the start value where the value in [Address + 1] is the end value.

Example: Device address: LW-100 Start time: 09:00:00 End time: 17:00:00 Write start value: 10 Write end value: 0

Use register: If control address is LW-n, then enter 10 in LW-n and  $\,$ 

enter 0 in LW-(n+1).



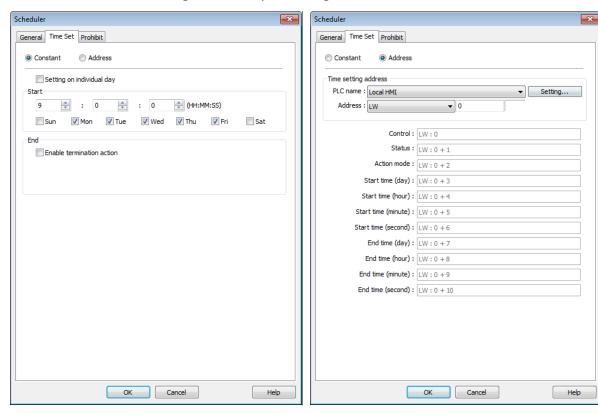




Only is an [End time] is set in the [Time set] tab will the [Write end value] box appear.

#### **Time Set**

Specify start time and end time. [Constant] allows specifying a date or period and time. [Address] allows controlling the time by the designated address.

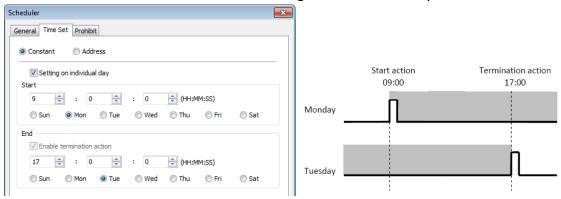


Constant

# Setting on individual day

If [Setting on individual day] is selected

The same start time and end time can be assigned to different days of the week.



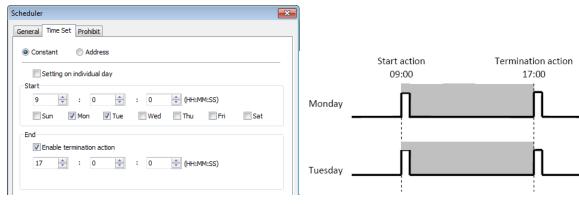




- Start and end time must be entered.
- Start and end time must be on a different time, or same time but different day.

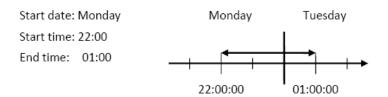
If [Setting on individual day] is not selected

Start time and end time entered must start and end within 24-hours.





- Start time and end time must be on a different time, different day.
- If an end time is earlier than a start time, the end action will occur in the next day.



#### Address

The scheduler object retrieves the start/end time and day of week information from word registers, enabling all parameters to be set and changed under PLC or user control.

Designated as the top address in a block of 11 sequential registers which are used to store time setting data.

The format of the 11 word registers should normally be 16-unsigned integer. If a 32-bit word address is chosen, only bits 0-15 are effective, and bits 16-31 should be written as zero.

The following describes each register.

# Control (Time setting address + 0)

When [Control] bit is ON, the HMI will read and update [Action mode], [Start time], and [End time] values.



Bit 0: no action 1: read times/action mode





HMI will not regularly read the data from [Action mode] (address + 2) to [End time]
 (address + 10). Please turn [Control] ON when the settings are changed.

# Status (Time setting address + 1)

When the read operation is completed, Bit00 of this register turns ON. If time data read is out of range or incorrect in any way Bit01 turns ON.

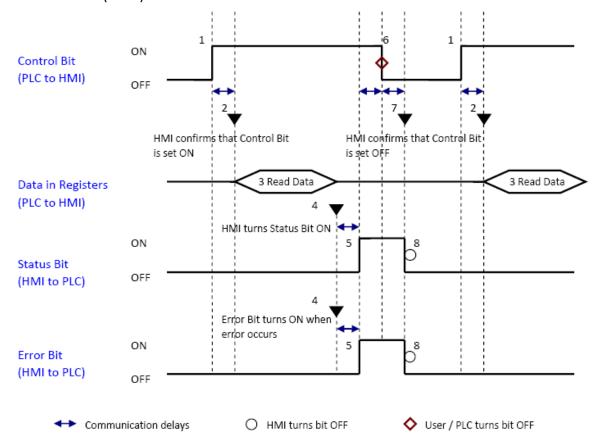
15	02	01	00	Bit
Reserved (0 fixed)		0	0	

Bit 00: Status bit: Read operation completed. (0: reading or reading not started. 1: reading completed.)

Bit 01: Error bit: Start or end time format incorrect. (0: corrected 1: error)



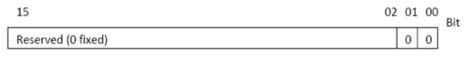
After the scheduler reads the data and the status is turned ON (The value in [Address + 1] = 01), the control bit must be turned OFF (address = 0). The status bit and error bit will be turned OFF (1→0) at the same time.





# Action mode (Time setting address + 2)

Enable/disable [Enable termination action] and [Setting on individual day]. Whatever the [Enable termination action] bit is, all the time data, from [Control] to [End time (second)], will be read.



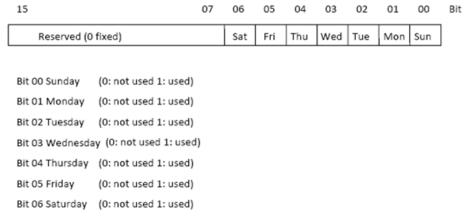
Bit 00 Enable termination action (0: Disabled 1: Enabled)
Bit 01 Setting on individual day (0: Disabled 1: Enabled)



- If [Enable termination action] is OFF, all 11 registers are still read but end time is ignored.
- If [Setting on individual day] is ON, make sure that all start end times are entered. If more than one start / end day bit is ON, and error will occur.

# Start/End Day (Start Day: Time setting address + 3, End Day: Time setting address + 7)

Designates which day of week is used to trigger the start or end action.



# Start/End Time (Start Time: Time setting address + 4 to + 6, End Time: Time setting address + 8 to + 10)

Hour: 0 – 23 Minute: 0 – 59 Second: 0 - 59 Values outside these ranges will cause error.



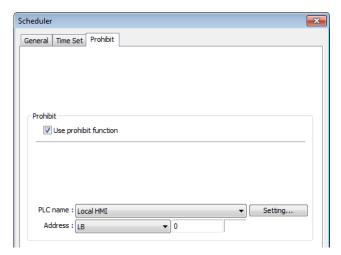
- 16-bit unsigned integer format must be used; BCD format is not supported here.
- In [Address] mode, [Control] bit should be set after HMI reboots to update scheduler time.
- When using RW address, [Control] bit should be set after HMI reboots to update scheduler time. Placing a Set Bit object with [Set ON when window opens] selected in the common window is recommended, this can retain last settings after HMI reboots.



End time depends on [Action mode] (address + 2). [Enable termination action] (Bit 00) and [Setting individual day] (Bit 01) are related:

Setting individual day	Enabled	Disabled	
Enable termination action	Enabled	Enabled	Disabled

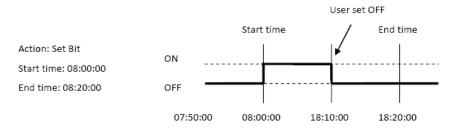
#### **Prohibit tab**



Before the scheduled action is performed, the HMI will read the specified bit state. If it is ON, the scheduled start/end action will be skipped. Otherwise, it will be performed normally.



- The maximum number of Scheduler objects in a project is 64.
- A time schedule applies one action only when the start time is reached.



- [Write start/end value] and [Prohibit] bit is read only once before start action. After that, even to change the state of [Prohibit] bit or [Write start/end value], the end action and the value written will not be affected. Also, to read data of [Write start/end value] and [Prohibit] bit, there is a delay of start action due to the communication.
- Each time RTC data is changed, scheduler list entries that possess both start and end times will be checked for in-range or out-range conditions. For in-range, the start action will occur. If the end action is not set, the new range is not recognized, the action will not occur.
- If several Scheduler objects are set to the same start time or end time, the action is performed in ascending order of the schedule number.



In [Time Set] » [Address] mode, the system will read [Control] word regularly. The length of the period depends on the system.

- In [Time Set] » [Address] mode, when start time and end time is out-range, error occurs in the set action time. (Note: BCD is not an acceptable format)
- In [Time Set] » [Address] mode, the action will not start up until the first time the time data is successfully updated.

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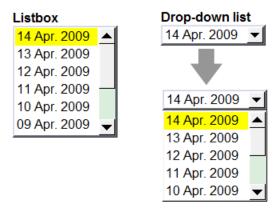


# 13.29. Option List

#### 13.29.1. Overview

Option List object displays a list of items that the user can view and select. Once the user selects an item, the corresponding data will be written to a word register.

There are two forms of this object – [List box] and [Drop-down list]. The [List box] lists all items and highlights the selected one. The [Drop-down list] normally displays only the selected item. Once the object is pressed, the system will display a list (which is similar to list box) as shown in the following figure.



#### 13.29.2. Configuration

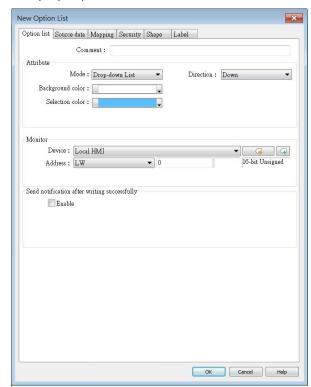


Click [Object] » [Option List] icon on the toolbar to open an Option List object property dialog box. Set up the properties, press OK button, and a new Option List object will be created.

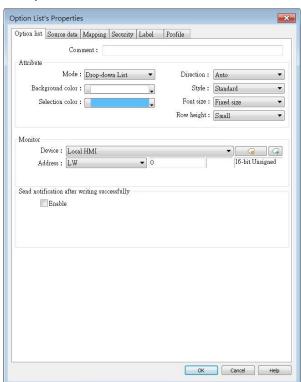


#### **Option List Tab**

#### eMT, iE, XE, mTV Series



#### cMT / cMT X Series



#### Setting

#### Description

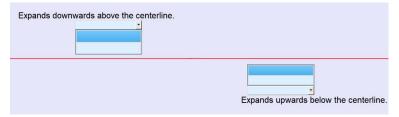
#### **Attribute**

**Mode:** The list style, either [List box] or [Drop-down list].

Background color: Set the background color.

**Selection color:** Set the background color for the selected item.

**Direction:** With the [Auto] option selected, the Option List expands based on its vertical alignment with the window's centerline as the reference. If the Option List is positioned above the centerline, its menu content expands downwards; conversely, if it's positioned below the centerline, the menu content expands upwards.



With the [Down] option selected, the Option List will consistently expand downwards. Conversely, with the [Up] option selected, the Option List will consistently expand upwards.

Please note that if the object is positioned near the window's edge



	and the option to expand towards the edge is selected, the menu
	content display will be compressed.
	Style: This option is available only when the selected mode is
	[Drop-down list]. Available styles are: [Standard] and [Classic]. The
	appearance of the objects will be shown in cMT / cMT X Style wher
	[Standard] is selected, and shown in iE/eMT/XE style when [Classic]
	is selected. When the project is converted from iE/eMT/XE to cMT,
	cMT X, the default style will be [Classic].
	Font size: When [Same size as label] is selected, the font size set in
	Label tab will be used for the drop-down list. When [Fixed size] is
	selected, the system default font size will be used for the
	drop-down list.
	Row height: Set the row height for the drop-down list.
Monitor	The corresponding value of the selected item will be written to
address	[Monitor address].
	Write when button is released
	If this check box is selected, the selected item value will be written
	to [Monitor address] after the button is released.
Send	
notification	Set On/Off the designated bit address after successfully writing
after writing	data to PLC.
successfully	



■ The [write when button is released] option is not available on cMT / cMT X Series models.

#### 13.29.2.1. Source of item data

#### Predefine

The list is manually defined in [Mapping] tab.

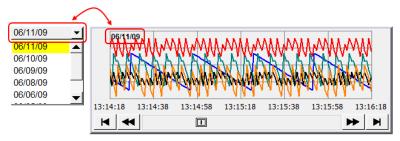
The number of items can be adjusted by [Item no.], and each item represents one state. Each item has a corresponding value which will be written to [Monitor address].

#### Dates of historical data





Option List object can be used with historical data display objects, such as Trend Display object, History Data Display object and Event Display object to control which history file should be shown. The figure below is an example of Option List used with Trend Display.



Setting	Description
Туре	Two options are available: [Event (Alarm) log] and [Data sampling].
Date	Set the date format. YYYY means a four digits year (EX: 2012), YY
	means a two digits year (EX: 12), MM means month and DD means
	day.
Data	Select which Data Sampling object is displayed when [Type] is [Data
Sampling	Sampling], and it should be the same as the [Data sampling object
	index] configured in [Trend Display] or [History Data Display].
Enable	
[delete	If selected, a control address can be set. Writing "1" to this address
history data]	will delete the history data of the specified date.
function	



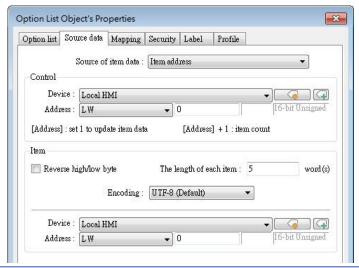
- In [Dates of historical data] mode, since the system automatically reads the historical data and finds the date information, it is not necessary to configure in the [Mapping] tab.
- The error message displayed in Option List can be modified in [Mapping] tab.

Item	Value	Item data	
▶ 0 (error)		Error!!	

#### Item address

The list will be read from the given [Item address] and controlled by [Control address]. The following options will be available:





Setting	Description				
Control	[Address]: If the value at this address is changed to 1, the option				
	list would be replaced by items defined at [Item address]. After				
	updating, the value will be restored to 0.				
	[Address + 1]: Define the number of items in [Item address].				
Item	Assign the item address				
	UNICODE				
	The item will use UNICODE characters, such as Chinese characters.				
	The length of each item				
	Define the number of letters for each item, the unit is Word.				

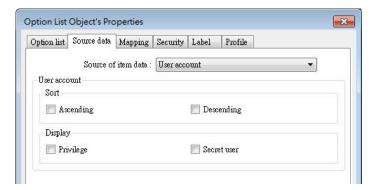


- The UNICODE characters used here should be used by Text object, so that EasyBuilder Pro will compile the needed fonts and download these fonts to HMI, then the UNICODE letters can be correctly displayed.
- [The number of items] multiplied by [The Length of each item] must be less than 4096 words.
- In [Item address] mode, the system automatically disables the settings in [Mapping] tab.
- Click the icon to download the demo project. Please confirm your internet connection before downloading the demo project.

# User account

If [Enhanced Security] mode is enabled, [User account] would appear in the [Source of item data] and it lists the names of users.





Setting	Description			
Sort	Select the sorting method from [Ascending] of [Descending].			
Display	If [Privilege] is selected, the privileges for each user will be displayed in option list.			
	If [Secret user] is selected, even though it is defined to be hidden in			
	[System parameter settings] » [Security] » [Enhanced Security], the			
	users will still be displayed in [Option List].			

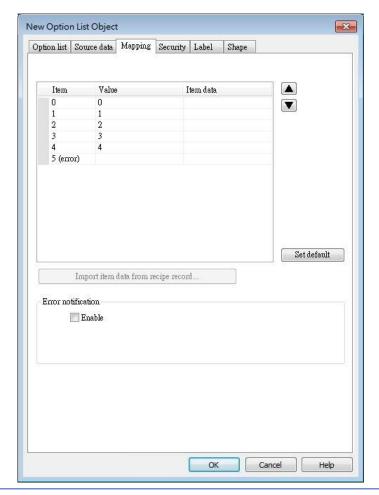


- The address that controls user index is [Control Address +2 (LW-n+2)] which is set in [System Parameters] » [Security] » [Enhanced Security].
- The [Privilege] option is not available on cMT / cMT X Series models.

#### **Mapping Tab**

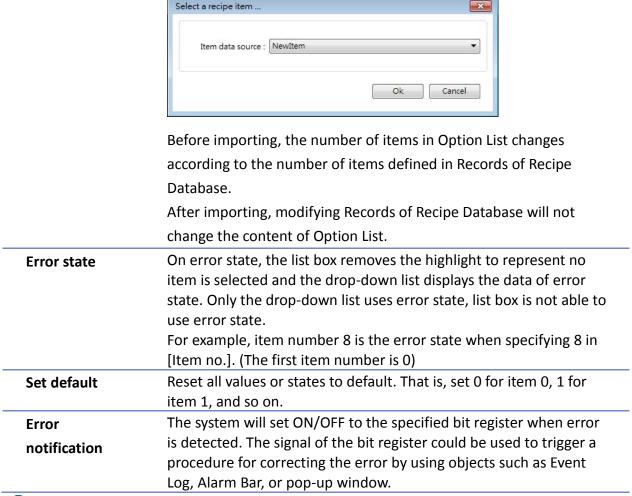
This table displays all available states/items, their item data and values. To change the number of available items, please go to [Option list tab] » [Attribute] » [Item no.].





Setting	Description
Item	The system lists all available items. Each item represents a state that will be displayed in the list. This field is read-only.
Value	Here user can assign value for each item, basing on the following two criteria:  For reading: If the value in [Monitor address] is changed, the object selects the first-matched item. If no item is matched, the status goes to error state and signals the notification bit register (if requested).  For writing: The system writes this value to [Monitor address] when user selects an item.
Item data	Text displayed for each item. The Option List object displays the text of all items in the list for users to review and select.
Import item	This feature is enabled when select [Recipe-Selection] as [Monitor
data from	address]. Click [Import item data from recipe record] to open the
recipe record	[Records of Recipe Database] setting dialog box. Select [Item data source], the data belonging to the selected column will all be imported to Option List object.





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# 13.30. Timer

#### 13.30.1. Overview

Timer object can be used to count the time in a specified mode. Timer object uses the following 6 variables:

Timer Variable	Туре	Description
Input bit (IN)	Bit	The main switch of Timer.
Measurement bit (TI)	Bit	Turns ON when the Timer begins
		counting time.
Output bit (Q)	Bit	Activated when the Timer finishes
		counting time.
Preset time (PT)	Word	Presets a time before the Timer
		begins counting time.
Elapsed time (ET)	Word	Displays the elapsed time.
Reset bit (R)	Bit	Resets the elapsed time (ET) to 0.

Timer (Per-page): The Timer can be placed in a project window and be activated only in that window.

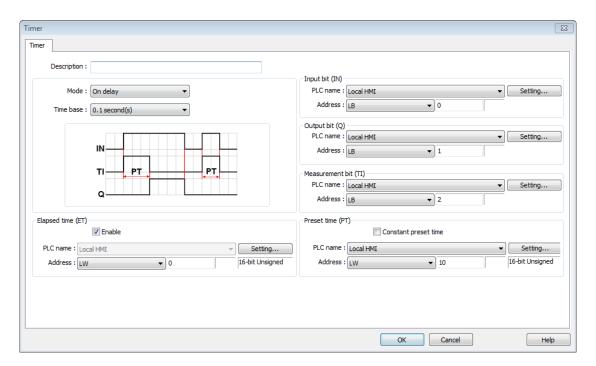
Timer (Global): Regardless of which window is displayed on HMI, the Timer starts counting time when the Input bit is in ON state.

# 13.30.2. Configuration



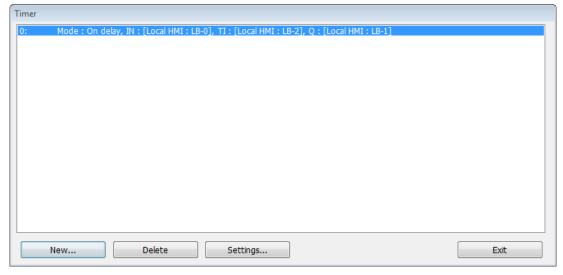
Click [Object] » [Time-related] » [Timer] icon on the toolbar to open the property dialog box as shown in the following figure.







- [Constant preset time] is only available for cMT / cMT X series.
- In a cMT / cMT X project, after the [Timer (Global)] icon is clicked, a Timer management window opens in which timers can be added by clicking [New].



#### On delay

Mode	Register				
	Input bit (IN): The main switch of Timer.				
IN	Measurement bit (TI): Turns ON when the Timer				
TI PT PT	begins counting time.				
"	Output bit (Q): Turns ON when the Timer finishes				
Q	counting time.				
1 2 3 4 5	Preset time (PT): Presets a time before the Timer				
	begins counting time.				
	Elapsed time (ET): Displays the elapsed time.				
	Description				

Period 1: When the IN turns ON, TI turns ON and the ET starts counting. The Q remains OFF.

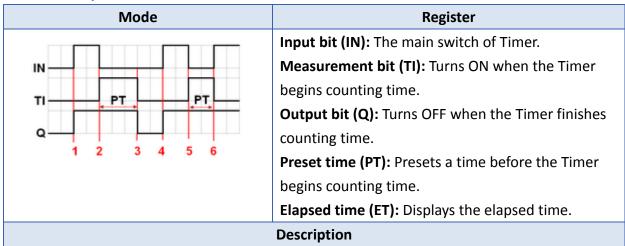
Period 2: When the ET equals to the PT, the TI turns OFF and the Q turns ON.

**Period 3**: When the IN turns OFF, the Q turns OFF and the ET is reset to 0.

**Period 4**: When the IN turns ON, the TI turns ON and the ET starts counting. The Q remains OFF.

**Period 5**: Turns IN OFF before the ET reaches the PT, the TI turns OFF, and the ET is reset to 0. Since the ET doesn't reach the PT, the Q remains OFF.

# Off delay



**Period 1**: When the IN turns ON, the TI remains OFF and the Q turns ON, the ET is reset to 0.

**Period 2**: When the IN turns OFF, the TI turns ON and the Q remains ON, the ET starts counting.

**Period 3**: When the ET equals to the PT, the Q and TI turn OFF.

**Period 4**: When the IN turns ON, the TI remains OFF and the Q turns ON, the ET is reset to 0.

**Period 5**: When the IN turns OFF, the TI turns ON and the Q remains ON, the ET starts counting.

**Period 6**: Turns the IN to ON before the ET reaches the PT, the TI turns OFF, the Q remains ON, and the ET is reset to 0,.



#### Pulse

Mode	Register				
	Input bit (IN): The main switch of Timer.				
IN	Measurement bit (TI): Turns ON when the Timer				
TI PT PT	begins counting time.				
TI FI FI	Output bit (Q): Turns ON when the Timer begins				
Q 1 2 3 4	counting time and turns OFF when the Timer				
	finishes counting time.				
	Preset time (PT): Presets a time before the Timer				
	begins counting time.				
	Elapsed time (ET): Displays the elapsed time.				
Description					

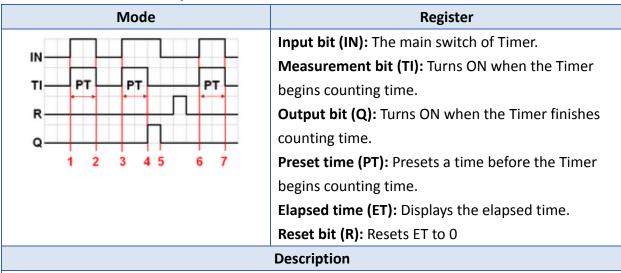
**Period 1**: When the IN turns ON, the TI and Q turn ON simultaneously, and the ET starts counting.

**Period 2**: When the ET equals to PT, the TI and Q turn OFF simultaneously. Since IN is turned OFF when counting time, the ET is reset to 0.

**Period 3**: When the IN turns ON, the TI and Q turn ON simultaneously, and the ET starts counting.

**Period 4**: When the ET equals the PT, the TI and Q turn OFF simultaneously.

# Accumulated ON delay



**Period 1**: When the IN turns ON, the TI turns ON and the elapsed time ET starts counting, the Q remains OFF.

**Period 2**: When the IN turns OFF, if the ET doesn't reach the PT, the TI turns OFF, and at the same time the Q remains OFF. The ET is in the retentive state.

**Period 3**: When the IN turns ON, the TI turns ON. The timer measurement starts again and the ET starts counting from the kept value. The Q remains OFF.

**Period 4**: When the ET reaches the PT, the TI turns OFF and the Q turns ON.

**Period 5**: When the IN turns OFF, the Q turns OFF. Turning ON the reset bit R will reset the ET to 0, and then the reset bit turns OFF.



# **Accumulated OFF delay**

Mode	Register				
	Input bit (IN): The main switch of Timer.				
IN-	Measurement bit (TI): Turns ON when the Timer				
TI PT PT	begins counting time.				
R	Output bit (Q): Turns OFF when the Timer finishes				
1 2 3 4 5 6 7 8 9 10	counting time.				
	Preset time (PT): Presets a time before the Timer				
	begins counting.				
	Elapsed time (ET): Displays the elapsed time.				
	Reset bit (R): Resets ET to 0				
Description					

**Period 1**: When the IN turns ON, the TI remains OFF and the Q turns ON.

Period 2: When the IN turns OFF, the TI turns ON and the Q remains ON. The ET starts counting.

**Period 3**: When the IN turns ON, the TI and Q remain ON, and the ET is in the retentive state.

**Period 4**: When the IN turns OFF again, the ET starts counting from the kept value.

Period 5: When the ET equals to the PT, the TI and Q turn OFF simultaneously. Turning ON the reset bit R will reset the ET to 0, and then the reset bit turns OFF.



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before downloading the demo project.



#### 13.31. Video In

#### 13.31.1. Overview

HMI provides the video In feature that enables users to monitor sites with cameras. The images/video can also be stored in external devices for further analysis. Sampling applications include site monitoring, or vehicle/building surveillance...etc.

The following tables show the video input and image capturing behaviors for different models.

Model		iP	iE	еМТ	mTV	XE	cMT-SVR	cMT-FHDX cMT-HDM	Other cMT/cMTX
	IP Camera	N/A	N/A	Υ	N/A	Υ	N/A	Υ	Υ
Supported	USB Camera	N/A	N/A	Υ	Υ	Υ	N/A	Υ	Υ
device type	Video Input	N/A	N/A	eMT3121A eMT3151A	N/A	N/A	N/A	N/A	N/A

Model		Non-cMT Series – Image Capture	cMT / cMT X Series – Image Capture/ Video Recording
	IP Camera		Image Capture: one image is captured
Image Capturing	USB Camera	One image is captured at the trigger moment.	at the trigger moment.  Video Recording: video is recorded, for a pre-determined duration, around the trigger moment.
	Video Input	Several images are captured around the trigger moment.	

# 13.31.2. Configuration



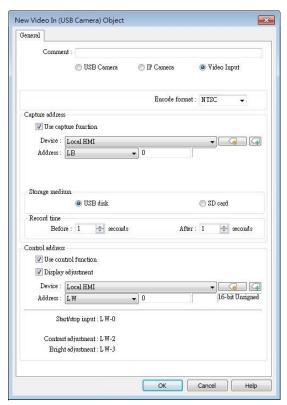
Click the Video In icon on the toolbar to open the property dialog box. Set up the properties, press OK button, and a new Video In object will be created.



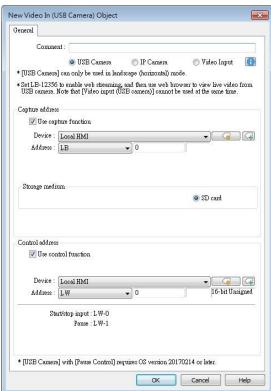
#### **General Tab**

# eMT, iE, XE, mTV Series

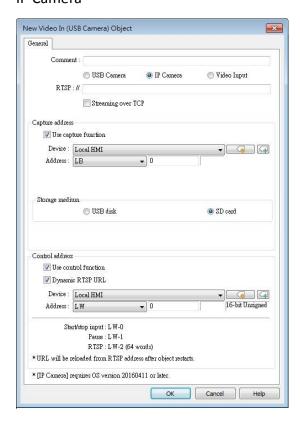
#### Video Input



#### **USB** Camera



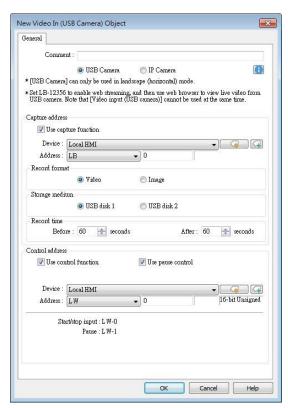
# IP Camera



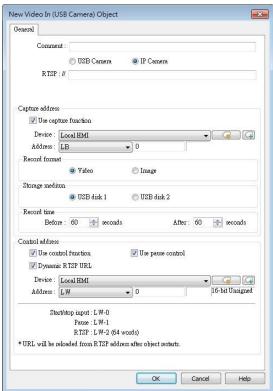


#### cMT, cMT X Series

#### **USB** Camera



#### **IP** Camera



Setting	Description	
Input channel	Select the Video Input channel from channel 1 or channel 2.	
	(Analog video systems)	
Encode	Select the format from NTSC or PAL. (Analog video systems)	
format	Select the format from NTSC of FAL. (Analog video systems)	
RTSP	Enter the IP camera's RTSP address.	
	When account and password are required for accessing the IP	
	Camera, an RTSP address with credentials embedded can be used.	
	For example:	
	admin:admin@192.168.1.119:554/cam/realmonitor?channel=1&subtype=0	
	Streaming over TCP	
	Select this check box to stream video over TCP.	
Capture	Select [Use capture function] check box and configure the settings.	
address	A non-cMT model can capture images while a cMT / cMT X model	
	not only can capture images but also can record an avi video from n	
	seconds before to n seconds after the triggering time of the	
	designated address.	
	Capture address	
	Designate the address that triggers image capturing.	



#### Storage medium

Designate the storage device.

Information about storage type and input type:

Input Type	Storage Type
Analog Input	SD card or USB disk.
USB Camera	SD card only. Exception: cMT3092X
IP Camera	SD card or USB disk.

# Record time (cMT / cMT X Series)

The camera records the video from and to the specified recording time (n seconds before and after the triggering time of the designated address). The video is then saved to the specified storage device. Please note that after the video is recorded, the HMI may take a while to compress the video. The time needed for compressing the video may differ between models depending on CPU performance. A red dot appears in the object indicating that recording or compressing is in progress. The HMI will not record the next video during compression.

# **Record time (eMT Series)**

Set a period of time to capture the images.

System	Method	
Analog video	<ul> <li>The longest period can be set from 10</li> </ul>	
system	seconds before triggering [Capture address]	
	to 10 seconds after triggering.	
	The time interval of image capturing is once	
	every second.	
	<ul> <li>The captured .jpg file will be named in the</li> </ul>	
	following format:	
	Before or after [Capture address] is	
	triggered: YYYYMMDDhhmmss.jpg	
	The moment that [Capture address] is	
	triggered: YYYYMMDDhhmmss@.jpg	
	For example, set [Record time] "Before" and	
	"After" to "5" seconds. When the state of [Capture	
	address] changes from OFF to ON, the system will	
	start capturing one image per second, from 5	
	seconds before the triggering time to 5 seconds	
	after the triggering time, which is 11 images in	



	total including the one captured at the triggering	
	moment.	
USB	Only the image of the triggering moment is	
Camera	captured. The name format:	
	YYYYMMDDhhmmss.png.	
IP Camera	Only the image of the triggering moment is	
	captured. The naming format:	
	YYYYMMDDhhmmss.png.	

Click the icon to download the demo project. Please confirm your internet connection before downloading the demo project.

# Control address

If enabled, enter certain value to the control address and the following addresses can control Video Input object. For example, if the designated control address is LW-n (n is any address), enter certain value to the designated addresses will execute commands as the following table.

# **Analog Video Systems**

Address	Value	Command
LW-n	0	Stop displaying image
	1	Open channel 1 and display the
		image on HMI
	2	Open channel 2 and display the
		image on HMI
	3	Open channel 1 but don't display the
		image on HMI (Capture function
		operable)
	4	Open channel 2 but don't display the
		image on HMI (Capture function
		operable)
LW-n+1	1	Pause / resume the video
LW-n+2	1~100	Adjust the contrast ratio
		(Analog video systems only)
LW-n+3	1~100	Adjust the brightness
		(Analog video systems only)

# **USB Camera / IP Camera**

Address Value Command		
LW-n 0 Stop displaying image		
	1	Start displaying image
LW-n+1	Pause / resume the video	
LW-n+2 string RTSP address for IP camera (64		



words)			

 After changing the value in [Control address (LW-n)], the system will keep the new value.

- After changing the value in [Control address + 1 (LW-n+1)], the system will execute the command and then reset the value to 0.
- If [Use control function] check box is not selected, the system will play the image of the selected channel.
- If [Display adjustment] check box is selected, the contrast ratio and brightness can be adjusted. (Analog video systems)



Only one channel can be opened at a time, regardless of the type of camera used.

# About analog video systems:

- Real-time images can still be captured when Video In is paused.
- Recommended analog video systems and resolutions:

a. 6			
	1:1	50%	
NTSC	720 x 480	360 x 240	
PAL	720 x 576	360 x 288	

Click the icon to download the demo project. Please confirm your internet connection before downloading the demo project.

#### About cMT / cMT X Series Video Recording

- Compressing the recorded video may take a period of time depending on the video length.
- When HMI is compressing a video, it will not record new video even if the designated address is triggered.

#### **About USB Camera:**

- USB camera cannot be viewed on cMT Viewer.
- When the USB Camera is disconnected during video playing, video will not resume when camera is connected again. If [Control address] is used in the project, please use the control address to stop and restart video. If [Control address] is not used, switch to another screen and then return, or restart HMI in order to resume the video.
- The maximum size of Video In object of eMT3070A is 340\*240, as for eMT3105P, eMT3120A, eMT3150A, XE, and mTV Series, the maximum size of Video in object is 640\*480.
- When using a USB Camera, the display resolution of the run-time video is determined by the resolution supported by the USB Camera that is closest to the size of the object. The resolution supported by the USB Camera may not be identical to the size of the object. Therefore, it is good practice to adjust the size of object according to the actual resolution



of the video.

When using a USB Camera, the right and bottom edge of the Video In object will keep a distance of 50 pixels away from the window edge to prevent the run-time video from exceeding the window.

■ When using a USB Camera, the background color of Video In object is black. If the resolution of the run-time video is smaller than the object, the empty area is colored black. Therefore, it is good practice to adjust the size of object according to the actual resolution of the video. The tested and available USB Cameras are: Logitech C170, Logitech C310, Logitech C910, LifeCam VX-2000.

Click the icon to watch the demonstration film. Please confirm your internet connection before playing the film.

Click the icon to download the demo project. Please confirm your internet connection before downloading the demo project.

#### **About IP Camera:**

- Viewing IP camera on cMT Viewer may be possible on a Windows PC, provided that appropriate third-party codecs are used.
- As compatibility may vary, testing with an actual device is recommended.
- A RTSP address is required for using IP camera. The RTSP address can be found in the configuration tool of the IP camera, or possibly from an online repository.
- When the IP Camera is disconnected during video streaming, video will not resume when the camera is connected again. If [Control address] is used in the project, please use the control address to stop and restart video. If [Control address] is not used, switch to another screen and then return, or restart HMI in order to resume the video.
- When using an IP camera, the display resolution of the run-time video will be same as that of the object drawn in the EasyBuilder Pro project. If the actual video resolution is different from the size of the object, the resolution will be adjusted to fit the object, which may cause distortion of video image. Therefore, it is good practice to adjust the size of object according to the actual resolution of the video.
- Use the IP cameras that comply with ONVIF standard, and use RTSP for video streaming.
- To ensure the quality and smoothness of the video, and not to affect HMI's general performance, adjust the settings of IP camera when video lags or high CPU loading is observed. As the project complexity and hardware specs vary from one case to another, please fine-tune the video parameters accordingly.
- Recommended video specification:

Resolution	960x544 (max.)
Format	H.264, MJPEG
Refresh Rate	15 fps
Transmission Speed	800kbps (max.)

Click the icon to download the demo project. Please confirm your internet connection before downloading the demo project.

Click the icon to watch the demonstration film. Please confirm your internet connection before playing the film.



# 13.32. System Message

#### 13.32.1. Overview

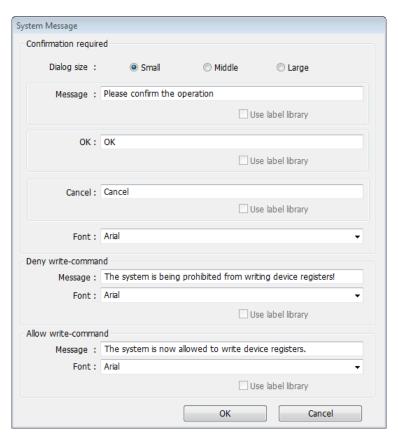
If objects use [Display confirmation request] or [local HMI supports monitor function only] is turned on/off, the corresponding messages configured here will be displayed in pop-up message boxes.

### 13.32.2. Configuration



Click the System Message icon on the toolbar to open the setting dialog box.

# **System Message**



Setting	Description
Dialog Size	Select the size for pop-up window and texts.
Confirmation	If an object uses [Display confirmation request], this message
required	would pop up when the object is used. [Message] shown on



	confirmation dialog box, and the text label of the 2 buttons, [OK]
	and [Cancel], can be set. Please use the same font for the labels of
	[Message], [OK] and [Cancel]. Additionally, only when selecting
	[Label Library] for [Message], the use of Label Library for [OK] and
	[Cancel] buttons can be enabled.
Deny	Displays when system tag LB-9196 (local HMI supports monitor
write-command	function only) is turned ON.
Allow	Displays when system tag LB-9196 (local HMI supports monitor
write-command	function only) is turned OFF.



# 13.33. Recipe View

#### 13.33.1. Overview

Recipe View object can be used to display a specific recipe. All items and values of the recipe can be viewed by using this object.

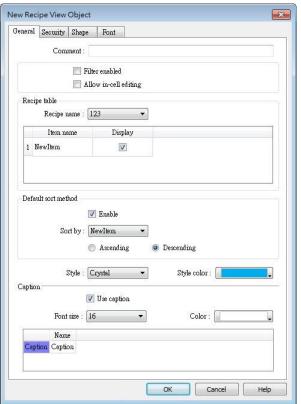
# 13.33.2. Configuration



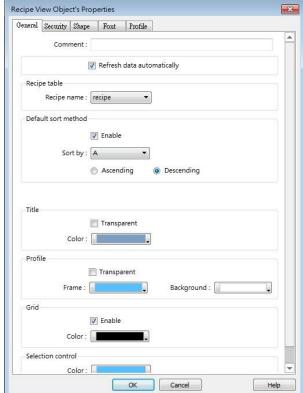
Click the Recipe View icon on the toolbar to open a Recipe View object property dialog box. Set up the properties, press OK button, and a new Recipe View object will be created.

#### **General Tab**

# cMT / cMT X Series



eMT, iE, XE, mTV Series



The name of each part of the Recipe View object is shown in the following figure.



	9
Setting	Description
Filter enabled	When selected, entering keywords in Recipe View to search for specific text is possible.
Allow in-cell editing	When selected, editing Recipe Database directly in Recipe View is possible.
Refresh data automatically	When selected, the system will automatically refresh Recipe View when recipe is changed; otherwise, Recipe View will be refreshed after window change.
Recipe table	Recipe name Choose the recipe name or look for other recipes from the drop-down list.  Display Choose an item to be displayed by selecting its checkbox.
Default sort method	Configure how the items are sorted. [Ascending] and [Descending] can be selected.
Style (cMT / cMT X Series only)	Available styles are: Default, Crystal, and Flat.
Caption (cMT / cMT X Series only)	With [Use caption] enabled, the text, font size, color, and name of the caption can be specified. (Use caption is only available when the selected style is Crystal or Flat.)
Title	The item name assigned in [Data/History] » [Recipe Database].  Transparent  If selected, the title row has no shading; the color selection is not available.
Profile	The frame and background color of the object can be set.  Transparent  Select to hide the background, the color selection is not available.
Grid	The dividing lines between columns and rows.  Enable  Select to show the grid.  Auto fit short column (cMT / cMT X Series Default style)



Selection Control

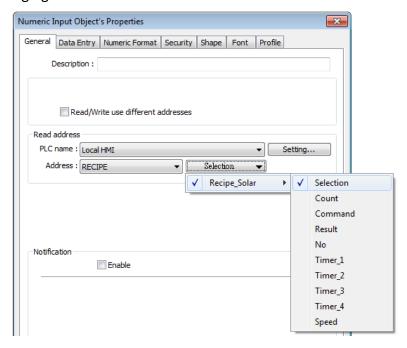
Shading color of the selected row.



There are 4 system registers that can be used to view/update/add/delete recipe database:

#### Selection

Current selection of record in Recipe View object, and it is numbered from zero. If the first record is chosen, the value of Selection will be 0. When the value of Selection is changed, the corresponding values will be updated, such as "No", "Timer\_1", "Timer\_2", as shown in the following figure.



#### Count

Show the number of records in current recipe.

#### **Command**

Enter certain value will send command to the selected record.

Enter "1": Add a new recipe record.

Enter "2": Update the selected recipe record.

Enter "3": Delete the selected recipe record.

Enter "4": Delete all recipe records.

Enter "5": Write the selected recipe record to PLC.

Enter "6": Update the recipe record selected from PLC.

#### Result

View the result of executing commands.

Displays "1": Command successfully executed.



Displays "2": The selected record does not exist.

Displays "4": Unknown command.

Displays "8": Records reach limit (10000 records), no new records can be added.

Display "16": Another command is being executed.

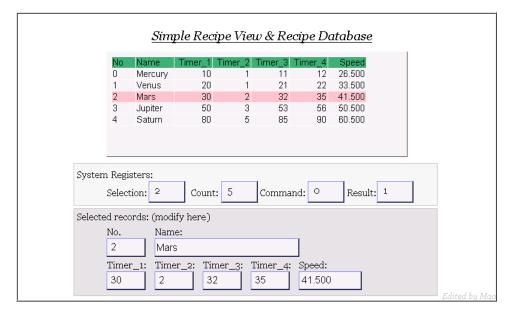
Display "32": Transfer command failed.

Please go to [Data/History] » [Recipe Database] tab to create the recipe data before using Recipe View object. See "24 Recipe Editor".

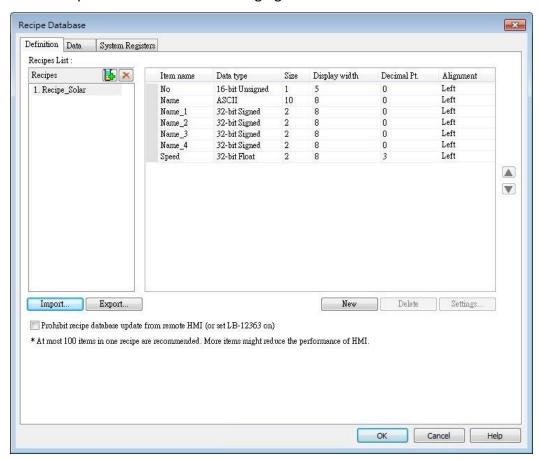


# **Example 1**

In this example, a recipe database is created to be displayed by Recipe View object. When you select a recipe record on Recipe View object, the value of [Selection] and the corresponding values will change accordingly. When finish designing, you can modify the recipe database by entering a value in [Command].



1. Create a recipe as shown in the following figure.





Recipe Database × Definition Data System Registers Recipes List: Name NewItem1 NewItem2 NewItem Test1 10 11 Test2 20 21 30 0 Test3 0 50 0 0 Test4 60 0 Test5  $\mathbf{v}$ 

2. In Data tab create a number of records as shown in the following figure.

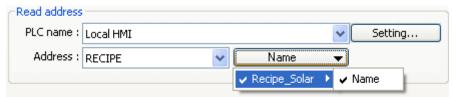
3. Create a Recipe View object and use the recipe database created in the preceding steps.

ОК

Cancel

Help

- 4. Create 4 Numeric objects using registers "Selection", "Count", "Command", and "Result".
- 5. Create corresponding input objects for "No", "Name", "Timer\_1", ..., "Timer\_4", "Speed". For example, "Name" is an ASCII item with size "10". Create an ASCII object and set device type to "RECIPE" » "Name".



- **6.** The project is then completed.
- 7. As shown above, "Mars" is selected and the corresponding items are also updated. There are 5 records so the "Count" displays "5". Try selecting different rows of the Recipe View object. Fields "Name", "Timer\_1", ...will change accordingly.
- **8.** Try the following operations:
- Δdd.

To add current data as a new record, enter "1" in "Command".

Update:
 To update recipe database, enter "2" in "Command".



- Delete:
  - To delete the selected record, enter "3" in "Command".
- Sort the items.
- Click the title to change the order.

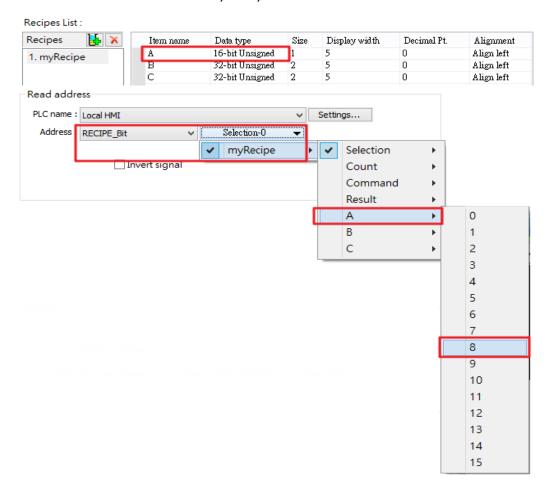


# **Example 2**

In this example, [RECIPE\_Bit] can be used to read / write individual bits of Recipe data.

Although BOOL type items cannot be added to Recipe Database, individual bit access of 16bit / 32bit data is possible.

As shown in the following figure, select [RECIPE\_Bit] for the read address of Bit object and point to the target item, and then the available Bit selections will be displayed. In this manner, Recipe Database can be used to record, read, and write bit data.





#### 13.34. Flow Block

#### 13.34.1. Overview

Flow Block object displays the flow status of the blocks in the pipe or the status of the transportation lines. Unlike Moving Shape object which requires a precise measurement between two points when drawing a straight line provided by users, the blocks flow at a fixed interval in a horizontal or vertical straight line. For cMT / cMT X Series models, drawing non-horizontal and non-vertical lines is possible.

The features of Flow Block:

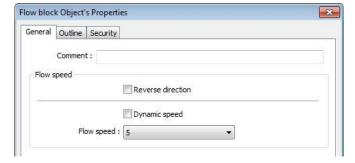
- Each section of the Flow Block must be a horizontal or vertical straight line and the blocks flow at a fixed interval within it. For cMT / cMT X Series models, drawing non-horizontal and non-vertical lines is possible (angle limit: 5 degrees).
- Dynamic speed and direction adjustment (Speed and direction can be controlled by a designated register.
- Security mechanism (Interlock), which hides Flow Block when the status of designated bit is invalid.

#### 13.34.2. Configuration



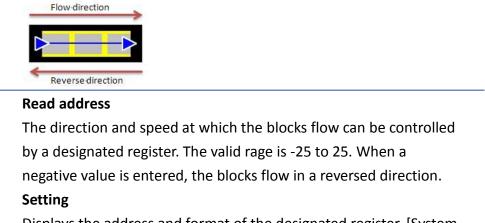
Click on the Flow Block icon on the toolbar or select [Objects] » [Animation] » [Flow Block] to create object.

#### **General Tab**



Setting	Description
Reverse	The blocks flow in the direction the object is drawn (the blue
direction	arrow). If select this check box, the blocks flow in the opposite
	direction.





Displays the address and format of the designated register. [System register], [Index register], and [Tag Library] can be set here.

25 flow speed levels, the valid range is 0 to 25 when [Dynamic

speed] is not selected. A larger value indicates a faster speed.

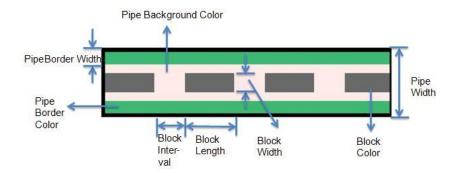
# Outline Tab

**Dynamic** 

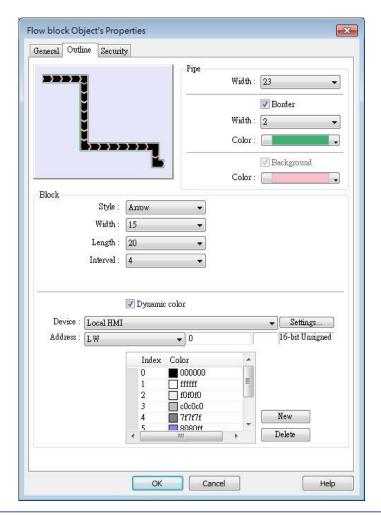
Flow speed

speed

For setting the outline property of Flow Block. The following illustration shows each item.







Setting	Description
Pipe	Sets the properties of the pipe within which the blocks flow. The
	background color, border width and color can be set. When the
	[Border] check box is selected, the background color must be set.
Block	Sets the properties of blocks. Style, width, length, interval and color
	can be set.
	Available styles are Rectangle and Arrow. The direction in which the
	arrows point to indicates the direction of the flow block.
	Rectangle: Arrow:
Dynamic	Allows dynamic color change with 256 customized colors,
color	numbered from 0 to 255 allowed. The color is selected by entering
	a value in the designated register. Entering a value greater than the
	largest color number changes the Flow Block to the last color in the
	list.

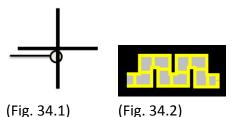


If both [Reverse direction] and [Dynamic speed] check boxes are selected in [General] tab,



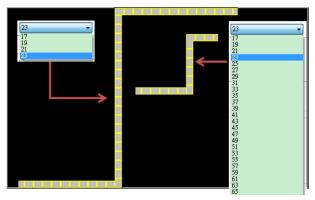
when entering a negative value in the designated register of dynamic speed, the blocks flow in the direction the object is drawn.

- When both [Arrow] and [Dynamic speed] are selected, the arrow will only show when a value is given to the designated address.
- To avoid the pipe lines from overlapping when drawing a turn, there is a minimum width planned at each turn. As shown in Fig. 34.1, the sign on the cross cursor defines the minimum width. Fig. 34.2 demonstrates that each turn is drawn in the minimum width.

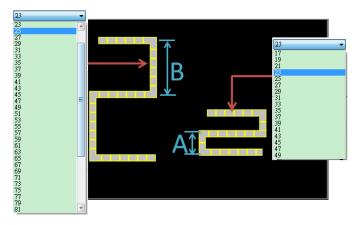


The valid range of the length, width, and height of the Flow Block can be adjusted according to the size of the object drawn and the size of the window.

As shown in the following figure, when the size of the Flow Block is larger, the valid range is restricted to prevent the flow block from exceeding the window size. When the size of the object is smaller, the adjustment range will be larger.



To prevent the flow block from overlapping itself, when the distance between two lines is shorter (Section A), the valid range is restricted. When the distance is longer (Section B), the adjustment range will be larger.

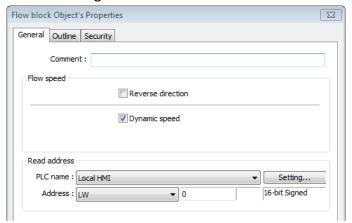




# **Example 1**

The demonstration below shows how to use [Dynamic speed] to control the direction and speed of Flow Block by a designated word register.

Create a Flow Block object and select [Dynamic speed] check box. Set [Address] to LW-0, and set the format to 16-bit Signed.



Create a Numeric object, set [Address] to LW-0. The high limit is 25, and the low limit is 2. -25. The format is 16-bit Signed.



Execute simulation or download the project to HMI. When entering a positive value in LW-0, the blocks flow in the direction the section is drawn. A larger value indicates a faster speed. When a negative value is entered, the blocks flow in a reversed direction, and the smaller value indicates a faster speed. When 0 is entered, it stops flowing.



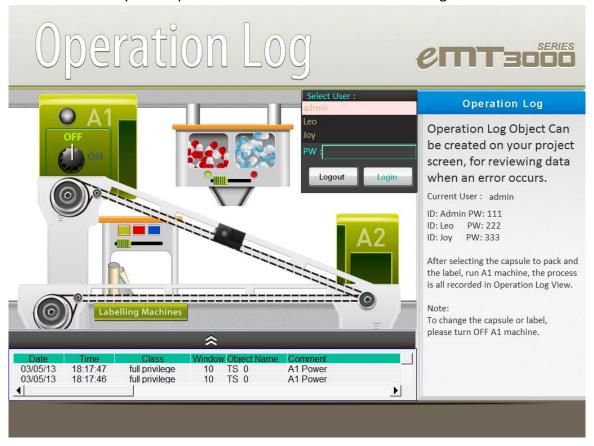
Click the icon to download the demo project. Please confirm your internet connection.

# 13.35. Operation Log

# 13.35.1. Operation Log Settings

#### 13.35.1.1. Overview

Operation Log records user's operation steps and displays the record in real-time. When an error occurs, use operation log to analyze the problem. The backup tables can be used to review the process in order to resolve the errors. Operation log, if configured properly, may also be used to satisfy the requirement for audit trail and electronic signature.



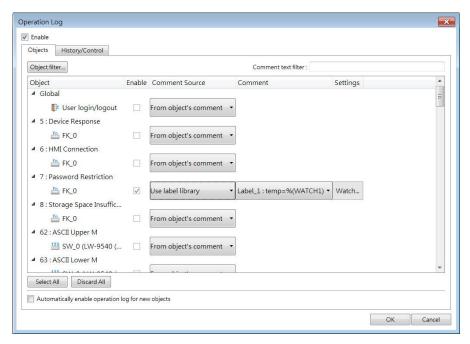


# 13.35.1.2. Configuration

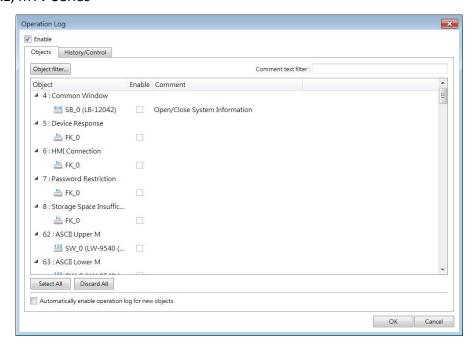


Select the objects to be recorded. Click [Data/History] » [Operation Log Setting], and then select [Enable operation log function] check box.

# cMT, cMT X Series



eMT, iE, XE, mTV Series

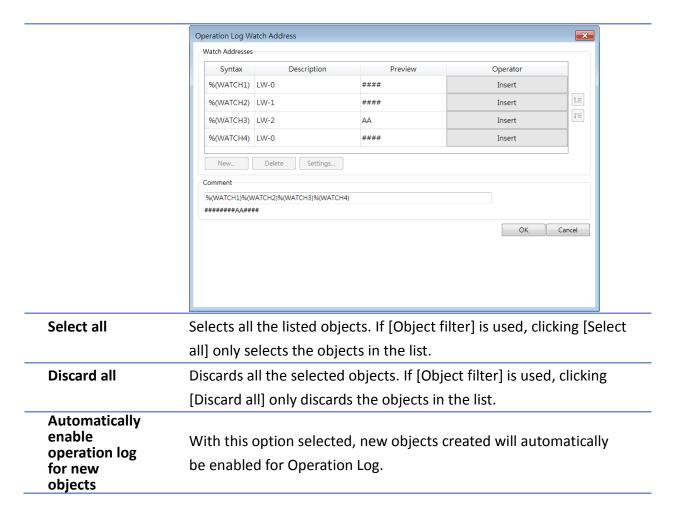




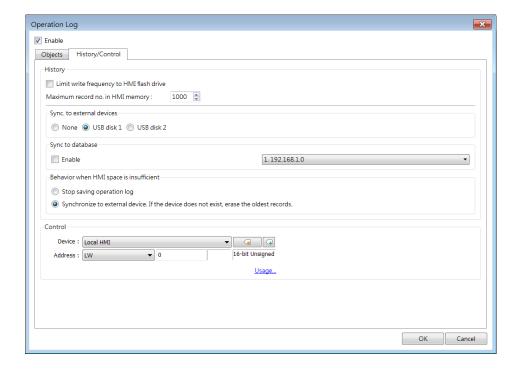
# **Objects**

Setting	Description
Object	With Operation Log function enabled, user login/logout activities
	and the objects that can be recorded are listed in the setting dialog
	box sorted by window numbers.
	[Filter]: By clicking [Object filter], all recordable objects are listed.
	Users can use the filter to more easily locate the desired objects.
Enable	The selected objects are recorded by Operation Log.
Comment	From object's comment
Source	The content in the [Comment] field of the Operation Log is sourced
	from the object's comment setting.
	New Toggle Switch/Bit Lamp  General Security Shape Label  Comment:  Bit Lamp  Toggle Switch  Customize
	Users can customize the content in the [Comment] field of the
	Operation Log by clicking [Watch].
	Use label library
	The [Comment] field supports the utilization of a label library,
	enabling the content to be recorded with translated text in different languages.
Settings	When the comment source is set to [Customize] or [Use label
	library], users can configure the watch addresses by clicking
	[Watch]. When a label library is used as the comment source, the
	watch address syntax should be defined within the label content.
	Up to four addresses can be simultaneously watched.





# **History/Control**





Setting	Description
Storage	Sets the way the records are stored.
settings	Limit write frequency to HMI flash drive
	When enabled, the system will store operation logs on the HMI at
	intervals of 10 seconds. To prevent the loss of operation log data
	between two storage actions caused by power-off, EasyBuilder Pro
	provides the system register LB-9034. By sending an ON signal to
	this register, the system will initiate a data storage process.
	Maximum record no. in HMI memory
	Sets the maximum number of records that can be stored in HMI
	memory.
	Sync. to external devices / database
	Stores backup data to SD card or USB disk. Backup data can be
	synchronized to database (cMT / cMT X Series).
	Behavior when HMI space is insufficient
	When HMI memory space is insufficient, two options are provided:
	[Stop saving operation log]: Stops saving new records in order to
	keep the earlier records.
	[Synchronize to external device]: Stores the Operation Log to the
	external device. When the device does not exist, the HMI clears the
	oldest records in its memory.
Control	Entering different values in the control address sends
address	corresponding commands to Operation Log and returns the result
	of executing the command.
	If control address is LW-n (where n is an arbitrary number), the
	address that returns the result of executing the command is
	LW-n+1.
	Control address (LW-n):
	(1): Clear all records.
	(2): Copy the records to the USB disk.
	(3): Copy the records to the SD card.
	(4): Copy the records to the USB disk and clear the records in HMI
	memory.
	(5): Copy the records to the SD card and clear the records in HMI
	memory.
	(6): Enable Operation Log.
	(7): Disable Operation Log.
	(8): Use history data stored in USB disk after changing HMI.



(9): Use history data stored in SD card after changing HMI.

(10): Copy the records to the database server. (cMT / cMT X Series)

(11): Copy the records to the database server and clear the records in HMI memory. (cMT / cMT X Series)

(12): Use existing historical data in database after changing to another HMI. (cMT / cMT X Series)

Execution result (LW-n+1):

(0): Processing.

(1): Execution succeeded.

(2): The device does not exist.

(3): The record does not exist.

(4): Unknown error.



- Operation Log can only record the operation of the objects that are manually triggered.
   Objects that cannot be manually triggered are not recorded, such as Time Based Data Transfer object.
- When running off-line or on-line simulation, Operation Log is stored under EasyBuilder installation directory: HMI\_memory\operationlog\operationlog.db
- Triggering Macro with a Set Bit object generates two records, the triggering of bit and the triggering of Macro.

# 13.35.2. Operation Log View

# 13.35.2.1. Overview

Operation Log View can be used to review the Operation Log.

# 13.35.2.2. Configuration

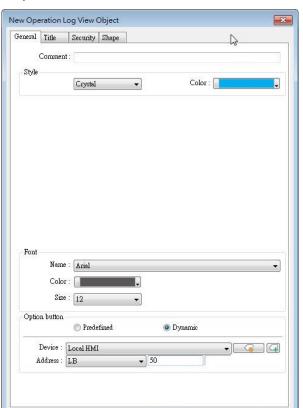


Before using Operation Log View, please follow the steps described in the preceding part to finish Operation Log Settings. Click [Data/History], and then click [Operation Log View].

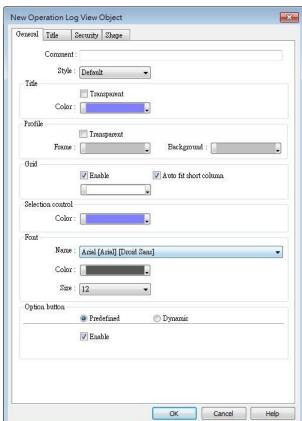


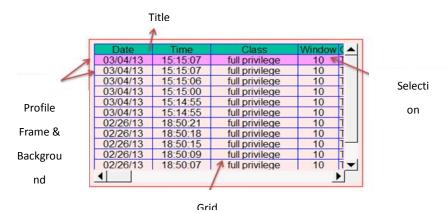
#### **General Tab**

# cMT, cMT X Series



# eMT, iE, XE, mTV Series





Cancel Help

Setting	Description	
Style	The style of Operation Log View object can be selected	
	from Default, Crystal, and Flat.	
Title/Profile/Grid/	These attributes can be configured when the chosen style	
Selection control	is Default.	
Font	Sets the color, font, and font size of the text displayed in	
	Operation Log View object.	



**Option button** visibility (cMT / cMT X Series)

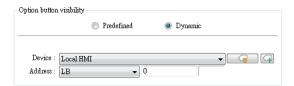
Show or hide the option button



#### **Predefined**

Select [Enable] to show the option button.

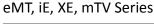
#### **Dynamic**

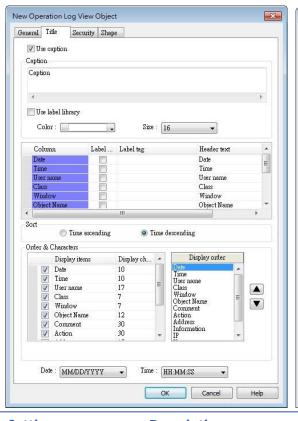


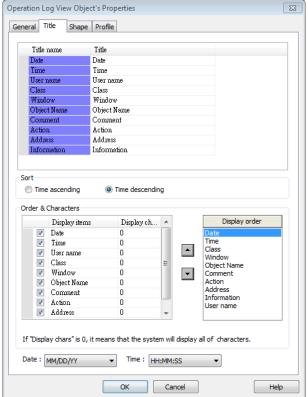
Designate a bit address to control option button visibility.

#### **Title Tab**

# cMT, cMT X Series







Setting	Description
Use Caption	Sets the caption displayed in Operation Log View object.
Title	Sets the title name of the columns displayed in Operation Log View
	object.
Sort	Sorts the records in time ascending or descending order.
Display order	Sets the order of the displayed item. If [Display chars.] is 0, all
	characters are displayed.
Date / Time	Sets the format of date and time displayed in Operation Log View



object.

# 13.35.3. Operation Log Printing

#### 13.35.3.1. Overview

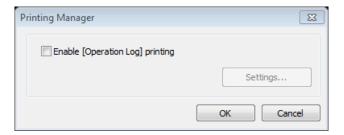
Operation Log Printing can generate an Operation Log sheet by printing out using a printer or by saving as JPEG file into an external device. Before using this function, please go to Operation Log Settings to finish the settings.

Operation Logs printed using cMT Viewer will be saved to the USB disk / SD card connected to the cMT / cMT X HMI.

# 13.35.3.2. Configuration

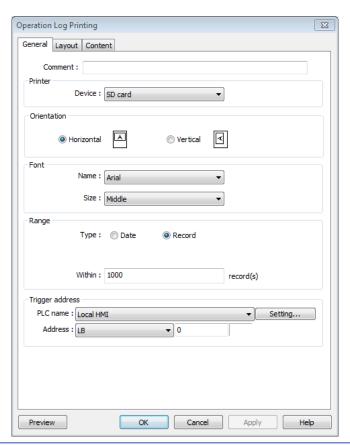


Select "Enable [Operation Log] printing" check box and click [Settings] button to open the Operation Log Printing dialog box.





# **General Tab**



Setting	Description			
<b>Printer</b> Select the device to save the Ope		peration Log she	et. If a printer is	
	selected, the pa	aper size should	be A4. If an exte	rnal device is
	selected, the O	peration Log sh	eet is saved as a J	IPEG file. The
	system generat	es a folder nam	ed "operationlog	sheet", and the files
	saved in the fol	der are named	"print date_sequ	ence number". For
	example, the fi	rst JPEG file save	ed on 2013/05/08	3 is named
	130508_0000 a	ind so on.		
Orientation	Sets the layout	of the Operatio	n Log sheet to be	horizontal or
	vertical.			
Font	Sets the font ar	nd the font size	to of the Operation	on Log sheet. The
	following table	lists the corresp	onding size.	
	Size	Title	Content	]
	Large	20 pt.	16 pt.	
	Middle	16 pt.	12 pt.	
	Small	12 pt.	8 pt.	
Range	Sets the range	of the Operation	n Log to be includ	led in the sheet.

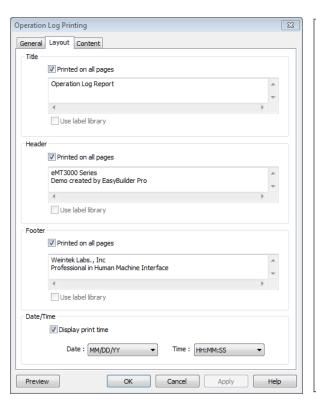
Sets the range by date, counted from the start day through the

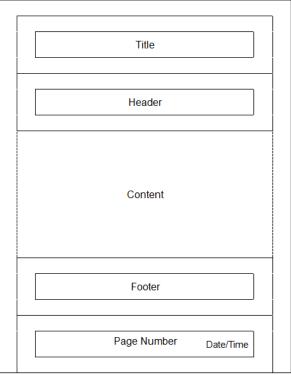


**Date** 

	number of days entered. The maximum available range is 180 days.
	Record
	Sets the range by the number of records. The maximum available
	range is 10000 records.
Trigger	Sets the register to control Operation Log Printing. When the
address	register is set ON, it starts printing. When the printing is done, the
	register is set OFF automatically.
Preview	Preview the result before generating the Operation Log sheet.

# **Layout Tab**





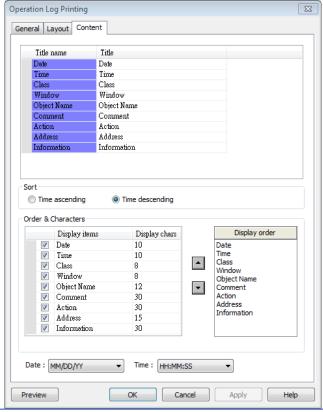
The layout of each part is shown in the above figure.

Setting	Description
Title	Sets the content of the title. The title is limited to one line.
	Printed on all pages
	If selected, the title is shown on each page; otherwise, the title is
	shown on the first page.
Header	Sets the content of the header. The header can have 5 lines in
	maximum.
	Printed on all pages
	If selected, the header is shown on each page; otherwise, the
	header is shown on the first page.
Footer	Sets the content of the footer. The footer can have 5 lines in



n all pages
I, the footer is shown on each page; otherwise, the footer
on the last page.
I, the date/time the in the sheet is shown on the
nt corner of each page; otherwise, the date/time is not
each page.

#### **Content Tab**



Setting	Description
Title	Sets the title displayed.
Sort	Time ascending
	The latest record is placed at the bottom.
	Time descending
	The latest record is placed at the top.
Date/Time	Sets the format of date and time displayed.

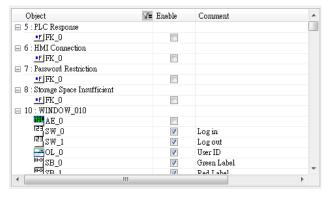
# 13.35.3.3. Demonstration

# **Example 1**

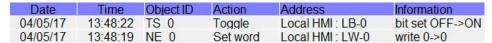
The following demonstration explains how to create an Operation Log project.



- 1. Create a Toggle Switch object and a Numeric object on window number 10.
- Go to Operation Log Settings; enable the Toggle Switch object and Numeric object on 2. window number 10.



- Create an Operation Log View object and finish relevant settings. 3.
- Run off-line simulation, trigger Toggle Switch and Numeric object. Operation Log is 4. displayed by Operation Log View object.



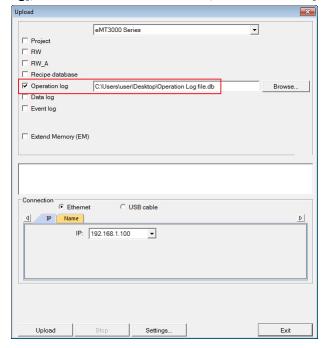


Click the icon to download the demo project. Please confirm your internet connection.

# **Example 2**

Upload Operation Log to PC by using Utility Manager or use Backup object to send the file by email.

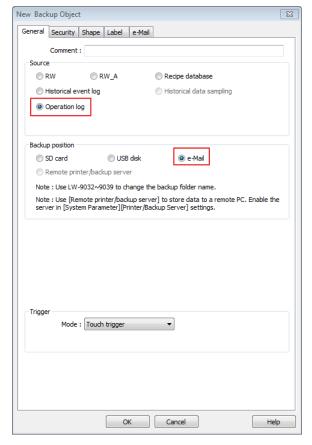
- Upload by Utility Manager
- Open Utility Manager, click [Upload]. 1.
- 2. Select [Operation log], enter file name and HMI IP, and then click [Upload].





- Send the sheet by e-mail
- 1. Open [System Parameter Settings] » [e-Mail] tab. Set e-mail server and the address of recipient and sender.

2. Create a Backup object, under [Source] select [Operation log], and under [Backup position] select [e-Mail].



For more information about e-Mail settings, see "5 System Parameter Settings".

Click the icon to download the demo project. Please confirm your internet connection before downloading the demo project.



# 13.36. Combo Button

#### 13.36.1. Overview

Combo Button can execute multiple commands. The former way was to overlay multiple objects in the same position, and the commands are executed in the order of the layer of the objects. This takes time to test the order when planning the project. Combo Button allows users to easily set multiple commands with one object, and freely adjust the order of executing commands.

The following are the features of Combo Button:

- Executes multiple commands.
- Allows adjusting the order of executing multiple commands.
- Displays the state in Bit or Word Lamp.

# 13.36.2. Configuration

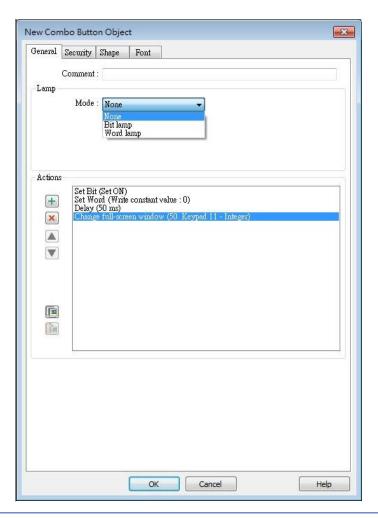


Click on the Combo Button icon on the toolbar or select [Objects] » [Combo Button] to create object. Configure object properties, click OK, a new Combo Button object will be created.



# 13.36.2.1. eMT, iE, XE, mTV

#### **General Tab**



# Setting Description

Lamp

The mode to display the state of a designated bit or word register.

None: Not using lamps to show states.

#### **Bit Lamp**

Displays the state of a designated bit address.

[Invert Signal] Reverses the display of ON / OFF states. For example, if [Invert signal] check box is selected, when the designated bit is OFF, the object displays ON state.

# **Word Lamp**

Displays the state according to the value of a designated word register.

[No. of state]: The number of states used by the object. The state is numbered from 0, so the number of states minus 1 will be the state number. If the value in the word register is  $\geq$  [No. of states] defined

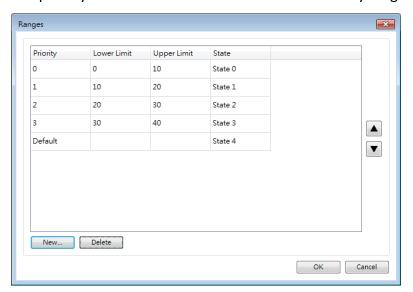


in Attribute, the highest state will be displayed.

If the number of states is set to 8, the valid states will be 0, 1, 2, ...,

7. In this case if the word value is 8 or higher, the system will display the state 7 shape.

[Change state by ranges]: Displays the state according to the range. When two ranges overlap, the state is determined by the priority. The priority is Default when the value is not within any range.



#### **Actions**

A combo button can execute up to 20 actions.

Key	Description
+	Add actions.
×	Delete the selected action.
	Change the order of the actions.
	Copy the selected action.
	Paste the copied action.

#### Add

# Delay

Delays the action for a few milliseconds. A combo button can set one [Delay] action only.

# **Set Bit**

Sets the designated bit ON or OFF.

Set style	Description
Set ON	Set ON the designated bit of the device.
Set OFF	Set OFF the designated bit of the device.
Toggle	Alternates the bit state each time pressed.

#### **Set Word**

Sets the value in the designated register.



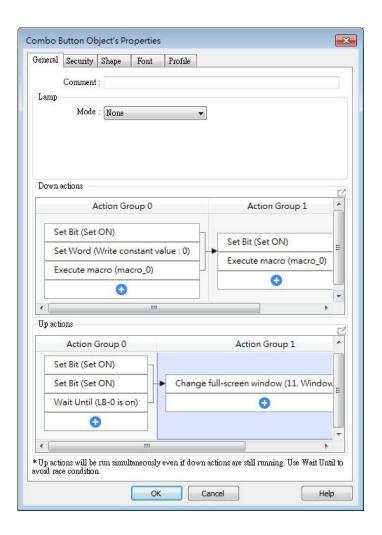
Set style	Description
Write	Writes a constant value to the designated
Constant Value	register.
JOG+	Increases value in register by a set amount in
	[Inc. value] each time when the button is
	pressed, to the [Upper limit].
JOG-	Decreases value in register by a set amount in
	[Dec. value] each time when the button is
	pressed, to the [Bottom limit].
Dynamic	Sets the Upper / Bottom limit by a designated
limits	register.
	When Dynamic Address is LW-n, where n is an
	arbitrary number, set upper limit when using
	[JOG+], and bottom limit when using [JOG-].

# **Change Window**

Switch to the designated window.

# 13.36.2.2. **cMT / cMT X Series**

# **General Tab**





Bit/Word Lamp actions are explained in 13.36.2.1 eMT, iE, XE, mTV.

For cMT Series, actions can be classified into action groups, whichs are put in sequence. Actions within a group are executed at the same time, and after the actions in the current

group have been all triggered, the actions in the next group will then be triggered. Please see

Ch13.53 Action Trigger for more information on the notes about action groups.

Setting	Description
Down actions	Execute action when the button is pressed.
Up actions	Execute action after the button is pressed and released.
Delay	Delay action for the specified time (ms).
Set Bit	Sets the designated bit address ON or OFF.
	Set ON
	Sets ON the designated bit.
	Set OFF
	Sets OFF the designated bit.
	Toggle
	Alternates the bit state.
	Momentary
	Momentary is a two-step action where pressing the button (Down
	action) will set the bit ON and then releasing the button (Up action)
	will set the bit OFF. Corresponding Down and Up actions will be
	created.
Set Word	Changes the value in the designated word address.
	Write constant value
	Writes the constant value to the designated register.
	Increment value (JOG+)
	Increases value in register by a set amount in [Inc. value], up to the
	[Upper limit].
	Decrement Value (JOG-)
	Decreases value in register by a set amount in [Dec. value], down to
	the [Bottom limit].
	Dynamic Limits (JOG+, JOG-)
	Sets the [Upper limit](JOG+) and [Buttom limit](JOG-) by a
	designated register.
	Write constant string
	Writes the constant string to the designated register.
Change	Switches to the designated window.
window	Change full-screen window: Changes to another base window.
	Change common window: Changes common window.



	Return to previous window: Changes from current screen to the
	previous one displayed. For example, when window no. 10 is
	changed to window no. 20, this function can be used to return to
	window no. 10. This function is only available for base window.
	Animation Setting:
	The effects are: Fade, Fly, Float, Wipe, Split, Circle, Clock, Zoom,
	Turn, Push. Different effects may be used for Start (window
	appears) and End (window disappears).
	[Duration] specifies how many milliseconds (ms) a transition effect
	takes to complete.
	[Direction] The direction of the transition.
Execute	Executes one of the Macros from the drop down list that has
Macro	already been configured by users. In an action group, [Execute
	Macro] is seen as completed as soon as it is triggered. Ever if a
	particular macro takes longer to complete, the system will not wait
	for the macro to complete running before moving on to the next
	action group.
Popup	
Window	Opens a designated window.
Close	
Window	Closes currently opened window.
Keyboard	Configures the button as a keypad key, and the character it enters,
Input	via [Numeric] or [ASCII] objects.
	Enter: Same as the keyboard's "Enter" function.
	Backspace: Same as the keyboard's "Backspace" function.
	Clear: Clear the value in the word register.
	Esc: Same as the [Close window] function; it is used to close the
	keyboard window.
	Reyboara Wiriaow.
	<b>Delete:</b> Same as the keyboard's "Delete" function, deletes the
	Delete: Same as the keyboard's "Delete" function, deletes the
	<b>Delete:</b> Same as the keyboard's "Delete" function, deletes the number or character on the right side of the text cursor. <b>Left:</b> Same as the keyboard's "←" key moves the text cursor to the
	Delete: Same as the keyboard's "Delete" function, deletes the number or character on the right side of the text cursor.  Left: Same as the keyboard's "←" key moves the text cursor to the left side of the previous number or character.
	Delete: Same as the keyboard's "Delete" function, deletes the number or character on the right side of the text cursor.  Left: Same as the keyboard's "←" key moves the text cursor to the left side of the previous number or character.
	<ul> <li>Delete: Same as the keyboard's "Delete" function, deletes the number or character on the right side of the text cursor.</li> <li>Left: Same as the keyboard's "←" key moves the text cursor to the left side of the previous number or character.</li> <li>Right: Same as the keyboard's "→" key moves the text cursor to the left side of the next number or character.</li> </ul>
	Delete: Same as the keyboard's "Delete" function, deletes the number or character on the right side of the text cursor.  Left: Same as the keyboard's "←" key moves the text cursor to the left side of the previous number or character.  Right: Same as the keyboard's "→" key moves the text cursor to the



Screen	Captures the current screen and saves it to an SD card or USB disk.	
Hardcopy	For headless HMI models (cMT-SVR / cMT-SVRX) connected to	
	specific interfaces, the available options for screen hardcopy are as	
	follows:	
	cMT-iV6: The captured screen can be saved to the SD card on	
	cMT-iV6.	
	cMT Viewer on PC: The "Screen Hardcopy" action is not supported,	
	please use the right-click "Screenshot" function instead.	
	cMT Viewer: The "Screen Hardcopy" action is not supported.	
Acknowledge		
all events	Acknowledges all events once.	
(Alarms)		
Import Data	Imports e-mail contacts or user accounts, or is used as USB Security	
	Key login.	
	Data Position:	
	[SD card] or [USB disk].	
	Account import mode:	
	If [Overwrite] is selected, the existing accounts will be overwritten	
	by new accounts. If [Append] is selected, accounts are appended.	
	Delete file after importing user accounts:	
	The system will delete the account data saved in the external	
	device after importing; this can prevent the account data from	
	leaking out.	
Wait Until	The next group will be executed only when the condition set for a	
	designated bit or word address is met.	
Data Transfer (Global)	Sends the value in the designated address to another address.	
File Transfer	Transfer files by FTP. HMI will connect to the FTP server in passive	
	mode.	
	General Tab:	
	Download: Transfer file from FTP server to local HMI.	
	Upload: Transfer file from local HMI to FTP server.	
	Server address:	
	[Direct], Designate server address related settings in EDDre	
	[Direct]: Designate server address related settings in EBPro.	
	[Dynamic]: Designate an address for changing the server address	
	[Dynamic]: Designate an address for changing the server address	



LW-n+1: IP (4 words)

LW-n+5: Port

LW-n+6: Authentication (0: None, 1: Account)

LW-n+7: Username (16 words) LW-n+23: Password (16 words) LW-n+39: Domain name (64 words)

#### Delete the source file after successful transfer

Following successful transfer, the source file will be deleted. When transferring in [Download (FTP -> HMI)] mode, please make sure that the account has the write permission on the FTP server.

#### File Tab:

Set file position and full path of FTP server / Local HMI. When a folder path is specified, all the files in that folder will be transferred, not including files in subfolders. When a file with identical file name already exists, it will be overwritten regardless.

#### **Status Tab:**

Designate an address for showing file transfer result and FTP server response. Please use the following link for more information on FTP server return codes.

https://en.wikipedia.org/wiki/List of FTP server return codes



- One Combo Button can only do one of these window actions, and only once: [Change Window], [Popup Window], and [Close Window].
- At most 20 groups can be created in a Combo Button, and at most 20 actions can be added into a group.
- File Transfer Error Codes:

Error Code	Description
0	File transferred successfully.
1	The HMI directory for download does not exist.
3	USB disk or SD card is not found.
4	HMI or FTP directory is empty.
5	Uploaded file does not exist.
8	Operation rejected by FTP server.
9	USB disk or SD card is full.
10	Unknown error.

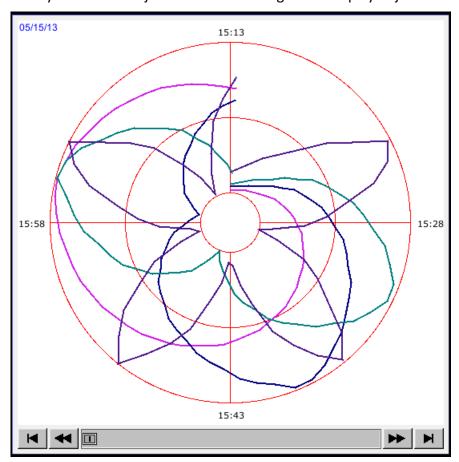
Click the icon to download the demo project. Please confirm your internet connection before downloading the demo project.



# 13.37. Circular Trend Display

# 13.37.1. Overview

Circular Trend Display object draws the trend curve of Data Sampling in a polar coordinate system, where y-axis represents the radial coordinate and the x-axis represents the angular coordinate. The way to use this object is similar to using Trend Display object.



# 13.37.2. Configuration



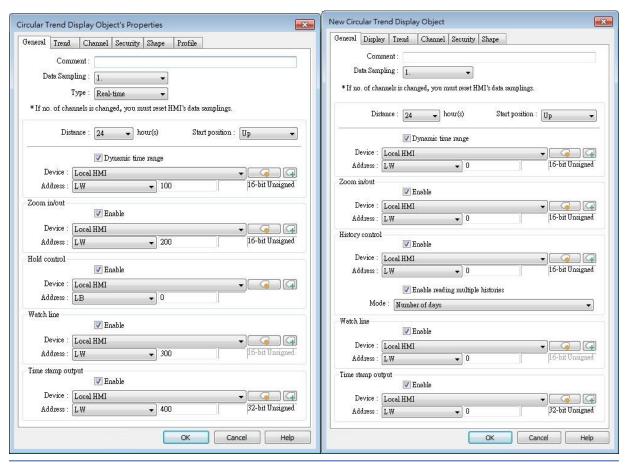
Click the Circular Trend Display icon on the toolbar to open the property dialog box. Set up the properties, press OK button, and a new Circular Trend Display object will be created.



#### **General Tab**

eMT, iE, XE, mTV





#### **Setting**

#### Description

### **Data Sampling**

Selects the data source for drawing the trend curve.

# Type (eMT, iE, XE, mTV Series)

Selects the type of the trend from [Real-time] or [History].

#### Real-time

In this mode, it displays a fixed number of sampling data from the moment HMI starts to present. The number of sampling data is determined by the [Max. data records (real-time mode)] setting of Data Sampling object. If the number of sampling data exceeds this number, the earlier data will not be displayed. To display earlier data or the data in other days, please select [History] mode.

[Hold control] address can be used to pause refreshing the display. This only stops displaying new data in the Circular Trend Display object, and the data is still being sampled by Data Sampling object.

# History



In this mode, it displays the sampled data sorted by date. Select the data source from [Data Sampling], and then use [History control] address to view the records of different dates.

#### Note

If [Show scroll control] check box in Trend Tab is not selected, the earlier data cannot be viewed when exceeding the specified [Distance].

For example: Set [Distance] to 1 (hour.), then sampling data earlier than one hour is not displayed.

# Refresh data automatically

If enabled, the window in which the Circular Trend Display object (in history mode) is placed will be refreshed once per second.

 The scroll controls can be used to check the refresh status.

If **u** button is displayed, the Circular Trend Display will be automatically refreshed.

If **b**utton is displayed, the Circular Trend Display will stop being refreshed.

- Scrolling backward and viewing earlier data will disable [Refresh data automatically]. The button displayed is at this moment.
- If [Refresh data automatically] is selected, the display is refreshed when change back to this window, regardless of the use of scroll controls.

Example: If [Refresh data automatically] is selected, scrolling to the earlier display stops auto-refresh. At this moment change to another window and then change back, the Circular Trend Display is still refreshed.

If [Refresh data automatically] is not enabled when building the project, to enable it directly on HMI, simply press . Please note that auto-refresh remains disabled after window change.



Distance	Defines the time length that the circle represents, the unit is hour, the range is 1 to 24 (hours).		
Start position	The position from where to start drawing the trend curve.		
	(Up)	(Right)	
	14:26:46 05/15/13 14:15 15:00 14:30	14:27:06 05/15/13 15:00 14:45	
	(Down)	(Left)	
	14:27:36 05/15/13 14:45 14:30 14:15	14:27:56 05/15/13 14:30 14:45	
Dynamic X-axis	If selected, a word register can be designated to control the		
time range	time length of Circular Trend Display. The unit is hour. If no		
	value is entered, the distance	value is entered, the distance is set to default.	
Zoom in / out	Enlarge or reduce the size of	Enlarge or reduce the size of the object. The maximum size	
	is 10 times larger. If 0 is enter	red in the designated register,	
	the effect equals entering 1,	the object remains the origina	
	size.		
Hold control	When the register is set ON,	When the register is set ON, suspend the update of Circular	
	Trend Display. It does not sto		
	Data Sampling object. This se	etting is available only in	
	Real-time mode.		
History control	History data is sorted by date	e. The system uses [History	
(eMT, iE, XE, mTV	control] to select the history		
Series)	different dates and then disp	lays it by Circular Trend	
	Display object.		
	_	d register in [History control] is	
	0, the Circular Trend Display	object displays the latest	

record. If the value is 1, the second latest record is displayed and so on. This setting is available only in History mode.

If use with Option List object and select data source as [Dates of historical data], the history data will be sorted by date and displayed in Option List object, see "13.29 Option List".

In the following example, when history control address is set to LW-n, and there are 4 sampling data: 20061120.dtl, 20061123.dtl, 0061127.dtl, 20061203.dtl. The corresponding data selected by the value in history control address is as the following list.

Value in LW-n	The sampling data displayed
0	20061203.dtl
1	20061127.dtl
2	20061123.dtl
3	20061120.dtl

History control (cMT, cMT X Series) Same as eMT, iE, XE mTV Series.

# **Enable reading multiple histories:**

In the following two modes, days are calculated backward.

# **Number of days**

Suppose the address is set to LW-n, then:

[LW-n]: The start day index from which to calculate number of days.

0: today, 1: yesterday, and so on.

[LW-n+2]: The total number of days before the start day.

# Specific days

Suppose the address is set to LW-n, then:

[LW-n]: The start day index from which to calculate number of days.

0: today, 1: yesterday, and so on.

[LW-n+2]: The end day index, the specified value must be greater than that of the start day index. For example, if start is 4 and end is 7, the specified days will be 4 days before to 7 days before.

#### Watch line

Displays a watch line when user touches the Circular Trend Display object, and the sampling data at the position of the watch line is output to the designated register. To display



sampling data with multiple channels, the system consecutively writes the data of each channel to the designated word register and the following registers. If the data format of each channel is different, the channels are sorted by the data format of its corresponding register. In the following example, when watch address is set to LW-n, and there are 4 sampling data, the format of each data is: 16-bit Unsigned, 32-bit Unsigned, 32bit Signed, and 16-bit Signed. The corresponding watch address is as the following list.

Channel	Data Format	Data Length	Watch Address
0	16-bit Unsigned	1 Word	LW-n
1	32-bit Unsigned	2 Words	LW-n+1
2	32-bit Signed	2 Words	LW-n+3
3	16-bit Signed	1 Word	LW-n+5

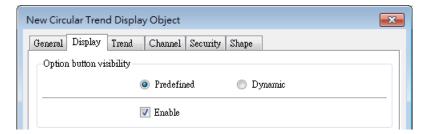
# Time stamp output

If selected, the system will start counting time from the first data sampled, and output the elapsed time counted of the latest data sampled to the register designated in [Time stamp output + 2]. When pressing a point on the trend curve, the relative time of the nearest data sample is then output to [Time stamp output address].

#### Note

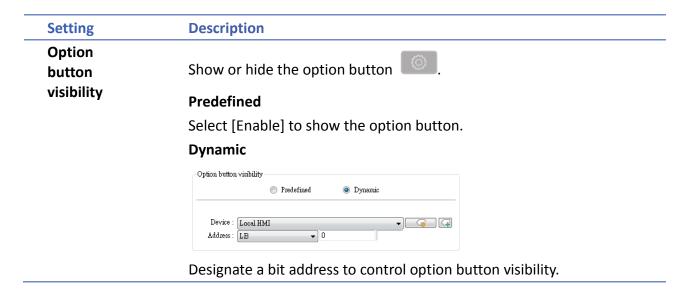
The format of the register designated in [Time stamp output] and [Time stamp output + 2] must be 32-bit. [Time stamp output + 2] is only available for Real-time mode while [Time stamp output] is available for Real time mode and History mode.

#### **Display Tab**

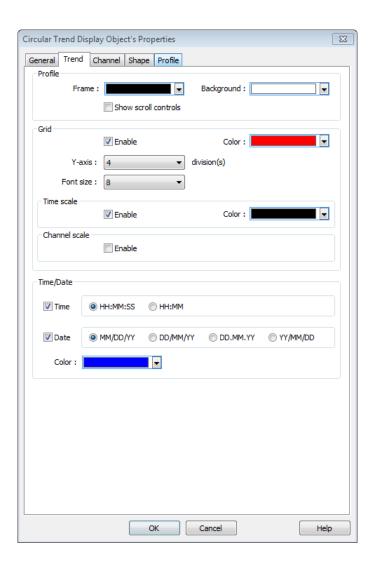


Display settings in this page are only supported on cMT / cMT X Series models.

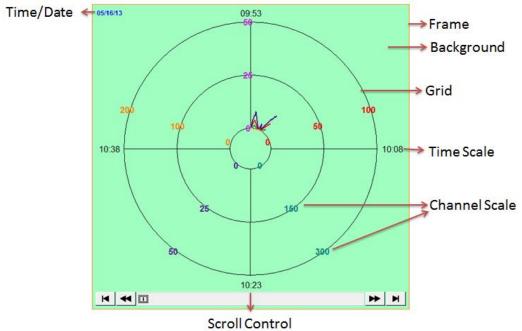




#### **Trend Tab**





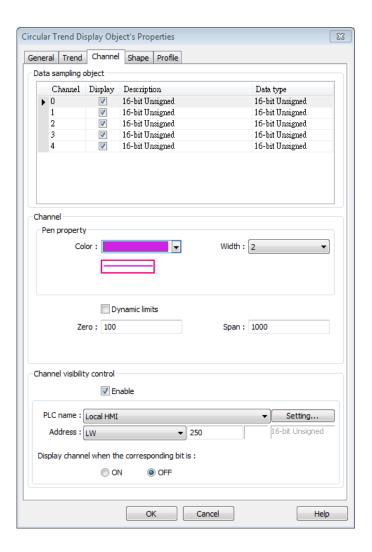


	Scioncontrol
Setting	Description
Profile	Frame
	Sets the color of the frame of the object.
	Background
	Sets the color of the background of the object.
	Show scroll controls
	The scroll controls are displayed for scrolling to view
	the sampling data of other time range. The
	minimum scrolling unit is determined by the setting
	of [Distance] in General tab. If [Show scroll controls]
	check box is not selected, the earlier data cannot be
	viewed when exceeding the specified [Distance].
	For example: Set [Distance] to 1 (hour.), then
	sampling data earlier than one hour is not displayed.
Grid	Sets the number and the color of the dividing lines.
	Y-axis
	Sets the number of divisions on Y axis.
	Font size
	Sets the size of the font which labels the time scale
	or channel scale.
	Time scale
	If enabled, displays the time scale. When the time
	length is longer than 1 hour, the scale division is 1
	hour. When the time length is set to 1 hour, the scale



	division is 15 minutes.
	Channel scale
	If enabled, displays the channel scale. The color of
	the font which labels the channel scale corresponds
	to the setting of the trend curve of each channel.
Time / Date	Time
	Sets the display format of time.
	Date
	Sets the display format of date.

#### **Channel Tab**



Setting	Description
Channel	Sets the style and the color of the trend curve, and
	the upper and lower limit of data that can be drawn
	on the trend curve. Up to 8 channels are supported
	simultaneously.



# Not selecting [Dynamic limits]

The upper and lower limits of the data are set by constants.

# **Selecting [Dynamic limits]**

The upper and lower limits are set by the designated register. When the address is LW-n, the corresponding addresses are as the following list.

Data format	16-bit	32-bit
Lower limit	LW-n	LW-n
Upper limit	LW-n+1	LW-n+2

# Channel Visibility Control

If [Enable] is selected, the bits of the designated word register will be used to show/hide each channel. First bit (Bit-0) controls the first channel; second bit (Bit-1) controls the second channel, and so on.

# Display channel when the corresponding bit is:

If [ON] is selected, when the corresponding bit is OFF, the channel is hidden. If [OFF] is selected, when the corresponding bit is ON, the channel is hidden. In the following example, the control address of channel visibility is set to LW-0 and each channel shows when the corresponding bit is OFF. If there are 5 channels, the visibility of the channels is as the following list.

Channel	Control address	Bit state	Display
0	LW_bit-000	OFF	YES
1	LW_bit-001	ON	NO
2	LW_bit-002	ON	NO
3	LW_bit-003	OFF	YES
4	LW_bit-004	OFF	YES



# 13.38. Picture View

#### 13.38.1. Overview

Picture View object plays slideshow of picture files saved in an external device such as a USB drive or SD card.

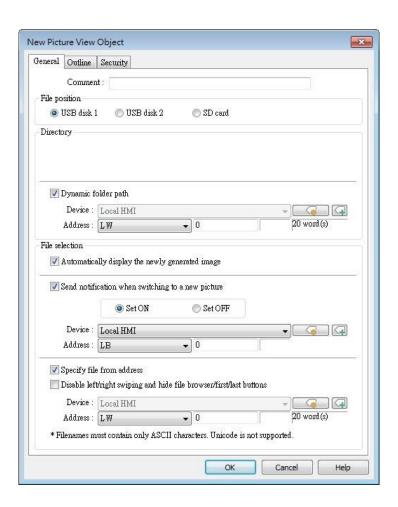
This object does not work remotely on cMT Viewer.

# 13.38.2. Configuration



Click the Picture View icon on the toolbar to open the property dialog box. Set up the properties, press OK button, and a new Picture View object will be created.

#### **General Tab**





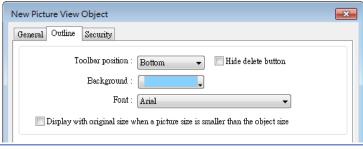
Setting	Description
File position	Select the file source of the picture files from [SD card] or
	[USB disk].
Directory	Specify the directory where the picture files are saved. The
	directory can be the one used for Video Input's capture
	feature or Function Key's screen hardcopy feature. The
	picture file saved in the external device can be
	immediately displayed.
	Dynamic folder path
	Designate folder path by a local address.
File selection	Automatically display the newly generated image
	When a new image is generated in the designated folder
	path, Picture View object will automatically display the
	new image.
	Send notification when switching to a new picture
	When [Automatically display the newly generated image]
	is selected, the state of the designated address changes to
	On/Off when the new picture is displayed on HMI.
	Specify file from address (hide toolbar)
	When enabled, the displayed picture is designated by a file
	name in a local address, and the toolbar will be hidden.



- The file name must be all in ASCII characters, and the Unicode characters are not supported.
- The supported picture formats are: .jpg, .bmp, .gif, .png.
- The size of the picture that can be displayed on an iP/iE/eMT/XE/mTV model is calculated in the following formula:
  - (image.width  $\times$  image.height) < (screen.width  $\times$  screen.height)  $\times$  4 Pictures with sizes exceeding this range cannot be displayed on HMI.
- Two-finger zoom in / out gestures are supported on capacitive touchscreens.



#### **Outline Tab**



# **Setting**

# **Description**

#### **Outline**

Specify the position, background color, and font of Picture View object. (Supported only on iP/iE/eMT/XE/mTV models.)

# Hide delete button

When selected, the delete button for deleting the viewed picture will be hidden in the Picture view object.

Display with original size when a picture size is smaller than the object size.

When selected, the picture will be displayed in its original size if it is smaller than the Picture View object. This can avoid distortion caused by enlarging the picture.

Click the icon to download the demo project. Please confirm your internet connection before downloading the demo project.



# 13.39. File Browser

#### 13.39.1. Overview

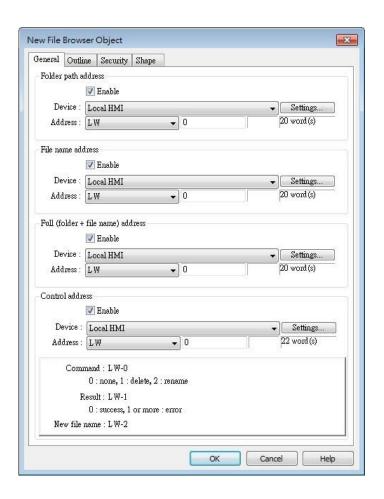
File Browser object can display filenames and their directories saved in the SD card or USB disk. Apart from browsing for the files in the external devices, the filenames and the directories selected in File Browser object can be written to the designated address.

This object does not work remotely on cMT Viewer.

# 13.39.2. Configuration



Click the File Browser icon on the toolbar, or select [Object] » [File Browser] to open a File Brower object property dialog box and set up the properties.

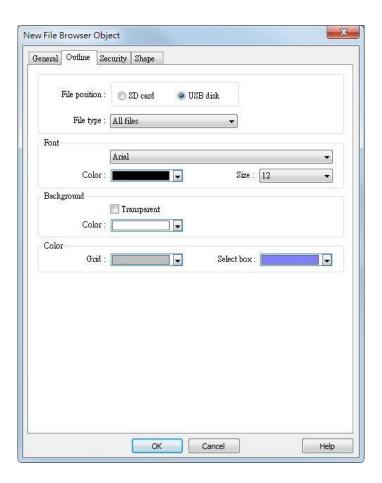




	New File Name: Control Address +2
	1 or more: Error
	0: Success
	Result: Control Address+1
	models)
	3: Select (only supported on cMT / cMT X Series
	2: Rename
	1: Delete
	0: None
	Command: Control Address
	file or changing file name in File Browser.
Control address	Designate the control address used for deleting a
name) address	selected file.
Full (folder + file	The full directory and file name of the currently
File name address	The file name of the currently selected file.
Folder path address	Current directory.
Setting	Description



#### **Outline Tab**



Setting	Description
Folder position	Select the position of the file from SD card or USB
	disk.
File type	File types to be displayed. Options include all files,
	CSV files, or image files. For cMT / cMT X Series
	models, there is also a PDF file option for use in
	conjunction with PDF reader.
Font / Background	Sat the attributes and fant of the chiest
/ Color	Set the attributes and font of the object.



- The file name and the directory of the selected file will be written to the designated address. To change file selection in File Browser to another file by changing the address, please enter the position of the file and then use the select command (=3).
- The system will read the folder path address and file name address when the HMI is restarted or when an external device is inserted to the unit. If valid data is can be read



from the designated address, the system will then automatically navigate to the appropriate directory and highlight the file according to the data read. If [Folder path address] is not enabled, the data at Full (folder + file name) address will be read.

Click the icon to watch the demonstration film. Please confirm your internet connection before playing the film.



# 13.40. Import/Export

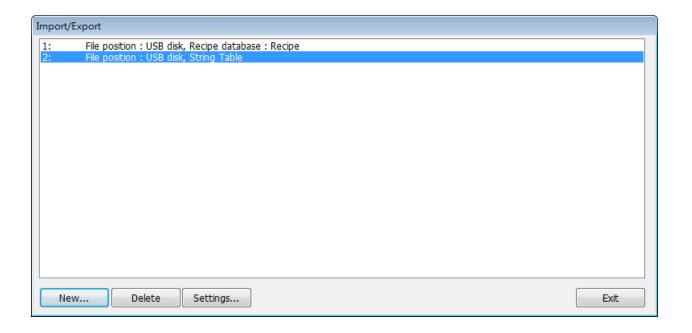
### 13.40.1. Overview

With Import/Export object, Recipe Database or String Table can be imported or exported.

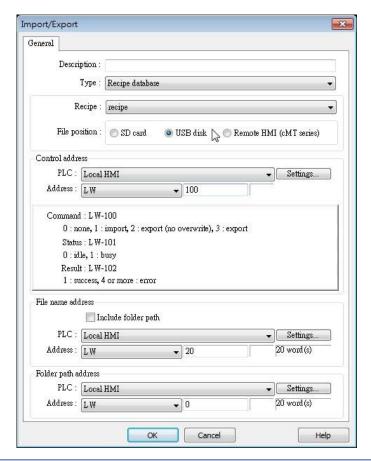
# 13.40.2. Configuration



Click the Import/Export icon on the toolbar to open the Import/Export Object management dialog box. To add an Import/Export object, click [New], set up the properties, press OK button and a new Import/Export object will be created.







Setting	Description
Туре	Select the file source from Recipe Database or
	String Table.
File position	Select the position of the file to be imported /
	exported from SD card, USB disk, or Remote HMI
	(cMT / cMT X Series). When Remote HMI is
	selected, please note that only files in cMT / cMT $\rm X$
	Series models can be imported.
Recipe	Select the recipe. This option is hidden when select
	String Table.
Control address	Designate the control address used for performing
	import/export, or displaying the result.
	Control: Control Address
	Recipe Database:
	0: None
	1: Import
	2: Export (no overwrite)



	3: Export
	String Table:
	0: None
	1: Delete
	2: Import
	4: Export (no overwrite)
	5: Export
	Status: Control Address+1
	0: Idle
	1: Busy
	Result: Control Address +2
	1: Success
	4: The file already exists, no overwriting.
	Other: Error
File name address	The name of the imported/exported file. If [Include
	folder path] is selected, the full directory and file
	name will be included at this address.
Folder path address	The directory of the imported/exported file.
Remote HMI address	When the file position is [Remote HMI (cMT / cMT
	X Series) ], please enter the remote HMI's IP
	address in this field.

# **Example 1**

The following is an example on recipe export/import settings.

Field	Setting
File position	USB disk
Recipe	Recipe_A (or other recipe)
Control address	LW-100
File name address	LW-200
Folder path address	LW-250

- 1. Create two ASCII Input objects. Set address to LW-200 and LW-250 respectively.
- 2. Enter the file name in LW-200: 2015\_recipe.csv.
- **3.** Enter the folder path in LW-250: Setting.
- 4. Use a Set Word object to write value 3 to LW-100. Then, Recipe\_A will be exported to the USB disk, in the "Setting/2015\_recipe.csv" file.





■ When performing "Export (no overwrite)" command, if the target file already exists, the export operation will be canceled, and the result value will be set to "4".

The following lists the result values and the information.

Result (HEX)	Information
0x1	Success.
0x4	File already existed and will not overwrite.
0x10	Invalid command.
0x100	Data contains non-numeric data.
0x101	Path contains invalid string "".
0x102	Communication error while updating Recipe DB.
0x103	Error while reading Recipe DB information from
	project file.
0x200	General exception.
0x201	General status error.
0x202	Import to unknown database type.
0x203	Error while validating Recipe DB table definition.
0x204	Error while validating Recipe DB table data.
0x205	Error while writing Recipe DB table definition.
0x206	Error while writing Recipe DB table data.
0x300	File error: Unknown error.
0x301	File error: Empty file name.
0x302	File error: The external device does not exist.
0x303	File error: Invalid file name (directory or special
	files), or a folder with the same name already exits.
0x304	File error: Unable to remove file.
0x305	File error: Open file stream error.
0x306	File error: Unhandled BOM.
0x307	File error: Error while parsing CSV file (incorrect
	formats).
0x308	File error: Insufficient space on the external device.
0x309	File error: Unable to find the file.
0x30A	File error: The CSV file contains over 10000 data
	rows.
0x400	Database general exception.



0x401	Database error: Unable to open table.
0x402	Database error: Unable to get rows.
0x403	Number of columns in CSV file and in Recipe DB do
	not match.
0x501	Unable to connect remote HMI.
0x503	Import from remote HMI database is prohibited.
0x504	Import from remote HMI database is not
	supported.

Click the icon to watch the demonstration film. Please confirm your internet connection before playing the film.

Click the icon to download the demo project. Please confirm your internet connection before downloading the demo project.



### **13.41.** Pie Chart

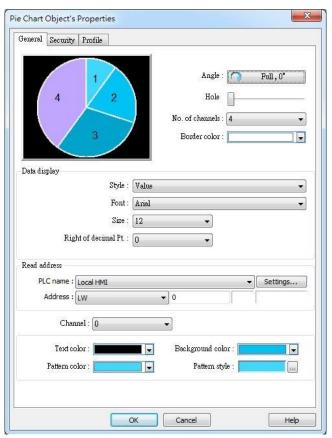
#### 13.41.1. Overview

The Pie Chart object draws a pie chart that is divided into slices to illustrate numerical proportion, according to the value of the designated read address.

# 13.41.2. Configuration



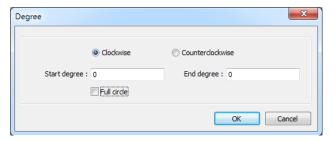
Click the Pie Chart icon on the toolbar to open the property dialog box. Set up the properties, press OK button, and a new Pie Chart object will be created.



Setting	Description
Angle	Set the [Start degree] of the chart. Choose the Chart
	to be [Clockwise] or [Counter clockwise].
	If [Full circle] isn't selected, then [End degree] must

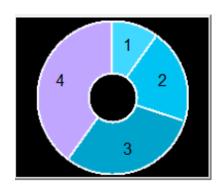


# be set.



Hole

Set the size of the hollow circle in the center of Pie Chart.

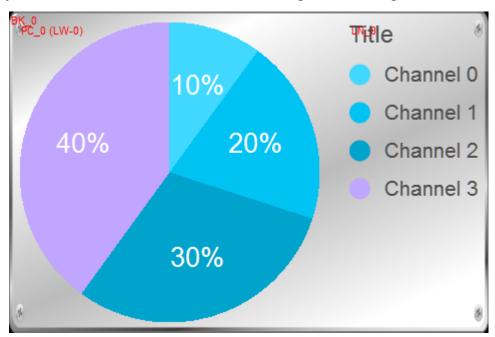


No. of channels	Set the number of channels to be displayed in the
	chart. The range is from 2 to 16.
Border color	Set the color of the border.
Data display	The [Style] can be set as [None], [Value] and
	[Percentage]. The [Font] and [Size] are for the text
	on the chart. For Value Style, the [Right of decimal
	Pt.] can set the value on the chart to be displayed
	with the decimal point. The [Right of decimal Pt.]
	option is only available for [Value] style.
Read Address	The address is for channel 1. The following
	consecutive addresses are for the rest of the
	channels. For example, if the Read Address is LW-0,
	then the Read Address for channel 2 is LW-1;
	channel 3 is LW-2and so on.
Channel	Set the [Text color], [Background color], [Pattern
	color], and [Pattern style] of the selected channel.
	The [Background color] is for the [Pattern style] that
	has background. If the [Pattern style] doesn't have a
	background, then the [Background color] doesn't
	need to be set.

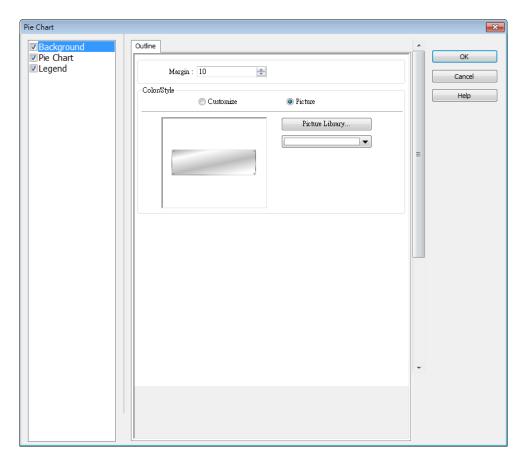


# 13.41.3. Combo Setting

cMT / cMT X Series HMI support combo setting for Pic Chart, which allows setting of multiple related objects at a time. Pic chart can be set with Background and Legend.



# **Background**

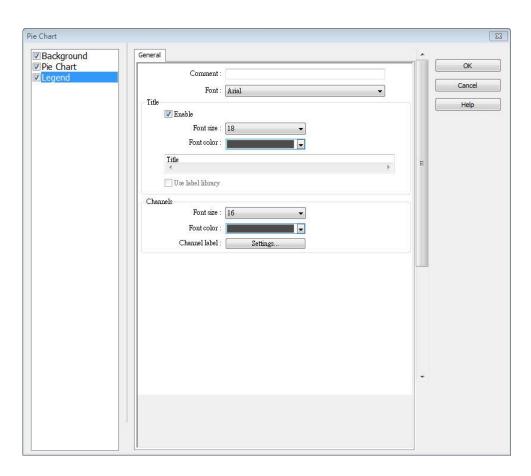




Setting	Description	
Margin	Specify the space between the background edge and	
	the objects.	
Color/Style	Customize	
	Color/Style	
	© Customize © Picture	
	Round: 10	
	Composition of Composition Com	
	Pattern : Pattern style :	
	Select a suitable background pattern and color.	
	Select a suitable background pattern and color.	
	Picture	
	Color/Style	
	Customize   Picture	

Use the default picture or choose a picture from Picture Library.

# Legend





Setting	Description
Title	Set whether to use a title for Pic Chart, and set the
	font size / font color of the title. The title can be
	selected from Label Library.
Channel	Set the channel label. When using Label Library, the
	number of the channels should be the same as the
	number of states in the library.

Click the icon to download the demo project. Please confirm your internet connection before downloading the demo project.



# **13.42.** Barcode

# 13.42.1. 2D Barcode Display

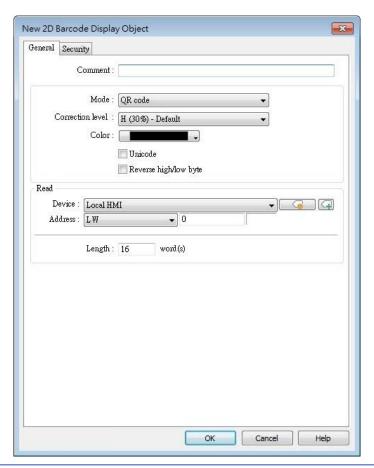
#### 13.42.1.1. Overview

The 2D Barcode Display object transfers the information from the read address into QR Code or Aztec Code.

# 13.42.1.2. Configuration



Click the 2D Barcode Display icon on the toolbar to open the property dialog box. Set up the properties, press OK button, and a new 2D Barcode Display object will be created.



Setting	Description
Mode	Supports QR code, Aztec code, Data Matrix.



Correction level	2D barcodes have error correction capability to restore data if the barcode is dirty or damaged.  QR code
	Four correction levels are available: L, M, Q, and H. The data restoration rate is listed below. (The data restoration rate for total codewords. Codeword is a unit that constructs the data
	area.)    Correction Level
	Aztec code supports error correction levels from 5% to 95%. Specifying a higher correction value results in a larger printed symbol and increases accuracy.
Color	Set the 2D barcode color.
UNICODE	By default, the 2D barcode is generated via ASCII encoding. If this check box is selected, the 2D barcode is generated via UNICODE encoding.  For characters that are not ASCII defined English alphabets or numbers, for example, Chinese or Korean characters, please select the Unicode check box.
Reverse high/low byte	By default, the 2D barcode is displayed in high byte then low byte order. With this option selected, the 2D barcode is displayed in a reverse order, low byte then high byte.
Read address	The 2D Barcode Display object will display the 2D barcode generated from the information entered by the read address. The word length limit of QR code: 1 ~ 1024.  The word length limit of Aztec code and Data Matrix: 1 ~ 2048.

# 13.42.2. Push Notification Barcode Display

### 13.42.2.1. Overview

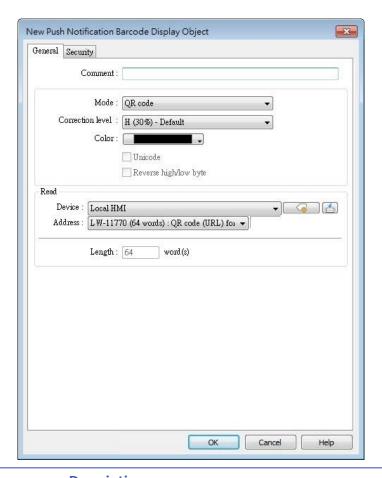
Push Notification Barcode Display object displays the QR code needed for setting up EasyAccess 2.0 push notification via messaging applications.

# 13.42.2.2. Configuration



Click the [Object] » [Barcodes] » [Push Notification Barcode Display] to open the property dialog box. Set up the properties, press OK button, and a new Push Notification Barcode Display object will be created.



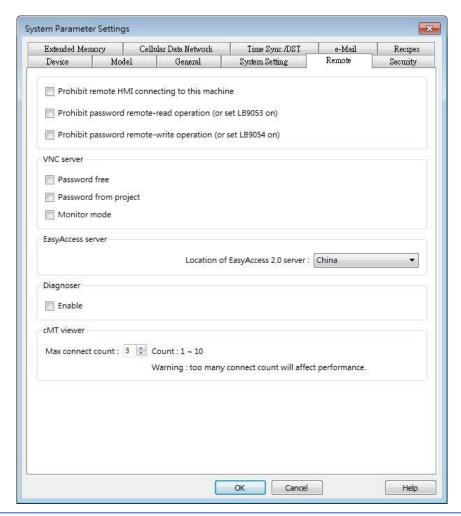


Setting	Description
Mode	Supports QR code, Aztec code, Data Matrix.
Correction level	2D barcodes have error correction capability to restore data if the barcode is dirty or damaged.  QR code  Four correction levels are available: L, M, Q, and H. The data restoration rate is listed below. (The data restoration rate for total codewords. Codeword is a unit that constructs the data area.)  Correction Level  L
	Aztec code Aztec code supports error correction levels from 5% to 95%. Specifying a higher correction value results in a larger printed symbol and increases accuracy.
Color	Set the 2D barcode color.
UNICODE	Cannot be changed by default.
Reverse high/low byte	Cannot be changed by default.



**Read address** Cannot be changed by default.

## **System Parameter Settings**



Setting	Description
EasyAccess	Global: Supports push notification features of Wechat,
Server	Facebook, and Line. China: Supports push notification features of WeChat only.

# **Push Notification Settings**

After downloading the project file to HMI, the QR code will be shown on HMI screen. For more information on setting up push notifications in WeChat, Facebook, and LINE, please refer to the link below (see version 2.8 and later).

https://support.ihmi.net/ea20/release-notes



### 13.42.3. Barcode Scanner (Android Camera)

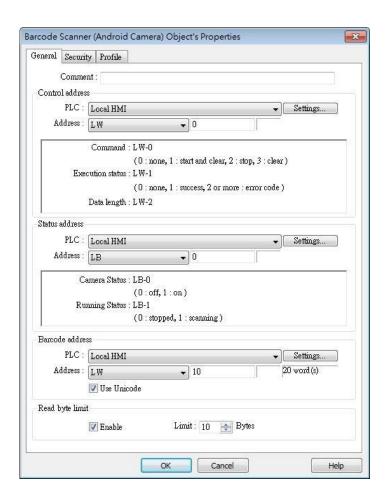
#### 13.42.3.1. Overview

By connecting an Android device (smartphone/tablet) equipped with a camera to a cMT / cMT X HMI using cMT Viewer installed on the Android device, the camera can be used to scan 1D or 2D barcodes.

### 13.42.3.2. Configuration



Click the Barcode Scanner icon on the toolbar or click [Objects] » [Barcodes] and then select [Barcode Scanner]. Configure the parameters and click OK; a Barcode Scanner object will be created.



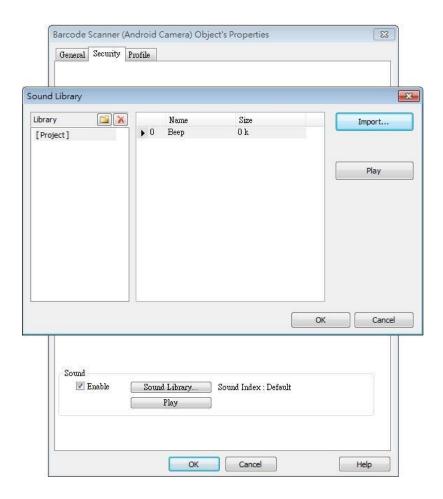




	Scanner.
	0: None
	1: Start and Clear
	2: Stop
	3: Clear
	Control address + 1: Shows Execution Status.
	0: None
	1: Success
	2 or more: Error Code
	Control address + 2: Shows data length scanned.
Status address	Status address: Shows camera status is On / Off.
	0: Off
	1: On
	Status address + 1: Shows whether scanning is
	ready.
	0: Stopped
	1: Ready for scanning
Barcode address	The address that stores the data read, UNICODE is
	allowed.
Read byte limit	If the data read exceeds this setting, the execution
	status turns to 2 (error code).



### **Security Tab**



Setting	Description
Sound	If Enable is selected, when data is read, a sound is
	emitted. The supported sound file format is .wav.



- Barcode Scanner is currently supported on cMT-SVR and cMT3151 models. Barcode
   Scanner cannot be opened using simulation mode or cMT Viewer.
- Supports: EAN/UPC, Code 128, Code 39, Interleaved 2 of 5 and QR Code.
- On the device, if other applications are also using the camera, or the camera is locked,
   cMT Viewer may not operate properly.
- In the project, when multiple cMT Viewer devices are connected, since the same address is shared between the devices, the devices will simultaneously scan if they are displaying the same window with Barcode Scanner.



## **Example 1**

The following demo project shows how to scan QR code using a tablet.

1. At the beginning, the display is dark.



Tap Start button, the status of Scanning turns ON, the display turns bright, and is ready for scanning.



3. When a QR code is read, the Execute Status turns 1, and the QR code is captured, its content will be displayed in Barcode Address group box. Unicode is also supported.





4. If the size of the data read exceeds the maximum allowable size set in Read Byte Limit (10 bytes in this project), the Execution Status turns to 2 (error code). The exceeding part will still be displayed in the ASCII objects in Barcode Address group box, since the data length displayed depends on the ASCII object settings (20 words in this project).



5. After changing to another page, Scanning turns OFF, the parameters are reserved. The parameters will be cleared when next time Start button is tapped, or Clear button is tapped.





Click the icon to download the demo project. Please confirm your internet connection before downloading the demo project.



# 13.43. String Table

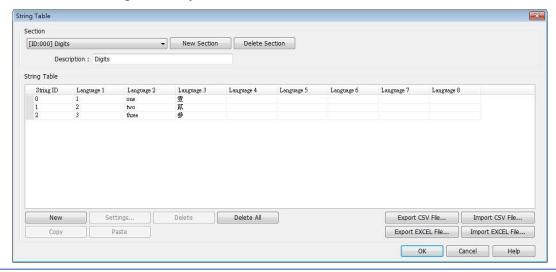
#### 13.43.1. Overview

By pre-configuring the texts and their corresponding numbers in the String Table, the text can be changed dynamically on HMI. String Table can also be used in a multi-language environment.

# 13.43.2. Configuration



Click [Project] » [String] to open the property dialog box. Set up the properties, press OK button, and a new String Table object will be created.



Setting	Description
Section	A list of all the existing String Tables.
	[New Section] Add a new String Table.
	[Delete Section] Delete the selected String Table.
New	Add a new string in the table.
Settings	Set the content of the selected string.
Export CSV File	Export all the existing String Tables as a *.csv file.
Import CSV File	Import *.csv file into the String Table.
Export EXCEL File	Export all the existing String Tables as a *.xls file.
Import EXCEL File	Import *.xls file into the String Table.



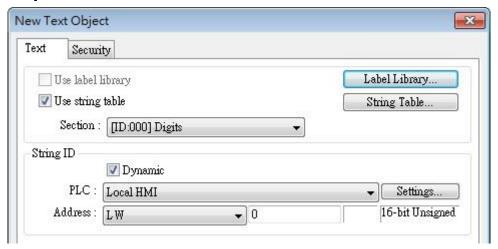
The font of each language in the String Table must be specified in Label Text Library.



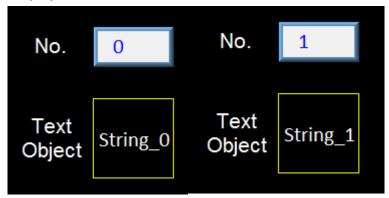
Number of rows from all sections combined is limited to 10000.

# **Example 1**

- 1. Create a String Table using the same settings as the preceding figure.
- 2. Create a Text object, select [Use string table] check box. In String ID group box, select [Dynamic] and set read address to LW-0.



- 3. Create a Numeric object, set address to LW-0.
- 4. When the value in LW-0 is 0, the No. 0 string is displayed; when the value in LW-0 is 1, the No. 1 string is displayed.





### **13.44.** Database

### 13.44.1. Database Server

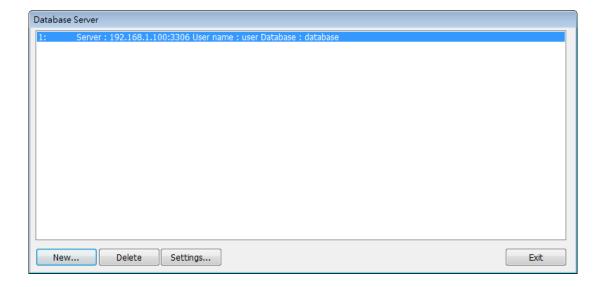
#### 13.44.1.1. Overview

Database Server object enables connection with MySQL or MS SQL database server, allowing users to send data log or event log to the database, or use SQL Query to access data from the database.

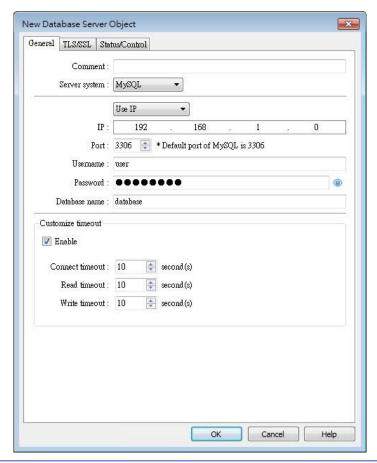
# 13.44.1.2. Configuration



Click the Database Server icon on the toolbar to create a Database Server object. Or, click [Data/History] » [Database Server] in the menu.







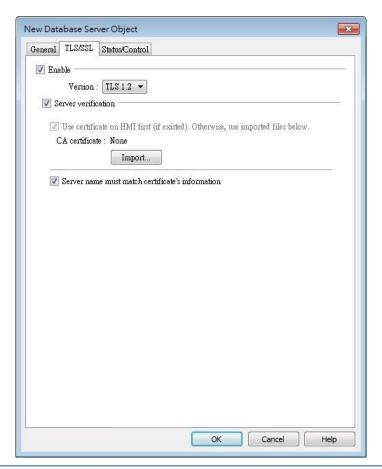
Setting	Description
Server system	Supported server systems: MySQL, MS SQL Server
IP	Enter the IP address of the database.
Use domain name	Use domain name ▼  Domain name : 127.0.0.1
	Supports designating a server using a domain name.
Use server name	Server system: MS SQL Server   Use server name   e.g. HOST/SQLEXPRESS  Server name: PC_NAME/UNSTANCE_NAME
	This option is only available when the selected server
	system is MS SQL Server. An instance stands for a
	communication port number, and the port number can
	be used to identify multiple database servers on the
	same computer.
	A server name can be in one of the following formats.
	<computer name="">\<instance name=""></instance></computer>



	<ul><li><computer name=""> (Connect to Default Instance :</computer></li></ul>
	MSSQLSERVER)
	<ip address="">\<instance name=""></instance></ip>
	<ip address=""> (Connect to Default Instance :</ip>
	MSSQLSERVER)
Port	Enter the port number of the database.
Username	Enter the username for connecting the database.
	The maximum is 32 words.
Password	Enter the password for connecting the database.
	The maximum is 32 words.
Database name	Enter the name of the database for collecting historical
	data.
<b>Customize timeout</b>	Timeouts for the following operations can be customized.
	Connect timeout
	The timeout for connection attempts. Connection
	attempts will be terminated when the timeout is
	reached.
	Read timeout
	The timeout for read operations.
	Write timeout
	The timeout for write operations.



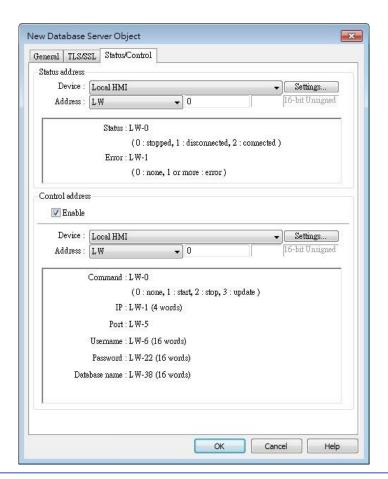
# TLS/SSL Tab



Setting	Description
Enable	Enable TLS/SSL security. TLS version can be selected
	from: TLS 1.0, TLS 1.1, and TLS 1.2.
Server verification	Enable
	Verify whether the server certificate is signed by CA
	(certificate authority) certificate. Server certificate is
	sent from server during connection.
	Server name must match certificate's information
	Verify whether the server's domain name or IP
	matches the records in the server certificate.
	Domain name and IP records are stored in Subject
	Alternative Name of the certificate.



# **Status/Control Tab**



### **Setting**

### **Description**

### Status address

LW-n: Displays the connection status of Database

#### Server.

Value	Description
0	Not attempting to connect to
	database.
1	Failed to connect to database.
2	Connection succeeded.

LW-n+1: Error indicator.

Value	Description
0	No error.
1	Unknown error.
2	Failed to connect to database.
3	Database blocks the
	unauthorized connection.
4	Incorrect database name.
5	Invalid domain name.
6	Exceeded connection limit.

# **Control address**

LW-n: Controls the operation of Database Server.

Value	Description
0	Ready
1	Start
2	Stop



3 Update	
LW-n+1: Sets the IP address of the database.	
LW-n+5: Sets the port number of the database.	
·	
LW-n+6: Sets the username for connecting database.	
LW-n+22: Sets the password for connecting database.	
LW-n+38: Sets the name of the database for collecting	
historical data.	



If sampled data is successfully synchronized to the SQL database, three tables will be generated in the database, and the sampled data is saved in \* data table.

Table	Description
<hmi name="">_<datalog name="">_data</datalog></hmi>	Saves data sampling
<pre><hmi name="">_<datalog name="">_data_format</datalog></hmi></pre>	System folder
<pre><hmi name="">_<datalog name="">_data_section</datalog></hmi></pre>	System folder

■ When synchronizing event log, the three tables generated in the database are listed as the following table, and the event log is saved in \*\_event table.

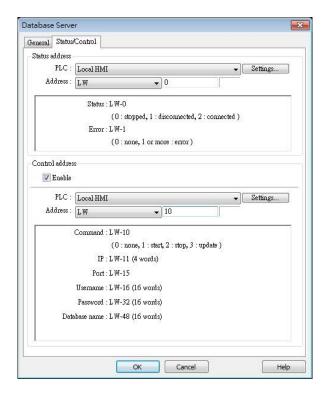
Table	Description
<hmi name="">_event</hmi>	Saves event log
<pre><hmi name="">_event_log</hmi></pre>	System folder
<pre><hmi name="">_event_update_time</hmi></pre>	System folder

- If the content of data sampling / event log, such as data format or event message, is changed and downloaded to HMI, please delete the tables listed above first, and then the new content will thus be effective.
- Azure SQL Server is supported. To use Azure SQL Server, select MS SQL as server system and use domain name. Azure SQL Server has firewall settings, please add the client into whitelist, and see how to configure by opening the link below: https://docs.microsoft.com/en-us/azure/azure-sql/database/single-database-manage#ma nage-an-existing-server

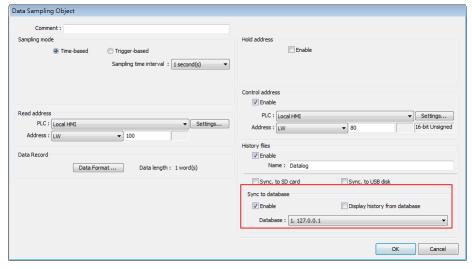
# **Example 1**

 Create a Database Server object, set Status Address to LW-0, and Control Address to LW-10.

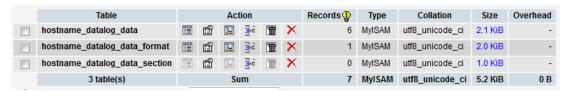




2. Create a Data Sampling object, in [Sync. to database] group box select [Enable], and set Control Address to LW-80, to update or clear HMI historical data.



- 3. If the database is successfully connected, the status indicator LW-0 displays 2 (connection succeeded), and the error indicator LW-10 displays 0 (no error).
- Write 2 in LW-80 (sync. data). Open SQL database, the data can be found in table <HMI NAME>\_<DATALOG NAME>\_data.





Click the icon to watch the demonstration film. Please confirm your internet connection before playing the film.

Click the icon to download the demo project. Please confirm your internet connection before downloading the demo project.



### 13.44.2. SQL Query

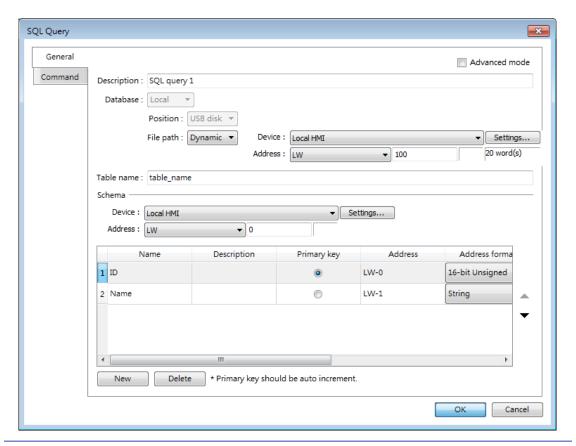
### 13.44.2.1. Overview

SQL Query can exchange data with SQL database. Before enabling SQL Query, please configure Database Server.

### 13.44.2.2. Configuration



Click [Data/History] » [SQL Query] to open the settings dialog box. Configure the parameters and click OK; a SQL Query will be created.



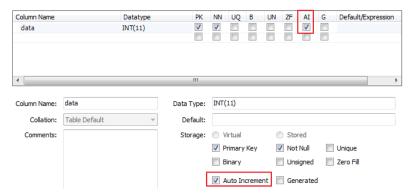
Setting	Description
Advanced Mode	Without [Advanced Mode] selected:
	Click [New] to add a new row or click [Import from
	server] to import an existing database.
	With [Advanced Mode] selected:
	Manually enter syntax in Command tab to control
	MySQL/MS SQL database. Please note that returning
	from Advanced Mode to General Mode is not



	possible.
Description	User's description about this query.
Database	Select the source database to read from.  Local: The source database is the SQLite database
	stored in a USB disk or SD card attached to HMI.  Click the icon to watch the demonstration film.
	Please confirm your internet connection before playing the film.
	Remote: The source database is the designated Database Server.
File path	Use [Static] or [Dynamic] directory for a local database. When [Static] is selected, please enter the directory in this dialog box. When [Dynamic] is selected, please designate an address as the data source for the file path.
Table name	Enter the name of this query table.
Schema	The data read from database will be filled into the corresponding address specified in the schema.  Please manually set Address Format after reading data.

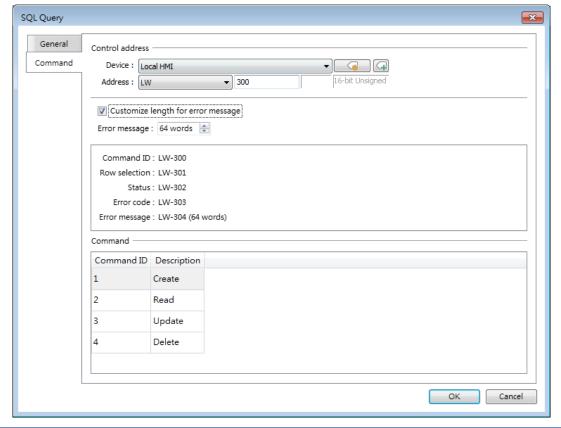


- A Primary Key should contain only numeric values.
- In MySQL, Auto Increment must be enabled for Primary Key.





#### **Command Tab**



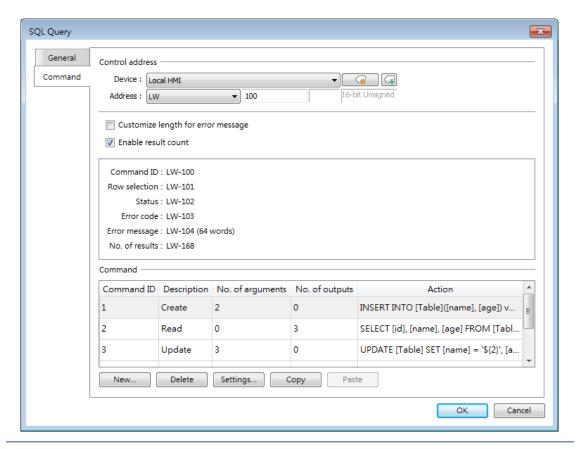
Setting	Description
Control address	Designate five consecutive registers to execute SQL commands and show results. Of the results, the length of error message can be customized.
Command	In standard mode (without checking Advanced mode box), the four basic commands of SQL (Create, Read, Update, and Delete) and their command ID are shown.

Click the icon to download the demo project. Please confirm your internet connection before downloading the demo project.

# 13.44.2.3. Advanced Mode

In the Command table in Advanced Mode, [No. of arguments], [No. of outputs], and [Action] columns can be found. Outputting multiple results to consecutive addresses at a time is possible.

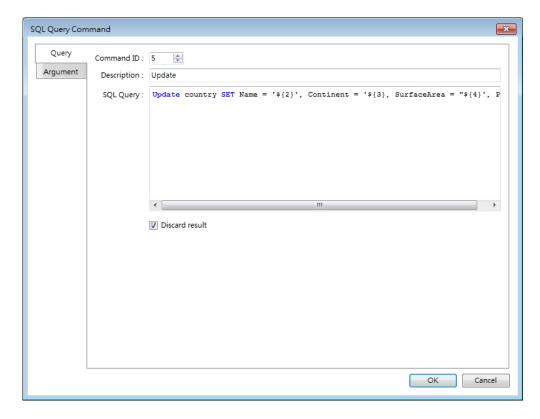




Setting	Description	
Control address	Specify the ID number used to give this command.	
Row selection	Specify a row.	
Status	Displays the execution status. See Ch13.44.2.4.	
Error code	Displays the execution result. See Ch13.44.2.5.	
Error message	ror message Displays the error message sent from database	
	server. The default length of the error message is 64	
	words. Customizing the length of the error message	
	is also possible, and the upper limit is 200 words.	
No. of results	Displays the number of output results.	
New / Delete /	Add, delete, set, or copy a SQL Query command.	
Settings / Copy		



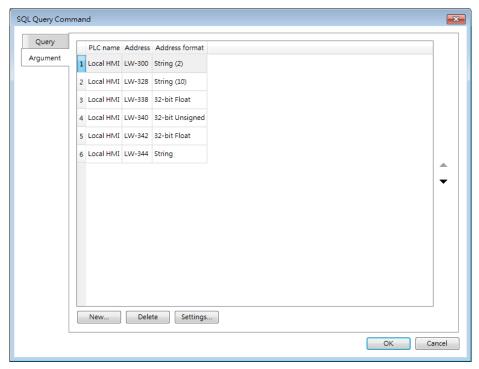
# **Query Tab**



Setting	Description
Command ID	Specify the ID number used to give this command.
Description	Enter the description of this command.
SQL Query	Enter the syntax for this command. An argument
	should be enclosed in braces: \${argument no.}
Discard result	With this checkbox selected, the result of executing
	this command will not be shown in SQL Query Result
	Viewer object. This checkbox can be selected for
	commands that are done directly to the database
	without the need for returning a result, such as
	INSERT INTO, UPDATE, DELETEetc.



#### **Argument Tab**

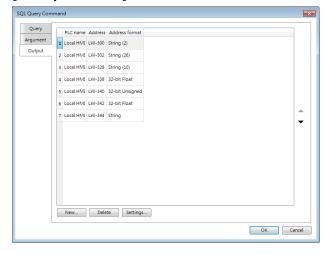


If argument is used in the syntax of a command in [Query] tab, the system will refer to the address specified in this tab according to the argument number enclosed in \${argument no.}.

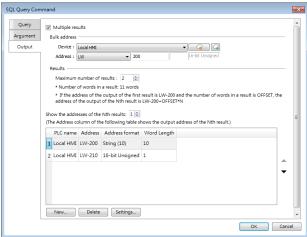
#### **Output Tab**

After reading database under Advanced Mode, the result will be stored in the addresses specified in this tab. Selecting [Multiple results] option can output multiple query results to consecutive addresses at a time.

#### [Multiple results] not selected



#### [Multiple results] selected



Setting	Description
Bulk address	Designate the start address for bulk output of
	results. The upper limit of data records is 10000



	(maximum number of results x number of columns).
Maximum number The upper limit is 1000 results. Suppose maximum	
of results	number of results is set to 100, and the returned
	number of query results is 300, then:
	When [Row selection] is set to 20, the 20 <sup>th~</sup> 119 <sup>th</sup>
	results are output to bulk addresses.
	When [Row selection] is set to 260, the 260 <sup>th~</sup> 299 <sup>th</sup>
	results are output to bulk addresses.
Show the	Shows the output address of the N <sup>th</sup> result in the
addresses of the	Address column of the table below this setting.
Nth results	If the address of the output of the first result is
	LW-200 and the number of words in a result is
	OFFSET, the address of the output of the N <sup>th</sup> result is
	LW-200+OFFSET*N.

Click the icon to download the demo project. Please confirm your internet connection before downloading the demo project.

# **13.44.2.4.** Status

Value	Meaning
0	Normal
1	Query result exceeds 1000 records. Using LIMIT clause can
	constrain the number of rows in one page.

# **13.44.2.5.** Error Code

Error Code	Meaning
0	No mistakes
1	Unknown error
2	Invalid command
3	Database Server is not connected yet
4	Argument cannot be read
5	Cannot write and output
6	Incorrect number of arguments
7	Error in MySQL, please read error message
8	Unsupported datatype
9	Number of columns exceeds the limit
10	Number of rows exceeds the limit
11	Unable to read local database directory
12	Name of local database does not exist



13	Internal error	
----	----------------	--

# 13.44.2.6. Converting Datatype

Converting datatype as shown in the following table will take place after reading MySQL database. If conversion cannot run properly, error code 5 will show. For example, when converting MySQL's INT into EasyBuilder Pro's 16-bit Unsigned, if the value exceeds the limit of 16-bit Unsigned, error code 5 will show.

MySQL data format	EasyBuilder Pro datatype
TINYINT	16/32-bit BCD
SMALLINT	16/32-bit HEX
MEDIUMINT	16/32-bit Binary
INT	16/32-bit Signed
BIGINT	16/32-bit Unsigned
BIT	
FLOAT	32-bit Float
DOUBLE	
DECIMAL	
DATETIME	String
CHAR, BINARY	
VARCHAR, VARBINARY	
TINYBLOB, TINYTEXT	
BLOB, TEXT	
MEDIUMBLOB, MEDIUMTEXT	
LONGBLOB, LONGTEXT	



#### 13.44.3. SQL Query Result Viewer

#### 13.44.3.1. Overview

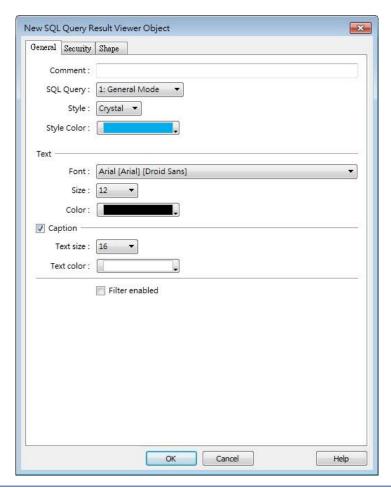
SQL Query Result Viewer shows the results obtained by running SQL Query.

# 13.44.3.2. Configuration



Click on [Data/History] » [SQL Query Result Viewer] to open the settings dialog box. Configure the parameters and click OK; a SQL Query Result Viewer will be created.

#### **General Tab**



Setting	Description
Comment	User's comment about this result viewer.
SQL Query	Select an existing SQL Query to show its result.
Style/ Style Color	Select a style and a color for this result viewer.
Text	Set the font, font size, and font color for the texts
	shown in this result viewer.



Caption	Set the font size and font color for the caption of this result viewer.
Table	This group box opens when selecting Default as
	style. The attributes of the result query table can be
	configured.
Filter enabled	With this checkbox selected, entering keywords in
	SQL Query Result Viewer to search for specific text is
	possible.



# 13.45. Dynamic Scale

#### 13.45.1. Overview

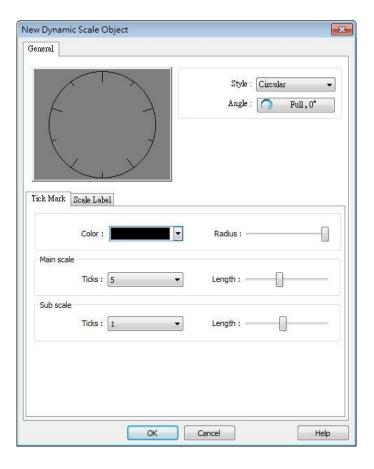
Dynamic Scale offers customizable tick marks and scale labels and can be used together with objects such as Trend Display, Bar Graph..., etc.

# 13.45.2. Configuration



Click the Dynamic Scale icon on the toolbar to open a Dynamic Scale object property dialog box. Set up the properties, press OK button, and a new Dynamic Scale object will be created.

#### **General Tab**



Setting	Description	
Style	Select the style from [Circular], [Horizontal], or [Vertical]. If select	
	[Circular], set the [Direction] and [Degree].	





#### **Direction**

Select from [Clockwise] or [Counterclockwise].

#### Degree

If [Full circle] is selected, set the start degree.

If [Full circle] is not selected, set the start and end degree.



#### **Tick Mark**

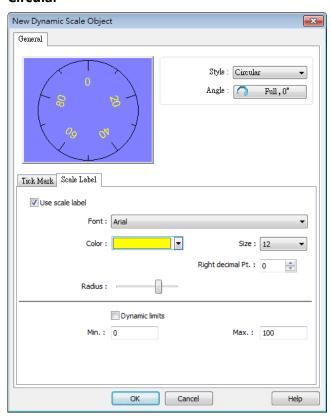
Select the color of the tick mark, and set the number of ticks for the main and sub scale (major and minor tick mark).

For [Circular] style, the length of the major and minor tick mark, and the radius of the circular tick mark can be set.

#### **Scale Label**

Displays major tick labels.

#### Circular



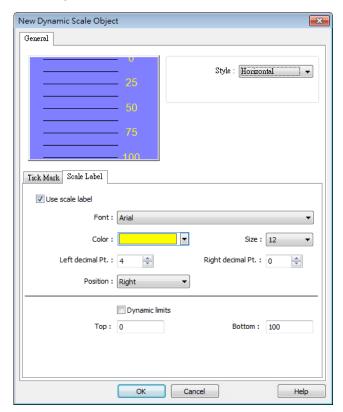
Set the font, font color, font size, and decimal point of the scale



label.

Set the radius start from the center of the object to the position to place the scale label.

#### Virtical / Horizontal



Set the font, font color, font size, and decimal point of the scale label.

Set the position to display the scale label.

The Max. and Min. limits of the scale label can be specified. If [Dynamic limits] is selected, the Max. and Min. limits can be set by the designated word addresses.



Click the icon to download the demo project. Please confirm your internet connection before downloading the demo project.



# 13.46. Dynamic Drawing

#### 13.46.1. Overview

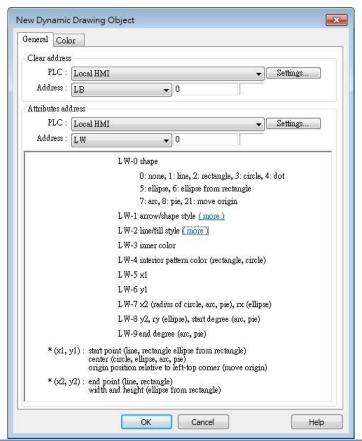
Dynamic Drawing object enables drawing a shape in a specified region on HMI screen at run time. The shape can be a line, a rectangle, a circle, or a dot. By setting the Attributes Addresses, the style and the color of the shape can be customized.

#### 13.46.2. Configuration



Click the Dynamic Drawing icon on the toolbar to open a Dynamic Drawing object property dialog box. Set up the properties, press OK button, and a new Dynamic Drawing object will be created.

#### **General Tab**



Setting Description
Clear Address Clears the drawing.



**Attributes Address** 

Changes the attributes in the drawing.

Entering different values in different Attributes Addresses brings different effects, as shown in the following table.

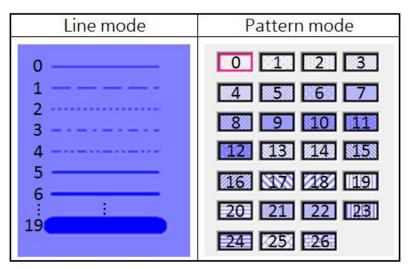
Attributes Address	Attributes Address+0	Attributes Address+1		Attributes Address+2	Attributes Address+3	Attributes Address+4
Default	0	Ones	Tens		Customizable	Customizable
		0: Non-arrow	0: Small	0: Solid line		
		1: Single-ended arrow (Hollow)	1: Large	1: Dashed line		
		2: Double-ended arrow (Hollow)		2: Dotted line		
Line	1	3: Single-ended arrow (Solid)		3: Dash Dot line	Line color	
		4: Double-ended arrow (Solid)		4: Dash Dot Dot line		
				5 and up: Solid line with thicknesses greater than 2		
Destande	2	0: Hollow		Drawn in Line mode	Rectangle color	Interior pattern
Rectangle	Rectangle 2	1: Solid		Drawn in Pattern mode	Rectangle color	color
Circle	3	0: Hollow		Drawn in Line mode	Circle color	Interior pattern
Circle	3	1: Solid		Drawn in Pattern mode	Circle color	color
Dot	4				Dot color	
Ellipse	5	0: Hollow		Drawn in Line mode	Ellipse color	Interior pattern
Lilipse	3	1: Solid		Drawn in Pattern mode	Lilipse coloi	color
Ellipse from	6	0: Hollow		Drawn in Line mode	Ellipso color	Interior pattern
Rectangle	O	1: Solid		Drawn in Pattern mode	Ellipse color	color
Arc	7			Drawn in Line mode	Arc color	
Pie	8	0: Hollow		Drawn in Line mode	Pie color	Interior pattern
FIG	O	1: Solid		Drawn in Pattern mode	FIE COIOI	color
Move Origin	21					

Attributes Address	Attributes Address+0	Attributes Address+5	Attributes Address+6	Attributes Address+7	Attributes Address+8	Attributes Address+9
Default	0					
Line	1	Start point X	Start point Y	End point X	End point Y	
Rectangle	2	Left-top point X	Left-top point Y	Right-bottom point	Right-bottom point Y	
Circle	3	Center point X	Center point Y	Radius		
Dot	4	Dot X	Dot Y			
Ellipse	5	Center point X	Center point Y	Radius on the X	Radius on the Y	

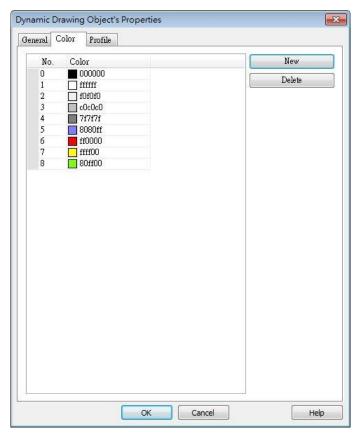


				axis	axis	
Ellipse from Rectangle	6	Left-top point X	Left-top point Y	Width	Height	
Arc	7	Center point X	Center point Y	Radius	Start degree	End degree
Pie	8	Center point X	Center point Y	Radius	Start degree	End degree
Move Origin	21	New origin X	New origin Y			

The values in [Attributes Address+2] represent different Line or Pattern styles, as shown in the following table.



# **Color Tab**



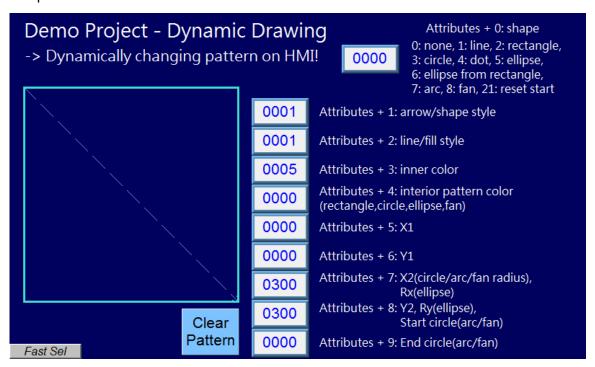
Setting	Description
New	Adds a color to be used in the drawing.
Delete	Deletes the selected color.



# **Example 1**

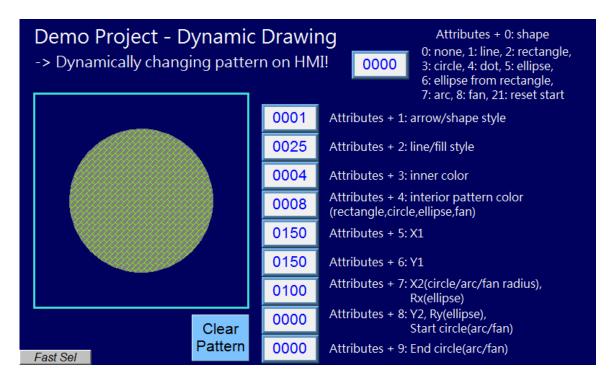
The following demo project demonstrates how to dynamically draw an arrow or a circle on HMI screen. To build the project, follow these steps:

- Create a Dynamic Drawing object, set Clear Address to LB-0, and Attributes Address to LW-0.
- 2. Create a Toggle Switch object, set address to LB-0, and select Toggle as switch style, for clearing the drawing.
- Create 10 Numeric objects, set addresses to LW-0~LW-9, for specifying the attributes in the drawing.
- 4. Run simulation or download the project to HMI to see the result. By entering 1 in LW-0, a line is drawn, and entering different values in LW-1~9 can change the style, the color, and the position of the line.



5. Press Clear Pattern button, and enter 3 in LW-0, a circle is drawn, and entering different values in LW-1~9 can change the style, the color, and the position of the circle.







- Before using Attributes Address, please define [Attributes Address + 1] ~ [Attributes Address + 9]. The system will reset the Attributes Address, after it is used.
- If the drawing is not cleared, the new drawing will overlap the previous one, and the maximum acceptable number of drawings in a Dynamic Drawing object is 1000.
- The maximum number of line styles is 19, which means the maximum thickness of a solid line is 16. The style numbers that exceed 19 will be displayed as 19.
- Find the color number in Color tab.
- The range of the start and end degree for Arc and Pie is 0 to 360 degrees.
- Origin position is relative to left-top corner (0,0). Giving "move origin" command will make (x1, y1) the new origin, and x1, y1 will keep on accumulating until being reset to (0,0) by clearing the drawing.
- If cMT Viewer is used to monitor a Dynamic Drawing object on a cMT / cMT X model, then PLW address is recommended to be used as the Attribute Address, so that drawing commands can be given to the cMT Viewer device's PLW addresses. This prevents the issue where the HMI and the cMT Viewer device show different drawing results.
- Click the icon to download the demo project. Please confirm your internet connection before downloading the demo project.



# 13.47. PDF Reader

#### 13.47.1. Overview

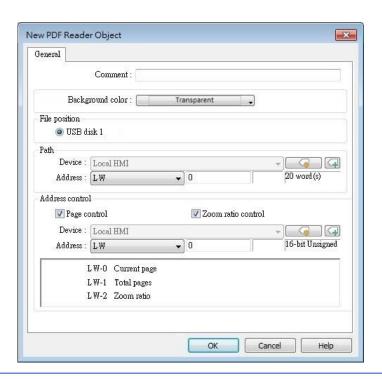
PDF Reader object enables viewing of PDF documents on HMI.

# 13.47.2. Configuration



Click the PDF Reader icon on the toolbar to create a PDF Reader object. Or, click [Object] » [Media] » [PDF Reader] in the menu.

#### **General Tab**



Description
Select the position where the PDF file is stored.
The directory of the PDF file stored in the external
device.
Current page
The page number of the current page. Set a value to
change the current page.
Total pages
Total number of pages of the PDF file.



Zoom ratio	Current zoom ratio. Set a value to change the zoom	
	ratio. Unit: %; i.e., the number 100 indicates 100%	
	display (1:1).	



- PDF Reader cannot be opened using simulation mode or cMT Viewer.
- The PDF files protected by passwords or restrictions cannot be read using PDF Reader.
- CPU loading may rise when multiple PDF Reader objects are opened simultaneously.
- When entering a page number in the Page Control register under multi-page view mode, the specified page will be opened in single-page view.
- Two-finger zoom in / out gestures are supported on capacitive touchscreens.

Click the icon to download the demo project. Please confirm your internet connection before downloading the demo project.



#### 13.48. Table

#### 13.48.1. Overview

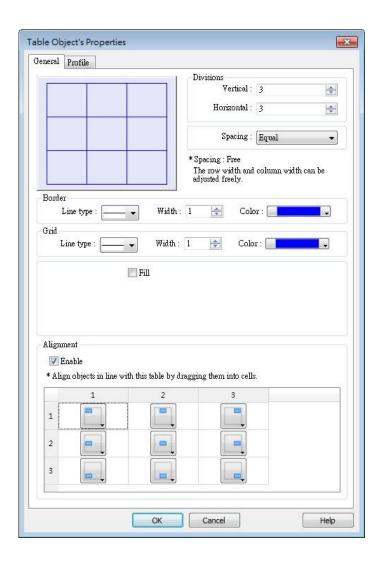
Table object allows users to draw a table in the project window and customize the border, grid, and pattern of the table.

# 13.48.2. Configuration



Click the Table icon on the toolbar to create a Table object. Or, click [Object] » [Table] in the menu.

#### **General Tab**





Setting	Description
Preview Window	Displays the settings result.
Vertical	Sets the number of columns in the table. Range:
	1~255
Horizontal	Sets the number of rows in the table. Range: 1~255
Spacing	The available options are [Equal] and [Free]. When
	[Free] is selected, the user can manually adjust the
	column width or row height in the editing window.
Border	Sets the type, width, and color of the border. [Line
	width] setting is available only when Solid line type
	is selected. The range of width is $0^{\sim}8$ . The line will
	become invisible when the width is set to 0.
Grid	Sets the type, width, and color of the grid. [Line
	width] setting is available only when Solid line type
	is selected. The range of width is $0^{\sim}8$ . The line will
	become invisible when the width is set to 0.
Fill	Sets the pattern style and color.
Alignment	By dragging the objects into the cells in the Table,
	the objects can align to the preset position. Different
	alignments can be set for each cell in the Table, by
	default the objects are center-aligned, and nine
	different alignments can be selected as shown in the
	screenshot of the settings window.
	With Alignment enabled, the maximum number of
	vertical / horizontal divisions is 32.
	Please note that this setting does not support the
	alignment of multiple groups of objects.



# **13.49. VNC Viewer**

#### 13.49.1. Overview

VNC Viewer can run on HMI to control a PC or a device remotely. VNC server must be installed on the remote device to be connected. On HMI the user can monitor and control the remote device.

## 13.49.2. Configuration



Click on the VNC Viewer icon on the toolbar or select [Objects] » [Media] » [VNC Viewer] to open the settings dialog box. Configure the parameters and click OK; a VNC Viewer object will be created.

#### **General Tab**







	connected.
Port	Enter the port number of the remote device to be
	connected.
Default Password	Enter the VNC password to log in the VNC server of
	the remote device. If Default Password is enabled,
	when connecting the remote device, VNC Viewer
	will automatically use the password specified here
	to log in, and the user doesn't need to enter the
	password.
Color level	Select from four color levels: Full (all available
	colors), Medium (256 colors), Low (64 colors), Very
	low (8 colors).
	Auto select (not all servers support this function)
	Allow VNC Viewer to automatically detect and select
	the color level supported by the server used.
	Enable run-time modification in [Control] function
	Select color level or decide whether to enable [Auto
	select] in HMI runtime using the control addresses
	that can be specified in the Control tab in the VNC
	Viewer settings dialog box.
Title bar	Enable
	When [Enable] is selected, a field shows for entering
	the caption in the title bar. The caption is limited to
	ASCII characters, and the font cannot be customized.
	The caption can be selected from Label Tag Library.
	Only when the title bar is enabled can the VNC
	Viewer window be moved or resized by dragging.
Option	Enable input from system keypad
	With this option selected, a keypad icon shows in
	the upper right corner of the VNC Viewer object,
	and the system keypad can be opened by clicking
	this icon.



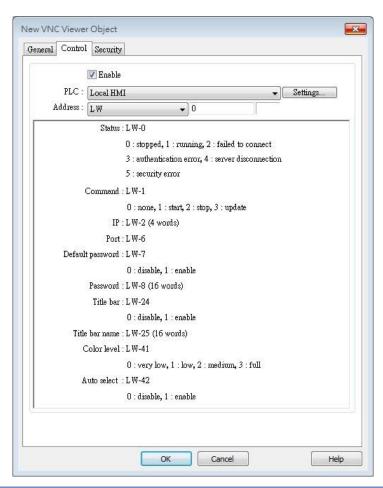
- eMT/iE/XE/mTV: VNC Viewer is supported for OS version 20160418 or later.
- cMT / cMT X Series: VNC Viewer is supported only on cMT series HMI screen accessed locally, and for OS version 20180928 or later.
- VNC Viewer cannot be simulated in on-line simulation mode.



VNC Viewer only mirrors the actual resolution of the VNC server device and does not support scaling.

When [Default password] is selected, HMI's Virtual Keyboard can only be called out manually. If [Default password] is not selected, the Virtual Keyboard can pop up automatically.

#### **Control Tab**



Setting	Description
IP	A set of word addresses can be specified to control
	VNC Viewer as well to display the connection status.
	Control address: Shows the connection status
	0: Stopped
	1: Running
	2: Failed to connect
	3: Authentication error
	4: Server disconnection error
	5: Security error
	Control address + 1: Command



0: None

1: Start

2: Stop

Control address+2~+5: IP

**Control address+6: Port Number** 

Control address+7: Default Password

0: Disable

1: Enable

Control address+8: Password (16 words)

Control address+24: Title bar

0: Disable

1: Enable

Control address+25: Title bar name (16 words)

Control address +41: Color level

0: Very low

1: Low

2: Medium

3: Full

Control address +42: Auto select

0: Disable

1: Enable



- The allowable value range that can be entered in Control Address+6 is 0~99. The actual Port Number will be the value entered in Control Address+6 plus 5900. For example, if the user enters 1 in Control Address+6, the actual Port Number will be 5901. However, if the user enters 100 in Control Address+6, the value will not be added by 5900, and the actual Port Number will be 100.
- In VNC Viewer, to use the HMI built-in Virtual Keyboard, please tap the Focus button on the Virtual Keyboard first, and then tap VNC Viewer screen. This will change the input target.





Click the icon to download the demo project. Please confirm your internet connection before downloading the demo project.

Click the icon to watch the demonstration film. Please confirm your internet connection before playing the film.



# 13.50. Contacts Editor

#### 13.50.1. Overview

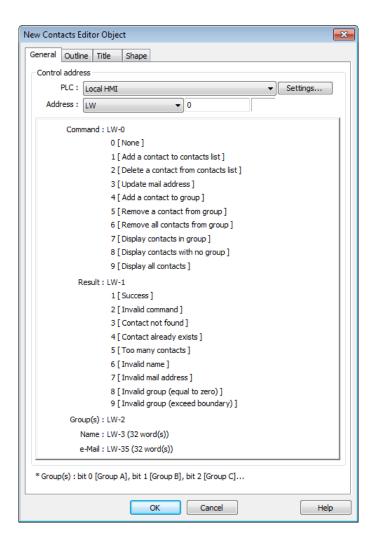
Contacts Editor enables users to dynamically add / modify / delete email contacts on HMI.

# 13.50.2. Configuration



Click the Contacts Editor icon on the toolbar to create a Contacts Editor object. Or, click [Objects] » [Contacts Editor] in the menu.

#### **General Tab**





Setting

# Description

#### **Control Address**

A set of word addresses can be specified to change contact list or to show results.

Control address: Gives commands.

Value	Command
0	None
1	Add a contact to contacts list
2	Delete a contact from contacts list
3	Update mail address
4	Add a contact to group
5	Remove a contact from group
6	Remove all contacts from group
7	Display contacts in group
8	Display contacts with no group
9	Display all contacts

#### Control address + 1: Shows execution result.

Value	Result
1	Success
2	Invalid command
3	Contact not found
4	Contact already exists
5	Too many contacts
6	Invalid name
7	Invalid mail address
8	Invalid group (equal to zero)
9	Invalid group (exceed boundary)

# Control address + 2: Group(s), uses bits to represent groups.

Value	Commands
0	Group A
1	Group B
2	Group C
3~15	Group D ~ Group P

Control address + 3: Name (32 word(s)), contact name

Control address + 35: e-Mail (32 word(s)), e-mail address

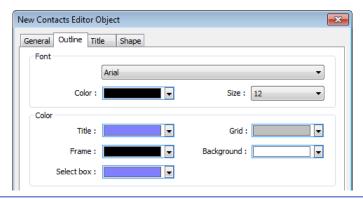




General tab cannot be found when the model used is a cMT / cMT X model.

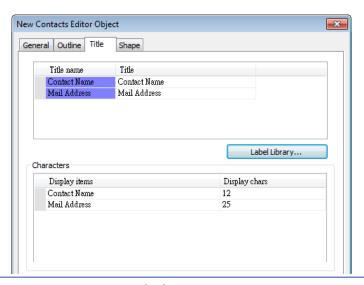
- Contact names do not support Unicode.
- The number of groups is specified in [System Parameter Settings] » [e-Mail] » [Recipients]. Please note that the number of groups cannot be dynamically changed on HMI.

#### **Outline**



Setting	Description
Font & Color	Select Contacts Editor object's font and color.

#### **Title**



Setting	Description
Title	The title shown in Contacts Editor.
Display chars	The displayable data length of each title in Contacts
	Editor. Range: 1~60



#### 13.51. Event Bar Chart

#### 13.51.1. Overview

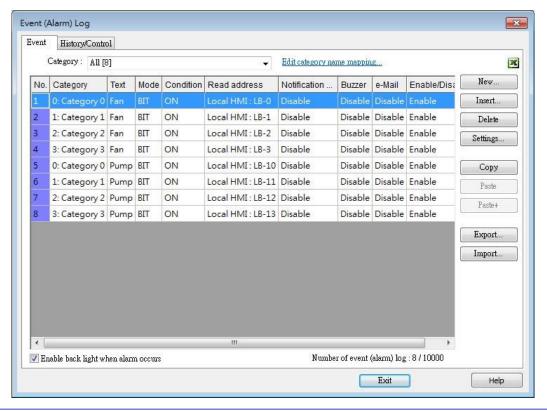
Event Bar Chart is a type of easy-to-use bar chart that can comprehensively illustrate project schedule. Using Event Bar Chart to illustrate HMI events or alarms can help users to clearly understand the time at which an event or alarm occurs, and its duration. Before drawing an Event Bar Chart, please configure Event Log object first.

This feature is only supported on cMT / cMT X Series models (excluding cMT-Gateway).

#### 13.51.2. Configuration

#### 13.51.2.1. Event Log

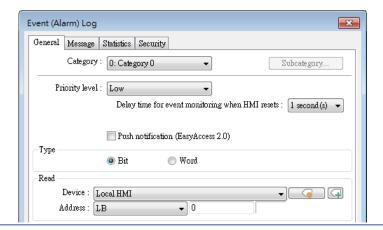
Click [Data/History] » [Event Log] in the menu to configure several event logs. This section describes the Event Bar Chart related settings that can be found in the Event Log settings dialog box.



Setting	Description
Edit category name	Event Day Chart will show the name of each estagon.
mapping	Event Bar Chart will show the name of each category.



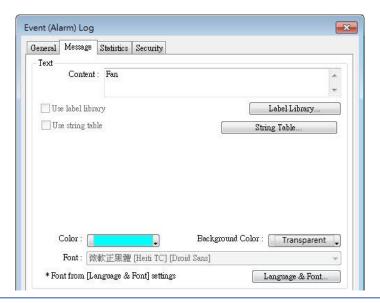
#### 13.51.2.2. **General Tab**



Category

Event Bar Chart will illustrate the duration of all events in one category, please select correct category in this field.

# **13.51.2.3.** Message Tab



Setting	Description
Text	Enter the name of the event log.
Color	Select the color for the bar shown in Event Bar Chart that illustrates this event log.

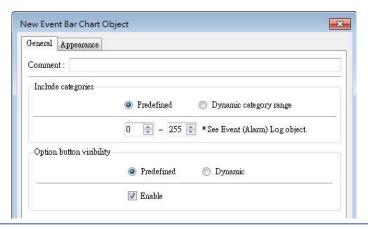


#### 13.51.2.4. Event Bar Chart



Click [Data/History] » [Event Bar Chart] in the menu to draw an Event Bar Chart.

#### **General Tab**



## Setting Description

#### Include

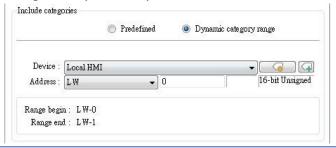
#### **Predefined**

# categories

Predefine a range of event categories to be displayed in the Event Bar Chart.

#### **Dynamic category range**

Use a set of consecutive addresses to select the display range of event categories dynamically.



# Option button visibility

Show or hide the option button of the object.

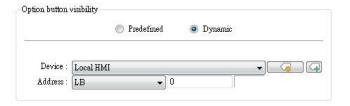
#### **Predefined**

Select [Enable] to show the option button.

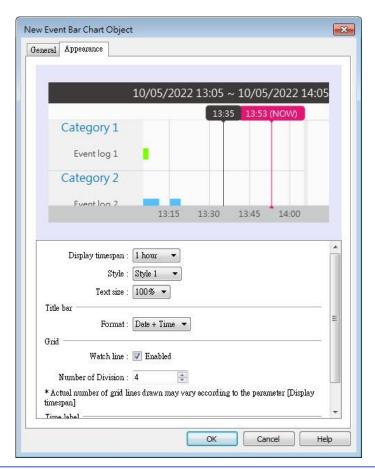
# **Dynamic**

Choose a bit address to control option button visibility.



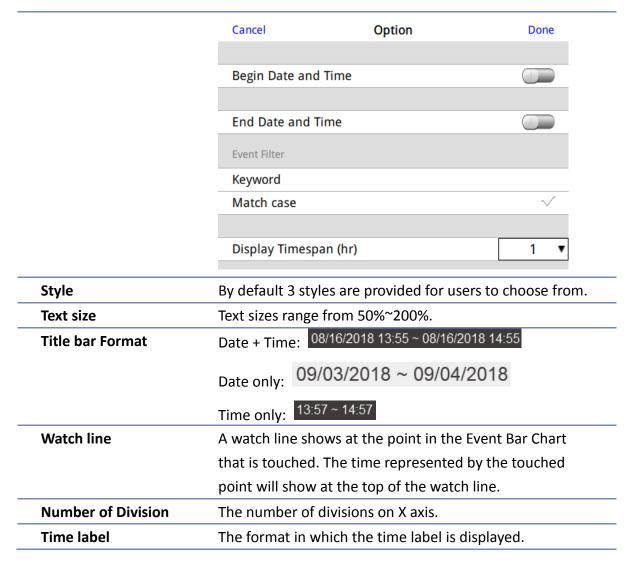


# **Appearance Tab**



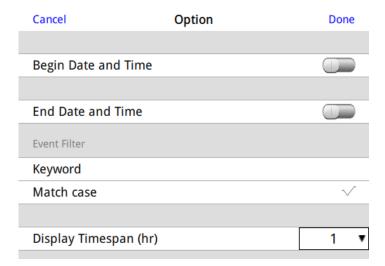
# Display timespan Specify the time interval that is measured as a number of hours. Events occur during this time interval will be illustrated in Event Bar Chart. Tapping in the upper right corner of the HMI screen can also change this setting.





#### **HMI Settings**

On cMT HMI or cMT Viewer, tap the icon in the upper-right corner of the object to open the following settings window.





Setting	Description
Begin Date and Time	Specify the begin date and time at which Event Bar
	Chart displays data. By default this setting is disabled,
	and Event Bar Chart displays from the begin date and
	time of the stored data.
End Date and Time	Specify the end date and time at which Event Bar Chart
	displays data. By default this setting is disabled, and
	Event Bar Chart ends at the end date and time of the
	stored data.
Event Filter	Keyword
	Events can be filtered by entering a keyword.
	Match case
	Use case-sensitive search when searching for events in
	English.
Display Timespan	Dynamically change the time range (1~96 hours.)
(hr.)	shown in Event Bar Chart. Select all to display all
	existing events.



When HMI power is off, the HMI will not be able to obtain the alarm states; therefore, the alarm states during the power off period will not be illustrated in Event Bar Chart, not even after the power turns on.



# 13.52. Action Trigger

#### 13.52.1. Overview

The Action Trigger object can trigger a sequence of action groups when the specified condition is met. Users can divide actions into action groups and the actions within the same group are executed at the same time when the specified condition is met. When all the actions within the same group are completed, the actions in the next group are then executed. This object is only available on cMT / cMT X Series models.

Action Trigger has two types, each with different modes for triggering action execution: Action Trigger (per-page): [Window open/close], [Backlight on/off], and [Value changed] modes.

Action Trigger (Global): [Idle timeout], [Value changed], [Control token], [User secure access], and [Condition object] modes.

# 13.52.2. Configuration

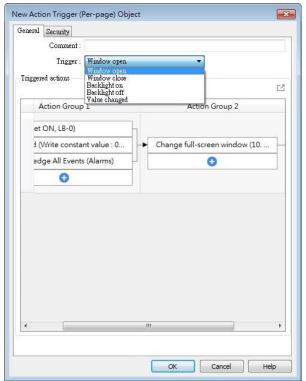


Click [Object] » [Action-related] » [Action Trigger (per-page)] or [Action Trigger (Global)] icon on the toolbar to open an Action Trigger object property dialog box. Clicking [New] can add a new Action Trigger.

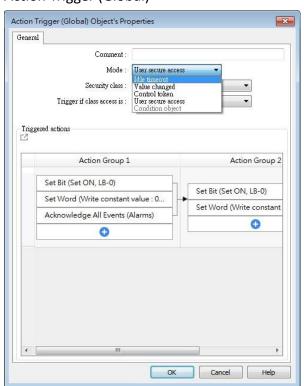


#### **General Tab**

# Action Trigger (Per-page)



# Action Trigger (Global)



Setting	Description
Trigger	Window open: Triggers actions when window opens. Settings in
(per-page)	Security tab will not be available when using this mode.
	Window close: Triggers actions when window closes.
	Backlight on: Triggers actions when backlight turns on.
	Backlight off: Triggers actions when backlight turns off.
	Value changed: When the state of the designated register meets the
	preset condition, Action Trigger will start executing.
Mode: Idle	If the screen is left untouched for more than the specified time limit
Timeout	configured in [Idle Timeout], Action Trigger will start executing.
(Global)	Range: 1~43200 seconds
Mode: Value	When the state of the designated register meets the preset
Changed	condition, Action Trigger will start executing.
(Global)	Check condition recursively when actions ended
	When all actions are completed, the trigger condition will be checked
	again; and if the condition is met, the actions will be triggered again.
	Dynamic condition value
	This option is available when [Word] is selected as Type. Selecting
	this option opens the [Read/Condition use different addresses]



	option. When [Read/Condition use different addresses] is not
	selected, the condition value is read from the next contiguous
	_
Carlad	register of [Value address].
Control	Trice and a stice as whose the Combant Talves is a serviced an arrangement
Token	Triggers actions when the Control Token is acquired or unacquired.
(Global)	
User Secure	Triggers actions when access to the specified security class is
Access	obtained or lost. When the security class is [Any], the actions can be
(Global)	triggered, regardless of class, when the access is obtained or lost.
Condition	Triggers actions when the conditions set in Condition object are met.
Object	Check condition recursively when actions ended
(Global)	When all actions are completed, the trigger condition will be checked
	again; and if the condition is met, the actions will be triggered again.
<b>Action Group</b>	Actions are classified into groups. Actions in the same group will
	simultaneously be triggered, and only after the actions in the
	previous group have been all triggered, the actions in the next group
	will then be triggered.
Delay	Delays the action for the specified time period (milliseconds).
Set Bit	Sets the designated bit address ON or OFF.
	Set ON
	Sets ON the designated bit.
	Set OFF
	Sets OFF the designated bit.
	Toggle
	Alternates the bit state.
Set Word	Changes the value in the designated word address.
	Write constant value
	Writes the constant value to the designated register.
	Increment value (JOG+)
	Increases value in register by a set amount in [Inc. value], up to the
	[Upper limit].
	Decrement Value (JOG-)
	Decreases value in register by a set amount in [Dec. value], down to
	the [Bottom limit].
	Dynamic Limits (JOG+, JOG-)
	Sets the [Upper limit](JOG+) and [Bottom limit](JOG-) by a
	designated register.
	5 5



	Writes the constant string to the designated register.
	Object Control Command (cMT / cMT X only)
	Listed for selection are commands (with their corresponding
	command values) available for the control address of various
	functions.
	System Tag Command (cMT / cMT X only)
	When a system tag is set as write address; for example, LW-9134:
	Language Mode, the commands relating to the system tag can be
	selected.
Change	Switches to the designated window. Change full-screen window can
window	only be the last action in the last group in an Action Trigger.
	Change full-screen window: Changes to another base window.
	Change common window: Changes common window.
	Return to previous window: Changes from current screen to the
	previous one displayed. For example, when window no. 10 is
	changed to window no. 20, this function can be used to return to
	window no. 10. This function is only available for base window.
	Animation Setting:
	The effects are: Fade, Fly, Float, Wipe, Split, Circle, Clock, Zoom, Turn,
	Push. Different effects may be used for Start (window appears) and
	End (window disappears).
	[Duration] specifies how many milliseconds (ms) a transition effect
	takes to complete.
	[Direction] The direction of the transition.
Execute	Executes one of the Macros from the drop-down list that has already
Macro	been configured by users. Running a macro may take a while to
	complete; therefore, when [Execute Macro] is put into an action
	group, it is seen as completed when it is triggered. The system will
	not wait for the macro to complete running before moving on to the
	next action group.
Popup	next detion group.
Window	Pops-up a designated window.
	Onene a calculator with an unchangeable appearance, allowing
Popup	Opens a calculator with an unchangeable appearance, allowing
Calculator	operators to do simple calculation and enter the result to a
Window	destination object by pressing the Enter key.
Keyboard	Inputs characters/control signals, as often used with [Numeric] or
Input	[ASCII] objects.
	Enter: Same as the keyboard's "Enter" function.



	Backspace: Same as the keyboard's "Backspace" function.
	Clear: Clear the value in the word register.
	Esc: Same as the [Close window] function; it is used to close the
	keyboard window.
	Delete: Same as the keyboard's "Delete" function, deletes the
	number or character on the right side of the text cursor.
	<b>Left:</b> Same as the keyboard's " $\leftarrow$ " key moves the text cursor to the
	left side of the previous number or character.
	<b>Right:</b> Same as the keyboard's " $\rightarrow$ " key moves the text cursor to the
	left side of the next number or character.
	Inc: Add 1 to the current value.
	Dec: Minus 1 from the current value.
	ASCII/UNICODE: Specify the character to be entered by this key.
Screen Hardcopy	Saves current screen as a hard copy file into a SD card or USB disk.
Acknowledge	
all events	Acknowledges all events at once.
(Alarms)	
Import Data	Imports the e-mail contacts or user accounts, or logs in using USB
	Security Key.
	Data Position:
	The external device to read data from. Options: USB disk or SD card.
	Account import mode:
	If [Overwrite] is selected, there will be only imported accounts after
	import. If [Append] is selected, there will be imported accounts in
	addition to existing accounts after import.
	Delete file after importing user accounts:
	The system will delete the account data saved in the external device
	after importing; this can prevent the account data from leaking out.
Wait Until	The next group will be executed only when the condition set for a
	designated bit or word address is met. However, if the condition is
	not met even after the set wait time (timeout), it can either move on
	to the next action group or end prematurely without continuing.
Data Transfer	
(Global)	Sends the value in the designated address to another address.
File Transfer	Transfer files by FTP. HMI will connect to the FTP server in passive
	mode.
	mode.



Download: Transfer file from FTP server to local HMI.

Upload: Transfer file from local HMI to FTP server.

#### Server address:

[Direct]: Designate server address related settings in EBPro.

[Dynamic]: Designate an address for changing the server address

related settings dynamically on HMI.

Suppose the dynamic address is set to LW-n, then:

LW-n: Host usage (0: IP, 1 Domain name)

LW-n+1: IP (4 words)

LW-n+5: Port

LW-n+6: Authentication (0: None, 1: Account)

LW-n+7: Username (16 words)

LW-n+23: Password (16 words)

LW-n+39: Domain name (64 words)

#### Delete the source file after successful transfer

Following successful transfer, the source file will be deleted. When transferring in [Download (FTP -> HMI)] mode, please make sure that the account has the write permission on the FTP server.

#### File Tab:

Set file position and full path of FTP server / Local HMI. When a folder path is specified, all the files in that folder will be transferred, not including files in subfolders. When a file with identical file name already exists, it will be overwritten regardless.

#### **Status Tab:**

Designate an address for showing file transfer result and FTP server response. Please use the following link for more information on FTP server return codes.

https://en.wikipedia.org/wiki/List of FTP server return codes

# Control

Token

The action to acquire or unacquire a Control Token.

Control Token: Select a Control Token.

**Action:** Set this action to acquire or unacquire a Control Token.

Max. waiting time: Continues or stops running the next action group if the Control Token is still not acquired even after the set [Max.

waiting time].



At most 1000 Action Triggers can be created in a project.



At most 20 groups can be created in an Action Trigger, and at most 20 actions can be added into a group.

- To rename an action group, right-click on the name of the action group and select [Rename].
- File Transfer Error Codes:

Error Code	Description
0	File transferred successfully.
1	The HMI directory for download does not exist.
3	USB disk or SD card is not found.
4	HMI or FTP directory is empty.
5	Uploaded file does not exist.
8	Operation rejected by FTP server.
9	USB disk or SD card is full.
10	Unknown error.



# 13.53. Calendar

## 13.53.1. Overview

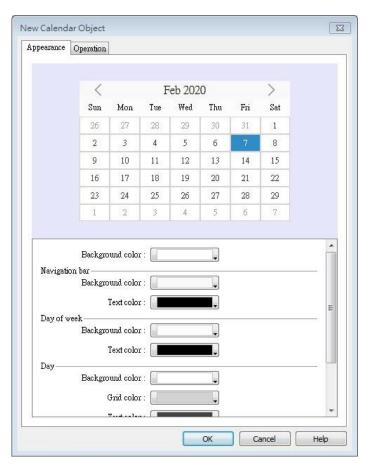
The Calendar object can show a calendar on cMT / cMT X Series HMI.

# 13.53.2. Configuration



Click [Object] » [Time-related] » [Calendar] icon on the toolbar to open a Calendar object property dialog box. Set up the properties, press OK button, and a new Calendar object will be created.

#### **General Tab**



Setting	Description
Appearance	Navigation bar Set the background color and text color of the
	navigation bar.
	Day of week Set the background color and text color of the days of



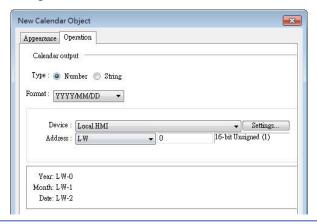
week.

**Day** Set the background color, grid color, and text color of the days.

**Today** Set the background color and text color to show today.

# Operation

Output the date information in a number or a string to the designated address.



Click the icon to watch the demonstration film. Please confirm your internet connection before playing the film.



# 13.54. Touch Gesture

#### 13.54.1. Overview

For some time, smartphones or tablets nowadays have been using gesture-based operation, e.g., pinch with five fingers to close an app. Now, with HMI having Touch Gesture object that supports up to 23 touch gestures, HMI can provide operating experience comparable to that of a smartphone or tablet.

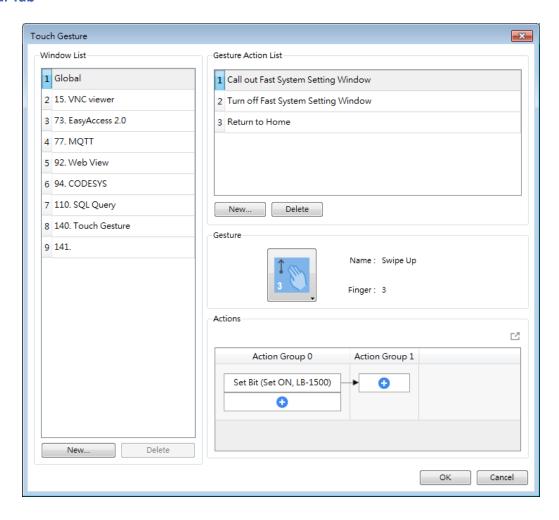
The Touch Gesture finger limit is 5.

# 13.54.2. Configuration



Click [Object] » [Action Related] »[Touch Gesture] icon on the toolbar to open the Touch Gesture property dialog box. Select a window and then add its allowable touch gestures.

## **General Tab**





Setting	Description
Window List	Allow the gesture actions to be used in a specific window or all
	windows. When Global is selected, one-finger gestures are not
	supported.
	Add/Delete
	Add or delete a window that allows this gesture action.
Gesture	Shows gesture action list for the window.
<b>Action List</b>	Add/Delete
	Add or delete a gesture action.
Actions	Set an action or group of actions triggered using this gesture. For
	more information on the actions, see Chapter 13.36 or 13.52 in this
	manual.



- Up to 16 gestures can be used for each window setting (global/individual).
- When the same gesture is used in both the Global window and an individual window, the gesture is effective only for the individual window.
- When a user performs a gesture on the screen, objects are still triggered when they are touched.
- The touch gesture for an individual window is only effective when the window is a base window. If the said window is a pop-up window, or overlaid windows, its touch gesture will be ineffective and its gesture actions will not be executed.
- Detection for the next gesture will only start when the actions for the current gesture have been completed.



# 13.55. PLC Web Browser

#### 13.55.1. Overview

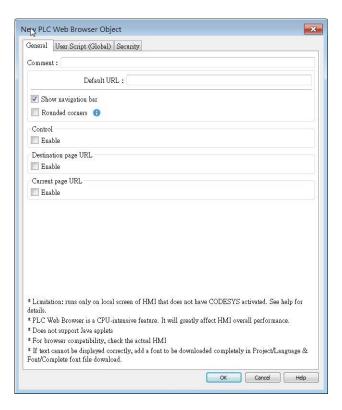
The PLC Web Browser object can be used for browsing PLC web pages. PLC Web Browser is supported only on cMT3072X, cMT3072XH, cMT3092X, cMT3152X, and cMT3162X.

# 13.55.2. Configuration



Click [Object] » [Media] » [PLC Web Browser] icon on the toolbar to open a PLC Web Browser object property dialog box. Set up the properties, press OK button, and a new PLC Web Browser object will be created.

#### **General Tab**



Setting	Description
Default URL	Enter the URL into the provided field.
Show	With this option selected, users can directly change URL, refresh
navigation	page, or zoom in/out web page by clicking the icons in the navigation
bar	bar displayed on HMI.



Icon	Command
$\leftarrow$	Go back to the previous page
$\rightarrow$	Go forward to the next page
0	Zoom out the page
•	Zoom in the page
	Return to homepage
C	Refresh the page

Rounded corners

With this option selected, the browser window will be displayed with rounded corners.

Control address

LW-n: Command ID

Value	Command
0	None
1	Go destination
2	Reload
3	Stop
4	Go back
5	Go forward
6	Clear cache
7	Clear cookie

## LW-n+1 Status

Value	Command
0	Load started
1	Load stopped
2	Load succeeded
3	Load failed

## LW-n+2 Error Code

Value	Command
0	No error
1	Internal error
2	Connection error
3	Certificate error
4	HTTP error
5	FTP error
6	DNS error

Destination page URL address

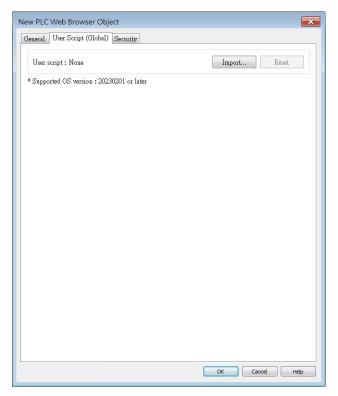
The designated register is for entering a URL with length limit 255 words. After entering the URL, please enter value 1 in the Command ID address to go to the destination page.



Current page URL address

Shows the URL of current page, the length limit is 255 words.

#### **User Script (Global)**



PLC Web Browser's User Script settings allow users to import a JavaScript file, which can be used to modify the webpage code. This User Script JS file is shared globally within the project, meaning it will have the same effect on all the PLC Web Browsers in the project.

This feature requires OS version 20230201 or later.

#### 13.55.3. Notes on PLC Web Browser

- 1 For more details about supported models and OS versions, please see Appendix A in this user manual.
- 2 PLC Web Brower object is designed specifically for connection to PLC's built-in web server, allowing users to access PLC web page to configure PLC and view PLC data. Using PLC Web Browser to connect to other types of websites may lead to unexpected results or errors.
- Displaying relatively complex web page using PLC Web Browser will occupy more memory and consume a large amount of CPU, which can significantly slow down HMI's operating speed. Users are advised to use change page function or a Direct/Indirect window to display PLC Web Browser object only when it is needed, in order to prevent reduction of system performance.
- 4 As HMI memory is limited, when the PLC Web Browser occupies too much memory, the system will automatically stop PLC Web Browser to ensure proper operation of HMI.



In consideration of performance, PLC Web Browser can only run on an HMI whose CODESYS is not activated.

- Due to rapid change in web technologies, it is not guaranteed that all PLC web servers are supported by PLC Web Browser in EasyBuilder Pro, and certain PLC web pages may not be correctly displayed using PLC Web Browser.
- 7 When multiple PLC Web Browser objects are placed in a single window, only one of them will run while the rest remain ineffective.
- 8 PLC Web Browser object displays web page on top of everything else even if there are other objects placed above it.
- 9 When the PLC Web Browser is clicked or tapped in cMT Viewer running on a PC, smart phone or tablet device, the default browser for the device will be used to open the web page. Note that, in this case, to access the PLC within the same network as HMI, the device running cMT Viewer should also be in the same network as the PLC.
- 10 Browsing web pages using PLC Web Browser on cMT-iV5/cMT-iV6 is not possible.
- 11 Features not supported by PLC Web Browser:
  - Save file as...
  - Text selection
  - Right-click menu
  - Drag & Drop
  - Windows prompt for entering account name and password (e.g., FTP login)
  - Playing videos, e.g. YouTube...etc.
  - Uploading / Download files.
- 12 If the text on a webpage is not displayed correctly in the PLC Web Browser, please refer to Chapter 15.5.5 in this user manual for information on how to download the complete font file to add support for non-built-in fonts in the OS to the PLC Web Browser.



# 13.56. Condition

#### 13.56.1. Overview

The Condition object can be used to replace the if-else statement in macro. When the specified conditions in the Condition object are met, the designated output bit address will be set ON. The output bit address can be used in objects' security settings, Event Log, Backup, and Data Transfer...etc. The Condition object can be selected in Action Trigger (Global) object's mode setting. Note that this object is available only on cMT / cMT X models.

## 13.56.2. Configuration



Click [Object] » [Condition] icon on the toolbar to open a Condition object property dialog box. Click [New] to add a new condition, and then click [OK] to create a Condition object.

#### **General Tab**





Setting	Description	
Name	Enter the name of this object.	
onditionals	Operator: Select AND / OR operator.	
	AND: The Condition object is effective when all the specified	
	conditions are met.	
	OR: The Condition object is effective when one of the specified	
	conditions is met.	
Туре	Value Address: Select an address type from Bit / Word.	
	Conditional	
	Name : Conditional 1	
	Type : Value Address ▼	
	Туре	
	Bit	
	Device : Local HMI	
	Address : LB     0	
	Condition	
	Enable if value is : OFF	
	Condition Object: Select another Condition object.	
	Conditional	
	Name : Conditional 1	
	Type : Condition Object ▼	
	Condition : 0. Condition Object 1 ▼	
	Enable if value is : ON ▼	



At most 128 Condition objects can be created in a project.

specified bit address will be set OFF.

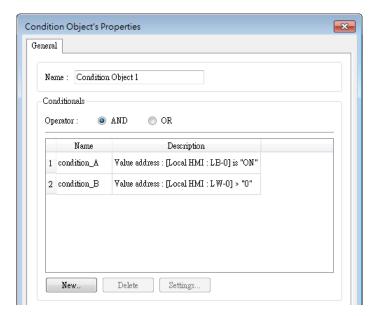
At most 8 conditions can be created in a Condition object.

## **Example 1**

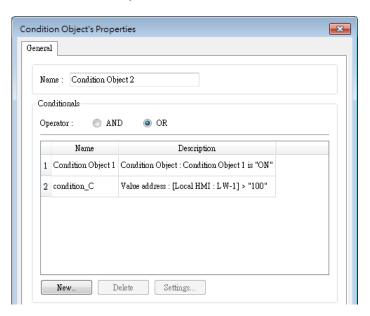
Here is an example of using Condition object to replace the if-else statement in macro. The macro below contains three conditions.

```
Work Space
                                                                                                                   Macro name : Demo
    Macro ID: 0
                                                                            Use execution condition
  Periodical execution
                                                                            Execute one time when HMI starts
                                                                                         Password Protect... [Disable]
   SC X B B A A A S
            macro_command main()
            bool condition A
            short condition_B, condition_C
            GetData(condition_A, "Local HMI", LB, 0, 1)
GetData(condition_B, "Local HMI", LW, 0, 1)
GetData(condition_C, "Local HMI", LW, 1, 1)
      10 \Box if (condition_A == 1 and condition_B > 0) or condition_C > 100 then
      11
      12
            //Execute content
      13
           end if
      14
      15
            end macro_command
 * Click the right mouse button to display edit menu.
                                                                                   On-line Simulation
                                                           Off-line Simulation
    GET/SET FN...
                              Save & Compile
```

Create a Condition object, add condition\_A and condition\_B, and then select AND operator as shown below.



2. Create another Condition object, add Condition Object 1 created in the previous step, add condition\_C, and then select OR operator as shown below.



3. Now the Condition objects can do the same thing as the macro, which triggers actions according to the conditions.

## **13.57.** FTP Server

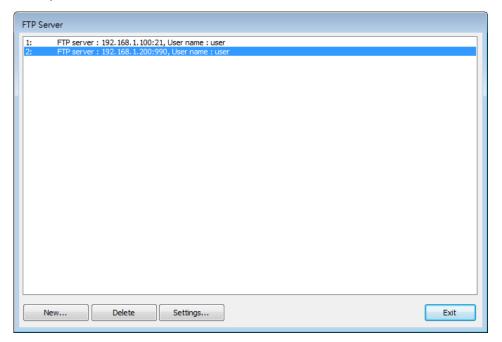
## 13.57.1. Overview

In FTP Server settings, FTP connection parameters can be configured. With FTP function enabled, backup files (screen hardcopy or historical data) can be transferred to FTP server on PC from HMI, in order to achieve the same effect as using EasyPrinter. This feature is only supported on cMT / cMT X Series models.

# 13.57.2. Configuration

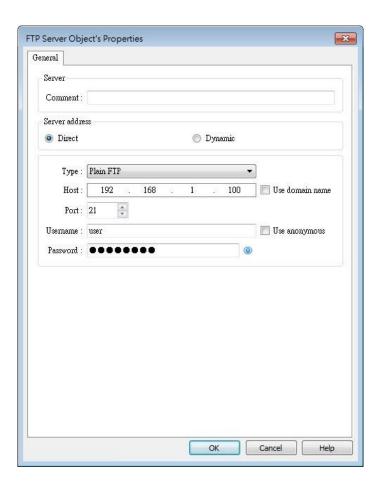


Click the FTP Server icon in Data/History tab to open the property dialog box. Set up the properties and press OK button to add a new FTP server.



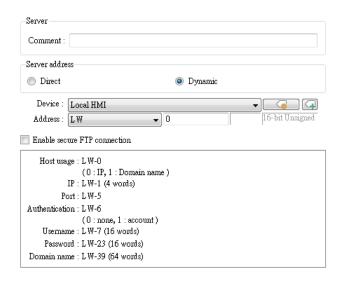


## **General Tab**



Setting	Description
Server address	Direct
	Use the server address related settings (e.g. Type, IP,
	Portetc.) in EasyBuilder Pro.
	Dynamic
	Specify an address for setting FTP connection parameters dynamically on HMI.





Туре	Plain FTP
	No encryption.
	Implicit FTP over TLS
	The entire connection is encrypted. Default TCP port is 990.
	Explicit FTP over TLS
	Encryption begins following authentication request (AUTH
	TLS). Default TCP port is 21.
Host	FTP server's IP address or domain name.
Port	FTP server's port number.
Username	FTP server's username.
Password	FTP server's password.



If "This server is used and cannot be deleted." message shows while deleting an FTP server, please disable FTP function in Home » System Parameters » FTP tab.



# 13.58. Date/Time

## 13.58.1. Overview

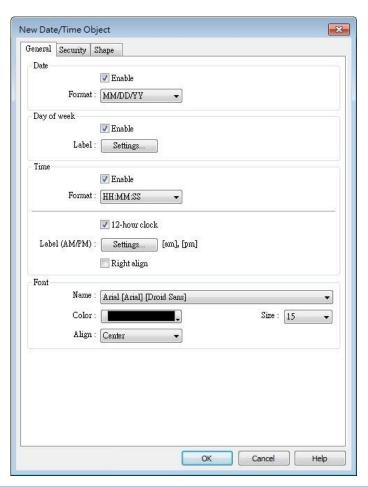
The Date/Time object displays the current date and time in the specified format and font.

# 13.58.2. Configuration



Click the Date/Time icon on the toolbar or click [Object] » [Time-related] » [Date/Time] in the menu to create a Date/Time object.

#### **General Tab**



Setting	Description
Date	Set the date format.
Day of week	Set the label of the days of the week.



Time	Set the time format.
Font	Set the font, color, size and alignment of the text displayed.



# 13.59. Template

# 13.59.1. Template Window

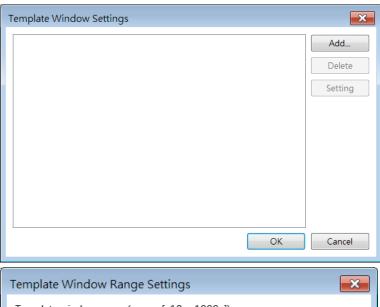
#### 13.59.1.1. Overview

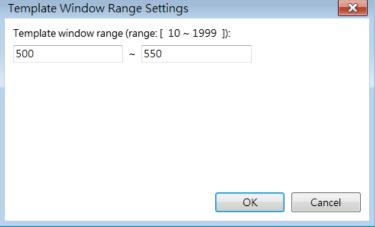
The Template Window object can be used to specify the source window for the Template object.

# 13.59.1.2. Configuration



Click on the [Object] » [Template] » [Template Window] icon on the toolbar to open the settings dialog box. Then click [Add], specify the template window range, and press the OK button. A new Template object will be created.







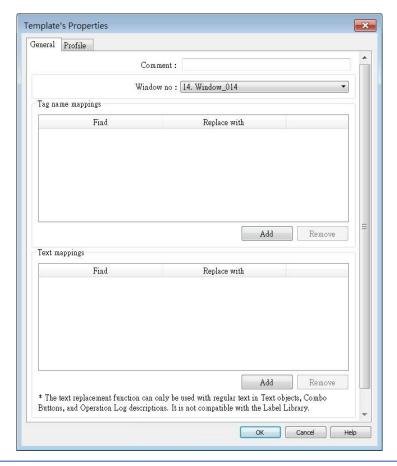
## 13.59.2. Template

## 13.59.2.1. Overview

The Template object reduces repetitive project design steps by replacing object addresses or texts based on Template Window settings.

# 13.59.2.2. Cofiguration

## **General Tab**



Setting	Description
Comment	User-defined object description.
Window no.	Select the source template window.
Tag name	Find a custom string in the tag name and replace it with
mappings	another custom string.
Text mappings	Find a custom string in the text label of a Text object, Combo Button, or Operation Log, and replace it with another custom string.



■ Tag name replacement is only supported for user-defined tags and tags using Symbolic



Addressing.

- Text mapping is not supported for objects using Label Tag Library.
- Template objects are only effective during the editing phase and will be transformed into independent objects after compilation. This means that when decompiling .exob/.cxob files, the resulting project file will only contain independent objects, not template objects.
- The Template Window cannot contain Template objects.
- Template objects become independent only after compilation; therefore, Address Viewer and Label Tag Library cannot display their status after address replacement.
- Objects that extend beyond the Template Window's range, including those that go beyond the range after text replacement, will be removed and not displayed by the Template objects.

# **Example**

Here is an example that demonstrates how to create a template:

1. Create two tags in Address Tag Library and name them Tag\_0 and Tag\_1.

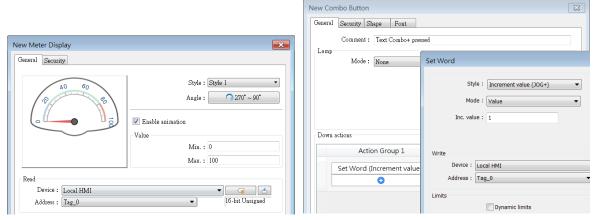


2. Create a new window and set its size which will determine the size of the Template object.



3. In the window created in step 2, place a Meter object and a Combo Button object, and set their read/write addresses to the Tag 0 created in step 1.

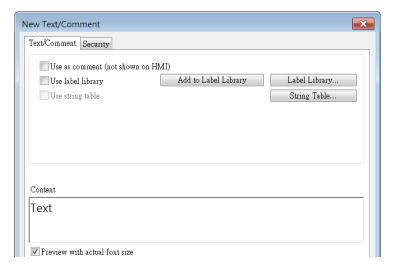




**4.** Set the Combo Button's comment to "Text Combo+ pressed" and its text label to "Combo+".

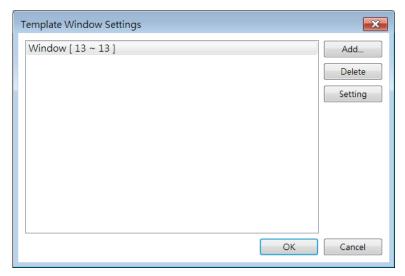


5. Place a Text object in the window created in step 2, and set its content to "Text".

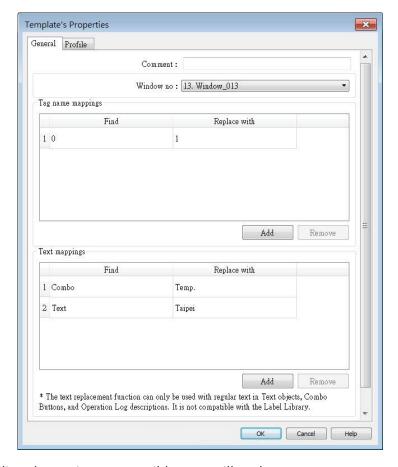


6. Set the window created in step 2 as the Template Window.





7. Create a Template object and configure it with the following settings.



8. After compiling the project, EasyBuilder Pro will replace any tag names containing "0" with "1" for objects in the Template Window that use them. This means that "Tab\_0" will be replaced by "Tag\_1". The text mapping feature will also replace object comments, text contents, and text labels according to the settings defined in the Template object.







# 14. Shape Library and Picture Library

This chapter explains how to build Shape Library and Picture Library.

14.1.	Overview	14-2
14.2.	Building Shape Library	14-2
14.3.	Building Picture Library	14-9
14.4.	Immediate Modification and Preview	. 14-15



# 14.1. Overview

EasyBuilder Pro provides Shape Library and Picture Library for visual effects on objects.

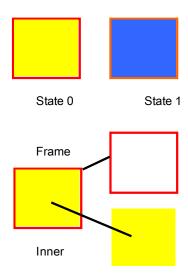
Picture Manager provides two modes: [Project] and [Library]. Pictures in [Project] mode will be stored in .emtp project file. Pictures in [Library] mode will be stored in EasyBuilder Pro libraries, or the user-defined directory.

Each Shape or Picture includes up to 256 states. This chapter explains how to build Shape Library and Picture Library.

For more information about using libraries while creating an object, see "9 Object General Properties".

# 14.2. Building Shape Library

Shapes are vector graphics constructed by lines, curves or polygons. A Shape can have more than one state, and each state includes two parts: frame and inner, as shown in the following figure.

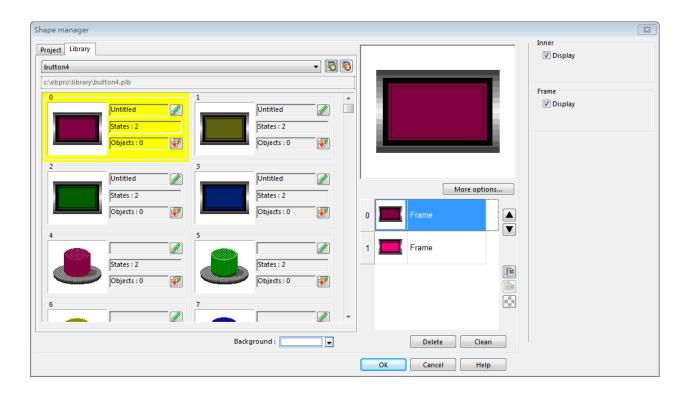


# 14.2.1. Shape manager

An object can use frame, inner or both. Click [Project] » [Shape], and the [Shape manager] dialog box appears.







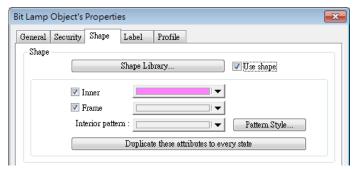
Setting	Description
Project	The Shape edited here will be saved in .emtp. Up to
	1000 Shapes can be added.
Library	The Shape edited here will be saved to the library
	directory on PC and will not be saved to .emtp
	project file.
<b></b>	Include existing .plb shape library files or create a
New library	new one. To create an empty library, enter a new
	file name and click [Open]. Up to 40 library files can
	be added.
Unattach library	Exclude currently selected library.
	Copy the selected Shape to [Project]. Only the
Copy to project	shapes that do not belong to the System Libraries
	can be copied. Shapes in System Frame/System
	Button/System Lamp/System Pipe cannot be
	copied.
Background	Select and preview the background color of the
	Shape. The color is only displayed in [Shape
	manager] dialog box, and is not displayed when
	placing the object in the screen.
More options	Set the color and style of [Inner], [Frame], and



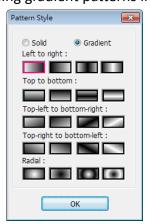
	[Pattern].
	Move the Shape to the previous / next state.
Сору	Copy the selected Shape.
Paste	Paste the copied Shape.
Insert transparent state	Insert a blank state after the selected state.
Delete	Delete the selected state of the shape.
Clean	Delete all the states of the selected shape.
ОК	Confirm to save the edited Shape.
Cancel	Cancel the editing event.
Help	Open help files.



The color of [Inner] and [Frame] can be selected in Shape Library. The selection of [Pattern Style] is only available in System Frame / System Button Library.



■ cMT / cMT X Series supports using gradient patterns in [Pattern Style], as follow:



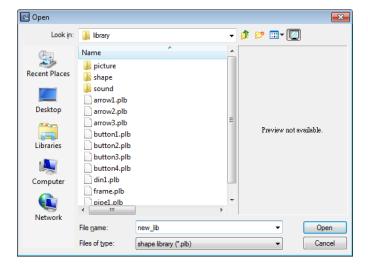
## 14.2.2. Steps to Build Shape Library

The following explains how to create a new Shape Library and add a Shape with two states into

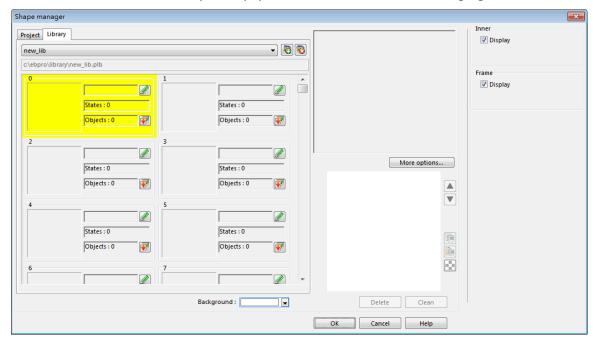


## the library.

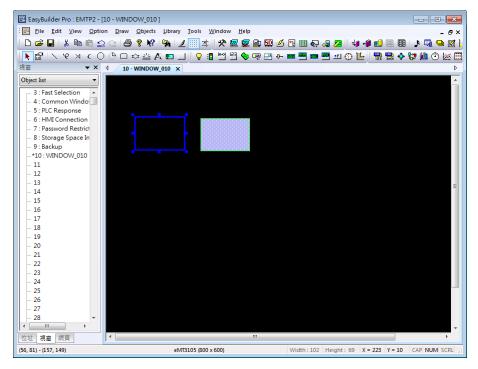
1. Click [New library] and enter the name of the new Shape Library, for example, "new\_lib".



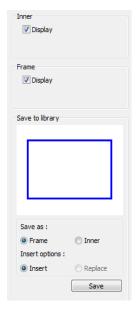
- 2. Click [Open], a popup dialog appears; click [Yes] to create the file.
- **3.** A new Shape Library [new\_lib] is added in [Shape manager], and its directory is shown below the name. This library is empty now as shown in the following figure.



4. Add a state to the selected Shape. First, use the drawing tools to draw a frame and inner in the window and select the frame to add to the Shape Library.



- 5. Click [Project] » [Shape] » [Save to shape] button in the toolbar, select [new\_lib], and select a number in this library. The selected number is highlighted yellow.
- 6. Save the Shape as [Frame], select [Insert], and click [Save].



Setting	Description
Inner	Displays the inner of the Shape.
Frame	Displays the frame of the Shape.
Save to library	Save as Frame
	Saves the Shape as a frame.
	Save as Inner
	Saves the Shape as inner.

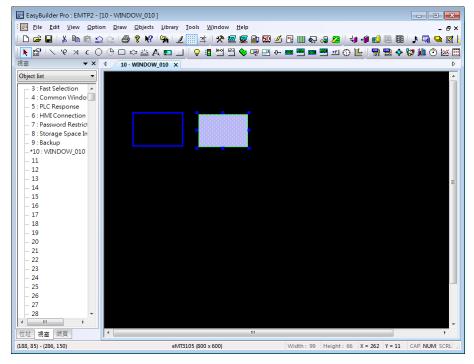


	Insert
	Inserts the Shape to be a new state.
	Replace
	Replaces a state with this Shape.
Save	Saves the settings above.

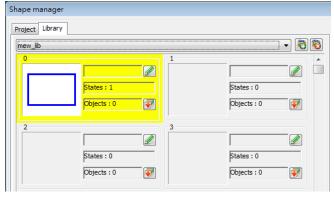
7. The following shows that a state of the Shape is added, and is defined as a frame.



8. Create the shape to be saved as inner. Select the shape drawn in the window.

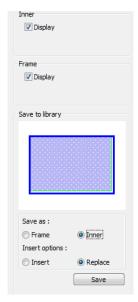


Click [Save to Shape Library] button in the toolbar, select [new\_lib], and select the same number as in creating the frame in this library. The selected number is highlighted yellow.



10. Save the Shape as [Inner], select [Replace], and click [Save].

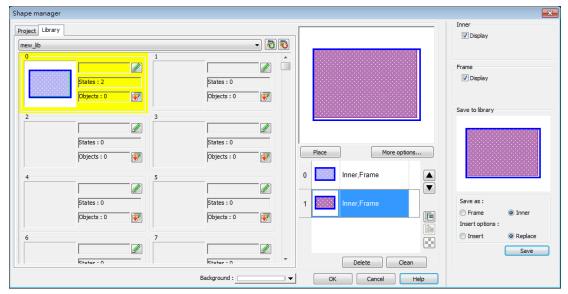




11. A state of a Shape can include [Inner], [Frame], or both. The state 0 of the Shape shown in the following figure includes both frame and inner. Click [OK], the state 0 of the Shape is created.



12. Follow the steps of creating state 0 and insert a new state set to state 1 as shown in the following figure. The Shape now has two states, click [OK] to finish setting.



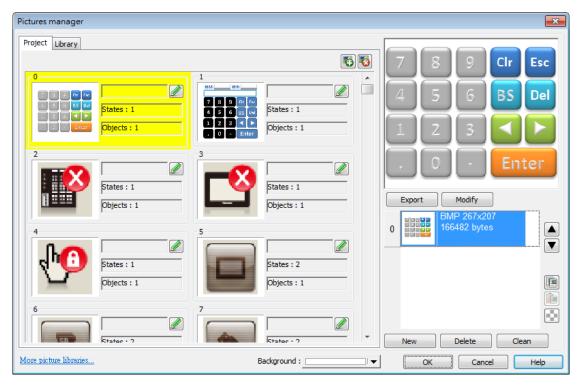


#### 14.3. Building Picture Library

#### 14.3.1. Picture manager

Click [Project] » [Picture] button in the toolbar and the [Picture manager] dialog box appears.





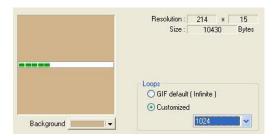
Description
The Picture edited here will be saved in .emtp. Up
to 1000 Pictures can be added.
The Picture edited here will be saved to the library
directory on PC and will not be saved to .emtp
project file.
Add the existing .flbx and .flb picture library files.
To add a new library that does not exist, enter a
new file name and click [Open], an empty library
file is created. Up to 40 library files can be added.
Delete the currently selected library.



Browse libraries	Search for path and view the pictures in the path.
Copy to project	Copy the Picture to [Project].
Background	Select the background color of the Picture. The
	color is only displayed in [Picture manager] dialog
	box, and is not displayed when placing the object in
	the screen.
More picture	Log in to Weintek Official Website to download
libraries	more libraries.
Export	Export the selected Picture.
Modify	Modify the settings of the selected Picture.
	Move the Picture to the previous / next state.
Сору	Copy the selected Picture.
	Paste the copied Picture. The Picture copied to the
Paste	clipboard can be imported to the library by pasting.
Insert transparent state	Insert a blank state after the selected state.
New	Add a new Picture.
Delete	Delete the selected Picture.
Clean	Delete all the Pictures listed here.
ОК	Confirm to save the edited Shape.
Cancel	Cancel the editing event.
Help	Open help files.

### Note

■ The supported picture formats are .bmp, .jpg, .gif, .dpd, .svg and .png. When adding a gif animation file in Picture Library, the loop times of this animated Picture can be set.

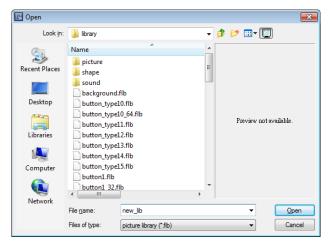




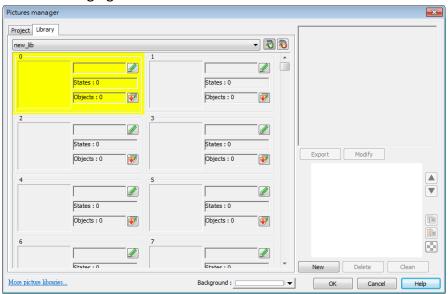
#### 14.3.2. Steps to Build Picture Library

The following example explains how to create a new Picture Library and add a Picture with two states into the library.

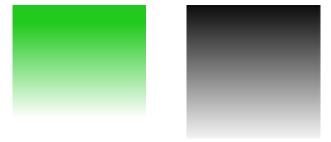
1. Click [New library] and enter the name of the new Picture Library.



- 2. Click [Open], a popup dialog appears; click [Yes] to create the file.
- **3.** A new Picture Library [new\_lib] is added in [Picture manager]. This library is empty as shown in the following figure.



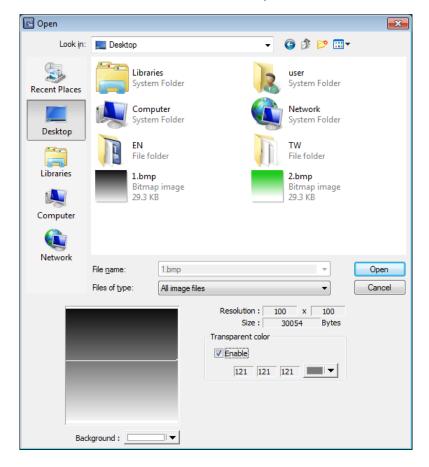
4. Draw the two pictures below to represent state 0 and state 1 respectively.



5. Select [new\_lib], and select a number in this library. The selected number is highlighted yellow.

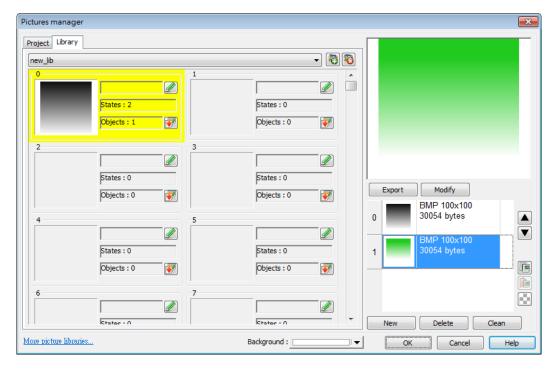


- 6. Click [New], and select the picture for state 0.
- 7. When the following dialog box is shown, select [Enable] check box to use transparent color. Set to RGB (121, 121, 121), the corresponding color in the picture below will be transparent. Or, click on a desired area with mouse to be the transparent area, the system will show the RGB of the clicked area automatically.



**8.** The Picture of state 0 is created. Follow the steps of creating state 0 to create state 1 by clicking [New] as shown in the following figure.





9. When finished, a complete Picture is created, click [OK]. In [Picture manager] dialog box it shows that the newly added Picture Number 0 is a bitmap picture with two states.

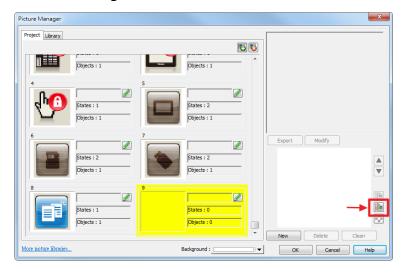
#### 14.3.3. Steps to Import Picture by Pasting

The following example explains how to import a Picture into the library by pasting the picture from the clipboard.

1. Copy the following picture to the clipboard.

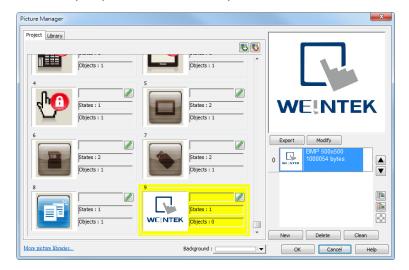


2. Click the Paste icon on the right side.





3. The Pictur can be easily imported to the library.

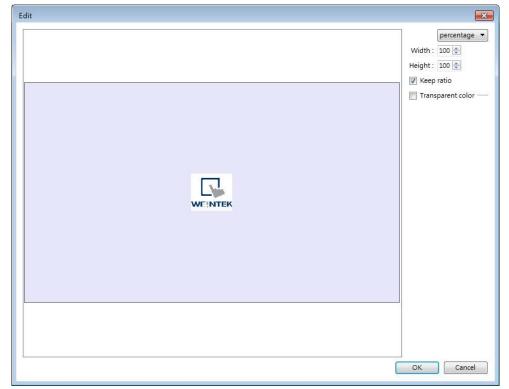


Pasting a picture directly from the clipboard into the project editing window is possible.

1. If the picture below is already in the clipboard.



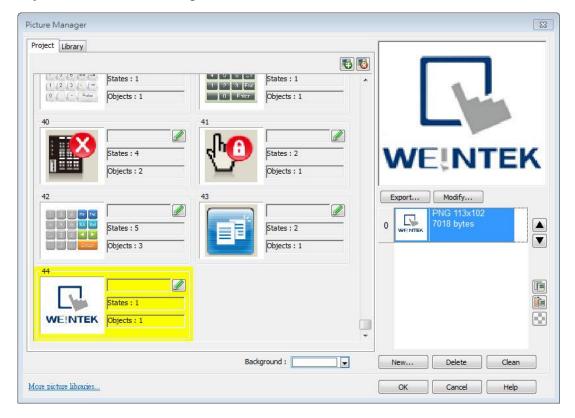
2. Pressing Ctrl+V key in the editing window will open the following dialog box.



- 3. The picture will be pasted into the editing window after clicking OK.
- 4. Double clicking the picture and open Picture Library, the picture can be found in the



#### Project tab in Picture Manager.



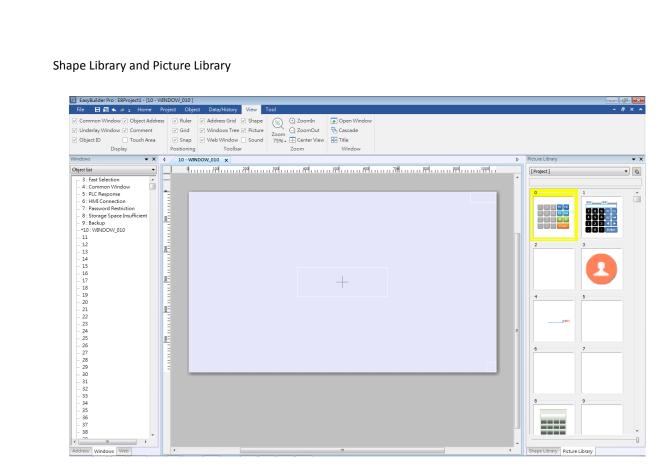


Transparent color can only be set for .bmp, .dpd, and .jpg picture files.

#### 14.4. Immediate Modification and Preview

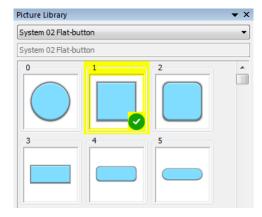
Shape Library / Picture Library settings windows are opened in the editing window. The user can immediately change the picture used by an object or multiple objects, and certain libraries support immediate color change.





#### 14.4.1. **Replacing a Picture**

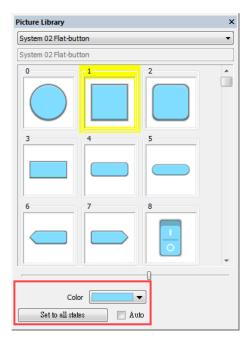
- 1. Click the object or objects whose picture is to be replaced.
- 2. Locate a new picture in Picture Library window and click the lower-right corner of that picture.



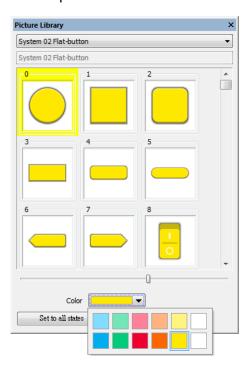
#### **Replacing a Color** 14.4.2.

The [Color] drop-down list appears when the selected library supports immediate color change.





- 1. Select an object or objects whose color is to be replaced.
- 2. Select a color from the Color drop-down list.



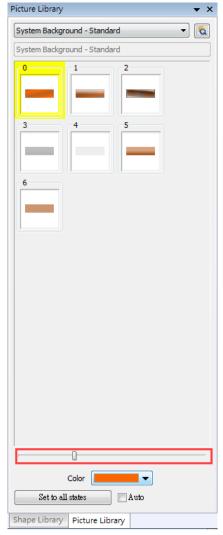
3. Click the lower-right corner of the new picture to apply.

Setting	Description
Set to all states	Apply the selected color to all states of the object
	that use the same picture.
Auto	Automatically execute [Set to all states].



#### 14.4.3. Extended Features

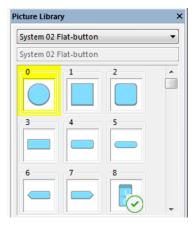
 In the settings window, dragging the slider leftward or rightward can make the thumbnail of the pictures smaller or bigger.



- Immediate preview can be achieved by:
- **1.** Select an object.
- 2. Press and hold the Shift key on the keyboard.
- **3.** Select a picture in the library to preview, and release the Shift key to return to current picture.

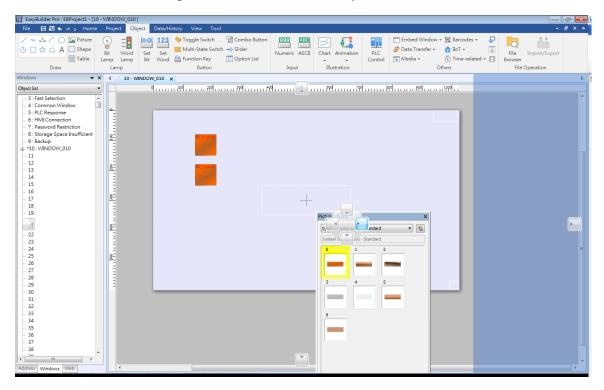






#### 14.4.4. Docking a Window

Users can drag the Shape / Picture Library window to a desired destination position. When dragging the window, a semi-transparent outline of the window shows where the window will be docked when releasing the mouse cursor at that point.





# 15. Label Tag Library and Multi-Language

This chapter explains how to build and use Label Tag Library.

15.1.	Overview	15-2
15.2.	Label Tag Library Manager	15-2
15.3.	Steps to create Label Tag Library	15-3
15.4.	Using Label Tag Library	15-4
15.5.	Selecting Language & Font	15-5
15.6.	Settings of Multi-Language	15-10

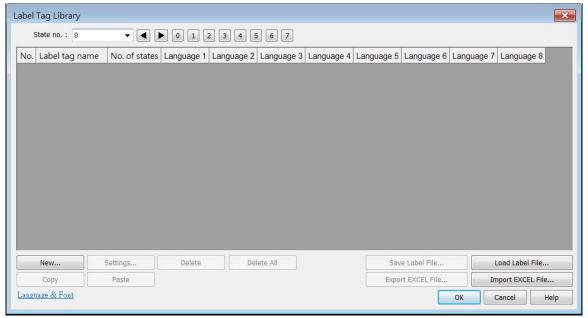


#### 15.1. Overview

The Label Tag Library feature enables a multi-language environment. When multiple languages are required, users can create the Label Tag Library and then select a suitable label in the project. The project will display the corresponding language in runtime based on the settings. EasyBuilder Pro supports up to 24 different languages simultaneously. This chapter will explain how to create and use the Label Tag Library.

#### 15.2. Label Tag Library Manager

Click [Project] » [Label] on the toolbar and the [Label Tag Library] dialog box appears.



Setting	Description
State no.	Indicates the current state. Each Label has a maximum of 256 states (state no. 0 ~ 255). The state no. is determined by [Language no.]. If less than 3 languages are used, the maximum state no. is 256. If more than 4 languages are used, divide 768 by the language number to get the maximum state no  For example, the number of languages is 24, then there are only 768/24 = 32 states.
New	Adds a new Label.
Settings	Sets the selected Label.
Save Label File	Saves all Labels in .lbl format.
Load Label File	Loads the existing .lbl file to the Label Library.



Export EXCEL File	Saves all Labels in .csv, .xls, or .xlsx format.
Import EXCEL file	Loads the existing .csv, .xls, or .xlsx file to the Label Library.



Unicode is not supported when importing and exporting an Excel file.

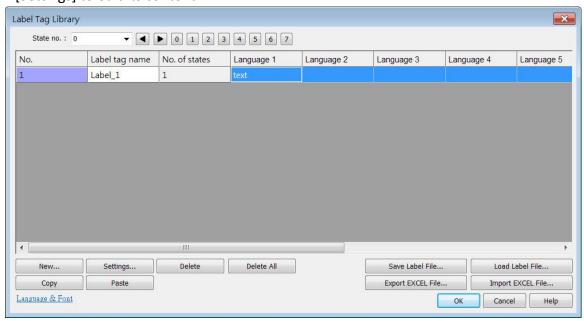
#### 15.3. Steps to create Label Tag Library

Please follow the steps to create a Label Tag Library.

1. From the Library menu, click [Label]. The Label Tag Library dialog box appears. Click [New] to specify the name of the Label and the number of states to be displayed by this Label.

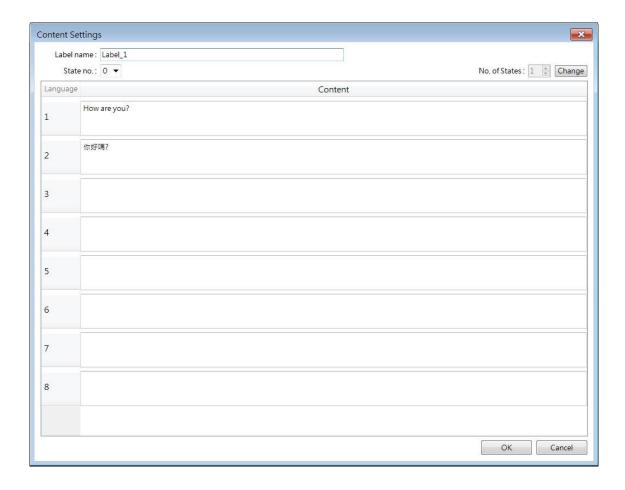


2. Click [OK] and a new label is added to the Label Tag Library. Select the label and click [Settings] to edit its content.



3. Edit the corresponding language content.

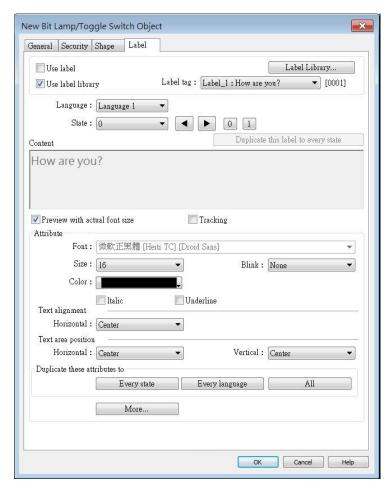




## 15.4. Using Label Tag Library

When there are defined labels in the Label Library, the labels can be found in the object's [Label] tab. Select [Use label library] check box, and select the label from the pull-down list [Label tag].





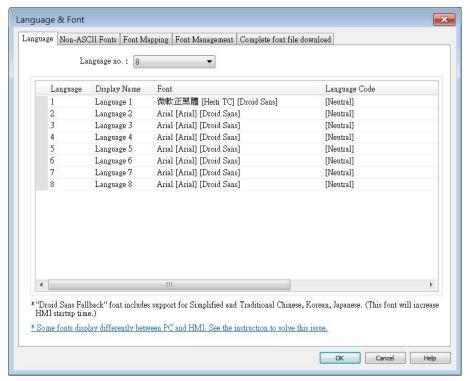
When a tag is selected, the content of the selected tag is shown in the [Content] field in its corresponding font style. Please note that from Language 2 to Language 24 can only be set the Font [Size], the others such as [Color], [Align], [Blink], etc. will follow the settings of Language 1.

#### 15.5. Selecting Language & Font

#### 15.5.1. Language

Click [Project] » [Language & Font] on the toolbar and the [Language & Font] dialog box appears.



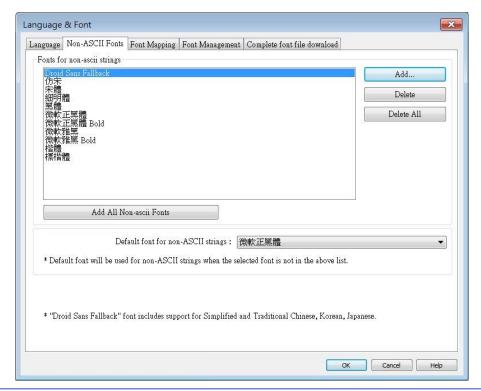


Setting	Description
Language no.	Specifies the number of languages used in a project.
Font	Shows language names and the fonts used for each language. A font description can be entered. [Language Code] allows changing the language used for push notification about the events in EasyAccess 2.0, when [Push notification (EasyAccess 2.0)] is enabled in Event Log.  Click the icon to watch the demonstration film. Please confirm your internet connection before

#### 15.5.2. Non-ASCII Fonts

Parameters in [Non-ASCII Fonts] tab determine the non-ASCII fonts. The non-ASCII fonts used are listed here. When using non-ascii characters or double byte characters (including Simplified or Traditional Chinese, Japanese, or Korean) which are not listed in [Fonts for non-ascii strings] table, EasyBuilder Pro will select a font from the list to substitute for it automatically.

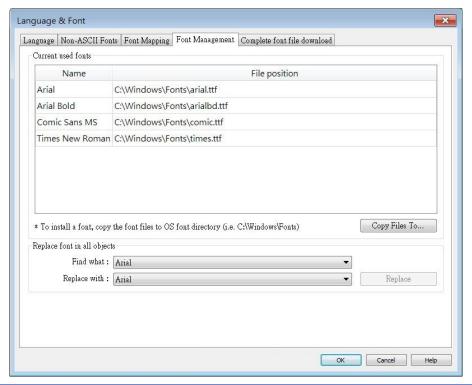




Setting	Description
Add All Non-ascii	The non-ascii fonts in Windows can be added to the
Fonts	[Fonts for non-ascii strings] table.
	Line spacing
	Set the space between multiple text lines.
<b>Default font for</b>	EasyBuilder will use the selected font as default font
non-ascii strings	for non-ascii strings.
Support Arabic,	Select this check box to correctly display these
Persian, Hebrew,	alphabets.
and Thai,	
alphabets	



#### 15.5.3. Font Management

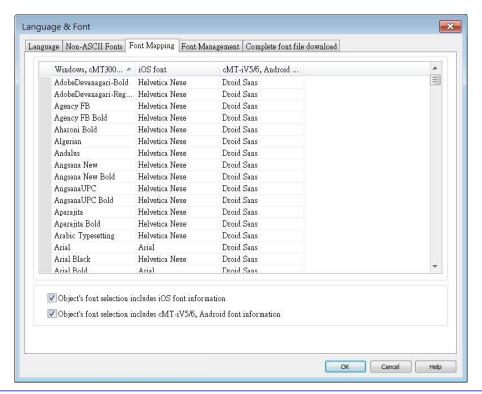


Setting	Description
Current used fonts	This table shows all the fonts used in this project and the file position of its font file.
Copy Files To	Copy the font file to the specified position.
Replace font in all objects	Change font at a time for all the objects using that font.

#### 15.5.4. Font Mapping

This tab lists the fonts used in Windows / cMT3000 and the mapping fonts in iOS / cMT-iV5 /cMT-iV6 / Android devices.



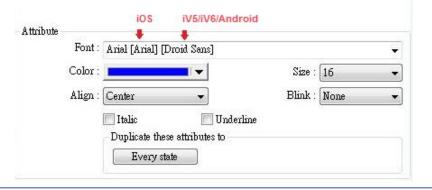


#### Setting

#### Description

Object's font
selection includes
iOS /
cMT-iV5 / cMT-iV6
/Android font
information

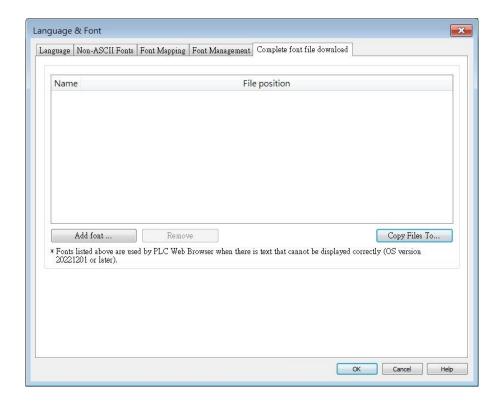
When the checkbox is selected, the fonts in iOS / cMT-iV5 / cMT-iV6 / Android that map to the select font in object property settings will be shown.



#### 15.5.5. Complete font file download

If the text on a webpage is not displayed correctly in the PLC Web Browser, the complete font file can be downloaded to HMI to add support for this font to the PLC Web Browser.





#### 15.6. Settings of Multi-Language

When displaying the texts in multiple languages, the system register "[LW-9134]: language mode" should be used too.

The value of [LW-9134: language mode] is ranged from 0 to 23. Different values correspond to different languages.

If not all languages are selected to compile and download, [LW-9134] will work differently. For example, user defines 5 different languages in the Label Tag Library:

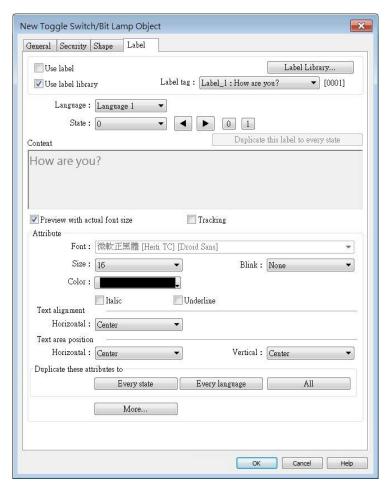
1: English, 2: Traditional Chinese, 3: Simplified Chinese, 4: French, 5: Korean If only Language 1, Language 3, and Language 5 are selected to compile then the corresponding values of [LW-9134] are:

0: English, 1: Simplified Chinese, 2: Korean

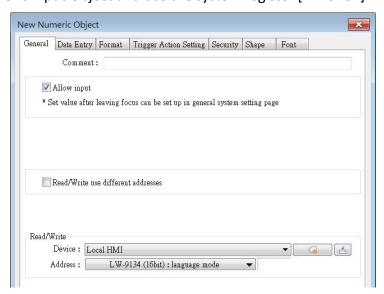
Please follow the steps to use multiple languages.

Create a Text/Comment object and select [Use label library] checkbox.



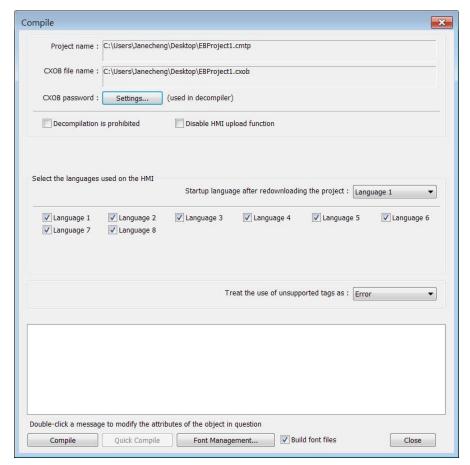


Create a Numeric Input Object and use the system register [LW-9134].



3. When compiling, select the defined languages.





**4.** The simulation is shown as followed: If the value of [LW-9134] is changed, the content of the Text object will be changed.



- When using a cMT / cMT X Series model, system register [LW-9134] is used to change the language mode in server, while [PLW-9134] is used to change the language mode on a portable tablet device.
- Only the label tags that are used in the project file will be contained in the \*.cxob / \*.exob file generated after compilation; therefore, no unused label tags will be contained in the



project file obtained by decompiling a \*.cxob / \*.exob file.

Click the icon to download the demo project that illustrates how to use the Option List object to switch between multiple languages. Please confirm your internet connection before downloading the demo project.

Click the icon to watch the demonstration film. Please confirm your internet connection before playing the film.



# 16. Address Tag Library

This chapter explains how to build and use Address Tag Library.

16.1.	Overview	16-2
16.2.	Building Address Tag Library	16-2
16.3.	Using Address Tag Library	16-5



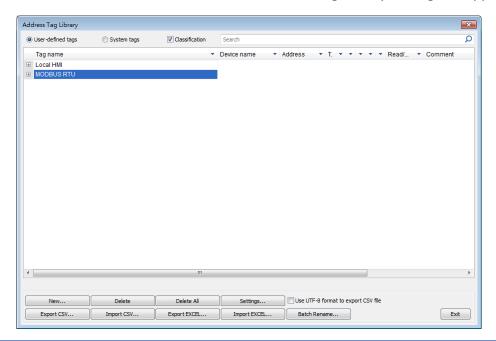
Address Tag Library 16-2

#### 16.1. Overview

Generally it is recommended to define the commonly used addresses in Address Tag Library when starting to build a project. It not only avoids accidental reuse of addresses but also improves project readability.

#### 16.2. Building Address Tag Library

Click [Project] » [Address] on the toolbar and the [Address Tag Library] dialog box appears.



Setting	Description
User-defined tags	Displays user-defined address tags.
System tags	Displays system registers. The registers listed cannot
	be deleted or changed.
Classification	With this checkbox selected, the system tags can be
	classified into categories according to their function.
	Users may customize classification by editing the
	system_tag.xml file, found under EasyBuilder Pro
	installation directory.
Search	A key word may be entered in the provided field to
	search for a specific tag.
New	Adds a new address tag. Please see the steps next
	page.
Settings	Sets the selected address tag.



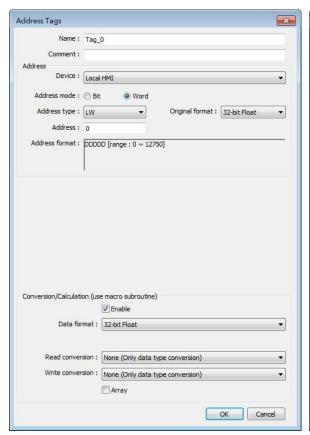
Delete All	Deletes all existing address tags.
Delete	Deletes the selected address tag.
Export CSV	Saves all current address tags as .csv file. Tag names of
	the tags used in the project file will be displayed in red
	in Excel.
Import CSV	Loads the existing .csv file of address tag to the
	current project.
Export EXCEL	Saves all current address tags as .xls file.
Import EXCEL	Loads the existing .xls file of address tag to the current
	project.
Use UTF-8 format	If selected, the .csv file will be exported in UTF-8
to export CSV file	format. If not selected, in ANSI format.
Batch rename	Rename multiple address tags of a device at a time.
	·

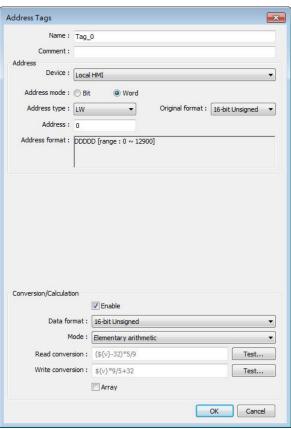


Address Tag Library 16-4

1. Click [New] and set the relevant properties.

eMT, iE, XE, mTV cMT, cMTX





Setting	Description
Name	The name of the address tag.
Comment	The information about the address tag.
Name	The name of the address tag.
Device	As defined in [System Parameter Settings] » [Device list].
Address mode	The tag address type; select [Bit] or [Word].
Address type	The available address types depend on [Device] and
	[Address mode].
Address	Address of the tag.
Original format	If select [Word] in [Address mode], the data format can be
	specified. When a tag with [Original format] specified is
	selected, the system will only use the specified format.
Conversion/Calculation	When enabled, the data format that the address tag will
(Use macro	be converted into can be specified. Macro subroutines can
subroutine)	be selected to do read/write conversion.
Mode (cMT / cMT X	Select Macro Subroutine mode or Elementary Arithmetic
only)	mode.

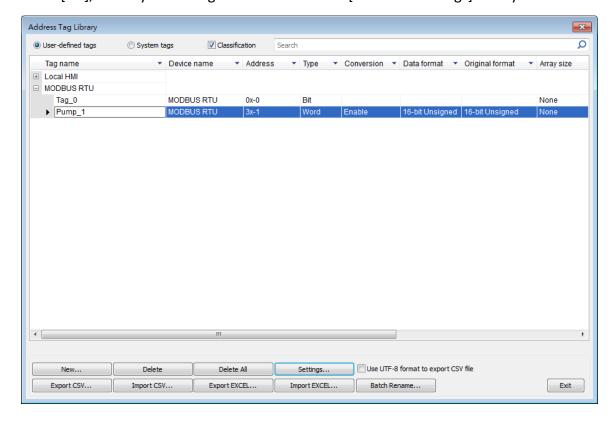


## Read / Write conversion

In Macro Subroutine mode, select the macro subroutine to do read/write conversion. The macro subroutine can only be selected when the data format is identical to the one in the macro subroutine.

In Elementary Arithmetic mode, valid formulas must be entered respectively in read conversion and write conversion fields. A valid arithmetic formula contains at least one and only one device value which is represented by \${v}. The available mathematical symbols include: +, -, \*, /, and parentheses ().

2. Click [OK], a newly added tag can be found in the [User-defined tags] library.

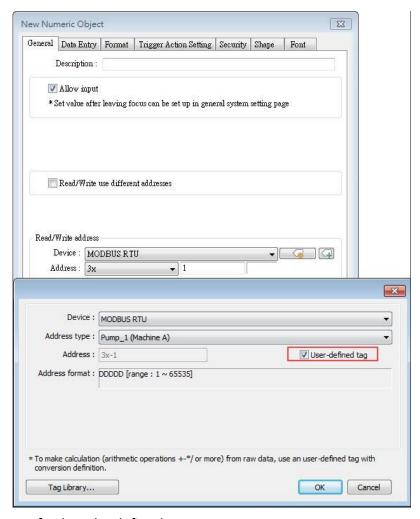


#### 16.3. Using Address Tag Library

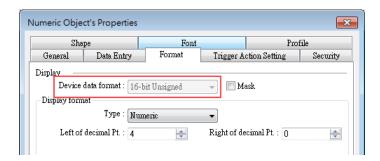
- 1. Create a tag in Address Tag Library.
- 2. Create an object, select [General] » [Device].
- Click [Settings] to finish the settings.
- Select [User-defined tag] check box.



Address Tag Library 16-6



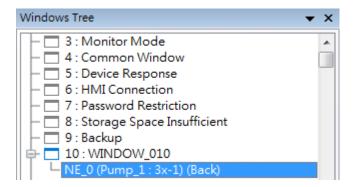
- 5. In [Address type] select the defined tag.
- **6.** If the data type is selected when creating the address tag, the system automatically restricts the data format to the one selected.



7. When finished, the window tree will show the address tag name used by the object.

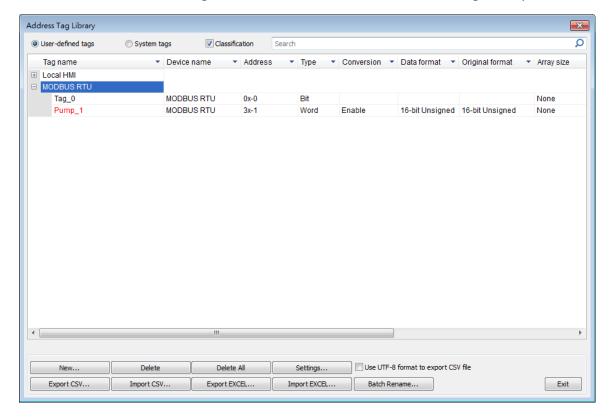


Address Tag Library 16-7





The name of the used tags will be written in red font in Address Tag Library.



Click the icon to download the demo project. Please confirm your internet connection before downloading the demo project.

# 17. Transferring Recipe Data

This chapter explains how to transfer recipe data.

17.1.	Overview	. 17-2
17.2.	Steps to Update Recipe Data with Ethernet or USB Cable	. 17-2
17.3.	Steps to Update Recipe Data with SD Card or USB Disk	. 17-3
17.4.	Transferring Recipe Data	. 17-4
17.5.	Saving Recipe Data Automatically	. 17-5



Transferring Recipe Data 17-2

#### 17.1. Overview

Recipe Data refers to the data stored in RW and RW\_A addresses. The way of reading and writing these addresses is the same as operating a word register. The difference is that recipe data is stored in flash memory, when restarting HMI, the latest data records in RW and RW\_A are kept.

The size of recipe data a RW address can store is 512K words, and RW\_A is 64K words. Users can update recipe data with SD card, USB disk, USB cable or Ethernet and use the data to update PLC data. Recipe Data can also be uploaded to PC; furthermore, PLC data can be saved in recipe data. The following explains the ways of transferring recipe data.

Click the icon to watch the demonstration film. Please confirm your internet connection before playing the film.

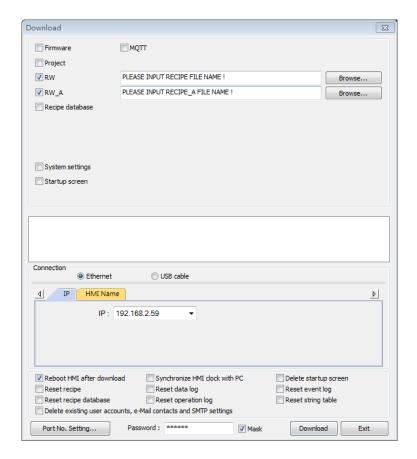
#### 17.2. Steps to Update Recipe Data with Ethernet or USB Cable

- 1. Open Utility Manager and click [Publish] » [Download].
- 2. Select [RW] and [RW\_A] and [Browse] for the source file.
- 3. After downloading, restart HMI, RW and RW\_A will be updated.

When [Reboot HMI after download] is selected, users don't have to manually reboot HMI. When [Reset recipe] check box is selected, the system will clear all the data in [RW] and [RW\_A] before downloading.



Transferring Recipe Data 17-3

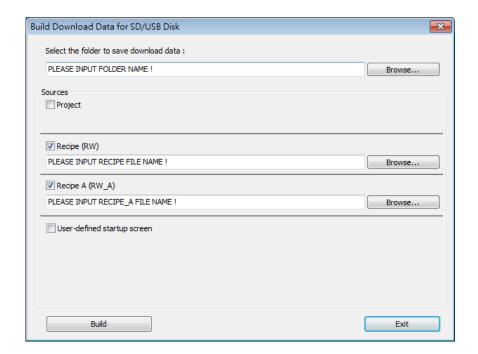


#### 17.3. Steps to Update Recipe Data with SD Card or USB Disk

- 1. Open Utility Manager and click [Publish] » [Build Download Data for SD/USB Disk].
- 2. Insert a SD card or USB disk into PC.
- 3. Click [Browse] to designate the file path.
- 4. Click [Build], EasyBuilder Pro will save the data in SD card or USB disk.



Transferring Recipe Data 17-4





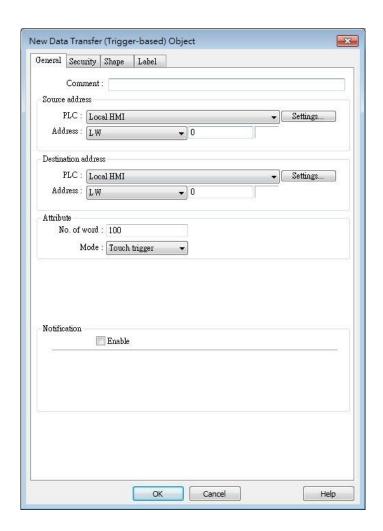
- When download data is successfully built, two folders can be found. The folder named according to the model used (e.g. emt3000, mt8000ie, mt8000xe, mtv, mtip...etc) is for storing project file, and the folder named history is for storing recipe data and data sampling / event log records.
- Please manually reboot HMI to update recipe data.

#### 17.4. Transferring Recipe Data

Use [Data Transfer (Trigger-based) Object] to transfer recipe data to a specific address, or save the data of this address in [RW] and [RW A].



Transferring Recipe Data 17-5



Setting	Description	
Source address	Sets the source of the data.	
Destination address	Sets the destination of the data to transfer to.	
Attribute	Sets the number of words to transfer from source	
	to destination.	

# 17.5. Saving Recipe Data Automatically

In order to prolong the life span of HMI flash memory, the system will automatically save the recipe data to HMI every minute. To avoid losing data when turning HMI off during the interval of saving data, system register [LB-9029: Save all recipe data to machine (set ON)] is provided. Set ON LB-9029 will make the system save recipe data once. Set ON [LB-9028: Reset all recipe data (set ON)], the system will clear all recipe data.



# 18. Macro Reference

This chapter describes the syntax, programming methods and usage of macro commands.

18.1.	Overview	18-2
18.2.	Instructions to use the Macro Editor	18-2
18.3.	Configuration	18-7
18.4.	Syntax	18-8
18.5.	Statement	18-14
18.6.	Function Blocks	18-19
18.7.	Built-In Function Block	18-22
18.8.	How to Create and Execute a Macro	18-99
18.9.	User Defined Macro Function	18-104
18.10.	Some Notes about Using the Macro	18-117
18.11.	Use the Free Protocol to Control a Device	18-117
18.12.	Compiler Error Message	18-122
18.13.	Sample Macro Code	18-128
18.14.	Macro TRACE Function	18-133
18.15.	Example of String Operation Functions	18-138
18.16.	Macro Password Protection	18-145
18.17.	Reading / Writing CAN bus Address Using Variable	18-147



### 18.1. Overview

Macros provide the additional functionality your application may need. Macros are automated sequences of commands that are executed at run-time. Macros allow you to perform tasks such as complex scaling operations, string handling, and user interactions with your projects. This chapter describes syntax, usage, and programming methods of macro commands.

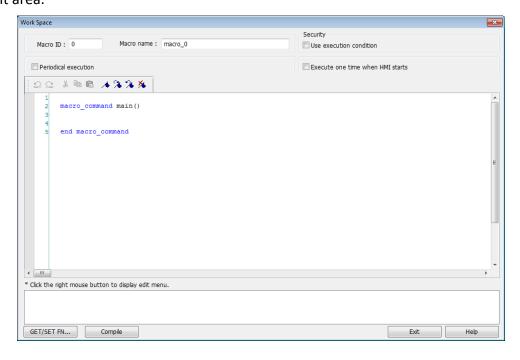
#### 18.2. Instructions to use the Macro Editor

Macro editor provides the following functions:

- Display line number
- Undo / Redo
- Cut / Copy / Paste
- Select All
- Toggle Bookmark / Previous Bookmark / Next Bookmark / Clear All Bookmarks
- Toggle All Outlining
- Security -> Use execution condition
- Periodical execution
- Execute one time when HMI starts

The instructions in the following part show you how to use these functions.

1. Open the macro editor; you'll see the line numbers displayed on the left-hand side of the edit area.





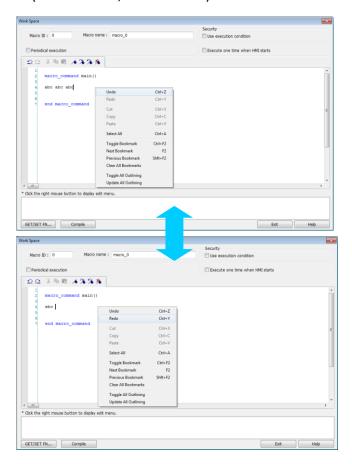
Right click on the edit area to open the pop-up menu as shown in the following figure. Disabled operations are colored grey, which indicates that it is not possible to use that function in the current status of the editor. For example, you should select some text to enable the copy function, otherwise it will be disabled. Keyboard shortcuts are also shown.



3. The toolbar provides [Undo], [Redo], [Cut], [Copy], [Paste], [Toggle Bookmark], [Next Bookmark], [Previous Bookmark] and [Clear All Bookmarks] buttons.

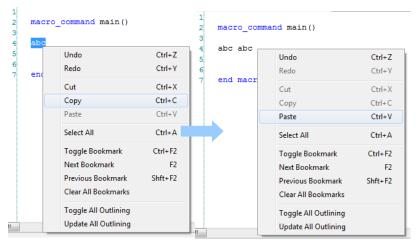


4. Any modification will enable the [Undo] function. [Redo] function will be enabled after the undo action is used. To perform the undo/redo, right click to select the item or use the keyboard shortcuts. (Undo: Ctrl+Z, Redo: Ctrl+Y).

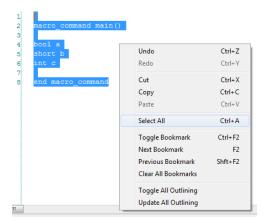




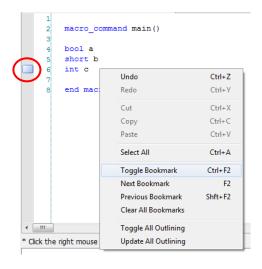
Select a word in the editor to enable the [Cut] and [Copy] function. After [Cut] or [Copy] is performed, [Paste] function is enabled.



6. Use [Select All] to include all the content in the edit area.

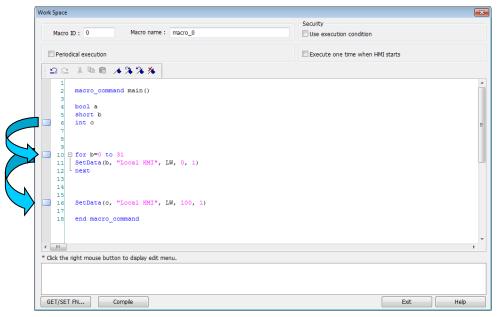


- 7. If the macro is too long, use bookmarks to manage and read the code with ease. The following illustration shows how it works.
- Move your cursor to the position in the edit area where to insert a bookmark. Right click, select [Toggle Bookmark]. There will be a blue little square that represents a bookmark on the left hand side of edit area.

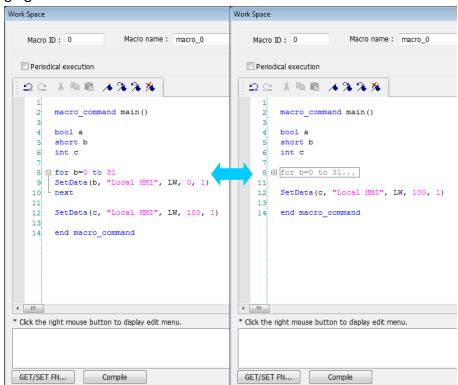




- If there is already a bookmark where the cursor is placed, select [Toggle Bookmark] to close it, otherwise to open it.
- Right click and select [Next Bookmark], the cursor will move to where the next bookmark locates. Selecting [Previous Bookmark] will move the cursor to the previous bookmark.



- Selecting [Clear All Bookmarks] will delete all bookmarks.

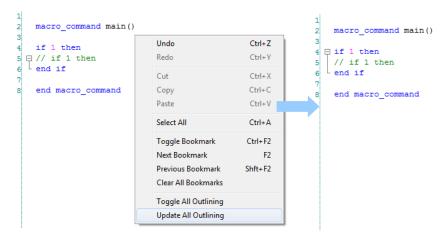




9. Right click to select [Toggle All Outlining] to open all folded macro code blocks.

```
macro command main()
      bool a
                                                                    macro command main()
      short b
      int c
                                                                     short b
                                                                     int c
  SetData(b, "Local HMI", LW, 0, 1)
                                                                 8 H for b=0 to 31...
                                                                                               Undo
                                                                                                                   Ctrl+Z
                                                                    SetData(c, "Local H
                                                                                               Redo
                                                                                                                   Ctrl+Y
      SetData(c, "Local HMI", LW, 100, 1)
 12
                                                                     end macro command
                                                                                               Сору
                                                                                                                   Ctrl+C
      end macro_command
                                                                                               Paste
                                                                                                                   Ctrl+V
                                                                                               Select All
                                                                                                                   Ctrl+A
                                                                                               Toggle Bookmark
                                                                                                                  Ctrl+F2
                                                                                               Next Bookmark
                                                                                               Previous Bookmark
                                                                                               Clear All Bookmarks
                                                              k the right mouse button to display
ck the right mouse button to display edit menu.
                                                                                               Toggle All Outlining
                                                                                               Update All Outlining
```

10. Sometimes the outlining might be incorrect since that the keywords are misjudged as shown in the following figure. To solve this problem, right click and select [Update All Outlining].

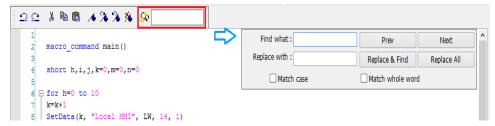


- 11. The statements enclosed in the following keywords are called a "block" of the macro code:
- Function block: sub end sub
- Iterative statements:
  - i. for next
  - ii. while wend
- Logical statements:
  - i. if end if
- Selective statements: select case end select
- 12. The macro editor is not a monopoly window. Returning to the main screen and editing the project with the Work Space window open is allowed.

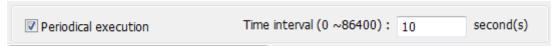




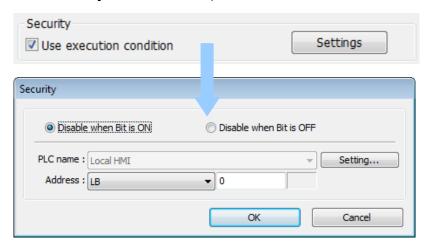
13. The macro editor provides Find and Replace features.



**14.** When [Periodical execution] is checked, this macro will be triggered periodically.



- **15.** Select [Security] » [Use execution condition] » [Settings] to enable security settings:
- [Disable when Bit is ON]: When Bit is ON, this macro is disabled.
- [Disable when Bit is OFF]: When Bit is OFF, this macro is disabled.



**16.** Select [Execute one time when HMI starts], this macro will be executed once when HMI starts up.

# 18.3. Configuration

A macro contains statements. The statements contain constants, variables, and operations. The statements are put in a specific order to create the desired output.

A macro has the following structure:



Global Variable Declaration	Optional	
Sub Function Block Declarations Local Variable Declarations	Optional	
End Sub		
macro_command main()  Local Variable Declarations  [Statements]	Required	
end macro_command	Required	

Macro must have one and only one main function which is the execution start point of macro. The format is:

macro\_command main()

# end macro\_command

Local variables are used within the main macro function or in a defined function block. Its value remains valid only within the specific block.

Global variables are declared before any function blocks and are valid for all functions in the macro. When local variables and global variables have the same declaration of name, only the local variables are valid.

The following example shows a simple macro which includes a variable declaration and a function call.

# **18.4.** Syntax

#### 18.4.1. Constants and Variables

#### 18.4.1.1. Constants

Constants are fixed values and can be directly written into statements. The formats are:



Constant Type	Note	Example
Decimal integer		345, -234, 0, 23456
Hexadecimal	Must begin with 0x	0x3b, 0xffff, 0x237
ASCII	Single character must be enclosed in single	ʻa', "data", "name"
	quotation marks and a string (group of	
	characters) must be enclosed in double	
	quotation marks. A backslash \ can be used	
	to escape the quotation marks contained in a	
	string. Therefore, to enclose a string	
	containing double quotation marks, please	
	use \" for the double quotation mark in the	
	string.	
Boolean		true, false

Here is an example using constants:

macro\_command main()

```
short A, B // A and B are variables
```

A = 1234

B = 0x12 // 1234 and 0x12 are constants

end macro command

# 18.4.1.2. Variables

Variables are names that represent information. The information can be changed as the variable is modified by statements.

#### **Naming Rules for Variables**

- A variable name must start with an alphabet.
- Variable names longer than 32 characters are not allowed.
- Reserved words cannot be used as variable names.

There are 8 different Variable types, 5 for signed data types and 3 for unsigned data types:

Variable Type	Description	Range
bool (boolean)	1 bit (discrete)	0, 1
char (character)	8 bits (byte)	+127 to -128
short (short integer)	16 bits (word)	+32767 to -32768
int (integer)	32 bits (double word)	+2147483647to -2147483648
float (floating point)	32 bits (double word)	
unsigned char	8 bits (byte)	0 to 255
unsigned short (short	16 bits (word)	0 to 65535



integer)		
unsigned int	32 bits (double word)	0 to 4,294,967,295
long (long integer)	64 bits (four words)	+281474976710655 ~
	(cMT / cMT X Series only)	-281474976710655
unsigned long (long	64 bits (four words)	0 ~ 281474976710655
integer)	(cMT / cMT X Series only)	0 2814/49/0/10055
double	64 bits (four words)	
	(cMT / cMT X Series only)	

#### **Declaring Variables**

Variables must be declared before being used. To declare a variable, specify the type before the variable name.

#### Example:

int a

short b, switch float pressure

unsigned short c

# **Declaring Arrays**

Macros support one-dimensional arrays (zero-based index). To declare an array of variables, specify the type and the variable name followed by the number of variables in the array enclosed in brackets "[]". The length of an array could be 1 to 4096. (Macros only support at most 4096 variables per macro).

#### Example:

int a[10]

short b[20], switch[30] float pressure[15]

The minimum array index is 0 and the maximum is (array size -1).

#### Example:

char data [100] // array size is 100

In this case, the minimum of array index is 0 and maximum of array index is 99 (=100-1)

# **Variable and Array Initialization**

There are two ways variables can be initialized:

By statement using the assignment operator (=)

## Example:

int a



float b[3]

a = 10

b[0] = 1

During declaration

char 
$$a = '5', b = 9$$

The declaration of arrays is a special case. The entire array can be initialized during declaration by enclosing comma separated values inside curly brackets "{}".

## Example:

float data[4] = {11, 22, 33, 44} // now data[0] is 11, data[1] is 22....

#### 18.4.2. Operators

Operators are used to designate how data is manipulated and calculated.

Operator	Description	Example
=	Assignment operator	pressure = 10
<b>Arithmetic Operators</b>	Description	Example
+	Addition	A = B + C
	Subtraction	A = B - C
*	Multiplication	A = B * C
	Division	A = B / C
% or mod	Modulo division (return remainder)	A = B % 5 or A = B mod 5

By default, integer numbers (1, 2,3..etc) are considered having integer data type; therefore, when division is carried out involving two integer numbers where the result should have decimal point, the decimal part will be removed. To avoid this, add .0 (1.0, 2.0, 3.0...etc) behind the dividend or the divisor to turn it into a floating point number calculation.

#### Examples:

A = 3/2 = 1 » 3 and 2 are both integers; therefore the result is an integer.

B = 3 / 2.0 = 1.5 » 3 is an integer whereas 2.0 is a floating point number, therefore the result is a floating point number.

C = 3.0 / 2 = 1.5 » 3.0 is a floating point number whereas 2 is an integer, therefore the result is a floating point number.

<b>Comparison Operators</b>	Description	Example
<	Less than	if A < 10 then B = 5
<=	Less than or equal to	if A <= 10 then B = 5
>	Greater than	if A > 10 then B = 5
>=	Greater than or equal to	if A >= 10 then B = 5
==	Equal to	if A == 10 then B = 5



<>	Not equal to	if A <> 10 then B = 5
Logic Operators	Description	Example
and	Logical AND	if A < 10 and B > 5 then C = 10
or	Logical OR	if A >= 10 or B > 5 then C = 10
xor	Logical Exclusive OR	if A xor 256 then B = 5
not	Logical NOT	if not A then B = 5

Shift and bitwise operators are used to manipulate bits of signed/unsigned character and integer variables. The priority of these operators is from left to right within the statement.

Shift Operators	Description	Example
<<	Shifts the bits in a bit set to	A = B << 8
	the left a specified number	
	of positions	
>>	Shifts the bits in a bit set to	A = B >> 8
	the right a specified number	
	of positions	

Bitwise Operators	Description	Example
&	Bitwise AND	A = B & 0xf
J	Bitwise OR	A = B   C
۸	Bitwise XOR	A = B ^ C
~	One's complement	A = ~B

#### **Priority of All Operators**

The overall priority of all operations from highest to lowest is as follows:

- 1. Operations within parenthesis are carried out first
- 2. Arithmetic operations
- 3. Shift and Bitwise operations
- 4. Comparison operations
- 5. Logic operations
- 6. Assignment

## **Reserved Keywords**

The following keywords are reserved for system. These keywords cannot be used as variable, array, or function names.



exit, macro command, for, to, down, step, next, return, bool, short, int, char, float, void, if, then, else, break, continue, set, sub, end, while, wend, true, false SQRT, CUBERT, LOG, LOG10, SIN, COS, TAN, COT, SEC, CSC, ASIN, ACOS, ATAN, BIN2BCD, BCD2BIN, DATE2ASCII, DATE2DEC, DEC2ASCII, FLOAT2ASCII, HEX2ASCII, DOUBLE2ASCII, ASCII2DEC, ASCII2FLOAT, ASCII2HEX, ASCII2DOUBLE, FILL, RAND, DELAY, SWAPB, SWAPW, LOBYTE, HIBYTE, LOWORD, HIWORD, GETBIT, SETBITON, SETBITOFF, INVBIT, ADDSUM, XORSUM, CRC, CRC8, CRC16\_CCITT, CRC16\_CCITT\_FALSE, CRC16\_X25, CRC16\_XMODEM, INPORT, OUTPORT, POW, GetCnvTagArrayIndex, GetError, GetData, GetDataEx, SetData, SetDataEx, SetRTS, GetCTS, Beep, SYNC TRIG MACRO, ASYNC TRIG MACRO, TRACE, FindDataSamplingDate, FindDataSamplingIndex, FindEventLogDate, FindEventLogIndex StringGet, StringGetEx, StringSet, StringSetEx, StringCopy, StringMid, StringMD5, StringDecAsc2Bin, StringBin2DecAsc, StringDecAsc2Float, StringFloat2DecAsc, StringHexAsc2Bin, StringBin2HexAsc, StringLength, StringCat, StringCompare, StringCompareNoCase, StringFind, StringReverseFind, StringFindOneOf, StringIncluding, StringExcluding, StringToUpper, StringToLower, StringToReverse, StringTrimLeft, StringTrimRight, StringInsert, String2Unicode, Unicode2Utf8, UnicodeCat, UnicodeCompare, UnicodeCopy, UnicodeExcluding, Uft82Unicode



# 18.5. Statement

#### 18.5.1. Definition Statement

This covers the declaration of variables and arrays. The formal construction is as follows:

type name

This defines a variable with name as "name" and type as "type".

Example:

int A // define a variable A as an integer

type name[constant]

This defines an array variable called "name" with size as "constant" and type as "type".

Example:

int B[10] // where define a variable B as a one-dimensional array of size 10

#### 18.5.2. Assignment Statement

Assignment statements use the assignment operator to move data from the expression on the right side of the operator to the variable on the left side. An expression is the combination of variables, constants and operators to yield a value.

VariableName Expression

Example

A = 2 where a variable A is assigned to 2

#### 18.5.3. Logical Statements

Logical statements perform actions depending on the condition of a boolean expression.

The syntax is as follows:

#### **Single-Line Format**

If <Condition> then

[Statements]

else

[Statements]

end if



Example:

if a == 2 then

b = 1

else

b = 2

end if

# **Block Format**

If <Condition> then
 [Statements]
else if <Condition-n> then
[Statements]
else
 [Statements]
end if

Example:

if a == 2 then

b = 1

else if a == 3 then

b = 2

else

b = 3

end if

# **Syntax description**

if	Must be used to begin the statement.
<condition></condition>	Required. This is the controlling statement. It is FALSE when the <condition> evaluates to 0 and TRUE when it evaluates to non-zero.</condition>
then	Must precede the statements to execute if the <condition> evaluates to TRUE.</condition>
[Statements]	It is optional in block format but necessary in single-line format without else. The statement will be executed when the <condition> is TRUE.</condition>
else if	Optional. The else if statement will be executed when the relative <pre><condition-n> is TRUE.</condition-n></pre>
<condition-n></condition-n>	Optional. see <condition></condition>
else	Optional. The else statement will be executed when <condition> and <condition-n> are both FALSE.</condition-n></condition>
end if	Must be used to end an if-then statement.



#### 18.5.4. Selective Statements

The select-case construction can be used like multiple if-else statements and perform selected actions depending on the value of the given variable. When the matched value is found, all the actions below will be executed until a break statement is met. The syntax is as follows:

#### Format without a Default Case

```
Select Case [variable]
Case [value]
[Statements]
break
end Select
```

## Example:

```
Select Case A
Case 1
b=1
break
end Select
```

#### Format with a Default Case (Case else)

```
Select Case [variable]
Case [value]
[Statements]
break
Case else
[Statements]
break

end Select
```

#### Example:

```
Select Case A

Case 1

b=1

break

Case else

b=0

break

end Select
```



# Multiple cases in the same block

```
Select Case [variable]
Case [value1]
  [Statements]
Case [value2]
  [Statements]
  break
end Select
```

# Example:

Select Case A
Case 1
break
Case 2
b=2
break
Case 3
b=3
break
end Select

# **Syntax description**

Select Case	Must be used to begin the statement.	
[variable]	Required. The value of this variable will be compared to the value of each case.	
Case else	Optional. It represents the default case. If none of the cases above are matched, the statements under default case will be executed. When a default case is absent, it will skip directly to the end of the select-case statements if there is no matched case.	
break	Optional. The statements under the matched case will be executed until the break command is reached. If a break command is absent, it simply keeps on executing next statement until the end command is reached.	
end Select	Indicates the end of the select-case statements.	

#### 18.5.5. Iterative Statements

Iterative statements control loops and repetitive tasks depending on condition. There are two types of iterative statements.



#### 18.5.5.1. for-next Statements

The for-next statement runs for a fixed number of iterations. A variable is used as a counter to track the progress and test for ending conditions. Use this for fixed execution counts. The syntax is as follows:

```
for [Conunter] = <StartValue> to <EndValue> [step <StepValue>]
   [Statements]
next [Counter]
```

#### Or

```
for [Conunter] = <StartValue> to <EndValue> [step <StepValue>]
   [Statements]
next [Counter]
```

## Example:

```
for a = 0 to 10 step 2
b = a
next a
```

# **Syntax description**

•		
for	Must be used to begin the statement	
[Counter]	Required. This is the controlling statement. The result of evaluating the variable is used as a test of comparison.	
<startvalue></startvalue>	Required. The initial value of [Counter]	
to/down	Required. This determines if the <step> increments or decrements the <counter>.  "to" increments <counter> by <stepvalue>.  "down" decrements <counter> by <stepvalue>.</stepvalue></counter></stepvalue></counter></counter></step>	
<endvalue></endvalue>	Required. The test point. If the <counter> is greater than this value, the macro exits the loop.</counter>	
step	Optional. Specifies that a <stepvalue> other than one is to be used.</stepvalue>	
[StepValue]	Optional. The increment/decrement step of <counter>. It can be omitted when the value is 1 If [step <stepvalue>] are omitted the step value defaults to 1.</stepvalue></counter>	
[Statements]	Optional. Statements to execute when the evaluation is TRUE. "for-next" loops may be nested.	
next	Required.	
[Counter]	Optional. This is used when nesting for-next loops.	



#### 18.5.5.2. while-wend Statements

The while-wend statement runs for an unknown number of iterations. A variable is used to test for ending conditions. When the condition is TRUE, the statements inside are executed repetitively until the condition becomes FALSE. The syntax is as follows.

```
while <Condition>
[Statements]
wend
```

## Example:

while a < 10 a = a + 10

wend

### **Syntax description**

while	Must be used to begin the statement.	
continue	Required. This is the controlling statement. When it is TRUE, the loop begins execution. When it is FALSE, the loop terminates.	
wend	Indicates the end of the while-end statements.	

#### 18.5.5.3. Other Control Commands

break	Used in for-next and while-wend. It skips immediately to the end of the iterative statement.
continue	Used in for-next and while-wend. It ends the current iteration of a loop and starts the next one.
return	The return command inside the main block can force the macro to stop anywhere. It skips immediately to the end of the main block.

# 18.6. Function Blocks

Function blocks are useful for reducing repetitive codes. It must be defined before use and supports any variable and statement type. A function block could be called by putting its name followed by parameters in parenthesis. After the function block is executed, it returns the value to the caller function where it is used as an assignment value or as a condition. A return type is not required in function definition, which means that a function block does not have to return a value. The parameters can also be ignored in function definition while the function has no need to take any parameters from the caller. The syntax is as follows:

#### Function definition with return type



```
sub type <name> [(parameters)]

Local variable declarations

[Statements]

[return [value]]

end sub
```

# Example:

```
sub int Add(int x, int y)
           int result
            result = x + y
            return result
        end sub
       macro_command main()
            int a = 10, b = 20, sum
            sum = Add(a, b)
       end macro_command
or:
  sub int Add()
            int result, x=10, y=20
            result = x + y
            return result
        end sub
       macro_command main()
            int sum
            sum = Add()
       end macro_command
```

# Function definition without return type

```
sub <name> [(parameters)]
    Local variable declarations
    [Statements]
end sub
```

# Example:

```
sub Add(int x, int y)
int result
result = x +y
```



```
end sub

macro_command main()

int a = 10, b = 20

Add(a, b)

end macro_command

or:

sub Add()

int result, x=10, y=20

result = x +y

end sub

macro_command main()

Add()

end macro_command
```

# **Syntax description**

Syntax description	
sub	Must be used to begin the function block
type	Optional. This is the data type of value that the function returns. A function block is not always necessary to return a value.
(parameters)	Optional. The parameters hold values that are passed to the function. The passed parameters must have their type declared in the parameter field and assigned a variable name.  For example: sub int MyFunction(int x, int y). x and y would be integers passed to the function. This function is called by a statement that looks similar to this: ret = MyFunction(456, pressure) where "pressure" must be integer according to the definition of function.  Notice that the calling statement can pass hard coded values or variables to the function. After this function is executed, an integer values is return to 'ret'.
Local variable declaration	Variables that are used in the function block must be declared first. This is in addition to passed parameters. In the above example x and y are variables that the function can used. Global variables are also available for use in function block.
[Statements]	Statements to execute
[return [value]]	Optional. Used to return a value to the calling statement. The value can be a constant or a variable. Return also ends function block execution. A function block is not always necessary to return a value, but, when the return type is defined in the beginning of the definition of function, the return command is needed.
end sub	Must be used to end a function block.



# **18.7.** Built-In Function Block

EasyBuilder Pro has many built-in functions for retrieving and transferring data to the devices, data management and mathematical functions.

# 18.7.1. Table of Functions

Please click on one of the function names in the table to see its details.

Function Name	Description	
Device Functions		
<u>GetData</u>	Receives data from the device.	
<u>GetDataEx</u>	Receives data from the device and continues executing next	
	command even if there's no response from the device.	
<u>GetError</u>	Gets an error code.	
<u>SetData</u>	Sends data to the device.	
<u>SetDataEx</u>	Sends data to the device and continues executing next command	
	even if there's no response from the device.	
Free Protocol Functions		
<u>GetCTS</u>	Gets CTS signal of RS-232.	
INPORT	Reads data from a COM port or Ethernet port.	
INPORT2	Reads data from a COM port or Ethernet port and then wait for a	
	the designated period of time.	
INPORT3	Reads data from a COM port or Ethernet port according to the	
	specified data size.	
INPORT4	Reads data from a COM port or Ethernet port and then stops	
	reading data when the ending character is reached.	
<u>OUTPORT</u>	Sends out the specified data to a device or controller via a COM	
	port or Ethernet port.	
<u>PURGE</u>	Clears the input and output buffers associated with the COM	
	port.	
<u>SetRTS</u>	Raises or lowers the RTS signal of RS-232.	
Process Control Functions		
ASYNC TRIG MACRO	Triggers the execution of a macro asynchronously in a running	
	macro.	
SYNC TRIG MACRO	Triggers the execution of a macro synchronously in a running	
	macro. The current macro will pause until the end of execution	
	of this called macro.	



DELAY	Suspends the execution of the current macro for at least the		
specified interval (time).			
Data Operation Functions			
FILL	Sets array elements to the specified value.		
<u>SWAPB</u>	Exchanges the high-byte and low-byte data of a 16-bit (Word).		
SWAPW	Exchanges the high-word and low-word data of a 32-bit (DINT).		
<u>LOBYTE</u>	Retrieves the low byte of a 16-bit source.		
<u>HIBYTE</u>	Retrieves the high byte of a 16-bit source.		
LOWORD	Retrieves the low word of a 32-bit source.		
HIWORD	Retrieves the high word of a 32-bit source.		
INVBIT	Inverts the state of designated bit position of a data source.		
<u>SETBITON</u>	Changes the state of designated bit position of a data source to		
	1.		
<u>SETBITOFF</u>	Changes the state of designated bit position of a data source to		
	0.		
GETBIT Gets the state of designated bit position of a data source.			
Data Type Conversion Functions			
ASCII2DEC	Converts an ASCII string to a decimal value.		
<u>ASCII2FLOAT</u>	Converts an ASCII string to a float value.		
<u>ASCII2HEX</u>	Converts an ASCII string to a hexadecimal value.		
ASCII2DOUBLE	Converts an ASCII string (source) to a double value.		
	This function is only supported on cMT /cMT X models.		
BIN2BCD	Converts a binary-type value to a BCD-type value.		
BCD2BIN	Converts a BCD-type value to a binary-type value.		
DATE2ASCII	Converts current date to an ASCII string.		
DATE2DEC	Converts current date to a decimal value.		
DEC2ASCII	Converts a decimal value to an ASCII string.		
FLOAT2ASCII	Converts a floating value to an ASCII string.		
HEX2ASCII	Converts a hexadecimal value to an ASCII string.		
DOUBLE2ASCII	Converts a double value (source) to an ASCII string.		
	This function is only supported on cMT /cMT X models.		
StringDecAsc2Bin	Converts a decimal string to an integer.		
StringBin2DecAsc	Converts an integer to a decimal string.		
StringDecAsc2Float	Converts a decimal string to floats.		
StringFloat2DecAsc	Converts a float to a decimal string.		
StringHexAsc2Bin	Converts a hexadecimal string to binary data.		
StringBin2HexAsc	Converts binary data to a hexadecimal string.		



	String Operation Functions	
String2Unicode	Converts all the characters in the source string to Unicode.	
StringCat	Appends source string to destination string.	
<u>StringCompare</u>	Performs a case-sensitive comparison of two strings.	
StringCompareNoCase	Performs a case-insensitive comparison of two strings.	
StringCopy	Copies one string to another.	
StringExcluding	Retrieves a substring of the source string that contains	
	characters that are not in the set string.	
<u>StringFind</u>	Returns the zero-based index of the first character of substring in	
	the source string that matches the target string.	
StringFindOneOf	Returns the zero-based index of the first character in the source	
	string that is also in the target string.	
<u>StringGet</u>	Receives data from the device.	
<u>StringGetEx</u>	Receives data from the device and continues executing next	
	command even if there's no response from the device.	
StringIncluding	Retrieves a substring of the source string that contains	
	characters in the set string, beginning with the first character in	
	the source string and ending when a character is found in the	
	source string that is not in the target string.	
StringInsert	Inserts a string in a specific location within the destination string	
	content.	
<u>StringLength</u>	Obtains the length of a string.	
StringMD5	Generates a string using MD5 message-digest algorithm.	
<u>StringMid</u>	Retrieves a character sequence from the specified offset of the	
	source string.	
StringReverseFind	Returns the position of the last occurrence of target string in the	
	source string.	
<u>StringSet</u>	Sends data to the device.	
<u>StringSetEx</u>	Sends data to the device and continues executing next command	
	even if there's no response from the device.	
StringToUpper	Converts all the characters in the source string to uppercase	
	characters.	
StringToLower	Converts all the characters in the source string to lowercase	
	characters.	
<u>StringToReverse</u>	Reverses the characters in the source string	
<u>StringTrimLeft</u>	Trims the leading specified characters in the set buffer from the	
	source string.	



source string.  Unicode2utf8 Converts a Unicode string to a UTF8 string.  UnicodeCat Concatenates two Unicode Strings UnicodeCompare Performs case-sensitive comparison between two Unicode strings.  UnicodeCopy Copies a Unicode string. UnicodeExcluding Retrieves a substring of the source string that contains characters that are not in the set string.  UnicodeLength Obtains the length of a Unicode string.  Utf82Unicode Converts a UTF8 string to a Unicode string.  Mathematics Functions  SQRT Calculates the square root of source.  CUBERT Calculates the cube root of source.  CUS Calculates the exponential of source.  COS Calculates the sine of source.  COS Calculates the tangent of source.  COT Calculates the totangent of source.  SEC Calculates the scoant of source.  SEC Calculates the coseant of source.  CSC Calculates the arc sine of source.  CSC Calculates the arc sine of source.  COS Calculates the arc tangent of source.				
Unicode2utf8 UnicodeCat Concatenates two Unicode Strings UnicodeCompare Performs case-sensitive comparison between two Unicode strings. UnicodeCopy Copies a Unicode string. UnicodeExcluding Retrieves a substring of the source string that contains characters that are not in the set string. UnicodeLength Obtains the length of a Unicode string. Utf82Unicode Converts a UTF8 string to a Unicode string.  Mathematics Functions  SQRT Calculates the square root of source. CUBERT Calculates the exponential of source.  COS Calculates the sine of source.  COS Calculates the tosine of source.  COS Calculates the tangent of source.  COT Calculates the tangent of source.  COT Calculates the cotangent of source.  COS Calculates the coscant of source.  COS Calculates the rosine of source.  COS Calculates the arc sine of	<u>StringTrimRight</u>	Trims the trailing specified characters in the set buffer from the		
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ACOS Calculates the arc cosine of source.  ATAN Calculates the arc tangent of source.  LOG Calculates the natural logarithm of a number.  LOG10 Calculates the base-10 logarithm of a number.  RAND Calculates a random integer.  CEIL Get the smallest integral value that is not less than input.  FLOOR Get the largest integral value that is not greater than input.	<u>CSC</u>	Calculates the cosecant of source.		
ATAN  Calculates the arc tangent of source.  LOG  Calculates the natural logarithm of a number.  LOG10  Calculates the base-10 logarithm of a number.  RAND  Calculates a random integer.  CEIL  Get the smallest integral value that is not less than input.  FLOOR  Get the largest integral value that is not greater than input.	ASIN	Calculates the arc sine of source.		
LOG Calculates the natural logarithm of a number.  LOG10 Calculates the base-10 logarithm of a number.  RAND Calculates a random integer.  CEIL Get the smallest integral value that is not less than input.  FLOOR Get the largest integral value that is not greater than input.	<u>ACOS</u>	Calculates the arc cosine of source.		
LOG10 Calculates the base-10 logarithm of a number.  RAND Calculates a random integer.  CEIL Get the smallest integral value that is not less than input.  FLOOR Get the largest integral value that is not greater than input.	<u>ATAN</u>	Calculates the arc tangent of source.		
Calculates a random integer.  CEIL Get the smallest integral value that is not less than input.  FLOOR Get the largest integral value that is not greater than input.	LOG	Calculates the natural logarithm of a number.		
CEIL Get the smallest integral value that is not less than input.  FLOOR Get the largest integral value that is not greater than input.	<u>LOG10</u>	Calculates the base-10 logarithm of a number.		
FLOOR Get the largest integral value that is not greater than input.	RAND	Calculates a random integer.		
	<u>CEIL</u>	Get the smallest integral value that is not less than input.		
ROUND Get the integral value that is nearest the input.	<u>FLOOR</u>	Get the largest integral value that is not greater than input.		
	ROUND	Get the integral value that is nearest the input.		
Statistics Functions				
AVERAGE Gets the average value from array.	<u>AVERAGE</u>	Gets the average value from array.		
HARMEAN Gets the harmonic mean value from array.	<u>HARMEAN</u>	Gets the harmonic mean value from array.		
MAX Gets the maximum value from array.	MAX	Gets the maximum value from array.		
MEDIAN Gets the median value from array.	MEDIAN	Gets the median value from array.		
MIN Gets the minimum value from array.	MIN	Gets the minimum value from array.		
STDEVP Gets the standard deviation value from array.	STDEVP	Gets the standard deviation value from array.		



CTD ELVC			
STDEVS	Gets the sample standard deviation value from array.		
Recipe Database Functions			
<u>RecipeGetData</u>	Gets recipe Data.		
RecipeQuery	Queries recipe data.		
<u>RecipeQueryGetData</u>	Gets the data in the query result obtained by RecipeQuery.		
RecipeQueryGetRecordID	Gets the record ID numbers of those records gained by RecipeQuery.		
RecipeSetData	Writes data to recipe database.		
	Data / Event Log Functions		
<u>FindDataSamplingDate</u>	Finds the date of the specified data sampling file.		
FindDataSamplingIndex	Finds the file index of the specified data sampling file.		
<u>FindEventLogDate</u>	Finds the date of the specified event log file.		
FindEventLogIndex	Finds the file index of the specified event log file.		
Checksum Functions			
ADDSUM	Adds up the elements of an array to generate a checksum.		
XORSUM	Uses XOR to calculate the checksum.		
BCC	Same as XORSUM.		
CRC	Calculates the 16-bit CRC of variables to generate a checksum.		
CRC8	Calculates the 8-bit CRC of variables to generate a checksum.		
CRC16 CCITT	Calculates the 16-bit CRC of variables to generate a CRC16_CCITT checksum.		
CRC16 CCITT FALSE	Calculates the 16-bit CRC of variables to generate a		
CRC16 X25	CRC16_CCITT_FALSE checksum.  Calculates the 16-bit CRC of variables to generate a CRC16_X25 checksum.		
CRC16 XMODEM	Calculates the 16-bit CRC of variables to generate a CRC16_XMODEM checksum.		
Miscellaneous Functions			
Beep	Plays beep sound.		
<u>Buzzer</u>	Turns ON / OFF the buzzer.		
TRACE	Prints out the current value of variables during run-time of macro for debugging.		
<u>GetCnvTagArrayIndex</u>	When an user-defined conversion tag uses array, the [Read conversion] subroutine can get the relative array index before doing conversion.		

# 18.7.2. Device

Name	GetData
Syntax	GetData(read_data[start], device_name, device_type, address_offset,
	data_count)



or

GetData(read\_data, device\_name, device\_type, address\_offset, 1)

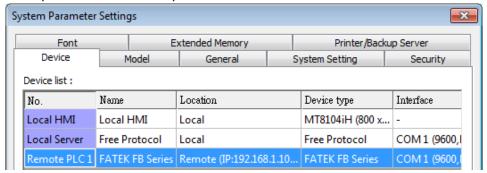
#### Description

Receives data from the device. When the data is not read successfully, the function will not continue executing the next command. Data is stored into read\_data[start]~read\_data[start + data\_count - 1].

data\_count is the amount of received data. In general, read\_data is an array, but if data\_count is 1, read\_data can be an array or an ordinary variable. Below are two methods to read one word data from the device.

macro\_command main()
short read\_data\_1[2], read\_data\_2
GetData(read\_data\_1[0], "FATEK KB Series", RT, 5, 1)
GetData(read\_data\_2, "FATEK KB Series", RT, 5, 1)
end macro\_command

Device\_name is the device name enclosed in the double quotation marks (") and this name has been defined in the device list of system parameters as follows (see FATEK KB Series):



Device\_type is the device type and encoding method (binary or BCD) of the device data. For example, if device\_type is LW\_BIN, it means the register is LW and the encoding method is binary. If use BIN encoding method, "\_BIN" can be ignored.

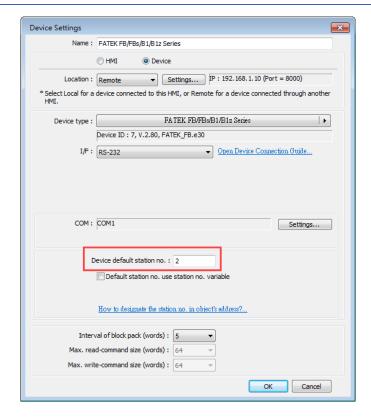
If *device\_type* is LW\_BCD, it means the register is LW and the encoding method is BCD.

Address offset is the address offset in the device.

For example, GetData(read\_data\_1[0], "FATEK KB Series", RT, 5, 1) represents that the address offset is 5.

If address\_offset uses the format -"N#AAAAA", N indicates that device's station number is N. AAAAA represents the address offset. This format is used while multiple devices or controllers are connected to a single serial port. For example, GetData(read\_data\_1[0], "FATEK KB Series", RT, 2#5, 1) represents that the device's station number is 2. If GetData() uses the default station number defined in the device list as follows, it is not necessary to define station number in address offset.





The number of registers actually read from depends on both the type of the *read\_data* variable and the value of the number of *data\_count*.

type of read_data	data_count	actual number of 16-bit register read
char (8-bit)	1	1
char (8-bit)	2	1
bool (8-bit)	1	1
bool (8-bit)	2	1
short (16-bit)	1	1
short (16-bit)	2	2
int (32-bit)	1	2
int (32-bit)	2	4
float (32-bit)	1	2
float (32-bit)	2	4

When a GetData() is executed using a 32-bit data type (int or float), the function will automatically convert the data. For example,

macro\_command main()
float f
GetData(f, "MODBUS", 6x, 2, 1) // f will contain a floating point value
end macro\_command

Example

macro\_command main()
bool a
bool b\_array[30]
char c



```
char c_array[20]
short s
short s array[50]
int i
int i_array[10]
float f
float f array[15]double g[10]
// get the state of LB2 to the variable a
GetData(a, "Local HMI", LB, 2, 1)
// get 30 states of LB0 ~ LB29 to the variables b array[0] ~ b array[29]
GetData(b array[0], "Local HMI", LB, 0, 30)
// get lower byte of LW-0 to the variable c
// note that char is 1 byte, and a LW address occupies 2 bytes (1 word).
Reading the first byte in a word register will get the lower byte of the word.
// Ex: when the value in LW-0 is 0x0201, then variable c will read 0x01
GetData(c, "Local HMI", LW, 0, 1)
// get data of LW1 ~ LW10 to the c array[0] ~ c array[19]
GetData(c array[0], "Local HMI", LB, 0, 20)
// get one word from LW-2 to the variable s
GetData(s, "Local HMI", LW, 2, 1)
// get 50 words from LW-0 ~ LW-49 to the variables s array[0] ~ s array[49]
GetData(s array[0], "Local HMI", LW, 0, 50)
// get 2 words from LW-6 ~ LW-7 to the variable e
// Ex: When value in LW-6 is 0x0002, in LW-7 is 0x0001, then i will read
0x00010002(65538)
// note that int occupies 2 words (32-bit)
GetData(i, "Local HMI", LW, 6, 1)
// get 20 words (10 integer values) from LW-0 ~ LW-19 to variables i array[0]
~ i_array[9], note that type of i_array[10] is int.
GetData(i array[0], "Local HMI", LW, 0, 10)
// get data from LW-10 ~ LW-11 to the variable f
// note that type of variable f is float.
GetData(f, "Local HMI", LW, 10, 1)
// get 30 words (15 float variables) from LW-0 ~ LW-29 to variables f array[0]
~ f array[14], note that type of f array[15] is float.
// note that float occupies 2 words (32-bit)
```



GetData(f_array[0], "Local HMI", LW, 0, 15)
end macro_command

Name	GetDataEx		
Syntax	GetDataEx(read_data[start], device_name, device_type, address_offset, data_count) or GetDataEx(read_data, device_name, device_type, address_offset, 1)		
Description	Receives data from the device and continues executing next command even when the read operation fails.  Descriptions of read_data, device_name, device_type, address_offset and data_count are the same as GetData.		
Example	macro_command main() bool a bool b bool b_array[30] char c char c_array[20] short s short s_array[50] int i int i_array[10] float f float f_array[15]  // get the state of LB2 to the variable a GetDataEX(a, "Local HMI", LB, 2, 1)  // get 30 states of LB0 ~ LB29 to the variables b_array[0] ~ b_array[29] GetDataEX(b_array[0], "Local HMI", LB, 0, 30)  // get lower byte of LW-0 to the variable c // note that char is 1 byte, and a LW address occupies 2 bytes (1 word). Reading the first byte in a word register will get the lower byte of the word. // Ex: when the value in LW-0 is 0x0201, then variable c will read 0x01 GetDataEX(c, "Local HMI", LW, 0, 1)  // get data of LW1 ~ LW10 to the c_array[0] ~ c_array[19] GetDataEX(c_array[0], "Local HMI", LB, 0, 20)  // get one word from LW-2 to the variable s GetDataEX(s, "Local HMI", LW, 2, 1)  // get 50 words from LW-0 ~ LW-49 to the variables s_array[0] ~ s_array[49]		
	GetDataEX(s_array[0], "Local HMI", LW, 0, 50)		



```
// get 2 words from LW-6 ~ LW-7 to the variable e
// Ex: When value in LW-6 is 0x0002, in LW-7 is 0x0001, then i will read
0x00010002(65538)
// note that int occupies 2 words (32-bit)
GetDataEX(i, "Local HMI", LW, 6, 1)
// get 20 words (10 integer values) from LW-0 ~ LW-19 to variables i_array[0]
~ i_array[9], note that type of i_array[10] is int.
GetDataEX(i array[0], "Local HMI", LW, 0, 10)
// get data from LW-10 ~ LW-11 to the variable f
// note that type of variable f is float.
GetDataEX(f, "Local HMI", LW, 10, 1)
// get 30 words (15 float variables) from LW-0 ~ LW-29 to variables f_array[0]
~ f_array[14], note that type of f_array[15] is float.
// note that float occupies 2 words (32-bit)
GetDataEX(f_array[0], "Local HMI", LW, 0, 15)
end macro command
```

Name	GetError	
Syntax	GetError (err)	
Description	Gets an error code.	
Example	ple macro_command main()	
	short err	
	char byData[10]	
	GetDataEx(byData[0], "MODBUS RTU", 4x, 1, 10)// read 10 bytes	
	GetDataEx(byData[b], Wobbos KTO, 4x, 1, 10/// Tead 10 bytes	
	// if err is equal to 0, it is successful to execute GetDataEx()	
	GetErr(err)// save an error code to err	
	end macro_command	
	Error code:	
	0: Normal	
	1: GetDataEx error	
	2: SetDataEx error	

Name	SetData
Syntax	SetData(send_data[start], device_name, device_type, address_offset, data_count) or



## SetData(send\_data, device\_name, device\_type, address\_offset, 1)

#### Description

Sends data to the device. When the data is not written successfully, the function will not continue executing the next command. Data is defined in <code>send\_data[start]~send\_data[start+data\_count-1]</code>.

data\_count is the amount of sent data. In general, send\_data is an array, but if data\_count is 1, send\_data can be an array or an ordinary variable. Below are two methods to send one word data.

```
macro_command main()
short send_data_1[2] = { 5, 6}, send_data_2 = 5
SetData(send_data_1[0], "FATEK KB Series", RT, 5, 1)
SetData(send_data_2, "FATEK KB Series", RT, 5, 1)
end macro_command
```

device\_name is the device name enclosed in the double quotation marks (") and this name has been defined in the device list of system parameters. device\_type is the device type and encoding method (binary or BCD) of the device data. For example, if device\_type is LW\_BIN, it means the register is LW and the encoding method is binary. If use BIN encoding method, "\_BIN" can be ignored.

If *device\_type* is LW\_BCD, it means the register is LW and the encoding method is BCD.

address\_offset is the address offset in the device.

For example, SetData(read\_data\_1[0], "FATEK KB Series", RT, 5, 1) represents that the address offset is 5.

If address\_offset uses the format —"N#AAAAA", N indicates that device's station number is N. AAAAA represents the address offset. This format is used while multiple devices or controllers are connected to a single serial port. For example, SetData(read\_data\_1[0], "FATEK KB Series", RT, 2#5, 1) represents that the device's station number is 2. If SetData () uses the default station number defined in the device list, it is not necessary to define station number in address offset.

The number of registers actually sends to depends on both the type of the *send\_data* variable and the value of the number of *data\_count*.

type of <i>read_data</i>	data_count	actual number of 16-bit register send
char (8-bit)	1	1
char (8-bit)	2	1
bool (8-bit)	1	1
bool (8-bit)	2	1
short (16-bit)	1	1
short (16-bit)	2	2
int (32-bit)	1	2
int (32-bit)	2	4



float (32-bit)		1	2		
	float (32-bit)	2	4		
	When a SetData() is executed using a 32-bit data type (int or float), the functio				
	will automatically send int-format or float-format data to the device. For				

on example,

```
macro command main()
float f = 2.6
SetData(f, "MODBUS", 6x, 2, 1) // will send a floating point value to the
device
end macro command
```

# Example

```
macro_command main()
int i
```

bool a = true bool b[30] short c = falseshort d[50] int e = 5 int f[10]

for i = 0 to 29 b[i] = true next i

for i = 0 to 49 d[i] = i \* 2next i

for i = 0 to 9 f[i] = i \* 3next i

// set the state of LB2 SetData(a, "Local HMI", LB, 2, 1) // set the states of LB0 ~ LB29 SetData(b[0], "Local HMI", LB, 0, 30) // set the value of LW-2 SetData(c, "Local HMI", LW, 2, 1) // set the values of LW-0  $\sim$  LW-49 SetData(d[0], "Local HMI", LW, 0, 50)

// set the values of LW-6 ~ LW-7, note that the type of e is int SetData(e, "Local HMI", LW, 6, 1)



```
// set the values of LW-0 ~ LW-19
// 10 integers equal to 20 words, since each integer value occupies 2 words.
SetData(f[0], "Local HMI", LW, 0, 10)
end macro_command
```

Name	SetDataEx
Syntax	SetDataEx (send_data[start], device_name, device_type, address_offset, data_count) or SetDataEx (send_data, device_name, device_type, address_offset, 1)
Description	Sends data to the device and continues executing next command even when the write operation fails.  Descriptions of send_data, device_name, device_type, address_offset and data_count are the same as SetData.
Example	macro_command main() int i bool a = true bool b[30] short c = false short d[50] int e = 5 int f[10]  for i = 0 to 29 b[i] = true next i  for i = 0 to 49 d[i] = i * 2 next i  for i = 0 to 9 f [i] = i * 3 next i  // set the state of LB2 SetDataEx (a, "Local HMI", LB, 2, 1)  // set the states of LB0 ~ LB29 SetDataEx (b[0], "Local HMI", LB, 0, 30)  // set the value of LW-2
	// set the value of LW-2 SetDataEx (c, "Local HMI", LW, 2, 1)



```
// set the values of LW-0 ~ LW-49
SetDataEx (d[0], "Local HMI", LW, 0, 50)

// set the values of LW-6 ~ LW-7, note that the type of e is int
SetDataEx (e, "Local HMI", LW, 6, 1)

// set the values of LW-0 ~ LW-19
// 10 integers equal to 20 words, since each integer value occupies 2 words.
SetDataEx (f[0], "Local HMI", LW, 0, 10)

end macro_command
```



### 18.7.3. Free Protocol

Name	GetCTS
Syntax	GetCTS(com_port, result)
Description	Gets CTS state for RS232.  com_port refers to the COM port number. It can be either a variable or a constant. result is used for receiving the CTS signal. It must be a variable.  This command receives CTS signal and stores the received data in the result variable. When the CTS signal is pulled high, it writes 1 to result, otherwise, it writes 0.
Example	macro_command main() char com_port=1 char result  GetCTS(com_port, result) // get CTS signal of COM1  GetCTS (1, result) // get CTS signal of COM1  end macro_command

Name	INPORT
Syntax	INPORT(read_data[start], device_name, read_count, return_value)
Description	Reads data from a COM port or the Ethernet port. The data is stored to  read_data[start]~ read_data[start + read_count - 1].  device_name is the name of a device defined in the device table and the device  must be a "Free Protocol"-type device.  read_count is the required amount of reading and can be a constant or a  variable.  If the function is used successfully to get sufficient data, return_value will  return the length of the read word.
Example	Below is an example of executing an action of reading holding registers of a MODBUS device.  // Read Holding Registers macro_command main() char command[32], response[32] short address, checksum short read_no, return_value, read_data[2]  FILL(command[0], 0, 32)// command initialization FILL(response[0], 0, 32)  command[0] = 0x1// station no command[1] = 0x3// function code : Read Holding Registers



```
address = 0
HIBYTE(address, command[2])
LOBYTE(address, command[3])
read_no = 2// read 2 words (4x_1 and 4x_2)
HIBYTE(read no, command[4])
LOBYTE(read no, command[5])
CRC(command[0], checksum, 6)
LOBYTE(checksum, command[6])
HIBYTE(checksum, command[7])
// send out a 'Read Holding Registers" command
OUTPORT(command[0], "MODBUS RTU Device", 8)
// read responses for a 'Read Holding Registers" command
INPORT(response[0], "MODBUS RTU Device", 9, return_value)
if return value > 0 then
read_data[0] = response[4] + (response[3] << 8)// data in 4x_1
read_data[1] = response[6] + (response[5] << 8)// data in 4x_2
SetData(read_data[0], "Local HMI", LW, 100, 2)
end if
end macro_command
```

Name	INPORT2
Syntax	INPORT2(response[start], device_name, receive_len, wait_time)
Description	Reads data from a COM port or the Ethernet port. The data read will be saved in the response array.  device_name is the name of a device defined in the device table and the device must be a "Free Protocol"-type device.  receive_len stores the length of the data received. It must be a variable.  receive_len can't exceed the size of response array.  wait_time (in millisecond) can be a constant or variable. After the data is read, if there's no upcoming data during the designated time interval, the function returns.
Example	macro_command main()  short wResponse[6], receive_len, wait_time=20  INPORT2(wResponse[0], "Free Protocol", receive_len, wait_time) // wait_time unit : millisecond



if receive_len > 0 then SetData(wResponse[0], "Local HMI", LW, 0, 6) // set responses to LW0 end if
end macro_command

INPORT3
<pre>INPORT3(response[start], device_name, read_count, receive_len)</pre>
Reads data from a communication port (COM Port or Ethernet Port). The data read will be saved in the response array.  The amount of data to be read can be specified. The data that is not read yet will be stored in HMI buffer memory for the next read operation, in order to prevent losing data.  device_name is the name of a device defined in the device table and the device must be a "Free Protocol"-type device.  read_count stores the length of the data read each time.  receive_len stores the length of the data received. It must be a variable.  receive_len can't exceed the size of response array.
macro_command main()  short wResponse[6], receive_len  INPORT3(wResponse[0], "Free Protocol", 6, receive_len) // read 6 words  if receive_len >= 6 then  SetData(wResponse[0], "Local HMI", LW, 0, 6) // set responses to LW0  end if  end macro_command

Name	INPORT4
Syntax	INPORT4(response[start], device_name, receive_len, tail_ascii)
Description	Reads data from a communication port (COM Port or Ethernet Port). The data read will be saved in the response array.  tail_ascii specifies the ending character. Data reading will stop when the ending character is reached.  device_name is the name of a device defined in the device table and the device must be a "Free Protocol"-type device.  receive_len stores the length of the data received. It must be a variable.  receive_len can't exceed the size of response array.
Example	macro_command main()



ch	har tail_ascii = 0x03// == ETX
sh	hort wResponse[1024], receive_len
II	NPORT4(wResponse[0], "Free Protocol", receive_len, 0x0d)// 0x0d == CR
II.	NPORT4(wResponse[0], "Free Protocol", receive_len, tail_ascii)
if	receive_len >= 6 then
Se	etData(wResponse[0], "Local HMI", LW, 0, 6)// set responses to LW0
	nd if
er	nd macro_command

Name	OUTPORT
Syntax	OUTPORT(source[start], device_name, data_count)
Description	Sends out the specified data from source[start] to source[start + data_count -1] to the device via a COM port or an Ethernet port.  device_name is the name of a device defined in the device table and the device must be a "Free Protocol"-type device.  data_count is the amount of sent data and can be a constant or a variable.
Example	To use an OUTPORT function, a "Free Protocol" device must be created first as follows:
	System Parameter Settings    Extended Memory



address = 0 HIBYTE(address, command[2]) LOBYTE(address, command[3])
command[4] = 0xff// force bit on command[5] = 0
CRC(command[0], checksum, 6)
LOBYTE(checksum, command[6]) HIBYTE(checksum, command[7])
// send out a "Write Single Coil" command OUTPORT(command[0], "MODBUS RTU Device", 8)
end macro_command

Name	PURGE
Syntax	PURGE (com_port)
Description	com_port refers to the COM port number which ranges from 1 to 3. It can be
-	either a variable or a constant. This function is used to clear the input and
	output buffers associated with the COM port.
Example	macro_command main()
	int com_port=3
	PURGE (com_port)
	PURGE (1)
	end macro_command

Name	SetRTS
Syntax	SetRTS(com_port, source)
Description	Sets RTS state for RS232.  com_port refers to the COM port number. It can be either a variable or a constant. source can be either a variable or a constant.  This command raise RTS signal while the value of source is greater than 0 and lower RTS signal while the value of source or under the O
Example	lower RTS signal while the value of source equals to 0.  macro_command main() char com_port=1 char value=1  SetRTS(com_port, value) // raise RTS signal of COM1 while value>0  SetRTS(1, 0) // lower RTS signal of COM1 end macro_command



### **18.7.4.** Process Control

Name	ASYNC_TRIG_MACRO
Syntax	ASYNC_TRIG_MACRO (macro_id or name)
Description	Triggers the execution of a macro asynchronously (use macro_id or macro name to designate this macro) in a running macro.  The current macro will continue executing the following instructions after triggering the designated macro; in other words, the two macros will be active simultaneously.  macro_id can be a constant or a variable.
Example	macro_command main() char ON = 1, OFF = 0  SetData(ON, "Local HMI", LB, 0, 1)  ASYNC_TRIG_MACRO(5)// call a macro (its ID is 5)  ASYNC_TRIG_MACRO("macro_1") // call a macro (its name is macro_1)  SetData(OFF, "Local HMI", LB, 0, 1)  end macro_command

Name	DELAY					
Syntax	DELAY(time)					
Description	Suspends the execution of the current macro for at least the specified interval (time). The unit of time is millisecond.  time can be a constant or a variable.					
Example	macro_command main() int time == 500  DELAY(100)// delay 100 ms  DELAY(time)// delay 500 ms  end macro_command					

Name	SYNC_TRIG_MACRO						
Syntax	SYNC_TRIG_MACRO(macro_id or name)						
Description	Triggers the execution of a macro synchronously (use <i>macro_id</i> or macro name to designate this macro) in a running macro.  The current macro will pause until the end of execution of this called macro. <i>macro_id</i> can be a constant or a variable.						
Example	macro_command main() char ON = 1, OFF = 0						



SetData(ON, "Local HMI", LB, 0, 1)				
SYNC_TRIG_MACRO(5) // call a macro (its ID is 5)				
SYNC_TRIG_MACRO("macro_1") // call a macro (its name is macro_1)				
SetData(OFF, "Local HMI", LB, 0, 1)				
end macro_command				

# 18.7.5. Data Operation

Name	FILL						
Syntax	FILL(source[start], preset, count)						
Description	Sets array elements from 'source[start]' to 'source[start + count - 1]' to the specified value (preset).  source and start must be a variable, and preset can be a constant or variable.						
Example	<pre>macro_command main() char result[4] char preset  FILL(result[0], 0x30, 4) // result[0] is 0x30, result[1] is 0x30, , result[2] is 0x30, , result[3] is 0x30  preset = 0x31 FILL(result[0], preset, 2) // result[0] is 0x31, result[1] is 0x31  end macro_command</pre>						

Name	SWAPB					
Syntax	SWAPB(source, result)					
Description	Exchanges the high-byte and low-byte data of a 16-bit source into result. source can be a constant or a variable. result must be a variable.					
Example	macro_command main() short source, result  SWAPB(0x5678, result)// result is 0x7856  source = 0x123 SWAPB(source, result)// result is 0x2301  end macro_command					



Name	SWAPW							
Syntax	SWAPW(source, result)							
Description	Exchanges the high-word and low-word data of a 32-bit source into result.							
	source can be a constant or a variable. result must be a variable.							
Example	macro_command main()							
	int source, result							
	SWAPW (0x12345678, result)// result is 0x56781234							
	source = 0x12345							
	SWAPW (source, result)// result is 0x23450001							
	and macro, command							
	end macro_command							

Name	LOBYTE					
Syntax	LOBYTE(source, result)					
Description	Retrieves the low byte of a 16-bit <i>source</i> into <i>result</i> .  source can be a constant or a variable. result must be a variable.					
Example	macro_command main() short source, result  LOBYTE(0x1234, result)// result is 0x34  source = 0x123 LOBYTE(source, result)// result is 0x23  end macro_command					

Name	HIBYTE							
Syntax	HIBYTE(source, result)							
Description	Retrieves the high byte of a 16-bit source into result.							
	source can be a constant or a variable. result must be a variable.							
Example	macro_command main()							
	short source, result							
	HIBYTE(0x1234, result)// result is 0x12							
	source = 0x123 HIBYTE(source, result)// result is 0x01							
	end macro_command							



Name	LOWORD							
Syntax	LOWORD(source, result)							
Description	Retrieves the low word of a 32-bit source into result.							
	source can be a constant or a variable. result must be a variable.							
Example	macro_command main()							
	int source, result							
	LOWORD(0x12345678, result)// result is 0x5678							
	source = 0x12345							
	LOWORD(source, result)// result is 0x2345							
	end macro_command							

Name	HIWORD					
Syntax	HIWORD(source, result)					
Description	Retrieves the high word of a 32-bit source into result.  source can be a constant or a variable. result must be a variable.					
Example	macro_command main() int source, result  HIWORD(0x12345678, result)// result is 0x1234  source = 0x12345  HIWORD(source, result)// result is 0x0001  end macro_command					

Name	INVBIT					
Syntax	INVBIT(source, result, bit_pos)					
Description	Inverts the state of designated bit position of a data (source), and puts changed data into result.  source and bit pos can be a constant or a variable. result must be a variable.					
Example	macro_command main() int source, result short bit_pos  INVBIT(4, result, 1)// result = 6  source = 6 bit_pos = 1 INVBIT(source, result, bit_pos)// result = 4					



	_		
end macro	command		
ena macro	COMMINIANO		

Name	SETBITON
Syntax	SETBITON(source, result, bit_pos)
Description	Changes the state of designated bit position of a data (source) to 1, and puts
-	changed data into <i>result</i> .
	source and bit_pos can be a constant or a variable.
	result must be a variable.
Example	macro_command main()
	int source, result
	short bit_pos
	SETBITON(1, result, 3)// result is 9
	source = 0
	bit_pos = 2
	SETBITON (source, result, bit_pos)// result is 4
	end macro_command

Name	SETBITOFF
Syntax	SETBITOFF(source, result, bit_pos)
Description	Changes the state of designated bit position of a data (source) to 0, and puts
	changed data into <i>result</i> .
	source and bit_pos can be a constant or a variable.
	result must be a variable.
Example	macro_command main()
	int source, result
	short bit_pos
	SETBITOFF(9, result, 3)// result is 1
	source = 4
	bit_pos = 2
	SETBITOFF(source, result, bit_pos)// result is 0
	end macro_command

Name	GETBIT
Syntax	GETBIT(source, result, bit_pos)
Description	Gets the state of designated bit position of a data (source) into result.
	result value will be 0 or 1.
	source and bit_pos can be a constant or a variable.
	result must be a variable.



Example	macro_command main()
	int source, result
	short bit_pos
	GETBIT(9, result, 3)// result is 1
	source = 4
	bit_pos = 2
	GETBIT(source, result, bit_pos)// result is 1
	end macro_command



## 18.7.6. Data Type Conversion

Name	ASCII2DEC
Syntax	ASCII2DEC(source[start], result, len)
Description	Transforms a string (source) into a decimal value saved to a variable (result).  The length of the string is len. The first character of the string is source[start].  source and len can be a constant or a variable. result must be a variable. start must be a constant.
Example	macro_command main() char source[4] short result  source[0] = '5'  source[1] = '6' source[2] = '7' source[3] = '8'  ASCII2DEC(source[0], result, 4) // result is 5678  end macro_command

Name	ASCII2FLOAT
Syntax	ASCII2FLOAT(source[start], result, len)
Description	Transforms a string (source) into a float value saved to a variable (result).  The length of the string is len. The first character of the string is source[start].  source and len can be a constant or a variable. result must be a variable. start must be a constant.
Example	macro_command main() char source[4] float result  source[0] = '5'  source[1] = '6' source[2] = '.' source[3] = '8'  ASCII2FLOAT (source[0], result, 4) // result is 56.8
	end macro_command



Name	ASCII2HEX
Syntax	ASCII2HEX (source[start], result, len)
Description	Transforms a string (source) into a hexadecimal value saved to a variable (result).  The length of the string is len. The first character of the string is source[start]. source and len can be a constant or a variable. result must be a variable. start must be a constant.
Example	macro_command main() char source[4] short result  source[0] = '5'  source[1] = '6' source[2] = '7' source[3] = '8'  ASCII2HEX (source[0], result, 4) // result is 0x5678  end macro_command

Name	ASCII2DOUBLE
Syntax	ASCII2DOUBLE (source[start], result, count)
Description	Transforms a string (source) into a double value saved to a variable (result).  The length of the string is count. The first character of the string is source[start].  source and count can be a constant or a variable. result must be a variable.  start must be a constant.
Example	macro_command main()  char source[4] = {'5', '6', '.', '8'}  double result  ASCII2DOUBLE(source[0], result, 4)// result == 56.8  SetData(result, "Local HMI", LW, 100, 1)
	end macro_command

Name	BIN2BCD
Syntax	BIN2BCD(source, result)
Description	Transforms a binary-type value (source) into a BCD-type value (result). source can be a constant or a variable. result must be a variable.
Example	macro_command main()



short source, result
BIN2BCD(1234, result)// result is 0x1234
source = 5678 BIN2BCD(source, result)// result is 0x5678
end macro_command

Name	BCD2BIN
Syntax	BCD2BIN(source, result)
Description	Transforms a BCD-type value ( <i>source</i> ) into a binary-type value ( <i>result</i> ). source can be a constant or a variable.
Example	macro_command main()
	short source, result  BCD2BIN(0x1234, result)// result is 1234  source = 0x5678  BCD2BIN(source, result)// result is 5678
	end macro_command

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Name	DATE2ASCII
Syntax	DATE2ASCII(day_offset, date[start], count, [separator])
Description	Transforms a date with day_offset added into an ASCII string, and saves it to an array (date).  count represents the length of the string and the unit of length depends on result's type.  separator separates year, month, and day. By default, the separator is "/".  day offset and count can be a constant or a variable.
	start and separator must be a constant.
Example	macro_command main() char result[10]  DATE2ASCII(5, result[0], 10) // result[0]~[9] == "2019/02/16"// today is 2019/02/11  DATE2ASCII(5, result[0], 10,2019/02/16"// today is 2019/02/11-16"// today is 2019/02/11  end macro_command



Name	DATE2DEC
Syntax	DATE2DEC(day_offset, date)
Description	Transforms a date with day_offset added into a decimal value saved to a variable (date).  day_offset can be a constant or a variable. date must be a variable.
Example	macro_command main() int day_offset = 5, date  DATE2DEC(0, date)
	end macro_command

Nama	DEC2ASCII
Name	
Syntax	DEC2ASCII(source, result[start], len)
Description	Transforms a decimal value (source) into an ASCII string and saves it to an array (result).  len represents the length of the string and the unit of length depends on result's type., i.e. if result's type is "char" (the size is byte), the length of the string is (byte * len). If result's type is "short" (the size is word), the length of the string is (word * len), and so on.  The first character is put into result[start], the second character is put into result[start + 1], and the last character is put into result[start + (len -1)]. source and len can be a constant or a variable. result must be a variable. start must be a constant.
Example	macro_command main() short source char result1[4] short result3[6] source = 5678  DEC2ASCII(source, result1[0], 4) // result1[0] is '5', result1[1] is '6', result1[2] is '7', result1[3] is '8' // the length of the string (result1) is 4 bytes( = 1 * 4) DEC2ASCII(source, result2[0], 4) // result2[0] is '5', result2[1] is '6', result2[2] is '7', result2[3] is '8' // the length of the string (result2) is 8 bytes( = 2 * 4)  source=-123 DEC2ASCII(source, result3[0], 6) // result1[0] is '-', result1[1] is '0', result1[2] is '0', result1[3] is '1' // result1[4] is '2', result1[5] is '3'



// the length of the string (result1) is 6 bytes( = 1 * 6)
end macro_command

Name	FLOAT2ASCII
Syntax	FLOAT2ASCII(source, result[start], len)
Description	Transforms a floating value (source) into ASCII string saved to an array (result). len represents the length of the string and the unit of length depends on result's type., i.e. if result's type is "char" (the size is byte), the length of the string is (byte * len). If result's type is "short" (the size is word), the length of the string is (word * len), and so on. source and len can be a constant or a variable. result must be a variable. start must be a constant.
Example	macro_command main() float source char result[4]  source = 56.8 FLOAT2ASCII (source, result[0], 4) // result[0] is '5', result[1] is '6', result[2] is '.', result[3] is '8' end macro_command

Name	HEX2ASCII
Syntax	HEX2ASCII(source, result[start], len)
Description	Transforms a hexadecimal value (source) into ASCII string saved to an array (result).  len represents the length of the string and the unit of length depends on result's type., i.e. if result's type is "char" (the size is byte), the length of the string is (byte * len). If result's type is "short" (the size is word), the length of the string is (word * len), and so on.
	source and len can be a constant or a variable. result must be a variable. start must be a constant.
Example	macro_command main() short source char result[4]
	source = 0x5678  HEX2ASCII (source, result[0], 4)  // result[0] is '5', result[1] is '6', result[2] is '7', result[3] is '8'  end macro_command



Name	DOUBLE2ASCII
Syntax	DOUBLE2ASCII (source, result[start], count)
Description	Transforms a double value (source) into ASCII string saved to an array (result).
	count represents the length of the string and the unit of length depends on
	result's type., i.e. if result's type is "char" (the size is byte), the length of the
	string is (byte * count). If result's type is "short" (the size is word), the length of
	the string is (word * count), and so on.
	source and count can be a constant or a variable. result must be a variable.
	start must be a constant.
	This function is only supported on cMT / cMT X models.
Example	macro_command main()
	double source = 56.8
	char result[4]
	DOUBLE2ASCII(source, result[0], 4)
	// result[0] == '5', result[1] == '6', result[2] == '.', result[3] == '8'
	,,[2] 3,
	end macro command

Name	StringDecAsc2Bin
Syntax	success = StringDecAsc2Bin(source[start], destination)
	or
	success = StringDecAsc2Bin("source", destination)
Description	This function converts a decimal string to an integer. It converts the decimal
	string in source parameter into an integer, and stores it in the destination
	variable.
	The source string parameter accepts both static string (in the form: "source")
	and char array (in the form: source[start]).
	Destination must be a variable, to store the result of conversion.
	This function returns a Boolean indicating whether the process has been
	successfully completed. If so, it returns true; otherwise it returns false. The
	string can only contain these characters: +, -, and 0 to 9. If the string contains
	other characters, it returns false.
	The success field is optional.
Example	macro_command main()
	char src1[5]="12345"
	int result1
	bool success1
	success1 = StringDecAsc2Bin(src1[0], result1)
	// success1=true, result1 is 12345
	char crc2[5] = " 6780"
	char src2[5] = "-6789" short result2
	bool success2
	טטטו אוננפאצ



```
success2 = StringDecAsc2Bin(src2[0], result2)

// success2 = true , result2 is -6789

char result3
bool success3
success3 = StringDecAsc2Bin("32768", result3)

// success3=true, but the result exceeds the data range of result3

char src4[2]="4b"
char result4
bool success4
success4 = StringDecAsc2Bin (src4[0], result4)

// success4=false, because src4 contains characters other than '+' or '-' and '0' to '9'

end macro_command
```

	StringBin2DecAsc
Syntax	success = StringBin2DecAsc (source, destination[start])
Description	This function converts an integer to a decimal string. It converts the integer in source parameter into a decimal string, and stores it in the destination buffer. Source can be either a constant or a variable.  Destination must be an one-dimensional char array, to store the result of conversion.  This function returns a Boolean indicating whether the process has been successfully completed. If so, it returns true; otherwise it returns false. If the length of decimal string after conversion exceeds the size of destination buffer, it returns false.  The success field is optional.
Example	macro_command main() int src1 = 2147483647 char dest1[20] bool success1 success1 = StringBin2DecAsc(src1, dest1[0]) // success1=true, dest1="2147483647"  short src2 = 0x3c char dest2[20] bool success2 success2 = StringBin2DecAsc(src2, dest2[0]) // success2=true, dest2="60"  int src3 = 2147483647 char dest3[5]



success3 = StringBin2DecAsc(src3, dest3[0]) // success3=false, dest3 remains the same.
end macro_command

Name	StringDecAsc2Float
Syntax	success = StringDecAsc2Float (source[start], destination)
	or
	success = StringDecAsc2Float ("source", destination)
Description	This function converts a decimal string to floats. It converts the decimal string in source parameter into float, and stores it in the destination variable. The source string parameter accepts both static string (in the form: "source") and char array (in the form: source[start]).  Destination must be a variable, to store the result of conversion.  This function returns a Boolean indicating whether the process has been successfully completed. If so, it returns true; otherwise it returns false. If the source string contains characters other than '0' to '9' or '.', it returns false.  The success field is optional.
Example	macro_command main() char src1[10]="12.345" float result1 bool success1 success1 = StringDecAsc2Float(src1[0], result1) // success1=true, result1 is 12.345
	float result2 bool success2 success2 = StringDecAsc2Float("1.234567890", result2) // success2=true, but the result exceeds the data range of result2, which // might result in loss of precision
	char src3[2]="4b" float result3 bool success3 success3 = StringDecAsc2Float(src3[0], result3) // success3=false, because src3 contains characters other than '0' to '9' or // '.' end macro_command

Name	StringFloat2DecAsc
Syntax	success = StringFloat2DecAsc(source, destination[start])
Description	This function converts a float to a decimal string. It converts the float in source parameter into a decimal string, and stores it in the destination buffer.
	Source can be either a constant or a variable.
	Destination must be an one-dimensional char array, to store the result of



	conversion.  This function returns a Boolean indicating whether the process has been successfully completed. If so, it returns true; otherwise it returns false. If the length of decimal string after conversion exceeds the size of destination buffer, it returns false.  The success field is optional.
Example	macro_command main() float src1 = 1.2345 char dest1[20] bool success1 success1 = StringFloat2DecAsc(src1, dest1[0]) // success1=true, dest1="1.2345"
	float src2 = 1.23456789 char dest2 [20] bool success2 success2 = StringFloat2DecAsc(src2, dest2 [0]) // success2=true, but it might lose precision
	float src3 = 1.2345 char dest3[5] bool success3 success3 = StringFloat2DecAsc(src3, dest3 [0]) // success3=false, dest3 remains the same.
	end macro_command

Name	StringHexAsc2Bin
Syntax	success = StringHexAsc2Bin (source[start], destination)
	or
	success = StringHexAsc2Bin ("source", destination)
Description	This function converts a hexadecimal string to binary data. It converts the
	hexadecimal string in source parameter into binary data, and stores it in the
	destination variable.
	The source string parameter accepts both static string (in the form: "source")
	and char array (in the form: source[start]).
	Destination must be a variable, to store the result of conversion.
	This function returns a Boolean indicating whether the process has been
	successfully completed. If so, it returns true; otherwise it returns false. If the
	source string contains characters other than '0' to '9', 'a' to 'f' or 'A' to 'F', it
	returns false.
	The success field is optional.
Example	macro_command main()
	char src1[5]="0x3c"
	int result1



```
bool success1
success1 = StringHexAsc2Bin(src1[0], result1)
// success1=true, result1 is 3c

short result2
bool success2
success2 = StringDecAsc2Bin("1a2b3c4d", result2)
// success2=true, result2=3c4d.The result exceeds the data range of
// result2

char src3[2]="4g"
char result3
bool success3
success3 = StringDecAsc2Bin (src3[0], result3)
// success3=false, because src3 contains characters other than '0' to '9'
// , 'a' to 'f' or 'A' to 'F'
end macro_command
```

Name	StringBin2HexAsc
Syntax	success = StringBin2HexAsc (source, destination[start])
Description	This function converts binary data to a hexadecimal string. It converts the binary data in source parameter into a hexadecimal string, and stores it in the destination buffer.  Source can be either a constant or a variable.  Destination must be an one-dimensional char array, to store the result of conversion.  This function returns a Boolean indicating whether the process has been successfully completed. If so, it returns true; otherwise it returns false. If the length of hexadecimal string after conversion exceeds the size of destination buffer, it returns false.  The success field is optional.  Please note that this function cannot convert negative values.
Example	macro_command main() int src1 = 20 char dest1[20] bool success1 success1 = StringBin2HexAsc(src1, dest1[0]) // success1=true, dest1="14"  short src2 = 0x3c char dest2[20] bool success2 success2 = StringBin2HexAsc(src2, dest2[0]) // success2=true, dest2="3c"



<pre>int src3 = 0x1a2b3c4d char dest3[6] bool success3 success3 = StringBin2HexAsc(src3, dest3[0]) // success3=false, dest3 remains the same.</pre>
end macro_command

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# 18.7.7. String Operation

Name	String2Unicode
Syntax	result = String2Unicode("source", destination[start])
Description	Converts all the characters in the source string to Unicode and stores the result in the destination buffer. The length of result string after conversion will be stored to result.  Source must be a constant but not a variable.
Example	macro_command main()  char dest[20] int result result = String2Unicode("abcde", dest[0]) // "result" will be set to 10. result = String2Unicode("abcdefghijklmno", dest[0]) // "result" will be set to 20. // "result" will be the length of converted Unicode string end macro_command

Name	StringCat
Syntax	success = StringCat (source[start], destination[start])
	or
	success = StringCat ("source", destination[start])
Description	This function appends source string to destination string. It adds the contents
	of source string to the last of the contents of destination string.
	The source string parameter accepts both static string (in the form: "source")
	and char array (in the form: source[start]).
	Destination must be an one-dimensional char array.
	This function returns a Boolean indicating whether the process has been
	successfully completed. If so, it returns true; otherwise it returns false. If the
	length of result string after concatenation exceeds the max. size of destination
	buffer, it returns false.
	The success field is optional.
Example	macro_command main()



```
char src1[20]="abcdefghij"
char dest1[20]="1234567890"
bool success1
success1= StringCat(src1[0], dest1[0])
// success1=true, dest1="123456790abcdefghij"

char dest2 [10]="1234567890"
bool success2
success2= StringCat("abcde", dest2 [0])
// success2=false, dest2 remains the same.

char src3[20]="abcdefghij"
char dest3[20]
bool success3
success3= StringCat(src3[0], dest3[15])
// success3=false, dest3 remains the same.

end macro_command
```

form: "string1") and
mparison. If two
alse.



bool ret3 ret3= StringCompare(a3[0], b3[0]) // ret3=false
end macro_command

Name	StringCompareNoCase
Syntax	ret = StringCompareNoCase(str1[start], str2[start])
	ret = StringCompareNoCase("string1", str2[start])
	ret = StringCompareNoCase(str1[start], "string2")
	ret = StringCompareNoCase("string1", "string2")
Description	Performs a case-insensitive comparison of two strings.
	The two string parameters accept both static string (in the form: "string1") and
	char array (in the form: str1[start]).
	This function returns a Boolean indicating the result of comparison. If two
	strings are identical, it returns true. Otherwise it returns false.
	The ret field is optional.
Example	macro_command main()
	char a1[20]="abcde"
	char b1[20]="ABCDE"
	bool ret1
	ret1= StringCompareNoCase(a1[0], b1[0])
	// ret1=true
	char a2[20]="abcde"
	char b2[20]="abcde"
	bool ret2
	ret2= StringCompareNoCase(a2[0], b2[0])
	// ret2=true
	char a3 [20]="abcde"
	char b3[20]="abcdefg"
	bool ret3
	ret3= StringCompareNoCase(a3[0], b3[0])
	// ret3=false
	end macro_command

Name	StringCopy
Syntax	success = StringCopy ("source", destination[start])
	or
	success = StringCopy (source[start], destination[start])
Description	Copies one string to another. This function copies a static string (which is
	enclosed in quotes) or a string that is stored in an array to the destination buffer.



The source string parameter accepts both static string (in the form: "source") and char array (in the form: source[start]). destination[start] must be an one-dimensional char array. This function returns a Boolean indicating whether the process has been successfully completed. If so, it returns true; otherwise it returns false. If the length of source string exceeds the max. size of destination buffer, it returns false and the content of destination remains the same. The success field is optional. macro\_command main() **Example** char src1[5]="abcde" char dest1[5] bool success1 success1 = StringCopy(src1[0], dest1[0]) // success1=true, dest1="abcde" char dest2[5] bool success2 success2 = StringCopy("12345", dest2[0]) // success2=true, dest2="12345" char src3[10]="abcdefghij" char dest3[5] bool success3 success3 = StringCopy(src3[0], dest3[0]) // success3=false, dest3 remains the same. char src4[10]="abcdefghij" char dest4[5] bool success4 success4 = StringCopy(src4[5], dest4[0]) // success4=true, dest4="fghij" end macro\_command



Name	StringExcluding
Syntax	success = StringExcluding (source[start], set[start], destination[start]) success = StringExcluding ("source", set[start], destination[start]) success = StringExcluding (source[start], "set", destination[start]) success = StringExcluding ("source", "set", destination[start])
Description	Retrieves a substring of the source string that contains characters that are not in the set string, beginning with the first character in the source string and ending when a character is found in the source string that is also in the target string.  The source string and set string parameters accept both static string (in the form: "source") and char array (in the form: source[start]).  This function returns a Boolean indicating whether the process has been successfully completed. If so, it returns true; otherwise it returns false. If the length of retrieved substring exceeds the size of destination buffer, it returns false.
Example	macro_command main() char src1[20]="cabbageabc" char set1[20]="ge" char dest1[20] bool success1 success1 = StringExcluding(src1[0], set1[0], dest1[0]) // success1=true, dest1="cabba" char src2[20]="cabbage"
	char dest2[20] bool success2 success2 = StringExcluding(src2[0], "abc", dest2[0]) // success2=true, dest2=""
	char set3[20]="ge" char dest3[4] bool success3 success3 = StringExcluding("cabbage", set3[0], dest3[0]) // success3=false, dest3 remains the same.
	end macro_command

Name	StringFind
Syntax	position = StringFind (source[start], target[start])
	position = StringFind ("source", target[start])
	position = StringFind (source[start], "target")
	position = StringFind ("source", "target")
Description	Returns the position of the first occurrence of target string in the source string.
	The two string parameters accept both static string (in the form: "source") and



	char array (in the form: source[start]).  This function returns the zero-based index of the first character of substring in the source string that matches the target string. Notice that the entire sequence of characters to find must be matched. If there is no matched substring, it returns -1.
Example	macro_command main() char src1[20]="abcde" char target1[20]="cd" short pos1 pos1= StringFind(src1[0], target1[0]) // pos1=2  char target2[20]="ce" short pos2 pos2= StringFind("abcde", target2[0]) // pos2=-1  char src3[20]="abcde" short pos3 pos3= StringFind(src3[3], "cd") // pos3=-1  end macro_command

Name	StringFindOneOf
Syntax	position = StringFindOneOf (source[start], target[start])
	position = StringFindOneOf ("source", target[start])
	position = StringFindOneOf (source[start], "target")
	position = StringFindOneOf ("source", "target")
Description	Returns the position of the first character in the source string that matches any
	character contained in the target string.
	The two string parameters accept both static string (in the form: "source") and
	char array (in the form: source[start]).
	This function returns the zero-based index of the first character in the source
	string that is also in the target string. If there is no match, it returns -1.



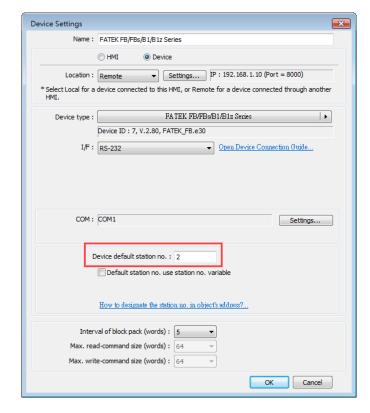
Example	macro_command main() char src1[20]="abcdeabcde" char target1[20]="sdf" short pos1 pos1= StringFindOneOf(src1[0], target1[0])
	<pre>// pos1=3  char src2[20]="abcdeabcde" short pos2 pos2= StringFindOneOf(src2[1], "agi") // pos2=4</pre>
	char target3 [20]="bus" short pos3 pos3= StringFindOneOf("abcdeabcde", target3[1]) // pos3=-1 end macro_command

Name	C+rin	gGet						
Name								
Syntax		StringGet(read_data[start], device_name, device_type, address_offset,						
		_count)						
Description	Rece	ives data fr	om the devi	ce. The String d	lata i	s stored into <i>r</i> e	ead_data[star	∕t]~
	read	_data[start	+ data_cour	nt - 1]. read_da	ıta m	ust be a one-d	limensional ch	าar
	array	/.						
	Data	_count is th	ne number o	f received char	acter	rs, it can be eit	her a constan	t or
	a var	iable.						
	Devi	ce_name is	the device n	ame enclosed	in th	e double quot	ation marks ("	')
	and	this name h	as been defi	ined in the devi	ice lis	st of system pa	arameters as	
	follo	ws (see FAT	EK KB Series	):				_
	S	stem Paramete	r Settings				X	Ŋ
		Font		Extended Memory		Printer/Backı	up Server	
		Device	Model	General	S	ystem Setting	Security	
		Device list :						
		No.	Name	Location		Device type	Interface	
		Local HMI	Local HMI	Local		MT8104iH (800 x		
		Local Server	Free Protocol	Local		Free Protocol	COM 1 (9600,I	
		Remote PLC 1	FATEK FB Series	Remote (IP:192.168	3.1.10	FATEK FB Series	COM 1 (9600,I	
	Devi	ce_type is t	he device ty	pe and encodir	ng me	ethod (binary o	or BCD) of the	<u> </u>
	devi	ce data. For	example, if	device_type is	LW_I	BIN, it means t	he register is	LW
	and	the encodir	g method is	binary. If use B	BIN ei	ncoding metho	od, "_BIN" car	n be
	igno	red.						
	If de	If device_type is LW_BCD, it means the register is LW and the encoding method						
	is BC	D.		_				
	Addr	ess_offset	s the addres	s offset in the	devic	e.		



For example, StringGet(read\_data\_1[0], "FATEK KB Series", RT, 5, 1) represents that the address offset is 5.

If address\_offset uses the format —"N#AAAAA", N indicates that device's station number is N. AAAAA represents the address offset. This format is used while multiple devices or controllers are connected to a single serial port. For example, StringGet(read\_data\_1[0], "FATEK KB Series", RT, 2#5, 1) represents that the device's station number is 2. If StringGet() uses the default station number defined in the device list as follows, it is not necessary to define station number in address\_offset.



The number of registers actually read from depends on the value of the number of *data count* since that the *read data* is restricted to char array.

type of read_data	data_count	actual number of
		16-bit register read
char (8-bit)	1	1
char (8-bit)	2	1

1 WORD register(16-bit) equals to the size of 2 ASCII characters. According to the above table, reading 2 ASCII characters is actually reading the content of one 16-bit register.

#### **Example**

macro\_command main()
char str1[20]

- // read 10 words from LW-0~LW-9 to the variables str1[0] to str1[19]
- // since that 1 word can store 2 ASCII characters, reading 20 ASCII
- // characters is actually reading 10 words of register
- StringGet(str1[0], "Local HMI", LW, 0, 20)



end macro_command

Name	StringGetEx
Syntax	StringGetEx (read_data[start], device_name, device_type, address_offset, data_count)
Description	Receives data from the device and continues executing next command even if there's no response from this device.  Descriptions of read_data, device_name, device_type, address_offset and data_count are the same as GetData.
Example	macro_command main() char str1[20] short test=0  // macro will continue executing test = 1 even if the MODBUS device is // not responding StringGetEx(str1[0], "MODBUS RTU", 4x, 0, 20) test = 1  // macro will not continue executing test = 2 until MODBUS device responds StringGet(str1[0], "MODBUS RTU", 4x, 0, 20) test = 2 end macro_command

Name	StringIncluding
Syntax	success = StringIncluding (source[start], set[start], destination[start])
	success = StringIncluding ("source", set[start], destination[start])
	success = StringIncluding (source[start], "set", destination[start])
	success = StringIncluding ("source", "set", destination[start])
Description	Retrieves a substring of the source string that contains characters in the set
	string, beginning with the first character in the source string and ending when a
	character is found in the source string that is not in the target string.
	The source string and set string parameters accept both static string (in the
	form: "source") and char array (in the form: source[start]).
	This function returns a Boolean indicating whether the process has been
	successfully completed. If so, it returns true; otherwise it returns false. If the
	length of retrieved substring exceeds the size of destination buffer, it returns
	false.



	was a same and was in ()
Example	macro_command main()
	char src1[20]="cabbageabc"
	char set1[20]="abc"
	char dest1[20]
	bool success1
	success1 = StringIncluding(src1[0], set1[0], dest1[0])
	// success1=true, dest1="cabba"
	char src2[20]="gecabba"
	char dest2[20]
	bool success2
	success2 = StringIncluding(src2[0], "abc", dest2[0])
	// success2=true, dest2=""
	char set3[20]="abc"
	char dest3[4]
	bool success3
	success3 = StringIncluding("cabbage", set3[0], dest3[0])
	// success3=false, dest3 remains the same.
	end macro_command

Name	StringInsert
Syntax	success = StringInsert (pos, insert[start], destination[start])
	success = StringInsert (pos, "insert", destination[start])
	success = StringInsert (pos, insert[start], length, destination[start])
	success = StringInsert (pos, "insert", length, destination[start])
Description	Inserts a string in a specific location within the destination string content.
	The insert location is specified by the pos parameter.
	The insert string parameter accepts both static string (in the form: "source")
	and char array (in the form: source[start]).
	The number of characters to insert can be specified by the length parameter.
	This function returns a Boolean indicating whether the process has been
	successfully completed. If so, it returns true; otherwise it returns false. If the
	length of string after insertion exceeds the size of destination buffer, it
	returns false.



Example	macro_command main()
	char str1[20]="but the question is"
	char str2[10]=", that is" char dest[40]="to be or not to be"
	bool success
	success = StringInsert(18, str1[3], 13, dest[0])
	// success=true, dest="to be or not to be the question"
	success = StringInsert(18, str2[0], dest[0])
	// success=true, dest="to be or not to be, that is the question"
	success = StringInsert(0, "Hamlet:", dest[0])
	// success=false, dest remains the same.
	end macro_command

Name	StringLength
Syntax	length = StringLength (source[start])
	or
	length = StringLength ("source")
Description	Obtains the length of a string. It returns the length of source string and stores it
	in the length field on the left-hand side of '=' operator.
	The source string parameter accepts both static string (in the form: "source") and char array (in the form: source[start]).
	· · · · · · · · · · · · · · · · · · ·
Faranala	The return value of this function indicates the length of the source string.
Example	macro_command main() char src1[20]="abcde"
	int length1
	length1= StringLength(src1[0]) // length1=5
	// lenguit-3
	char src2[20]={'a', 'b', 'c', 'd', 'e'}
	int length2
	length2= StringLength(src2[0])
	// length2=5
	char src3[20]="abcdefghij"
	int length3
	length3= StringLength(src3 [2])
	// length3=8
	end macro_command



Name	StringMD5
Syntax	result = StringMD5(source[start], destination[start]) result = StringMD5("source", destination[start])
Description	Retrieves a string using MD5 Message-Digest algorithm.  The source string parameter accepts both static string (in the form: "source") and char array (in the form: source[start]). For source[start], the start offset of the substring is specified by the index value.  destination[start] must be a one-dimensional char array, to store the retrieved substring.  This function returns the length of MD5 string stored in result.
Example	<pre>macro_command main() char source[32] = "password", dest[32] int result  result = StringMD5(source[0], dest[0]) result = StringMD5("password", dest[0]) // "result" will be set to 32. // "result" will be the length of MD5 string. // dest[] = 5f4dcc3b5aa765d61d8327deb882cf99  end macro_command</pre>

Name	StringMid				
Syntax	success = StringMid (source[start], count, destination[start])				
	or				
	success = StringMid ("string", start, count, destination[start])				
Description	Retrieves a character sequence from the specified offset of the source string				
	and stores it in the destination buffer.				
	The source string parameter accepts both static string (in the form: "source")				
	and char array (in the form: source[start]). For source[start], the start offset of				
	the substring is specified by the index value. For static source string("source"),				
	the second parameter(start) specifies the start offset of the substring.				
	The count parameter specifies the length of substring being retrieved.				
	Destination must be an one-dimensional char array, to store the retrieved				
	substring.				
	This function returns a Boolean indicating whether the process has been				
	successfully completed. If so, it returns true; otherwise it returns false. If the				
	length of retrieved substring exceeds the size of destination buffer, it returns				
	false.				
	The success field is optional.				
Example	macro_command main()				
	char src1[20]="abcdefghijklmnopqrst"				
	char dest1[20]				
	bool success1				
	success1 = StringMid(src1[5], 6, dest1[0])				



```
// success1=true, dest1="fghijk"

char src2[20]="abcdefghijklmnopqrst"
 char dest2[5]
 bool success2
 success2 = StringMid(src2[5], 6, dest2[0])
 // success2=false, dest2 remains the same.

char dest3[20]="12345678901234567890"
 bool success3
 success3 = StringMid("abcdefghijklmnopqrst", 5, 5, dest3[15])
 // success3= true, dest3="123456789012345fghij"

end macro_command
```

Name	StringReverseFind		
Syntax	position = StringReverseFind (source[start], target[start])		
	position = StringReverseFind ("source", target[start])		
	position = StringReverseFind (source[start], "target")		
	position = StringReverseFind ("source", "target")		
Description	Returns the position of the last occurrence of target string in the source string.		
	The two string parameters accept both static string (in the form: "source") and		
	char array (in the form: source[start]).		
	This function returns the zero-based index of the first character of substring in		
	the source string that matches the target string. Notice that the entire		
	sequence of characters to find must be matched. If there exists multiple		
	substrings that matches the target string, function will return the position of		
	the last matched substring. If there is no matched substring, it returns -1.		



Example	macro_command main()
	char src1[20]="abcdeabcde"
	char target1[20]="cd"
	short pos1
	pos1= StringReverseFind(src1[0], target1[0])
	// pos1=7
	char target2[20]="ce"
	short pos2
	pos2= StringReverseFind("abcdeabcde", target2[0])
	// pos2=-1
	char src3[20]="abcdeabcde"
	short pos3
	·
	pos3= StringReverseFind(src3[6], "ab")
	// pos3=-1
	end macro_command

Name	StringSet
Syntax	StringSet(send_data[start], device_name, device_type, address_offset, data_count)
Description	Sends data to the device. Data is defined in <code>send_data[start] ~ send_data[start + data_count - 1]</code> . send_data must be a one-dimensional char array. <code>data_count</code> is the number of sent characters, it can be either a constant or a variable. <code>device_name</code> is the device name enclosed in the double quotation marks (") and this name has been defined in the device list of system parameters. <code>device_type</code> is the device type and encoding method (binary or BCD) of the device data. For example, if <code>device_type</code> is LW_BIN, it means the register is LW and the encoding method is binary. If use BIN encoding method, "_BIN" can be ignored. If <code>device_type</code> is LW_BCD, it means the register is LW and the encoding method is BCD. <code>address_offset</code> is the address offset in the device. For example, StringSet(read_data_1[0], "FATEK KB Series", RT, 5, 1) represents that the address offset is 5. If <code>address_offset</code> uses the format —"N#AAAAA", N indicates that device's station number is N. AAAAA represents the address offset. This format is used while multiple devices or controllers are connected to a single serial port. For example, StringSet(read_data_1[0], "FATEK KB Series", RT, 2#5, 1) represents that the device's station number is 2. If SetData () uses the default station number defined in the device list, it is not necessary to define station number in <code>address_offset</code> .



The number of registers actually sends to depends on the value of the number of *data\_count*, since that *send\_data* is restricted to char array.

type of	data_count	actual number of
read_data		16-bit register send
char (8-bit)	1	1
char (8-bit)	2	1

1 WORD register(16-bit) equals to the size of 2 ASCII characters. According to the above table, sending 2 ASCII characters is actually writing to one 16-bit register. The ASCII characters are stored into the WORD register from low byte to high byte. While using the ASCII Display object to display the string data stored in the registers, *data\_count* must be a multiple of 2 in order to display full string content. For example:

macro\_command main()
char src1[10]="abcde"
StringSet(src1[0], "Local HMI", LW, 0, 5)
end macro\_command

The ASCII Display object shows:



If data\_count is an even number that is greater than or equal to the length of the string, the content of string can be completely shown:

macro\_command main()
char src1[10]="abcde"
StringSet(src1[0], "Local HMI", LW, 0, 6)
end macro\_command



#### **Example**

macro\_command main()

char str1[10]="abcde"

- // Send 3 words to LW-0~LW-2
- // Data are being sent until the end of string is reached.
- // Even though the value of data\_count is larger than the length of string
- // , the function will automatically stop.

StringSet(str1[0], "Local HMI", LW, 0, 10)



end macro_command

	Chain a Cat Five
Name	StringSetEx
Syntax	StringSetEx (send_data[start], device_name, device_type, address_offset, data_count)
Description	Sends data to the device and continues executing next command even if there's no response from this device.  Descriptions of send_data, device_name, device_type, address_offset and data_count are the same as StringSet.
Example	macro_command main() char str1[20]="abcde" short test=0  // macro will continue executing test = 1 even if the MODBUS device is // not responding StringSetEx(str1[0], "MODBUS RTU", 4x, 0, 20) test = 1  // macro will not continue executing test = 2 until MODBUS device responds StringSet(str1[0], "MODBUS RTU", 4x, 0, 20) test = 2
	end macro_command

Name	StringToUpper
Syntax	success = StringToUpper (source[start], destination[start])
	success = StringToUpper ("source", destination[start])
Description	Converts all the characters in the source string to uppercase characters and
	stores the result in the destination buffer.
	The source string parameter accepts both static string (in the form: "source")
	and char array (in the form: source[start]).
	This function returns a Boolean indicating whether the process has been
	successfully completed. If so, it returns true; otherwise it returns false. If the
	length of result string after conversion exceeds the size of destination buffer, it
	returns false.



Example	macro_command main() char src1[20]="aBcDe" char dest1[20] bool success1 success1 = StringToUpper(src1[0], dest1[0]) // success1=true, dest1="ABCDE"
	<pre>char dest2[4] bool success2 success2 = StringToUpper("aBcDe", dest2[0]) // success2=false, dest2 remains the same. end macro_command</pre>

Name	StringToLower
Syntax	success = StringToLower (source[start], destination[start])
	success = StringToLower ("source", destination[start])
Description	Converts all the characters in the source string to lowercase characters and
	stores the result in the destination buffer.
	The source string parameter accepts both static string (in the form: "source")
	and char array (in the form: source[start]).
	This function returns a Boolean indicating whether the process has been
	successfully completed. If so, it returns true; otherwise it returns false. If the
	length of result string after conversion exceeds the size of destination buffer, it
	returns false.
Example	macro_command main()
	char src1[20]="aBcDe"
	char dest1[20]
	bool success1
	success1 = StringToLower(src1[0], dest1[0])
	// success1=true, dest1="abcde"
	char dest2[4]
	bool success2
	success2 = StringToLower("aBcDe", dest2[0])
	// success2=false, dest2 remains the same.
	end macro_command

Name	StringToReverse
Syntax	success = StringToReverse (source[start], destination[start])
	success = StringToReverse ("source", destination[start])
Description	Reverses the characters in the source string and stores it in the destination
_	buffer.



	The source string parameter accepts both static string (in the form: "source") and char array (in the form: source[start]).
	/
	This function returns a Boolean indicating whether the process has been
	successfully completed. If so, it returns true; otherwise it returns false. If the
	length of reversed string exceeds the size of destination buffer, it returns false.
Example	macro_command main()
	char src1[20]="abcde"
	char dest1[20]
	bool success1
	success1 = StringToReverse(src1[0], dest1[0])
	// success1=true, dest1="edcba"
	char dest2[4] bool success2 success2 = StringToReverse("abcde", dest2[0]) // success2=false, dest2 remains the same.
	end macro_command

Name	StringTrimLeft
Syntax	success = StringTrimLeft (source[start], set[start], destination[start])
Syntax	success = StringTrimLeft ("source", set[start], destination[start])
	success = StringTrimLeft (source[start], "set", destination[start])
	success = StringTrimLeft ("source", "set", destination[start])
Description	
Description	Trims the leading specified characters in the set buffer from the source string.
	The source string and set string parameters accept both static string (in the
	form: "source") and char array (in the form: source[start]).
	This function returns a Boolean indicating whether the process has been
	successfully completed. If so, it returns true; otherwise it returns false. If the
	length of trimmed string exceeds the size of destination buffer, it returns false.
Example	macro_command main()
	char src1[20]= "# *a*#bc"
	char set1[20]="# *"
	char dest1[20]
	bool success1
	success1 = StringTrimLeft (src1[0], set1[0], dest1[0])
	// success1=true, dest1="a*#bc"
	,,
	char set2[20]={'#', ' ', '*'}
	char dest2[4]
	bool success2
	success2 = StringTrimLeft ("# *a*#bc", set2[0], dest2[0])
	// success2=false, dest2 remains the same.



```
char src3[20]="abc *#"

char dest3[20]
bool success3
success3 = StringTrimLeft (src3[0], "# *", dest3[0])
// success3=true, dest3="abc *#"

end macro_command
```

Name	StringTrimRight
Syntax	success = StringTrimRight (source[start], set[start], destination[start])
	success = StringTrimRight ("source", set[start], destination[start])
	success = StringTrimRight (source[start], "set", destination[start])
	success = StringTrimRight ("source", "set", destination[start])
Description	Trims the trailing specified characters in the set buffer from the source string.
	The source string and set string parameters accept both static string (in the
	form: "source") and char array (in the form: source[start]).
	This function returns a Boolean indicating whether the process has been
	successfully completed. If so, it returns true; otherwise it returns false. If the
	length of trimmed string exceeds the size of destination buffer, it returns false.
Example	macro_command main()
	char src1[20]= "# *a*#bc# * "
	char set1[20]="# *"
	char dest1[20]
	bool success1
	success1 = StringTrimRight(src1[0], set1[0], dest1[0])
	// success1=true, dest1="# *a*#bc"
	char set2[20]={'#', ' ', '*'}
	char dest2[20]
	bool success2
	success2 = StringTrimRight("# *a*#bc", set2[0], dest2[0])
	// success2=true, dest2="# *a*#bc"
	char src3[20]="ab**c *#"
	char dest3[4]
	bool success3
	success3 = StringTrimRight(src3[0], "# *", dest3[0])



// success3=false, dest3 remains the same.
end macro_command

Name	Unicode2Utf8
Syntax	result = Unicode2Utf8(source[start], destination[start])
Description	Converts the source Unicode string to UTF8 string and stores the result in the destination buffer. This function returns a Boolean indicating whether the process is successfully done or not. If successful, it returns true,; otherwise it returns false.
Example	<pre>macro_command main()  char unicode_str[20] char utf8_str[20] String2Unicode("ABC", unicode_str[0]) bool result  result = Unicode2Utf8(unicode_str[0], utf8_str[0]) // "result" will be set to true. "utf8_str" will equal "ABC" encoded in UTF8 StringCat("DEF", utf8_str[0]) // "utf8_str" will equal "ABCDEF" encoded in UTF8  char dst[20] bool result2  result2 = Utf82Unicode(utf8_str[0], dst[0]) // "result" will be set to true. "dst" will equal "ABCDEF" encoded in Unicode. end macro_command</pre>

Name	UnicodeCat
Syntax	result = UnicodeCat(source[start], destination[start])
	or
	result = UnicodeCat("source", destination[start])
Description	This function concatenate strings. It appends the source string to the
	destination string.
	The source string parameter accepts both static string (e.g. "source") and char
	array (e.g. source[start]).
	destination[start] must be an one-dimensional char array.
	This function returns a Boolean indicating whether the process has been
	successfully completed. If successful, it returns true; otherwise it returns false.
	If the length of the result string after concatenation exceeds the max. size of
	destination buffer, it returns false, and the destination string remains
	unchanged.
Example	macro_command main()



Name	UnicodeCompare
Syntax	result = UnicodeCompare(string1[start], string2[start])
	result = UnicodeCompare("string1", string2[start])
	result = UnicodeCompare(string1[start], "string2")
	result = UnicodeCompare("string1", "string2")
Description	Performs case-sensitive comparison of two strings.
	The two string parameters accept both static string (e.g. "string") and char
	array (e.g. string[start]).
	This function returns a Boolean indicating the result of comparison. If two
	strings are identical, it returns true. Otherwise it returns false.
Example	macro_command main()
	char str1[10]=" $\theta \alpha \beta \theta \gamma$ "
	char str2[8]=" $\alpha\beta\gamma\delta$ "
	bool result
	result = UnicodeCompare(str1[0], str2[0]) // "result" will be set to false.
	result = UnicodeCompare(str1[0], " $\theta\alpha\beta\theta\gamma$ ") // "result" will be set to true.
	end macro_command

Name	UnicodeCopy
Syntax	result = UnicodeCopy("source", destination[start])
	or
	result = UnicodeCopy(source[start], destination[start])
Description	Copies a string. This function copies a static string (which is enclosed in quotes)



	or a string that is stored in an array to the destination buffer. The source string parameter accepts both static string (e.g. "source") and char array (in the form: source[start]). destination[start] must be an one-dimensional char array. This function returns a Boolean indicating whether the process has been successfully completed. If so, it returns true; otherwise it returns false. If the length of source string exceeds the max. size of destination buffer, it returns false and the content of destination remains unchanged. The result field is optional.
Example	macro_command main() char strSrc[14]="αβθγδθε" //αβθγδθε
	char strDest[14]
	bool result
	result = UnicodeCopy(strSrc[0], strDest[0]) // "result" will be set to true.
	result = UnicodeCopy("αβθγδθε", strDest[0])
	// "result" will be set to true, strDest = αβθγδθε"
	result = UnicodeCopy("αβγδεζαβγδεζ", strDest[0])
	// "result" will be set to false.
	// The size of source string exceeds the size of destination string.
	end macro_command

Name	UnicodeExcluding
Syntax	result = UnicodeExcluding(source[start], set[start], destination[start])
	result = UnicodeExcluding("source", set[start], destination[start]) result = UnicodeExcluding(source[start], "set", destination[start])
	result = UnicodeExcluding("source", "set", destination[start])
Description	Retrieves a substring of the source string that contains characters that are not
	in the set string. The result string is the part of the source string beginning with
	the first character and ending before any character in the target string is found
	in the source string.
	The source string and set string parameters accept both static string (in the
	form: "source") and char array (in the form: source[start]).
	This function returns a Boolean indicating whether the process has been
	successfully completed. If so, it returns true; otherwise it returns false. If the
	length of retrieved substring exceeds the size of destination buffer, it returns
	false.



Example	macro_command main()
	char source[14]="γδξκθλθ, dest[8]
	char set[4]="λθ"
	bool result
	result = UnicodeExcluding(source[0], set[0], dest[0]) // the function succeeds.
	// "result" will be set to true and "dest" will be set to "γδξκ".
	result = UnicodeExcluding(source[0], set[0], dest[4]) // the function fails.
	// "result" will be set to false due to insufficient destination buffer size.
	end macro_command

Name	UnicodeLength
Syntax	result = UnicodeLength(source[start])
	or
	result = UnicodeLength("source")
Description	Obtains the length of a Unicode string.
	The source string parameter accepts both static string (e.g. "source") and char
	array (in the form: source[start]).
	The returned value is the length of the source string.
Example	macro command main()
	_ "
	char strSrc[6]="ÅÈÑ"
	int result1, result2
	result1 = UnicodeLength(strSrc[0]) // "result1" is equal to 3
	result2 = UnicodeLength("trSrc[0]) // "re2" is equal to 3
	end macro_command

Name	Utf82Unicode
Syntax	result = Utf82Unicode(source[start], destination[start])
Description	Converts the source UTF8 string to a Unicode string and stores the result in the destination buffer. This function returns a Boolean indicating whether the process has been successfully completed. If so, it returns true; otherwise it returns false.
Example	macro_command main()



```
char unicode_str[20]
char utf8_str[20]
String2Unicode("ABC", unicode_str[0])
bool result

result = Unicode2Utf8(unicode_str[0], utf8_str[0])
// "result" will be set to true. "utf8_str" will equal "ABC" encoded in UTF8
StringCat("DEF", utf8_str[0]) // "utf8_str" will equal "ABCDEF" encoded in UTF8

char dst[20]
bool result2

result2 = Utf82Unicode(utf8_str[0], dst[0])
// "result" will be set to true. "dst" will equal "ABCDEF" encoded in Unicode.
end macro_command
```

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### 18.7.8. Mathematics

Name	SQRT
Syntax	SQRT(source, result)
Description	Calculates the square root of <i>source</i> and stores the result into <i>result</i> .  source can be a constant or a variable. result must be a variable.  source must be a nonnegative value.
Example	macro_command main() float source, result  SQRT(15, result)  source = 9.0  SQRT(source, result)// result is 3.0
	end macro_command



Name	CUBERT
Syntax	CUBERT(source, result)
Description	Calculates the cube root of source and stores the result into <i>result</i> .  source can be a constant or a variable. result must be a variable.  source must be a nonnegative value.
Example	macro_command main() float source, result  CUBERT (27, result) // result is 3.0  source = 27.0  CUBERT(source, result)// result is 3.0
	end macro_command

Name	POW
Syntax	POW(source1, source2, result)
Description	Calculates source1 to the power of source2. source1 and source2 can be a constant or a variable. result must be a variable. source1 and source2 must be a nonnegative value.
Example	macro_command main() float y, result y = 0.5 POW (25, y, result) // result = 5 end macro_command

Name	SIN
Syntax	SIN(source, result)
Description	Calculates the sine of source (degree) into result.
	source can be a constant or a variable. result must be a variable.
Example	macro_command main()
	float source, result
	SIN(90, result)// result is 1
	source = 30
	SIN(source, result)// result is 0.5
	end macro_command

Name	COS
Syntax	COS(source, result)
Description	Calculates the cosine of source (degree) into result.



	source can be a constant or a variable. result must be a variable.
Example	macro_command main()
	float source, result
	COS(90, result)// result is 0
	source = 60
	COS(source, result)// result is 0.5
	end macro_command

Name	TAN
Syntax	TAN(source, result)
Description	Calculates the tangent of source (degree) into result.
	source can be a constant or a variable. result must be a variable.
Example	macro_command main()
	float source, result
	TAN(45, result)// result is 1
	source = 60
	TAN(source, result)// result is 1.732
	end macro_command

Name	СОТ
Syntax	COT(source, result)
Description	Calculates the cotangent of <i>source</i> (degree) into <i>result</i> .
	source can be a constant or a variable. result must be a variable.
Example	macro_command main()
-	float source, result
	COT(45, result)// result is 1
	source = 60
	COT(source, result)// result is 0.5774
	end macro_command

Name	SEC
Syntax	SEC(source, result)
Description	Calculates the secant of source (degree) into result.
	source can be a constant or a variable. result must be a variable.
Example	macro_command main()



float source, result
SEC(45, result)// result is 1.414
source = 60 SEC(source, result)// if source is 60, result is 2
end macro_command

Name	CSC
Syntax	CSC(source, result)
Description	Calculates the cosecant of <i>source</i> (degree) into <i>result</i> . <i>source</i> can be a constant or a variable. <i>result</i> must be a variable.
Example	macro_command main() float source, result  CSC(45, result)// result is 1.414  source = 30 CSC(source, result)// result is 2  end macro_command



Name	ASIN
Syntax	ASIN(source, result)
Description	Calculates the arc sine of <i>source</i> into <i>result</i> (degree).
	source can be a constant or a variable. result must be a variable.
Example	macro_command main()
	float source, result
	ASIN(0.8660, result)// result is 60
	source = 0.5 ASIN(source, result)// result is 30
	end macro_command

Name	ACOS
Syntax	ACOS(source, result)
Description	Calculates the arc cosine of <i>source</i> into <i>result</i> . <i>source</i> can be a constant or a variable. <i>result</i> must be a variable.
Example	macro_command main() float source, result  ACOS(0.8660, result)// result is 30  source = 0.5 ACOS(source, result)// result is 60  end macro_command

Name	ATAN
Syntax	ATAN(source, result)
Description	Calculates the arc tangent of <i>source</i> into <i>result</i> .  source can be a constant or a variable. result must be a variable.
Example	macro_command main() float source, result  ATAN(1, result)// result is 45  source = 1.732 ATAN(source, result)// result is 60  end macro_command



Name	LOG
Syntax	LOG (source, result)
Description	Calculates the natural logarithm of a number and saves into result.
	source can be either a variable or a constant. result must be a variable.
Example	macro_command main()
	float source = 100, result
	LOG (source, result)// result is approximately 4.6052
	end macro_command

Name	LOG10
Syntax	LOG10(source, result)
Description	Calculates the base-10 logarithm of a number and saves into result.
	source can be either a variable or a constant. result must be a variable.
Example	macro_command main()
	float source = 100, result
	LOG10 (source, result) // result is 2
	end macro_command

Name	RAND
Syntax	RAND(result)
Description	Calculates a random integer and saves into <i>result</i> . (Range: $0 \sim 32766$ ) <i>result</i> must be a variable.
Example	macro_command main() short result  RAND (result) //result is not a fixed value when executes macro every time end macro_command

Name	CEIL	
Syntax	result=CEIL(source)	
Description	Get the smallest integral value that is not less than input.	
Example	macro_command main()	
	float x = 3.8 int result  result = CEIL(x)// result = 4 end macro_command	



Name	FLOOR	
Syntax	result=FLOOR(source)	
Description	Get the largest integral value that is not greater than input.	
Example	macro_command main()	
	float x = 3.8 int result	
	result = FLOOR(x) // result = 3	
	end macro_command	

Name	ROUND	
Syntax	result=ROUND(source)	
Description	Get the integral value that is nearest the input.	
Example	macro_command main()	
	float x = 5.55 int result	
	result = ROUND(x) // result = 6	
	end macro_command	

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## 18.7.9. Statistics

Name	AVERAGE	
Syntax	AVERAGE(source[start], result, count)	
Description	Gets the average value from array.	
Example	int data[5] = {1, 2, 3, 4, 5} float result	
	AVERAGE(data[0], result, 5) // result is equal to 3 AVERAGE(data[2], result, 3) // result is equal to 4	

Name	HARMEAN
Syntax	HARMEAN(source[start], result, count)
Description	Gets the harmonic mean value from array.
Example	int data[10] = {1, 2, 3, 4, 5, 6, 7, 8, 9, 10}



float result	
HARMEAN(data[0], result, 10)	// result is equal to 3.414

Name	MAX	
Syntax	MAX(source[start], result, count)	
Description	Gets the maximum value from array.	
Example	int data[5] = {1, 2, 3, 4, 5} int result	
	MAX(data[0], result, 5) // result is equal to 5 MAX(data[1], result, 3) // result is equal to 4	

Name	MEDIAN	
Syntax	MEDIAN(source[start], result, count)	
Description	Gets the median value from array.	
Example	int data[10] = {1, 2, 3, 4, 5, 6, 7, 8, 9, 10} float result  MEDIAN(data[0], result, 10) // result is equal to 5.5	

Name	MIN	
Syntax	MIN(source[start], result, count)	
Description	Gets the minimum value from array.	
Example	int data[5] = {1, 2, 3, 4, 5} int result	
	MIN(data[0], result, 5) // result is equal to 1 MIN(data[1], result, 3) // result is equal to 2	

Name	STDEVP	
Syntax	STDEVP(source[start], result, count)	
Description	Gets the standard deviation value from array.	
Example	int data[10] = {1, 2, 3, 4, 5, 6, 7, 8, 9, 10} float result  STDEVP(data[0], result, 10) // result is equal to 2.872	

Name	STDEVS
Syntax	STDEVS(source[start], result, count)
Description	Gets the sample standard deviation value from array.
Example	int data[10] = {1, 2, 3, 4, 5, 6, 7, 8, 9, 10} float result



STDEVS(data[0], result, 10)	// result is equal to 3.027
	// · · · · · · · · · · · · · · · · · ·

# 18.7.10. Recipe Database

Name	RecipeGetData
Syntax	RecipeGetData(destination, recipe_address, record_ID)
Description	Gets Recipe Data. The gained data will be stored in <i>destination</i> , and must be a variable. <i>recipe_address</i> consists of recipe name and item name: "recipe_name.item_name". record_ID specifies the ID number of the record in recipe being gained.
Example	macro_command main() int data=0 char str[20] int recordID bool result  recordID = 0 result = RecipeGetData(data, "TypeA.item_weight", recordID) // From recipe "TypeA" get the data of the item "item_weight" in record 0.  recordID = 1 result = RecipeGetData(str[0], "TypeB.item_name", recordID) // From recipe "TypeB" get the data of the item "item_name" in record 1.
	end macro_command

Name	RecipeQuery
Syntax	RecipeQuery (SQL_command, destination)
Description	Uses SQL statement to query recipe data. The number of records of query result will be stored in the <i>destination</i> . This must be a variable. SQL command can be static string or char array. Example:  RecipeQuery("SELECT * FROM TypeA", destination) or RecipeQuery(sql[0], destination) SQL statement must start with "SELECT * FROM" followed by recipe name and query condition.
Example	int total_row=0 char sql[100]="SELECT * FROM TypeB" short var bool result  result = RecipeQuery("SELECT * FROM TypeA", total_row) // Query Recipe "TypeA". Store the number of records of query result in total_row.



result = RecipeQuery(sql[0], total_row) // Query Recipe "TypeB". Store the number of records of query result in total_row.
result = RecipeQuery("SELECT * FROM Recipe WHERE Item >%(var)", total_row) // Query "Recipe", where "Item" is larger than var. Store the number of records of query result in total_row.
end macro_command

Name	RecipeQueryGetData
Syntax	RecipeQueryGetData (destination, recipe_address, result_row_no)
Description	Gets the data in the query result obtained by RecipeQuery. This function must be called after calling RecipeQuery, and specify the same recipe name in recipe_address as RecipeQuery.  result_row_no specifies the sequence row number in query result
Example	macro_command main()
	int data=0
	int total_row=0
	int row_number=0
	bool result query
	bool result_data
	result_query = RecipeQuery("SELECT * FROM TypeA", total_row) // Query Recipe "TypeA". Store the number of records of query result in total_row. if (result_query) then for row_number=0 to total_row-1 result_data = RecipeQueryGetData(data, "TypeA.item_weight", row_number) next row_number end if
	end macro_command

Name	RecipeQueryGetRecordID
Syntax	RecipeQueryGetRecordID (destination, result_row_no)
Description	Gets the record ID numbers of those records gained by RecipeQuery. This function must be called after calling RecipeQuery.  result_row_no specifies the sequence row number in query result, and write the obtained record ID to destination.
Example	macro_command main()  int recordID=0 int total_row=0 int row_number=0 bool result_query



```
bool result_id

result_query = RecipeQuery("SELECT * FROM TypeA", total_row)

// Query Recipe "TypeA". Store the number of records of query result in total_row.

if (result_query) then

for row_number=0 to total_row-1

result_id = RecipeQueryGetRecordID(recordID, row_number)

next row_number

end if

end macro_command
```

Name	RecipeSetData
Syntax	RecipeSetData(source, recipe address, record_ID)
Description	Writes data to recipe. If success, returns true, else, returns false.  recipe_address consists of recipe name and item name:  "recipe_name.item_name".  record_ID specifies the ID number of the record in recipe being modified.
Example	macro_command main()  int data=99 char str[20]="abc" int recordID bool result  recordID = 0 result = RecipeSetData(data, "TypeA.item_weight", recordID) // set data to recipe "TypeA", where item name is "item_weight" and the record ID is 0.  recordID = 1 result = RecipeSetData(str[0], "TypeB.item_name", recordID) // set data to recipe "TypeB", where item name is "item_name" and the record ID is 1.
	end macro_command

Click the icon to download the demo project. Please confirm your internet connection before downloading the demo project.

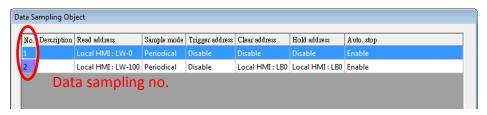
## **18.7.11.** Data/Event Log

Name	FindDataSamplingDate
Syntax	return_value = FindDataSamplingDate (data_log_number, index, year, month, day)
	or FindDataSamplingDate (data_log_number, index, year, month, day)



## Description

A query function for finding the date of specified data sampling file according to the data sampling no. and the file index. The date is stored into year, month and day respectively in the format of YYYY, MM and DD.



The directory of saved data: [Storage location]\[filename]\yyyymmdd.dtl. The data sampling files under the same directory are sorted according to the file name and are indexed starting from 0. The most recently saved file has the smallest file index number. For example, if there are four data sampling files as follows:

20101210.dtl

20101230.dtl

20110110.dtl

20110111.dtl

The file index are:

20101210.dtl -> index is 3

20101230.dtl -> index is 2

20110110.dtl -> index is 1

20110111.dtl -> index is 0

return\_value equals to 1 if referred data sampling file is successfully found, otherwise it equals to 0.

data\_log\_number and index can be constant or variable. year, month, day and return\_value must be variable. return\_value is optional.

## **Example**

macro command main()

short data\_log\_number = 1, index = 2, year, month, day

short success

// if there exists a data sampling file named 20101230.dtl, with data sampling // number 1 and file index 2.

// the result after execution: success == 1, year == 2010, month == 12 and //day == 30

success = FindDataSamplingDate(data log number, index, year, month, day)

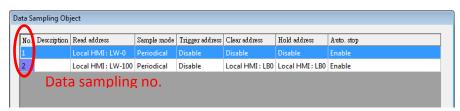
end macro command

Click the icon to download the demo project. Please confirm your internet connection before downloading the demo project.

Name	FindDataSamplingIndex
Syntax	return_value = FindDataSamplingIndex (data_log_number, year, month, day, index) or FindDataSamplingIndex (data_log_number, year, month, day, index)
Description	A query function for finding the file index of specified data sampling file according to the data sampling no. and the date. The file index is stored into



index. year, month and day are in the format of YYYY, MM and DD respectively.



The directory of saved data: [Storage location]\[filename]\yyyymmdd.dtl. The data sampling files under the same directory are sorted according to the file name and are indexed starting from 0. The most recently saved file has the smallest file index number. For example, if there are four data sampling files as follows:

20101210.dtl

20101230.dtl

20110110.dtl

20110111.dtl

The file index are:

20101210.dtl -> index is 3

20101230.dtl -> index is 2

20110110.dtl -> index is 1

20110111.dtl -> index is 0

return\_value equals to 1 if referred data sampling file is successfully found, otherwise it equals to 0.

data\_log\_number, year, month and day can be constant or variable. index and return\_value must be variable. return\_value is optional.

#### **Example**

macro command main()

short data\_log\_number = 1, year = 2010, month = 12, day = 10, index short success

// if there exists a data sampling file named 20101210.dtl, with data sampling // number 1 and file index 2.

// the result after execution: success == 1 and index == 2

success = FindDataSamplingIndex (data\_log\_number, year, month, day, index)

end macro\_command

Click the icon to download the demo project. Please confirm your internet connection before downloading the demo project.

Name	FindEventLogDate
Syntax	return_value = FindEventLogDate (index, year, month, day)
	or
	FindEventLogDate (index, year, month, day)
Description	A query function for finding the date of specified event log file according to file index. The date is stored into year, month and day respectively in the format of YYYY, MM and DD.
	The event log files stored in the designated position (such as HMI memory storage or external memory device) are sorted according to the file name and are indexed starting from 0. The most recently saved file has the smallest file



	index number. For example, if there are four event log files as follows:
	EL_20101210.evt
	EL_20101230.evt
	EL_20110110.evt
	EL_20110111.evt
	The file index are:
	EL_20101210.evt -> index is 3
	EL_20101230.evt -> index is 2
	EL_20110110.evt -> index is 1
	EL_20110111.evt -> index is 0
	return_value equals to 1 if referred data sampling file is successfully found,
	otherwise it equals to 0.
	index can be constant or variable. year, month, day and return_value must be
	variable. return_value is optional.
Example	macro_command main()
-	short index = 1, year, month, day
	short success
	// if there exists an event log file named EL_20101230.evt , with index 1
	// the result after execution: success == 1, year == 2010, month == 12, day //==
	30
	success = FindEventLogDate (index, year, month, day)
	end macro_command

Click the icon to download the demo project. Please confirm your internet connection before downloading the demo project.

return_value = FindEventLogIndex (year, month, day, index) or FindEventLogIndex (year, month, day, index)  Description  A query function for finding the file index of specified event log file according to date. The file index is stored into index. year, month and day are in the format of YYYY, MM and DD respectively.  The event log files stored in the designated position (such as HMI memory storage or external memory device) are sorted according to the file name and are indexed starting from 0. The most recently saved file has the smallest file index number. For example, if there are four event log files as follows:  EL_20101210.evt EL_20110110.evt EL_20110111.evt The file index are:	Name	FindEventLogIndex
Description  A query function for finding the file index of specified event log file according to date. The file index is stored into index. year, month and day are in the format of YYYY, MM and DD respectively.  The event log files stored in the designated position (such as HMI memory storage or external memory device) are sorted according to the file name and are indexed starting from 0. The most recently saved file has the smallest file index number. For example, if there are four event log files as follows:  EL_20101210.evt  EL_201101110.evt  EL_201101111.evt  The file index are:	Syntax	—
to date. The file index is stored into index. year, month and day are in the format of YYYY, MM and DD respectively.  The event log files stored in the designated position (such as HMI memory storage or external memory device) are sorted according to the file name and are indexed starting from 0. The most recently saved file has the smallest file index number. For example, if there are four event log files as follows:  EL_20101210.evt  EL_20110110.evt  EL_20110111.evt  The file index are:		
EL_20101210.evt -> index is 3 EL_20101230.evt -> index is 2 EL_20110110.evt -> index is 1 EL_20110111.evt -> index is 0 return_value equals to 1 if referred data sampling file is successfully found, otherwise it equals to 0.	Description	A query function for finding the file index of specified event log file according to date. The file index is stored into index. year, month and day are in the format of YYYY, MM and DD respectively.  The event log files stored in the designated position (such as HMI memory storage or external memory device) are sorted according to the file name and are indexed starting from 0. The most recently saved file has the smallest file index number. For example, if there are four event log files as follows:  EL_20101210.evt  EL_20101230.evt  EL_20110111.evt  The file index are:  EL_20101230.evt -> index is 3  EL_20101230.evt -> index is 2  EL_20110111.evt -> index is 1  EL_20110111.evt -> index is 0  return_value equals to 1 if referred data sampling file is successfully found,



	index can be constant or variable. year, month, day and return_value must be variable. return_value is optional.
Example	macro_command main() short year = 2010, month = 12, day = 10, index short success
	// if there exists an event log file named EL_20101210.evt, with index 2 // the result after execution: success == 1, index == 2 success = FindEventLogIndex (year, month, day, index) end macro command

Click the icon to download the demo project. Please confirm your internet connection before downloading the demo project.

## 18.7.12. Checksum

Name	ADDSUM
Syntax	ADDSUM(source[start], result, data_count)
Description	Adds up the elements of an array (source) from source[start] to source[start + data_count - 1] to generate a checksum. Puts in the checksum into result. result must be a variable. data_count is the amount of the accumulated elements and can be a constant or a variable.
Example	macro_command main() char data[5] short checksum  data[0] = 0x1 data[1] = 0x2 data[2] = 0x3 data[3] = 0x4 data[4] = 0x5  ADDSUM(data[0], checksum, 5)// checksum is 0xf end macro_command

Name	XORSUM
Syntax	XORSUM(source[start], result, data_count)
Description	Uses XOR to calculate the checksum from source[start] to source[start +
	data_count - 1]. Puts the checksum into result. result must be a variable.
	data_count is the amount of the calculated elements of the array and can be a
	constant or a variable.
Example	macro_command main()
	char data[5] = $\{0x1, 0x2, 0x3, 0x4, 0x5\}$
	short checksum



XORSUM(data[0], checksum, 5)// checksum is 0x1
end macro_command

Name	BCC
Syntax	BCC(source[start], result, data_count)
Description	Same as XORSUM.
Example	macro_command main() char data[5] = {0x1, 0x2, 0x3, 0x4, 0x5} char checksum  BCC(data[0], checksum, 5) // checksum is 0x1
	end macro_command

Name	CRC
Syntax	CRC(source[start], result, data_count)
Description	Calculates 16-bit CRC of the variables from source[start] to source[start + data_count - 1]. Puts in the 16-bit CRC into result. result must be a variable. data_count is the amount of the calculated elements of the array and can be a constant or a variable.
Example	macro_command main() char data[5] = {0x1, 0x2, 0x3, 0x4, 0x5} short checksum  CRC(data[0], checksum, 5) // checksum is 0xbb2a, 16-bit CRC end macro_command

Name	CRC8
Syntax	CRC8(source[start], result, data_count)
Description	Calculates 8-bit CRC of the variables from source[start] to source[start + data_count - 1]. Puts in the 8-bit CRC into result. result must be a variable. data_count is the amount of the calculated elements of the array and can be a constant or a variable.
Example	macro_command main()



Name	CRC16_CCITT
Syntax	CRC16_CCITT (source[start], result, data_count)
Description	Calculates 16-bit CRC of the variables from source[start] to source[start + data_count - 1] using CRC-16/CCITT algorithm. Puts in the 16-bit CRC into result. result must be a variable.  data count is the amount of the calculated elements of the array and can be a
	constant or a variable.
Example	macro_command main()  char source[5] = "12345"  short crc result
	CRC16_CCITT(source[0], crc_result, 5) //crc_result = 0xA5A2
	end macro_command

Name	CRC16_CCITT_FALSE
Syntax	CRC16_CCITT_FALSE (source[start], result, data_count)
Description	Calculates 16-bit CRC of the variables from <code>source[start]</code> to <code>source[start + data_count - 1]</code> using CRC-16/CCITT-FALSE algorithm. Puts in the 16-bit CRC into <code>result</code> must be a variable. <code>data_count</code> is the amount of the calculated elements of the array and can be a constant or a variable.
Example	macro_command main()  char source[5] = "12345" short crc_result CRC16_CCITT_FALSE(source[0], crc_result, 5) //crc_result = 0x4560  end macro_command

Name	CRC16_X25
Syntax	CRC16_X25 (source[start], result, data_count)
Description	Calculates 16-bit CRC of the variables from <code>source[start]</code> to <code>source[start + data_count - 1]</code> using CRC16/X25 algorithm. Puts in the 16-bit CRC into <code>result</code> . <code>result</code> must be a variable. <code>data_count</code> is the amount of the calculated elements of the array and can be a constant or a variable.
Example	macro_command main()  char source[5] = "12345" short crc_result CRC16_X25(source[0], crc_result, 5) //crc_result = 0xBB40  end macro_command



Name	CRC16_XMODEM
Syntax	CRC16_XMODEM (source[start], result, data_count)
Description	Calculates 16-bit CRC of the variables from <code>source[start]</code> to <code>source[start + data_count - 1]</code> using CRC16/XMODEM algorithm. Puts in the 16-bit CRC into <code>result</code> . <code>result</code> must be a variable. <code>data_count</code> is the amount of the calculated elements of the array and can be a constant or a variable.
Example	macro_command main()  char source[5] = "12345"  short crc_result  CRC16_ XMODEM(source[0], crc_result, 5) //crc_result = 0x546C  end macro_command

## 18.7.13. Miscellaneous

Name	Веер
Syntax	Beep ()
Description	Plays beep sound. This command plays a beep sound with frequency of 800 hertz and duration of 30 milliseconds.
Example	macro_command main()  Beep()  end macro_command

Name	Buzzer
Syntax	Buzzer ()
Description	Turns ON / OFF the buzzer.



Example	macro_command main()
	char on = 1, off = 0 Buzzer(on) // turn on the buzzer
	DELAY(1000) // delay 1 second
	Buzzer(off) // turn off the buzzer
	DELAY(500) // delay 500ms
	Buzzer(1) // turn on the buzzer
	DELAY(1000) // delay 1 second
	Buzzer(0) // turn off the buzzer
	end macro_command

Name	TRACE
Syntax	TRACE(format, argument)
Description	Use this function to send specified string to the EasyDiagnoser / cMT Diagnoser. Users can print out the current value of variables during run-time of macro for debugging.
	When TRACE encounters the first format specification (if any), it converts the value of the first argument after format and outputs it accordingly.
	format refers to the format control of output string. A format specification, which consists of optional (in []) and required fields (in red font), has the following form:
	%[flags] [width] [.precision] type
	Each field of the format specification is described as below:
	flags (optional):
	<ul> <li>- : Aligns left. When the value has fewer characters than the specified width, it will be padded with spaces on the left.</li> </ul>
	+ : Precedes the result with a plus or minus sign (+ or -)
	width (optional):  A nonnegative decimal integer controlling the minimum number of characters printed.
	precision (optional):
	A nonnegative decimal integer which specifies the precision and the number of characters to be printed.
	type:
	C or c : specifies a single-byte character
	d : signed decimal integer
	i : signed decimal integer
	o : unsigned octal integer
	u : unsigned decimal integer
	X or x : unsigned hexadecimal integer



	IId . signed lang integral (CA bit) (aNAT / aNAT V Carios anky)		
	Ild : signed long integer (64-bit) (cMT / cMT X Series only)		
	llu : unsigned long integer (64-bit) (cMT / cMT X Series only)		
	f : signed floating-point value		
	Ilf : double-precision floating-point value		
	E or e : Scientific notation in the form "[ – ]d.dddd e [sign]ddd", where		
	d is a single decimal digit, dddd is one or more decimal digits, ddd is		
	exactly three decimal digits, and sign is + or –.		
	exactly times decimal digits, and sign is 1 of 1.		
	The length of output string is limited to 256 characters. Extra characters will be		
	ignored.		
	The <i>argument</i> part is optional. One format specification converts exactly one		
	· · · · ·		
	argument.		
Example	macro_command main()		
	char c1 = 'a'		
	short s1 = 32767		
	float f1 = 1.234567		
	TRACE("The results are") // output: The results are		
	TRACE("c1 = %c, s1 = %d, f1 = %f", c1, s1, f1)		
	// output: c1 = a, s1 = 32767, f1 = 1.234567		
	,,		
	end macro command		

Click the icon to download the demo project. Please confirm your internet connection before downloading the demo project.

Name	GetCnvTagArrayIndex
Syntax	GetCnvTagArrayIndex( <i>array_index</i> )
Description	When a user-defined conversion tag uses array, the GetCnvTagArrayIndex() function of [Read conversion] subroutine can get the relative array index before doing conversion.
Example	Sub short newfun(short param) Int index GetCnvTagArrayIndex(index) If index is 2, the third data record in the array will be converted. return param end sub

## 18.8. How to Create and Execute a Macro

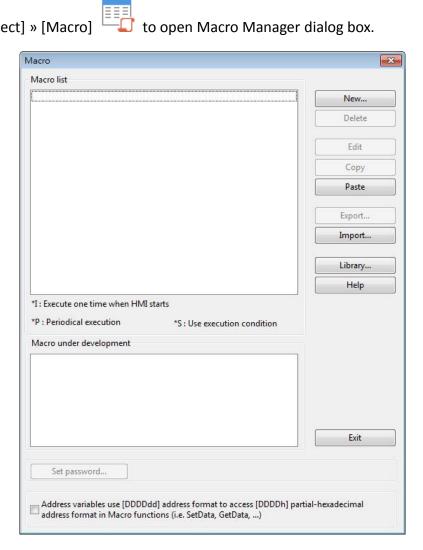
## 18.8.1. How to Create a Macro

Please follow the steps below to create a macro.



Click [Project] » [Macro] 1.





In Macro Manager, all macros compiled successfully are displayed in "Macro list", and all macros under development or cannot be compiled are displayed in "Macro under development". The following is a description of the various buttons.

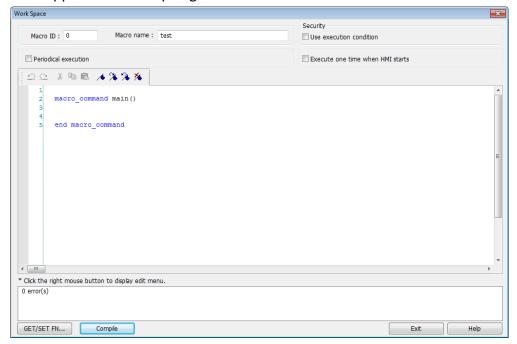
Setting	Description
New	Opens a blank "WorkSpace" editor for creating a
	new macro.
Delete	Deletes the selected macro.
Edit	Opens the "WorkSpace" editor, and loads the
	selected macro.
Сору	Copies the selected macro into the clipboard.
Paste	Pastes the macro in the clipboard into the list, and
	creates a new name for the macro.
Export	Save the selected macro as *.edm file.
Import	Import an *.edm file to the project.



Library

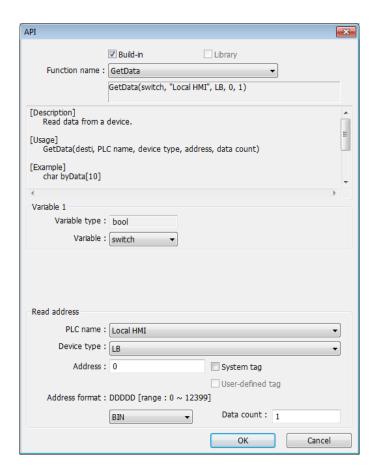
Open Macro Function Library managing dialog.

2. Press the [New] button to create an empty macro and open the macro editor. Every macro has a unique number defined at [Macro ID], and must have a macro name, otherwise an error will appear while compiling.

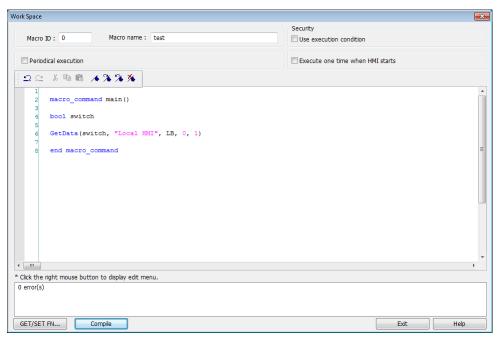


3. Design your macro. To use built-in functions (like SetData()) or GetData()), press [Get/Set FN...] button to open API dialog box and select the function and set essential parameters.





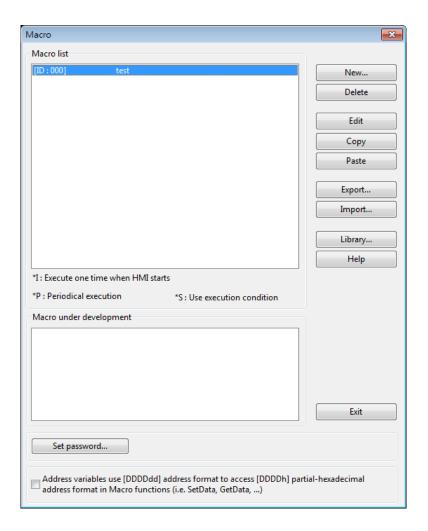
4. After the completion of a new macro, press [Compile] button to compile the macro.



5. If there is no error, press [Exit] button and a new macro "macro\_test" will be in "Macro list".



18-103





#### 18.8.2. Execute a Macro

There are several ways to execute a macro.

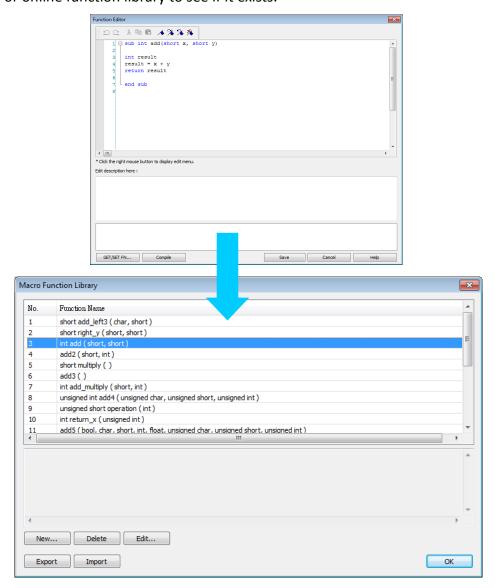
- Use a PLC Control object
- 1. Open [PLC Control] and add one PLC Control object with the [Type of control] as [Execute macro program].
- 2. Select the macro in [Macro name]. Choose a bit and select a trigger condition to trigger the macro. In order to guarantee that the macro will run only once, consider latching the trigger bit, and then resetting the trigger condition within the macro.
- 3. Use a [Set Bit] or Toggle Switch object to change the bit to activate the macro.
- Use a [Set Bit] or Toggle Switch object
- On the [General] tab of the [Set Bit] or [Toggle Switch] dialog box, select the [Execute Macro] option.
- Select the macro to execute. The macro will be executed one time when the button is activated.
- Use a Function Key object
- 1. On the [General] tab of the [Function Key] dialog, select the [Execute Macro] option.
- Select the macro to execute. The macro will execute one time when the button is activated.
- In macro editor, use
- 1. [Periodical Execution]: Macro will be triggered periodically.
- **2.** [Execute one time when HMI starts]: Macro will be executed once HMI starts.
- In Window Settings, Macro group box
- 1. [Open]: When the window opens, run the selected macro once.
- 2. [Cycle]: When the window opens, run the selected macro every 0.5 second.
- 3. [Close]: When the window closes, run the selected macro once.
- Click the icon to watch the demonstration film. Please confirm your internet connection before playing the film.

## 18.9. User Defined Macro Function

When editing Macro, to save time of defining functions, user may search for the needed from built-in Macro Function Library. However, certain functions, though frequently used, may not be found there. In this case, user may define the needed function and save it for future use. Next time when the same function is required, the saved functions can be called from [Macro



Function Library] for easier editing. Additionally, [Macro Function Library] greatly enhances the portability of user-defined functions. Before building a function please check the built-in functions or online function library to see if it exists.



## 18.9.1. Import Function Library File

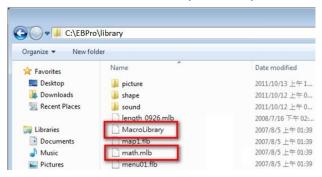
Open a project in HMI programming software, the default Function Library File will be read automatically and the function information will be loaded in. At this moment if a user-defined function is called, the relevant .mlb file must be imported first.

- 1. Default Function Library File Name: MacroLibrary (without filename extension)
- Function Library Directory: HMI programming software installation directory\library (folder)
- 3. \library (folder) contains two types of function library files: Without filename extension: MacroLibrary, the Default Function Library for HMI programming software to read at the beginning.



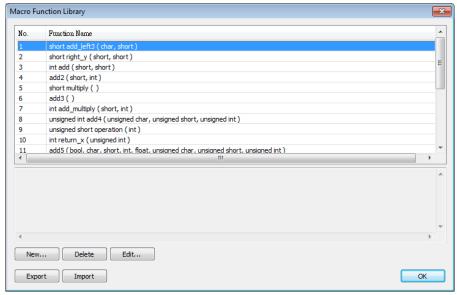
With filename extension (.mlb): Such as "math.mlb". The files to be read / written when users import / export. These files are portable and can be called from the folder when needed.

**4.** When opening HMI programming software, only the functions in Default Function Library will be loaded in, to use functions in .mlb files, please import them first.

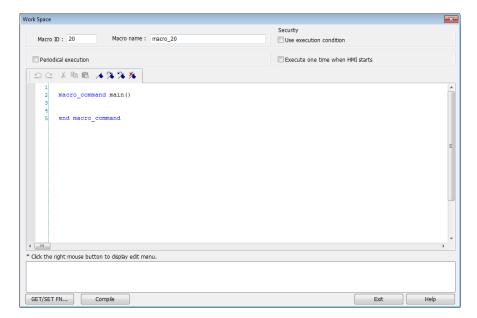


### 18.9.2. How to Use Macro Function Library

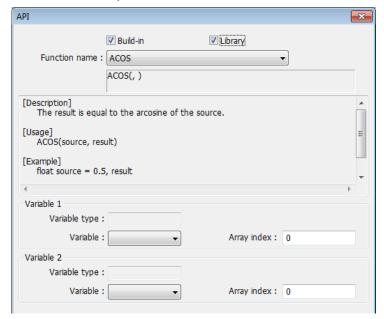
1. Select the function directly from Macro Function Library.



2. In WorkSpace click [GET/SET FN...] to open API dialog box.

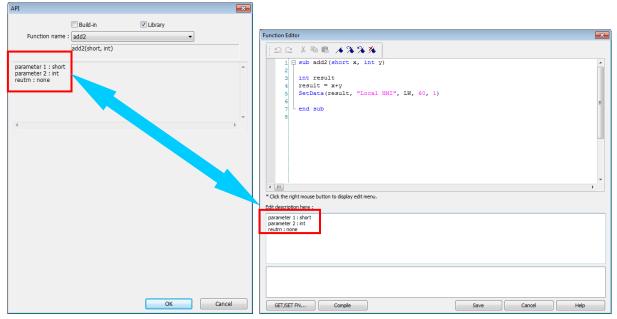


3. At least check one from [Library] or [Build-in] and select the function to be used.



4. The description displayed in API dialog box is the same as written in Function Editor.





**5.** Select the function to be used, fill in the corresponding variables according to the data type.

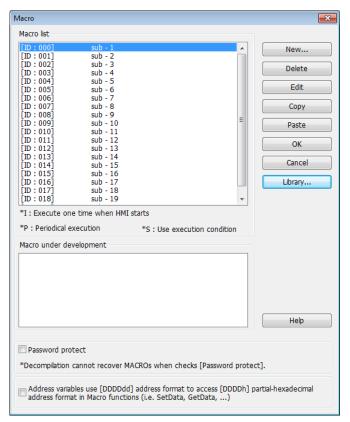
```
1 macro_command main() 2 macro_command main()
3 short a 4 short a 5 int b,result 5 int b,result 6 6 7 add2(short, int) 7 result = add2(a, b)
8 end macro_command 9 end macro_command
```

**6.** Upon completion of the steps above, user-defined functions can be used freely without defining the same functions repeatedly.

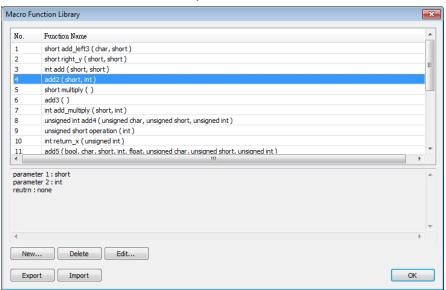
### 18.9.3. Function Library Management Interface

1. Open macro management dialog, click [Library] to open [Macro Function Library] dialog box.





2. A list of functions is shown. When the project is opened, the software will load all the functions in the Macro Function Library.



3. Each listed function has the following format:

return\_type function\_name ( parameter\_type1, ..., parameter\_typeN)

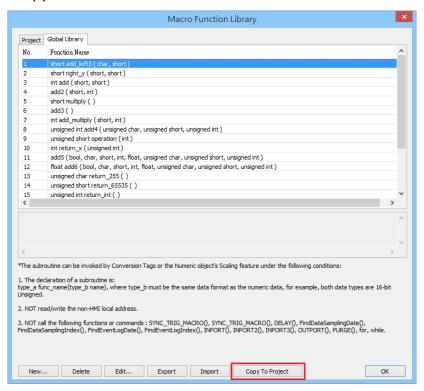
return\_type indicates the type of the return value. If this value does not exist, this column will be omitted. function\_name indicates the name of the function. "N" in parameter\_typeN stands for the number of parameter types. If this function does not



need any parameter, this column will be omitted.

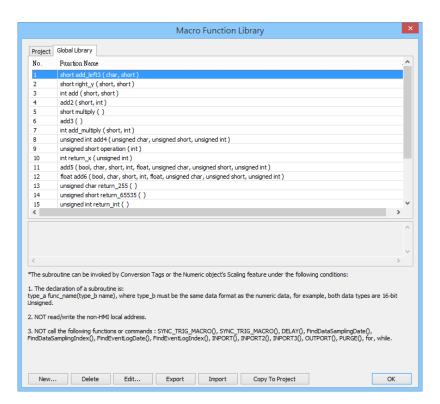
```
1  sub int ADD(int a, int b)
2  int ret
3  ret = a+b
4  return ret
5  end sub
```

4. Macro function can be embedded in the project file. Select the function and then click [Copy To Project], then you can find this function in [Project] tab. When opening the project on another computer, this function can still be used. When compiling the project, the .exob file will included the functions that are used. Please note that decompiling the project will only produce the macro commands that are used.

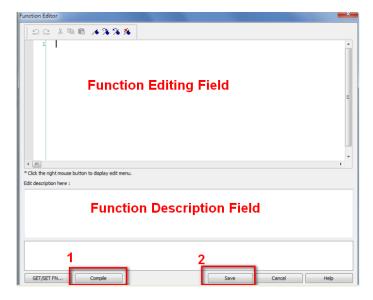


#### 18.9.3.1. Create a Function

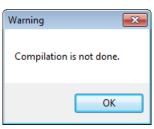
1. Click [New] to enter Function Editor.



2. Edit function in Function Editor.

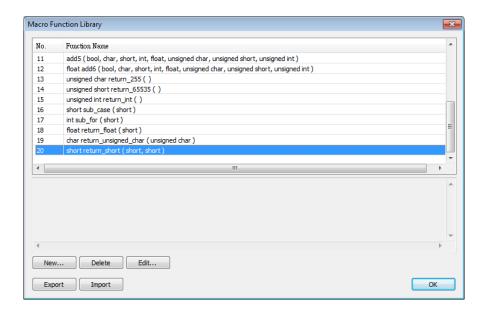


- **3.** Edit the function description to describe what the specification is, how to use ... etc.
- **4.** After editing, click [Compile] and [Save] to save this function to the Library. Otherwise, a warning is shown.



5. Successfully add a function into Macro Function Library.



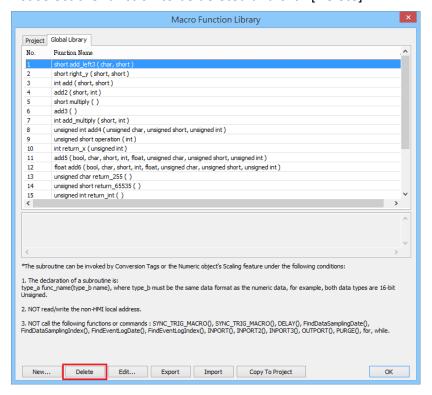




- The total size of data type can be declared in a function is 4096 bytes.
- Function name must only contain alphanumeric characters, and cannot start with a number.

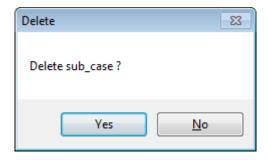
#### 18.9.3.2. Delete a Function

1. In function list select the function to be deleted and click [Delete].



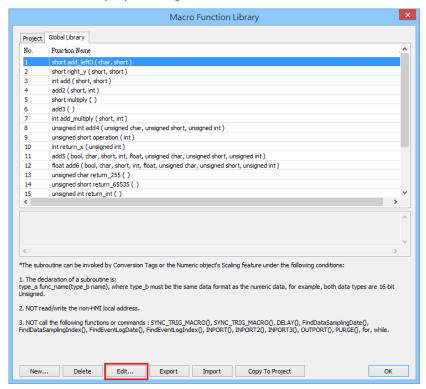
Click [Yes] to confirm, [No] to cancel the deletion. Click [Yes] to delete MAX\_SHORT function.





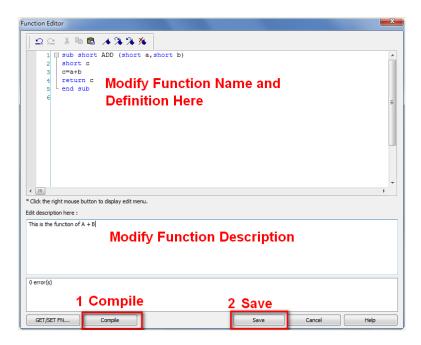
#### 18.9.3.3. Modify a Function

- 1. Users can modify the functions exist in the Library.
- Select a function to modify by clicking [Edit] to enter Function Editor.



3. Double click the function to be modified can also enter Function Editor.

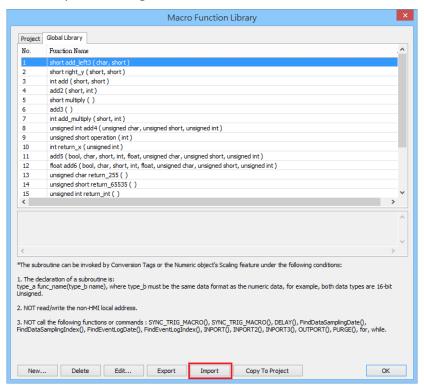




After modifying, [Compile] then [Save] before leaving.

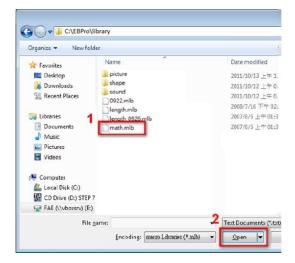
#### 18.9.3.4. Import a Function

1. Functions can be imported using an external .mlb file.

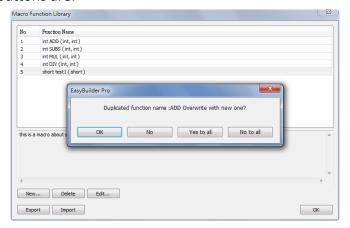


2. For example, import a function library "math.mlb" which contains a function "test1". Click [Open].





**3.** When importing a function which already exists in the Library, a confirmation pop-up will be shown. The buttons are:



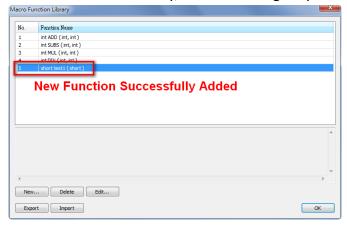
[OK]: Overwrite the existing function with the imported one.

[NO]: Cancel the importing of the function with the same name.

[Yes to all]: Overwrite using all the imported functions with the same name.

[No to all]: Cancel the importing of all the functions with the same name.

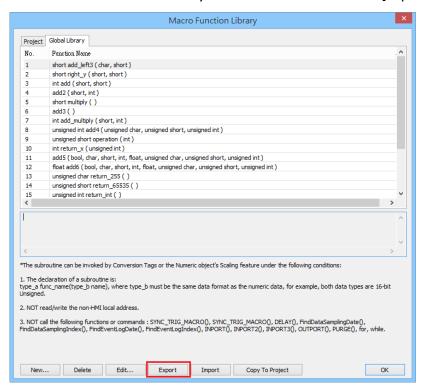
**4.** The imported functions will be saved in Default Function Library, so if "math.mlb" file is deleted, "test1" will still exist in the Library, even restarting EasyBuilder Pro.



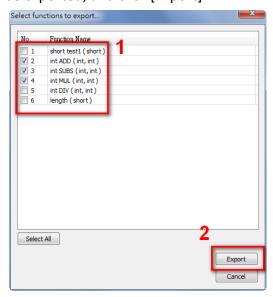


## 18.9.3.5. Export a Function

1. Export the function from Function Library and save as .mlb file. Click [Export].



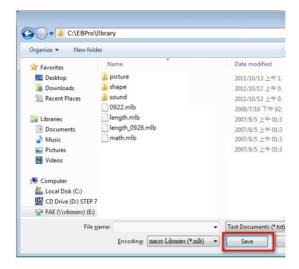
2. Select the function to be exported, and click [Export].



- A "math.mlb" file can be found under export directory. This file contains 4 functions: ADD, SUBS, MUL, and DIV.
- **4.** The exported .mlb file can be imported on another PC. Open HMI programming software, import, then the functions in this file can be used.



18-117



## 18.10. Some Notes about Using the Macro

1. The maximum storage space of local variables in a macro is 4K bytes. So the maximum array size of different variable types are as follows:

char a[4096] bool b[4096] short c[2048] int d[1024] float e[1024] long f[512] double g[512]

- 2. A maximum of 255 macros are allowed in an EasyBuilder Pro project. However, for cMT X Series projects, that number is increased to 500.
- A macro may cause the HMI to be unresponsive. Possible reasons may include:
- It contains an undesired infinite loop.
- Array size exceeds the available variable storage space in a macro.
- 4. The device communication speed may affects execution speed of the macro . Similarly, having too many macros may slow down the communication between an HMI and a device.

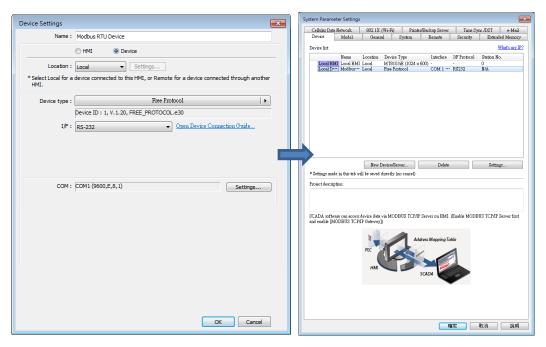
#### 18.11. Use the Free Protocol to Control a Device

If EasyBuilder Pro does not provide a driver for a specific device, users can use OUTPORT and INPORT built-in functions to control the device. The data sent by OUTPORT and INPORT must follow the communication protocol of the device. The following example explains how to use

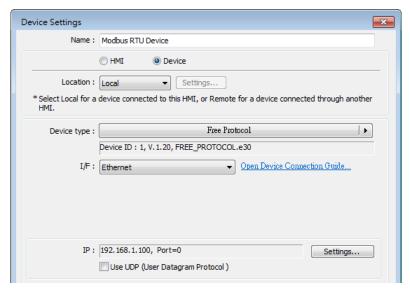


these two functions to control a MODBUS RTU device.

1. First, create a new device in the device table. The device type of the new device is set to "Free Protocol" and named with "MODBUS RTU device" as follows:



2. The interface of the device (I/F) uses [RS-232]. If a MODBUS TCP/IP device is connected, the interface should be [Ethernet] with correct IP and port number as follows:



Suppose that the HMI will read the data of 4x\_1 and 4x\_2 on the device. First, utilize OUTPORT to send out a read request to the device. The format of OUTPORT is:

OUTPORT(command[start], device\_name, cmd\_count)

Since "MODBUS RTU device" is a MODBUS RTU device, the read request must follow MODBUS RTU protocol. The request uses "Reading Holding Registers (0x03)" command to read data. The following picture displays the content of the command. (The items of the station number (byte 0) and the last two bytes (CRC) are ignored).



Request					
	Function code	1 Byte	0x03		
	Starting Address	2 Bytes	0x0000 to 0xFFFF		
	Quantity of Registers	2 Bytes	1 to 125 (0x7D)		
Response					
	Function code	1 Byte	0x03		
	Byte count	1 Byte	2 x N*		
	Register value	N* x 2 Bytes			
	*N = Quantity of Registers				
Error					
	Error code	1 Byte	0x83		
	Exception code	1 Byte	01 or 02 or 03 or 04		

Depending on the protocol, the content of a read command as follows (The total is 8 bytes):

```
command[0]: station number
                                                  (BYTE 0)
command[1]: function code
                                                  (BYTE 1)
command[2]: high byte of starting address
                                                  (BYTE 2)
command[3]: low byte of starting address
                                                  (BYTE 3)
command[4]: high byte of quantity of registers
                                                  (BYTE 4)
command[5]: low byte of quantity of registers
                                                  (BYTE 5)
command[6]: low byte of 16-bit CRC
                                                  (BYTE 6)
command[7]: high byte of 16-bit CRC
                                                  (BYTE 7)
```

So a read request is designed as follows:

```
char command[32]
short address, checksum

FILL(command[0], 0, 32) // initialize command[0]~command[31] to 0

command[0] = 0x1 // station number
command[1] = 0x3 // read holding registers (function code is 0x3)

address = // starting address (4x_1) is 0
HIBYTE(address, command[2])
LOBYTE(address, command[3])

read_no = 2 // the total words of reading is 2 words
HIBYTE(read_no, command[4])
LOBYTE(read_no, command[5])

CRC(command[0], checksum, 6) // calculate 16-bit CRC

LOBYTE(checksum, command[6])
HIBYTE(checksum, command[7])
```

Lastly, use OUPORT to send out this read request to the device.

```
OUTPORT(command[0], "MODBUS RTU Device", 8) // send read request
```

After sending out the request, use INPORT to get the response from the device. Depending on the protocol, the content of the response is as follows (the total byte is 9):



```
response[0]: station number
                                              (BYTE 0)
response[1]: function code
                                               (BYTE 1)
response[2]: byte count
                                               (BYTE 2)
response[3]: high byte of 4x_1
                                              (BYTE 3)
response[4]: low byte of 4x 1
                                              (BYTE 4)
response[5]: high byte of 4x_2
                                               (BYTE 5)
response[6]: high byte of 4x_2
                                              (BYTE 6)
response[7]: low byte of 16-bit CRC
                                               (BYTE 7)
response[8]: high byte of 16-bit CRC
                                              (BYTE 8)
The format of INPORT is:
```

```
INPORT(response[0], "MODBUS RTU Device", 9, return_value) // read response
```

Where the real read count is restored to the variable return\_value (unit is byte). If return\_value is 0, it means reading fails in executing INPORT.

According to the MODBUS RTU protocol specification, the correct response[1] must be equal to 0x03. After getting correct response, calculate the data of 4x\_1 and 4x\_2 and put in the data into LW-100 and LW-101 of HMI.

```
If (return_value) >0 and response[1] == 0x3) then
  read_data[0] = response[4] + (response[3] << 8) // 4x_1
  read_data[1] = response[6] + (response[5] << 8) // 4x_2

SetData(read_data[0], "Local HMI", LW, 100, 2)
endif</pre>
```

The complete macro is as follows:



```
// Read Holding Registers
macro command main()
  char command[32], response[32]
  short address, checksum
  short read no, return value, read data[2], i
  FILL(command[0], 0, 32)// initialize command[0]~command[31] to 0
  FILL(response[0], 0, 32)
  command[0] = 0x1// station number
  command[1] = 0x3// read holding registers (function code is 0x3)
  address = 0
  address = 0// starting address (4x_1) is 0
  HIBYTE(address, command[2])
  LOBYTE(address, command[3])
  read_no = 2/ the total words of reading is 2 words
  HIBYTE(read no, command[4])
  LOBYTE(read_no, command[5])
  CRC(command[0], checksum, 6)// calculate 16-bit CRC
  LOBYTE(checksum, command[6])
  HIBYTE(checksum, command[7])
  OUTPORT(command[0], "MODBUS RTU Device", 8 )// send request
  INPORT(response[0], "MODBUS RTU Device", 9, return_value)// read response
  if (return value > 0 and response[1] == 0x3) then
    read data[0] = response[4] + (response[3] << 8)// 4x 1
    read_data[1] = response[6] + (response[5] << 8)// 4x_2
    SetData(read_data[0], "Local HMI", LW, 100, 2)
  end if
  end macro command
```

The following example explains how to design a request to set the status of 0x\_1. The request uses "Write Single Coil(0x5)" command.



Request					
-	Function code	1 Byte	0x05		
	Output Address	2 Bytes	0x0000 to 0xFFFF		
	Output Value	2 Bytes	0x0000 or 0xFF00		
_					
Respo	Response				
	Function code	1 Byte	0x05		
	Output Address	2 Bytes	0x0000 to 0xFFFF		
	Output Value	2 Bytes	0x0000 or 0xFF00		
Error					
	Error code	1 Byte	0x85		
	Exception code	1 Byte	01 or 02 or 03 or 04		

The complete macro is as follows:

```
// Write Single Coil (ON)
macro_command main()
char command[32], response[32]
short address, checksum
short i, return value
FILL(command[0], 0, 32)// initialize command[0]~ command[31] to 0
FILL(response[0], 0, 32)
command[0] = 0x1// station number
command[1] = 0x5// function code : write single coil
address = 0
HIBYTE(address, command[2])
LOBYTE(address, command[3])
command[4] = 0xff// force 0x_1 on
command[5] = 0
CRC(command[0], checksum, 6)
LOBYTE(checksum, command[6])
HIBYTE(checksum, command[7])
OUTPORT(command[0], "MODBUS RTU Device", 8)// send request
INPORT(response[0], "MODBUS RTU Device", 8, return_value)// read response
end macro command
```

Click the icon to download the demo project. Please confirm your internet connection before downloading the demo project.

## 18.12. Compiler Error Message

Error Message Format



error C# : error description

(# is the error message number)

Example: error C37: undeclared identifier: i

When there are compile errors, the description of the error can be found by the compiler error message number.

### Error Description

(C1) syntax error: 'identifier'

There are many possibilities to cause compiler error.

## For example:

macro\_command main()
char i, 123xyz // this is an unsupported variable name
end macro\_command

(C2) 'identifier' used without having been initialized

Macro must define the size of an array during declaration.

#### For example:

macro\_command main()

char i

int g[i] // i must be a numeric constant
end macro command

(C3) redefinition error: 'identifier'

The name of variable and function within its scope must be unique.

#### For example:

macro\_command main()
int g[10] , g // error
end macro\_command

(C4) function name error: 'identifier'

Reserved keywords and constant cannot be the name of a function

#### For example:

sub int if() // error



```
(C5) parentheses have not come in pairs
Statement missing "(" or ")"
For example:
macro_command main ) // missing "("
(C6) illegal expression without matching 'if'
Missing expression in "if" statement
(C7) illegal expression (no 'then') without matching 'if'
Missing "then" in "if" statement
(C8) illegal expression (no 'end if')
Missing "end if"
(C9) illegal 'end if' without matching 'if'
Unfinished "If' statement before "End If"
(C10) illegal 'else'
The format of "if" statement is:
if [logic expression] then
[ else [if [logic expression] then ] ]
end if
Any format other than this format will cause a compile error.
(C17) illegal expression (no 'for') without matching 'next'
"for" statement error: missing "for" before "next"
(C18) illegal variable type (not integer or char)
Should be integer or char variable
(C19) variable type error
Missing assign statement
(C20) must be keyword 'to' or 'down'
Missing keyword "to" or "down"
```



(C21) illegal expression (no 'next') The format of "for" statement is: for [variable] = [initial value] to [end value] [step] next [variable] Any format other than this format will cause a compile error. (C22) 'wend' statement contains no 'while' "While" statement error: missing "while" before "Wend" (C23) illegal expression without matching 'wend' The format of "While" statement is: while [logic expression] wend Any format other than this format will cause a compile error. (C24) syntax error: 'break' "break" statement can only be used in "for", "while" statement. (C25) syntax error: 'continue' "continue" statement can only be used in "for" statement, or "while" statement. (C26) syntax error Error in expression. (C27) syntax error The mismatch of an operation object in expression can cause a compile error. For example: macro command main() int a, b for a = 0 to 2 b = 4 + xyz // illegal : xyz is undefined next a



end macro\_command (C28) must be 'macro\_command' There must be 'macro\_command' (C29) must be key word 'sub' The format of function declaration is: sub [data type] function\_name(...) ..... end sub For example:: sub int pow(int exp) ..... end sub format other than this format will cause a compile error. (C30) number of parameters is incorrect Mismatch of the number of parameters (C31) parameter type is incorrect Mismatch of data type of parameter. When a function is called, the data type and the number of parameters should match the declaration of function, otherwise it will cause a compile error. (C32) variable is incorrect The parameters of a function must be equivalent to the arguments passing to a function to avoid compile error. (C33) function name: undeclared function (C34) expected constant expression Illegal array index format. (C35) invalid array declaration



(C36) array index error

```
(C37) undeclared identifier: i 'identifier'
Any variable or function should be declared before use.
(C38) un-supported device data address
The parameter of GetData( ... ) , SetData( ... ) should be legal device address. If the address is
illegal, this error message will be shown.
(C39) 'identifier' must be integer, char or constant
The format of array is:
Declaration: array_name[constant] (constant is the size of the array)
Usage: array_name[integer, character or constant]
Any format other than this format will cause a compile error.
(C40) execution syntax should not exist before variable declaration or constant definition
For example:
macro_command main( )
int a, b
for a = 0 To 2
   b = 4 + a
int h, k // illegal – definitions must occur before any statements or expressions
         // for example, b = 4 + a
next a
end macro_command
(C41) float variables cannot be contained in shift calculation
(C42) function must return a value
(C43) function should not return a value
(C44) float variables cannot be contained in calculation
(C45) device address error
```



(C46) array size overflow (max. 4k)

(C47) macro command entry function is not only one

(C48) macro command entry function must be only one The only one main entrance of macro is : macro\_command function\_name() end macro\_command

(C49) an extended addressee's station number must be between 0 and 255

#### For example:

SetData(bits[0] , "PLC 1", LB , 300#123, 100)

// illegal: 300#123 means the station number is 300, but the maximum is 255

(C50) an invalid device name

Device name is not defined in the device list of system parameters.

(C51) macro command do not control a remote device A macro can only control a local machine.

#### For example:

SetData(bits[0], "PLC 1", LB, 300#123, 100)

"PLC 1" is connected with the remote HMI, so it cannot work.

(C95) total number of characters exceeds 100000

The total number of characters for a macro command should not exceed 100,000.

To utilize a macro command that exceeds the character limit, users need to adjust the command's character count to be below 100,000 first. Once adjusted, the SYNC\_TRIG\_MACRO function can be employed to synchronously trigger the execution of other macro commands. This approach enables the successful execution of a macro command with a total character count exceeding 100,000.

#### 18.13. Sample Macro Code

• "for" statement and other expressions (arithmetic, bitwise shift, logic and comparison) macro\_command main() int a[10], b[10], i

$$b[0] = (400 + 400 << 2) / 401$$



```
b[1] = 22 *2 - 30 % 7
b[2] = 111 >> 2
b[3] = 403 > 9 + 3 >= 9 + 3 < 4 + 3 <= 8 + 8 == 8
b[4] = not 8 + 1 and 2 + 1 or 0 + 1 xor 2
b[5] = 405 and 3 and not 0
b[6] = 8 & 4 + 4 & 4 + 8 | 4 + 8 ^ 4
b[7] = 6 - (^4)
b[8] = 0x11
b[9] = 409
for i = 0 to 4 step 1
 if (a[0] == 400) then
       GetData(a[0], "Device 1", 4x, 0,9)
       GetData(b[0],"Device 1", 4x, 11,10)
 end If
  next i
  end macro_command
     "while", "if" and "break" statements
  macro_command main()
 int b[10], i
 i = 5
  while i == 5 - 20 % 3
       GetData(b[1], "Device 1", 4x, 11, 1)
       if b[1] == 100 then
            break
       end if
  wend
  end macro_command
    Global variables and function call
 char g
  sub int fun(int j, int k)
      int y
       SetData(j, "Local HMI", LB, 14, 1)
       GetData(y, "Local HMI", LB, 15, 1)
```



```
g = y
     return y
end Sub
macro_command main()
     int a, b, i
a = 2
b = 3
    i = fun(a, b)
     SetData(i, "Local HMI", LB, 16, 1)
end macro_command
   "if" statement
macro_command main()
     int k[10], j
     for j = 0 to 10
          k[j] = j
     next j
     if k[0] == 0 then
     SetData(k[1], "Device 1", 4x, 0, 1)
     end if
if k[0] == 0 then
          SetData(k[1], "Device 1", 4x, 0, 1)
     else
     SetData(k[2], "Device 1", 4x, 0, 1)
end if
     if k[0] == 0 then
          SetData(k[1], "Device 1", 4x, 1, 1)
     else if k[2] == 1 then
     SetData(k[3], "Device 1", 4x, 2, 1)
end If
```



```
if k[0] == 0 then
    SetData(k[1], "Device 1", 4x, 3, 1)
else if k[2] == 2 then
    SetData(k[3], "Device 1", 4x, 4, 1)
else
    SetData(k[4], "Device 1", 4x, 5, 1)
end If
end macro_command

"while" and "wend" statements
macro_command main()
char i = 0
int a[13], b[14], c = 4848
```

b[0] = 13

while b[0]

$$a[i] = 20 + i * 10$$

if a[i] == 120 then
c =200
break
end if

i = i + 1

wend

SetData(c, "Device 1", 4x, 2, 1) end macro command

 "break" and "continue" statements macro\_command main() char i = 0 int a[13], b[14], c = 4848

b[0] = 13

while b[0]



```
a[i] = 20 + i * 10
          if a[i] == 120 then
          c = 200
          i = i + 1
               continue
          end if
     i = i + 1
     if c == 200 then
          SetData(c, "Device 1", 4x, 2, 1)
     break
          end if
wend
end macro_command
   Array
macro_command main()
int a[25], b[25], i
b[0] = 13
for i = 0 to b[0] step 1
     a[i] = 20 + i * 10
next i
SetData(a[0], "Device 1", 4x, 0, 13)
end macro command
   Syntax for placing quotation marks in a string applies to variable declaration and
   function's argument.
macro_command main()
char data[40]= "\"Note\" "
StringCopy("This is a \"test\" for weintek", data[7])
```



end macro\_command

//The string contains "Note" This is a "test" for weintek

18-133

## 18.14. Macro TRACE Function

TRACE function can be used with EasyDiagnoser / cMT Diagnoser to show the current content of the variables. For users of cMT /cMT X series, a better, more straightforward way would be to use the Macro Debugger in the cMT Diagnoser for debugging. The use of TRACE function is not required.

The following example explains how to use TRACE function in macro and then use EasyDiagnoser for monitoring.

First of all, add a new macro "macro\_0" in the project, and in "macro\_0" add TRACE ("LW = %d", a). "%d" indicates display current value of LW in decimal format. The content of "macro\_0" is as follows:

```
macro_command main()

short a

GetData(a, "Local HMI", LW, 0, 1)

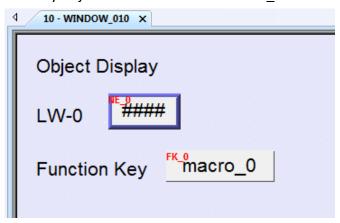
a=a+1

SetData(a, "Local HMI", LW, 0, 1)

TRACE ("LWO = %d", a)

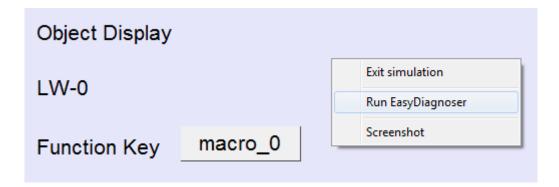
end macro_command
```

2. Secondly, add a Numeric Display object and a Function Key object in window no. 10 of the project. The Function Key object is used to execute macro 0.

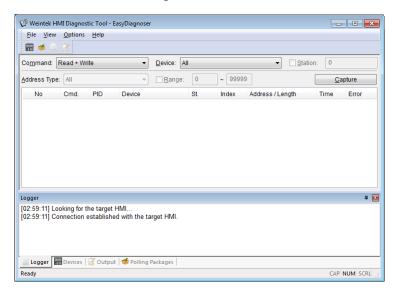


- 3. Lastly, compile the project and execute [Off-line simulation] or [On-line simulation].
- **4.** When processing simulation on PC, right click and select "Run EasyDiagnoser" in the pop-up menu.





5. Afterwards, EasyDiagnoser will be started. [Logger] window displays whether EasyDiagnoser is able to connect with the HMI to be watched or not. [Output] window displays the output of the TRACE function. The illustration below shows that EasyDiagnoser succeeds in connecting with HMI.

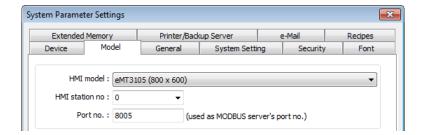


When EasyDiagnoser is not able to connect with HMI, [Logger] window displays content as shown in the following figure:

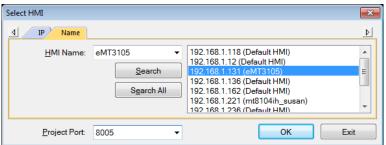


6. The possible reason of not being able to get connection with HMI can be failure in executing simulation on PC. Another reason is that the Port No. used in project for simulation on PC is incorrect (or occupied by system). Please change Port No. as shown, compile project then do simulation again.





7. In EasyDiagnoser, the Port No. should be set the same as the Port No. in the project.



The three consecutive ports of the project port no. are preserved for HMI communication. In the setting above as an example, Port No. is set as 8005. Port 8005, 8006 and 8007 should be reserved. In this case when executing simulation on PC, please make sure that these ports are not occupied by other programs.

#### **TRACE Syntax List**

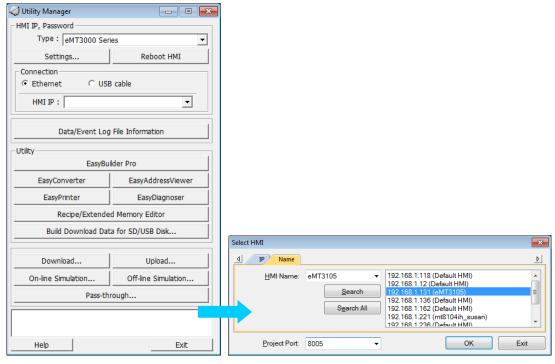
Name	TRACE
Syntax	TRACE(format, argument)
Description	Use this function to send specified string to the EasyDiagnoser / cMT Diagnoser. Users can print out the current value of variables during run-time of macro for debugging.  When TRACE encounters the first format specification (if any), it converts the value of the first argument after format and outputs it accordingly. format refers to the format control of output string. A format specification, which consists of optional (in []) and required fields (in red font), has the following form:  %[flags] [width] [.precision] type Each field of the format specification is described as below: flags (optional):  -: Aligns left. When the value has fewer characters than the specified width, it will be padded with spaces on the left. +: Precedes the result with a plus or minus sign (+ or -) width (optional):  A nonnegative decimal integer controlling the minimum number of characters printed. precision (optional):  A nonnegative decimal integer which specifies the precision and the number of characters to be printed.
	C or c : specifies a single-byte character d : signed decimal integer



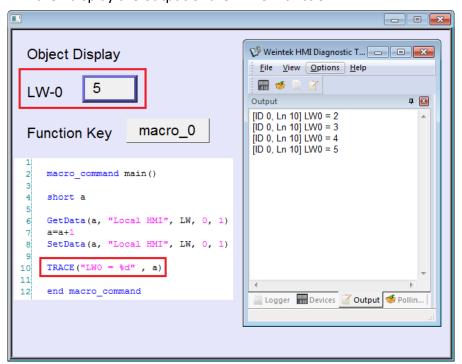
i : signed decimal integer : unsigned octal integer 0 : unsigned decimal integer u : unsigned hexadecimal integer X or x : signed long integer (64-bit) (cMT / cMT X Series only) lld : unsigned long integer (64-bit) (cMT / cMT X Series only) llu : signed floating-point value f llf : double-precision floating-point value E or e : Scientific notation in the form "[ - ]d.dddd e [sign]ddd", where d is a single decimal digit, dddd is one or more decimal digits, ddd is exactly three decimal digits, and sign is + or -. The length of output string is limited to 256 characters. Extra characters will be ignored. The *argument* part is optional. One format specification converts exactly one argument. macro command main() Example char c1 = 'a' short s1 = 32767float f1 = 1.234567TRACE("The results are") // output: The results are TRACE("c1 = %c, s1 = %d, f1 = %f", c1, s1, f1) // output: c1 = a, s1 = 32767, f1 = 1.234567 end macro command

- 8. Use LB-9059 to disable MACRO TRACE function (when ON). When set ON, the output message of TRACE won't be sent to EasyDiagnoser.
- 9. Users can directly execute EasyDiagnoser.exe from Utility Manager. In Utility Manager, current HMI on line will be listed; users can simply select the HMI to be watched. Please note that Project Port should be the same as Port No. used in project file.





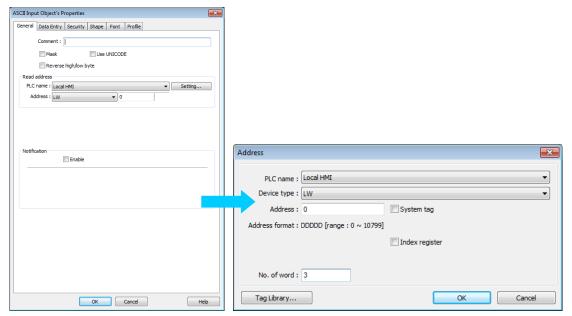
- 10. Download the project to HMI and start the project. If EasyDiagnoser is unable to get connection with the HMI to be watched, it is possible that HMI power is not ON, or Port No. is incorrect. This may cause EasyDiagnoser to connect then disconnect with HMI continuously. Please check the Port No. in EasyDiagnoser settings.
- 11. When EasyDiagnoser succeeds in connecting with HMI, simply execute macro\_0, [Output] window will then display the output of the TRACE function.





## **18.15.** Example of String Operation Functions

String operation functions are added to macro to provide a convenient way to operate strings. The term "string" means a sequence of ASCII characters, and each of them occupies 1 byte. The sequence of characters can be stored into 16-bit registers with least significant byte first. For example, create an ASCII Input object and setup as follows:



Run simulation and input "abcdef":



The string "abcdef" is stored in LW-0~LW-2 as follows (LB represents low byte and HB represents high byte):

	HB	LB
LW0	'B'	'A'
LW1	'D'	'C'
LW2	'F'	'E'
LW3		
LW4		
LW5		

The ASCII Input object reads 1 word (2 bytes) at a time as described in the previous chapter. Suppose an ASCII Input object is set to read 3 words as shown in the above example, it can actually read at most 6 ASCII characters since that one ASCII character occupies 1 byte.

In order to demonstrate the powerful usage of string operation functions, the following examples will show you step by step how to create executable project files using the new



functions; starts from creating a macro, ends in executing simulation.

1. To read (or write) a string from a device:

Create a new macro:

```
Macro Ist

New...
```

Edit the content:

```
macro_command main()

macro_command main()

char str[20]

StringGet(str[0], "Local HMI", LW, 0, 20)

StringSet(str[0], "Local HMI", LW, 50, 20)

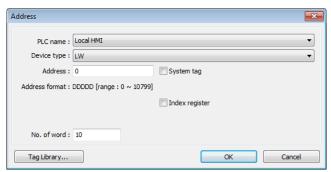
end macro_command
```

The first function "StringGet" is used to read a string from LW-0~LW-19, and store it into the str array. The second function "StringSet" is used to output the content of str array.

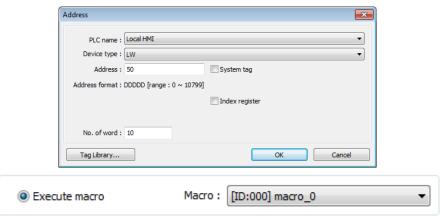
Add one ASCII Input object and one If Function Key object in window 10 of the project. The settings of these objects are shown as below. Function Key object is used to execute macro\_0.



# ASCII Input object:

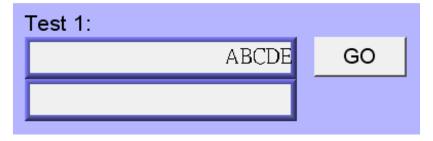


## ■ Function Key object:



Lastly, use  $\ref{lastly}$  [Compile] to compile the project and execute  $\ref{lastly}$  [Off-line simulation] or  $\ref{lastly}$  [On-line simulation]. Follow the steps below to operate the executing project:

- Step 1. Input string.
- Step 2. Press "GO" button.



Step 3. Output string.



2. Initialization of a string.

Create a new macro and edit the content:



```
1
2  macro_command main()
3
4  char str1[20]="abcde"
5  char str2[20]={'a','b','c','d','e'}
6
7  StringSet(str1[0], "Local HMI", LW, 0, 20)
8  StringSet(str2[0], "Local HMI", LW, 50, 20)
9
10  end macro_command
```

The data enclosed in double quotation mark (" ") is viewed as a string. str1 is initialized as a string while str2 is initialized as a char array. The following snapshot of simulation shows the difference between str1 and str2 using two ASCII Input objects.



Macro compiler will add a terminating null character ('\0') at the end of a string. The function "StringSet" will send each character of str1 to registers until a null character is reached. The extra characters following the null character will be ignored even if the data count is set to a larger value than the length of string.

On the contrary, macro compiler will not add a terminating null character ( $^{\prime}$ \0 $^{\prime}$ ) at the end of a char array. The actual number of characters of str2 being sent to registers depends on the value of data count that is passed to the "StringSet" function.

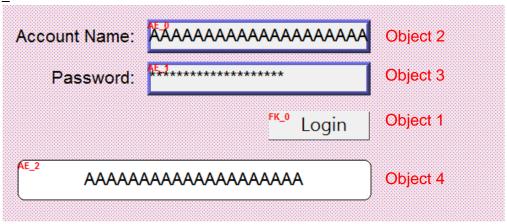
3. A simple login page.

Create a new macro and edit the content, for example, Macro [ID:001] macro 1.



```
macro_command main()
    char name[20]="admin"
    char password[20]="123456"
    char name input[20], password input[20]
    char message_success[40]="Success! Access Accepted."
    char message_fail[40]="Fail! Access Denied."
    char message_clear[40]
    bool name_match=false, password_match=false
10
11
12
    StringGet(name_input[0], "Local HMI", LW, 0, 20)
    StringGet(password_input[0], "Local HMI", LW, 50, 20)
13
14
    name_match = StringCompare(name_input[0], name[0])
15
   password_match = StringCompare(password_input[0], password[0])
16
17
    FILL(message_clear[0], 0x20, 40) //FILL with white space
18
    StringSet(message_clear[0], "Local HMI", LW, 100, 40)
19
20
21 p if (name match==true and password match==true) then
        StringSet(message success[0], "Local HMI", LW, 100, 40)
22
    else
23
        StringSet(message fail[0], "Local HMI", LW, 100, 40)
24
25
   end if
26
    end macro command
27
```

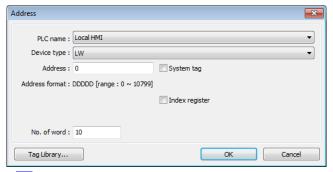
The first two "StringGet" functions will read the strings input by users and store them into arrays named name\_input and password\_input separately. Use the function "StringCompare" to check if the input account name and password are matched. If the account name is matched, name\_match is set true; if the password is matched, password\_match is set true. If both name\_match and password\_match are true, output the string "Success! Access Accepted.". Otherwise, output the string "Fail! Access Denied.". Add ASCII Input and Function Key objects in window 10 of the project. The settings of these objects are shown as below. Function Key object is used to execute macro 1.



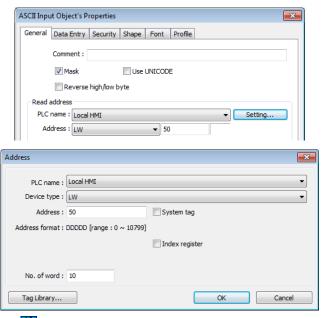
Object 1: Function Key 
Select [Execute macro] and Macro: [ID:000] macro 1.



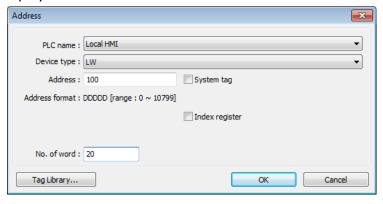
Object 2: ASCII Input 😃



Object 3: ASCII Input 😃



Object 4: ASCII Display

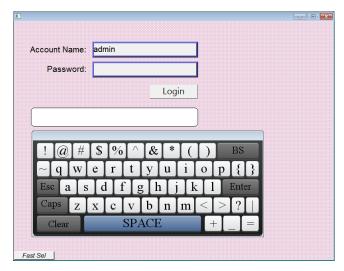


Lastly, use  $\ref{lastly}$  [Compile] to compile the project and execute  $\ref{lastly}$  [Off-line simulation] or  $\ref{lastly}$  [On-line simulation]. Follow the steps below to operate the executing project:

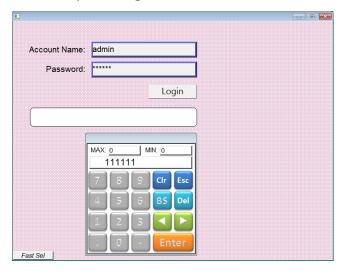


Macro Reference 18-144

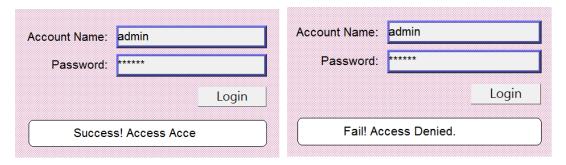
Step 1. Enter account name.



Step 2. Enter password and press [Login] button.



Step 3. Login succeeded or failed.

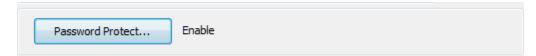




### 18.16. Macro Password Protection

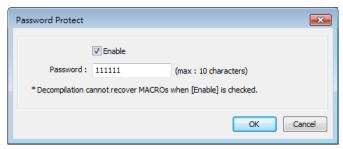
A password can be set to protect all the macros in the list, or an individual macro.

### **Protecting all macros:**

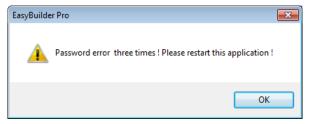


In Macro Manager window there's the [Password Protect...] button, click it and then click [Enable] to set a password less than or equals to 10 characters (support ASCII character only, e.g. "a\$#\*hFds").

After setting the password, users will have to enter correct password when opening Macro Manager.



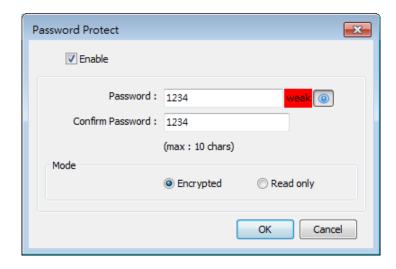
EasyBuilder Pro should be rebooted for typing the password again after 3 incorrect attempts.



### **Protecting individual macro:**

In the Work Space for editing an individual macro, click the [Password Protect...] button and then click [Enable] to set a password less than or equals to 10 characters (support ASCII character only, e.g. "a\$#\*hFds"). [Encrypted] and [Read only] modes work as follows.





### [Encrypted]

Encrypt the macro content. Entering macro editing window will require password.

EasyBuilder Pro should be rebooted for typing the password again after 3 incorrect attempts opening the same macro.

(The number of allowable incorrect attempts may vary between macros.)

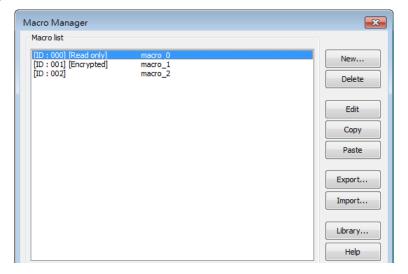
### [Read-only]

The user can only view the content of the macro and will not be able to edit it.

With this mode selected, macro editing window can be opened directly from Macro Manager; however, a password is required after clicking [Password Protect...] button.

EasyBuilder Pro should be rebooted for typing the password again after 3 incorrect attempts.

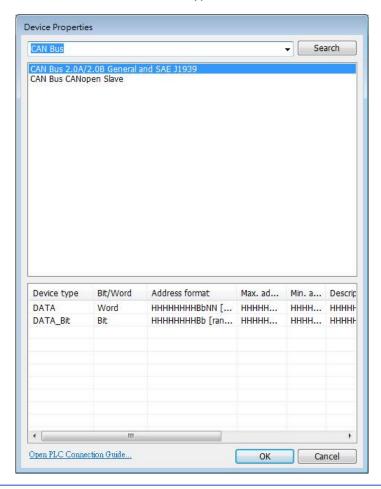
In the macro list, the selected mode for each macro is shown.





### 18.17. Reading / Writing CAN bus Address Using Variable

In "CAN Bus 2.0A/2.0B General and SAE J1939" driver, two device types can be found: DATA and DATA\_Bit, and the formats of these device types are shown in the following window.



Device Type & Address Format	Description
	H: ID
DATA	B: Byte position(1~8)
НННННННВЫNN	b: Bit position (1~8)
	NN: Bit number(1~64)
DATA DIA	H: ID
<b>DATA_Bit</b> НННННННВb	B: Byte position(1~8)
	b: Bit position(1~8)

The ID is represented in hexadecimal while the position and number are represented in decimal, please see the usage below.

### **Examples:**



Macro Reference 18-148

```
Variable is not used:
short f
GetData(f, "CAN Device", DATA, 4e55108, 1)
GetData(f, "CAN Device", DATA, 4e65108, 1

Variable is used:
short f
unsigned int address = 0x4e55108
GetData(f, "CAN Device", DATA, address, 1)
address = address + 0x10000// == 0x4e65108
GetData(f, "CAN Device", DATA, address, 1)
```

#### Please note that:

1. Declare variable as "Unsigned int" and use hexadecimal to represent address. Since the size of Unsigned int is 4 bytes and Bb, NN take 1 byte respectively, when using a variable for address parameter to read/write DATA\_Bit device type, the format will change to HHHHHHBb (Max. ID: 0xffffff), and when using a variable for address parameter to read/write DATA device type, the format will change to HHHHBbNN (Max. ID: 0xffff).



# 19. Configure HMI as a MODBUS Server

This chapter explains how to configure HMI as a MODBUS Server.

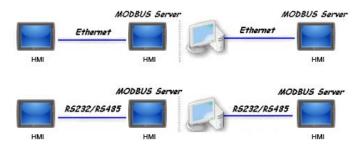
19.1.	Overview	. 19-2
19.2.	Steps to Create a MODBUS Server	. 19-2
19.3.	Steps to Access a MODBUS Server	. 19-4
19.4.	Changing MODBUS Server Station Number Online	. 19-7
19.5.	MODBUS Address Type	. 19-7



### 19.1. Overview

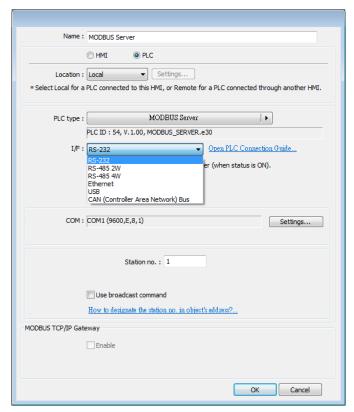
Once the HMI is configured as a MODBUS device, the data of HMI can be read or written via MODBUS protocol.

As shown in the following figure, the HMI is configured as a MODBUS device (also called MODBUS Server). The HMI, PC or other devices can use MODBUS protocol to read or write HMI data via Ethernet or RS-232 / RS-485 interface.



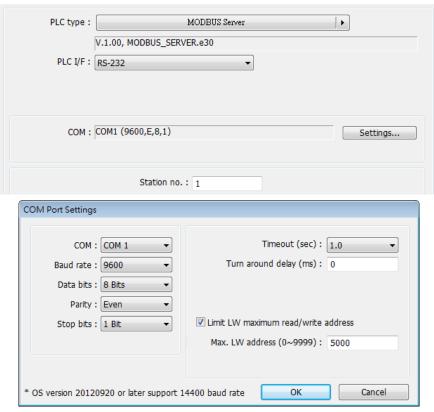
### 19.2. Steps to Create a MODBUS Server

To configure the HMI as a MODBUS device, add a new device to the device list in [System Parameters] first. Click [PLC type] drop-down box and select "MODBUS Server" driver. [PLC I/F] includes: RS-232 / RS-485 2W / RS-485 4W / Ethernet / USB / CAN BUS. Choose the PLC interface appropriate for your PLC model.

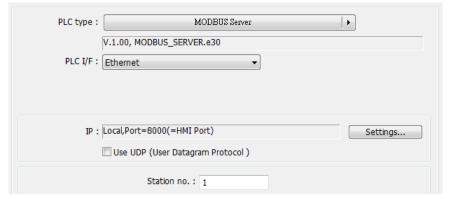




2. If [PLC I/F] is set to [RS-232] or [RS-485], please select [COM] (COM 1 ~ COM 3) and set correct communication parameters as shown in the following figure. MODBUS Server [Station no.] is set to 1. Click [Settings], the maximum LW address range read / written by Modbus Client can be set. When the object in the project uses a LW register, the Modbus Client will not be able to read or write an address that is not within the specified range.

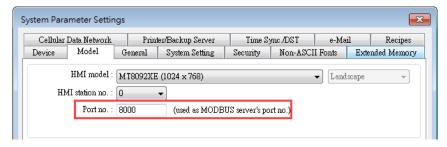


If [PLC I/F] is set to [Ethernet], please set [Port no.].

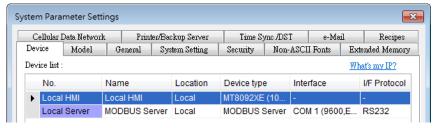


The [Port no.] of MODBUS Server and HMI must be the same. To change the port number, please set in the [System Parameters] » [Model] tab.



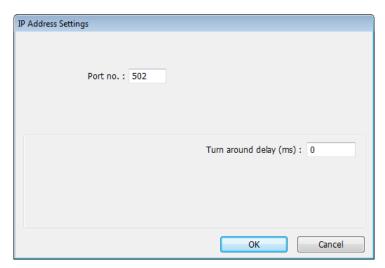


3. When finished, MODBUS Server is listed in [Device] tab. The configuration of MODBUS device is completed. Compile the .emtp file and download the compiled .exob file to the HMI, then HMI data can be read or written by using MODBUS protocol.





For cMT / cMT X Series models, if [Ethernet] PLC interface is chosen, port number can be specifed.

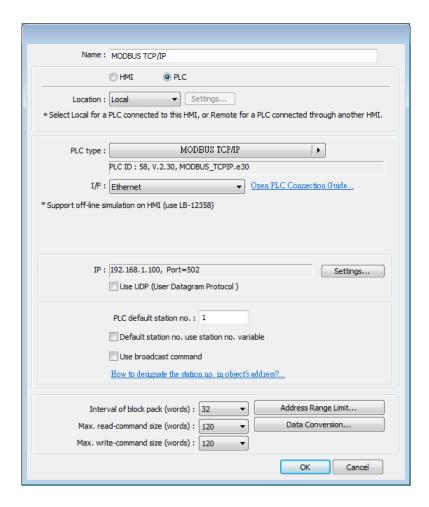


### 19.3. Steps to Access a MODBUS Server

Two HMIs can be configured as one MODBUS client and one MODBUS server to communicate and exchange data.

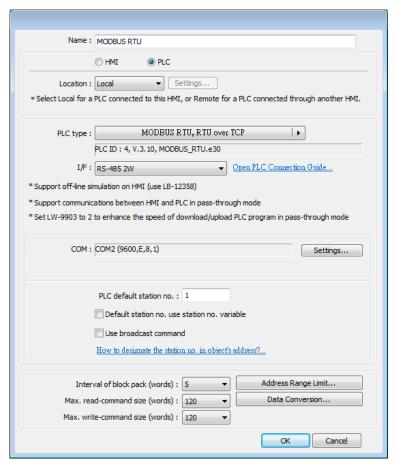
 Add a new device in client's device list. If the client chooses [Ethernet] PLC interface, set [PLC type] to "MODBUS TCP/IP" and fill in the correct [IP address] (the IP of MODBUS Server), [Port no.], and [Station no.].



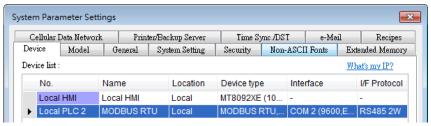


If the client chooses [RS-232] or [RS-485] PLC interface, the [PLC type] must be set to "MODBUS RTU", and its communication parameters also must be configured correctly.

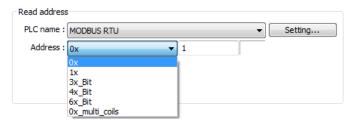




2. When finished, click [OK], then a new device "MODBUS RTU" is listed in the [Device] tab.



In the setting page of each object, select "MODBUS RTU" in [PLC name], and set the address of MODBUS RTU.



Since the server is an HMI, the corresponding read and write addresses are listed below:

0x/1x (1 ~ 12800)	LB (0 ~ 12799)
3x/4x/5x (1 ~ 9999)	LW (0 ~ 9998)
3x/4x/5x (10000 ~ 65535)	RW (0 ~ 55535)



### 19.4. Changing MODBUS Server Station Number Online

EasyBuilder Pro provides the following system registers to change MODBUS Server station number online.

LW-9541	MODBUS/ASCII server station no. (COM 1)
LW-9542	MODBUS/ASCII server station no. (COM 2)
LW-9543	MODBUS/ASCII server station no. (COM 3)
LW-9544	MODBUS/ASCII server station no. (Ethernet)

### 19.5. MODBUS Address Type

In the EasyBuilder Pro, the address types of MODBUS protocol are 0x, 1x, 3x, 4x, 5x, 6x, 3x\_bit and 4x\_bit. MODBUS RTU function codes are listed below:

_		
0x: Coils	A read and write device type. When reading a bit with this device type, the function code is 01H. When writing a bit, the function code is 05H. When writing multiple bits, the function code is 0fH.	
1x: Discrete Inputs	A read only device type. When reading a bit the function code is 02H.	
3x: Input Registers	A read only device type. When reading data, the function code is 04H.	
4x: Holding Register	A read and write device type. When reading data, the function code is 03H. When writing data, the function code is 10H.	
5x	The function code is the same as 4x. The difference is that 5x makes double word swap when the format is 32-bit unsigned. If the data read by 4x is 0x1234, the data read by 5x is 0x3412.	
6x	A read and write device type. When reading data, the function code is 03H. The difference from 4x is that when writing data, the function code is 06H, meaning to write a single register.	
3x_bit	The function code is the same as 3x. The difference is that 3x_bit reads a single bit in the data.	
4x_bit	The function code is the same as 4x. The difference is that 4x_bit reads a single bit in the data.	
6x_bit	The function code is the same as 6x. The difference is that 6x_bit reads a single bit in the data.	

For more information, see "37 MODBUS TCP/IP Gateway".

Click the icon to download the demo project. Please confirm your internet connection before downloading the demo project.



# 20. How to Connect a Barcode Scanner

This chapter explains how to connect a barcode scanner and the relevant settings.

20.1.	Overview	. 20-2
20.2.	Steps to Connect a Barcode Scanner	. 20-2
20.3	CDC/POS Mode	20-6



### 20.1. Overview

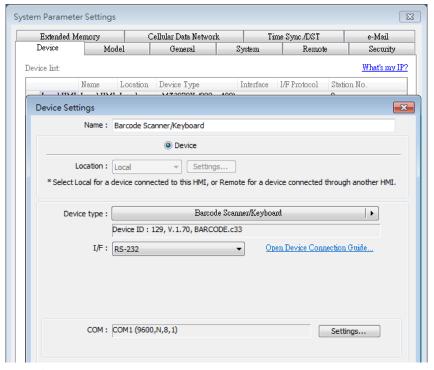
An HMI can connect with a barcode scanner via the following interfaces:

- USB
- COM port

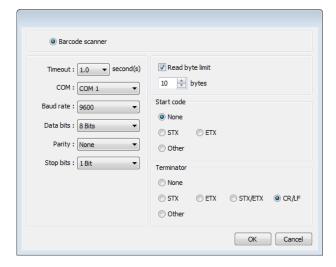
To connect a barcode scanner, please add a new device by the following steps.

### 20.2. Steps to Connect a Barcode Scanner

1. In EasyBuilder Pro click [System Parameters] » [Device list] and add a new device.



2. Click [Settings...] and finish the settings.





Setting	Description	
Timeout	When [Barcode scanner] is selected, if the device reads	
	slowly, a longer timeout is suggested for the device to	
	complete reading data.	
	When [Keyboard] is selected, a time range can be set	
	for keyboard entries. The system starts counting time	
	from the first entry.	
СОМ	When using COM port, please set the communication	
Baud rate Data bits	parameters correctly.	
Parity	When using USB, there is no need to set the	
Stop bits	parameters.	
Read byte limit	With this option selected, the number of bytes a	
	barcode scanner reads is restricted in order to prevent	
	overloading. The range is 10 to 1024.	
	Please note that the data cannot be read if it exceeds	
	the limit.	
Start code	The data is only valid when the first data is identical to	
	the start code, otherwise the data will be ignored. The	
	start code will not be stored in the address of barcode	
	scanner.	
	None	
	When no start code is used, HMI will save all the data to	
	the designated address of barcode scanner.	
	STX	
	Use 0x02 as start code.	
	ETX	
	Use 0x03 as start code.	
	Other	
	Use user-defined start code.	
	Example: If the start code is 255 (0xff), and the data	
	read is:	
	Oxff 0x34 0x39 0x31 0x32 0x30 0x30 0x34 0x37	
	The data saved in the designated barcode scanner	
	address will be:	
	0x34 0x39 0x31 0x32 0x30 0x30 0x34 0x37	
Terminator	A terminator represents the end of data stream.	
	None	
	When no terminator is used, HMI will save all the data	



to the designated address of barcode scanner. **STX** Use 0x02 as terminator. **ETX** Use 0x03 as terminator. STX/ETX Use 0x02 or 0x03 as terminator. CR/LF Use 0x0a or 0x0d as terminator. Other Use user-defined terminator. Example: If the terminator is 55 (0x37), and the data read is: 0x34 0x39 0x31 0x32 0x30 0x30 0x34 0x37 The data saved in the designated barcode scanner address will be: 0x34 0x39 0x31 0x32 0x30 0x30 0x34

After adding the barcode scanner in the device list, it can then be selected in object settings with the following addresses to use.

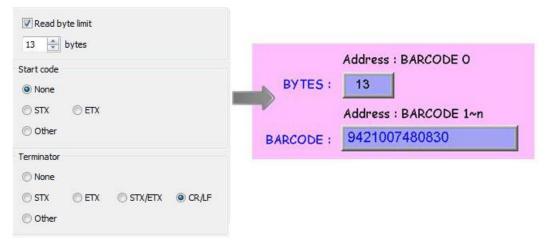
Address Type	<b>Address Name</b>	Description
Bit	FLAG	FLAG 0 indicates the status of data
		reading. When reading data, the status of
		FLAG 0 is set OFF and will return ON after
		reading data successfully.
	RESET	RESET 0 clears the data of BARCODE and
		RESULT when set ON.
	CONNECT_STAT	CONNECT_STATUS 0 indicates whether
	US	the barcode scanner (USB interface) is
		connected. When the status is ON, the
		barcode scanner is connected.
Word	BARCODE	BARCODE 0: Number of bytes currently
		read.
		BARCODE 1 ~ n: Stores the data read.
	RESULT	RESULT 0 indicates the result of data
		reading. The following codes indicate:
		<b>0x00</b> Waiting to read BARCODE.



<b>0x01</b> BARCODE successfully read.
<b>0x02</b> Invalid BARCODE format.
<b>0x03</b> The number of bytes specified in
[Read byte limit] exceeded.
<b>0x04</b> The Start Code of the data read
does not match the setting.
<b>0x05</b> The Terminator of the data read
does not match the setting.

### **Example 1**

The following is a setting example, the barcode is 9421007480830. BARCODE 0 is the address of Numeric Object (BYTES) and BARCODE 1  $^{\sim}$  n is the address of ASCII object (BARCODE).



In the example the data stored in the barcode scanner address is listed in the following table:

<b>Barcode Scanner Address</b>	Data
	13 bytes (decimal)
	However, the data saved is 14 bytes = 7
BARCODE 0	words. It is because when the number of
	bytes is an odd number, the system adds a
	byte (0x00) to make it an even number.
BARCODE 1	3439 (HEX)
BARCODE 2	3132 (HEX)
BARCODE 3	3030 (HEX)
BARCODE 4	3437 (HEX)
BARCODE 5	3038 (HEX)
BARCODE 6	3338 (HEX)
BARCODE 7	0030 (HEX)





An HMI can only be connected with one USB barcode scanner. When the device list in the project includes this kind of device, the system register LB-9064: [enable USB barcode device (disable keyboard) (when ON)] is set ON. To enable USB keyboard again and stop using USB barcode scanner, please set LB-9064 OFF.

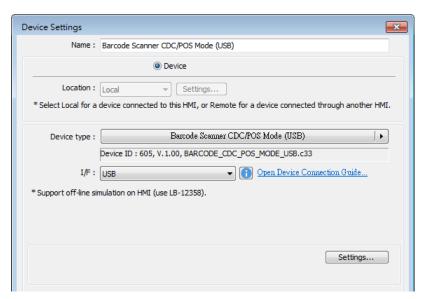


Click the icon to download the demo project. Please confirm your internet connection.

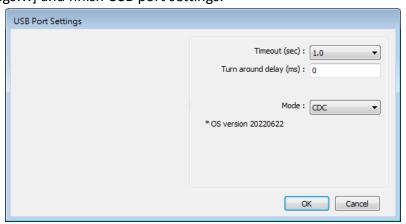
#### 20.3. **CDC/POS Mode**

Certain barcode scanners can be configured to communicate in CDC or POS mode for higher reading speed.

In [System Parameters] » [Device list] add a "Barcode Scanner CDC/POS Mode (USB)" device.



Click [Settings...] and finish USB port settings.





Setting	Description
Timeout (sec)	The barcode scanner is considered as disconnected
	when the HMI has not received a response from the
	barcode scanner for a period of time set by timeout.
	In CDC mode, due to the lack of the terminating
	character, the timeout setting determines the elapsed
	time before the HMI stops receiving data.
Turn around	The HMI delays the sending of the next command for
delay (ms)	the specified period of time.
Mode	Select CDC or POS mode.

After adding the barcode scanner in the device list, it can then be selected in object settings with the following addresses to use.

Address Type	<b>Address Name</b>	Description
Bit	flag	Indicates the status of data
		reading. When reading data, the
		status of flag is set OFF and will
		return ON after data is
		successfully read.
Word	data	data 0~1999: Store the data
		read.
	state	state 0: The value is 0 when no
		barcode scanner is detected, and
		the value is 1 when the barcode
		scanner is connected
		successfully.
	len	Len 0: Number of bytes currently
		read.



# 21. Ethernet Communication and Multi-HMI Connection

This chapter explains how to connect multiple devices via Ethernet.

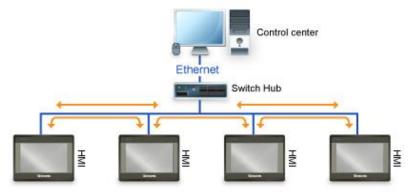
21.1.	Overview	. 21-2
21.2.	HMI to HMI Communication	. 21-2
21.3.	PC to HMI Communication	. 21-3
21.4.	Operate the PLC Connected with Other HMI	. 21-4



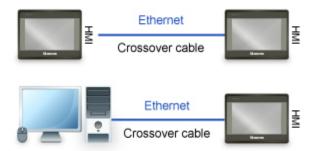
### 21.1. Overview

There are two ways of Ethernet communication:

Use RJ45 straight through cable and hub.



 Use RJ45 crossover cable and without hub, but this is limited to point-to-point connection (HMI to HMI or PC to HMI).



Through Ethernet network, the system provides the following methods for data transmission:

- HMI to HMI communication.
- PC to HMI communication.
- Operating the PLC connected to another HMI.

### 21.2. HMI to HMI Communication

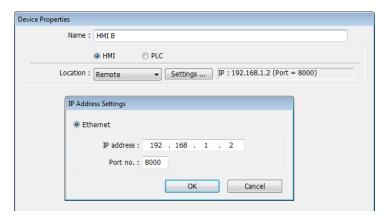
To exchange data between one HMI and another HMI, add a new remote HMI device in [System Parameter Settings]. If there are 2 HMIs (HMI A and HMI B), in order to use a Set Bit object on HMI A to control [LB-0] on HMI B, the setting of the project of HMI A is explained in the following part.



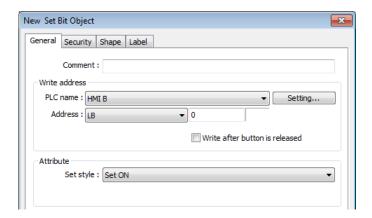
1. Set the IP address of the two HMIs, for example, HMI A: 192.168.1.1, HMI B: 192.168.1.2.



2. In [System Parameters] » [Device list], add a remote HMI B (IP: 192.168.1.2).



**3.** Create a Set Bit Object, select "HMI B" in [PLC name] to control the address of the remote HMI.





- One HMI can handle requests from a maximum of 64 HMIs simultaneously.
- One cMT / cMT X Series model can handle requests from a maximum of 32 HMIs simultaneously.

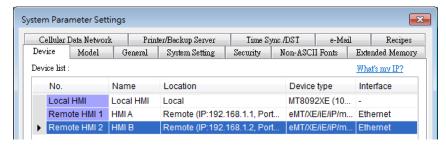
### 21.3. PC to HMI Communication

With On-line Simulation, PC can collect data from HMI through Ethernet network and save the data files to PC. To connect PC with two HMIs (HMI A and HMI B), the setting of the project on PC is explained in the following part.

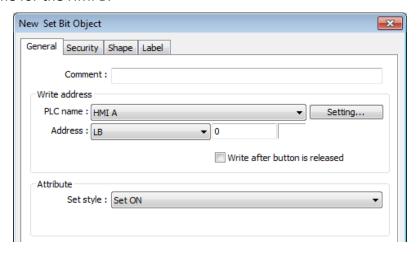


- 1. Set the IP address of the two HMIs, for example, HMI A: 192.168.1.1, HMI B: 192.168.1.2.
- 2. In [System Parameter Settings] » [Device list], add a remote HMI A (IP: 192.168.1.1) & HMI B (IP: 192.168.1.2).





3. Create a Set Bit Object, select "HMI A" in [PLC name] to control the address of the remote HMI A. Same for the HMI B.

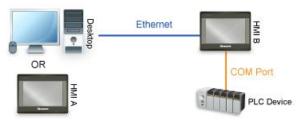




- A PC can control at most 64 HMIs simultaneously.
- As shown above, HMI can also control PC. PC can be seen as another HMI, that is, adding a remote HMI in the project of HMI A / HMI B, and the IP of the remote HMI is set to the IP of PC.

## 21.4. Operating the PLC Connected with Other HMI

Through Ethernet network, PC or HMI can operate the PLC that is connected to another HMI. If PLC is connected to COM 1of HMI B, when using PC or HMI A to read PLC data, the setting of the project of PC or HMI A is explained in the following part.

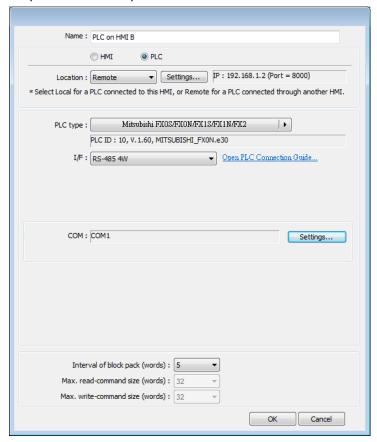


### 21.4.1. Settings of eMT / iE / XE / mTV / iP Series

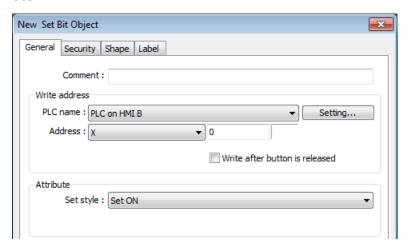
1. Set the IP address of HMI B, for example, 192.168.1.2.



2. In [System Parameter Settings] » [Device list], add a remote PLC, and set [Name] to "PLC on HMI B". Set correct parameters. Since this PLC is connected to remote HMI B, set the IP address to HMI B (IP: 192.168.1.2).



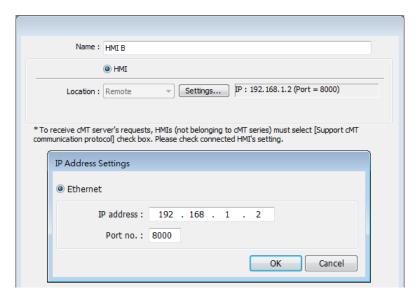
3. Create a Set Bit Object, select "PLC on HMI B" in [PLC name] to control the PLC connected with the remote HMI B.



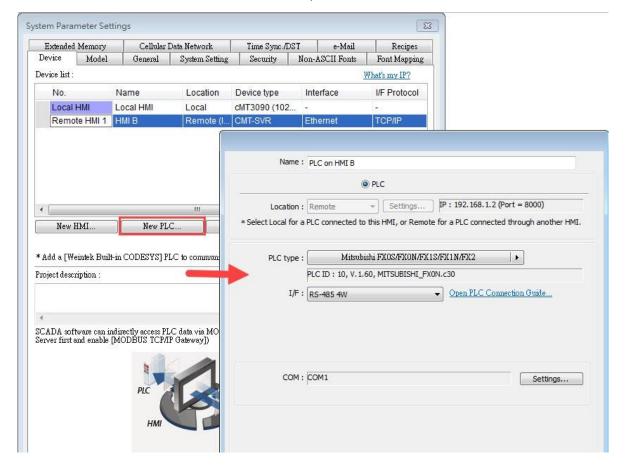
### 21.4.2. Settings of cMT / cMT X Series models

- 1. Set the IP address of HMI B, for example, 192.168.1.2.
- 2. In [System Parameters] » [Device list], click [New HMI]. Set the IP address to HMI B (IP: 192.168.1.2).



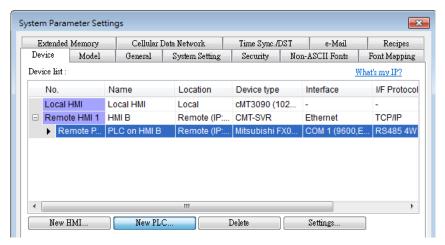


3. In the project of HMI B, go to [System Parameter Settings] » [Device list], click [New PLC], set [Name] to "PLC on HMI B". Set correct parameters.

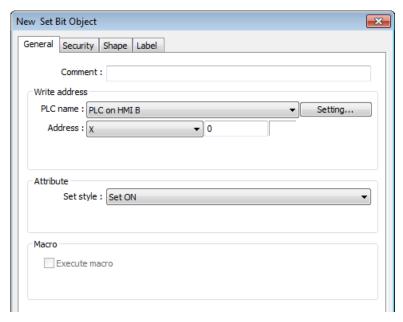




4. When finished, a remote PLC can be found under Remote HMI 1. Local HMI 1 stands for HMI A, Remote HMI 1 stands for HMI B, and Remote PLC 1 is connected with HMI B.



5. Create a Set Bit Object, select "PLC on HMI B" in [PLC name] to control the PLC connected with the remote HMI B.





■ When the remote HMI in a cMT/cMT X Series project is an eMT/iE/XE/mTV model, please select [Support iE/XE/eMT/mTV HMI communication protocol and EasyWatch] check box in the [Model] tab in [System Parameters]. Similarly, when the remote HMI in an eMT/iE/XE/mTV project is a cMT / cMT X Series model, please select [Support cMT communication protocol] to establish communication between cMT/cMT X and eMT/iE/XE/mTV models.



# 22. System Registers

This chapter introduces different types of registers.

22.	1.	Ove	rview	22-3
22.	2.	The	Address Ranges of Local HMI	22-4
	22.	2.1.	Bits	22-4
	22.	2.2.	Words	22-4
22.	3.	Syste	em Registers	22-4
	22.	3.1.	HMI Time	22-5
	22.	3.2.	HMI Operation	22-7
	22.	3.3.	Touch Position	22-8
	22.	3.4.	Local HMI Network Information	22-9
	22.	3.5.	Project File Information	22-11
	22.	3.6.	Storage Space Management	22-12
	22.	3.7.	Recipe and Extended Memory	22-13
	22.	3.8.	Data Sampling	22-16
	22.	3.9.	Event Log	22-18
	22.	3.10.	Station Number Variables	22-21
	22.	3.11.	Index Registers	22-22
	22.	3.12.	MODBUS Server Communication	22-24
	22.	3.13.	Communication Parameter Settings	22-25
	22.	3.14.	Communication Status and Control with Device (COM)	22-29
	22.	3.15.	Communication Status and Control with Device (Ethernet)	22-31
	22.	3.16.	Communication Status and Control with Device (USB)	22-41
	22.	3.17.	Communication Status and Control with Device (CAN Bus)	22-42
	22.	3.18.	Communication Status and Control with Remote HMI	22-43
	22.	3.19.	Communication Status and Control with Remote Device	22-58
	22.	3.20.	Local/Remote Operation Restrictions	22-60
	22.	3.21.	Communication Error Codes	22-61
	22.	3.22.	Driver ID	22-63
	22.	3.23.	DLT645 Controller	22-63
	22.	3.24.	[Device No Response] Window Control	22-63
	22.	3.25.	[Fast Selection] Window Control	22-64
	22.	3.26.	EasyAccess	22-64
	22.	3.27.	EasyAccess 2.0	22-64



22.3.28. Remote Print/Backup Server	22-65
22.3.29. Pass-Through Settings	22-66
22.3.30. VNC Control	22-68
22.3.31. Project Key and HMI Key	22-68
22.3.32. USB Security Key	22-69
22.3.33. User Name and Password	22-69
22.3.34. Macro	22-71
22.3.35. Input Object Function	22-73
22.3.36. Time Sync./Daylight Saving Time	22-73
22.3.37. Cellular Data Network	22-75
22.3.38. WiFi Setting	22-76
22.3.39. OPC UA Server	22-78
22.3.40. e-Mail	22-79
22.3.41. cMT Viewer and Diagnoser	22-81
22.3.42. CODESYS Information	22-83
22.3.43. Miscellaneous	22-8/



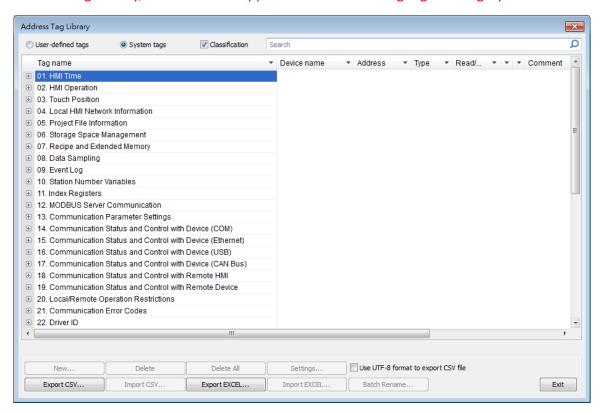
### 22.1. Overview

Some Word and Bit addresses are reserved in EasyBuilder Pro. These registers are reserved for different functions. This chapter introduces different types of registers.

The "C" letter in the register tables stands for "Control", which means that this register not only allows write operation, but also can be controlled by Macro or a remote HMI.

When using a cMT/cMT X Series model, the PLW and PLB registers can be selected. LW/LB are local registers whereas PLW/PLB are client registers. The client device can be: cMT-iV5, cMT-iV6, iOS, Android device...etc. When connecting a cMT/cMT X Series model with one or multiple client devices, the PLW/PLB registers can be set on the client devices.

Please note that the supported system tags may vary between models and can be checked in the Address Tag Library, where the unsupported ones will be highlighted in gray.





# 22.2. The Address Ranges of Local HMI

### 22.2.1. Bits

Register	<b>Device Type</b>	Range	Format
Local Bits (for users)	LB	0 ~ 8999	DDDDD
Local Bits (for system registers)	LB	9000 ~ 12895	DDDDD
Client Bits	PLB	0 ~ 12399	DDDDD
Local Word Bits	LW_Bit	0 ~ 1290015	DDDDDdd DDDDD: address dd: bit no. (00 ~ 15)
Client Word Bits	PLW_Bit	0 ~ 1230015	DDDDDdd DDDDD: address dd: bit no. (00 ~ 15)
Retentive Bit Index	RBI	0 ~ 65535f	DDDDDh DDDDD: address h: bit no. (0 ~ f) Use LW-9000 as Index Register, and correspond to RW_Bit
Retentive Word Bits	RW_Bit	0 ~ 524287f	DDDDDh DDDDD: address h: bit no. $(0 \sim f)$
Retentive A Word Bits	RW_A_Bit	0 ~ 65535f	DDDDDh DDDDD: address h: bit no. $(0 \sim f)$
Client Retentive Word Bits	PRW_Bit	0 ~ 52428715	DDDDDdd DDDDD: address dd: bit no. (00 ~ 15)

### **22.2.2.** Words

Register	<b>Device Type</b>	Range	Format	
Local Words	LW	0 ~ 8999	DDDDD	
(for users)				
Local Words	LW	9000 ~ 12900	DDDDD	
(for system				
registers)				
Client Words	PLW	0 ~ 12300	DDDDD	



Retentive	RW	0 ~ 524287	DDDDDD
Words			
Retentive A	RW_A	0 ~ 65535	DDDDD
Words			
Retentive	RWI	0 ~ 65535	DDDDD
Word			Use LW-9000 as Index
Index			Register, and
			correspond to RW
Client	PRW	0 ~ 524287	DDDDDD
Retentive			
Words			
Extended	EM0 ~ EM15	0 ~	DDDDDDDDD
Memory		1073741823	
Words			

# 22.3. System Registers

### 22.3.1. HMI Time

		Read(R)/	Read(R)/Write(W)/Control(C)			
Address	Description	Local HMI	Macro	Remote HMI	on cMT	
LB-11958	time setting error (when ON) *Note 3	R	R	R	Υ	
LW-9010	(16bit-BCD) : local second	R/W	R/C	R/C	Υ	
LW-9011	(16bit-BCD) : local minute	R/W	R/C	R/C	Υ	
LW-9012	(16bit-BCD) : local hour	R/W	R/C	R/C	Υ	
LW-9013	(16bit-BCD) : local day	R/W	R/C	R/C	Υ	
LW-9014	(16bit-BCD) : local month	R/W	R/C	R/C	Υ	
LW-9015	(16bit-BCD) : local year	R/W	R/C	R/C	Υ	
LW-9016	(16bit-BCD) : local week	R	R	R	Υ	
LW-9017	(16bit) : local second	R/W	R/C	R/C	Υ	
LW-9018	(16bit) : local minute	R/W	R/C	R/C	Υ	
LW-9019	(16bit) : local hour	R/W	R/C	R/C	Υ	
LW-9020	(16bit) : local day	R/W	R/C	R/C	Υ	
LW-9021	(16bit) : local month	R/W	R/C	R/C	Υ	
LW-9022	(16bit): local year *Note 1	R/W	R/C	R/C	Υ	
LW-9023	(16bit) : local week *Note 2	R	R	R	Υ	
LW-9030	(32bit) : system time (unit : 0.1 second)	R	R	R	Υ	



LW-9048	(16bit) : time (0 : AM, 1 : PM)	R/W	R/C	R/C	Υ
LW-9049	(16bit) : local hour (12-hour format)	R/W	R/C	R/C	Υ



- Value range: 2000 ~ 2035.
- 2. Value range: 0 ~ 6, stand for Sunday ~ Saturday.
- 3. When using LW-9010 to LW-9023 to update RTC time and an invalid value is set, the time before the update will be restored and the system register [LB-11958: time setting error] will be set ON. Updating time on PC during simulation by using LW-9010 to LW-9023 is ineffective.



# 22.3.2. HMI Operation

		Read(R)/Write(W)/Control(C)			Supported
Address	Description	Local HMI	Macro	Remote HMI	on cMT
LB-9018	disable(set ON)/enable (set OFF) mouse cursor	R/W	R/C	R/C	Υ
LB-9019	disable(set ON)/enable (set OFF) sound output	R/W	R/C	R/C	Y
LB-9020	show (set ON)/ hide (set OFF) system setting bar	R/W	R/C	R/C	Y
LB-9033	disable(when on)/enable (when off) HMI upload function *Note 1	R/W	R/C	R	Υ
LB-9040	backlight up (set ON) *Note 2	W	С	С	Υ
LB-9041	backlight down (set ON) *Note 2	W	С	С	Υ
LB-9047	reboot HMI (set ON when LB-9048 is on)	W	С	С	Υ
LB-9048	reboot-HMI protection	R/W	R/C	R/C	Υ
LB-9062	open hardware setting dialog (set ON)	W	С	С	Υ
LB-9063	disable(set ON)/enable(set OFF) popping information dialog while finding an USB disk	R/W	R/C	R/C	Y
LB-9064	enable USB barcode device (disable keyboard) (when ON) *Note 5	R/W	R/C	R	Υ
LB-11959	LED indicator control *Note 4	R/W	R/C	R/C	N
LB-12042	open/close [System information] dialog (set ON/set OFF)	R/W	R/C	R/C	N
LB-12051	buzzer control (active when ON)	R/W	R/C	R/C	Υ
LB-12360	CPU loading alarm (> 95%) *Note 6	R	R	R	Υ
LB-12364	show (set ON)/hide (set OFF) [Reset HMI to default] button in calibration mode	R/W	R/C	R/C	N
LB-12660	status of reset button (when the button is pressed, status is ON)	R	R	R	Y
LB-12665	open USB/SD card download/upload dialog	R/W	R/C	R/C	Υ
LB-12752	disable(set OFF)/enable(set ON) vibration. (Supported OS version : 20200618 or later) *Note 7	R/W	R/C	R/C	Υ
LW-9007	(16bit) : hardware index	R	R	R	N
LW-9008	(32bit-float) : battery voltage *Note 3	R	R	R	N
LW-9025	(16bit) : CPU loading (x 100%)	R	R	R	Υ
LW-9026	(16bit) : OS version (year)	R	R	R	Υ
LW-9027	(16bit) : OS version (month)	R	R	R	Y



LW-9028	(16bit) : OS version (day)	R	R	R	Υ
LW-9040	(16bit): backlight index *Note 2	R/W	R/C	R/C	Υ
LW-9051	(16bit) : audio volume (0 ~100)	R/W	R/C	R/C	Υ
LW-9054	(32bit) : HMI model ID	R	R	R	Υ
LW-9080	(16bit) : backlight saver time (unit : minute)	R/W	R/C	R/C	Υ
LW-9081	(16bit) : screen saver time (unit : minute)	R/W	R/C	R/C	Y
LW-9141	(16bit) : HMI station no.	R/W	R/C	R/C	Y
LW-9199	(16bit) : external keyboard layout : 0:	D ()A/	D/C	D/C	Υ
	(QWERTY), 1: (AZERTY), 2: (Cyrillic)	R/W	R/C	R/C	Y
LW-9350	(16bit) : pending command no. in local HMI	R	R	R	Υ
LW-10884	(16 words) : HMI name	R/W	R/C	R/C	Υ
LW-11155	(32bit) : the total size of HMI memory (K	R	R	R	Υ
	bytes)	ĸ	ĸ	ĸ	Ť
LW-11157	(32bit) : the free size of HMI memory (K bytes)	R	R	R	Υ
LW-11159	(16bit) : memory loading (x 100%)	R	R	R	Υ
LW-11382		R	R		Υ
	DIP 2, bit 2 : DIP 3)	ĸ	ĸ	R	Ť



- 1. After changing the settings, please reboot HMI for the updates to take effect.
- Use LW-9040 together with LB-9040 ~ LB-9041 to adjust the backlight brightness, range: 0 ~ 31.
- **3.** Only supported by eMT Series. When the battery voltage level, indicated by LW-9008, drops below 2.8V, battery replacement is recommended.
- **4.** When multiple mTV or cMT-SVR/cMT-HDM/cMT-FHD devices are used, this register can be triggered to make the LED indicator blink for identifying the device.
- 5. LB-9064: Enable USB barcode device (disable keyboard).
- Click the icon to download the demo project. Please confirm your internet connection.
- **6.** This register will be set to ON if CPU loading remains over 95% for 30 seconds.
- **7.** Only supported on cMT3162X.

### 22.3.3. Touch Position

		Read(R)/Write(W)/Control(C)			Supported
Address	Description	Local HMI	Macro	Remote HMI	on cMT
LW-9041	(16bit) : touch status word(bit 0 on = user is	R	R	R	V
	touching the screen)	IV.	IX.	K	'
LW-9042	(16bit) : touch x position	R	R	R	Υ



LW-9043	(16bit) : touch y position	R	R	R	Υ
LW-9044	(16bit) : leave x position	R	R	R	Υ
LW-9045	(16bit) : leave y position	R	R	R	Υ

Click the icon to download the demo project that explains how to how to trigger relevant registers to change page with finger slide. Please confirm your internet connection.

### 22.3.4. Local HMI Network Information

Address	Description	Read(R)/Write(W)/Control(C)			Supported
		Local HMI	Macro	Remote HMI	on cMT
LB-12041	refresh HMI ethernet information (DHCP, gateway, netmask, IP) (set ON)	R/W	R/C	R/C	Υ
LB-12094	update ethernet 1 setting (IP, netmask, gateway) (set ON)	R/W	R/C	R/C	Y
LB-12095	update ethernet 2 setting (IP, netmask) (set ON)	R/W	R/C	R/C	Υ
LW-9125	(16bit): HMI ethernet 1 gateway 0 (for HMI use only)	R/W	R/C	R/C	Y
LW-9126	(16bit): HMI ethernet 1 gateway 1 (for HMI use only)	R/W	R/C	R/C	Υ
LW-9127	(16bit): HMI ethernet 1 gateway 2 (for HMI use only)	R/W	R/C	R/C	Y
LW-9128	(16bit): HMI ethernet 1 gateway 3 (for HMI use only)	R/W	R/C	R/C	Y
LW-9129	(16bit): HMI ethernet 1 IP 0 (for HMI use only)	R/W	R/C	R/C	Υ
LW-9130	(16bit): HMI ethernet 1 IP 1 (for HMI use only)	R/W	R/C	R/C	Υ
LW-9131	(16bit): HMI ethernet 1 IP 2 (for HMI use only)	R/W	R/C	R/C	Υ
LW-9132	(16bit): HMI ethernet 1 IP 3 (for HMI use only)	R/W	R/C	R/C	Υ
LW-9133	(16bit) : ethernet port no.	R	R	R	Υ
LW-9135	(16bit): HMI media access control (MAC) address 0	R	R	R	Y
LW-9136	(16bit): HMI media access control (MAC) address 1	R	R	R	Y
LW-9137	(16bit): HMI media access control (MAC) address 2	R	R	R	Y
LW-9138	(16bit): HMI media access control (MAC) address 3	R	R	R	Υ



LW-9139	(16bit): HMI media access control (MAC) address 4	R	R	R	Y
LW-9140	(16bit): HMI media access control (MAC) address 5	R	R	R	Y
LW-10750	(16bit): HMI ethernet 1 Mask 0 (for HMI use only)	R/W	R/C	R/C	Y
LW-10751	(16bit): HMI ethernet 1 Mask 1 (for HMI use only)	R/W	R/C	R/C	Υ
LW-10752	(16bit): HMI ethernet 1 Mask 2 (for HMI use only)	R/W	R/C	R/C	Υ
LW-10753	(16bit): HMI ethernet 1 Mask 3 (for HMI use only)	R/W	R/C	R/C	Y
LW-10786	(16bit): HMI ethernet 2 IP 0 (for HMI use only)	R/W	R/C	R/C	Υ
LW-10787	(16bit): HMI ethernet 2 IP 1 (for HMI use only)	R/W	R/C	R/C	Y
LW-10788	(16bit): HMI ethernet 2 IP 2 (for HMI use only)	R/W	R/C	R/C	Y
LW-10789	(16bit): HMI ethernet 2 IP 3 (for HMI use only)	R/W	R/C	R/C	Υ
LW-10790	(16bit): HMI ethernet 2 netmask 0 (for HMI use only)	R/W	R/C	R/C	Y
LW-10791	(16bit): HMI ethernet 2 netmask 1 (for HMI use only)	R/W	R/C	R/C	Y
LW-10792	(16bit): HMI ethernet 2 netmask 2 (for HMI use only)	R/W	R/C	R/C	Y
LW-10793	(16bit): HMI ethernet 2 netmask 3 (for HMI use only)	R/W	R/C	R/C	Y
LW-10794	(16bit): HMI ethernet 2 gateway 0 (for HMI use only)	R/W	R/C	R/C	Y
LW-10795	(16bit): HMI ethernet 2 gateway 1 (for HMI use only)	R/W	R/C	R/C	Y
LW-10796	(16bit): HMI ethernet 2 gateway 2 (for HMI use only)	R/W	R/C	R/C	Y
LW-10797	(16bit): HMI ethernet 2 gateway 3 (for HMI use only)	R/W	R/C	R/C	Y
LW-10798	(16bit): ethernet 2 media access control (MAC) address 0	R	R	R	Y
LW-10799	(16bit): ethernet 2 media access control (MAC) address 1	R	R	R	Y
LW-10800	(16bit): ethernet 2 media access control	R	R	R	Y



	(MAC) address 2				
LW-10801	(16bit): ethernet 2 media access control	R	R	R	Υ
	(MAC) address 3	K	, n	, n	ī
LW-10802	(16bit): ethernet 2 media access control	R	R	R	Y
	(MAC) address 4	N.	, n	, n	Ţ
LW-10803	(16bit) : ethernet 2 media access control	R	R	R	Y
	(MAC) address 5	K	, n	, n	Ť
LW-10804	V-10804 (16bit): HMI ethernet 1 domain name system R/W	R/C	R/C	Y	
	(DNS) server IP0	N/ VV	NyC	R/C	ī
LW-10805	(16bit): HMI Ethernet 1 domain name system	R/W	R/C	R/C	Υ
	(DNS) server IP1	N/ VV	N/C	R/C	Ĭ
LW-10806	(16bit): HMI Ethernet 1 domain name system	R/W	R/C	R/C	Υ
	(DNS) server IP2	N/ VV	NyC	R/C	Y 
LW-10807	(16bit): HMI Ethernet 1 domain name system	R/W	R/C	R/C	Υ
	(DNS) server IP3	11, 44	1,7,0	NyC	'
LW-10808	(16bit): HMI ethernet 2 domain name system	R/W	R/C	R/C	Υ
	(DNS) server IP0	11,7 00	Tyc	11/ C	'
LW-10809	(16bit): HMI ethernet 2 domain name system	R/W	R/C	R/C	Y
	(DNS) server IP1	11, 11	11,10	11,70	'
LW-10810	(16bit): HMI ethernet 2 domain name system	R /\//	R/W R/C	R/C	Y
	(DNS) server IP2	10, 00	11,10	11,7 C	'
LW-10811	(16bit): HMI ethernet 2 domain name system	R/W	R/C	R/C	Υ
	(DNS) server IP3	1,7 **	11,10	1,7,0	•
LW-10812	(16bit) : obtain an IP address automatically	R/W	R/C	R/C	Y
	(DHCP => 0 : off, 1 : on)	1,7 **	11, 0	1,7,0	'
LW-10813	(16bit) : obtain an ethernet 2 IP address	R/W	R/C	R/C	Y
	automatically (DHCP => 0 : off, 1 : on)	11, 44	1,7,0	1.70	,
LW-10815	(16bit): link speed of ethernet 1 (0:failure, 10	R	R	R	Y
	(10M), 100 (100M), 1000 (1G))	,,	,,	,	'
LW-10816	(16bit): link speed of ethernet 2 (0:failure, 10	R	R R R	R	Y
	(10M), 100 (100M), 1000 (1G))	^	11	11	1

# 22.3.5. Project File Information

		Read(R)/Write(W)/Control(C)			Supported
Address	Description	Local HMI	Macro	Remote HMI	on cMT
LW-9100	(16bit) : project name (14 words)	R	R	R	Υ



LW-9116	(32bit) : project size in bytes	R	R	R	Υ
LW-9118	(32bit) : project size in K bytes	R	R	R	Υ
LW-9120	(32bit) : EasyBuilder Pro version	R	R	R	Υ
LW-9122	(16bit) : project compiled date [year]	R	R	R	Υ
LW-9123	(16bit) : project compiled date [month]	R	R	R	Υ
LW-9124	(16bit) : project compiled date [day]	R	R	R	Υ
LW-11440	(16bit): project compiled time [hour] (24-hour format)	R	R	R	Y
LW-11441	(16bit) : project compiled time [minute]	R	R	R	Υ
LW-11442	(16bit) : project compiled time [second]	R	R	R	Υ
LW-12752	(16 words) : project checksum	R	R	R	Υ
LW-12825	(32bit) : EasyBuilder Pro version (full)	R	R	R	Υ

## 22.3.6. Storage Space Management

System registers listed in this section are available exclusively for models equipped with an SD card slot or two USB ports only.

		Read(R)/	Write(W)/0	Control(C)	Supported
Address	Description	Local HMI	Macro	Remote HMI	on cMT
LB-9035	HMI free space insufficiency alarm (when ON)	R	R	R	Υ
LB-9036	SD card free space insufficiency alarm (when ON)	R	R	R	Υ
LB-9037	USB disk 1 free space insufficiency alarm (when ON)	R	R	R	Υ
LB-9038	USB disk 2 free space insufficiency alarm (when ON) *Note 1	R	R	R	Υ
LB-12048	USB disk 1 status (exists when ON)	R	R	R	Υ
LB-12049	USB disk 2 status (exists when ON) *Note 1	R	R	R	Υ
LB-12050	SD card status (exists when ON)	R	R	R	Υ
LW-9070	(16bit): free space insufficiency warning (Mega bytes)	R	R	R	N
LW-9071	(16bit): reserved free space size (Mega bytes)	R	R	R	N
LW-9072	(32bit): HMI current free space (K bytes)	R	R	R	Υ
LW-9074	(32bit): SD current free space (K bytes)	R	R	R	Υ
LW-9076	(32bit): USB disk 1 current free space (K bytes)	R	R	R	Υ
LW-9078	(32bit) : USB disk 2 current free space (K	R	R	R	N



	bytes) *Note 1				
LW-11458	(32bit): HMI total space for history data (K bytes) *Note 2	R	R	R	Υ
LW-11460	(32bit): HMI current free space for history data (K bytes) *Note 2	R	R	R	Υ
LW-12492	(4 words): last detected USB partition ID  *Note 3	R	R	R	Υ
LW-12496	(32-bit float): last detected USB partition size (GB) *Note 3	R	R	R	Υ
LW-12498	(4 words): set the partition ID to be used as USB1 *Note 3	R/W	R/C	R/C	Υ
LW-12502	(4 words): set the partition ID to be used as USB2 *Note 3	R/W	R/C	R/C	Υ
LW-12829	(32bit): HMI available space for history data (K bytes)	R	R	R	Υ



- 1. The registers relating to USB disk 2 are only supported on iP / iE and cMT X Series models.
- 2. Only available on cMT / cMT X Series model.
- 3. When a USB's partition ID is manually set in LW-12498/LW-12502, only this USB disk will be identified as USB1/USB2. To remove the partition ID association, please set an empty value in LW-12498/LW-12502. When the same partition ID is used as both USB1 ID (LW-12498) and USB2 ID (LW-12502), the USB disk associated with this USB ID will be identified as USB1.

Click the icon to download the demo project that explains how to use LW-9072 ~ LW-9076 with Backup Object. Please confirm your internet connection.

#### 22.3.7. Recipe and Extended Memory

		Read(R)/	Supported		
Address	Description	Local HMI	Macro	Remote HMI	on cMT
LB-9028	reset all recipe data (set ON)	W	С	С	Υ
LB-9029	save all recipe data to machine (set ON)	W	С	С	Υ
LB-9460	EM0's storage device (SD card) does not exist (when ON)	R	R	R	Υ
LB-9461	EM1's storage device (SD card) does not exist (when ON)	R	R	R	Υ



LB-9462	EM2's storage device (SD card) does not exist (when ON)	R	R	R	Y
LB-9463	EM3's storage device (SD card) does not exist (when ON)	R	R	R	Y
LB-9464	EM4's storage device (SD card) does not exist (when ON)	R	R	R	Y
LB-9465	EM5's storage device (SD card) does not exist (when ON)	R	R	R	Y
LB-9466	EM6's storage device (SD card) does not exist (when ON)	R	R	R	Υ
LB-9467	EM7's storage device (SD card) does not exist (when ON)	R	R	R	Y
LB-9468	EM8's storage device (SD card) does not exist (when ON)	R	R	R	Y
LB-9469	EM9's storage device (SD card) does not exist (when ON)	R	R	R	Y
LB-9470	EMO's storage device (USB disk) does not exist (when ON)	R	R	R	Υ
LB-9471	EM1's storage device (USB disk) does not exist (when ON)	R	R	R	Y
LB-9472	EM2's storage device (USB disk) does not exist (when ON)	R	R	R	Υ
LB-9473	EM3's storage device (USB disk) does not exist (when ON)	R	R	R	Y
LB-9474	EM4's storage device (USB disk) does not exist (when ON)	R	R	R	Y
LB-9475	EM5's storage device (USB disk) does not exist (when ON)	R	R	R	Υ
LB-9476	EM6's storage device (USB disk) does not exist (when ON)	R	R	R	Y
LB-9477	EM7's storage device (USB disk) does not exist (when ON)	R	R	R	Υ
LB-9478	EM8's storage device (USB disk) does not exist (when ON)	R	R	R	Υ
LB-9479	EM9's storage device (USB disk) does not exist (when ON)	R	R	R	Y
LB-9480	EM0's storage device (USB disk 2) does not	R	R	R	Υ



	exist (when ON)				
LB-9481	EM1's storage device (USB disk 2) does not				
	exist (when ON)	R	R	R	Y
LB-9482	EM2's storage device (USB disk 2) does not	D	D	D	Y
	exist (when ON)	R	R	R	ř
LB-9483	EM3's storage device (USB disk 2) does not	R	R	R	Y
	exist (when ON)	IX.	I.	IX.	,
LB-9484	EM4's storage device (USB disk 2) does not	R	R	R	Y
	exist (when ON)				
LB-9485	EM5's storage device (USB disk 2) does not	R	R	R	Y
	exist (when ON)				
LB-9486	EM6's storage device (USB disk 2) does not	R	R	R	Y
	exist (when ON)				
LB-9487	EM7's storage device (USB disk 2) does not	R	R	R	Y
	exist (when ON)				
LB-9488	EM8's storage device (USB disk 2) does not	R	R	R	Y
	exist (when ON)				
LB-9489	EM9's storage device (USB disk 2) does not	R	R	R	Υ
	exist (when ON)				
LB-12363	Prohibit recipe database update from remote	R/W	R/C	R/C	Y
LD 42004	HMI (set ON)				
LB-12801	EM10's storage device (SD card) does not	R	R	R	Y
LB-12802	exist (when ON)  EM11's storage device (SD card) does not				
LD-120U2	exist (when ON)	R	R	R	Y
LB-12803	EM12's storage device (SD card) does not				
LD 12003	exist (when ON)	R	R	R	Y
LB-12804	EM13's storage device (SD card) does not				
	exist (when ON)	R	R	R	Y
LB-12805	EM14's storage device (SD card) does not				
	exist (when ON)	R	R	R	Y
LB-12806	EM15's storage device (SD card) does not				V
	exist (when ON)	R	R	R	Y
LB-12807	EM10's storage device (USB disk) does not	D	D	D	V
	exist (when ON)	R	R	R	Y
LB-12808	EM11's storage device (USB disk) does not	R	R	R	Y
	exist (when ON)	11	1.	11	' 



LB-12809	EM12's storage device (USB disk) does not exist (when ON)	R	R	R	Υ
LB-12810	EM13's storage device (USB disk) does not exist (when ON)	R	R	R	Y
LB-12811	EM14's storage device (USB disk) does not exist (when ON)	R	R	R	Y
LB-12812	EM15's storage device (USB disk) does not exist (when ON)	R	R	R	Y
LB-12813	EM10's storage device (USB disk 2) does not exist (when ON)	R	R	R	Υ
LB-12814	EM11's storage device (USB disk 2) does not exist (when ON)	R	R	R	Υ
LB-12815	EM12's storage device (USB disk 2) does not exist (when ON)	R	R	R	Υ
LB-12816	EM13's storage device (USB disk 2) does not exist (when ON)	R	R	R	Υ
LB-12817	EM14's storage device (USB disk 2) does not exist (when ON)	R	R	R	Υ
LB-12818	EM15's storage device (USB disk 2) does not exist (when ON)	R	R	R	Y

#### 22.3.8. Data Sampling

System registers listed in this section are available exclusively for models equipped with an SD card slot or two USB ports only.

Using system registers to delete files, view or update Data Sampling related file information is not supported on cMT Series models. Files can be deleted using the control address designated in Data Sampling settings window, please see Chapter 8 in this manual for more information.

		Read(R)/Write(W)/Control(C)			Supported
Address	Description	Local HMI	Macro	Remote HMI	on cMT
LB-9025	delete the earliest data sampling file on HMI memory (set ON)	W	С	С	N
LB-9026	delete all data sampling files on HMI memory (set ON)	w	С	С	Υ
LB-9027	refresh data sampling information on HMI memory (set ON)	w	С	С	N
LB-9034	save event/data sampling to HMI, USB disk,	W	С	С	Υ



	SD card (set ON) *Note 1				
LB-11949	delete the earliest data sampling file on SD	W	С	С	N
	card (set ON)	VV	C	C	IN
LB-11950	delete all data sampling files on SD card (set	w	С	С	Y
	ON)	VV	C	C	ľ
LB-11951	refresh data sampling information on SD card	w	С	С	N
	(set ON)	VV	C	C	14
LB-11952	delete the earliest data sampling file on USB	w	С	С	N
	disk 1 (set ON)	VV	C	C	14
LB-11953	delete all data sampling files on USB disk 1	w	С	С	Y
	(set ON)	VV	C	C	ı
LB-11954	refresh data sampling information on USB disk	W	С	С	N
	1 (set ON)	VV	C	C	I V
LB-11955	delete the earliest data sampling file on USB	w	С	С	N
	disk 2 (set ON) *Note 3	VV	C	C	14
LB-11956	delete all data sampling files on USB disk 2	W	С	С	Υ
	(set ON) *Note 3	VV	C	C	'
LB-11957	refresh data sampling information on USB disk	W	С	С	N
	2 (set ON) *Note 3	VV	C	C	IN.
LW-9063	(16bit) : no. of data sampling files on HMI	R	R	R	N
	memory	IX.	I.	IX.	14
LW-9064	(32bit) : size of data sampling files on HMI	R	R	R	N
	memory (bytes)	IX.	I.	IX.	I V
LW-10489	(16bit) : no. of data sampling files on SD card	R	R	R	N
LW-10490	(32bit) : size of data sampling files on SD card	R	R	R	N
	(bytes)	IX.	I.	IX.	14
LW-10492	(16bit) : no. of data sampling files on USB disk	R	R	R	N
	1	IX.	IV.	IX.	IV
LW-10493	(32bit) : size of data sampling files on USB disk	R	R	R	N
	1 (bytes)	n	, n	n n	IN
LW-10495	(16bit): no. of data sampling files on USB disk	R	R	R	N
	2 *Note 3	κ	, r	r.	IN
LW-10496	(32bit) : size of data sampling files on USB disk	R	R	R	N
	2 (bytes) *Note 3	, n	, n	, n	IN



- 1. The shortest interval between two successful executions is 2 seconds.
- 2. The registers for deleting or updating data samplings do not work during simulation on



PC.

3. The registers relating to USB disk 2 are only supported on iP / iE Series models.

#### **22.3.9.** Event Log

System registers listed in this section are available exclusively for models equipped with an SD card slot or two USB ports only.

Using system registers to delete files, view or update Event Log related file information is not supported on cMT Series models. Files can be deleted using the control address designated in Event Log settings window, please see Chapter 7 in this manual for more information.

		Read(R)/	Write(W)/	Control(C)	Supported
Address	Description	Local HMI	Macro	Remote HMI	on cMT
LB-9021	reset current event log (OFF->ON)	W	С	С	N
LB-9022	delete the earliest event log file on HMI memory (set ON)	W	С	С	N
LB-9023	delete all event log files on HMI memory (set ON)	W	С	С	Y
LB-9024	refresh event log information on HMI memory (set ON)	W	С	С	N
LB-9034	save event/data sampling to HMI, USB disk, SD card (set ON) *Note 2	W	С	С	Υ
LB-9042	acknowledge all alarm events (set ON)	W	С	С	Y
LB-9043	unacknowledged events exist (when ON)	R	R	R	Υ
LB-11940	delete the earliest event log file on SD card (set ON)	W	С	С	N
LB-11941	delete all event log files on SD card (set ON)	W	С	С	Υ
LB-11942	refresh event log information on SD card (set ON)	W	С	С	N
LB-11943	delete the earliest event log file on USB disk  1 (set ON)	W	С	С	N
LB-11944	delete all event log files on USB disk 1 (set ON)	w	С	С	Υ
LB-11945	refresh event log information on USB disk 1 (set ON)	w	С	С	N
LB-11946	delete the earliest event log file on USB disk 2 (set ON) *Note 4	W	С	С	N
LB-11947	delete all event log files on USB disk 2 (set ON) *Note 4	W	С	С	Y



LB-11948	refresh event log information on USB disk 2 (set ON) *Note 4	W	С	С	N
LB-12024	disable alarm buzzer (set ON)	W	С	С	Υ
LB-12399	status is on when alarm exists in any category *Note 5	R	R	R	Υ
LB-12400	status is on when alarm exists in category 0 *Note 5	R	R	R	Υ
LB-12401	status is on when alarm exists in category 1 *Note 5	R	R	R	Υ
LB-12402	status is on when alarm exists in category 2 *Note 5	R	R	R	Υ
LB-12403	status is on when alarm exists in category 3 *Note 5	R	R	R	Υ
LB-12404	status is on when alarm exists in category 4 *Note 5	R	R	R	Υ
LB-12405	status is on when alarm exists in category 5 *Note 5	R	R	R	Υ
LB-12406	status is on when alarm exists in category 6 *Note 5	R	R	R	Υ
LB-12407	status is on when alarm exists in category 7 *Note 5	R	R	R	Υ
LB-12655	status is on when alarm exists in category 255 *Note 5	R	R	R	Υ
LW-9060	(16bit) : no. of event log files on HMI memory	R	R	R	N
LW-9061	(32bit) : size of event log files on HMI memory (bytes)	R	R	R	N
LW-9450	(16bit): time tag of event log – second *Note  1	R/W	R/C	R/C	Y
LW-9451	(16bit): time tag of event log – minute *Note  1	R/W	R/C	R/C	Y
LW-9452	(16bit): time tag of event log – hour *Note 1	R/W	R/C	R/C	Υ
LW-9453	(16bit): time tag of event log – day *Note 1	R/W	R/C	R/C	Y
LW-9454	(16bit): time tag of event log – month *Note  1	R/W	R/C	R/C	Υ
LW-9455	(16bit): time tag of event log – year *Note 1	R/W	R/C	R/C	Υ
LW-10480	(16bit) : no. of event log files on SD card	R	R	R	N



LW-10481	(32bit) : size of event log files on SD card				
	(bytes)	R	R	R	N
LW-10483	(16bit) : no. of event log files on USB disk 1	R	R	R	N
LW-10484	(32bit) : size of event log files on USB disk 1				
	(bytes)	R	R	R	N
LW-10486	(16bit) : no. of event log files on USB disk 2				
	*Note 4	R	R	R	N
LW-10487	(32bit) : size of event log files on USB disk 2	R	R	R	N
	(bytes) *Note 4	N.	N.	N.	IN
LW-11443	(16bit) : push notification alarm status (0 :	R	R	R	Υ
	none; 1 : green; 2 : yellow; 3 : red)	I.	K	IX.	'
LW-11499	total no. of alarms *Note 5	R	R	R	Υ
LW-11500	no. of alarms in category 0 *Note 5	R	R	R	Υ
LW-11501	no. of alarms in category 1 *Note 5	R	R	R	Υ
LW-11502	no. of alarms in category 2 *Note 5	R	R	R	Υ
LW-11503	no. of alarms in category 3 *Note 5	R	R	R	Υ
LW-11504	no. of alarms in category 4 *Note 5	R	R	R	Υ
LW-11505	no. of alarms in category 5 *Note 5	R	R	R	Υ
LW-11506	no. of alarms in category 6 *Note 5	R	R	R	Υ
LW-11507	no. of alarms in category 7 *Note 5	R	R	R	Υ
LW-11755	no. of alarms in category 255 *Note 5	R	R	R	Υ
LW-11763	(16bit) : total no. of low priority level alarms	D	D	D	Υ
	*Note 5	R	R	R	Y
LW-11764	(16bit) : total no. of normal priority level	R	R	R	Υ
	alarms *Note 5	N.	N.	I.	T
LW-11765	(16bit): total no. of high priority level alarms	R	R	R	Υ
	*Note 5	17	17	17	ı
LW-11766	(16bit): total no. of emergency priority level	R	R	R	Υ
	alarms *Note 5	,	,,	1,	'



- 1. If LW-9450 ~ LW-9455 are used to get Event Log time, please enable in [system parameters] » [General].
  - Click the icon to download the demo project that explains how to use the system registers LW-9450 to LW-9455 to be the time tag of event log. Please confirm your internet connection.
- 2. The shortest interval between two successful executions is 2 seconds.



3. The registers for deleting or updating event logs do not work during simulation on PC.

- 4. The registers relating to USB disk 2 are only supported on iP / iE Series models.
- 5. Supported only on cMT / cMT X Series.

#### 22.3.10. Station Number Variables

							Supported
Address	Description	Local HMI	Macro	Remote HMI	on cMT		
LW-10000	(16bit): var0 - station no variable (usage: var0#address)	R/W	R/C	R/C	Y		
LW-10001	(16bit): var1 - station no variable (usage: var1#address)	R/W	R/C	R/C	Y		
LW-10002	(16bit): var2 - station no variable (usage: var2#address)	R/W	R/C	R/C	Y		
LW-10003	(16bit): var3 - station no variable (usage: var3#address)	R/W	R/C	R/C	Y		
LW-10004	(16bit): var4 - station no variable (usage: var4#address)	R/W	R/C	R/C	Y		
LW-10005	(16bit): var5 - station no variable (usage: var5#address)	R/W	R/C	R/C	Y		
LW-10006	(16bit): var6 - station no variable (usage: var6#address)	R/W	R/C	R/C	Y		
LW-10007	(16bit): var7 - station no variable (usage: var7#address)	R/W	R/C	R/C	Y		
LW-10008	(16bit): var8 - station no variable (usage: var8#address)	R/W	R/C	R/C	Y		
LW-10009	(16bit): var9 - station no variable (usage: var9#address)	R/W	R/C	R/C	Υ		
LW-10010	(16bit): var10 - station no variable (usage: var10#address)	R/W	R/C	R/C	Y		
LW-10011	(16bit): var11 - station no variable (usage: var11#address)	R/W	R/C	R/C	Y		
LW-10012	(16bit): var12 - station no variable (usage: var12#address)	R/W	R/C	R/C	Y		
LW-10013	(16bit): var13 - station no variable (usage: var13#address)	R/W	R/C	R/C	Y		
LW-10014	(16bit): var14 - station no variable (usage: var14#address)	R/W	R/C	R/C	Y		



22-22 **System Registers** 

LW-10015	(16bit) : var15 - station no variable	(usage:	R/W	R/C	R/C	٧
	var15#address)		1,4,4	1,70	11,0	•



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### 22.3.11. Index Registers

		Read(R)/	Write(W)/	Control(C)	Supported
Address	Description	Local HMI	Macro	Remote HMI	on cMT
LW-9000	(16bit) : index register of RWI	R/W	R/C	R/C	Υ
LW-9200	(16bit) : address index 0	R/W	R/C	R/C	Υ
LW-9201	(16bit) : address index 1	R/W	R/C	R/C	Υ
LW-9202	(16bit) : address index 2	R/W	R/C	R/C	Υ
LW-9203	(16bit) : address index 3	R/W	R/C	R/C	Υ
LW-9204	(16bit) : address index 4	R/W	R/C	R/C	Υ
LW-9205	(16bit) : address index 5	R/W	R/C	R/C	Υ
LW-9206	(16bit) : address index 6	R/W	R/C	R/C	Υ
LW-9207	(16bit) : address index 7	R/W	R/C	R/C	Υ
LW-9208	(16bit) : address index 8	R/W	R/C	R/C	Υ
LW-9209	(16bit) : address index 9	R/W	R/C	R/C	Υ
LW-9210	(16bit) : address index 10	R/W	R/C	R/C	Υ
LW-9211	(16bit) : address index 11	R/W	R/C	R/C	Υ
LW-9212	(16bit) : address index 12	R/W	R/C	R/C	Υ
LW-9213	(16bit) : address index 13	R/W	R/C	R/C	Υ
LW-9214	(16bit) : address index 14	R/W	R/C	R/C	Υ
LW-9215	(16bit) : address index 15	R/W	R/C	R/C	Υ
LW-9230	(32bit) : address index 16	R/W	R/C	R/C	Υ
LW-9232	(32bit) : address index 17	R/W	R/C	R/C	Υ
LW-9234	(32bit) : address index 18	R/W	R/C	R/C	Υ
LW-9236	(32bit) : address index 19	R/W	R/C	R/C	Y
LW-9238	(32bit) : address index 20	R/W	R/C	R/C	Υ
LW-9240	(32bit) : address index 21	R/W	R/C	R/C	Υ
LW-9242	(32bit) : address index 22	R/W	R/C	R/C	Υ
LW-9244	(32bit) : address index 23	R/W	R/C	R/C	Υ
LW-9246	(32bit) : address index 24	R/W	R/C	R/C	Y
LW-9248	(32bit) : address index 25	R/W	R/C	R/C	Υ
LW-9250	(32bit) : address index 26	R/W	R/C	R/C	Y



LW-9252	(32bit): address index 27	D // /	5/6	- /-	
	(32bit) . dudiess illuex 27	R/W	R/C	R/C	Υ
LW-9254	(32bit) : address index 28	R/W	R/C	R/C	Υ
LW-9256	(32bit) : address index 29	R/W	R/C	R/C	Υ
LW-9258	(32bit): address index 30	R/W	R/C	R/C	Υ
LW-9260	(32bit): address index 31	R/W	R/C	R/C	Υ
PLW-9200	(16bit): private address index 0	R/W	N/A	N/A	Υ
PLW-9201	(16bit) : private address index 1	R/W	N/A	N/A	Υ
PLW-9202	(16bit): private address index 2	R/W	N/A	N/A	Υ
PLW-9203	(16bit): private address index 3	R/W	N/A	N/A	Υ
PLW-9204	(16bit): private address index 4	R/W	N/A	N/A	Υ
PLW-9205	(16bit): private address index 5	R/W	N/A	N/A	Υ
PLW-9206	(16bit): private address index 6	R/W	N/A	N/A	Υ
PLW-9207	(16bit): private address index 7	R/W	N/A	N/A	Υ
PLW-9208	(16bit): private address index 8	R/W	N/A	N/A	Υ
PLW-9209	(16bit) : private address index 9	R/W	N/A	N/A	Υ
PLW-9210	(16bit): private address index 10	R/W	N/A	N/A	Υ
PLW-9211	(16bit) : private address index 11	R/W	N/A	N/A	Υ
PLW-9212	(16bit) : private address index 12	R/W	N/A	N/A	Υ
PLW-9213	(16bit) : private address index 13	R/W	N/A	N/A	Υ
PLW-9214	(16bit) : private address index 14	R/W	N/A	N/A	Υ
PLW-9215	(16bit) : private address index 15	R/W	N/A	N/A	Υ
PLW-9230	(32bit) : private address index 16	R/W	N/A	N/A	Υ
PLW-9232	(32bit) : private address index 17	R/W	N/A	N/A	Υ
PLW-9234	(32bit) : private address index 18	R/W	N/A	N/A	Υ
PLW-9236	(32bit) : private address index 19	R/W	N/A	N/A	Υ
PLW-9238	(32bit): private address index 20	R/W	N/A	N/A	Υ
PLW-9240	(32bit): private address index 21	R/W	N/A	N/A	Υ
PLW-9242	(32bit): private address index 22	R/W	N/A	N/A	Υ
PLW-9244	(32bit): private address index 23	R/W	N/A	N/A	Υ
PLW-9246	(32bit): private address index 24	R/W	N/A	N/A	Υ
PLW-9248	(32bit): private address index 25	R/W	N/A	N/A	Υ
PLW-9250	(32bit) : private address index 26	R/W	N/A	N/A	Υ
PLW-9252	(32bit) : private address index 27	R/W	N/A	N/A	Υ
PLW-9254	(32bit) : private address index 28	R/W	N/A	N/A	Υ
PLW-9256	(32bit) : private address index 29	R/W	N/A	N/A	Υ
PLW-9258	(32bit) : private address index 30	R/W	N/A	N/A	Υ
		R/W	N/A	N/A	Υ



22-24 **System Registers** 



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#### 22.3.12. MODBUS Server Communication

		Read(R)/	Supported		
Address	Description	Local HMI	Macro	Remote HMI	on cMT
LB-9055	MODBUS server (COM 1) receives a request (when ON)	R	R	R	Υ
LB-9056	MODBUS server (COM 2) receives a request (when ON)	R	R	R	Υ
LB-9057	MODBUS server (COM 3) receives a request (when ON)	R	R	R	Y
LB-9058	MODBUS server (ethernet) receives a request (when ON)	R	R	R	Y
LB-12052	MODBUS server status (disabled when ON)	R/W	R/C	R/C	Υ
LW-9270	(16bit) : request's function code - MODBUS server (COM 1)	R	R	R	Y
LW-9271	(16bit): request's starting address - MODBUS server (COM 1)	R	R	R	Y
LW-9272	(16bit): request's quantity of registers - MODBUS server (COM 1)	R	R	R	Y
LW-9275	(16bit) : request's function code - MODBUS server (COM 2)	R	R	R	Y
LW-9276	(16bit): request's starting address - MODBUS server (COM 2)	R	R	R	Y
LW-9277	(16bit): request's quantity of registers - MODBUS server (COM 2)	R	R	R	Y
LW-9280	(16bit) : request's function code - MODBUS server (COM 3)	R	R	R	Y
LW-9281	(16bit): request's starting address - MODBUS server (COM 3)	R	R	R	Y
LW-9282	(16bit): request's quantity of registers - MODBUS server (COM 3)	R	R	R	Y
LW-9285	(16bit) : request's function code - MODBUS server (ethernet)	R	R	R	Y
LW-9286	(16bit): request's starting address - MODBUS server (ethernet)	R	R	R	Y



LW-9287	(16bit): request's quantity of registers -				
	MODBUS server (ethernet)	R	R	R	Y
LW-9288	(16bit) : last error code - MODBUS server (ethernet)	R	R	R	Υ
LW-9289	(16bit) : last error code - MODBUS server (COM 1)	R	R	R	Y
LW-9290	(16bit) : last error code - MODBUS server (COM 2)	R	R	R	Y
LW-9291	(16bit): last error code - MODBUS server (COM 3)	R	R	R	Y
LW-9541	(16bit): MODBUS/ASCII server station no. (COM 1)	R/W	R/C	R/C	Y
LW-9542	(16bit): MODBUS/ASCII server station no. (COM 2)	R/W	R/C	R/C	Y
LW-9543	(16bit): MODBUS/ASCII server station no. (COM 3)	R/W	R/C	R/C	Y
LW-9544	(16bit): MODBUS/ASCII server station no. (ethernet)	R/W	R/C	R/C	Y
LW-9570	(32bit) : received data count (bytes) (COM 1 MODBUS server)	R	R	R	Υ
LW-9572	(32bit) : received data count (bytes) (COM 2 MODBUS server)	R	R	R	Y
LW-9574	(32bit) : received data count (bytes) (COM 3 MODBUS server)	R	R	R	Y
LW-9576	(32bit) : received data count (bytes) (Ethernet MODBUS server)	R	R	R	Y

## 22.3.13. Communication Parameter Settings

				Read(R)/Write(W)/Control(C) Su	
Address	Description	Local HMI	Macro	Remote HMI	on cMT
LB-9030	activate COM 1 new communication settings	R/W	R/C	R/C	Υ
	(LW-9550~9554) (set ON)	.,,	.,, 0	., -	·
LB-9031	activate COM 2 new communication settings	R/W	R/C	R/C	Υ
	(LW-9555~9559) (set ON)	117 VV	NyC	II/C	'
LB-9032	activate COM 3 new communication settings	5.044	D/C	n/c	V
	(LW-9560~9564) (set ON)	R/W	R/C	R/C	Y



LB-9065	disable/enable COM 1 broadcast station no.	R/W	R/C	R/C	Υ
LB-9066	disable/enable COM 2 broadcast station no.	R/W	R/C	R/C	Υ
LB-9067	disable/enable COM 3 broadcast station no.	R/W	R/C	R/C	Υ
LW-9550	(16bit) : COM 1 mode (0:RS232,1:RS485				
	2W,2:RS485 4W) (use LB-9030 to activate all	R/W	R/C	R/C	Y
	communication settings)				
LW-9551	(16bit) : COM 1 baud rate				
	(7:1200,8:2400,0:4800,1:9600,10:14400,	R/W	R/C	R/C	Y
	2:19200,11:28800,3:38400,4:57600,) *Note	11,7 00	lyc	11,70	'
	1				
LW-9552	(16bit) : COM 1 databits (7 : 7 bits, 8 : 8 bits)	R/W	R/C	R/C	Y
LW-9553	(16bit): COM 1 parity (0:none, 1:even, 2:odd,	R/W	R/C	R/C	Y
	3:mark, 4:space)	11,7 VV	Tyc	NyC	'
LW-9554	(16bit): COM 1 stop bits (1:1 bit, 2:2 bits)	R/W	R/C	R/C	Y
LW-9555	(16bit) : COM 2 mode (0:RS232,1:RS485				
	2W,2:RS485 4W) (use LB-9031 to activate all	R/W	R/C	R/C	Y
	communication settings)				
LW-9556	(16bit): COM 2 baud rate	R/W			
	(7:1200,8:2400,0:4800,1:9600,10:14400,		/ R/C	R/C R/C	Y
	2:19200,11:28800,3:38400,4:57600,) *Note	IV/ VV	NyC		ı
	1				
LW-9557	(16bit): COM 2 databits (7:7 bits, 8:8 bits)	R/W	R/C	R/C	Y
LW-9558	(16bit): COM 2 parity (0:none, 1:even, 2:odd,	R/W	R/C	R/C	Υ
	3:mark, 4:space)	IV, VV	NyC	NyC	ı
LW-9559	(16bit): COM 2 stop bits (1:1 bit, 2:2 bits)	R/W	R/C	R/C	Y
LW-9560	(16bit) : COM 3 mode (0:RS232,1:RS485 2W)				
	(use LB-9032 to activate all communication	R/W	R/C	R/C	Y
	settings)				
LW-9561	(16bit) : COM 3 baud rate				
	(7:1200,8:2400,0:4800,1:9600,10:14400,	R/W	R/C	R/C	Y
	2:19200,11:28800,3:38400,4:57600,) *Note	ry vv	NyC	N/C	ľ
	1				
LW-9562	(16bit): COM 3 databits (7:7 bits, 8:8 bits)	R/W	R/C	R/C	Y
LW-9563	(16bit): COM 3 parity (0:none, 1:even, 2:odd,	R/W	D/C	p/c	Y
	3:mark, 4:space)	r/ vv	R/C	R/C	r 
LW-9564	(16bit): COM 3 stop bits (1:1 bit, 2:2 bits)	R/W	R/C	R/C	Y
LW-9565	(16bit) : COM 1 broadcast station no.	R/W	R/C	R/C	Y



			T	1	
LW-9566	(16bit): COM 2 broadcast station no.	R/W	R/C	R/C	Y
LW-9567	(16bit): COM 3 broadcast station no.	R/W	R/C	R/C	Y
LW-10500	(16bit): device 1 timeout (unit: 100ms, 0:	R/W	R/C	R/C	Υ
	50ms)	T() VV	11/10	NC	'
LW-10501	(16bit) : device 1 turn around delay (unit : ms)	R/W	R/C	R/C	Y
LW-10502	(16bit) : device 1 send ACK delay (unit : ms)	R/W	R/C	R/C	Y
LW-10503	(16bit) : device 1 parameter 1	R/W	R/C	R/C	Υ
LW-10504	(16bit) : device 1 parameter 2	R/W	R/C	R/C	Υ
LW-10505	(16bit) : device 2 timeout (unit : 100ms, 0 : 50ms)	R/W	R/C	R/C	Y
LW-10506	(16bit) : device 2 turn around delay (unit : ms)	R/W	R/C	R/C	Y
LW-10507	(16bit): device 2 send ACK delay (unit : ms)	R/W	R/C	R/C	Y
LW-10507	(16bit): device 2 parameter 1	R/W	R/C	R/C	Y
LW-10508	(16bit) : device 2 parameter 2	R/W	R/C	R/C	Y
LW-10510	· ·	ry vv	N/C	N/C	I
TAA-10210	(16bit): device 3 timeout (unit: 100ms, 0: 50ms)	R/W	R/C	R/C	Y
LW-10511	(16bit): device 3 turn around delay (unit: ms)	R/W	R/C	R/C	Y
LW-10512	(16bit): device 3 send ACK delay (unit: ms)	R/W	R/C	R/C	Υ
LW-10513	(16bit) : device 3 parameter 1	R/W	R/C	R/C	Υ
LW-10514	(16bit) : device 3 parameter 2	R/W	R/C	R/C	Y
LW-10515	(16bit) : device 4 timeout (unit : 100ms)	R/W	R/C	R/C	Υ
LW-10516	(16bit) : device 4 turn around delay (unit : ms)	R/W	R/C	R/C	Υ
LW-10517	(16bit): device 4 send ACK delay (unit: ms) (SIEMENS S7/400 Link type)	R/W	R/C	R/C	Y
LW-10518	(16bit): device 4 parameter 1 (SIEMENS S7/400 rack)	R/W	R/C	R/C	Y
LW-10519	(16bit): device 4 parameter 2 (SIEMENS S7/400 CPU slot)	R/W	R/C	R/C	Y
LW-10520	(16bit) : device 5 timeout (unit : 100ms)	R/W	R/C	R/C	Υ
LW-10521	(16bit) : device 5 turn around delay (unit : ms)	R/W	R/C	R/C	Y
LW-10522	(16bit) : device 5 send ACK delay (unit : ms)	p. 6.	- 1-	- 1-	
	(SIEMENS S7/400 Link type)	R/W	R/C	R/C	Y
LW-10523	(16bit) : device 5 parameter 1 (SIEMENS	5.4	2/5	2/2	.,
	S7/400 rack)	R/W	R/C	R/C	Y
LW-10524	(16bit) : device 5 parameter 2 (SIEMENS	<b>-</b> <i>t</i> ···	_ , -		
	S7/400 CPU slot)	R/W	R/C	R/C	Y
LW-10525	(16bit) : device 6 timeout (unit : 100ms)	R/W	R/C	R/C	Y



LW-10526       (16bit): device 6 turn around delay (unit: ms)       R/W       R/C       R/C       Y         LW-10527       (16bit): device 6 send ACK delay (unit: ms) (SIEMENS \$77400 Link type)       R/W       R/C       R/C       Y         LW-10528       (16bit): device 6 parameter 1 (SIEMENS \$77400 crck)       R/W       R/C       R/C       Y         LW-10529       (16bit): device 6 parameter 2 (SIEMENS \$77400 CPU slot)       R/W       R/C       R/C       Y         LW-10530       (16bit): device 7 timeout (unit: 100ms)       R/W       R/C       R/C       Y         LW-10531       (16bit): device 7 send ACK delay (unit: ms) (SIEMENS \$77400 Link type)       R/W       R/C       R/C       Y         LW-10532       (16bit): device 7 parameter 1 (SIEMENS \$77400 clnk type)       R/W       R/C       R/C       Y         LW-10533       (16bit): device 7 parameter 2 (SIEMENS \$77400 clnk type)       R/W       R/C       R/C       Y         LW-10534       (16bit): device 8 timeout (unit: 100ms)       R/W       R/C       R/C       Y         LW-10535       (16bit): device 8 turn around delay (unit: ms)       R/W       R/C       R/C       Y         LW-10537       (16bit): device 8 send ACK delay (unit: ms)       R/W       R/C       R/C       Y						
CSIEMENS 57/400 Link type    R/W   R/C   R/C   Y	LW-10526	(16bit): device 6 turn around delay (unit: ms)	R/W	R/C	R/C	Υ
S7/400 rack   R/W R/C R/C Y   Y	LW-10527		R/W	R/C	R/C	Υ
S7/400 CPU slot)   R/W   R/C   R/C   Y	LW-10528	· · ·	R/W	R/C	R/C	Υ
LW-10531       (16bit): device 7 turn around delay (unit: ms)       R/W       R/C       R/C       Y         LW-10532       (16bit): device 7 send ACK delay (unit: ms)       R/W       R/C       R/C       Y         LW-10533       (16bit): device 7 parameter 1 (SIEMENS S7/400 rack)       R/W       R/C       R/C       Y         LW-10534       (16bit): device 7 parameter 2 (SIEMENS S7/400 rack)       R/W       R/C       R/C       Y         LW-10534       (16bit): device 8 timeout (unit: 100ms)       R/W       R/C       R/C       Y         LW-10535       (16bit): device 8 turn around delay (unit: ms)       R/W       R/C       R/C       Y         LW-10536       (16bit): device 8 send ACK delay (unit: ms)       R/W       R/C       R/C       Y         LW-10537       (16bit): device 8 parameter 1 (SIEMENS S7/400 Link type)       R/W       R/C       R/C       Y         LW-10538       (16bit): device 8 parameter 1 (SIEMENS S7/400 rack)       R/W       R/C       R/C       Y         LW-10539       (16bit): device 8 parameter 2 (SIEMENS S7/400 crown by S7/400 CPU sloty)       R/W       R/C       R/C       Y         LW-10655       (16bit): device 32 turn around delay (unit: ms)       R/W       R/C       R/C       Y         LW-1065	LW-10529		R/W	R/C	R/C	Υ
LW-10532   (16bit) : device 7 send ACK delay (unit : ms)   R/W   R/C   R/C   Y	LW-10530	(16bit) : device 7 timeout (unit : 100ms)	R/W	R/C	R/C	Υ
(SIEMENS 57/400 Link type)  LW-10533 (16bit): device 7 parameter 1 (SIEMENS	LW-10531	(16bit) : device 7 turn around delay (unit : ms)	R/W	R/C	R/C	Υ
S7/400 rack    R/W   R/C   R/C   Y	LW-10532		R/W	R/C	R/C	Y
S7/400 CPU slot)   R/W   R/C   R/C   Y	LW-10533		R/W	R/C	R/C	Υ
LW-10536       (16bit): device 8 turn around delay (unit: ms)       R/W       R/C       R/C       Y         LW-10537       (16bit): device 8 send ACK delay (unit: ms)       R/W       R/C       R/C       Y         LW-10538       (16bit): device 8 parameter 1 (SIEMENS S7/400 rack)       R/W       R/C       R/C       Y         LW-10539       (16bit): device 8 parameter 2 (SIEMENS S7/400 CPU slot)       R/W       R/C       R/C       Y         LW-10655       (16bit): device 32 timeout (unit: 100ms)       R/W       R/C       R/C       Y         LW-10656       (16bit): device 32 turn around delay (unit: ms)       R/W       R/C       R/C       Y         LW-10657       (16bit): device 32 send ACK delay (unit: ms)       R/W       R/C       R/C       Y         LW-10658       (16bit): device 32 parameter 1       R/W       R/C       R/C       Y	LW-10534		R/W	R/C	R/C	Υ
LW-10537       (16bit): device 8 send ACK delay (unit: ms) (SIEMENS S7/400 Link type)       R/W       R/C       R/C       Y         LW-10538       (16bit): device 8 parameter 1 (SIEMENS S7/400 rack)       R/W       R/C       R/C       Y         LW-10539       (16bit): device 8 parameter 2 (SIEMENS S7/400 CPU slot)       R/W       R/C       R/C       Y         LW-10655       (16bit): device 32 timeout (unit: 100ms)       R/W       R/C       R/C       Y         LW-10656       (16bit): device 32 turn around delay (unit: ms)       R/W       R/C       R/C       Y         LW-10657       (16bit): device 32 send ACK delay (unit: ms)       R/W       R/C       R/C       Y         LW-10658       (16bit): device 32 parameter 1       R/W       R/C       R/C       Y	LW-10535	(16bit) : device 8 timeout (unit : 100ms)	R/W	R/C	R/C	Υ
Columbia Strict Stric	LW-10536	(16bit): device 8 turn around delay (unit: ms)	R/W	R/C	R/C	Υ
R/W   R/C   R/C   Y	LW-10537		R/W	R/C	R/C	Υ
R/W   R/C   R/C   Y	LW-10538		R/W	R/C	R/C	Υ
LW-10656       (16bit): device 32 turn around delay (unit: ms)       R/W       R/C       R/C       Y         LW-10657       (16bit): device 32 send ACK delay (unit: ms)       R/W       R/C       R/C       Y         LW-10658       (16bit): device 32 parameter 1       R/W       R/C       R/C       Y	LW-10539		R/W	R/C	R/C	Y
R/W   R/C   R/C   Y	LW-10655	(16bit) : device 32 timeout (unit : 100ms)	R/W	R/C	R/C	Υ
LW-10658 (16bit) : device 32 parameter 1 R/W R/C R/C Y	LW-10656		R/W	R/C	R/C	Υ
	LW-10657	(16bit): device 32 send ACK delay (unit: ms)	R/W	R/C	R/C	Υ
LW-10659 (16bit) : device 32 parameter 2 R/W R/C R/C Y	LW-10658	(16bit) : device 32 parameter 1	R/W	R/C	R/C	Υ
	LW-10659	(16bit) : device 32 parameter 2	R/W	R/C	R/C	Υ



1. The Baud Rates are: 0:4800, 1:9600, 2:19200, 3:38400, 4:57600, 5:115200, 6:187.5K, 7:1200, 8:2400, 10:14400, 11:28800, 12:76800



## 22.3.14. Communication Status and Control with Device (COM)

		Read(R)/	Supported		
Address	Description	Local HMI	Macro	Remote HMI	on cMT
LB-9150	auto. connection for device 1 (COM 1) (when ON)	R/W	R/C	R/C	Y
LB-9151	auto. connection for device 2 (COM 2) (when ON)	R/W	R/C	R/C	Y
LB-9152	auto. connection for device 3 (COM 3) (when ON)	R/W	R/C	R/C	Y
LB-9200	device 1 status (SN0, COM 1), set on to retry connection.	R/W	R/C	R/C	Y
LB-9201	device 1 status (SN1, COM 1), set on to retry connection	R/W	R/C	R/C	Y
LB-9202	device 1 status (SN2, COM 1), set on to retry connection	R/W	R/C	R/C	Y
LB-9203	device 1 status (SN3, COM 1), set on to retry connection	R/W	R/C	R/C	Y
LB-9204	device 1 status (SN4, COM 1), set on to retry connection	R/W	R/C	R/C	Y
LB-9205	device 1 status (SN5, COM 1), set on to retry connection	R/W	R/C	R/C	Y
LB-9206	device 1 status (SN6, COM 1), set on to retry connection	R/W	R/C	R/C	Y
LB-9207	device 1 status (SN7, COM 1), set on to retry connection	R/W	R/C	R/C	Y
LB-9455	device 1 status (SN255, COM 1), set on to retry connection	R/W	R/C	R/C	Y
LB-9500	device 2 status (SN0, COM 2), set on to retry connection.	R/W	R/C	R/C	Y
LB-9501	device 2 status (SN1, COM 2), set on to retry connection	R/W	R/C	R/C	Y
LB-9502	device 2 status (SN2, COM 2), set on to retry connection	R/W	R/C	R/C	Y
LB-9503	device 2 status (SN3, COM 2), set on to retry connection	R/W	R/C	R/C	Y
LB-9504	device 2 status (SN4, COM 2), set on to retry connection	R/W	R/C	R/C	Y



LB-9505	device 2 status (SN5, COM 2), set on to retry connection	R/W	R/C	R/C	Y
LB-9506	device 2 status (SN6, COM 2), set on to retry connection	R/W	R/C	R/C	Y
LB-9507	device 2 status (SN7, COM 2), set on to retry connection	R/W	R/C	R/C	Υ
LB-9755	device 2 status (SN255, COM 2), set on to retry connection	R/W	R/C	R/C	Υ
LB-9800	device 3 status (SN0, COM 3), set on to retry connection	R/W	R/C	R/C	Y
LB-9801	device 3 status (SN1, COM 3), set on to retry connection	R/W	R/C	R/C	Y
LB-9802	device 3 status (SN2, COM 3), set on to retry connection	R/W	R/C	R/C	Y
LB-9803	device 3 status (SN3, COM 3), set on to retry connection	R/W	R/C	R/C	Y
LB-9804	device 3 status (SN4, COM 3), set on to retry connection	R/W	R/C	R/C	Y
LB-9805	device 3 status (SN5, COM 3), set on to retry connection	R/W	R/C	R/C	Y
LB-9806	device 3 status (SN6, COM 3), set on to retry connection	R/W	R/C	R/C	Y
LB-9807	device 3 status (SN7, COM 3), set on to retry connection	R/W	R/C	R/C	Y
LB-10055	device 3 status (SN255, COM 3), set on to retry connection	R/W	R/C	R/C	Y
LB-12030	COM 1 status (OFF : normal, ON : open failed) *Note 1	R	R	R	Y
LB-12031	COM 2 status (OFF : normal, ON : open failed)	R	R	R	Y
LB-12032	COM 3 status (OFF : normal, ON : open failed)	R	R	R	Y
LB-12033	COM 4 status (OFF : normal, ON : open failed)	R	R	R	Y
LB-12034	COM 5 status (OFF : normal, ON : open failed)	R	R	R	Y
LB-12035	COM 6 status (OFF : normal, ON : open failed)	R	R	R	Y
LB-12036	COM 7 status (OFF : normal, ON : open failed)	R	R	R	Y
LB-12037	COM 8 status (OFF : normal, ON : open failed)	R	R	R	Y
LB-12038	COM 9 status (OFF : normal, ON : open failed)	R	R	R	Y
LW-9351	(16bit) : pending command no. in device 1	R	R	R	Υ



	(COM 1)				
LW-9352	(16bit) : pending command no. in device 2 (COM 2)	R	R	R	Υ
LW-9353	(16bit): pending command no. in device 3 (COM 3)	R	R	R	Υ



1. The ON state of COM is for checking if COM is occupied by other program during simulation on PC.

## 22.3.15. Communication Status and Control with Device (Ethernet)

		Read(R)/	Supported		
Address	Description	Local HMI	Macro	Remote HMI	on cMT
LB-9153	auto. connection for device 4 (ethernet) (when ON)	R/W	R/C	R/C	Υ
LB-9154	auto. connection for device 5 (ethernet) (when ON)	R/W	R/C	R/C	Υ
LB-9155	auto. connection for device 6 (ethernet) (when ON)	R/W	R/C	R/C	Y
LB-9156	auto. connection for device 7 (ethernet) (when ON)	R/W	R/C	R/C	Y
LB-9157	auto. connection for device 8 (ethernet) (when ON)	R/W	R/C	R/C	Y
LB-9158	auto. connection for device 9 (ethernet) (when ON)	R/W	R/C	R/C	Y
LB-9189	auto. connection for device 40 (ethernet) (when ON)	R/W	R/C	R/C	Υ
LB-10070	forced to reconnect device 4 (ethernet) when IP or system parameters changed on-line (set ON)	R/W	R/C	R/C	Υ
LB-10071	forced to reconnect device 5 (ethernet) when IP or system parameters changed on-line (set ON)	R/W	R/C	R/C	Y
LB-10072	forced to reconnect device 6 (ethernet) when IP or system parameters changed on-line (set ON)	R/W	R/C	R/C	Y
LB-10073	forced to reconnect device 7 (ethernet) when	R/W	R/C	R/C	Υ



	IP or system parameters changed on-line (set				
	ON)				
LB-10074	forced to reconnect device 8 (ethernet) when				
	IP or system parameters changed on-line (set	R/W	R/C	R/C	Y
	ON)				
LB-10075	forced to reconnect device 9 (ethernet) when				
	IP or system parameters changed on-line (set	R/W	R/C	R/C	Y
	ON)				
LB-10099	forced to reconnect device 33 (ethernet)				
	when IP or system parameters changed	R/W	R/C	R/C	Y
	on-line (set ON)				
LB-10100	device 4 status (ethernet), set on to retry	5.000	5/6	5.45	.,
	connection	R/W	R/C	R/C	Υ
LB-10101	device 4 status (SNO, ethernet), set on to	- 6	- 1-	- 1-	
	retry connection	R/W	R/C	R/C	Υ
LB-10102	device 4 status (SN1, ethernet), set on to	,			
	retry connection	R/W	R/C	R/C	Υ
LB-10103	device 4 status (SN2, ethernet), set on to				
	retry connection	R/W	R/C	R/C	Υ
LB-10104	device 4 status (SN3, ethernet), set on to				
	retry connection	R/W	R/C	R/C	Υ
LB-10105	device 4 status (SN4, ethernet), set on to				
	retry connection	R/W	R/C	R/C	Υ
LB-10106	device 4 status (SN5, ethernet), set on to				
	retry connection	R/W	R/C	R/C	Υ
LB-10107	device 4 status (SN6, ethernet), set on to				
	retry connection	R/W	R/C	R/C	Υ
LB-10108	device 4 status (SN7, ethernet), set on to				
	retry connection	R/W	R/C	R/C	Υ
LB-10356	device 4 status (SN255, ethernet), set on to				
	retry connection	R/W	R/C	R/C	Y
LB-10400	device 5 status (ethernet), set on to retry				
	connection	R/W	R/C	R/C	Υ
LB-10401	device 5 status (SNO, ethernet), set on to				
22 23 101	retry connection	R/W	R/C	R/C	Υ
LB-10402	device 5 status (SN1, ethernet), set on to				
20 10402	retry connection	R/W	R/C	R/C	Υ
	reay connection				



LB-10403	device 5 status (SN2, ethernet), set on to retry connection	R/W	R/C	R/C	Y
LB-10404	device 5 status (SN3, ethernet), set on to retry connection	R/W	R/C	R/C	Y
LB-10405	device 5 status (SN4, ethernet), set on to retry connection	R/W	R/C	R/C	Y
LB-10406	device 5 status (SN5, ethernet), set on to retry connection	R/W	R/C	R/C	Y
LB-10407	device 5 status (SN6, ethernet), set on to retry connection	R/W	R/C	R/C	Y
LB-10408	device 5 status (SN7, ethernet), set on to retry connection	R/W	R/C	R/C	Y
LB-10656	device 5 status (SN255, ethernet), set on to retry connection	R/W	R/C	R/C	Y
LB-10700	device 6 status (ethernet), set on to retry connection	R/W	R/C	R/C	Y
LB-10701	device 6 status (SNO, ethernet), set on to retry connection	R/W	R/C	R/C	Y
LB-10702	device 6 status (SN1, ethernet), set on to retry connection	R/W	R/C	R/C	Y
LB-10703	device 6 status (SN2, ethernet), set on to retry connection	R/W	R/C	R/C	Y
LB-10704	device 6 status (SN3, ethernet), set on to retry connection	R/W	R/C	R/C	Y
LB-10705	device 6 status (SN4, ethernet), set on to retry connection	R/W	R/C	R/C	Y
LB-10706	device 6 status (SN5, ethernet), set on to retry connection	R/W	R/C	R/C	Y
LB-10707	device 6 status (SN6, ethernet), set on to retry connection	R/W	R/C	R/C	Y
LB-10708	device 6 status (SN7, ethernet), set on to retry connection	R/W	R/C	R/C	Υ
LB-10956	device 6 status (SN255, ethernet), set on to retry connection	R/W	R/C	R/C	Y
LB-11000	device 7 status (ethernet), set on to retry connection	R/W	R/C	R/C	Y
LB-11001	device 7 status (SNO, ethernet), set on to	R/W	R/C	R/C	Υ



	retry connection				
LB-11002	device 7 status (SN1, ethernet), set on to retry connection	R/W	R/C	R/C	Y
LB-11003	device 7 status (SN2, ethernet), set on to retry connection	R/W	R/C	R/C	Y
LB-11004	device 7 status (SN3, ethernet), set on to retry connection	R/W	R/C	R/C	Y
LB-11005	device 7 status (SN4, ethernet), set on to retry connection	R/W	R/C	R/C	Y
LB-11006	device 7 status (SN5, ethernet), set on to retry connection	R/W	R/C	R/C	Y
LB-11007	device 7 status (SN6, ethernet), set on to retry connection	R/W	R/C	R/C	Y
LB-11008	device 7 status (SN7, ethernet), set on to retry connection	R/W	R/C	R/C	Υ
LB-11256	device 7 status (SN255, ethernet), set on to retry connection	R/W	R/C	R/C	Y
LB-11300	device 8 status (ethernet), set on to retry connection	R/W	R/C	R/C	Y
LB-11301	device 8 status (SNO, ethernet), set on to retry connection	R/W	R/C	R/C	Y
LB-11302	device 8 status (SN1, ethernet), set on to retry connection	R/W	R/C	R/C	Y
LB-11303	device 8 status (SN2, ethernet), set on to retry connection	R/W	R/C	R/C	Y
LB-11304	device 8 status (SN3, ethernet), set on to retry connection	R/W	R/C	R/C	Y
LB-11305	device 8 status (SN4, ethernet), set on to retry connection	R/W	R/C	R/C	Y
LB-11306	device 8 status (SN5, ethernet), set on to retry connection	R/W	R/C	R/C	Y
LB-11307	device 8 status (SN6, ethernet), set on to retry connection	R/W	R/C	R/C	Y
LB-11308	device 8 status (SN7, ethernet), set on to retry connection	R/W	R/C	R/C	Y
LB-11556	device 8 status (SN255, ethernet), set on to retry connection	R/W	R/C	R/C	Υ



LB-11600	device 9 status (ethernet), set on to retry connection	R/W	R/C	R/C	Y
LB-11601	device 9 status (SNO, ethernet), set on to retry connection	R/W	R/C	R/C	Y
LB-11602	device 9 status (SN1, ethernet), set on to retry connection	R/W	R/C	R/C	Y
LB-11603	device 9 status (SN2, ethernet), set on to retry connection	R/W	R/C	R/C	Y
LB-11604	device 9 status (SN3, ethernet), set on to retry connection	R/W	R/C	R/C	Y
LB-11605	device 9 status (SN4, ethernet), set on to retry connection	R/W	R/C	R/C	Y
LB-11606	device 9 status (SN5, ethernet), set on to retry connection	R/W	R/C	R/C	Y
LB-11607	device 9 status (SN6, ethernet), set on to retry connection	R/W	R/C	R/C	Y
LB-11608	device 9 status (SN7, ethernet), set on to retry connection	R/W	R/C	R/C	Y
LB-11856	device 9 status (SN255, ethernet), set on to retry connection	R/W	R/C	R/C	Y
LB-11900	device 10 status (ethernet), set on to retry connection	R/W	R/C	R/C	Y
LB-11901	device 11 status (ethernet), set on to retry connection	R/W	R/C	R/C	Y
LB-11902	device 12 status (ethernet), set on to retry connection	R/W	R/C	R/C	Y
LB-11903	device 13 status (ethernet), set on to retry connection	R/W	R/C	R/C	Y
LB-11904	device 14 status (ethernet), set on to retry connection	R/W	R/C	R/C	Y
LB-11905	device 15 status (ethernet), set on to retry connection	R/W	R/C	R/C	Y
LB-11906	device 16 status (ethernet), set on to retry connection	R/W	R/C	R/C	Y
LB-11939	device 49 status (ethernet), set on to retry connection	R/W	R/C	R/C	Υ
LB-12670	auto. connection for device 41 (ethernet)	R/W	R/C	R/C	Y



	(when ON)				
LB-12671	auto. connection for device 42 (ethernet) (when ON)	R/W	R/C	R/C	Y
LB-12672	auto. connection for device 43 (ethernet) (when ON)	R/W	R/C	R/C	Υ
LB-12673	auto. connection for device 44 (ethernet) (when ON)	R/W	R/C	R/C	Υ
LB-12693	auto. connection for device 64 (ethernet) (when ON)	R/W	R/C	R/C	Y
LB-12700	device 50 status (ethernet), set on to retry connection	R/W	R/C	R/C	Y
LB-12701	device 51 status (ethernet), set on to retry connection	R/W	R/C	R/C	Y
LB-12702	device 52 status (ethernet), set on to retry connection	R/W	R/C	R/C	Y
LB-12703	device 53 status (ethernet), set on to retry connection	R/W	R/C	R/C	Υ
LB-12714	device 64 status (ethernet), set on to retry connection	R/W	R/C	R/C	Υ
LB-12720	forced to reconnect device 34 (ethernet) when IP or system	R/W	R/C	R/C	Υ
LB-12721	forced to reconnect device 35 (ethernet) when IP or system	R/W	R/C	R/C	Υ
LB-12722	forced to reconnect device 36 (ethernet) when IP or system	R/W	R/C	R/C	Υ
LB-12723	forced to reconnect device 37 (ethernet) when IP or system	R/W	R/C	R/C	Y
LB-12750	forced to reconnect device 64 (ethernet) when IP or system	R/W	R/C	R/C	Υ
LW-9354	(16bit): pending command no. in device 4 (ethernet)	R	R	R	Y
LW-9355	(16bit): pending command no. in device 5 (ethernet)	R	R	R	Y
LW-9356	(16bit): pending command no. in device 6 (ethernet)	R	R	R	Y
LW-9357	(16bit): pending command no. in device 7 (ethernet)	R	R	R	Υ



LW-9389	(16bit): pending command no. in device 39 (ethernet)	R	R	R	Y
LW-9600	(16bit): device 4's IPO (IP address = IPO:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-9601	(16bit): device 4's IP1 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-9602	(16bit): device 4's IP2 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-9603	(16bit): device 4's IP3 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-9604	(16bit) : device 4's port no.	R/W	R/C	R/C	Υ
LW-9605	(16bit): device 5's IPO (IP address = IPO:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-9606	(16bit): device 5's IP1 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-9607	(16bit): device 5's IP2 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-9608	(16bit): device 5's IP3 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-9609	(16bit) : device 5's port no.	R/W	R/C	R/C	Υ
LW-9610	(16bit): device 6's IPO (IP address = IPO:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-9611	(16bit): device 6's IP1 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-9612	(16bit): device 6's IP2 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-9613	(16bit): device 6's IP3 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-9614	(16bit) : device 6's port no.	R/W	R/C	R/C	Y
LW-9615	(16bit): device 7's IPO (IP address = IPO:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-9616	(16bit): device 7's IP1 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-9617	(16bit): device 7's IP2 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-9618	(16bit): device 7's IP3 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Υ



LW-9619	(16bit) : device 7's port no.	R/W	R/C	R/C	Υ
LW-9620	(16bit): device 8's IPO (IP address = IPO:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-9621	(16bit): device 8's IP1 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-9622	(16bit): device 8's IP2 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-9623	(16bit): device 8's IP3 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-9624	(16bit) : device 8's port no.	R/W	R/C	R/C	Y
LW-9625	(16bit): device 9's IPO (IP address = IPO:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-9626	(16bit): device 9's IP1 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-9627	(16bit): device 9's IP2 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-9628	(16bit): device 9's IP3 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-9629	(16bit) : device 9's port no.	R/W	R/C	R/C	Y
LW-9765	(16bit): device 37's IPO (IP address = IPO:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-9766	(16bit): device 37's IP1 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-9767	(16bit): device 37's IP2 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-9768	(16bit): device 37's IP3 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-9769	(16bit) : device 37's port no.	R/W	R/C	R/C	Y
LW-11472	(16bit): device 4's ID0 (Beckhoff AMS NetId = ID0:ID1:ID2:ID3:ID4:ID5)	R/W	R/C	R/C	Y
LW-11473	(16bit): device 4's ID1 (Beckhoff AMS NetId = ID0:ID1:ID2:ID3:ID4:ID5)	R/W	R/C	R/C	Y
LW-11474	(16bit): device 4's ID2 (Beckhoff AMS NetId = ID0:ID1:ID2:ID3:ID4:ID5)	R/W	R/C	R/C	Y
LW-11475	(16bit): device 4's ID3 (Beckhoff AMS NetId = ID0:ID1:ID2:ID3:ID4:ID5)	R/W	R/C	R/C	Y
LW-11476	(16bit) : device 4's ID4 (Beckhoff AMS NetId =	R/W	R/C	R/C	Y



	ID0:ID1:ID2:ID3:ID4:ID5)				
LW-11477	(16bit) : device 4's ID5 (Beckhoff AMS NetId =	R/W	R/C	R/C	Υ
	ID0:ID1:ID2:ID3:ID4:ID5)	.,,	1,7,0	.,, c	•
LW-11478	(16bit) : device 5's ID0 (Beckhoff AMS NetId =	R/W	R/C	R/C	Y
	ID0:ID1:ID2:ID3:ID4:ID5)	IV) VV	NyC	NC	<b>'</b>
LW-11479	1479 (16bit) : device 5's ID1 (Beckhoff AMS NetId = R/W	R/C	R/C	Υ	
	ID0:ID1:ID2:ID3:ID4:ID5)	r/ vv	R/C	R/C	Ť
LW-11480	(16bit) : device 5's ID2 (Beckhoff AMS NetId =	R/W	R/C	R/C	Υ
	ID0:ID1:ID2:ID3:ID4:ID5)	ry vv	N/C	R/C	T
LW-11481	(16bit) : device 5's ID3 (Beckhoff AMS NetId =	D ///	D/C	D/C	V
	ID0:ID1:ID2:ID3:ID4:ID5)	R/W	R/C	R/C	Y
LW-11482	(16bit) : device 5's ID4 (Beckhoff AMS NetId =	D ///	D/C	D/C	V
	ID0:ID1:ID2:ID3:ID4:ID5)	R/W	R/C	R/C	Y
LW-11483	(16bit) : device 5's ID5 (Beckhoff AMS NetId =	D ()44	D/C	D/C	V
	ID0:ID1:ID2:ID3:ID4:ID5)	R/W	R/C	R/C	Y
LW-11484	(16bit) : device 6's ID0 (Beckhoff AMS NetId =	5 (14)	2/6	D/C	v
	ID0:ID1:ID2:ID3:ID4:ID5)	R/W	R/C	R/C	Y
LW-11485	(16bit) : device 6's ID1 (Beckhoff AMS NetId =	5 (14)	D/C	D/C	Υ
	ID0:ID1:ID2:ID3:ID4:ID5)	R/W	R/C	R/C	Y
LW-11486	(16bit) : device 6's ID2 (Beckhoff AMS NetId =	R/W	R/C	R/C	Υ
	ID0:ID1:ID2:ID3:ID4:ID5)	r/ vv	R/C	R/C	Ť
LW-11487	(16bit) : device 6's ID3 (Beckhoff AMS NetId =	R/W	R/C	R/C	Y
	ID0:ID1:ID2:ID3:ID4:ID5)	IV) VV	NyC	NyC	ľ
LW-11488	(16bit) : device 6's ID4 (Beckhoff AMS NetId =	R/W	R/C	R/C	Υ
	ID0:ID1:ID2:ID3:ID4:ID5)	IV) VV	NyC	NyC	ľ
LW-11489	(16bit) : device 6's ID5 (Beckhoff AMS NetId =	R/W	R/C	R/C	Υ
	ID0:ID1:ID2:ID3:ID4:ID5)	ry vv	N/C	R/C	T
LW-11490	(16bit) : device 7's ID0 (Beckhoff AMS NetId =	R/W	R/C	R/C	Y
	ID0:ID1:ID2:ID3:ID4:ID5)	ry vv	N/C	R/C	T
LW-11491	(16bit) : device 7's ID1 (Beckhoff AMS NetId =	R/W	R/C	R/C	Υ
	ID0:ID1:ID2:ID3:ID4:ID5)	r/ vv	R/C	R/C	Ť
LW-11492	(16bit) : device 7's ID2 (Beckhoff AMS NetId =	R/W	R/C	R/C	Υ
	ID0:ID1:ID2:ID3:ID4:ID5)	rt/ VV	N/C	N/C	Ĭ
LW-11493	(16bit) : device 7's ID3 (Beckhoff AMS NetId =	R/W	R/C	R/C	Υ
	ID0:ID1:ID2:ID3:ID4:ID5)	n/ vv	n/C	n/C	Ť
LW-11494	(16bit) : device 7's ID4 (Beckhoff AMS NetId =	R/W	R/C	R/C	Υ
	ID0:ID1:ID2:ID3:ID4:ID5)	rs/ VV	N/C	N/C	Ţ



LW-11495	(16bit): device 7's ID5 (Beckhoff AMS NetId = ID0:ID1:ID2:ID3:ID4:ID5)	R/W	R/C	R/C	Υ
LW-12110	(16bit): device 38's IPO (IP address = IPO:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-12111	(16bit): device 38's IP1 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-12112	(16bit) : device 38's IP2 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-12113	(16bit): device 38's IP3 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-12114	(16bit) : device 38's port no.	R/W	R/C	R/C	Υ
LW-12115	(16bit) : device 39's IPO (IP address = IPO:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-12116	(16bit): device 39's IP1 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-12117	(16bit) : device 39's IP2 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-12118	(16bit) : device 39's IP3 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-12119	(16bit) : device 39's port no.	R/W	R/C	R/C	Υ
LW-12120	(16bit): device 40's IPO (IP address = IPO:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-12121	(16bit): device 40's IP1 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-12122	(16bit): device 40's IP2 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-12123	(16bit): device 40's IP3 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-12124	(16bit) : device 40's port no.	R/W	R/C	R/C	Υ
LW-12125	(16bit): device 41's IPO (IP address = IPO:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-12126	(16bit): device 41's IP1 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-12127	(16bit) : device 41's IP2 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-12128	(16bit) : device 41's IP3 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Υ



LW-12129	(16bit) : device 41's port no.	R/W	R/C	R/C	Υ
LW-12240	(16bit): device 64's IPO (IP address = IPO:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-12241	(16bit): device 64's IP1 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-12242	(16bit): device 64's IP2 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-12243	(16bit): device 64's IP3 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-12244	(16bit) : device 64's port no.	R/W	R/C	R/C	Υ

Click the icon to download the demo project. Please confirm your internet connection before downloading the demo project.

## 22.3.16. Communication Status and Control with Device (USB)

		Read(R)/Write(W)/Control(C)		Supported	
Address	Description	Local HMI	Macro	Remote HMI	on cMT
LB-9190	auto. connection for device (USB) (when ON)	R/W	R/C	R/C	Υ
LB-9191	device status (USB), set on to retry connection	R/W	R/C	R/C	Υ
LW-9390	(16bit): pending command no. in device (USB)	R	R	R	Υ



## 22.3.17. Communication Status and Control with Device (CAN Bus)

		Read(R)/Write(W)/Control(C)			Supported
Address	Description	Local HMI	Macro	Remote HMI	on cMT
LB-12080	auto. connection for device (CAN Bus) (when ON)	R/W	R/C	R/C	Y
LB-12081	device status (CAN Bus) set on to retry connection	R/W	R/C	R/C	Υ
LB-12100	pause CAN Bus device 1 communication (when ON)	R/W	R/C	R/C	Y
LB-12101	pause CAN Bus device 2 communication (when ON)	R/W	R/C	R/C	Y
LB-12102	pause CAN Bus device 3 communication (when ON)	R/W	R/C	R/C	Υ
LB-12103	pause CAN Bus device 4 communication (when ON)	R/W	R/C	R/C	Υ
LB-12104	pause CAN Bus device 5 communication (when ON)	R/W	R/C	R/C	Υ
LB-12105	pause CAN Bus device 6 communication (when ON)	R/W	R/C	R/C	Y
LB-12106	pause CAN Bus device 7 communication (when ON)	R/W	R/C	R/C	Y
LB-12107	pause CAN Bus device 8 communication (when ON)	R/W	R/C	R/C	Y
LB-12108	pause CAN Bus device 9 communication (when ON)	R/W	R/C	R/C	Y
LB-12109	pause CAN Bus device 10 communication (when ON)	R/W	R/C	R/C	Υ
LB-12354	pause CAN Bus device 255 communication (when ON)	R/W	R/C	R/C	Y
LW-9392	(16bit): pending command no. in device (CAN Bus)	R	R	R	Υ



### 22.3.18. Communication Status and Control with Remote HMI

		Read(R)/	/Write(W)/	Supported	
Address	Description	Local HMI	Macro	Remote HMI	on cMT
LB-9068	auto. connection for remote HMI 1 (when ON)	R/W	R/C	R/C	Y
LB-9069	auto. connection for remote HMI 2 (when ON)	R/W	R/C	R/C	Υ
LB-9070	auto. connection for remote HMI 3 (when ON)	R/W	R/C	R/C	Y
LB-9071	auto. connection for remote HMI 4 (when ON)	R/W	R/C	R/C	Y
LB-9072	auto. connection for remote HMI 5 (when ON)	R/W	R/C	R/C	Y
LB-9073	auto. connection for remote HMI 6 (when ON)	R/W	R/C	R/C	Υ
LB-9074	auto. connection for remote HMI 7 (when ON)	R/W	R/C	R/C	Y
LB-9075	auto. connection for remote HMI 8 (when ON)	R/W	R/C	R/C	Y
LB-9099	auto. connection for remote HMI 32 (when ON)	R/W	R/C	R/C	Y
LB-9100	remote HMI 1 status (set on to retry connection)	R/W	R/C	R/C	Y
LB-9101	remote HMI 2 status (set on to retry connection)	R/W	R/C	R/C	Y
LB-9102	remote HMI 3 status (set on to retry connection)	R/W	R/C	R/C	Y
LB-9103	remote HMI 4 status (set on to retry connection)	R/W	R/C	R/C	Y
LB-9104	remote HMI 5 status (set on to retry connection)	R/W	R/C	R/C	Y
LB-9105	remote HMI 6 status (set on to retry connection)	R/W	R/C	R/C	Υ
LB-9106	remote HMI 7 status (set on to retry connection)	R/W	R/C	R/C	Y
LB-9107	remote HMI 8 status (set on to retry connection)	R/W	R/C	R/C	Y



LB-9148	remote HMI 49 status (set on to retry connection)	R/W	R/C	R/C	N/A
LB-9149	forced to reconnect remote HMI when IP changed on-line (set ON)	R/W	R/C	R/C	Y
LB-12754	auto. connection for remote HMI 33 (when ON)	R/W	R/C	R/C	Y
LB-12755	auto. connection for remote HMI 34 (when ON)	R/W	R/C	R/C	Y
LB-12756	auto. connection for remote HMI 35 (when ON)	R/W	R/C	R/C	Y
LB-12757	auto. connection for remote HMI 36 (when ON)	R/W	R/C	R/C	Y
LB-12758	auto. connection for remote HMI 37 (when ON)	R/W	R/C	R/C	Y
LB-12759	auto. connection for remote HMI 38 (when ON)	R/W	R/C	R/C	Y
LB-12760	auto. connection for remote HMI 39 (when ON)	R/W	R/C	R/C	Y
LB-12761	auto. connection for remote HMI 40 (when ON)	R/W	R/C	R/C	Y
LB-12762	auto. connection for remote HMI 41 (when ON)	R/W	R/C	R/C	Y
LB-12763	auto. connection for remote HMI 42 (when ON	R/W	R/C	R/C	Y
LB-12764	auto. connection for remote HMI 43 (when ON)	R/W	R/C	R/C	Υ
LB-12765	auto. connection for remote HMI 44 (when ON)	R/W	R/C	R/C	Y
LB-12766	auto. connection for remote HMI 45 (when ON)	R/W	R/C	R/C	Y
LB-12767	auto. connection for remote HMI 46 (when ON)	R/W	R/C	R/C	Y
LB-12768	auto. connection for remote HMI 47 (when ON)	R/W	R/C	R/C	Y
LB-12769	auto. connection for remote HMI 48 (when ON)	R/W	R/C	R/C	Υ
LB-12770	auto. connection for remote HMI 49 (when	R/W	R/C	R/C	Υ



	ON)				
LB-12771	auto. connection for remote HMI 50 (when ON)	R/W	R/C	R/C	Y
LB-12772	auto. connection for remote HMI 51 (when ON)	R/W	R/C	R/C	Y
LB-12773	auto. connection for remote HMI 52 (when ON)	R/W	R/C	R/C	Y
LB-12774	auto. connection for remote HMI 53 (when ON)	R/W	R/C	R/C	Y
LB-12775	auto. connection for remote HMI 54 (when ON)	R/W	R/C	R/C	Y
LB-12776	auto. connection for remote HMI 55 (when ON)	R/W	R/C	R/C	Y
LB-12777	auto. connection for remote HMI 56 (when ON)	R/W	R/C	R/C	Y
LB-12778	auto. connection for remote HMI 57 (when ON)	R/W	R/C	R/C	Υ
LB-12779	auto. connection for remote HMI 58 (when ON)	R/W	R/C	R/C	Υ
LB-12780	auto. connection for remote HMI 59 (when ON)	R/W	R/C	R/C	Y
LB-12781	auto. connection for remote HMI 60 (when ON)	R/W	R/C	R/C	Y
LB-12782	auto. connection for remote HMI 61 (when ON)	R/W	R/C	R/C	Y
LB-12783	auto. connection for remote HMI 62 (when ON)	R/W	R/C	R/C	Y
LB-12784	auto. connection for remote HMI 63 (when ON)	R/W	R/C	R/C	Υ
LB-12785	auto. connection for remote HMI 64 (when ON)	R/W	R/C	R/C	Y
LB-12786	remote HMI 50 status (set on to retry connection)	R/W	R/C	R/C	Y
LB-12787	remote HMI 51 status (set on to retry connection)	R/W	R/C	R/C	Y
LB-12788	remote HMI 52 status (set on to retry connection)	R/W	R/C	R/C	Y



LB-12789	remote HMI 53 status (set on to retry				
LB-12765	connection)	R/W	R/C	R/C	Y
LB-12790	remote HMI 54 status (set on to retry	5.44	D./C	2/0	.,
	connection)	R/W	R/C	R/C	Y
LB-12791	remote HMI 55 status (set on to retry	R/W	R/C	R/C	Y
	connection)	N/ VV	N/C	N/C	ı
LB-12792	remote HMI 56 status (set on to retry	R/W	R/C	R/C	Y
	connection)	1,7 00	1,7 C	11,0	'
LB-12793	remote HMI 57 status (set on to retry	R/W	R/C	R/C	Y
	connection)	.,	- 7 -	- 4 -	
LB-12794	12794 remote HMI 58 status (set on to retry R/W	R/C	R/C	Y	
	connection)	·	·	·	
LB-12795	remote HMI 59 status (set on to retry	R/W	R/C	R/C	Y
	connection)				
LB-12796	remote HMI 60 status (set on to retry	R/W	R/C	R/C	Y
	connection)				
LB-12797	remote HMI 61 status (set on to retry	R/W	R/C	R/C	Y
LD 42700	connection)				
LB-12798	remote HMI 62 status (set on to retry	R/W	R/C	R/C	Y
LD 42700	connection)				
LB-12799	remote HMI 63 status (set on to retry connection)	R/W	R/C	R/C	Y
LB-12800	remote HMI 64 status (set on to retry				
LB-12800	connection)	R/W	R/C	R/C	Y
LW-9800	(16bit) : remote HMI 1's IPO (IP address =				
217 3000	IPO:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-9801	(16bit) : remote HMI 1's IP1 (IP address =				
	IPO:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-9802	(16bit) : remote HMI 1's IP2 (IP address =				
	IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-9803	(16bit) : remote HMI 1's IP3 (IP address =		_ ,-		
	IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-9804	(16bit) : remote HMI 1's port no.	R/W	R/C	R/C	Y
LW-9805	(16bit) : remote HMI 2's IPO (IP address =	D /\A/	D/C	D/C	V
	IPO:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-9806	(16bit) : remote HMI 2's IP1 (IP address =	R/W	R/C	R/C	Y
	IP0:IP1:IP2:IP3)	11/ VV	N/C	N/C	ľ



	I				
LW-9807	(16bit): remote HMI 2's IP2 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-9808	(16bit): remote HMI 2's IP3 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-9809	(16bit) : remote HMI 2's port no.	R/W	R/C	R/C	Y
LW-9810	(16bit): remote HMI 3's IPO (IP address = IPO:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-9811	(16bit): remote HMI 3's IP1 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-9812	(16bit): remote HMI 3's IP2 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-9813	(16bit): remote HMI 3's IP3 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-9814	(16bit) : remote HMI 3's port no.	R/W	R/C	R/C	Y
LW-9815	(16bit): remote HMI 4's IPO (IP address = IPO:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-9816	(16bit): remote HMI 4's IP1 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-9817	(16bit): remote HMI 4's IP2 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-9818	(16bit): remote HMI 4's IP3 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-9819	(16bit) : remote HMI 4's port no.	R/W	R/C	R/C	Υ
LW-9820	(16bit): remote HMI 5's IPO (IP address = IPO:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-9821	(16bit): remote HMI 5's IP1 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-9822	(16bit): remote HMI 5's IP2 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-9823	(16bit): remote HMI 5's IP3 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-9824	(16bit) : remote HMI 5's port no.	R/W	R/C	R/C	Y
LW-9825	(16bit): remote HMI 6's IPO (IP address = IPO:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-9826	(16bit): remote HMI 6's IP1 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-9827	(16bit) : remote HMI 6's IP2 (IP address =	R/W	R/C	R/C	Y



	T			I	
	IP0:IP1:IP2:IP3)				
LW-9828	(16bit): remote HMI 6's IP3 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-9829	(16bit) : remote HMI 6's port no.	R/W	R/C	R/C	Υ
LW-9830	(16bit): remote HMI 7's IPO (IP address = IPO:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-9831	(16bit): remote HMI 7's IP1 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-9832	(16bit): remote HMI 7's IP2 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-9833	(16bit): remote HMI 7's IP3 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-9834	(16bit) : remote HMI 7's port no.	R/W	R/C	R/C	Υ
LW-9835	(16bit): remote HMI 8's IPO (IP address = IPO:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-9836	(16bit): remote HMI 8's IP1 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-9837	(16bit): remote HMI 8's IP2 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-9838	(16bit): remote HMI 8's IP3 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-9839	(16bit) : remote HMI 8's port no.	R/W	R/C	R/C	Υ
LW-9895	(16bit): remote HMI 20's IPO (IP address = IPO:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-9896	(16bit): remote HMI 20's IP1 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-9897	(16bit): remote HMI 20's IP2 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-9898	(16bit): remote HMI 20's IP3 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-9899	(16bit) : remote HMI 20's port no.	R/W	R/C	R/C	Υ
LW-9905	(16bit): remote HMI 21's IPO (IP address = IPO:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-9906	(16bit): remote HMI 21's IP1 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-9907	(16bit): remote HMI 21's IP2 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Υ



LW-9908	(16bit): remote HMI 21's IP3 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-9909	(16bit) : remote HMI 21's port no.	R/W	R/C	R/C	Υ
LW-9910	(16bit): remote HMI 22's IPO (IP address = IPO:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-9911	(16bit): remote HMI 22's IP1 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-9912	(16bit): remote HMI 22's IP2 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-9913	(16bit): remote HMI 22's IP3 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-9914	(16bit) : remote HMI 22's port no.	R/W	R/C	R/C	Y
LW-9915	(16bit): remote HMI 23's IPO (IP address = IPO:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-9916	(16bit): remote HMI 23's IP1 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-9917	(16bit): remote HMI 23's IP2 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-9918	(16bit): remote HMI 23's IP3 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-9919	(16bit) : remote HMI 23's port no.	R/W	R/C	R/C	Υ
LW-9920	(16bit): remote HMI 24's IPO (IP address = IPO:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-9921	(16bit): remote HMI 24's IP1 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-9922	(16bit): remote HMI 24's IP2 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-9923	(16bit): remote HMI 24's IP3 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-9924	(16bit) : remote HMI 24's port no.	R/W	R/C	R/C	Υ
LW-9925	(16bit): remote HMI 25's IPO (IP address = IPO:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-9926	(16bit): remote HMI 25's IP1 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-9927	(16bit) : remote HMI 25's IP2 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-9928	(16bit) : remote HMI 25's IP3 (IP address =	R/W	R/C	R/C	Υ



	IP0:IP1:IP2:IP3)				
LW-9929	(16bit) : remote HMI 25's port no.	R/W	R/C	R/C	Υ
LW-9930	(16bit): remote HMI 26's IPO (IP address = IPO:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-9931	(16bit) : remote HMI 26's IP1 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-9932	(16bit) : remote HMI 26's IP2 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-9933	(16bit): remote HMI 26's IP3 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-9934	(16bit) : remote HMI 26's port no.	R/W	R/C	R/C	Υ
LW-9935	(16bit) : remote HMI 27's IPO (IP address = IPO:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-9936	(16bit): remote HMI 27's IP1 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-9937	(16bit): remote HMI 27's IP2 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-9938	(16bit): remote HMI 27's IP3 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-9939	(16bit) : remote HMI 27's port no.	R/W	R/C	R/C	Υ
LW-9940	(16bit): remote HMI 28's IPO (IP address = IPO:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-9941	(16bit): remote HMI 28's IP1 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-9942	(16bit): remote HMI 28's IP2 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-9943	(16bit): remote HMI 28's IP3 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-9944	(16bit) : remote HMI 28's port no.	R/W	R/C	R/C	Υ
LW-9945	(16bit): remote HMI 29's IPO (IP address = IPO:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-9946	(16bit): remote HMI 29's IP1 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-9947	(16bit) : remote HMI 29's IP2 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-9948	(16bit): remote HMI 29's IP3 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Υ



LW-9949	(16bit) : remote HMI 29's port no.	R/W	R/C	R/C	Υ
LW-9950	(16bit): remote HMI 30's IPO (IP address = IPO:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-9951	(16bit): remote HMI 30's IP1 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-9952	(16bit): remote HMI 30's IP2 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-9953	(16bit): remote HMI 30's IP3 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-9954	(16bit) : remote HMI 30's port no.	R/W	R/C	R/C	Υ
LW-9955	(16bit): remote HMI 31's IPO (IP address = IPO:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-9956	(16bit): remote HMI 31's IP1 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-9957	(16bit): remote HMI 31's IP2 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-9958	(16bit): remote HMI 31's IP3 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-9959	(16bit) : remote HMI 31's port no.	R/W	R/C	R/C	Υ
LW-9960	(16bit): remote HMI 32's IPO (IP address = IPO:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-9961	(16bit): remote HMI 32's IP1 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-9962	(16bit): remote HMI 32's IP2 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-9963	(16bit): remote HMI 32's IP3 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-9964	(16bit) : remote HMI 32's port no.	R/W	R/C	R/C	Υ
LW-9995	(16bit): remote HMI 39's IPO (IP address = IPO:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-9996	(16bit): remote HMI 39's IP1 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-9997	(16bit) : remote HMI 39's IP2 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-9998	(16bit): remote HMI 39's IP3 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-9999	(16bit) : remote HMI 39's port no.	R/W	R/C	R/C	Y
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LW-12506	(16bit) : remote HMI 40's IPO (IP address = IPO:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-12507	(16bit): remote HMI 40's IP1 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-12508	(16bit) : remote HMI 40's IP2 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-12509	(16bit) : remote HMI 40's IP3 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-12510	(16bit) : remote HMI 40's port no.	R/W	R/C	R/C	Υ
LW-12511	(16bit): remote HMI 41's IPO (IP address = IPO:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-12512	(16bit) : remote HMI 41's IP1 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-12513	(16bit) : remote HMI 41's IP2 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-12514	(16bit) : remote HMI 41's IP3 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-12515	(16bit) : remote HMI 41's port no.	R/W	R/C	R/C	Υ
LW-12516	(16bit): remote HMI 42's IPO (IP address = IPO:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-12517	(16bit) : remote HMI 42's IP1 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-12518	(16bit) : remote HMI 42's IP2 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-12519	(16bit) : remote HMI 42's IP3 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-12520	(16bit) : remote HMI 42's port no.	R/W	R/C	R/C	Υ
LW-12521	(16bit): remote HMI 43's IPO (IP address = IPO:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-12522	(16bit) : remote HMI 43's IP1 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-12523	(16bit) : remote HMI 43's IP2 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-12524	(16bit) : remote HMI 43's IP3 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-12525	(16bit) : remote HMI 43's port no.	R/W	R/C	R/C	Υ
LW-12526	(16bit) : remote HMI 44's IPO (IP address =	R/W	R/C	R/C	Υ



	IPO:IP1:IP2:IP3)				
	(16bit) : remote HMI 44's IP1 (IP address =				Υ
LW-12527	IP0:IP1:IP2:IP3)	R/W	R/C	R/C	
	(16bit) : remote HMI 44's IP2 (IP address =				Y
LW-12528	IPO:IP1:IP2:IP3)	R/W	R/C	R/C	
	(16bit) : remote HMI 44's IP3 (IP address =	- 6	- 1-	- 1-	Υ
LW-12529	IP0:IP1:IP2:IP3)	R/W	R/C	R/C	
LW-12530	(16bit) : remote HMI 44's port no.	R/W	R/C	R/C	Y
	(16bit) : remote HMI 45's IPO (IP address =	D //A/	D/C	D/C	Υ
LW-12531	IP0:IP1:IP2:IP3)	R/W	R/C	R/C	
	(16bit) : remote HMI 45's IP1 (IP address =	D /\A/	D/C	D/C	Υ
LW-12532	IP0:IP1:IP2:IP3)	R/W	R/C	R/C	
	(16bit) : remote HMI 45's IP2 (IP address =	R/W	R/C	R/C	Υ
LW-12533	IP0:IP1:IP2:IP3)	IN/ VV	N/C	N/C	
	(16bit) : remote HMI 45's IP3 (IP address =	R/W	R/C	R/C	Y
LW-12534	IP0:IP1:IP2:IP3)	IN/ VV	N/C	N/C	
LW-12535	(16bit) : remote HMI 45's port no.	R/W	R/C	R/C	Υ
	(16bit) : remote HMI 46's IP0 (IP address =	R/W	R/C	R/C	Υ
LW-12536	IP0:IP1:IP2:IP3)	11,7 44	11,7 C	100	
	(16bit) : remote HMI 46's IP1 (IP address =	R/W	R/C	R/C	Υ
LW-12537	IP0:IP1:IP2:IP3)	1,7 00	1,7 C	11,0	
	(16bit) : remote HMI 46's IP2 (IP address =	R/W	R/C	R/C	Y
LW-12538	IP0:IP1:IP2:IP3)	.,	.,, -	- 4 -	
	(16bit) : remote HMI 46's IP3 (IP address =	R/W	R/C	R/C	Y
LW-12539	IP0:IP1:IP2:IP3)	.,	.,, -	., .	
LW-12540	(16bit) : remote HMI 46's port no.	R/W	R/C	R/C	Y
	(16bit) : remote HMI 47's IPO (IP address =	R/W	R/C	R/C	Υ
LW-12541	IPO:IP1:IP2:IP3)	,	, -	, -	
	(16bit) : remote HMI 47's IP1 (IP address =	R/W	R/C	R/C	Υ
LW-12542	IPO:IP1:IP2:IP3)	,	·		
	(16bit) : remote HMI 47's IP2 (IP address =	R/W	R/C	R/C	Υ
LW-12543	IPO:IP1:IP2:IP3)				
	(16bit) : remote HMI 47's IP3 (IP address =	R/W	R/C	R/C	Υ
LW-12544	IPO:IP1:IP2:IP3)				
LW-12545	(16bit) : remote HMI 47's port no.	R/W	R/C	R/C	Y
	(16bit) : remote HMI 48's IPO (IP address =	R/W	R/C	R/C	Y
LW-12546	IP0:IP1:IP2:IP3)				



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LW-12547	(16bit) : remote HMI 48's IP1 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-12548	(16bit): remote HMI 48's IP2 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LVV-12548	·				
	(16bit) : remote HMI 48's IP3 (IP address =	R/W	R/C	R/C	Y
LW-12549	IPO:IP1:IP2:IP3)				
LW-12550	(16bit) : remote HMI 48's port no.	R/W	R/C	R/C	Y
	(16bit) : remote HMI 49's IPO (IP address =	R/W	R/C	R/C	Y
LW-12551	IP0:IP1:IP2:IP3)	11, 11	11,00	TI, C	
	(16bit) : remote HMI 49's IP1 (IP address =	D ///	D/C	D/C	Y
LW-12552	IP0:IP1:IP2:IP3)	R/W	R/C	R/C	
	(16bit) : remote HMI 49's IP2 (IP address =	- 4	- 1-	- 1-	Y
LW-12553	IP0:IP1:IP2:IP3)	R/W	R/C	R/C	
	(16bit) : remote HMI 49's IP3 (IP address =				Υ
LW-12554	IPO:IP1:IP2:IP3)	R/W	R/C	R/C	
LW-12555	(16bit) : remote HMI 49's port no.	R/W	R/C	R/C	Y
	(16bit) : remote HMI 50's IPO (IP address =	,	, -	, -	Υ
LW-12556	IPO:IP1:IP2:IP3)	R/W	R/C	R/C	·
211 12330	(16bit) : remote HMI 50's IP1 (IP address =				Υ
LW-12557	IPO:IP1:IP2:IP3)	R/W	R/C	R/C	'
LVV-12337	·				Y
111/ 42550	(16bit) : remote HMI 50's IP2 (IP address =	R/W	R/C	R/C	Y
LW-12558	IPO:IP1:IP2:IP3)				
	(16bit) : remote HMI 50's IP3 (IP address =	R/W	R/C	R/C	Y
LW-12559	IPO:IP1:IP2:IP3)				
LW-12560	(16bit) : remote HMI 50's port no.	R/W	R/C	R/C	Y
	(16bit) : remote HMI 51's IPO (IP address =	R/W	R/C	R/C	Υ
LW-12561	IP0:IP1:IP2:IP3)	.,,	1,70	1,70	
	(16bit) : remote HMI 51's IP1 (IP address =	R/W	R/C	R/C	Y
LW-12562	IP0:IP1:IP2:IP3)	I N/ VV	R/C	N/C	
	(16bit) : remote HMI 51's IP2 (IP address =	5 //4/	2/0	D/C	Υ
LW-12563	IP0:IP1:IP2:IP3)	R/W	R/C	R/C	
	(16bit) : remote HMI 51's IP3 (IP address =				Υ
LW-12564	IPO:IP1:IP2:IP3)	R/W	R/C	R/C	
LW-12565	(16bit) : remote HMI 51's port no.	R/W	R/C	R/C	Y
	(16bit) : remote HMI 52's IPO (IP address =		-		Υ
LW-12566	IPO:IP1:IP2:IP3)	R/W	R/C	R/C	
LW-12567	(16bit) : remote HMI 52's IP1 (IP address =	R/W	R/C	R/C	Y
211 12307	(1-0217) 11-1111 02 3 H 1 (II dudie33 -	11, 10	1,7,0	1,7,0	•



	IP0:IP1:IP2:IP3)				
	(16bit) : remote HMI 52's IP2 (IP address =				Y
LW-12568	IP0:IP1:IP2:IP3)	R/W	R/C	R/C	
	(16bit) : remote HMI 52's IP3 (IP address =				Υ
LW-12569	IP0:IP1:IP2:IP3)	R/W	R/C	R/C	
LW-12570	(16bit) : remote HMI 52's port no.	R/W	R/C	R/C	Υ
	(16bit) : remote HMI 53's IPO (IP address =	D //A/	D/C	D/C	Υ
LW-12571	IP0:IP1:IP2:IP3)	R/W	R/C	R/C	
	(16bit) : remote HMI 53's IP1 (IP address =	R/W	R/C	R/C	Υ
LW-12572	IPO:IP1:IP2:IP3)	K/VV	K/C	K/C	
	(16bit) : remote HMI 53's IP2 (IP address =	R/W	R/C	R/C	Υ
LW-12573	IPO:IP1:IP2:IP3)	IN/ VV	N/C	N/C	
	(16bit) : remote HMI 53's IP3 (IP address =	R/W	R/C	R/C	Υ
LW-12574	IPO:IP1:IP2:IP3)	IN/ VV	N/C	N/C	
LW-12575	(16bit) : remote HMI 53's port no.	R/W	R/C	R/C	Y
	(16bit) : remote HMI 54's IPO (IP address =	R/W	R/C	R/C	Υ
LW-12576	IPO:IP1:IP2:IP3)	I TY VV	NC	NC	
	(16bit) : remote HMI 54's IP1 (IP address =	R/W	R/C	R/C	Υ
LW-12577	IPO:IP1:IP2:IP3)	IV, VV	NC	NC	
	(16bit) : remote HMI 54's IP2 (IP address =	R/W	R/C	R/C	Υ
LW-12578	IPO:IP1:IP2:IP3)	11,7 VV	Tyc	100	
	(16bit) : remote HMI 54's IP3 (IP address =	R/W	R/C	R/C	Υ
LW-12579	IPO:IP1:IP2:IP3)	11,7 44	11,0	1,7,0	
LW-12580	(16bit) : remote HMI 54's port no.	R/W	R/C	R/C	Υ
	(16bit) : remote HMI 55's IPO (IP address =	R/W	R/C	R/C	Υ
LW-12581	IPO:IP1:IP2:IP3)	11,7 VV	TO C	100	
	(16bit) : remote HMI 55's IP1 (IP address =	R/W	R/C	R/C	Υ
LW-12582	IPO:IP1:IP2:IP3)	11, 44	1,7,0	190	
	(16bit) : remote HMI 55's IP2 (IP address =	R/W	R/C	R/C	Υ
LW-12583	IPO:IP1:IP2:IP3)	11, 44	190	190	
	(16bit) : remote HMI 55's IP3 (IP address =	R/W	R/C	R/C	Υ
LW-12584	IPO:IP1:IP2:IP3)	11, 44	1,7,0	1,7,0	
LW-12585	(16bit) : remote HMI 55's port no.	R/W	R/C	R/C	Υ
	(16bit) : remote HMI 56's IPO (IP address =	R/W	R/C	R/C	Υ
LW-12586	IPO:IP1:IP2:IP3)	11, 44	1,4,0	1,7,0	
	(16bit) : remote HMI 56's IP1 (IP address =	R/W	R/C	R/C	Υ
LW-12587	IPO:IP1:IP2:IP3)	11, 44	1,7,0	1.7.0	



	(16bit) : remote HMI 56's IP2 (IP address =				Υ
LW-12588	IPO:IP1:IP2:IP3)	R/W	R/C	R/C	ī
	(16bit): remote HMI 56's IP3 (IP address =	R/W	R/C	R/C	Υ
LW-12589	IP0:IP1:IP2:IP3)	IV, VV	NyC	NC	
LW-12590	(16bit) : remote HMI 56's port no.	R/W	R/C	R/C	Υ
	(16bit) : remote HMI 57's IPO (IP address =	R/W	R/C	R/C	Υ
LW-12591	IP0:IP1:IP2:IP3)	IV/ VV	NC	NC	
	(16bit) : remote HMI 57's IP1 (IP address =	R/W	R/C	R/C	Υ
LW-12592	IP0:IP1:IP2:IP3)	11,700	11,00	1,7,0	
	(16bit) : remote HMI 57's IP2 (IP address =	R/W	R/C	R/C	Υ
LW-12593	IP0:IP1:IP2:IP3)	.,,	1,70	.,, c	
	(16bit) : remote HMI 57's IP3 (IP address =	R/W	R/C	R/C	Υ
LW-12594	IP0:IP1:IP2:IP3)	.,	.,,	., -	
LW-12595	(16bit) : remote HMI 57's port no.	R/W	R/C	R/C	Υ
	(16bit) : remote HMI 58's IPO (IP address =	R/W	R/C	R/C	Υ
LW-12596	IPO:IP1:IP2:IP3)	,	·	·	
	(16bit) : remote HMI 58's IP1 (IP address =	R/W	R/C	R/C	Υ
LW-12597	IPO:IP1:IP2:IP3)				
	(16bit) : remote HMI 58's IP2 (IP address =	R/W	R/C	R/C	Υ
LW-12598	IPO:IP1:IP2:IP3)				
	(16bit) : remote HMI 58's IP3 (IP address =	R/W	R/C	R/C	Υ
LW-12599	IPO:IP1:IP2:IP3)	5 /4/	D/C	D/6	V
LW-12600	(16bit) : remote HMI 58's port no.	R/W	R/C	R/C	Y
40.504	(16bit) : remote HMI 59's IPO (IP address =	R/W	R/C	R/C	Υ
LW-12601	IPO:IP1:IP2:IP3)				V
IW 12602	(16bit) : remote HMI 59's IP1 (IP address =	R/W	R/C	R/C	Υ
LW-12602	IPO:IP1:IP2:IP3)				Y
LW-12603	(16bit) : remote HMI 59's IP2 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	ĭ
LVV-12003	(16bit) : remote HMI 59's IP3 (IP address =				Υ
LW-12604	IPO:IP1:IP2:IP3)	R/W	R/C	R/C	1
LW-12605	(16bit) : remote HMI 59's port no.	R/W	R/C	R/C	Y
277 12003	(16bit) : remote HMI 60's IPO (IP address =	11/ 44	1,7,0	1,70	Y
LW-12606	IPO:IP1:IP2:IP3)	R/W	R/C	R/C	,
211 22000	(16bit) : remote HMI 60's IP1 (IP address =				Υ
LW-12607	IPO:IP1:IP2:IP3)	R/W	R/C	R/C	·
LW-12608	(16bit) : remote HMI 60's IP2 (IP address =	R/W	R/C	R/C	Υ
	, , , , , , , , , , , , , , , , , , , ,	<u> </u>	, -	• -	



	IP0:IP1:IP2:IP3)				
	(16bit) : remote HMI 60's IP3 (IP address =	- 6	- 1-	- 1-	Υ
LW-12609	IP0:IP1:IP2:IP3)	R/W	R/C	R/C	
LW-12610	(16bit) : remote HMI 60's port no.	R/W	R/C	R/C	Y
	(16bit) : remote HMI 61's IPO (IP address =	R/W	R/C	R/C	Υ
LW-12611	IP0:IP1:IP2:IP3)	K/ VV	K/C	N/C	
	(16bit) : remote HMI 61's IP1 (IP address =	R/W	R/C	R/C	Y
LW-12612	IP0:IP1:IP2:IP3)	IV, VV	NC	NC	
	(16bit) : remote HMI 61's IP2 (IP address =	R/W	R/C	R/C	Υ
LW-12613	IP0:IP1:IP2:IP3)	11,7 44	11, C	1,7,0	
	(16bit) : remote HMI 61's IP3 (IP address =	R/W	R/C	R/C	Υ
LW-12614	IPO:IP1:IP2:IP3)	10, 00	11,0	11,0	
LW-12615	(16bit) : remote HMI 61's port no.	R/W	R/C	R/C	Y
	(16bit) : remote HMI 62's IP0 (IP address =	R/W	R/C	R/C	Υ
LW-12616	IP0:IP1:IP2:IP3)	1,7 00	1,7,0	11,0	
	(16bit) : remote HMI 62's IP1 (IP address =	R/W	R/C	R/C	Y
LW-12617	IPO:IP1:IP2:IP3)	.,	.,, 0	.,, C	
	(16bit) : remote HMI 62's IP2 (IP address =	R/W	R/C	R/C	Y
LW-12618	IPO:IP1:IP2:IP3)	.,,	.,, 5	.,, c	
	(16bit) : remote HMI 62's IP3 (IP address =	R/W	R/C	R/C	Y
LW-12619	IPO:IP1:IP2:IP3)	,	, -	, -	
LW-12620	(16bit) : remote HMI 62's port no.	R/W	R/C	R/C	Y
	(16bit) : remote HMI 63's IPO (IP address =	R/W	R/C	R/C	Y
LW-12621	IPO:IP1:IP2:IP3)	,	,	,	
	(16bit) : remote HMI 63's IP1 (IP address =	R/W	R/C	R/C	Υ
LW-12622	IPO:IP1:IP2:IP3)	,	·	·	
	(16bit) : remote HMI 63's IP2 (IP address =	R/W	R/C	R/C	Y
LW-12623	IPO:IP1:IP2:IP3)	,	·	·	
	(16bit) : remote HMI 63's IP3 (IP address =	R/W	R/C	R/C	Y
LW-12624	IPO:IP1:IP2:IP3)	-	-	-	
LW-12625	(16bit) : remote HMI 63's port no.	R/W	R/C	R/C	Y
	(16bit) : remote HMI 64's IPO (IP address =	R/W	R/C	R/C	Y
LW-12626	IPO:IP1:IP2:IP3)				
	(16bit) : remote HMI 64's IP1 (IP address =	R/W	R/C	R/C	Y
LW-12627	IPO:IP1:IP2:IP3)				
	(16bit) : remote HMI 64's IP2 (IP address =	R/W	R/C	R/C	Y
LW-12628	IP0:IP1:IP2:IP3)				



LW-12629	(16bit): remote HMI 64's IP3 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-12630	(16bit) : remote HMI 64's port no.	R/W	R/C	R/C	Υ

## 22.3.19. Communication Status and Control with Remote Device

		Read(R)/	Supported		
Address	Description	Local HMI	Macro	Remote HMI	on cMT
LW-10050	(16bit): IPO of the HMI connecting to remote	D /\A/	D/C	D/C	N
	device 1 (IP address = IPO:IP1:IP2:IP3)	R/W	R/C	R/C	N
LW-10051	(16bit): IP1 of the HMI connecting to remote	R/W	R/C	R/C	N
	device 1 (IP address = IPO:IP1:IP2:IP3)	K/VV	R/C	R/C	N
LW-10052	(16bit): IP2 of the HMI connecting to remote	R/W	R/C	R/C	N
	device 1 (IP address = IPO:IP1:IP2:IP3)	K/VV	R/C	R/C	N
LW-10053	(16bit): IP3 of the HMI connecting to remote	R/W	R/C	D/C	N
	device 1 (IP address = IP0:IP1:IP2:IP3)	N/ VV	N/C	R/C	N
LW-10054	(16bit) : port no. of the HMI connecting to	R/W	R/C	R/C	N
	remote device 1	I I VV	N/C	R/C	IN
LW-10055	(16bit): IPO of the HMI connecting to remote	D /M/	D/C	R/C	N
	device 2 (IP address = IPO:IP1:IP2:IP3)	R/W	R/C		N
LW-10056	(16bit): IP1 of the HMI connecting to remote	R/W	R/C	R/C	N
	device 2 (IP address = IP0:IP1:IP2:IP3)	N/ VV	N/C	.,, C	IN
LW-10057	(16bit): IP2 of the HMI connecting to remote	R/W	R/C	R/C	N
	device 2 (IP address = IP0:IP1:IP2:IP3)	N/ VV	N/C	R/C	IN
LW-10058	(16bit): IP3 of the HMI connecting to remote	R/W	R/C	R/C	N
	device 2 (IP address = IP0:IP1:IP2:IP3)	N/ VV	N/C	R/C	IN
LW-10059	(16bit) : port no. of the HMI connecting to	R/W	N D/C	R/C R/C	N
	remote device 2	IN/ VV	R/C	N/C	IN
LW-10060	(16bit): IPO of the HMI connecting to remote	R/W	R/C	R/C	N
	device 3 (IP address = IPO:IP1:IP2:IP3)	N/ VV	N/C	R/C	IN
LW-10061	(16bit): IP1 of the HMI connecting to remote	R/W	R/C	R/C	N
	device 3 (IP address = IPO:IP1:IP2:IP3)	N/ VV	N/C	R/C	IN
LW-10062	(16bit): IP2 of the HMI connecting to remote	te R/W	R/C	R/C	N
	device 3 (IP address = IPO:IP1:IP2:IP3)	n/ VV	N/C	n/C	IN
LW-10063	(16bit): IP3 of the HMI connecting to remote		p/c	p/c	N
	device 3 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	IN
LW-10064	(16bit) : port no. of the HMI connecting to	R/W	R/C	R/C	N



	remote device 3				
LW-10065	(16bit): IPO of the HMI connecting to remote device 4 (IP address = IPO:IP1:IP2:IP3)	R/W	R/C	R/C	N
LW-10066	(16bit): IP1 of the HMI connecting to remote device 4 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	N
LW-10067	(16bit): IP2 of the HMI connecting to remote device 4 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	N
LW-10068	(16bit): IP3 of the HMI connecting to remote device 4 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	N
LW-10069	(16bit) : port no. of the HMI connecting to remote device 4	R/W	R/C	R/C	N
LW-10205	(16bit): IPO of the HMI connecting to remote device 32 (IP address = IPO:IP1:IP2:IP3)	R/W	R/C	R/C	N
LW-10206	(16bit): IP1 of the HMI connecting to remote device 32 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	N
LW-10207	(16bit): IP2 of the HMI connecting to remote device 32 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	N
LW-10208	(16bit): IP3 of the HMI connecting to remote device 32 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	N
LW-10209	(16bit) : port no. of the HMI connecting to remote device 32	R/W	R/C	R/C	N
LW-10300	(16bit): remote device 1's IPO (IP address = IPO:IP1:IP2:IP3)	R/W	R/C	R/C	N
LW-10301	(16bit): remote device 1's IP1 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	N
LW-10302	(16bit): remote device 1's IP2 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	N
LW-10303	(16bit): remote device 1's IP3 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	N
LW-10304	(16bit) : remote device 1's port no.	R/W	R/C	R/C	N
LW-10305	(16bit): remote device 2's IPO (IP address = IPO:IP1:IP2:IP3)	R/W	R/C	R/C	N
LW-10306	(16bit): remote device 2's IP1 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	N
LW-10307	(16bit): remote device 2's IP2 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	N
LW-10308	(16bit) : remote device 2's IP3 (IP address =	R/W	R/C	R/C	N



	IP0:IP1:IP2:IP3)				
LW-10309	(16bit) : remote device 2's port no.	R/W	R/C	R/C	N
LW-10310	(16bit): remote device 3's IPO (IP address = IPO:IP1:IP2:IP3)	R/W	R/C	R/C	N
LW-10311	(16bit): remote device 3's IP1 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	N
LW-10312	(16bit): remote device 3's IP2 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	N
LW-10313	(16bit): remote device 3's IP3 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	N
LW-10314	(16bit) : remote device 3's port no.	R/W	R/C	R/C	N
LW-10315	(16bit): remote device 4's IPO (IP address = IPO:IP1:IP2:IP3)	R/W	R/C	R/C	N
LW-10316	(16bit): remote device 4's IP1 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	N
LW-10317	(16bit): remote device 4's IP2 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	N
LW-10318	(16bit): remote device 4's IP3 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	N
LW-10319	(16bit) : remote device 4's port no.	R/W	R/C	R/C	N
LW-10455	(16bit): remote device 32's IPO (IP address = IPO:IP1:IP2:IP3)	R/W	R/C	R/C	N
LW-10456	(16bit): remote device 32's IP1 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	N
LW-10457	(16bit): remote device 32's IP2 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	N
LW-10458	(16bit): remote device 32's IP3 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	N
LW-10459	(16bit) : remote device 32's port no.	R/W	R/C	R/C	N

# 22.3.20. Local/Remote Operation Restrictions

Address	Description	Read(R)/	Supported		
		Local HMI	Macro	Remote HMI	on cMT
LB-9044	disable remote control (when ON)	R/W	R/C	R/C	Υ
LB-9053	prohibit password remote-read operation (when ON)	R/W	R/C	R/C	Y



LB-9054	prohibit password remote-write operation (when ON)	R/W	R/C	R/C	Y
LB-9196	local HMI supports monitor function only (when ON)	R/W	R/C	R/C	Υ
LB-9197	support monitor function only for remote HMIs (when ON)	R/W	R/C	R/C	Υ
LB-9198	disable local HMI to trigger a MACRO (when ON)	R/W	R/C	R/C	Υ
LB-9199	disable remote HMI to trigger a MACRO (when ON)	R/W	R/C	R/C	Υ

### 22.3.21. Communication Error Codes

		Read(R)/	Read(R)/Write(W)/Control(C)			
Address	Description	Local HMI	Macro	Remote HMI	on cMT	
LW-9400	(16bit) : error code for device 1	R	R	R	Υ	
LW-9401	(16bit) : error code for device 2	R	R	R	Υ	
LW-9402	(16bit) : error code for device 3	R	R	R	Υ	
LW-9403	(16bit) : error code for device 4	R	R	R	Υ	
LW-9404	(16bit) : error code for device 5	R	R	R	Υ	
LW-9405	(16bit) : error code for device 6	R	R	R	Υ	
LW-9406	(16bit) : error code for device 7	R	R	R	Υ	
LW-9407	(16bit) : error code for device 8	R	R	R	Υ	
LW-9449	(16bit) : error code for device 50	R	R	R	Υ	
LW-9490	(16bit) : error code for USB device	R	R	R	Υ	
LW-9492	(16bit) : error code for CAN-Bus device	R	R	R	Υ	



22-62



# 1. A list of the explanation of device communication error codes:

Error Code	Cause of Communication Error
0	Normal
1	The device is busy and not yet ready to process a command.
2	Communication error due to unexpected reason.
3	The device does not exist.
4	The device using the specified station number does not exist.
5	Incorrect address format.
6	Read/Write unsupported address.
7	The driver of the device does not exist.
8	The COM port does not exist.
9	Incorrect IP address or unable to connect the device.
10	Checksum error.
11	Unidentified command.
12	Ignore
20	The USB device is improperly connected.
21	The CAN Bus device is improperly connected.
22	No reply from the device.
23	Insufficient data read from the device before timeout.
24	The Conversion Tag used by the object does not exist or the content is incorrect.
25	HMI is not accepting any commands from a remote HMI.
251	Read/Write exceeding number of words from/to the register of the MODBUS device.
252	MODBUS device replies incorrect data format.
253	MODBUS device checksum error.



### 22.3.22. Driver ID

Address	Description	Read(R)/	Supported		
		Local HMI	Macro	Remote HMI	on cMT
LW-9300	(16bit) : driver ID of local device 1	R	R	R	Υ
LW-9301	(16bit) : driver ID of local device 2	R	R	R	Υ
LW-9302	(16bit) : driver ID of local device 3	R	R	R	Υ
LW-9303	(16bit) : driver ID of local device 4	R	R	R	Υ
LW-9331	(16bit) : driver ID of local device 32	R	R	R	Υ

### **22.3.23. DLT645** Controller

		Read(R)/	Read(R)/Write(W)/Control(C)			
Address	Description	Local HMI	Macro	Remote HMI	on cMT	
LW-10700	(4 words): DLT_645 operator (COM 1)	R/W	R/C	R/C	Υ	
LW-10704	(4 words): DLT_645 password (COM 1)	R/W	R/C	R/C	Υ	
LW-10708	(6 words): DLT_645 address (COM 1)	R/W	R/C	R/C	Υ	
LW-10715	(4 words): DLT_645 operator (COM 2)	R/W	R/C	R/C	Υ	
LW-10719	(4 words): DLT_645 password (COM 2)	R/W	R/C	R/C	Υ	
LW-10723	(6 words): DLT_645 address (COM 2)	R/W	R/C	R/C	Y	
LW-10730	(4 words): DLT_645 operator (COM 3)	R/W	R/C	R/C	Υ	
LW-10734	(4 words): DLT_645 password (COM 3)	R/W	R/C	R/C	Υ	
LW-10738	(6 words): DLT_645 address (COM 3)	R/W	R/C	R/C	Y	

# 22.3.24. [Device No Response] Window Control

		Read(R)/Write(W)/Control(C)			Supported
Address	Description	Local HMI	Macro	Remote HMI	on cMT
LB-9192	disable USB device's "Device No Response" dialog (when ON)	R/W	R/C	R/C	Υ
LB-11960	disable device 1's "Device No Response" dialog (when ON)	R/W	R/C	R/C	Υ
LB-11961	disable device 2's "Device No Response" dialog (when ON)	R/W	R/C	R/C	Y
LB-11962	disable device 3's "Device No Response" dialog (when ON)	R/W	R/C	R/C	Y
LB-11963	disable device 4's "Device No Response" dialog (when ON)	R/W	R/C	R/C	Υ
LB-11964	disable device 5's "Device No Response" dialog (when ON)	R/W	R/C	R/C	Υ
LB-11965	disable device 6's "Device No Response"	R/W	R/C	R/C	Υ



22-64 **System Registers** 

	dialog (when ON)				
LB-11966	disable device 7's "Device No Response" dialog (when ON)	R/W	R/C	R/C	Υ
LB-11967	disable device 8's "Device No Response" dialog (when ON)	R/W	R/C	R/C	Υ
LB-12023	disable device 64's "Device No Response" dialog (when ON)	R/W	R/C	R/C	Υ
LB-12082	disable CAN Bus device's "Device No Response" dialog (when ON)	R/W	R/C	R/C	Υ

## 22.3.25. [Fast Selection] Window Control

Address	Description	Read(R)/Write(W)/Control(C)			Supported
		Local HMI	Macro	Remote HMI	on cMT
LB-9013	hide (set ON)/show (set OFF) FS window	R/W	R/C	R/C	N
LB-9014	hide (set ON)/show (set OFF) FS button	R/W	R/C	R/C	N
LB-9015	hide (set ON)/show (set OFF) FS window/button	R/W	R/C	R/C	N

### 22.3.26. EasyAccess

	Description	Read(R)/	Supported		
Address		Local HMI	Macro	Remote HMI	on cMT
LB-9051	disconnect (set OFF)/connect (set ON) EasyAccess server	R/W	R/C	R/C	N
LB-9052	status of connecting to EasyAccess server	R	R	R	N





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### 22.3.27. EasyAccess 2.0

		Read(R)/	Supported		
Address	Description	Local HMI	Macro	Remote HMI	on cMT
LW-10820	(16bit) : disable (set 0)/enable (set 1) (EasyAccess 2.0)	R/W	R/C	R/C	Y
LW-10821	(5 words) : session ID (EasyAccess 2.0)	R	R	R	Y
LW-10826	(2 words): password (EasyAccess 2.0)	R	R	R	Υ
LW-10828	(16bit): execution status (EasyAccess 2.0)	R	R	R	Y
LW-10829	(16bit): the last error code (EasyAccess	R	R	R	Y



	2.0)				
LW-11170	(16bit): Proxy Disable/Enable (0:disable, 1:enable) (EasyAccess 2.0)	R/W	R/C	R/C	Y
LW-11171	(16bit): Proxy Type (0:HTTP, 1:SOCKSv4, 2:SOCKSv5) (EasyAccess 2.0)	R/W	R/C	R/C	Y
LW-11172	(16bit): Proxy Server IPO (EasyAccess 2.0)	R/W	R/C	R/C	Υ
LW-11173	(16bit): Proxy Server IP1 (EasyAccess 2.0)	R/W	R/C	R/C	Υ
LW-11174	(16bit): Proxy Server IP2 (EasyAccess 2.0)	R/W	R/C	R/C	Υ
LW-11175	(16bit): Proxy Server IP3 (EasyAccess 2.0)	R/W	R/C	R/C	Υ
LW-11176	(16bit): Proxy Server Port (EasyAccess 2.0)	R/W	R/C	R/C	Υ
LW-11177	(16bit): Proxy authentication (0:disable, 1:enable) (EasyAccess 2.0)	R/W	R/C	R/C	Y
LW-11178	(16 words) : Proxy username (EasyAccess 2.0)	R/W	R/C	R/C	Y
LW-11194	(16 words) : Proxy password (EasyAccess 2.0)	R/W	R/C	R/C	Y
LW-11210	(20 words) : Hardware key (EasyAccess 2.0)	R	R	R	Y
LW-11296	(16bit): Location of EasyAccess 2.0 server (0: Global, 1: China)	R/W	R/C	R/C	Υ
LW-11770	(64 words) : QR code (URL) for WeChat push notification (EasyAccess 2.0)	R	R	R	Υ
LW-11982	(16 words): HMI domain (EasyAccess 2.0)	R	R	R	Υ
LW-12773	(16 words) : Number of connected user (EasyAccess 2.0)	R	R	R	Υ
LW-12774	(16 words) : Connected user 1 (EasyAccess 2.0)	R	R	R	Y
LW-12790	(16 words) : Connected user 2 (EasyAccess 2.0)	R	R	R	Y
LW-12806	(16 words): Connected user 3 (EasyAccess 2.0)	R	R	R	Υ

# 22.3.28. Remote Print/Backup Server

		Read(R)/	Read(R)/Write(W)/Control(C)			
Address	Description	Local HMI	Macro	Remote HMI	on cMT	
LB-10069	forced to reconnect remote					
	printer/backup server when IP changed	R/W	R/C	R/C	N	
	on-line (set ON)					
LB-12040	remote printer/backup server	D	R		N	
	disconnection alarm (when ON)	R	ĸ	R	N	
LW-9770	(16bit): remote printer/backup server IPO	D (M)	D/C	- /-	N	
	(IP0:IP1:IP2:IP3)	R/W	R/C	R/C	N	



22-66 **System Registers** 

LW-9771	(16bit): remote printer/backup server IP1 (IP0:IP1:IP2:IP3)	R/W	R/C	R/C	N
LW-9772	(16bit): remote printer/backup server IP2 (IP0:IP1:IP2:IP3)	R/W	R/C	R/C	N
LW-9773	(16bit): remote printer/backup server IP3 (IP0:IP1:IP2:IP3)	R/W	R/C	R/C	N
LW-9774	(6 words): remote printer/backup server user name *Note 1	R/W	R/C	R/C	N
LW-9780	(6 words) : remote printer/backup server password *Note 1	R/W	R/C	R/C	N



When change settings using LW-9774 and LW-9780, please reboot HMI for the new settings to take effect.



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## 22.3.29. Pass-Through Settings

	Description	Read(R)/	Read(R)/Write(W)/Control(C)		
Address		Local HMI	Macro	Remote HMI	on cMT
LW-9901	(16bit): pass-through source COM port (1~3: COM 1~COM 3)	R/W	R/C	R/C	Υ
LW-9902	(16bit): pass-through destination COM port (1~3: COM 1~COM 3)	R/W	R/C	R/C	Y
LW-9903	(16bit): pass-through control (0: normal, 1: pause, 2: stop communications between HMI and device when executing pass-through)	R/W	R/C	R/C	Y
LW-9904	(16bit): pass-through server port no. (2000~2100)	R/W	R/C	R/C	Y
LW-10850	(16bit): disable/enable (0: disable, 1: normal, 2: IP limited) (siemens pass-through)	R/W	R/C	R/C	Y
LW-10851	(16bit): destination COM port (siemens pass-through)	R/W	R/C	R/C	Y



22-67 **System Registers** 

LW-10852	(16bit) : destination PLC station no.	R/W	R/C	R/C	Y
	(siemens pass-through)	n, w	NyC	N/C	T
LW-10853	(16bit) : communication protocol (0 :				
	invalid, 1: PPI, 2: MPI) (siemens	R/W	R/C	R/C	Υ
	pass-through)				
LW-10854	(16bit): IPO of connecting client (IP				
	address = IP0:IP1:IP2:IP3) (siemens	R/W	R/C	R/C	Y
	pass-through)				
LW-10855	(16bit): IP1 of connecting client (IP				
	address = IP0:IP1:IP2:IP3) (siemens	R/W	R/C	R/C	Υ
	pass-through)				
LW-10856	(16bit): IP2 of connecting client (IP				
	address = IP0:IP1:IP2:IP3) (siemens	R/W	R/C	R/C	Υ
	pass-through)				
LW-10857	(16bit): IP3 of connecting client (IP				
	address = IP0:IP1:IP2:IP3) (siemens	R/W	R/C	R/C	Υ
	pass-through)				
LW-10858	(16bit): IPO of designated client (IP				
	address = IP0:IP1:IP2:IP3) (siemens	R/W	R/C	R/C	Υ
	pass-through)				
LW-10859	(16bit): IP1 of designated client (IP				
	address = IP0:IP1:IP2:IP3) (siemens	R/W	R/C	R/C	Υ
	pass-through)				
LW-10860	(16bit): IP2 of designated client (IP				
	address = IP0:IP1:IP2:IP3) (siemens	R/W	R/C	R/C	Υ
	pass-through)				
LW-10861	(16bit): IP3 of designated client (IP				
	address = IP0:IP1:IP2:IP3) (siemens	R/W	R/C	R/C	Υ
	pass-through)				
LW-10862	(16bit) : connection status (0 : ready, 1 :				V
	client connecting) (siemens pass-through)	R	R	R	Y
LW-10863	(16bit): execution status (0: normal, 1:				Y
	error) (siemens pass-through)	R	R	R	
LW-10864	(16bit) : the last error (siemens	-	_		
	pass-through)	R	R	R	Y



For more information about Siemens pass-through feature, see "29 Pass-through".





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#### 22.3.30. VNC Control

		Read(R)/	Read(R)/Write(W)/Control(C)		
Address	Description	Local HMI	Macro	Remote HMI	on cMT
LB-12088	enable VNC monitor mode (when ON) *Note 1	R/W	R/C	R/C	Y
LB-12089	VNC pass word free (when ON) *Note 1	R/W	R/C	R/C	Υ
LB-12090	a VNC client connecting to HMI (when ON)(OS version 20120621 or later supports only)	R	R	R	Υ
LB-12091	disable auto-logout function when a VNC client connecting to HMI (when ON)(OS version 20120621 or later supports only)	R/W	R/C	R/C	Y
LB-12092	enable VNC (set ON), disable VNC (set OFF)	R/W	R/C	R/C	Y
LB-12093	VNC connection mode (OFF: single connection, ON: multi connection) (OS version 2013.05.09 or later support)*Note1	R/W	R/C	R/C	Y
LB-12824	disable touch control when a VNC client connects to HMI (when ON) (supported OS version 20230526 or later) *Note2	R/W	R/C	R/C	N
LW-9530	(4 words): VNC server password	R/W	R/C	R/C	Υ



- On eMT, iE, XE, mTV, iP models, to change VNC mode, use LB-12092 to stop and then restart VNC to update the setting.
- When the touch control is switched to the VNC client, an icon will appear in the 2. top left corner of the window. If the system register to disable touch control is enabled while VNC monitoring mode is active, the control will remain on the HMI side. Activating the system register to disable touch control will also disable the connected USB mouse control. However, control can be restored to the USB mouse by simply reinserting it.

#### 22.3.31. Project Key and HMI Key

		Read(R)/	Supported		
Address	Description	Local HMI	Macro	Remote HMI	on cMT
LB-9046	project key is different from HMI key	R	R	R	Y



22-69 **System Registers** 

	(when ON)				
LW-9046	(32bit) : HMI key *Note 1	R/W	R/C	R	Υ



When change HMI Key using LW-9046, please reboot HMI for the new settings to take



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# 22.3.32. USB Security Key

		Read(R)/	ontrol(C)	Supported	
Address	Description	Local HMI	Macro	Remote HMI	on cMT
LW-11160	(16bit) : start time of USB security key - year	R	R	R	Υ
LW-11161	(16bit) : start time of USB security key - month	R	R	R	Υ
LW-11162	(16bit) : start time of USB security key - day	R	R	R	Υ
LW-11163	(16bit) : start time of USB security key - hour	R	R	R	Υ
LW-11164	(16bit) : start time of USB security key - minute	R	R	R	Y
LW-11165	(16bit) : expiration time of USB security key - year	R	R	R	Υ
LW-11166	(16bit) : expiration time of USB security key - month	R	R	R	Υ
LW-11167	(16bit) : expiration time of USB security key - day	R	R	R	Υ
LW-11168	(16bit) : expiration time of USB security key - hour	R	R	R	Υ
LW-11169	(16bit) : expiration time of USB security key - minute	R	R	R	Y

#### 22.3.33. User Name and Password

		Read(R)/	Supported		
Address	Description	Local HMI	Macro	Remote HMI	on cMT
LB-9050	user logout *Note 2	W	С	С	N
LB-9060	password error *Note 2	R	R	R	N
LB-9061	update password (set ON) *Note 2	W	С	С	N
LB-12056	the user touches an unauthorized object	R	R	R	Υ



22-70 **System Registers** 

	(when ON)				
PLB-12056	the user touches an unauthorized object (when ON) (on tablet)	R	N/A	N/A	Y
LW-9082	(16bit): auto logout time (unit: minute, 0: disable the function)	R/W	R/C	R/C	Y
LW-9219	(16bit) : user no. (1~12) *Note 2	R/W	R/C	R/C	N
LW-9220	(32bit): password *Note 2	R/W	R/C	R/C	N
LW-9222	(16bit): object classes can be operated for current user (bit 0:A, bit 1:B,bit 2:C,)	R	R	R	Y
PLW-9222	(16bit): object classes (on tablet) can be operated for current user (bit 0:A, bit 1:B,bit 2:C,)	R	N/A	N/A	Y
LW-9500	(32bit): user 1's password *Note 2	R/W	R/C	R/C	N
LW-9502	(32bit): user 2's password *Note 2	R/W	R/C	R/C	N
LW-9504	(32bit): user 3's password *Note 2	R/W	R/C	R/C	N
LW-9506	(32bit): user 4's password *Note 2	R/W	R/C	R/C	N
LW-9508	(32bit) : user 5's password *Note 2	R/W	R/C	R/C	N
LW-9510	(32bit) : user 6's password *Note 2	R/W	R/C	R/C	N
LW-9512	(32bit) : user 7's password *Note 2	R/W	R/C	R/C	N
LW-9514	(32bit) : user 8's password *Note 2	R/W	R/C	R/C	N
LW-9516	(32bit): user 9's password *Note 2	R/W	R/C	R/C	N
LW-9518	(32bit) : user 10's password *Note 2	R/W	R/C	R/C	N
LW-9520	(32bit) : user 11's password *Note 2	R/W	R/C	R/C	N
LW-9522	(32bit): user 12's password *Note 2	R/W	R/C	R/C	N
LW-10754	(8 words) : current user name *Note 1	R	R	R	Y
PLW-10754	(8 words) : current user name (on tablet) *Note 1	R	N/A	N/A	Υ



- Only for [Security] » [Enhanced security mode].
- Only for [Security] » [General mode].



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### 22.3.34. Macro

		Read(R)/	/Write(W)/C	ontrol(C)	Supported
Address	Description	Local HMI	Macro	Remote HMI	on cMT
LB-9059	disable macro TRACE function (when ON) *Note1	R/W	R/C	R/C	Υ
LW-10900	(16bit): macro 0 status (0:ready, 3:executing, 5:waiting response, 9:waiting sync, 17:delay, 32:abnormal end (exceed array size))	R	R	R	Y
LW-10901	(16bit): macro 1 status (0:ready, 3:executing, 5:waiting response, 9:waiting sync, 17:delay, 32:abnormal end (exceed array size))	R	R	R	Y
LW-10902	(16bit): macro 2 status (0:ready, 3:executing, 5:waiting response, 9:waiting sync, 17:delay, 32:abnormal end (exceed array size))	R	R	R	Y
LW-10903	(16bit): macro 3 status (0:ready, 3:executing, 5:waiting response, 9:waiting sync, 17:delay, 32:abnormal end (exceed array size))	R	R	R	Y
LW-10904	(16bit): macro 4 status (0:ready, 3:executing, 5:waiting response, 9:waiting sync, 17:delay, 32:abnormal end (exceed array size))	R	R	R	Y
LW-10905	(16bit): macro 5 status (0:ready, 3:executing, 5:waiting response, 9:waiting sync, 17:delay, 32:abnormal end (exceed array size))	R	R	R	Y
LW-10906	(16bit): macro 6 status (0:ready, 3:executing, 5:waiting response, 9:waiting sync, 17:delay, 32:abnormal end (exceed array size))	R	R	R	Y
LW-10907	(16bit): macro 7 status (0:ready, 3:executing, 5:waiting response, 9:waiting sync, 17:delay, 32:abnormal end (exceed array size))	R	R	R	Y
LW-10908	(16bit): macro 8 status (0:ready, 3:executing, 5:waiting response, 9:waiting sync, 17:delay, 32:abnormal end (exceed array size))	R	R	R	Y
LW-10909	(16bit): macro 9 status (0:ready, 3:executing, 5:waiting response, 9:waiting sync, 17:delay, 32:abnormal end (exceed	R	R	R	Y



	array size))				
LW-11154	(16bit): macro 254 status (0:ready,				
	3:executing, 5:waiting response, 9:waiting	_			.,
	sync, 17:delay, 32:abnormal end (exceed	R	R	R	Y
	array size))				
LW-12247	(16bit): macro 255 status (0: ready, 3:				
	executing, 5: waiting response, 9: waiting	D	D	D	v
	sync, 17: delay, 32: abnormal end (exceed	R	R	R	Y
	array size))				
LW-12248	(16bit): macro 256 status (0: ready, 3:				
	executing, 5: waiting response, 9: waiting	D	D	D	V
	sync, 17: delay, 32: abnormal end (exceed	R	R	R	Y
	array size))				
LW-12249	(16bit): macro 257 status (0: ready, 3:				
	executing, 5: waiting response, 9: waiting	R	R	D	Y
	sync, 17: delay, 32: abnormal end (exceed	N.	N.	R	r
	array size))				
LW-12250	(16bit): macro 258 status (0: ready, 3:				
	executing, 5: waiting response, 9: waiting	R	R R	R	Υ
	sync, 17: delay, 32: abnormal end (exceed	1,	Ι.	IV.	'
	array size))				
LW-12251	(16bit): macro 259 status (0: ready, 3:				
	executing, 5: waiting response, 9: waiting	R	R	R	Υ
	sync, 17: delay, 32: abnormal end (exceed	•			•
	array size))				
LW-12252	(16bit): macro 260 status (0: ready, 3:				
	executing, 5: waiting response, 9: waiting	R	R	R	Υ
	sync, 17: delay, 32: abnormal end (exceed		, ,		1
	array size))				
LW-12253	(16bit): macro 261 status (0: ready, 3:				
	executing, 5: waiting response, 9: waiting	R	R R	R	Y
	sync, 17: delay, 32: abnormal end (exceed				-
	array size))				
LW-12254	(16bit): macro 262 status (0: ready, 3:				
	executing, 5: waiting response, 9: waiting	R	R	R	Υ
	sync, 17: delay, 32: abnormal end (exceed				
	array size))				
LW-12255	(16bit): macro 263 status (0: ready, 3:				
	executing, 5: waiting response, 9: waiting	R	R	R	Υ
	sync, 17: delay, 32: abnormal end (exceed				
	array size))				
LW-12256	(16bit): macro 264 status (0: ready, 3:				
	executing, 5: waiting response, 9: waiting	R	R	R	Υ
	sync, 17: delay, 32: abnormal end (exceed				
	array size))				



22-73 **System Registers** 

LW-12491	(16bit): macro 499 status (0: ready, 3:				
	executing, 5: waiting response, 9: waiting	D	D	D	V
	sync, 17: delay, 32: abnormal end (exceed	ĸ	ĸ	ĸ	Y
	array size))				



1. LB-9059: Disable macro trace function.



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# 22.3.35. Input Object Function

	Description	Read(R)/	Read(R)/Write(W)/Control(C)			
Address		Local HMI	Macro	Remote HMI	on cMT	
LW-9002	(32bit-float) : input high limit	R	R	R	Υ	
LW-9004	(32bit-float) : input low limit	R	R	R	Υ	
LW-9052	(32bit-float): the previous input value of the numeric input object	R	R	R	Y	
PLW-9052	(32bit-float) : the previous input value of the numeric input object	R	N/A	N/A	Υ	
LW-9150	(32 words) : keyboard's input data (ASCII)	R	R	R	Υ	
LW-9540	(16bit): reserved for caps lock	R/W	R/C	R/C	Υ	

## 22.3.36. Time Sync./Daylight Saving Time

		Read(R)/	/Write(W)/	Control(C)	Supported
Address	Description	Local HMI	Macro	Remote HMI	on cMT
LB-12055	failed to execute time synchronization (when	R	R	R	Υ
	ON)	IV.	I.	11	'
LB-12355	daylight saving time period (when ON)	R	R	R	Υ
LW-11260	(16bit): enable/disable the daylight saving	D /\A/	D/C	D/C	Υ
	time (DST) (0:disable, 1:enable)	R/W	R/C	R/C	ť
LW-11261	(16bit): hour of the DST bias	R/W	R/C	R/C	Υ
LW-11262	(16bit): minute of the DST bias	R/W	R/C	R/C	Υ
LW-11263	(16bit): month of the year when DST starts	R/W	R/C	R/C	Υ
LW-11264	(16bit): week of the month when DST starts	R/W	R/C	R/C	Υ
	(1~5)		N/C	R/C	1
LW-11265	(16bit) : day of the week when DST starts (0 $^{\sim}$	R/W	R/C	R/C	Υ



	6)				
LW-11266	(16bit) : hour of local time when DST starts	R/W	R/C	R/C	Υ
LW-11267	(16bit) : minute of local time when DST starts	R/W	R/C	R/C	Υ
LW-11268	(16bit) : month of the year when DST ends	R/W	R/C	R/C	Υ
LW-11269	(16bit): week of the month when DST ends (1~5)	R/W	R/C	R/C	Υ
LW-11270	(16bit): day of the week when DST ends ( $0^{\sim}6$ )	R/W	R/C	R/C	Υ
LW-11271	(16bit) : hour of local time when DST ends	R/W	R/C	R/C	Υ
LW-11272	(16bit) : minute of local time when DST ends	R/W	R/C	R/C	Υ
LW-11273	(16bit): enable/disable time synchronization				
	via NTP (Network Time Protocol) server	R/W	R/C	R/C	Υ
	(0:disable, 1:enable)				
LW-11274	(16bit) : execute time synchronization when HMI starts (0:disable, 1:enable)	R/W	R/C	R/C	Y
LW-11275	(16bit): server response time has been adjusted in accordance with DST (0:disable, 1:enable)	R/W	R/C	R/C	Y
LW-11276	(16bit) : HMI time zone (unit : minute)	R/W	R/C	R/C	Υ
LW-11277	(16bit) : server response time (server time zone) (unit : minute)	R/W	R/C	R/C	Υ
LW-11278	(16bit): IP 0 of network time server 1 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-11279	(16bit): IP 1 of network time server 1 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-11280	(16bit): IP 2 of network time server 1 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-11281	(16bit): IP 3 of network time server 1 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-11282	(16bit): IP 0 of network time server 2 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-11283	(16bit): IP 1 of network time server 2 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-11284	(16bit): IP 2 of network time server 2 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-11285	(16bit): IP 3 of network time server 2 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-11286	(16bit): IP 0 of network time server 3 (IP	R/W	R/C	R/C	Υ



	address = IP0:IP1:IP2:IP3)				
LW-11287	(16bit): IP 1 of network time server 3 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-11288	(16bit) : IP 2 of network time server 3 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-11289	(16bit): IP 3 of network time server 3 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-11290	(16bit) : IP 0 of network time server 4 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-11291	(16bit): IP 1 of network time server 4 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-11292	(16bit): IP 2 of network time server 4 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Υ
LW-11293	(16bit): IP 3 of network time server 4 (IP address = IP0:IP1:IP2:IP3)	R/W	R/C	R/C	Y
LW-11294	(32bit) : update interval (time synchronization interval) (10 $^{\sim}$ 86400, unit : second)	R/W	R/C	R/C	Υ

### 22.3.37. Cellular Data Network

		Read(R)/	/Write(W)/	Control(C)	Supported
Address	Description	Local HMI	Macro	Remote HMI	on cMT
LW-11297	(16 words) : PIN code of SIM card (cellular network)	R/W	R/C	R/C	Y
LW-11313	(16 words) : Access Point Name (cellular network)	R/W	R/C	R/C	Y
LW-11329	(16 words) : username (cellular network)	R/W	R/C	R/C	Υ
LW-11345	(16 words) : password (cellular network)	R/W	R/C	R/C	Y
LW-11361	(16 words) : dial number (cellular network)	R/W	R/C	R/C	Υ
LW-11377	(16bit): stop (set 0)/start (set 1) connection (cellular network)	R/W	R/C	R/C	Υ
LW-11378	(16bit): last error code (0:success, 1:incorrect PIN code, 2:no SIM, 3:no device, 4:puk locked, 5:other) (cellular network)	R	R	R	Υ
LW-11379	(16bit): connection status (0:no device, 1:disconnect, 2:connecting, 3:connected) (cellular network)	R	R	R	Y



LW-11380	(16bit): stop (set 0)/start (set 1) connection (USB tethering)	R/W	R/C	R/C	Y
LW-11381	(16bit): connection status (0:no device, 1:disconnect, 2:connected, 3:fail, 4:OS not support, 5:HMI not support) (USB tethering)	R	R	R	Y
LW-12631	(16bit): signal strength (dBm) (0: failed, others: signal strength) (cellular network)	R	R	R	Υ
LW-12632	(8 words) : IMEI (cellular network)	R	R	R	Υ
LW-12640	(10 words) : ICCID code of SIM card (cellular network)	R	R	R	Υ

# 22.3.38. WiFi Setting

System registers listed in this section are available exclusively for HMI models that support WiFi only, e.g. MT8103iE, cMT3103, cMT-SVR-200...etc.

A al alma s s	Description		Write(W)/0		Supported
Address	Description	Local HMI	Macro	Remote HMI	on cMT
LB-12365	update wifi setting (IP, netmask, gateway,	ПІУІІ		ПІЛІ	
LD-12303	DNS) (set ON)	R/W	R/C	R/C	Y
12.42555	, , ,	5 / 1 / 1	2/2	5/6	.,
LB-12666	disable(set OFF)/enable(set ON) WiFi Hotspot	R/W	R/C	R/C	Y
LB-12667	refresh WiFi Hotspot setting (SSID, password)	R/W	R/C	R/C	Y
	(set ON)	10, 44	1,7 €	1,70	·
LB-12820	M02 status (0: unplugged, 1: plugged in)	R	R	R	Υ
LW-11383	(16bit): WiFi control (1: disconnect, 2:				
	connect, 3: popup setting dialog, 4: connect	R/W	R/C	R/C	Υ
	by SSID)				
LW-11384	(16bit) : WiFi error code (0: no error, 1: no				
	such device, 2. radio is off, 3: parameter is	R	R	R	Υ
	invalid)				
LW-11385	(16bit) : WiFi status (0: stopped; 1:	_	_	_	.,
	connecting; 2: connected)	R	R	R	Υ
LW-11386	(16 words) : WiFi connected SSID	R	R	R	Υ
LW-11402	(16bit): WiFi signal level (0: none, 1: weak, 2:				.,
	fair, 3: good, 4: excellent) *Note2	R	R	R	Y
LW-11403	(16bit): WiFi country code *Note1	R/W	R/C	R/C	Υ
LW-11404	(16bit) : WiFi radio (0: Off, 1: On)	R/W	R/C	R/C	Υ
LW-11405	(16bit): WiFi signal strength (dBm) (0, 1, 2:	R	R	R	Υ



	failed, others: signal strength)				
LW-11410	(16bit) : HMI WiFi IP 0 (for HMI use only)	R/W	R/C	R/C	Υ
LW-11411	(16bit) : HMI WiFi IP 1 (for HMI use only)	R/W	R/C	R/C	Υ
LW-11412	(16bit) : HMI WiFi IP 2 (for HMI use only)	R/W	R/C	R/C	Υ
LW-11413	(16bit): HMI WiFi IP 3 (for HMI use only)	R/W	R/C	R/C	Υ
LW-11414	(16bit): HMI WiFi netmask 0 (for HMI use only)	R/W	R/C	R/C	Υ
LW-11415	(16bit) : HMI WiFi netmask 1 (for HMI use only)	R/W	R/C	R/C	Υ
LW-11416	(16bit) : HMI WiFi netmask 2 (for HMI use only)	R/W	R/C	R/C	Υ
LW-11417	(16bit) : HMI WiFi netmask 3 (for HMI use only)	R/W	R/C	R/C	Υ
LW-11418	(16bit): HMI WiFi gateway 0 (for HMI use only)	R/W	R/C	R/C	Υ
LW-11419	(16bit): HMI WiFi gateway 1 (for HMI use only)	R/W	R/C	R/C	Υ
LW-11420	(16bit): HMI WiFi gateway 2 (for HMI use only)	R/W	R/C	R/C	Υ
LW-11421	(16bit): HMI WiFi gateway 3 (for HMI use only)	R/W	R/C	R/C	Υ
LW-11422	(16bit): HMI WiFi media access control (MAC) address 0	R	R	R	Υ
LW-11423	(16bit): HMI WiFi media access control (MAC) address 1	R	R	R	Υ
LW-11424	(16bit): HMI WiFi media access control (MAC) address 2	R	R	R	Υ
LW-11425	(16bit): HMI WiFi media access control (MAC) address 3	R	R	R	Υ
LW-11426	(16bit): HMI WiFi media access control (MAC) address 4	R	R	R	Υ
LW-11427	(16bit): HMI WiFi media access control (MAC) address 5	R	R	R	Υ
LW-11428	(16bit): HMI WiFi domain name system (DNS) server IP 0	R/W	R/C	R/C	Υ
LW-11429	(16bit): HMI WiFi domain name system (DNS) server IP 1	R/W	R/C	R/C	Υ



22-78

LW-11430       (16bit) : HMI WiFi domain name system (DNS) server IP 2       R/W       R/C       R/C       Y         LW-11431       (16bit) : HMI WiFi domain name system (DNS) server IP 3       R/W       R/C       R/C       Y         LW-11432       (16bit) : obtain an WiFi IP address automatically (DHCP => 0 : off, 1 : on)       R/W       R/C       R/C       Y         LW-12006       (16 words) : WiFi Hotspot SSID (enable to apply)       R/W       R/C       R/C       Y         LW-12022       (32 words) : WiFi Hotspot password (enable to apply)       R/W       R/C       R/C       Y         LW-12703       (16 words : WiFi SSID to connect       R/W       R/C       R/C       Y         LW-12719       (32 words) : WiFi password to use       R/W       R/C       R/C       Y         LW-12719       (32 words) : WiFi security mode to use (0: WPA/WPA2, 1: WEP, 2: NONE)       R/W       R/C       R/C       Y         LW-12751       (16bit) : WiFi Hotspot security mode (0: NONE, 1: WPA-MIX-PSK)       R/W       R/C       R/C       Y         LW-12769       (16bit) : WiFi Hotspot server address IPO       R       R       R       Y         LW-12770       (16bit) : WiFi Hotspot server address IP2       R/W       R/C       R/C       Y						
LW-11432   (16bit): obtain an WiFi IP address   automatically (DHCP => 0: off, 1: on)   R/W   R/C   R/C   Y	LW-11430	, , ,	R/W	R/C	R/C	Υ
LW-12006   (16 words) : WiFi Hotspot SSID (enable to apply)   R/W   R/C   R/C   Y	LW-11431		R/W	R/C	R/C	Υ
LW-12022   (32 words) : WiFi Hotspot password (enable to apply)   R/W   R/C   R/C   Y	LW-11432	, i	R/W	R/C	R/C	Υ
LW-12703       (16 words : WiFi SSID to connect       R/W       R/C       R/C       Y         LW-12719       (32 words) : WiFi password to use       R/W       R/C       R/C       Y         LW-12751       (16bit) : WiFi security mode to use (0: WPA/WPA2, 1: WEP, 2: NONE)       R/W       R/C       R/C       Y         LW-12768       (16bit) : WiFi Hotspot security mode (0: NONE, 1: WPA-MIX-PSK)       R/W       R/C       R/C       Y         LW-12769       (16bit) : WiFi Hotspot server address IPO       R       R       R       Y         LW-12770       (16bit) : WiFi Hotspot server address IP1       R       R       R       Y         LW-12771       (16bit) : WiFi Hotspot server address IP2       R/W       R/C       R/C       Y	LW-12006	· · ·	R/W	R/C	R/C	Y
LW-12719       (32 words): WiFi password to use       R/W       R/C       R/C       Y         LW-12751       (16bit): WiFi security mode to use (0: WPA/WPA2, 1: WEP, 2: NONE)       R/W       R/C       R/C       Y         LW-12768       (16bit): WiFi Hotspot security mode (0: NONE, 1: WPA-MIX-PSK)       R/W       R/C       R/C       Y         LW-12769       (16bit): WiFi Hotspot server address IPO       R       R       R       Y         LW-12770       (16bit): WiFi Hotspot server address IP1       R       R       R       Y         LW-12771       (16bit): WiFi Hotspot server address IP2       R/W       R/C       R/C       Y	LW-12022	· · · · ·	R/W	R/C	R/C	Y
LW-12751 (16bit): WiFi security mode to use (0: WPA/WPA2, 1: WEP, 2: NONE)  LW-12768 (16bit): WiFi Hotspot security mode (0: NONE, 1: WPA-MIX-PSK)  LW-12769 (16bit): WiFi Hotspot server address IPO R R R R Y  LW-12770 (16bit): WiFi Hotspot server address IP1 R R R Y  LW-12771 (16bit): WiFi Hotspot server address IP2 R/W R/C R/C Y	LW-12703	(16 words : WiFi SSID to connect	R/W	R/C	R/C	Υ
LW-12768(16bit): WiFi Hotspot security mode (0: NONE, 1: WPA-MIX-PSK)R/WR/CR/CYLW-12769(16bit): WiFi Hotspot server address IP0RRRRLW-12770(16bit): WiFi Hotspot server address IP1RRRYLW-12771(16bit): WiFi Hotspot server address IP2R/WR/CR/CY	LW-12719	(32 words) : WiFi password to use	R/W	R/C	R/C	Υ
R/W   R/C   R/C   Y	LW-12751	, , ,	R/W	R/C	R/C	Υ
LW-12770 (16bit): WiFi Hotspot server address IP1 R R R Y LW-12771 (16bit): WiFi Hotspot server address IP2 R/W R/C R/C Y	LW-12768		R/W	R/C	R/C	Y
LW-12771 (16bit): WiFi Hotspot server address IP2 R/W R/C R/C Y	LW-12769	(16bit): WiFi Hotspot server address IPO	R	R	R	Υ
	LW-12770	(16bit): WiFi Hotspot server address IP1	R	R	R	Υ
LW-12772 (16bit): WiFi Hotspot server address IP3 R R Y	LW-12771	(16bit): WiFi Hotspot server address IP2	R/W	R/C	R/C	Υ
	LW-12772	(16bit): WiFi Hotspot server address IP3	R	R	R	Υ



**System Registers** 

- 1. Please enter WiFi country code in ASCII for uppercase letters, the setting will take effect after rebooting HMI. Wireless regulations vary from country to country. The country code selection affects the list of channels of the wireless radio.
- 2. The signal strength is classified into four levels: 1. Weak (<-70 dBm), 2. Fair (-60  $^{\sim}$  -70 dBm), 3. Good (-50  $^{\sim}$  -60 dBm), 4. Excellent (>-50 dBm)

#### 22.3.39. OPC UA Server

	Description	Read(R)/	Supported		
Address		Local HMI	Macro	Remote HMI	on cMT
LW-11435	(16bit): OPC UA Server status (0: Stopped, 1: Started)	R	R	R	Υ
LW-11436	(16bit) : OPC UA Server error code (0: Success, 1 or more: Error) *Note 1	R	R	R	Υ
LW-11437	(16bit): OPC UA Server control command (0: None, 1: Start, 2: Stop)	R/W	R/C	R/C	Υ
LB-12753	clear OPC UA HAD data	R/W	R/C	R/C	Υ



22-79



1. Error codes of failed steps include:

Code	Cause of Error
0	No error
1	Unknown error
2	Invalid certificate

#### 22.3.40. e-Mail

		Read(R)/	Supported		
Address	Description	Local HMI	Macro	Remote HMI	on cMT
LB-12053	failed to send an [Event Log] e-Mail (when ON)	R	R	R	Υ
LB-12054	failed to send an [Backup Object] e-Mail (when ON)	R	R	R	Υ
LW-9216	(16bit): the result of importing email data  *Note 1	R	R	R	Υ
LW-11444	(16bit) : failed step (e-Mail) *Note 2	R	R	R	Υ
LW-11445	(16bit) : error code (e-Mail) *Note 3	R	R	R	Y



- 1. 1: import succeeded, 2: import failed (file doesn't exist), 4: incorrect file format or file cannot be decrypted.
- **2.** Error codes of failed steps include:

Code	Cause of Error
0	CSMTP_NO_ERROR
100	WSA_STARTUP = Unable to initialize winsock2
101	WSA_VER = Wrong version of the winsock2
102	WSA_SEND = Function send() failed
103	WSA_RECV = Function recv() failed
104	WSA_CONNECT = Function connect failed
105	WSA_GETHOSTBY_NAME_ADDR = Unable to determine remote server
106	WSA_INVALID_SOCKET = Invalid winsock2 socket
107	WSA_HOSTNAME = Function hostname() failed
108	WSA_IOCTLSOCKET = Function ioctlsocket() failed
109	WSA_SELECT
110	BAD_IPV4_ADDR = Improper IPv4 address



200	UNDEF_MSG_HEADER = Undefined message header
201	UNDEF_MAIL_FROM = Undefined mail sender
202	UNDEF_SUBJECT = Undefined message subject
203	UNDEF_RECIPIENTS = Undefined at least one recipient
204	UNDEF_RECIPIENT_MAIL = Undefined recipient mail
205	UNDEF_LOGIN = Undefined user login
206	UNDEF_PASSWORD = Undefined user password
207	BAD_LOGIN_PASSWORD = Invalid user login or password
208	BAD_DIGEST_RESPONSE = Server returned a bad digest MD5 response
209	BAD_SERVER_NAME = Unable to determine server name for digest MD5 response
300	COMMAND_MAIL_FROM = Server returned error after sending MAIL FROM
301	COMMAND_EHLO = Server returned error after sending EHLO
302	COMMAND_AUTH_PLAIN = Server returned error after sending AUTH PLAIN
303	COMMAND_AUTH_LOGIN = Server returned error after sending AUTH LOGIN
304	COMMAND_AUTH_CRAMMD5 = Server returned error after sending AUTH CRAM-MD5
305	COMMAND_AUTH_DIGESTMD5 = Server returned error after sending AUTH DIGEST-MD5
306	COMMAND_DIGESTMD5 = Server returned error after sending MD5 DIGEST
307	COMMAND_DATA = Server returned error after sending DATA
308	COMMAND_QUIT = Server returned error after sending QUIT
309	COMMAND_RCPT_TO = Server returned error after sending RCPT TO
310	MSG_BODY_ERROR = Error in message body
400	CONNECTION_CLOSED = Server has closed the connection
401	SERVER_NOT_READY = Server is not ready
402	SERVER_NOT_RESPONDING = Server not responding
403	SELECT_TIMEOUT =
404	FILE_NOT_EXIST = File not exist
405	MSG_TOO_BIG = Message is too big
406	BAD_LOGIN_PASS = Bad login or password
407	UNDEF_XYZ_RESPONSE = Undefined xyz SMTP response
408	LACK_OF_MEMORY = Lack of memory
409	TIME_ERROR = time() error
410	RECVBUF_IS_EMPTY = RecvBuf is empty
411	SENDBUF_IS_EMPTY = SendBuf is empty
412	OUT_OF_MSG_RANGE = Specified line number is out of message size
413	COMMAND_EHLO_STARTTLS = Server returned error after sending STARTTLS
414	SSL_PROBLEM = SSL problem
415	COMMAND_DATABLOCK = Failed to send data block



416	STARTTLS_NOT_SUPPORTED = The STARTTLS command is not supported by the server
417	LOGIN_NOT_SUPPORTED = AUTH LOGIN is not supported by the server

**3.** Error messages sent from mail server can be shown by designating a word address (length adjustable) in System Parameter Settings » e-Mail tab » [Error message].

## 22.3.41. cMT Viewer and Diagnoser

	Description	Read(R)/Write(W)/Control(C)			Supported
Address		Local HMI	Macro	Remote HMI	on cMT
LB-12656	enable Diagnoser (set ON), disable (set OFF)	R/W	R/C	R/C	Y
LB-12657	Diagnoser password free (when ON)	R/W	R/C	R/C	Y
LW-11756	(4 words) : Diagnoser password	R/W	R/C	R/C	Y
LW-11839	(16bit) : number of connected clients (cMT Viewer)	R	R	R	Υ
LW-11840	(8 words) : client 1 user name	R	R	R	Y
LW-11848	(8 words) : client 2 user name	R	R	R	Y
LW-11856	(8 words) : client 3 user name	R	R	R	Y
LW-11864	(8 words) : client 4 user name	R	R	R	Y
LW-11872	(8 words) : client 5 user name	R	R	R	Y
LW-11880	(8 words) : client 6 user name	R	R	R	Y
LW-11888	(8 words) : client 7 user name	R	R	R	Y
LW-11896	(8 words) : client 8 user name	R	R	R	Y
LW-11904	(8 words) : client 9 user name	R	R	R	Y
LW-11912	(8 words) : client 10 user name	R	R	R	Y
LW-11940	(16bit): client 1 IPO (IP address = IPO:IP1:IP2:IP3)	R	R	R	Y
LW-11941	(16bit): client 1 IP1 (IP address = IP0:IP1:IP2:IP3)	R	R	R	Y
LW-11942	(16bit): client 1 IP2 (IP address = IP0:IP1:IP2:IP3)	R	R	R	Y
LW-11943	(16bit): client 1 IP3 (IP address = IP0:IP1:IP2:IP3)	R	R	R	Y
LW-11944	(16bit): client 2 IPO (IP address = IPO:IP1:IP2:IP3)	R	R	R	Y
LW-11945	(16bit): client 2 IP1 (IP address = IP0:IP1:IP2:IP3)	R	R	R	Y
LW-11946	(16bit): client 2 IP2 (IP address = IP0:IP1:IP2:IP3)	R	R	R	Υ



LW-11947	(16bit): client 2 IP3 (IP address = IP0:IP1:IP2:IP3)	R	R	R	Y
LW-11948	(16bit): client 3 IPO (IP address = IPO:IP1:IP2:IP3)	R	R	R	Y
LW-11949	(16bit) : client 3 IP1 (IP address = IP0:IP1:IP2:IP3)	R	R	R	Υ
LW-11950	(16bit): client 3 IP2 (IP address = IP0:IP1:IP2:IP3)	R	R	R	Y
LW-11951	(16bit): client 3 IP3 (IP address = IP0:IP1:IP2:IP3)	R	R	R	Y
LW-11952	(16bit): client 4 IPO (IP address = IPO:IP1:IP2:IP3)	R	R	R	Y
LW-11953	(16bit): client 4 IP1 (IP address = IP0:IP1:IP2:IP3)	R	R	R	Y
LW-11954	(16bit) : client 4 IP2 (IP address = IP0:IP1:IP2:IP3)	R	R	R	Y
LW-11955	(16bit) : client 4 IP3 (IP address = IP0:IP1:IP2:IP3)	R	R	R	Υ
LW-11956	(16bit): client 5 IPO (IP address = IPO:IP1:IP2:IP3)	R	R	R	Y
LW-11957	(16bit) : client 5 IP1 (IP address = IP0:IP1:IP2:IP3)	R	R	R	Y
LW-11958	(16bit): client 5 IP2 (IP address = IP0:IP1:IP2:IP3)	R	R	R	Y
LW-11959	(16bit): client 5 IP3 (IP address = IP0:IP1:IP2:IP3)	R	R	R	Y
LW-11960	(16bit): client 6 IPO (IP address = IPO:IP1:IP2:IP3)	R	R	R	Y
LW-11961	(16bit): client 6 IP1 (IP address = IP0:IP1:IP2:IP3)	R	R	R	Y
LW-11962	(16bit): client 6 IP2 (IP address = IP0:IP1:IP2:IP3)	R	R	R	Y
LW-11963	(16bit) : client 6 IP3 (IP address = IP0:IP1:IP2:IP3)	R	R	R	Y
LW-11964	(16bit) : client 7 IPO (IP address = IPO:IP1:IP2:IP3)	R	R	R	Υ
LW-11965	(16bit) : client 7 IP1 (IP address =	R	R	R	Y



System Registers 22-83

	IP0:IP1:IP2:IP3)				
LW-11966	(16bit) : client 7 IP2 (IP address =		_	_	v
	IP0:IP1:IP2:IP3)	R	R	R	Y
LW-11967	(16bit) : client 7 IP3 (IP address =		_	_	.,
	IP0:IP1:IP2:IP3)	R	R	R	Y
LW-11968	(16bit) : client 8 IPO (IP address =				.,
	IP0:IP1:IP2:IP3)	R	R	R	Y
LW-11969	(16bit) : client 8 IP1 (IP address =				V
	IP0:IP1:IP2:IP3)	R	R	R	Y
LW-11970	(16bit) : client 8 IP2 (IP address =				V
	IP0:IP1:IP2:IP3)	R	R	R	Y
LW-11971	(16bit) : client 8 IP3 (IP address =			_	V
	IP0:IP1:IP2:IP3)	R	R	R	Y
LW-11972	(16bit) : client 9 IPO (IP address =	В	R	R	V
	IP0:IP1:IP2:IP3)	R			Y
LW-11973	(16bit) : client 9 IP1 (IP address =				V
	IP0:IP1:IP2:IP3)	R	R	R	Y
LW-11974	(16bit) : client 9 IP2 (IP address =	D	D	D	Y
	IP0:IP1:IP2:IP3)	R	R	R	Y
LW-11975	(16bit) : client 9 IP3 (IP address =	D	D	D	Υ
	IP0:IP1:IP2:IP3)	R	R	R	Y
LW-11976	(16bit) : client 10 IPO (IP address =	R	R	D	Υ
	IP0:IP1:IP2:IP3)	, n	N.	R	Ť
LW-11977	(16bit) : client 10 IP1 (IP address =	D	D		Υ
	IP0:IP1:IP2:IP3)	R	R	R	Ť
LW-11978	(16bit) : client 10 IP2 (IP address =	D	D	D	Υ
	IP0:IP1:IP2:IP3)	R	R	R	Y
LW-11979	(16bit) : client 10 IP3 (IP address =	R	D	R	Y
	IP0:IP1:IP2:IP3)		R		Ť
PLW-11998	(8 words) : Control Token release countdown	R	N/A	N/A	Υ
			<u> </u>		

# 22.3.42. CODESYS Information

Address	ss Description		Write(W)/0	Control(C) Remote	Supported on cMT
		Local I HMI		НМІ	OII CIVII
LW-11760	(16bit): CODESYS firmware status (0:error,	R	R	R	٧
	1:start, 2:stop)	11	11	11	'



System Registers 22-84

LW-11761	(16bit): CODESYS application status (0:error,	R	R	R	V
	1:start, 2:stop)	N.	N.	N.	Ť
LW-11762	(16bit): CODESYS login status (0:error,	D	R	R	v
	1:login, 2:logout)	R	N.	N.	Ť
LW-12059	2059 (16bit) : CODESYS firmware version (year)		R	R	Υ
LW-12060	(16bit) : CODESYS firmware version (month)	R	R	R	Υ
LW-12061	12061 (16bit): CODESYS firmware version (day)		R	R	Υ

# 22.3.43. Miscellaneous

		Read(R)/	Write(W)/	Control(C)	Supported
Address	Description	Local HMI	Macro	Remote HMI	on cMT
LB-9000~ LB-9009	mmanii aa aa ah		R/C	R/C	Υ
LB-9010	data-transfer write indicator	R	R	R	Υ
LB-9011	data-transfer read indicator	R	R	R	Υ
LB-9012	data-transfer execution indicator	R	R	R	Υ
LB-9016	status is on when any remote HMI client				
	connects to this HMI that acts as a remote	R	R	R	Υ
	нмі				
LB-9017	disable write-back in PLC control's [change window]		R/C	R/C	Y
LB-9039	status of file backup activity (backup in process if ON)		R	R	Y
LB-9045	memory-map communication fails (when ON)		R	R	Υ
LB-9049	LB-9049 disable/enable watch dog (use LW-11456 set watch dog timeout) *Note 1		R/C	R/C	Y
LB-12356	enable(set on)/disable(set off) web streaming	R/W	R/C	R/C	Υ
LB-12357	LB-12357 web streaming status (on: enabled / off: disabled)		R	R	Y
LB-12358	B-12358 enable (when ON) / disable (when OFF) off-line simulation on HMI *Note 5		R/C	R/C	Y
LB-12361	LB-12361 status of operation log function (OFF: disabled, ON: enabled)		R	R	Y
LB-12664	Cache Hit (cMT-G03)	R	R	R	Υ
LB-12668	668 SECS license status (0: not activated, 1: activated)		R	R	Y
LB-12819			R	R	Y



LB-12822	disable(set OFF)/enable(set ON) ethernet bridge mode	R/W	R/C	R/C	Υ
LW-9006	(16bit) : connected client no.	R	R	R	Υ
LW-9024	(16bit) : memory link system register	R/W	R/C	R/C	Υ
LW-9032	(8 words) : folder name of backup history files to SD, USB memory *Note 3	R/W	R/C	R/C	Υ
LW-9050	(16bit) : current base window ID	R	R	R	Υ
PLW-9050	(16bit) : current base window ID (on tablet)	R	N/A	N/A	Υ
LW-9134	(16bit) : language mode *Note 2	R/W	R/C	R/C	Υ
PLW-9134	(16bit): language mode (on tablet) *Note 2	R/W	N/A	N/A	Υ
LW-9900	(16bit): HMI run mode (0: normal mode, 1-3: test mode (COM 1-COM 3)	R/W	R/C	R/C	Y
LW-10762	(8 words) : slot1 user name	R/W	R/C	R/C	Υ
LW-10770	(8 words) : slot2 user name	R/W	R/C	R/C	Υ
LW-10778	(8 words) : slot3 user name	R/W	R/C	R/C	Υ
LW-10814	(16bit): connecting to a Weintek HMI (0:none, 1:connecting) *Note 4	R	R	R	Y
LW-11456	(16bit): watch dog timeout (3 ~ 10), unit: second *Note 1	R/W	R/C	R/C	Y
LW-12245	(32bit) : BACnet/IP server device id	R/W	R/C	R/C	Υ
LW-12824	(16 bit): Flash disk health status (0: unavailable or unsupported 1: good 2: fair 3: poor) *Note 7	R	R	R	Y
LW-12827	(16bit) : BACnet/IP server port no.	R/W	R/C	R/C	Υ



- When LB-9049 watch dog function is enabled, watch dog automatically reboots the system after the HMI stops functioning for a specified period of time.
- 2. To display texts on objects in multiple languages, except for using Label Library, the system reserved register [LW-9134: language mode] is needed. The value range in LW-9134 is 0 ~ 23. The values in LW-9134 relates to the languages downloaded to HMI. LW-9134 value and language correspondence vary according to the languages selected during project compilation and download.

For example: If 5 languages are defined by user in Label Library as Language 1 (Traditional Chinese), Language 2 (Simplified Chinese), Language 3 (English), Language 4 (French), and Language 5 (Japanese). If only Language 1, 3, 5 are downloaded, the corresponding language of the value in LW-9134 will be 0  $\rightarrow$  Language 1 (Traditional Chinese), 1  $\rightarrow$ Language 3 (English), 2 → Language 5 (Japanese). The following demo project explains how to switch languages using Option List Object and LW-9134.



Click the icon to download the demo project. Please confirm your internet connection.



System Registers 22-86

3. Click the icon to download the demo project. Please confirm your internet connection.

- **4.** When the USB Host is connected to a Weintek HMI, the address is set to 1, for testing if the USB Client of another Weintek HMI works normally.
- 5. This register allows switching to off-line mode on HMI. In off-line mode, "Device No Response" message will not show even when HMI is not properly connected. In this case, device related objects can still operate, however, the values are not read by / written to the device.
- 6. Supported on cMT-CTRL01.
- 7. When the health status of the flash disk is poor, please promptly contact your local distributor for assistance to prevent the HMI from experiencing booting issues.



# 23. HMI Supported Printers

This chapter describes the printers supported by HMI and the setup steps.

23.1.	The Supported Printer Types	23-2
23.2.	Steps to Add a New Printer and Start Printing	23-5
23.3.	Installing Network Printer on cMT / cMT X HMI	23-7
23.4.	Installing PPD File on cMT / cMT X HMI	23-10
23.5.	CUPS Printing Support	23-12



# **23.1.** The Supported Printer Types

HMI supported printer drivers include the following types:

Printer type	Description
SP-M, D, E, F	Serial printers, please configure communication parameters to match the printer. [Pixels of width] must be correctly set and can't exceed printer default setting:  100 pixels for 1610 series printers.  220 pixels for 2407, 4004 series printers.  The driver uses EPSON ESC Protocol for Serial Micro Printers.
EPSON ESC/P2 Series	Serial printers, please configure communication parameters to match the printer.  The ESPON ESC/P2 printer protocol is used.  Impact Printer: LQ-300, LQ-300+, LQ-300K+  (RS-232), LQ-300+II (RS-232)  Inkjet Printer: Stylus Photo 750  Laser Printer: EPL-5800
• HP PCL Series (USB)	HP compatible USB printers that support HP PCL5 protocol or PostScript3 Printer Control Language. The printers that support PCL5 or later versions will support PCL5 protocol due to the downward compatibility of PCL.



### Axiohm A630



Micro printer from France connects via serial port; please configure communication parameters to match the printer.

### SPRT



Serial printers, please configure communication parameters to match the printer. [Pixels of width] must be correctly set and can't exceed printer default setting "100".

### EPSON TM-L90



Serial printers, please configure communication parameters to match the printer. [Pixels of width] must be correctly set and can't exceed printer default setting "576".

### EPSON TM-T70



Serial printers, please configure communication parameters to match the printer. [Pixels of width] must be correctly set and can't exceed printer default setting "576".

The paper cutting mode can be selected: [No cut] / [Partial cut].

### BRIGHTEK WH-A19



Supported models: A92R10-00E72A
72 in model number represents hexadecimal printer, and A represents wide voltage 5~9V. This is the same as the A6 16 impact printer.

### BRIGHTEK WH-E19



Serial printers, please configure the same communication parameters as the printer.

### BRIGHTEK WH-E22



Supported models:

E22R10-00E725: Same as A7 16 impact printer.
A7 represents A72R90-31E72A.
E221R90-00E11740GA: Serial printer, connects
through RS-485 port, please use a RS232-to-RS485

converter.

### BRIGHTEK WH-C1/C2



Serial printers, please configure communication parameters to match the printer. The paper cutting mode can be selected: [No cut] / [Half cut] / Full cut].

### Remote Printer Server

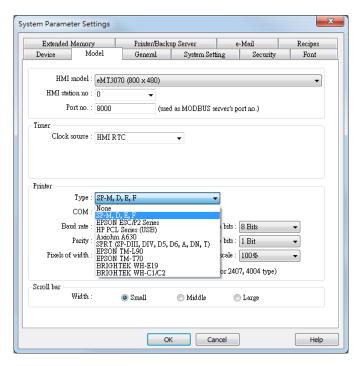


Use EasyPrinter to start printing by the printers connected with PC via Ethernet. This works under MS Windows so most printers on the market are supported.

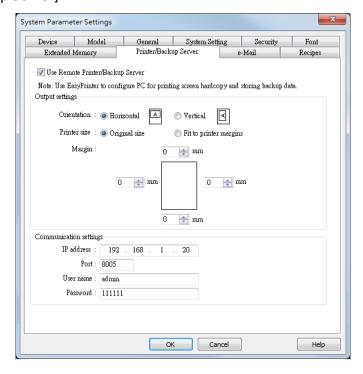


# 23.2. Steps to Add a New Printer and Start Printing

- **1.** Add printer type.
- In [System Parameter Settings] » [Model] select the printer type and set the relevant parameters.



To connect Remote Printer Server, set the parameters in [System Parameter Settings] »
 [Printer/Backup Server].



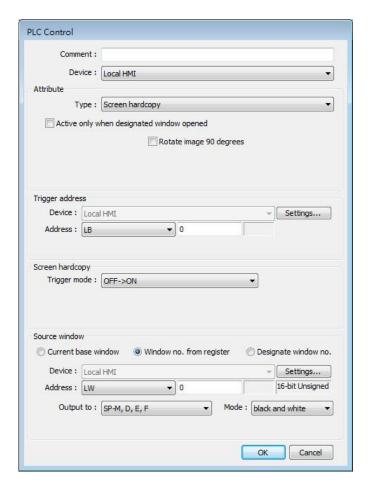


- 2. Start printing.
- Start printing with Function Key.



Or, use PLC Control [Screen hardcopy] to start printing with a designated bit address.





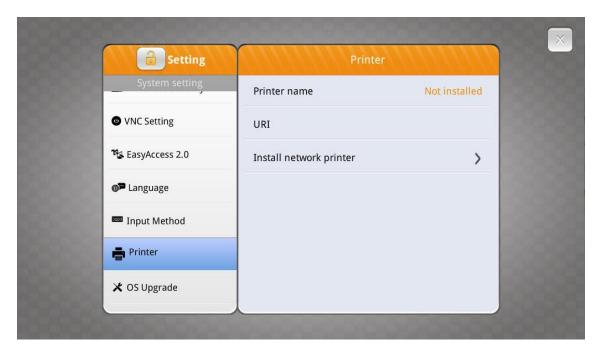
# 23.3. Installing Network Printer on cMT / cMT X HMI

Opening system setting on a cMT / cMT X Series model and selecting [Install network printer] can install more printers apart from the ones listed in the preceding chapters.

1. Tap to open system setting and log in, find [Printer] » [Install network printer].



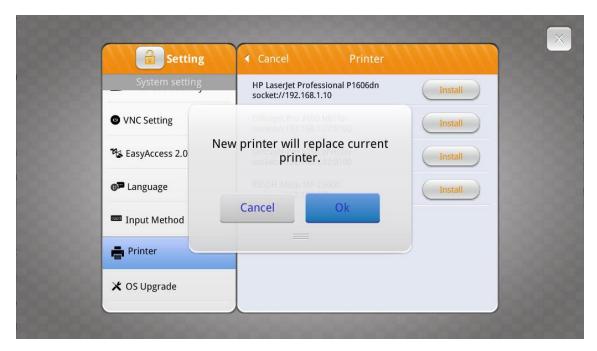
23-8



2. HMI needs a few seconds to search for the network printers on the same network.



**3.** Select a network printer and tap [Install] to install its driver. The new printer driver will replace the former one since only one printer can be installed at a time.



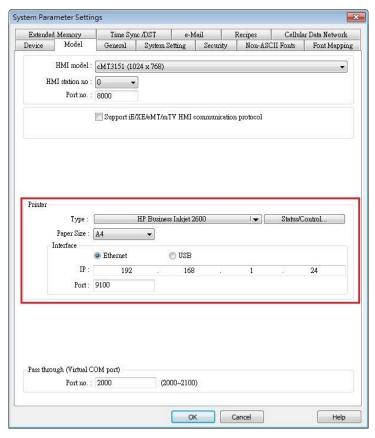
**4.** The network printer is ready for use after installation is completed.



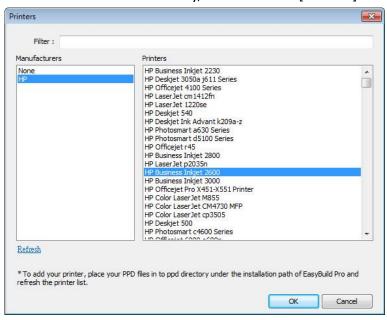
# 23.4. Installing PPD File on cMT / cMT X HMI

Installing the PPD file from a printer driver on a cMT / cMT X Series model is also possible.

1. Go to [System Parameter Settings] » [Model] tab.

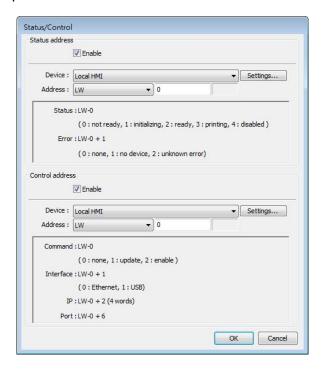


2. Select a printer type. To add a new printer, place the printer's PPD file in the ppd folder under EasyBuilder Pro installation directory, and then click [Refresh].



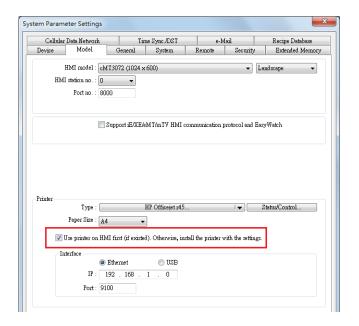


Use Status Address to monitor printer status, and use Control Address to dynamically update connection parameters.





- Installing PPD file is not supported on cMT-SVR and cMT Gateway models.
- HP printers are recommended since they may have better compatibility with cMT / cMT X models. Printers should be tested beforehand.
- Please install a printer on a cMT / cMT X Series model by using [Install network printer] in the system setting first; if this doesn't work, installing PPD file is the second option.
- To use the printer selected in the project file, please do not select [Use printer on HMI first (if existed)] option if a printer driver is already installed on HMI. By giving command 1: update in the control address, the printer selected in the project file will be used.



# 23.5. CUPS Printing Support

The cMT / cMT X Series model process print jobs by using CUPS; therefore, the printer installed on a cMT/cMT X Series model must support CUPS. For more information about CUPS, please visit <a href="https://en.wikipedia.org/wiki/CUPS">https://en.wikipedia.org/wiki/CUPS</a>.

Below are two ways to find out whether a printer supports CUPS:

- Check with your printer's manufacturer.
- Test your printer on a PC running Linux and install a PPD file by following these steps:
- Install CUPS on a Linux PC and make sure that CUPS is working properly. Enter http://localhost:631 in your browser.
- 2. Open the Home tab and select [Adding Printers and Classes].





### **CUPS 1.4.2**

CUPS is the standards-based, open source printing system developed by Apple Inc. for Mac OS® X and other UNIX®-like operating systems.



#### **CUPS for Users CUPS for Administrators** CUPS for Developers Overview of CUPS Adding Printers and Classes Introduction to CUPS Programming Command-Line Printing and Options Managing Operation Policies CUPS API What's New in CUPS 1.4 Filter and Backend Programming Printer Accounting Basics User Forum Server Security HTTP and IPP APIs Using Kerberos Authentication PPD API Using Network Printers Raster API cupsd.conf Reference PPD Compiler Driver Information File Reference Find Printer Drivers Developer Forum

3. Select [Add Printer] under Printers.



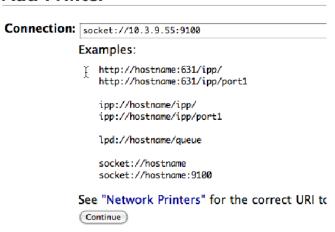
4. In the window that follows, select [AppSocket].





5. Enter the printer's IP address, e.g. socket://10.3.9.55:9100.

### **Add Printer**



6. Enter the printer's name.

### **Add Printer**

Name:	GK420D
	(May contain any printable characters ex
Description:	Ethernet-10.3.9.55
	(Human-readable description such as "H
Location:	LAB
	(Human-readable location such as "Lab :
Connection:	socket://10.3.9.55:9100
Sharing:	☐ Share This Printer
	(Continue)

7. Select the printer's manufacturer and model name. If your printer does not exist in the list, you may ask the manufacturer which is the PPD file you can use for replacement.

### **Add Printer**

Name: GK420D

Description: Ethernet-10.3.9.55

Location: LAB

Connection: socket://10.3.9.55:9100

Sharing: Do Not Share This Printer

Make: Samsung Savin Seiko Sharp Shinko Sony Star Tally

Xerox

Continue



Name: GK420D

Description: Ethernet-10.3.9.55

Location: LAB

Connection: socket://10.3.9.\$5:9100 Sharing: Do Not Share This Printer

Make: Zebra (Select Another Make/Manufacturer)

Model: Zebra CPCL Label Printer (en) Zebra EPL1 Label Printer (en) Zebra EPL2 Label Printer (en)

Or Provide a PPD File: Choose File no file selected

(Add Printer)

After adding the printer, find its PPD file in /etc/cups/ppd in Linux, import the PPD file to 8. EasyBuilder Pro (see 23.4 in this chapter), and then download the project to HMI.

9. If this doesn't work, please contact your nearest Weintek distributor.



# 24. Recipe Editor

This chapter explains how to use Recipe Editor.

24.1.	Overview	24-2
24.2.	Recipe / Extended Memory Editor Setting	24-2
24.3.	Recipe Database Settings	24-4



Recipe Editor 24-2

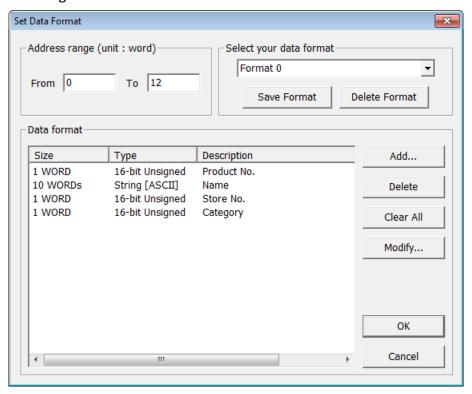
### 24.1. Overview

Recipe Editor is used to create, view, and edit recipe data.

EasyBuilder Pro also provides another tool for editing recipe: Recipe Records. To use this tool; first define a recipe in EasyBuilder Pro [Data/History] » [Recipe Database] tab, and then use [Recipe View Object] to display the content. The following introduces the usage of these two editing tools.

### 24.2. Recipe / Extended Memory Editor Setting

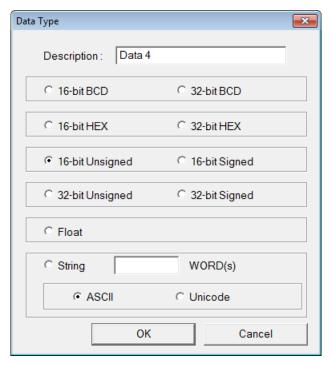
- 1. Open Utility Manager and click [Recipe/Extended Memory Editor].
- 2. To add new .rcp or .emi files, click [File] » [New].
- 3. Set address range and select data format.



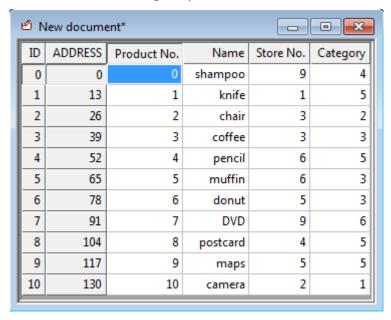
Setting	Description
Address range	Fill in address range, the unit of which is word.
Select your data	Save the specified data format for loading next time.
format	The saved file name is "dataEX.fmt" under
	EasyBuilder Pro's installation directory.
Data format	Edit new data format in this field.



4. Click [Add] to enter a description of the data type, and select data format. When selecting [String], please enter the length (words) and select [ASCII] or [Unicode].



5. After setup, click [OK] to start editing recipe data.



In this example, the total length of data format is 13 words. Each 13 words will be one set of recipe data.

The first set: "product no." = address 0, "Name" = address 1  $\sim$  10, "Store No." = address 11, "Category" = address 12;

The second set: "product no." = address 13, "Name" = address 14 ~ 23, "Store No." = address 24, "Category" = address 25;...and so on.



24-4



**Recipe Editor** 

After editing recipe data, it can be saved as .rcp, .emi, or .csv files. The .rcp files can be downloaded to HMI using Utility Manager or external devices (USB drive or SD card). The .emi files can be saved directly to the external device which is inserted to HMI as extended memory (EM).

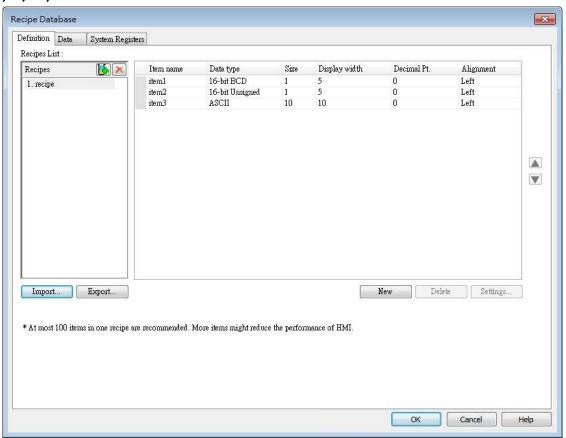
### 24.3. Recipe Database Settings

In EasyBuilder Pro, open [Data/History] » [Recipe Database] to define recipes, set transfer method and edit recipe data.

### 24.3.1. Definition

In Definition tab configure recipe database settings including recipe name, item name, data type...etc.

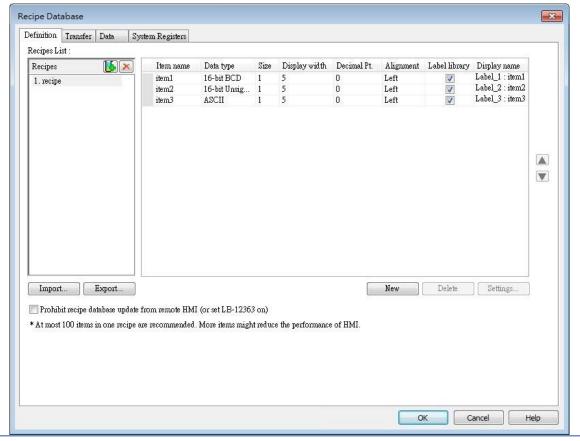
### eMT, iE, XE, mTV Series





Recipe Editor 24-5

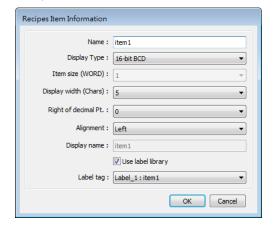
### cMT / cMT X Series



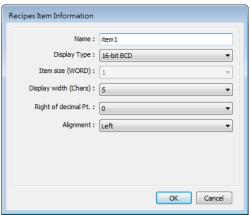
Setting	Description
Recipes List	Add or delete a recipe, the maximum is 100 recipes.
New Add a new item, the maximum is 1000 items.	
Settings	Configure recipe settings, see the following description.
Delete	Delete the selected items.
Import	Import recipe definition.
Export	Export recipe definition. The exported file will not contain
	recipe records.

### Click [Settings]:

### cMT, cMT X Series



eMT, iE, XE, mTV Series





Setting	Description
Name	Enter recipe item name.
Display Type	Setting item data type.
Item size (WORD)	Setting the size of the item.
Display with (Chars)	Setting the number of characters of the item to be displayed.
Right of decimal pt.	Setting the decimal place when displaying data.
Alignment	Setting the alignment when displaying data. [Align left], [Align center], and [Align right] can be selected.
Use label library	On cMT / cMT X series, setting display name is possible. The display name is by default the same as the item name or it may be a tag from Label Tag Library. Please see Chapter 16 Address Tag Library for more details.

#### **24.3.2.** Transfer

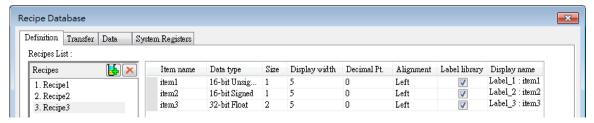
Transfer tab contains the settings for transferring records between the recipe database and designated destinations.

### **Bulk transfer**

Transfer destinations of a record are consecutive addresses starting from the designated address.



Under this mode, the data type settings of destination addresses must follow those of the recipe items. The following table shows the bulk transfer result when LW-0 is designated as the starting address given settings in the following figure.

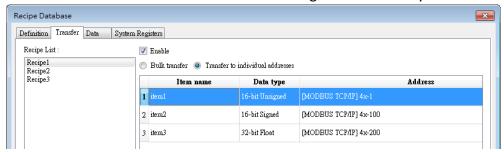




Item Name	Destination	Data Type of Dest. Address
item1	LW-0	16-bit Unsigned
item2	LW-1	32-bit Signed
item3	LW-3	32-bit Float

### Transfer to individual addresses

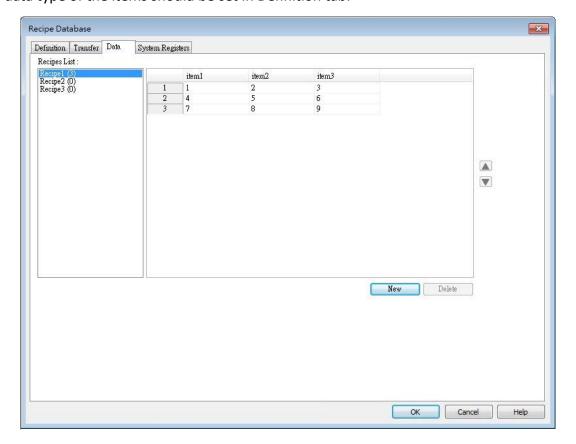
Transfer destination of each item within a record is configured individually.



Under this mode, the data type setting of each destination addresses must also follow those of the corresponding recipe item. In the settings shown above, the data type of address 4x-1 should be 16-bit Signed, and 4x-100 should be 32-bit Signed, and so on.

### 24.3.3. Data

Data tab contains an editor for recipe content. Before recipe content can be edited in this tab, the data type of the items should be set in Definition tab.

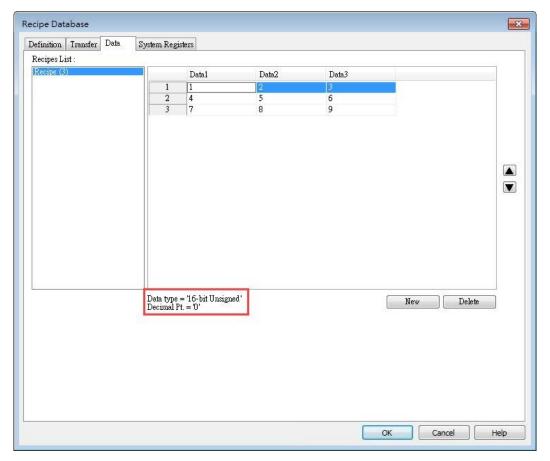




In the example shown above, Recipe created in the Definition tab can be found. Items shown on the right hand side come from item names added in Definition tab. Data of each item name can be configured in this tab following the data type defined in the Definition tab.

Setting	Description		
Recipes:	The recipes created in Definition tab. The number		
	enclosed in brackets shows the total number of		
	records in the corresponding recipe.		
Add	Adds records into the recipe according to the		
	defined data type.		
Delete	Deletes the edited content.		
Up / Down Arrows	Moves the selected record upward / downward.		

To define recipes according to the specified data type, click [Add] button above the record list to insert a new record and start editing each item. When click on the item, the item's data type will be shown under the record list. This helps users to fill in each item with appropriate value. Click [OK] to confirm and save the records.

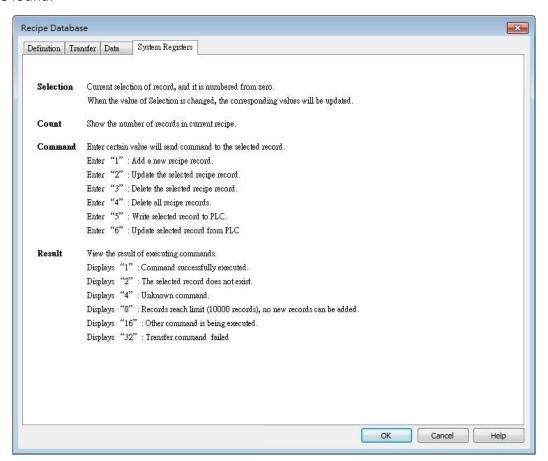




Recipe Editor 24-9

### 24.3.4. System Registers

In System Register tab, a list of recipe database related control addresses and their descriptions can be found.

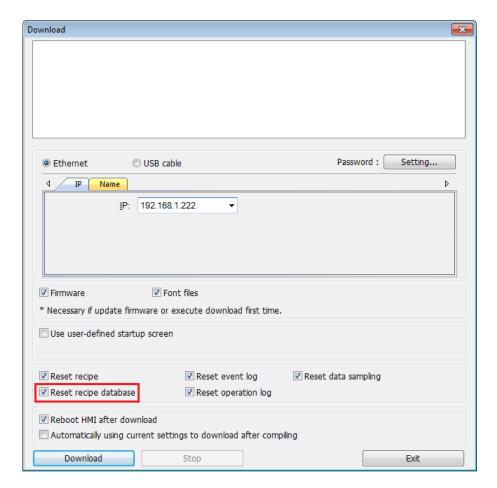




- The maximum number of Recipe Database acceptable in a project file is 100 Recipe Databases. A Recipe Database can contain 1000 items.
- Each recipe can hold a maximum of 10000 records.
- The maximum data length acceptable in a Recipe Database is 2000 words. Exceeding the limit can lead to compilation failure.
- The name of Recipe Database and recipe items should be in alphanumeric.
- The recipe records will be stored in the .exob file after compilation and will be downloaded to HMI. These recipes cannot be shared with other project files. If users need to modify the recipe contents and download them to the HMI, make sure that [Reset recipe database] check box is selected during download. If not, the recipe database in the HMI will not be updated.



Recipe Editor 24-10



Click the icon to watch the demonstration film. Please confirm your internet connection before playing the film.



# 25. EasyConverter

This Chapter explains how to use EasyConverter.

25.1.	Overview	25-2
25.2.	Converting Data Log File to Excel File	25-2
25.3.	Converting Event Log File to Excel File	25-4
25.4.	Converting Operation Log File to Excel File	25-7
25.5.	Converting Multiple Files	25-8
25.6.	Scaling Function	<b>2</b> 5-9
25.7.	Batch File	25-10
25.8.	Examination of Historical Data Integrity	25-14



### 25.1. Overview

EasyConverter can read the HMI's Data Log files, Event Log files, and Operation Log files and convert them to Excel or PDF format.

- From Utility Manager click [Data Conversion] » [EasyConverter].
- From EasyBuilder Pro menu select [Tool] » [Data/Event Log Converter].



Click the icon to watch the demonstration film. Please confirm your internet connection before playing the film.

### 25.2. Converting Data Log File to Excel File

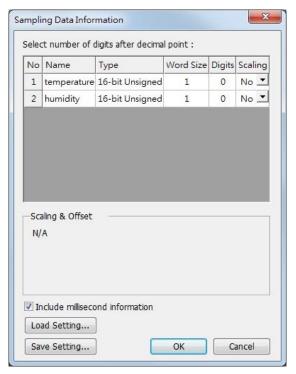
1. If the Data Log file format is .db, and the file includes data of more than one day, the data to be viewed can be specified by selecting a date range. (If the file format is .dtl, please skip this step.)



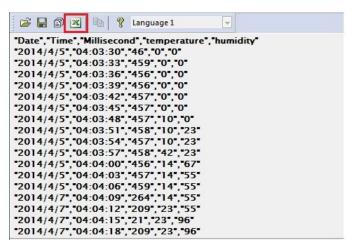
2. The following is the setting dialog box, please set based on actual needs.



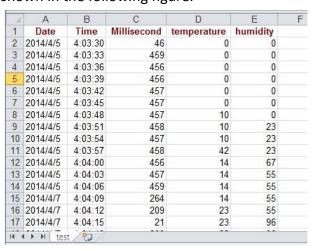
EasyConverter 25-3



**3.** Click [OK], the Data Log layout is shown in the following figure. Click [Export to Excel]. The file will be converted to Excel format.



4. The Excel layout is shown in the following figure.







- If the file requires over six million cells in Excel format, only partial data will be shown in EasyConverter. (The complete data will still be exported to xls / xlsx file.)
- The file will be automatically separated into different sheets in the xls / xlsx file under these conditions:
  - 1. Exceeds 60 thousand rows in a single sheet.
  - 2. Exceeds 1.5 million cells in a single sheet.
- To export the file in PDF format, click [File] » [Save as].

### 25.3. Converting Event Log File to Excel File

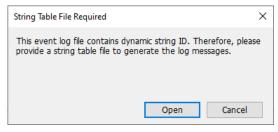
If the Event Log file format is .db, and the file includes data of more than one day, the data
to be viewed can be specified by selecting a date range.
(If the file format is .evt, please skip this step.)



2. If the .db file of Event Log contains multiple languages, the language to be viewed can be specified. (If the file format is .evt, please skip this step.)



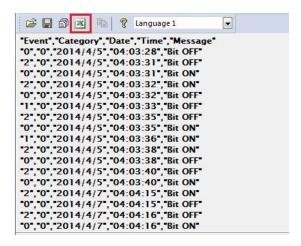
**3.** When the .db file of Event Log contains dynamic string ID, to correctly display the corresponding string of a triggered event, please manually select a .csv file path of string table.



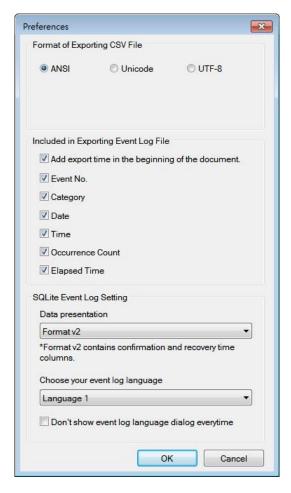
4. Click [OK], the Event Log layout is shown in the following figure. Click [Export to Excel].



The file will be converted to Excel format.



If the format of the opened Event Log file is DB, then in EasyConverter menu » Edit » Preferences » SQLite Event Log Setting, a data presentation format can be selected. When Format v2 is selected, the acknowledge time and recovered time of an event can be displayed in the same row.







5. The Excel layout is shown in the following figure.

34.	Α	В	C	D	E	F
1	Event	Category	Date	Time	Message	
2	0	0	2014/4/5	4:03:28	Bit OFF	
3	2	0	2014/4/5	4:03:31	Bit OFF	
4	0	0	2014/4/5	4:03:31	Bit ON	
5	2	0	2014/4/5	4:03:32	Bit ON	
6	0	0	2014/4/5	4:03:32	Bit OFF	
7	1	0	2014/4/5	4:03:33	Bit OFF	
8	2	0	2014/4/5	4:03:35	Bit OFF	
9	0	0	2014/4/5	4:03:35	Bit ON	
10	1	0	2014/4/5	4:03:36	Bit ON	
11	2	0	2014/4/5	4:03:38	Bit ON	
12	0	0	2014/4/5	4:03:38	Bit OFF	
13	2	0	2014/4/5	4:03:40	Bit OFF	
14	0	0	2014/4/5	4:03:40	Bit ON	
15	2	0	2014/4/7	4:04:15	Bit ON	

4	Α	В	С	D	Е	F	G	Н	1	J	K
1	2022/06/1	1 14:44:26									
2											
3	Category	rigger dat	rigger tim	nowledge	nowledge	covered da	covered ti	Message	urrence Co	lapsed Tim	e
4	0	2022/6/14	11:07:30	*	*	2022/6/14	11:07:30	String Tab	1	0	
5	0	2022/6/14	11:07:31	*	*	2022/6/14	11:07:31	String Tab	2	0	
6	0	2022/6/14	11:07:32	*	*	2022/6/14	11:07:32	String Tab	3	0	
7	0	2022/6/14	11:07:32	*	*	2022/6/14	11:07:33	String Tab	4	1	
8	0	2022/6/14	11:07:34	*	*	2022/6/14	11:07:34	String Tab	5	1	
9											
	← →	event	+								:



- The "Event" column can be found. 0-> Event triggered; 1-> Event acknowledged; 2-> Event returns to normal.
- If the file requires over six million cells in Excel format, opening the file in EasyCoverter only partially shows the data. (The complete data will be exported to xls / xlsx file.)
- The file will be automatically separated into different sheets in the xls / xlsx file under these conditions:
  - 1. Exceeds 60 thousand rows in a single sheet.
  - 2. Exceeds 1.5 million cells in a single sheet.
- When a string table is used, and its .csv file is placed in the same folder as event log's .db file with the same filename (e.g. event log: event.db, string table: event.csv), then the string table can be automatically loaded when loading the .db in EasyConverter; that is, no prompt window pops up asking for the file path of the string table.
- In EasyConverter, the maximum number of rows allowed in a file is 285 thousand rows; that is, the file cannot be opened in EasyConverter after exceeding this limit.



To export the file in PDF format, click [File] » [Save as].

### 25.4. Converting Operation Log File to Excel File

1. If the Operation Log file includes data of more than one day, the data to be viewed can be specified by selecting a date range.



2. Click [OK], the Operation Log layout is shown in the following figure. Click [Export to Excel]. The file will be converted to Excel format.

```
"ID", 'Date', 'Time', 'User, Name', 'Class', 'Window', 'Object, Name', 'Comment', 'Action', 'Address', 'Information' 
"1", '2014/4/28", '06:47:57", "", "10", 'NE_9", "month', "Set word', "LW-9220 (32bit): password', write 111' 
"2", '2014/4/28", '06:47:59", ':noname:, "ADEF', "10", 'NE_4", 'day', 'Set word', 'LW-9020 (16bit): local day', write 29' 
"3", '2014/4/29", '09:48:10", :noname:, "ADEF', "10", 'NE_5", 'hour, 'Set word', 'LW-9019 (16bit): local hour', write 9' 
"4", '2014/4/29", '09:48:10", :noname:, "ADEF', "10", 'NE_2", 'year', 'Set word', 'LW-9022 (16bit): local year', write 2014' 
"5", '2014/4/29", '09:48:16", :noname:, "ADEF', "10", 'NE_6', "minute', 'Set word', 'LW-9018 (16bit): local minute', write 50' 
"7", '2014/4/29", '09:50:20", :noname:, "ADEF', "10", 'NE_6', "month', 'Set word', 'LW-9219 (16bit): user no. (1~12)', write 2" 
"8", '2014/4/29", '09:50:22", :noname:, "ADEF', '10", 'NE_9', "month', 'Set word', 'LW-9220 (32bit): password', 'write 222" 
"9", '2014/4/29", '09:50:26", :noname:, "B", '10", 'NE_3", "month', 'Set word', 'LW-9021 (16bit): local month', 'write 6'
```

3. The Excel layout is shown in the following figure.





- If the file requires over six million cells in Excel format, opening the file in EasyConverter only partially shows the data. (The complete data will be exported to xls / xlsx file.)
- The file will be automatically separated into different sheets in the xls / xlsx file under these conditions:
  - 1. Exceeds 60 thousand rows in a single sheet.
  - 2. Exceeds 1.5 million cells in a single sheet.
- To export the file in PDF format, click [File] » [Save as].

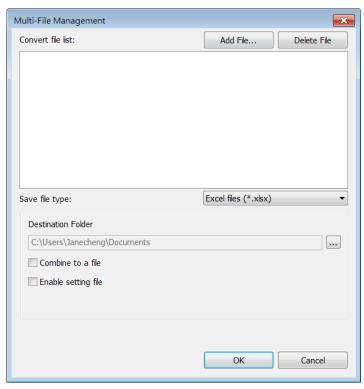


# 25.5. Converting Multiple Files

1. Click [Multi-File] to open the following dialog box.

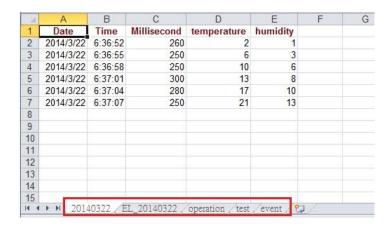


2. Click [Add File...] to add the files to be converted, and then select the file type to save the files as, either [Excel files] or [PDF files]. If [Excel files] is selected without choosing the [Combine to a file] option, the files will be exported to separate Excel files.



**3.** If [Combine to a file] is selected, the files will be separated into different sheets of one Excel file as shown in the following figure.

EasyConverter 25-9





The files cannot be combined when the total size of the files exceeds 32MB.

# 25.6. Scaling Function

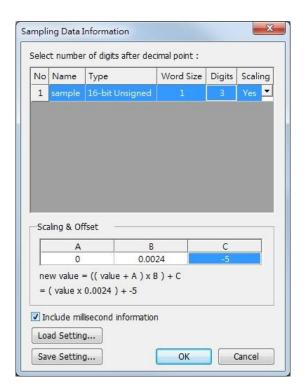
When opening a Data Log file, the scaling function can be set.

The equation of scaling new value =  $[(value + A) \times B] + C$ , and users can set the values of A, B, and C.

A -> lower limit of the value; B -> [(scaled max) - (scaled min) / (upper limit) - (lower limit)]; C -> scaled min.

For example, here is a voltage data with a format of 16-bit unsigned (range: 0 ~ 4096).

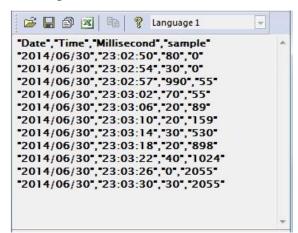
To convert the data to volt, range form -5V to +5V, the new value =  $[(value + 0) \times 0.0024] + (-5)$ .





Before scaling:

# After scaling:



```
"Date", "Time", "Millisecond", "sample"
"2014/06/30", "23:02:50", "80", "-5.000"
"2014/06/30", "23:02:54", "30", "-5.000"
"2014/06/30", "23:03:57", "990", "-4.868"
"2014/06/30", "23:03:02", "70", "-4.868"
"2014/06/30", "23:03:10", "20", "-4.618"
"2014/06/30", "23:03:14", "30", "-3.728"
"2014/06/30", "23:03:18", "20", "-2.845"
"2014/06/30", "23:03:22", "40", "-2.542"
"2014/06/30", "23:03:26", "0", "-0.068"
"2014/06/30", "23:03:30", "30", "-0.068"
```

The settings described above can be saved as a settings file in \*.lgs format, and then loaded next time if needed.

# 25.7. Batch File

EasyConverter command line can execute batch file (.bat), and convert .dtl or .evt files into .xls or .csv files for export. It can also back up historical data from the database to the PC. In the batch file, the user can define the format of the exported file (ex: ASCII, Unicode, or UTF-8), and decide whether or not to include millisecond information or load settings file. The following explains how to create batch file (.bat) and provides some relevant notes.

### Parameters:

[/c{a,8,u}] [/t{0,1}] [/s "Format file"] ["Src file"] ["Dest file"] [/d{0,1,2}] [/l{0,1,2}] [/h "Hostname"] [/n "Data Log Name"] [/g "Config File"] [/i "Time Interval"] ["Dest file"]

# Example:

EasyConverter.exe /ca /t1 /s "C:\Format.lgs" "C:\Src.dtl" "C:\Dest.csv"

EasyConverter.exe /t1 /s "C:\Format.lgs" "C:\Src.dtl" "C:\Dest.xls"

EasyConverter.exe /d1 /l0 /h "hostname" /g "D:\config.ini" /i "5~2" "D:\test\"

EasyConverter.exe /d1 /l1 /h "hostname" /n "log000" /g "D:\config.ini" "D:\test\"

Paramete	r Description
/c{a,8,u}	(Optional) Only required when exporting a CSV file.
	/ca, ASCII (Default)
	/c8, UTF-8
	/cu, Unicode

(Optional) Select whether to include milliseconds.



/t{0,1}

EasyConverter 25-11

	/t0, no millisecond information
	/t1, have millisecond information (Default)
/s	(Optional) To specified data format from source file.
	Specified /s: Need to specify "Format file".
	"Format file", File path of the imported *.lgs file. (e.g.
	"C:\Format.lgs")
/d{0,1,2}	(Optional) To specified database type to open.
	/d0, Open db file
	/d1, Connect to MySQL server
	/d2, Connect to MS-SQL server
/I{0,1,2}	(Optional) Converted log type, must have with MySQL/MS-SQL
	server.
	/IO, Event log
	/I1, Data log
	/I2, Operation log
/h	(Optional) To specified (HMI) hostname of table prefix, must have
	with MySQL/MS-SQL server.
	Specified /h: Need to specify "Hostname"
	"Hostname", hostname of HMI. (e.g. "cMT-XXXX")
/n	(Optional) To specified data log name of table prefix, must have
	when converting data log with MySQL/MS-SQL server.
	Specified /n: Need to specify "Datalog name"
	"Datalog name", data log name of HMI. (e.g. "log000")
/g	(Optional) Specifies the directory of the config.ini file. This
	parameter is necessary when /d1 or /d2 is used.
	e.g.
	/g "D:\config.ini"
	The file can be downloaded by clicking this download icon.
/i	(Optional) To specified relative date interval range
	Specified /i: Need to specify "m~n"
	"m~n", convert relative date range from previous m days ago to
	previous n days, m > n. (e.g. "5~2")
	m: From m days ago at 0:00 to m days ago at 23:59.
	m~n: From m days ago at 0:00 to n days ago at 23:59.
	m~: From m days ago at 0:00 to the last record in the db.
	$^{\sim}$ n: From the first record in the db to n days ago at 23:59.
	e.g. /i "m~n"



"Src file"	(Optional) The path of source file. (e.g. "C:\Src.dtl")
	Acceptable file types: .dtl, .evt, .db
"Dest file"	(Optional) The path of destination file. (e.g. "C:\Dest.xls")
	Determine the format of the file extension, for .xls, .xlsx, .csv, .pdf
	file.



If the file name and path of "Dest file" is not specified in command line, the system will export the file to the same path as "Src file".

You can also find the commands above by entering the file path of EasyConverter.exe in Windows cmd.exe as shown in the following window.

Example: Enter "D:\EasyBuilder\EB Pro>EasyConverter.exe -h"



EasyConverter 25-13

```
C:\Windows\System32\cmd.exe
                                                                                                                                                                                                               ×
D:\SVN_v6.05.02\SW>EasyConverter.exe -h
 sage:
 /c[a,8,n}] [/b{0,1}] [/t{0,1}] [/s "Format file"] ["Src file"] ["Dest file"]
[/d{0,1,2}] [/l{0,1,2}] [/h "Hostname"] [/n "Datalog name"] [/g "Config path"] ["Dest file"]
 example:
CasyConverter.exe /ca /b1 /t1 /s "C:\Format.lgs" "C:\Src.dt1" "C:\Dest.csv"
CasyConverter.exe /t1 /s "C:\Format.lgs" "C:\Src.dt1" "C:\Dest.xls"
CasyConverter.exe /d1 /10 /h "cMT-XXXX" /g "C:\config.ini" "C:\Dest.xls"
CasyConverter.exe /d1 /11 /h "cMT-XXXX" /n "log000" /g "C:\config.ini" "C:\Dest.xls"
CasyConverter.exe /d1 /12 /h "cMT-XXXX" /g "C:\config.ini" "C:\Dest.xls"
/c{a,u,8} -- (Option) Only required when exporting a CSV file.
/ca, ASCII (Default)
/c8, UTF-8
/cu, Unicode
 b{0,1} -- (Option) Add BOM (Byte Order Mark) to file header so that EXCEL can interpret non-ASCII strings correctly.
/b0, do not write BOM
/b1, write BOM (Default)
  t{0,1} -- (Option) Select whether or not to include milliseconds.
/t0, no millisecond information
/t1, have millisecond information (Default)
  s -- (Option) To specified data format from source file.
Specified /s: Need to specify "Format file"
   "Format file", File path of the imported *.lgs file. (e.g. "C:\Format.lgs")
 v -- (Option) To validate if records within database are not modified.
Validation mode only validate database, will not convert files
 d(0,1,2) -- (Option) To specified database type to open.
/d0, Open db file
/d1, Connect to MySQL server
/d2, Connect to MS-SQL server
 l{0,1,2} -- (Option) Converted log type, must have with MySQL/MS-SQL server.
//O, Event log
//I, Data log
//I2, Operation log
  h -- (Option) To specified (HMI)hostname of table prefix, must have with MySQL/MS-SQL server.
Specified /h: Need to specify "Hostname"
   "Hostname", hostname of HMI. (e.g. "cMT-XXXX")
  n -- (Option) To specified data log name of table prefix, must have when converting data log with MySQL/MS-SQL server.
Specified /n: Need to specify "Datalog name"
   "Datalog name", data log name of HMI. (e.g. "log000")
 i -- (Option) To specified relative date interval range
Specified /i: Need to specify "m~n"
   "m~n", convert relative date range from previous m days ago to previous n days, m > n. (e.g. "5~2")
  g -- (Option) To specified connection info file path
Specified /g: Need to specify connection info file path "Connection Info Path"
```

# Example

To convert the file 20150919 stored in "D:\EasyBuilder\EB Pro\HMI\_memory" from .dtl to .xls, and then save the file to the desktop, you can use the following command lines.

**Scene 1:** If the .bat file is placed in the same directory as EasyConverter, then the command line is:

EasyConverter.exe "D:\EasyBuilder\EB Pro\HMI\_memory\20150919.dtl" "C:\Users\Desktop\20150919.xls"

**Scene 2:** If the .bat file is placed in a different directory from EasyConverter, the directory to store EasyConverter.exe. must be specified, and the command line will be:



"D:\EasyBuilder\EB Pro\EasyConverter.exe" "D:\EasyBuilder\EB Pro\HMI\_memory\20150919.dtl" "C:\Users\Desktop\20150919.xls"

# 25.8. Examination of Historical Data Integrity

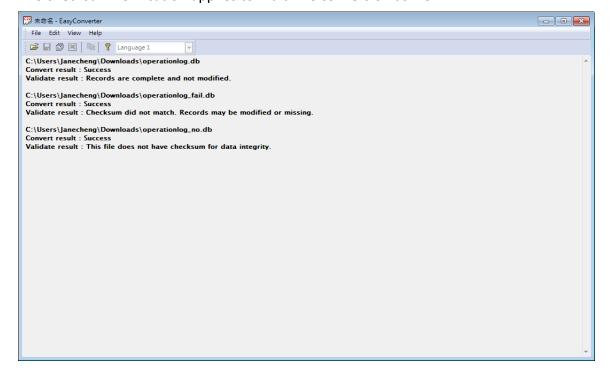
With EasyConverter, the data log / event log / operation log file obtained from backup feature can be checked for data integrity by verifying its checksum. When EasyConverter opens a file that might have been tampered with, an alert window below will pop up.



In EasyConverter's status bar, the checksum verification results are illustrated with the following icons:

- The file does not contain checksum for examining data integrity.
- Checksum did not match. Records may have been modified or missing.
- All records are complete, and no modifications have been made.

The checksum verification applies to multi-file conversion as well.





EasyConverter 25-15

File integrity may also be checked in command line. Use parameter /v to enter verification mode, and no conversion will take place under this mode.

e.g.

EasyConverter.exe /v "C:\Src.db"



# 26. EasyPrinter

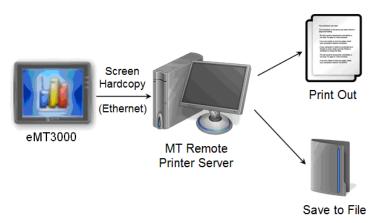
This chapter explains the setup steps of EasyPrinter.

26.1.	Overview	26-2
26.2.	Using EasyPrinter as a Printer Server	26-3
26.3.	Using EasyPrinter as a Backup Sever	26-5
26.4.	EasyPrinter Operation Guide	26-10
26.5.	Convert Batch File	26-15



# 26.1. Overview

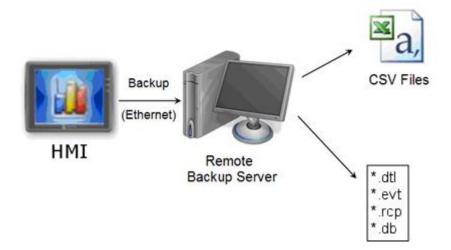
EasyPrinter is a Win32 application and can only run on MS Windows 7 SP1 / 8 / 10. It enables HMI to output screen hardcopies to a remote PC via Ethernet. The following explains how to use EasyPrinter.



Here are some advantages of using EasyPrinter:

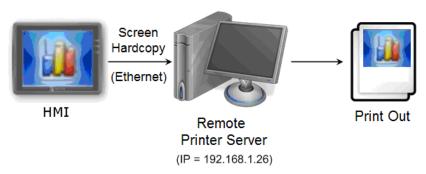
- EasyPrinter provides two modes of hardcopy output: [Print Out] and [Save to File]. Users can use either or both modes.
- Since EasyPrinter runs on MS Windows system, it supports most of the printers available on the market.
- Multiple HMIs can share one printer so users don't have to prepare printers for each HMI.

Additionally, EasyPrinter can also be a backup server. Users can use Backup objects on HMI to copy history files such as Data Sampling records and Event Log to a remote PC via Ethernet. Please see the following illustration:





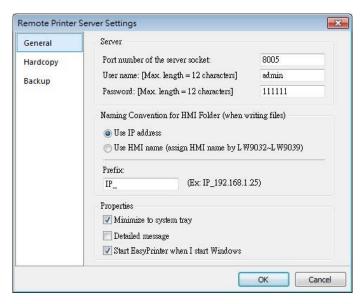
# 26.2. Using EasyPrinter as a Printer Server



Users can make screen hardcopies with a Function Key object. The hardcopies will be transferred to the Remote Printer Server via Ethernet and then printed out.

### 26.2.1. Setup Procedure in EasyPrinter

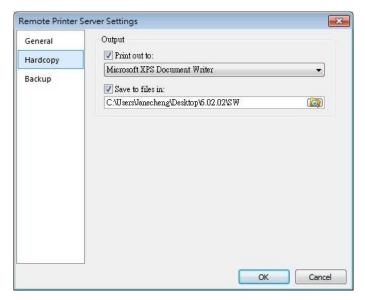
In EasyPrinter's main menu, select [Options] » [Settings] and the following dialog box appears:



- 1. Select [General] on the left hand side.
- 2. In [Server], set [Port number of the server socket] to "8005", [User name] to "admin" and [Password] to "111111". (These are default values.)
- 3. In [Naming Convention for HMI Folder], select [Use IP address] and enter "IP\_" in the [Prefix] field.
- 4. In [Properties], select [Minimize to system tray] check box. Select [Start EasyPrinter when I start Windows] if necessary.

Set the print out location.





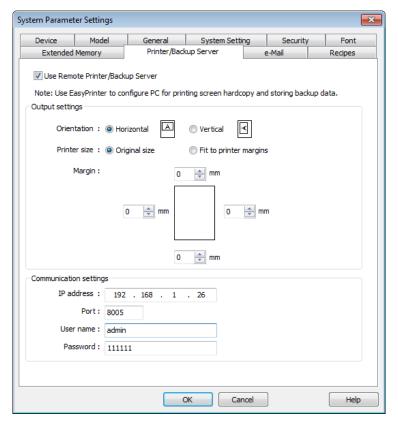
- 1. Select [Hardcopy] on the left hand side.
- 2. Under [Output] select [Print out to] and choose a printer as the output device for screen hardcopies. (The printer shown in the image above is an example; please select an actual printer located in your network environment.)
- 3. Select [Save to files in:] and browse for the directory to save the hardcopy file.
- 4. Click [OK] to confirm the settings.
- 5. In EasyPrinter main menu select [File] » [Enable Output] to output any incoming print request.

### 26.2.2. Setup Procedure in EasyBuilder Pro

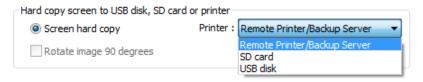
The setting procedure of EasyPrinter in EasyBuilder Pro:

- 1. Open a new project or an existing project in EasyBuilder Pro.
- 2. In EasyBuilder Pro main menu select [Home] » [System Parameters] » [Printer/Backup Server] and select [Use Remote Printer/Backup Server] check box.





- 3. Under [Output settings] set appropriate values for left / top / right / bottom margins. (The margins are all set to 15mm in the example.)
- 4. Under [Communication settings] fill in the [IP address] of the printer server according to the settings in EasyPrinter. Set [Port] to "8005", [User name] to "admin" and [Password] to "111111".
- Click [OK].
- 6. In EasyBuilder Pro main menu select [Objects] » [Button], select [Function Key], select [Screen hardcopy] and set [Printer] to [MT Remote Printer/Backup Server].



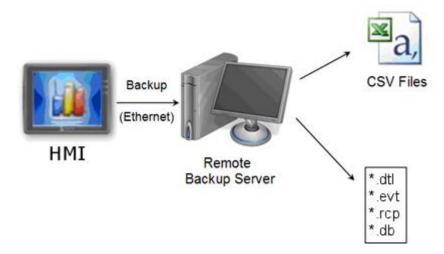
- Place the Function Key object in the common window (window no. 4) so that screen hardcopies can be captured anytime when needed.
- **8.** Compile and download the project to HMI. Press the Function Key object on the screen to make a screen hardcopy.



- A PLC Control object can also be used to make screen hardcopies.
- Alarm information cannot be printed via EasyPrinter.
- EasyPrinter can only communicate with HMI via Ethernet. Please check that the HMI has appropriate network settings.



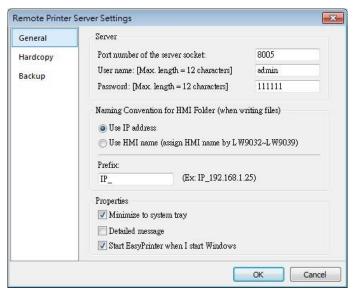
# 26.3. Using EasyPrinter as a Backup Sever



Backup objects can upload historical data and Operation Log to remote backup server.

### 26.3.1. Setup Procedure in EasyPrinter

In EasyPrinter's main menu, select [Objects] » [Settings] and the following dialog box will appear:

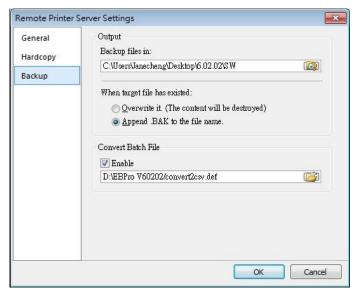


- 1. Select [General] on the left hand side.
- 2. Under [Server] set [Port number of the server socket] to "8005", [User name] to "admin" and [Password] to "111111". (These are default values.)
- 3. Under [Naming Convention for HMI Folder] select [Use IP address] and enter "IP\_" in the [Prefix] field.
- 4. Under [Properties] select [Minimize to system tray]. Select [Start EasyPrinter when I start



Windows] if necessary.

Set the backup location.



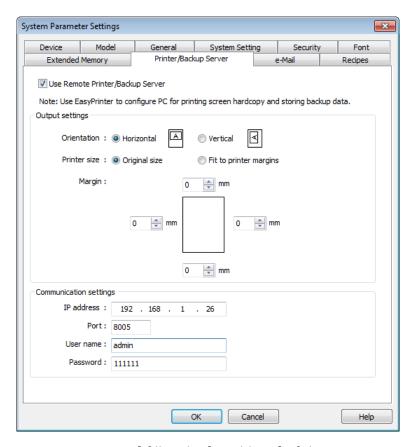
- 1. Select [Backup] on the left.
- 2. Under [Output] click the Dutton to browse and select a storage directory of the incoming history files.
- 3. Click [OK] to confirm the settings.
- 4. In the main menu, select [File] » [Enable Output] to backup data in the selected directory.

### 26.3.2. Setup Procedure in EasyBuilder Pro

The setup procedure of EasyPrinter in EasyBuilder Pro:

- 1. Open a new project or an existing project in EasyBuilder Pro.
- 2. In EasyBuilder Pro's main menu, select [Home] » [System Parameters] » [Printer/Backup Server] and select the [Use Remote Printer/Backup Server] check box.



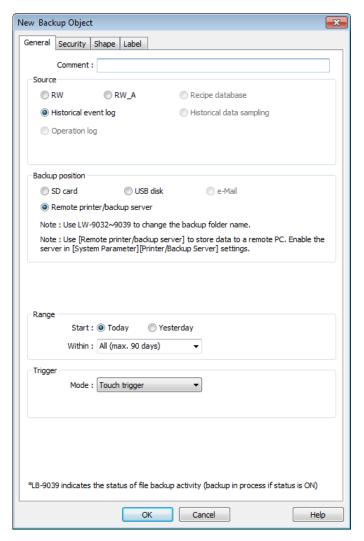


- 3. Under [Communication settings] fill in the [IP address] of the printer server according to the settings in EasyPrinter. Set the [Port] to "8005", [User name] to "admin" and [Password] to "111111". (Note: These are default values.)
- 4. Click [OK].

### Create a Backup object.

 In EasyBuilder Pro's main menu, select [Data/History] » [Backup] and the following dialog box appears:





- 2. Under [Source] select [Historical event log] (or [RW], [RW A] if needed.)
- 3. Under [Backup position] select [Remote printer/backup server].
- 4. Under [Range] select [Today] and [All] (or other options if needed.)
- 5. Under [Trigger] select [Touch trigger].
- **6.** Click [OK].
- 7. Place the [Backup] object in the common window (window no. 4), and users will be able to make backups anytime when needed.
- **8.** Compile and download the project to HMI. Press the Backup object on the screen to make a backup of the history data.



- The Backup object can also be triggered by a bit address.
- Users can arrange a Scheduler object, which turns a bit ON at the end of a week, to trigger the Backup object to automatically back up all history data.

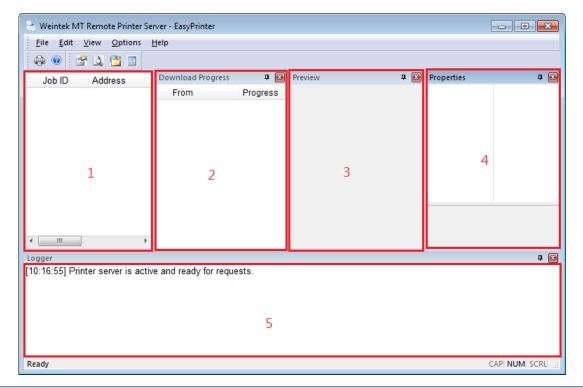


# 26.4. EasyPrinter Operation Guide

The following introduces the interface and operation of EasyPrinter.

# 26.4.1. EasyPrinter Managing Window

EasyPrinter main menu is divided into 5 parts as shown in the following figure:



Area	Name	Description
1	Job List	Lists all incoming tasks, such as screen
		hardcopy and backup requests.
2	<b>Download Progress</b>	Shows the download progress of incoming
		requests.
3	Preview	Shows the preview image of the screen
		hardcopy task selected from [Job List].
4	Properties	Shows the information about the task
		selected from [Job List].
5	Logger	Shows the time and message information of
		events such as incoming request, incorrect
		password, etc.



# 26.4.2. Operation Guide

The following describes the function of EasyPrinter menu items.

Menu	Description	
File	Enable Output	
	If selected, EasyPrinter processes the tasks one by one,	
	otherwise, EasyPrinter stores the tasks in memory.	
Edit	Edit	
	Edits screen hardcopy by setting [Orientation], [Scaling] and	
	[Margins].	
	Delete	
	Deletes the selected tasks permanently.	
	Select All	
	Selects all tasks from [Job List].	
View	Properties Bar	
	Shows or hide the Property Window.	
	Preview Bar	
	Shows or hide the Preview Window.	
	Download Bar	
	In [Download Progress] Window, the mode to display download	
	progress can be set by clicking the header of the [progress]	
	column as shown in the following figure:	
	Download Progress 4 🖎	
	From Progress	
	✓ Percentage Display	
	Data Length Display	
	Logger Bar	
	EasyPrinter can reserve up to 10,000 messages in Message	
	Window. If a new message comes in, the oldest message will be	
	deleted.	
Options	Please see the following page.	



■ EasyPrinter can only reserve up to 128 MB of task data in memory. If the memory is full, any request coming in afterwards will be rejected. Users must either operate [Enable

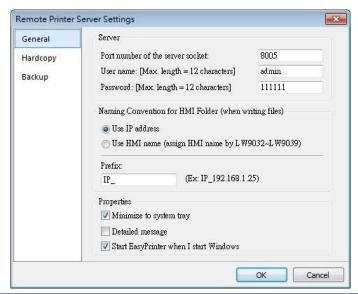


Output] or delete some tasks to make room for new tasks.

- The backup task is not editable.
- [Edit] is available only when a task is selected.
- [Delete] is available when at least one task is selected.

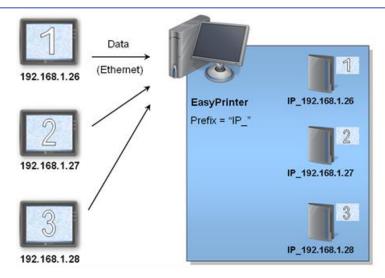
The following is the detail for [Options] » [Settings]

In General Tab:



Setting	Description	
Server	Port number of the server socket	
	Sets the Ethernet port number to connect the HMI. Range: 1 $^{\sim}$	
	65535. Default: 8005.	
	User name / Password	
	Sets the user name and password to let only authorized HMIs send	
	requests to EasyPrinter.	
Naming	EasyPrinter uses different folders to store files (e.g. hardcopy	
Convention	bitmap files, backup files) from different HMI. There are two ways	
for HMI	to name the folders:	
Folder Use IP address		
	EasyPrinter names the folder as [Prefix] + [IP address] after the	
	HMI at this IP address sends request.	





### **Use HMI name**

EasyPrinter names the folder in [Prefix] + [HMI name] after the HMI this name indicates sends request.

### **Properties**

# Minimize to system tray

If this check box is selected, the EasyPrinter shortcut icon will be placed in the system tray in PC. Double click the on icon in system tray to open EasyPrinter.

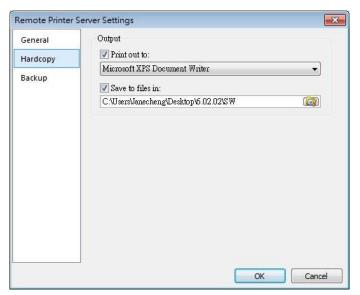
### **Detailed message**

Select this check box to display more detailed messages about events in the message window.

### Start EasyPrinter when I start Windows

Select this check box to automatically run EasyPrinter when Windows starts.

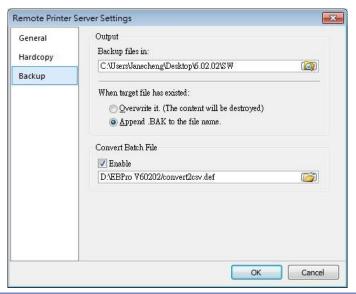
# In Hardcopy Tab:





Setting	Description
Output	Print out to
	EasyPrinter prints out the hardcopy result with the specified
	printers.
	Save to files in
	EasyPrinter converts the hardcopy result into a bitmap file and
	saves it in the specified directory. The bitmap files are found at:
	[Specified Path] \ [HMI Folder] \ yymmdd_hhmm.bmp
	For example, when a hardcopy request is given at 17:35:00,
	12/Jan/2009, the bitmap file will be named "090112_1735.bmp".
	And if there is another bitmap file generated within the same
	minute, it will be named "090112_1735_01.bmp" and so on.

# In Backup Tab:



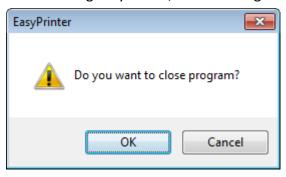
Setting	Description	
Output	Backup files in:	
	EasyPrinter stores the backup files to the specified	
	path.	
	The upper directory is the same:	
	[Specified Path] \ [HMI Name] or [IP address]	
	The lower directory:	
	For Event Log files:	
	\ eventlog\ EL_yyyymmdd.evt	
	For Data Sampling files:	
	\ datalog \ [File name of the Data Sampling] \ yyyymmdd.dtl	



	For Recipe files:	
	\ recipe \ recipe.rcp or recipe_a.rcp	
	For Recipe Database:	
	\recipe \ recipe.db	
	<ul><li>For Operation Log:</li></ul>	
	\operationlog\operationlog.db	
Convert Batch File	Select [Enable] to convert the selected history file	
	to .csv or .xls (Excel) format of Convert Batch Files.	



- System registers LW-9032 to LW-9039 can be used to specify HMI name.
- When closing EasyPrinter, the following dialog will appear.



### 26.5. Convert Batch File

EasyPrinter provides a conversion tool to convert the uploaded Data Sampling and Event Log history files to .csv files automatically. To do so, please select [Enable] under [Convert Batch File] to make EasyPrinter convert the history files.

In the following illustration, the conversion is actually executed by EasyConverter. EasyPrinter simply follows the criteria in Convert Batch File and activates EasyConverter with proper arguments to achieve the conversion.



Convert Batch File + EasyConverter



■ EasyConverter is another Win32 application that converts history data into .csv or MS



Excel .xls files. Users can find it in the EasyBuilder Pro installation directory.

 Users requesting this function must ensure EasyPrinter and EasyConverter are placed in the same directory.

### 26.5.1. The Default Value of Convert Batch File

The following is the default Convert Batch File: convert2csv.def

Listing 1. Default Convert Batch File

1: "dtl", "EasyConverter /c \$( Pathname)"

2: "evt", "EasyConverter /c \$( Pathname)"

There are two lines in the file. Each line has two arguments separated by a comma and forms a criterion of how to process a specific type of files. The first argument stands for the extension name of the file type to be processed. The second argument stands for the command to be executed in console mode. Please note that "\$(Pathname)" is a key word to inform EasyPrinter to replace it with the real name of the converted backup file. For example, if a Data Sampling history file named 20090112.dtl is uploaded and stored, EasyPrinter will send out the following command to a console window:

1: EasyConverter /c 20090112.dtl

A file named 20090112.csv is created.

The criteria of the default Convert Batch File:

- 1. Convert all Data Sampling history files (.dtl) into .csv files.
- 2. Convert all Event Log history files (.evt) into .csv files.



- "\$(Pathname)" in the second argument stands for the full path name of the file. In the previous case, EasyPrinter replaces it with:
  - [Specified Path] \ [HMI Folder] \ [datalog] \ [Folder name of the Data-Sampling object] \ 20090112.dtl
- EasyPrinter interprets the Convert Batch File in line basis, that is, each line forms a criterion.
- Any two arguments should be separated by a comma.
- Every argument should be put in double quotes.
- Do not put any comma inside an argument.
- Supported parameters for batch file: \$(PathName), \$(HmiName), and \$(IP) which stand for file path, HMI name, and HMI IP address.
- When [Start EasyPrinter when I start Windows] option is selected, please add in the file path where EasyConverter is placed, which is usually the EBPro installation directory in



your PC, as shown below.

1: "dtl", "C:\EBPro\EasyConverter /c \$(Pathname)" 2: "evt", "C:\EBPro\EasyConverter /c \$(Pathname)"



For more information, see "25 Easy Converter".

### 26.5.2. **Specialized Criteria**

The specialized criterion are needed when:

- Upload file to a specific HMI, see listing 2.
- Identify the HMI by HMI name, see listing 3.
- Process differently to different Data Sampling, see listing 4.

(This can only be used for Data Sampling file with the file name "voltage".)

The 3rd argument ("\*") indicates this criterion accepts the Data Sampling files that meet the criterion from any HMI. Users can also change the 3rd argument to "192.168.1.26", "192.168.1.\*", or HMI name, etc. for narrowing the range of the target HMI.

Listing 2. Specialized Criterion for the HMI IP: 192.168.1.26

1: "dtl", "EasyConverter /c \$(Pathname)", "192.168.1.26"

Listing 3. Specialized Criterion for HMI name: Weintek 01

1: "dtl", "EasyConverter /c \$(Pathname)", "Weintek\_01"

Listing 4. Specialized Creterion for Data Sampling file name: Voltage

1: "dtl", "EasyConverter /s Voltage.lgs \$(Pathname)", "\*", "Voltage"

### The Format of a Convert Batch File 26.5.3.

The following explains the arguments in a criterion.

HMI IP / Name Condition 1 Condition 2 File Type Command (line)

File Type

This argument specifies the extension name of the uploaded file in this criterion. (e.g. ".dtl" for Data Sampling history files, ".evt" for Event Log history files)

Command (line)

The command EasyPrinter sends to a console window if the uploaded file meets the criterion.

HMI IP / Name

This argument specifies the HMI that meets the criterion.

Condition 1

This argument specifies the folder name of the Data Sampling files that meet the criterion.



This is not effective to other format of files.

Condition 2
 Not used (Reserved for future use).

### 26.5.4. The Order of Examining Criterion

EasyPrinter examines criterion in descending order every time a file is uploaded. Once the file meets a criterion, it stops the examination and starts over for the next file. Therefore, users should place the criterion with a wider range downward in the Convert Batch File and place the more specific criteria upward. For example:

```
"evt", "EasyConverter /c $(Pathname)"

"dtl", "EasyConverter /c $(Pathname)", "192.168.1.26"

"dtl", "EasyConverter /c $(Pathname)", "my_HMI_01"

"dtl", "EasyConverter /c $(Pathname)", "my_HMI_02"

"dtl", "EasyConverter /s Voltage.lgs $(Pathname)", "*", "Voltage"

The correct order of examination would be: (from bottom to top)

"dtl", "EasyConverter /s Voltage.lgs $(Pathname)", "*", "Voltage"
```

"dtl", "EasyConverter /c \$(Pathname)", "my\_HMI\_01"

"dtl", "EasyConverter /c \$(Pathname)", "192.168.1.26"

"dtl", "EasyConverter /c \$(Pathname)", "my\_HMI\_02"

"dtl", "EasyConverter /c \$(Pathname)"

"evt", "EasyConverter /c \$(Pathname)"



# 27. Simulation in EasySimulator / cMT Viewer

This chapter explains how to use EasySimulator / cMT Viewer to run on-line / off-line simulation without having to start the simulator from EasyBuilder Pro.

27.1.	EasySimulator	27-2
27.2	cMT Viewer	27-3



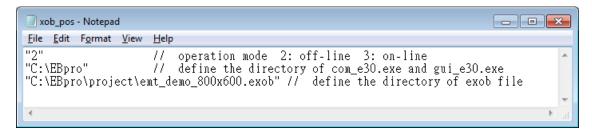
# 27.1. EasySimulator

### **27.1.1.** Overview

EasySimulator allows users to run on-line or off-line simulation for eMT/iE/XE/mTV/iP models without having to start the simulator from EasyBuilder Pro. To do this, please prepare the required files and follow the steps to setup EasySimulator.

### 27.1.2. Steps to setup EasySimulator

- 1. Prepare the following required files and put them into the same folder.
- [driver] → [win32]
- com\_e30.exe
- EasySimulator.exe
- gui e30.exe
- sqlite3.dll
- xob pos.def
- libcurl.dll
- libeay32.dll
- MFC71.dll
- mosquitto.dll
- mosquittopp.dll
- pthreadVC2.dll
- ssleay32.dll
- 2. Open **xob pos.def** by using a text editing tool (e.g. Notepad) and edit the contents.



Line number	Description
1	"2" run an Off-line Simulation; "3" run an On-line Simulation.
2	The directories of the relevant files.
	(e.g. com_e30.exe, gui_e30.exe, EasySimulator.exeetc.)
3	The full path of the .exob file.

- 3. Double click on EasySimulator.exe to start a simulation.
- 4. On-line / Off-line Simulation is displayed on the screen.





- The required files can be found in the EasyBuilder Pro installation directory. Please install EasyBuilder Pro first then copy the required files to your PC.
- If EasySimulator.exe is not activated, please check if the installation directory is correct.
- If the "Failed to open project file: No such file or directory" dialog box appears, this indicates that there is an error of the .exob file path, please check again.

### 27.2. cMT Viewer

### **27.2.1.** Overview

cMT Viewer allows users to run on-line / off-line simulation for cMT/cMT X models without having run EasyBuilder Pro itself.

### 27.2.2. Steps to setup cMT Viewer

- 1. Use a third-party software, e.g. WinRAR, to decompress .cxob file twice and then a project file will be generated in the mt8000 folder.
- 2. Open Command Prompt and then use the commands below.

### **On-line Simulation**

cMTViewer.exe -ns "path/to/project/file" -allinone

### **Off-line Simulation**

cMTViewer.exe -fs "path/to/project/file" -allinone



# 28. EasySystemSetting

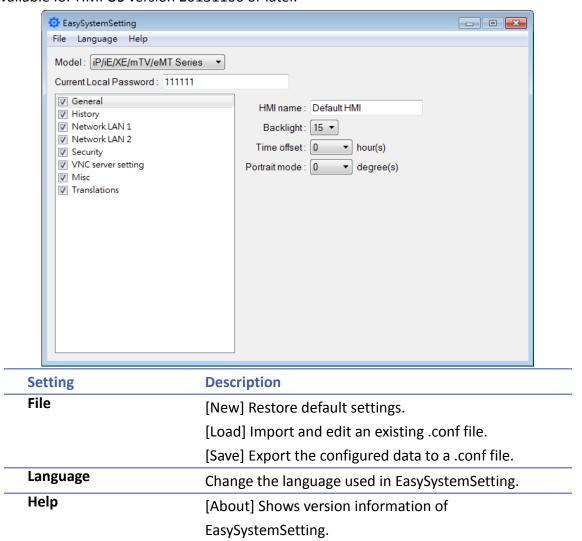
This chapter explains how to use EasySystemSetting.

28.1.	EasySystemSetting	28-2
28.2.	Configuring EasySystemSetting	28-5



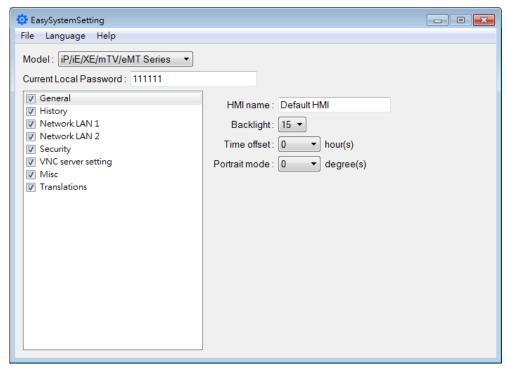
# 28.1. EasySystemSetting

EasySystemSetting allows updating hardware system settings by using a SD card or USB drive. EasySystemSetting can be opened by clicking EasySystemSetting.exe under EasyBuilder Pro installation directory, or clicking [Tool] » [SystemSetting] Editor in EasyBuilder Pro. The feature is available for HMI OS version 20131106 or later.





# iP/iE/XE/mTV/eMT Series

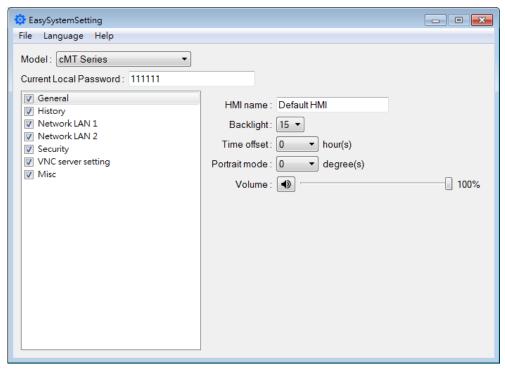


Since the description of system settings can be found in Chapter 4, the following introduces only the General tab.

Setting	Description
Current Local	Please enter the password used to log in System
Password	Parameter Settings.
General	[HMI name] Enter HMI name. The name should only
	contain [A~Z], [a~z], [0~9], [-] and [.].
	[Back light] Adjust LCD backlight brightness.
	[Time offset] Set the HMI RTC with offset.
	For example, if the current RTC time is 15:00:00, and
	the time offset is set to -3, the updated time will be
	12:00:00.
	[Portrait mode] Set the display mode.



# cMT/cMT X Series



Since the description of system settings can be found in Chapter 4, the following introduces only the General tab.

Setting	Description
Current Local Password	Please enter the password used to log in System
Passworu	Parameter Settings.
General	[HMI name] Enter HMI name. The name should only
	contain [A $^z$ ], [a $^z$ ], [0 $^9$ ], [-] and [.].
	[Back light] Adjust LCD backlight brightness.
	[Time offset] Set the HMI RTC with offset.
	For example, if the current RTC time is 15:00:00, and
	the time offset is set to -3, the updated time will be
	12:00:00.
	[Portrait mode] Set the display mode.
	[Volume] Adjust sound volume.

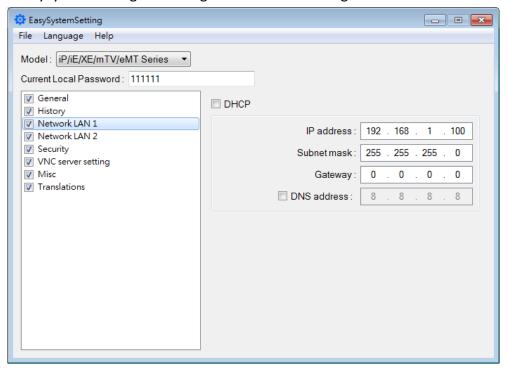


# 28.2. Configuring EasySystemSetting

The following explains how to update HMI IP address by using SD card or USB drive.

# iP/iE/XE/mTV/eMT Series

1. Open EasySystemSetting and change the Network settings as shown below.



- 2. Click [File] » [Save] to generate a "systemsetting.conf" file.
- Close EasySystemSetting.
- **4.** In EasyBuilder Pro click [Build Download Files], select [Use system setting], and browse for the systemsetting.conf file.



- 5. Click [Build] to generate the download file to be saved into the external device.
- 6. Insert the external device that stores the download file to HMI and the Download/Upload dialog box appears.

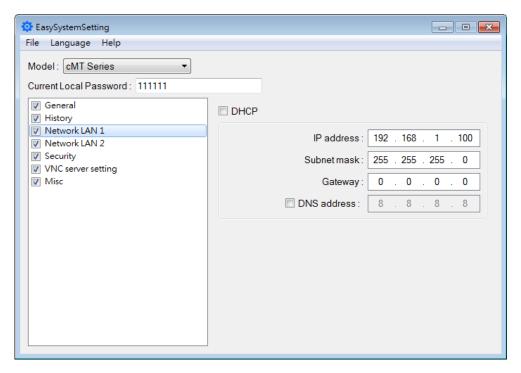


7. Press [Load System setting] and then the [Download Config Settings] message appears.
The project file will be updated after finishing system settings.

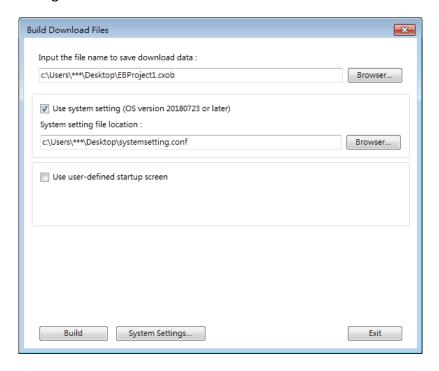
### cMT/cMT X Series

1. Open EasySystemSetting and change the Network settings as shown below.





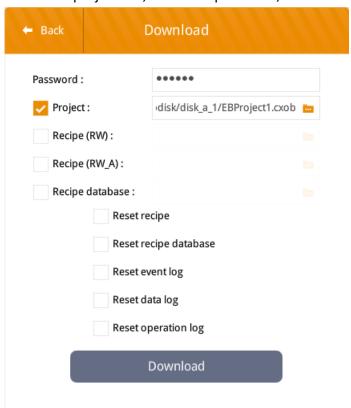
- 2. Click [File] » [Save] to generate a "systemsetting.conf" file.
- Close EasySystemSetting.
- **4.** In EasyBuilder Pro click [Build Download Files], select [Use system setting], and browse for the systemsetting.conf file.



- 5. Click [Build] to generate a compiled file and a system setting file with the same filename (EBProject1.cxob & EBProject1.conf). Save these files in the same directory in an external device.
- 6. Insert the external device to HMI and the Download/Upload dialog box appears; click



Download. Browse for the project file, enter the password, and then click Download.





System setting file can be downloaded using Utility Manager or EasyBuilder Pro.



## 29. Pass-through

This chapter explains how to set up Pass-through mode.

29.1.	Overview	29-2
29.2.	Serial Pass Through Ethernet Mode	29-2
29.3.	Serial Pass-Through COM Port Mode	29-7
29.4.	Pass-through Control	29-9
29.5.	SIEMENS S7-200 PPI and S7-300 MPI Pass-through Settings	29-10
29.6.	Fthernet Pass-Through	29-15



## 29.1. Overview

The Pass-through feature allows PC applications to control PLC via HMI. In this case the HMI is an adaptor.

The Serial Pass-Through feature provides two modes:

- Ethernet
- COM port

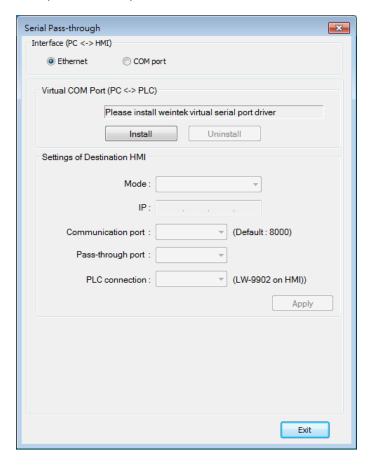
Click [Pass-through] in Utility Manager to open the setting dialog box.

## 29.2. Serial Pass Through Ethernet Mode

#### 29.2.1. Steps to Install Virtual Serial Port Driver

Before using [Ethernet] mode, please check if Weintek virtual serial port driver has been installed. Please always install the latest patch of Windows Update to ensure proper operation of virtual serial port driver.

 Open Utility Manager to check if the driver has been installed. If it shows [Please install weintek virtual serial port driver], please click [Install].





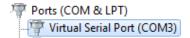
If the dialog below pops up during installation asking for verification, please click [Continue Anyway].



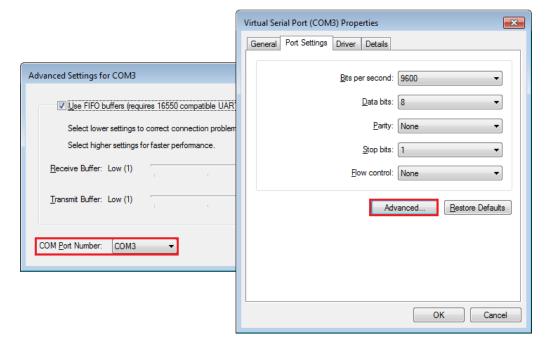
3. When finished, the [Virtual COM Port (PC <-> PLC)] field displays the virtual COM port used.

#### 29.2.2. Steps to Change the Virtual Serial Port Number

1. Open [Device Manager] and find Virtual Serial Port.

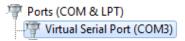


To change to another COM Port Number, double-click Virtual Serial Port and open [Port Settings] » [Advanced].



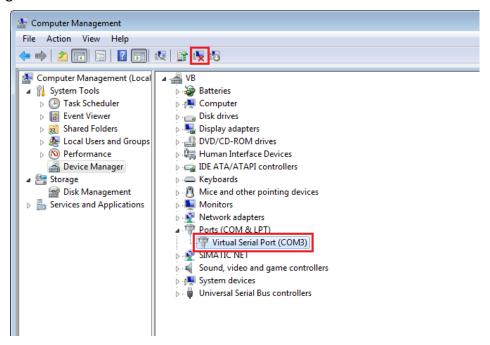
#### 29.2.3. Steps to Uninstall the Virtual Serial Port

1. Open [Device Manager] and find Virtual Serial Port.





To uninstall the Virtual Serial Port, select it and click the [Uninstall] button in the Device Manager toolbar.

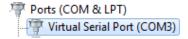


3. Click [OK] to uninstall this Virtual Serial Port.

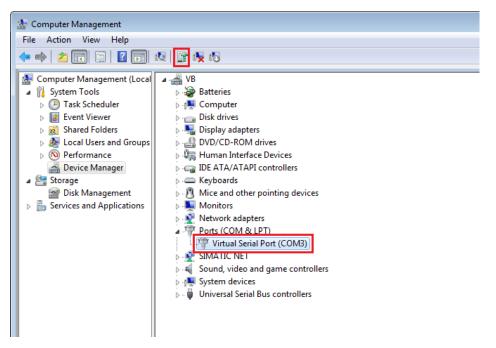


#### 29.2.4. Steps to Update Virtual Serial Port Driver

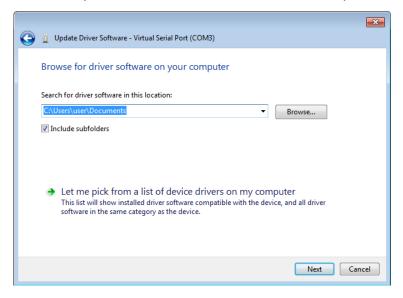
1. Open [Device Manager] and find Virtual Serial Port.



2. To update virtual serial port driver software, select Virtual Serial Port and click the [Update Driver Software] button in the Device Manager toolbar.



3. Browser for the directory of the driver, and then click [Next] to update the driver.

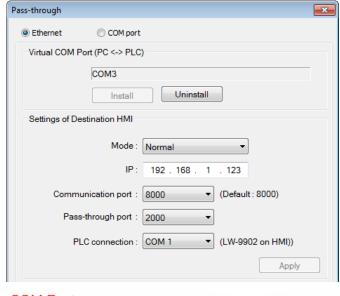


## 29.2.5. Settings of Ethernet mode

After installing the virtual serial port driver, follow the steps to use Ethernet mode of pass-through feature.

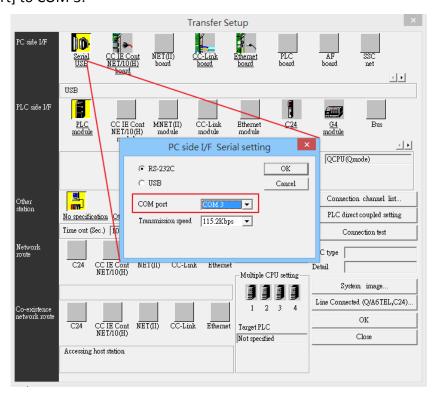
- 1. Set the IP address of the HMI connected with PLC.
- 2. Set the communication port and the serial port that connects HMI with PLC.
- 3. Click [Apply], to apply the settings.







4. When running PC application, set COM port to the used virtual serial port. For example, in Mitsubishi application, if the virtual serial port is COM 3, set [PC side I/F Serial setting] » [COM port] to COM 3.

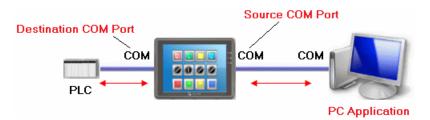


5. With the correct configurations, upon execution of PLC application on PC, HMI will be



automatically switched to Pass-through mode. During Pass-through, the PLC is controlled by PC via the virtual serial port. Pass-through mode will be turned off when the application ends.

## 29.3. Serial Pass-Through COM Port Mode



[Source COM Port] The port connects HMI with PC.

[Destination COM Port] The port connects HMI with PLC.

To use [COM port] mode of Pass-through, please set the properties of Source COM Port and Destination COM Port correctly.

Click the icon to download the demo project. Please confirm your internet connection before downloading the demo project.

## 29.3.1. Settings of COM Port Mode

There are two ways to enable [COM port] mode of Pass-through feature.

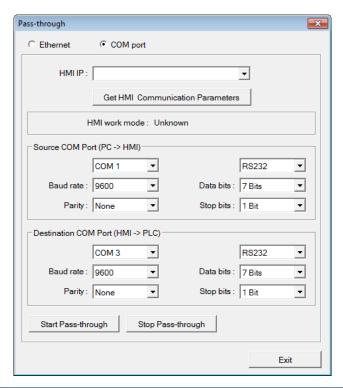
- Using Utility Manager.
- Using system registers.

LW-9901: pass-through source COM port (1  $\sim$  3: COM 1  $\sim$  COM 3) LW-9902: pass-through destination COM port (1  $\sim$  3: COM 1  $\sim$  COM 3)

#### 29.3.2. Using Utility Manager

1. Click [Serial Pass-Through] button in Utility Manager to set the communication parameters as shown in the following figure.





Setting	Description
HMI IP	HMI IP address.
Get HMI Communication	Reads the settings of Source and Destination COM
Parameters	port. Click this button to update the communication
	parameters.
Source COM Port (PC->HMI) /	The communication parameters of Source and
<b>Destination COM Port</b>	Destination COM Port are displayed.
(HMI->PLC)	The settings will be applied when [Start
	Pass-through] is clicked.
Baud rate /	Source and Destination COM Port parameters should
Data bits /	be set to be same. Since [Source COM Port]
Parity /	connects PC, select RS-232 mode in most situations;
Stop bits	[Destination COM Port] connects PLC, so the setting
	depends on the PLC type, and can be one of RS-232,
	RS-485 2W, or RS-485 4W.



When pass-through feature is no longer needed, click [Stop Pass-through] to stop it. HMI will then resume communication with PLC.

There are three work modes of HMI.



Mode	Description	
Unknown	The work mode before reading the settings of HMI.	
Normal	The work mode after reading the settings of HMI.	
	The HMI does not accept any data form the Source	
	COM Port.	
Pass-through	The work mode is "Pass-through." the PC connected	
	via Source COM Port can control the PLC connected	
	via Destination COM Port.	

#### 29.3.3. Using System Registers

Another way of enabling pass-through is by writing to LW-9901(Source COM port) and LW-9902 (Destination COM port). When the values of LW-9901 and LW-9902 match the conditions below, HMI will start Pass-through automatically:

- The values of LW-9901 and LW-9902 are 1 to 3 (1 to 3: COM 1 to COM 3).
- The values of LW-9901 and LW-9902 are different.

To change the communication parameters, just change the value in the related registers and set ON the appropriate registers: [LB-9030: update COM 1 communication parameters], [LB-9031: update COM 2 communication parameters] and [LB-9032: update COM 3 communication parameters]. HMI will then update the settings.



- To stop Pass-through, change the values of LW-9901 and LW-9902 to 0.
- For some models (eMT, cMT...etc), COM1 RS232 RTS/CTS share the same pins (Pin no. 7 and 8) with COM3 RS232 RX/TX. When COM3 is not used in the device list, Pin no. 7 and 8 is used for COM1 RS232. To activate Pin no. 7 and 8 for COM3 RS232 RX/TX, please add COM3's Master Slave driver or Free Protocol driver into the device list in System Parameter Settings.

## 29.4. Pass-through Control

Generally speaking, during pass-through, HMI closes its connection with the PLC until the pass-through mode ends. However, certain PLC drivers allow communications between HMI and PLC in pass-through mode.



To see whether a driver supports concurrent communication, see "PLC Connection Guide".

Pass-through control is controlled by LW-9903. The following table shows valid LW-9903 values and their features.



LW-9903	Description
0 (Default)	Normal Mode. Communications between HMI
	and PLC in pass-through mode is allowed.
2	Stop Mode. No communications between HMI
	and PLC in pass-through mode



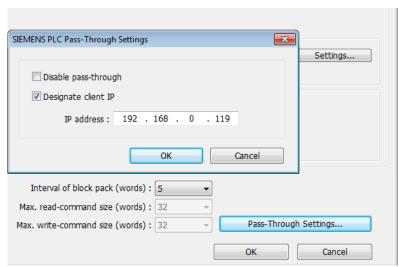
Due to speed limitation, users may wish to set LW-9903 to 2 to enhance the speed of program download/upload in pass-through mode.

## 29.5. SIEMENS S7-200 PPI and S7-300 MPI Pass-through Settings

EasyBuilder Pro supports SIEMENS S7-200 PPI and S7-300 MPI pass-through feature.

### 29.5.1. EasyBuilder Pro Settings

Launch EasyBuilder Pro, go to [System Parameter Settings] » [Device list], and then add SIEMENS S7-200 PPI or S7-300 MPI device. Click [Pass-Through Settings] and the following dialog box appears.



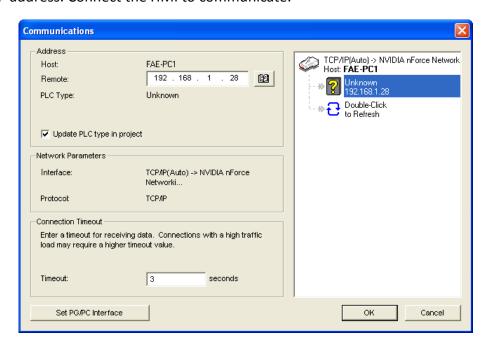
Setting	Description
Disable pass-through	Select this check box to disable pass-through
	mode. By default this check box is not selected.
Designate client IP	Designate client HMI IP address used in
	pass-through mode.

#### 29.5.2. S7-200 PPI Connection

Confirm that the HMI used in pass-through communication is started and connected to the



network. Launch STEP 7 Micro/Win, open [Communications] dialog box, and then search for the HMI IP address. Connect the HMI to communicate.



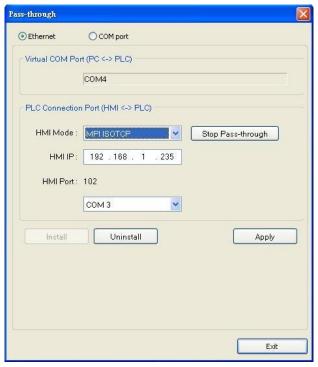
#### 29.5.3. S7-300 MPI Connection

Connect via virtual COM port or Ethernet.

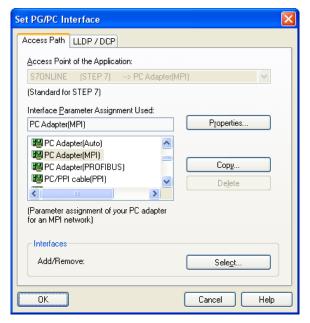
#### 29.5.3.1. Virtual COM Port

 In Utility Manager run [Pass-Through], in [HMI Mode] select "MPI ISOTCP" to install virtual serial port driver. Set the HMI IP address and the COM port that connects PLC, and then start Pass-through.

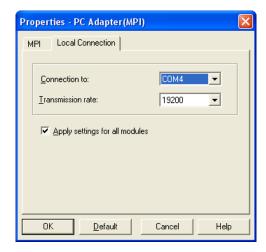




2. In STEP 7, go to [Option] » [Set PG/PC Interface]. Confirm that the interface used is "PC Adapter(MPI)", and then click [Properties]. Select the same COM port as the virtual serial port. In the example COM 4 is used.



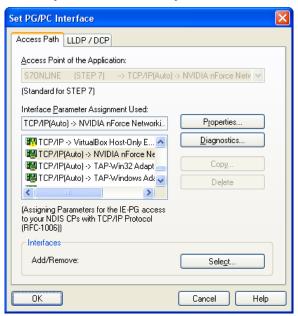




3. When finished, STEP 7 can be used to Upload / Download PLC program via HMI.

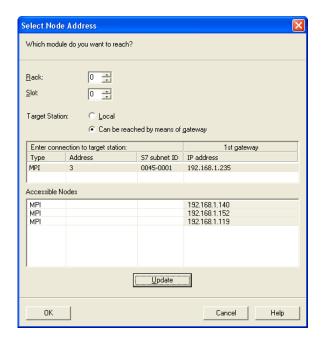
#### 29.5.3.2. Ethernet

1. In STEP 7 go to [Option] » [Set PG/PC Interface]. As shown in the following figure, select "TCP/IP(Auto) -> the name of the network interface card".



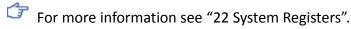
2. Go to [PLC] » [Update station to PG], in [Target Station] select [Can be reached by means of gateway]. From left to right columns enter MPI, PLC station number, S7 Subnet ID, and HMI IP address. When finished, S7 can upload PLC program to STEP 7 via HMI.





## 29.5.4. Registers of SIEMENS Pass-through

System registers from LW-10850 to LW-10864 are used to set or indicate pass-through status of SIEMENS devices.



During pass-through mode, LW-10863 indicates errors and LW-10864 displays error code. The following table lists the error codes, the description of each code, and the possible reason.

(The client usually refers to STEP 7 PLC program)

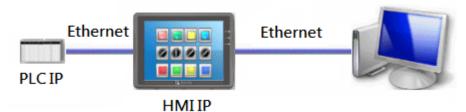
Error Code	Description	Possible Reason
0	Successfully executed	
1	Prohibit client from connecting HMI	HMI is already running pass-through and won't accept any request from other client.
2	Prohibit client from connecting HMI	When LW-10850 is set to 1, the client IP for connecting HMI is different from the IP specified in LW-10858 ~ LW-10861.
3	Invalid communication protocol	Incorrect setting in LW-10853.
4	Invalid PLC station number	The PLC station number specified in LW-10852 does not exist.
5	Delayed communication	PLC connection failure.
6	Busy communication	PLC does not accept pass-through request, please confirm PLC settings.
7	Invalid pass-through request	Environment setup failure.

Click the icon to download the demo project. Please confirm your internet connection before downloading the demo project.



## 29.6. Ethernet Pass-Through

Ethernet Pass-through feature is available when both PLC and PC connect to HMI via Ethernet. Ethernet Pass-through allows running the application on PC to control PLC through HMI. This feature is only supported on cMT / cMT X Series models.

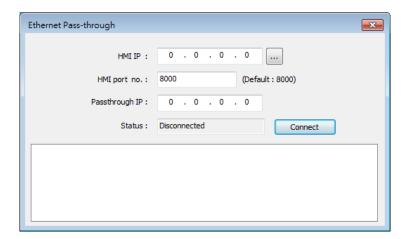


1. Launch Utility Manager, select cMT / cMT X Series, and then open Analysis & Testing tab in which Ethernet Pass-through can be found.



2. Click [Ethernet Pass-through] and then fill in the communication parameters.





Setting	Description
HMI IP	Enter HMI's IP address.
HMI port no.	Enter the port number used to connect to HMI.
	By default the port number is 8000.
Passthrough IP	Enter the IP address of the device to be
	controlled under Ethernet Pass-through mode.
Status	After filling in the communication parameters,
	click [Connect] to see the connection status.



- One HMI can only use one Ethernet Pass-through IP.
- Ethernet Pass-through feature is disabled when system register LB-9044 (disable remote control) is ON.

## 30. Project Protection

This chapter explains the settings relevant to project protection.

30.1.	Overview	. 30-2
30.2.	EXOB/CXOB Password	. 30-2
30.3.	Decompilation is Prohibited	. 30-3
30.4.	Disable HMI Upload Function	. 30-3
30.5.	Project Key	. 30-3
30.6.	MTP File Password	. 30-4



## 30.1. Overview

EasyBuilder Pro provides a number of features to protect a project file.

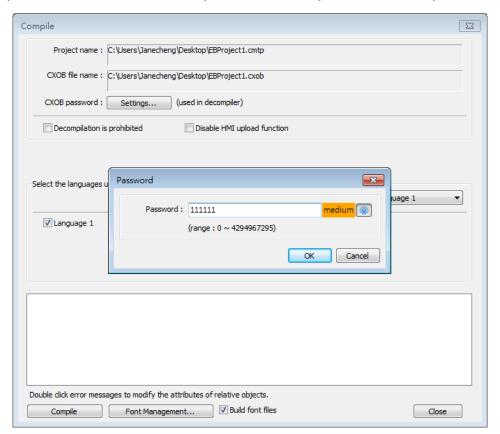


The protected projects cannot be decrypted by the factory since they are encrypted by users; therefore, please remember your password.

## 30.2. EXOB/CXOB Password

After editing a project (.emtp/.cmtp), users can compile the project to .exob/.cxob format. The .exob/.cxob file can be downloaded to HMI. Password can be set to protect the .exob/.cxob file in [EXOB/CXOB password] when compiling. (Password range: 0 ~ 4294967295)

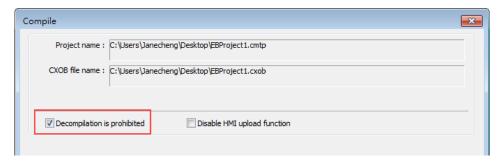
A password is needed when attempting to decompile the .exob/.cxob file back to .emtp/.cmtp file. If the password is entered incorrectly for three times, please restart EasyBuilder Pro.





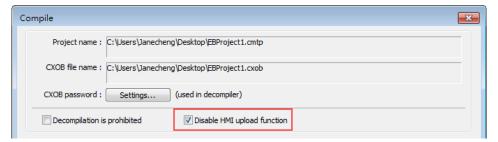
## 30.3. Decompilation is Prohibited

After a project (.emtp/.cmtp) is edited, users can compile the project to .exob/.cxob format. The .exob/.cxob file can be downloaded to HMI. If [Decompilation is prohibited] check box is selected when compiling, the setting in [EXOB/CXOB password] will be ignored. Furthermore, the .exob/.cxob file cannot be decompiled to .emtp/.cmtp file.



## 30.4. Disable HMI Upload Function

EasyBuilder Pro provides a system reserved register [LB-9033]. When this register is set ON, the .exob/.cxob file cannot be uploaded. When attempting to upload an .exob/.cxob file with this register set ON, the file obtained after uploading is 0 byte, and cannot be decompiled. Please reboot HMI for the changed setting to take effect.



## 30.5. Project Key

Projects can be restricted to run on a specific HMI.

The setting is in [System Parameters] » [General] » [Project key].



Enable and set the [Project key] (password range:  $0 \sim 4294901750$ ). System registers LW-9046  $\sim$  LW-9047 (32-bit) can be used to set the [HMI key] for HMI. The values in LW-9046 and



30-4

LW-9047 cannot be accessed by a remote device. The .exob/.cxob file obtained after compiling can only be executed on HMI when [HMI key] and [Project key] match. If the keys don't match, LB-9046 is set ON. To change [HMI key], please reboot HMI.



When [HMI key] and [Project key] don't match, HMI and PLC cannot communicate.



Click the icon to download the demo project. Please confirm your internet connection.

#### 30.6. **MTP File Password**

After a project (.emtp/.cmtp) is edited, a password can be set to protect the .emtp/.cmtp file. In [System Parameters] » [Security] tab, enable [Project password] and click [Settings] (password range: 1 ~ 4294967295).

The password will be needed when attempting to open the .emtp/.cmtp file.





When using "Window Copy" function, if the source file is protected by MTP password, please enter the correct password for the system to execute window copy.

# 31.cMT Diagnoser

This chapter explains cMT Diagnoser which allows diagnostic operations in cMT / cMT X Series Model.

31.1.	Overview	31-2
31.2.	How to Start Diagnoser	31-2
31.3.	cMT Diagnoser User Interface	31-4
31.4.	Additional Notes	. 31-18



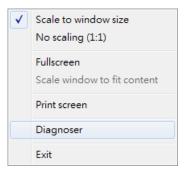
### 31.1. Overview

cMT Diagnoser can monitor data and status of all objects in the current window when it is connected to an HMI, show the status of individual communication packet, show communication status with MQTT server, and debug macros.

## 31.2. How to Start Diagnoser

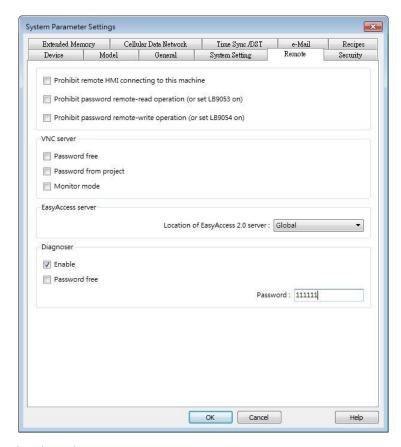
cMT Diagnoser can be used in simulation mode or on HMI. When it is used on HMI, it can be opened from within cMT Viewer, or run an independent program named as cMT Diagnoser be directly opened on HMI.

1. In on-line/off-line simulation, cMT Diagnoser can be opened by clicking the right mouse button in cMT Viewer simulation screen and then click Diagnoser.

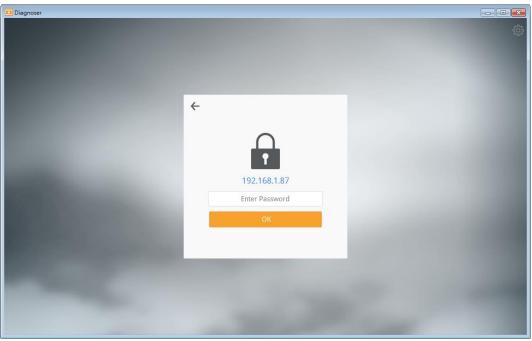


2. To permit connection to HMI from cMT Diagnoser, enable the Diagnoser option which is found in the [System Parameters] » [Remote] tab in EasyBuilder Pro.



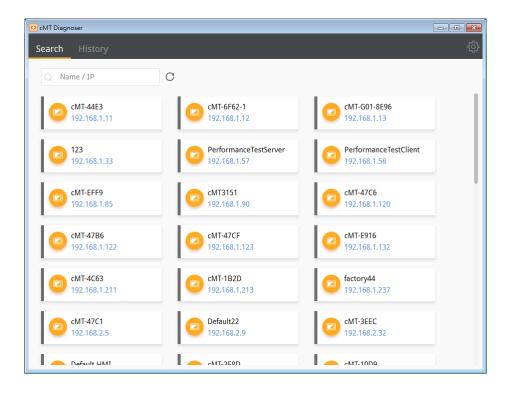


After downloading the project to HMI, cMT Viewer can open cMT Diagnoser. If [Password free] is not selected in Remote tab in previous step, a password is required for running cMT Diagnoser.



**3.** Execute cMTDiagnoser.exe, which can be run independently, in EasyBuilder Pro installation directory, and find an HMI to connect to.

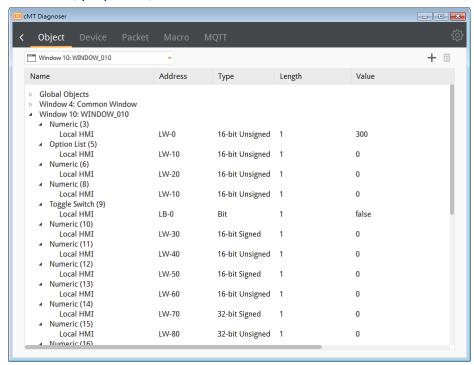




## 31.3. cMT Diagnoser User Interface

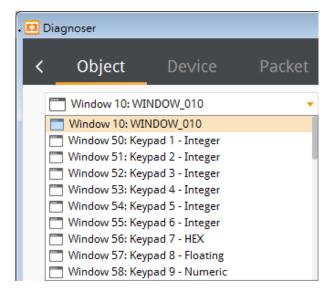
#### 31.3.1. Object Settings

1. In the Object tab in cMT Diagnoser user interface, the objects used in the current window and their addresses, properties, and statuses are shown in a table.

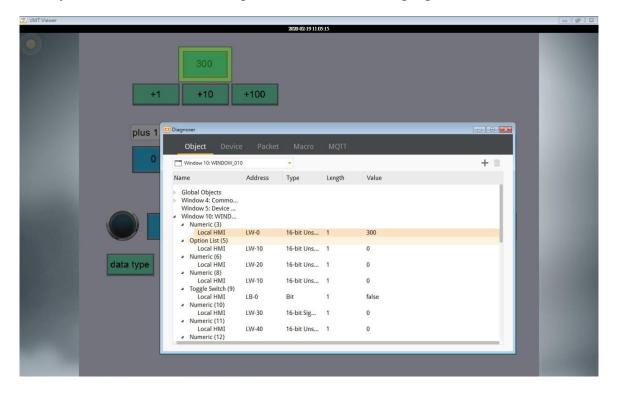


2. Selecting a window from the drop-down list can quickly change to another window.

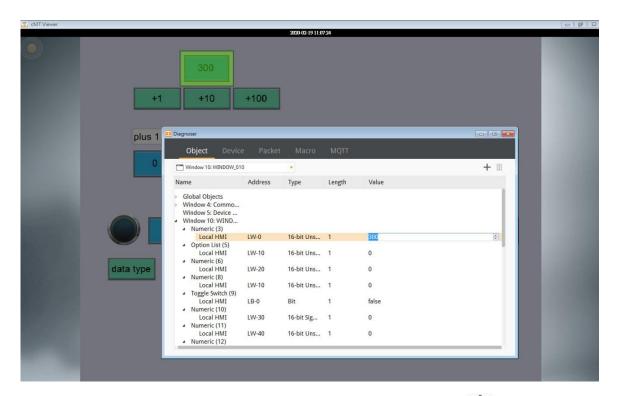




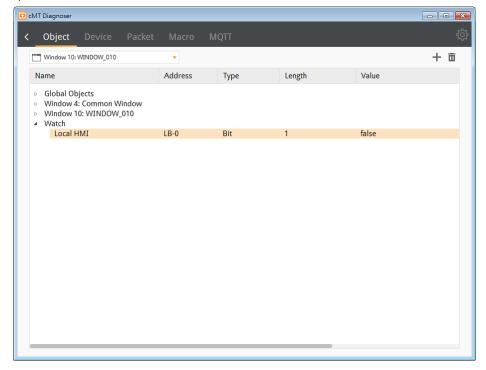
3. The object selected in the cMT Diagnoser window will be highlighted as shown below.



4. The value of an object can be changed by double-clicking on it in cMT Diagnoser window.

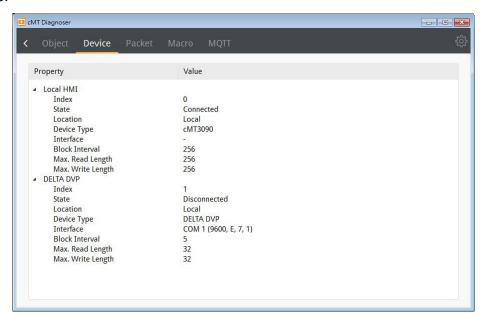


5. In cMT Diagnoser, watch addresses can be added or deleted. Click to add a new address, or select an address and then click to delete it.



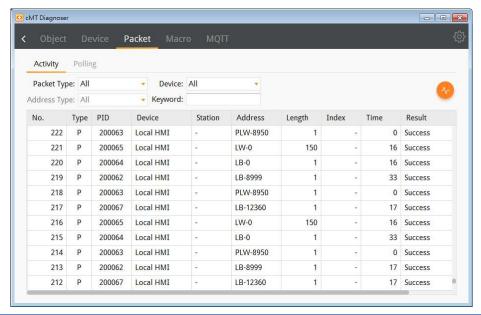
## 31.3.2. Device Settings

 The state and property of the device communicating with HMI is shown in the Device tab.



#### 31.3.3. Packet Settings

 In the Packet tab, select the ranges and then click to observe communication status between HMI and PLC.

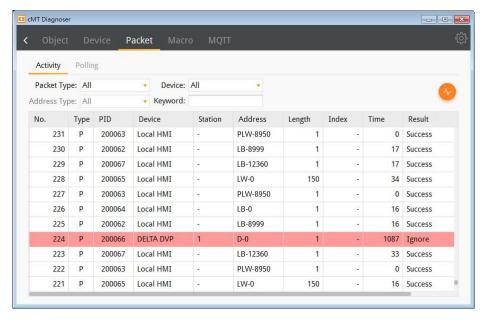


Item	Description
Packet	All
Туре	Displays all packets in Activity area.
	Read



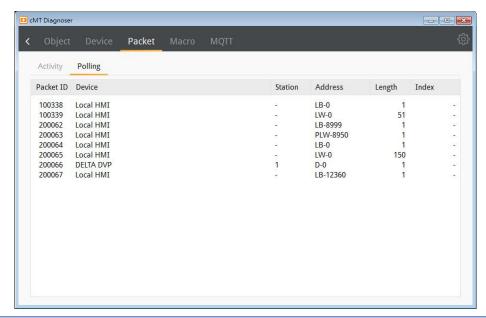
	Displays only Read packets in Activity area.
	Write
	Displays only Write packets in Activity area.
	Polling
	Displays only Polling packets in Activity area.
Device	All
	Displays the information of Local HMI and PLC.
	Local HMI
	Displays the information of Local HMI.
	PLC
	Displays the information of PLC.
Station	Selects the PLC station number to be displayed.
	(This function is disabled when selecting [All] in [Device].)
Address	Selects all or a preferred address type to be displayed.
Туре	(This function is disabled when selecting [All] in [Device].)
Keyword	Displays information that contains the keyword entered.

When communication error occurs, information relating to the error will be highlighted in red in the Activity page, and the cause of error is shown in the Result column.



2. The Polling page shows the information of the polling packets periodically sent from HMI, including the start address, length...etc.

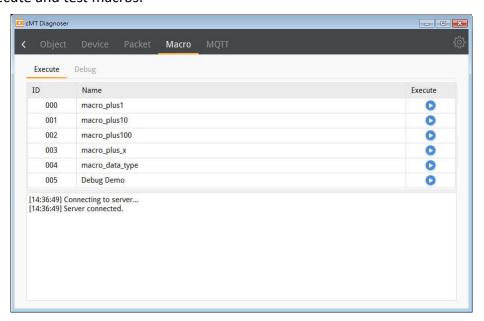




Item	Description
Packet ID	Use the Packet ID to find the invalid object.
Device	Displays HMI and PLC type.
Station	Displays PLC station number.
Address/Length	Displays the device type and the size of the packet.
Index	Displays the index register number of the object.

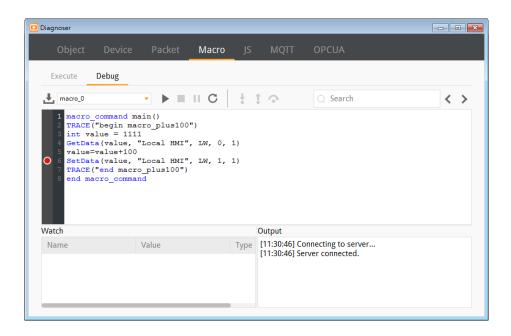
## 31.3.4. Macro Settings

1. Execute and test macros.



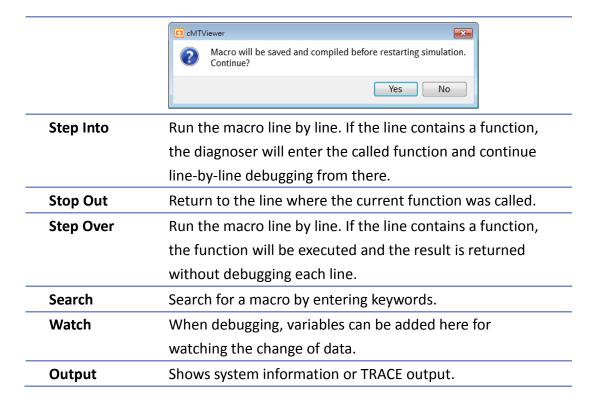
2. Macro Debugger Tool.





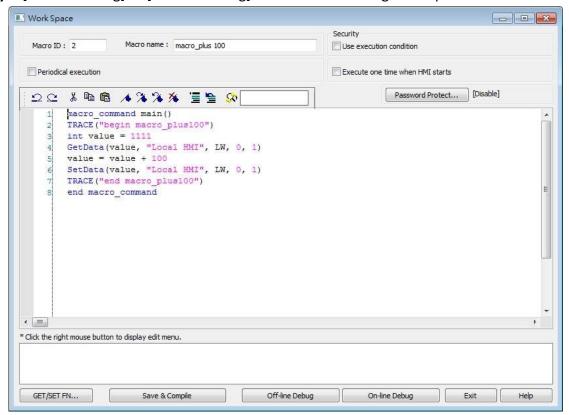
Item	Description
Load	Macro Debug File can be generated when compiling a
macro	project file in EasyBuilder Pro, and it is placed in the same
debug file	directory as the compilation file. Macro Debug File has a
	file name extension of ".debug". When an unmatched
	debug file is loaded, the following message window
	shows.
	cMT Diagnoser
	This debug file cannot be used with current project.
	OK
Start	Chart delevering an average manage frame a baseling sint
debugging	Start debugging or execute macro from a breakpoint.
Stop	Stan dahugging
debugging	Stop debugging.
Break	Pause macro debugging manually. A Breakpoint can be set
	at a statement by clicking the grey margin on the left-hand
	side of the statement. When a macro is launched, it will
	run until the Breakpoint, and wait for the next command.
Restart	After running on-line / off-line simulation in macro work
simulation	space, the macro can be revised directly in the Diagnoser
	window. After revising the macro, the simulation can be
	restarted by clicking Restart Simulation, and then the





Macro Debug in cMT Diagnoser can be opened in the following ways, each with different privilege requirements and operation steps.

Way1. [On-line Debug] or [Off-line Debug] within macro editing work space.



Click [On-line Debug] or [Off-line Debug]. Software will generate a Macro Debug File. Also,



macro editing work space window will close and be replaced by cMT Viewer simulation and cMT Diagnoser, the latter of which loads the Macro Debug File automatically. When the macro is being debugged in cMT Diagnoser's, the macro codes can actually be modified.

Upon completing macro debugging, close the cMT Viewer simulation. The macro editing work space should appear again, and it will ask whether you want to update the macro with the changes made in cMT Diagnoser.

Way2. On-line simulation / off-line simulation in EasyBuilder Pro.

The Macro Debug File is automatically generated after compiling the project file. When cMT Viewer simulation window is shown by running simulation in EasyBuilder Pro, open cMT Diagnoser from the right-click menu. The system imports the debug file automatically when it detects one. In simulation mode, macro can only be debugged but not changed.

Note: There must be at least one macro in the project for the Macro Debug File to be generated during compilation.

**Way3.** Downloading the project file to HMI and then running cMT Diagnoser. The Macro Debug File should be manually imported in the Macro Debugger, and under this

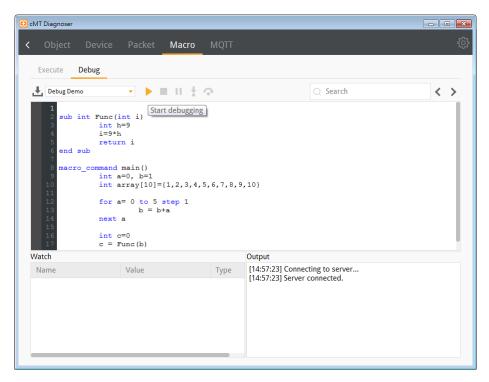
mode the macro can only be debugged but not changed.

#### An Example of Macro Debugging

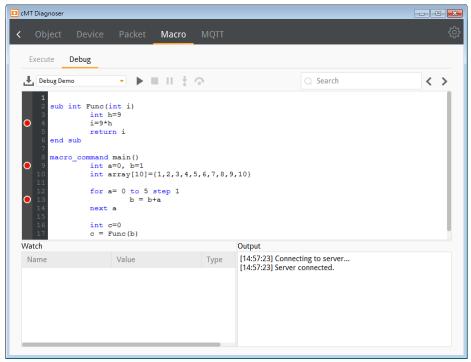
The following steps show an example about how to debug macro.

1. Click [Start Debugging].



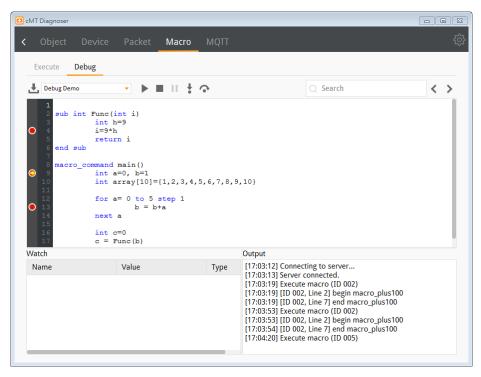


2. Set Breakpoints in the grey margin on the left-hand side of the lines. The Breakpoints are represented by red dots.

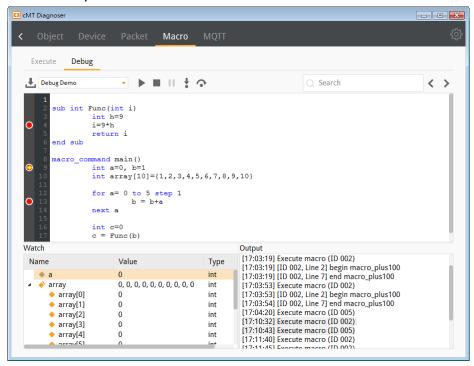


**3.** After debugging is started, it will stop at the first breakpoint, now marked by a yellow arrow.



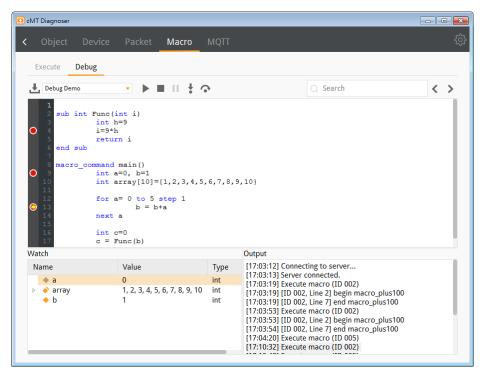


4. At this moment, variables can be added monitored in the Watch table as shown below.
Contents of arrays can be monitored as well.

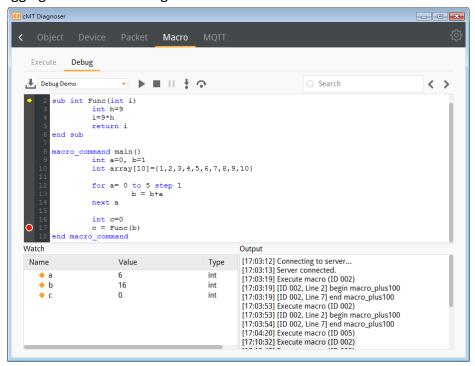


5. After the Start Debugging button is clicked once again, macro will run and stop at the next breakpoint. The changes of values are shown in the Watch list.



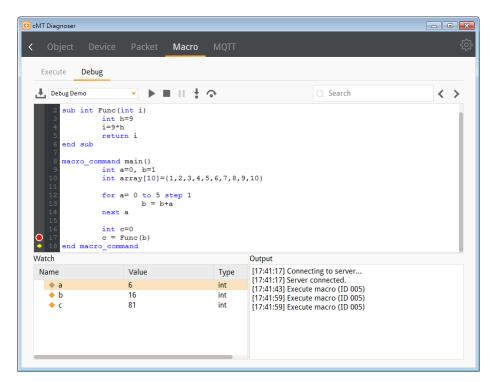


6. Click the Step Into button to run macro debugging line by line. If the line contains a function, cMT Diagnoser will enter the called function and continue line-by-line debugging from there. Changes of values can be observed in the Watch table.

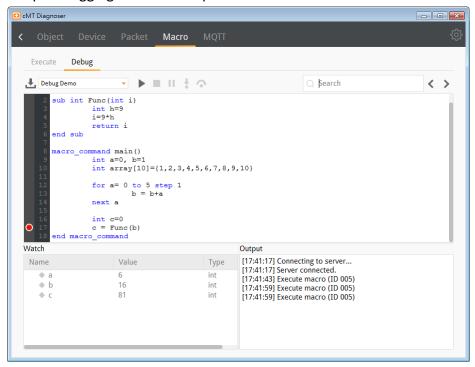


7. Click the Step Over button to run the macro line by line. Now, if the line contains a function, the result will be returned without debugging each line within the function call. When debugging meets a Breakpoint within the function call though, it stops there.





8. Click Stop Debugging button to stop.

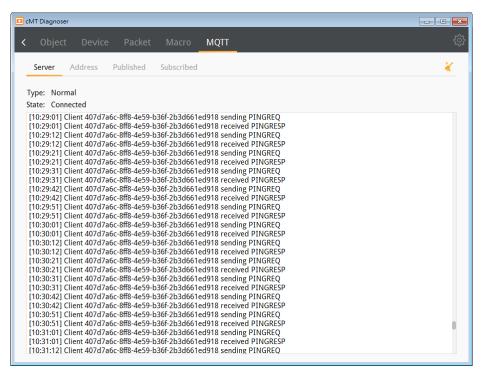


## 31.3.5. MQTT Settings

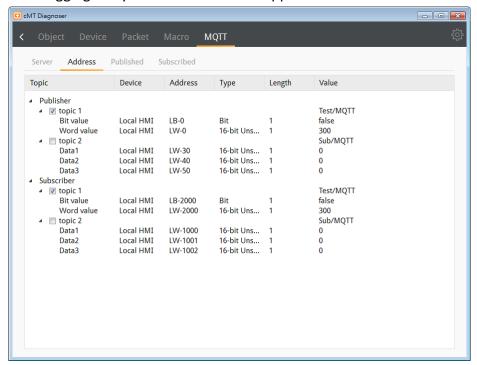
In Server tab the type and state of MQTT server is shown. Supported cloud services
include: Normal / Azure IoT Hub / Sparkplug / Google Cloud IoT Core. Please note that
AWS IoT is not supported.



cMT Diagnoser 31-17

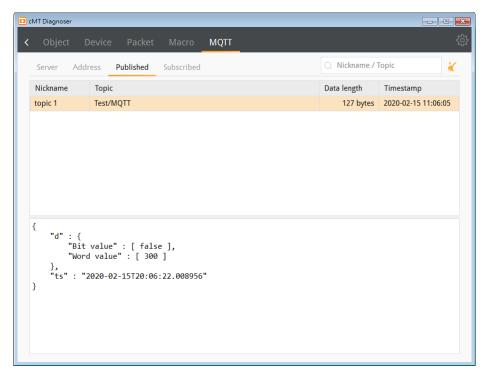


In Address tab the Topics published and subscribed by the HMI are shown. Selecting the checkbox of a topic in this tab can make cMT Diagnoser receive all MQTT messages published and subscribed, allowing cMT Diagnoser to change address data for easier MQTT debugging. Only normal servers are supported.

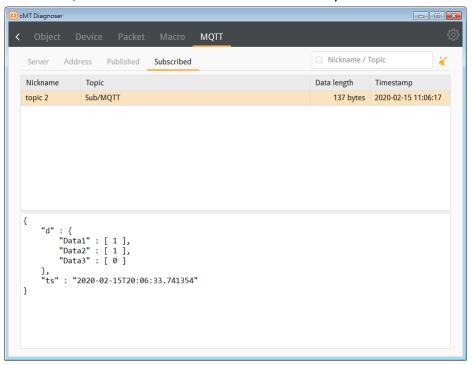


3. In Published tab the message published from HMI is shown. When Raw Data is used as content format, data will be shown in hexadecimal. Only normal servers are supported.





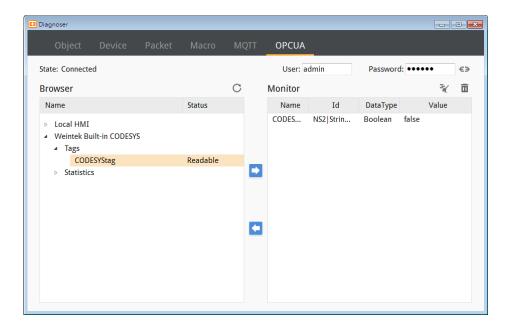
4. In Subscribe tab the message subscribed by HMI is shown. When Raw Data is used as content format, data will be shown in hexadecimal. Only normal servers are supported.



## 31.3.6. OPC UA Settings

1. Users can log in by entering the credentials to monitor values of OPC UA nodes.





#### **31.3.7.** JS Settings

1. In this tab users can view console messages of JS objects.

```
Object Device Packet Macro JS MQTT OPCUA

[17:11:42] [mousemove] event = {x: 258, y: 223}
[17:11:42] markers [ {x: 216.07142857142858, y: 220.10837438423644 }]
[17:11:43] [mousemove] event = {x: 246, y: 228}
[17:11:43] [mousemove] event = {x: 246, y: 228}
[17:11:43] [mousemove] event = {x: 200, y: 248}
[17:11:43] [mousedown] event = {x: 202, y: 248}
[17:11:43] [mousedown] event = {x: 282, y: 218}
[17:11:43] [mousedown] event = {x: 344, y: 214}
[17:11:43] [mousedown] event = {x: 346, y: 222}
[17:11:43] [mousemove] event = {x: 416, y: 225}
[17:11:43] [mousemove] event = {x: 440, y: 225}
[17:11:43] [mousemove] event = {x: 422, y: 225}
[17:11:43] [mousemove] event = {x: 429, y: 225}
[17:11:43] [mousemove] event = {x: 429, y: 225}
[17:11:43] [mousemove] event = {x: 433, y: 226}
[17:11:43] [mousemove] event = {x: 336, y: 224}
[17:11:43] [mousemove] event = {x: 338, y: 284}
[17:11:43] [mousemove] event = {x: 338, y: 284}
[17:11:43] [mousemove] event = {x: 282, y: 263}
[17:11:43] [mousemove] event = {x: 283, y: 284}
[17:11:43] [mousemove] event = {x: 273, y: 266}
[17:11:43] [mousemove] event = {x: 274, y: 266}
[17:11:44] [mousemove] event = {x: 275, y: 266}
[17:11:44] [mousemove] event = {x: 215, y: 266}
[17:11:44] [mo
```

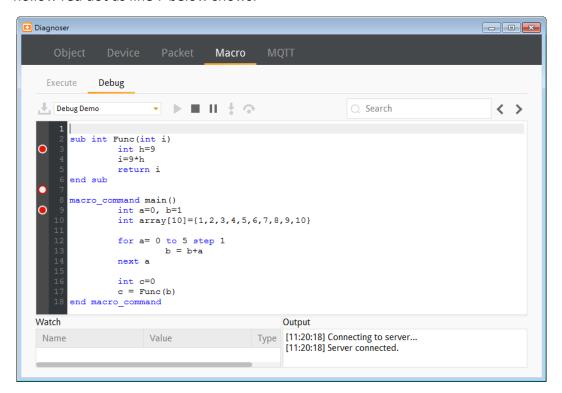
#### 31.4. Additional Notes

- cMT Diagnoser supports the monitoring all PLC addresses that HMI can access, including Tag PLC addresses.
- 2. Address values can be displayed in Decimal/HEX/Binary formats. Right-click anywhere on a monitor page to bring the menu up for the change.
- 3. When closing cMT Viewer with cMT Diagnoser opened, cMT Diagnoser will resume last state and pops up when cMT Viewer simulation window opens again. If Diagnoser is



31-20

- closed before closing cMT Viewer, users should manually open Diagnoser in next simulation.
- 4. When monitoring cMT-SVR/cMT-SVRX models, connecting directly with cMT Diagnoser displays only global object information. To view information for objects within the current window, connect through cMT Viewer and access Diagnoser with a right-click.
- 5. When [Password Protect] is enabled in Macro Manager, the Macro Debug File cannot be generated after compilation.
- 6. Password Protect can be enabled for an individual macro, and two modes are available: Encrypted and Read Only. To debug a password protected macro, a password is required to unlock the macro in cMT Diagnoser. If the macro is protected in Read Only mode, it can only be viewed but not changed when debugging. If the macro is protected in Encrypted mode, it cannot be viewed at all.
- 7. When a macro is not successfully compiled, it will be put into the Macro Under Development list and will not be contained in the Macro Debug File.
- 8. cMT Diagnoser can only debug one macro at a time. When debugging a macro, executing another macro will not be effective.
- 9. When the breakpoint is placed on irrelevant lines, such as beside an empty line, variable declaration without initial value assignment, the breakpoint will be represented by a hollow red dot as line 7 below shows.





## 32. FTP Server Application

This chapter explains how to use FTP Server.

32.1.	Overview	32-2
32.2.	Steps to Log in FTP Server	32-2
32.3.	Backup History Data and Update Recipe Data	32-3



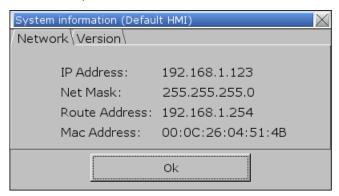
FTP Server Application 32-2

## 32.1. Overview

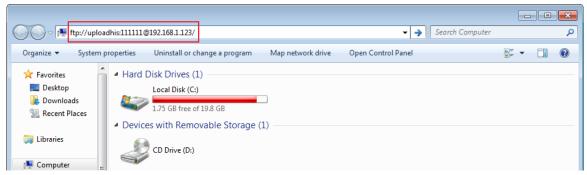
Apart from saving the history data from an HMI to your PC by using SD card, USB disk or EasyPrinter, the FTP Server can also do the backup. After downloading a project to the HMI, the FTP Server can be used to backup or update the history data and the recipe data, but not able to delete those data. Please disconnect from FTP before removing an SD card or USB disk, otherwise these external devices may not work when next time inserted.

## 32.2. Steps to Log in FTP Server

1. Before logging in FTP Server, please check the HMI IP address.



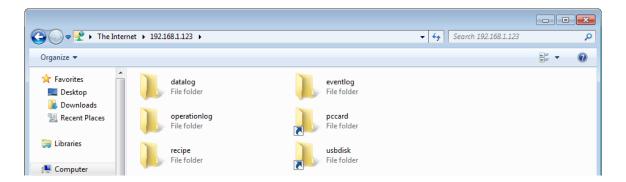
2. On PC, enter the HMI IP address: <a href="ftp://192.168.1.123">ftp://192.168.1.123</a> (example), then log in by the user name: uploadhis, and enter the HMI [history upload password] (if not changed, the default password is 111111). Or, directly enter <a href="ftp://uploadhis:111111@192.168.1.123/">ftp://uploadhis:111111@192.168.1.123/</a>



**3.** After entering the IP address, the ftp address: <a href="ftp://192.168.1.123">ftp://192.168.1.123</a> and its folders are shown as below:



FTP Server Application 32-3



## 32.3. Backup History Data and Update Recipe Data

- Steps to backup Data Sampling records
- 1. Click "datalog" folder to view the files.
- 2. Click the file to check the records.
- 3. Copy and paste the needed files to your PC.



- Steps to backup Event (Alarm) Log records
- 1. Click "eventlog" folder to view the files.
- 2. Copy and paste the needed files to your PC.



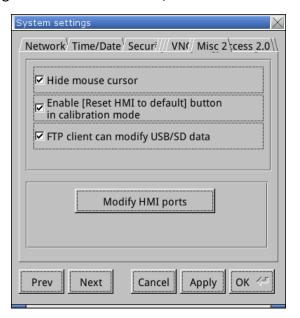
- Steps to backup or update Recipe records
- 1. Click "recipe" folder to view the files.
- 2. Copy and paste the needed files to your PC.

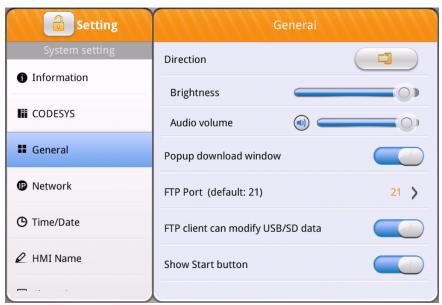


- Steps to modify data in USB/SD from FTP client
- 1. By default, [FTP client can modify USB/SD data] option is not selected. With this option selected, files in USB/SD can be deleted or modified from FTP client.



As shown below, this option can be found in system settings » Misc 2 tab on MT Series, and in system settings » General tab on cMT / cMT X Series.







- Since the recipe data is automatically saved per minute, after updating "recipe.rcp" or "recipe\_a.rcp", the HMI must be rebooted within one minute or the saving will be failed.
- The HMI can be rebooted by the system registers: [LB-9047] (reboot HMI) and [LB9048] (reboot HMI protection). You can set [LB-9048] ON first, and then set [LB-9047] ON to reboot the HMI.
- When using FTP server, the date of modification for the files on HMI will be UTC+0, and when users view these files on PC, the date of modification is added by PC's time zone, which can make the time different from the actual time.



# 33. Easy Diagnoser

This chapter explains how to use EasyDiagnoser.

33.1.	Overview	33-2
33.2.	Configuration	33-2
33.3.	EasyDiagnoser Settings	33-3
33.4.	Error Code	33-9
33.5.	Window Adjustment	33-10



## 33.1. Overview

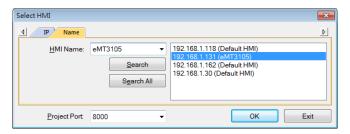
EasyDiagnoser is a tool for detecting the error in the communication of HMI with PLC.

## 33.2. Configuration

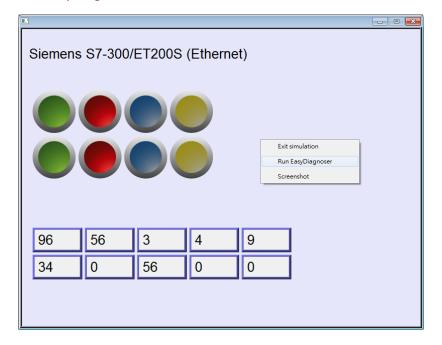
The following steps explain how to configure EasyDiagnoser.

- 1. Open Utility Manager and click EasyDiagnoser.
- 2. Set the HMI IP address. Enter IP address or click [Search All], and then enter [Project Port].



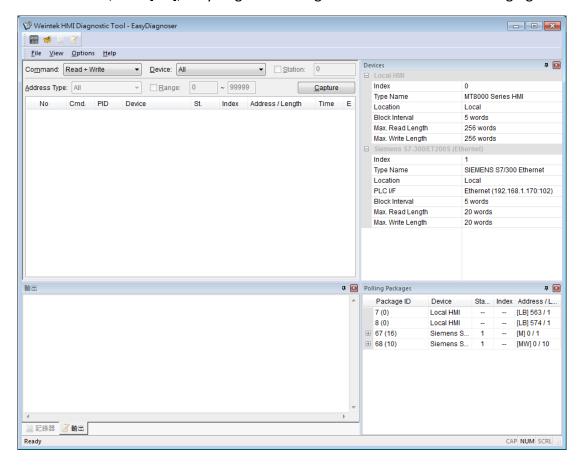


Or, during On-line simulation, right click and select [Run EasyDiagnoser] to open EasyDiagnoser. EasyDiagnoser will monitor the communication between PC and PLC.





3. When finished, click [OK], EasyDiagnoser dialog box is shown in the following figure.



## 33.3. EasyDiagnoser Settings

## 33.3.1. Main Menu

Item	Description
File	Save As
	The communication data can be saved as .xls file which can be
	opened by Excel.
	Exit
	Exits current file.
View	Device Bar displays Device window.
	Package Bar displays Package window.
	Logger Bar displays Logger window.
	Output Bar displays Output window.
Options	Toolbars displays toolbar icons of Device Bar, Package Bar,
	Logger Bar, and Output Bar.



**Status Bar** displays information of CAP, NUM, and SCRL at the bottom of EasyDiagnoser window.

**Update Package List** displays the Polling Package information of current page.

**Show Object ID (HMI)** shows the ID of the objects on HMI as shown in the following figure.



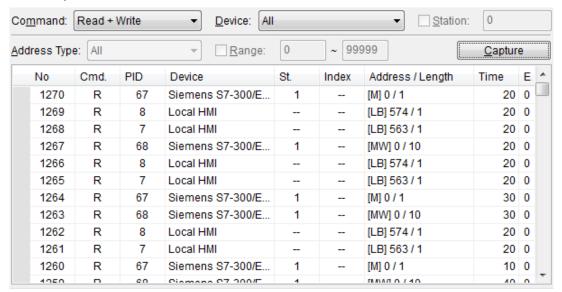
**Clear Activity List** clears all the information recorded during communication.

Help

Displays EasyDiagnoser version information.

### 33.3.2. Activity Area

In the activity area, users can observe the communication between HMI and PLC.



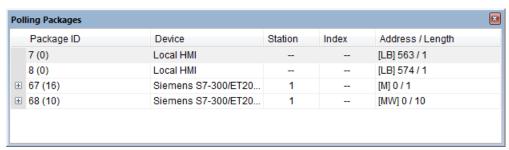
Item	Description
Command	Read + Write
	Displays Read and Write information in activity area.
	Read
	Displays only Read information in activity area.
	Write



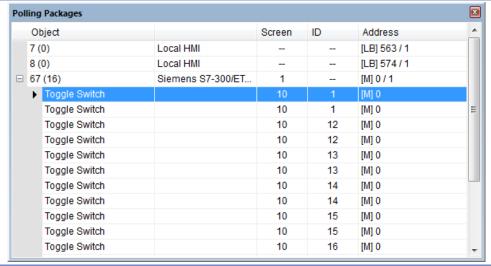
	Displays only Write information in activity area.
Device	All
Device	Displays the information of Local HMI and PLC.
	<ul> <li>If command is set to Read + Write, the Read and Write</li> </ul>
	information of Local HMI and PLC will be displayed in the
	activity area.
	<ul> <li>If command is set to Read, the Read information of Local</li> </ul>
	HMI and PLC will be displayed in the activity area.
	<ul> <li>If command is set to Write, the Write information of Local</li> </ul>
	HMI and PLC will be displayed in the activity area.
	Local HMI
	Displays the information of Local HMI.
	<ul> <li>If command is set to Read + Write, the Read and Write</li> </ul>
	information of Local HMI will be displayed in the activity
	area.
	<ul> <li>If command is set to Read, the Read information of Local</li> </ul>
	HMI will be displayed in the activity area.
	<ul> <li>If command is set to Write, the Write information of Local</li> </ul>
	HMI will be displayed in the activity area.
	PLC
	Displays the information of PLC.
	<ul><li>If command is set to Read + Write, the Read and Write</li></ul>
	information of PLC will be displayed in the activity area.
	<ul> <li>If command is set to Read, the Read information of PLC</li> </ul>
	will be displayed in the activity area.
	<ul> <li>If command is set to Write, the Write information of PLC</li> </ul>
	will be displayed in the activity area.
Station	Selects the PLC station number to be displayed.
	(This function is disabled when selecting [All] in [Device]).
Address	Selects all or a preferred address type to be displayed.
Туре	(This function is disabled when selecting [All] in [Device]).
Range	Sets the range of address types.
	(This function is disabled when selecting [All] in [Device]).
Capture	Click to start/stop capturing the communication message.
Error	Please see "33.4 Error Code".



## 33.3.3. Polling Packages



Item	Description
Package ID	Uses the Package ID to check the error of the object.
Device	Displays HMI and PLC type.
Station	Displays PLC station number.
Index	Displays the index register numbers of the objects.
Address /	Displays the device type and the size of the package (in
Length	words).

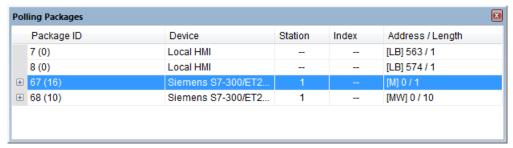


Item	Description
Object	Check the object in the package.
Screen	The window in the project where the object is placed.
ID	The ID number of the object.
Address	The address of the object.



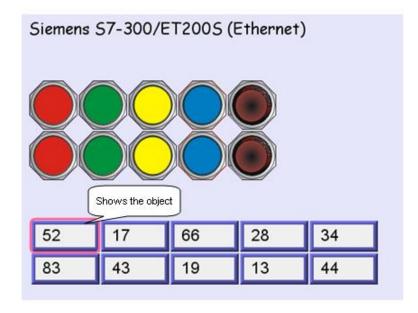


Click [Package ID], the device station number will be displayed in the 3rd column.



Double click [Package ID] then select [object] to display the position of the object.
For example, select [Numeric Input] and the screen no. displays 10.
This shows that this object is in window no. 10 in the project and will be marked with pink frame on HMI as shown in the following figures

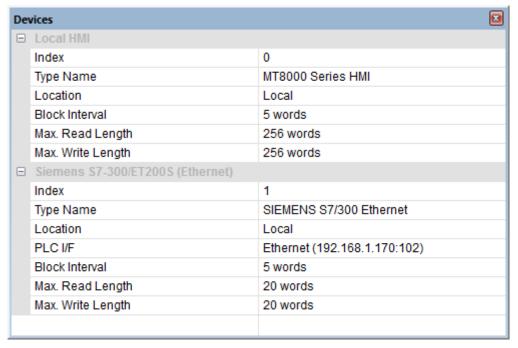
	Object		Screen	ID	Address
	7 (0)	Local HMI			[LB] 563 / 1
	8 (0)	Local HMI			[LB] 574 / 1
+	67 (16)	Siemens S7-300/ET20	1	-	[M] 0 / 1
	68 (10)	Siemens S7-300/ET20	1		[MW] 0 / 10
	▶ Numeric Input		10	2	[MW] 0
	Numeric Input		10	3	[MW] 2
	Numeric Input		10	4	[MW] 4
	Numeric Input		10	5	[MW] 6
	Numeric Input		10	6	[MW] 8
	Numeric Input		10	7	[MW] 10
	Numeric Input		10	8	[MW] 12
	Numeric Input		10	9	[MW] 14
	Numeric Input		10	10	[MW] 16
	Numeric Input		10	11	[MW] 18





#### 33.3.4. **Devices**

Displays the information of HMI and PLC.



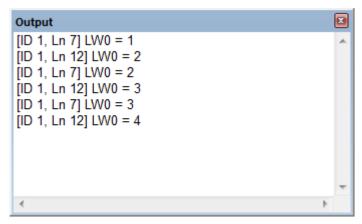
#### **Output (Macro debug)** 33.3.5.

With Macro Trace function, the executing status of Macro can be seen.

In the illustration below, for [ID 1, Ln 7] and [ID 1, Ln 12]

ID 1 represents Macro name.

Ln 7 and Ln 12 represent that data are in the 7<sup>th</sup> and 12<sup>th</sup> line of Macro.





For more information, see "18 Macro Reference".



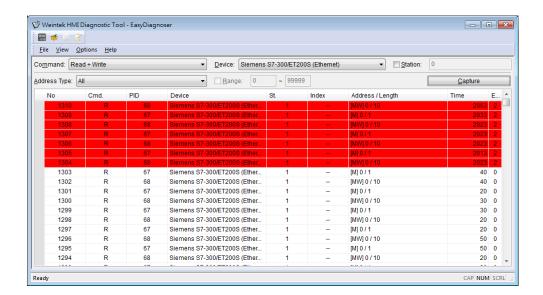
## 33.4. Error Code

In the activity area, the reason of error can be found through the error codes listed below.

Error Code	Cause of Communication Error
0	Normal
1	The device is busy and not yet ready to process a command.
2	Communication error due to unexpected reason.
3	The device does not exist.
4	The device using the specified station number does not exist.
5	Incorrect address format.
6	Read/Write unsupported address.
7	The driver of the device does not exist.
8	The COM port does not exist.
9	Incorrect IP address or unable to connect the device.
10	Checksum error.
11	Unidentified command.
12	Ignore
20	The USB device is improperly connected.
21	The CAN Bus device is improperly connected.
22	No reply from the device.
23	Insufficient data read from the device before timeout.
24	The Conversion Tag used by the object does not exist or the content is incorrect.
25	HMI is not accepting any commands from a remote HMI.
251	Read/Write exceeding number of words from/to the register of the MODBUS device.
252	MODBUS device replies incorrect data format.
253	MODBUS device checksum error.

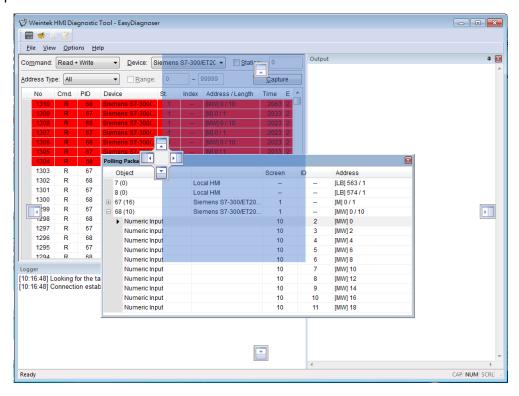
When error occurs, the error message will be shaded red as shown in the following figure.





## 33.5. Window Adjustment

Users can drag or use the smart docking icons in editing window to place the windows to a desired position.





 EasyDiagnoser doesn't support Siemens S7/1200 (Ethernet) and Allen-Bradley Ethernet/IP (CompactLogix/ControlLogix) – Free Tag Names since both of the PLCs use tag.



Click the icon to watch the demonstration film. Please confirm your internet connection before playing the film.



# 34. Control Token (cMT / cMT X)

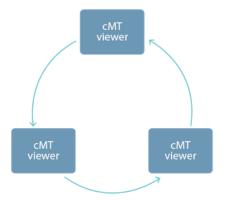
This chapter explains how to use Control Token.

34.1.	Overview	. 34-2
34.2.	Configuration	. 34-2
	Demonstration	



Control Token 34-2

## 34.1. Overview



One cMT / cMT X HMI can be simultaneously controlled by multiple cMT Viewer clients. To ensure system safety by preventing an object to be controlled by multiple clients simultaneously, a control token can be set. Only one cMT Viewer client can acquire the control token at a time, and only the cMT Viewer client that acquires control token can operate the object. The rest of the clients can acquire the token one by one when the token is not occupied.

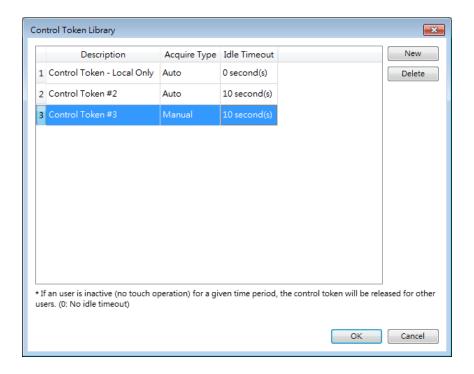
## 34.2. Configuration



Click [Project] » [Control Token] to open the settings window.



Control Token 34-3



Setting	Description
Description	Specify the name of the selected control token.
	Control Token – Local Only
	When this token is selected, only the local HMI can
	operate the object. This token is available only for
	models that have built-in cMT Viewer: cMT3072,
	cMT3090, cMT3151, cMT-HDMetc.
Acquire Type	Select an acquire type from [Auto] or [Manual].
	Auto
	With this option selected, cMT Viewer will
	automatically acquire the control tokens set for all
	objects in the current window. The control token will
	be released after leaving this window.
	Manual
	The control token can be acquired or released by
	triggering an Action Trigger or a Combo Button.
Idle Timeout	Setting Idle Timeout helps avoid the issue that
	prevents other users from gaining operating right
	when the token possessor, having finished operation,
	does not release the control token. When the token
	possessor's HMI remains inactive (no touch operation)
	for a given time period, the control token will be



released.
The setting range allowed for Idle Timeout is 0~86400
seconds. For "Control Token- Local Only", the Idle
Timeout can only be zero and is not adjustable.



- Control tokens are allocated on a first come first served basis, and a control token can be possessed by one cMT Viewer client at a time. Attempts made for acquiring a control token when it is unavailable will be put into a queue, and it becomes available, it will be passed to the next one in the queue.
- A cMT Viewer client can simultaneously possess multiple control tokens.
- In Auto mode, when changing to a new window, even if the object with the same control token appears in both previous and new window, the control token is reacquired upon entering the new window. If the object with the control token is placed in an overlay window or a common window, and the same overlay window is used in both previous and new window, then reacquiring control token will not take place.
- When cMT Viewer client is disconnected from the Server, and the connection is recovered within 30 seconds, reacquiring control token is not necessary. When the disconnection goes longer than 30 seconds, reacquiring control token is necessary.

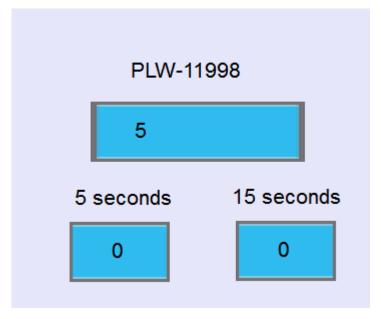
## 34.3. Demonstration

To monitor idle time countdown, use an ASCII object with system register PLW-11998. When two or more control tokens are used, this system register will count down from least idle time until elapsed.

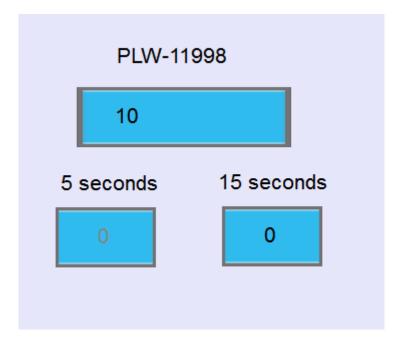
In the following example, on the top, ASCII object shows idle time countdown from PLW-11998. The bottom two objects use two different control tokens, one with a 5-second idle time and the other 15-second. When running simulation, PLW-11998 will count down from five seconds.



Control Token 34-5



After 5 seconds, the bottom left object turns grey due to expired control token, and another object has 10 seconds left for countdown.



## 35. EasyWatch

This chapter explains how to use EasyWatch.

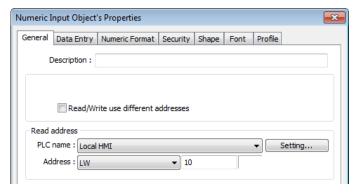
35.1.	Overview	35-2
35.2.	Configuration	35-2
35.3.	Monitor Settings	35-4
35.4.	Macro Settings	35-9
35.5.	HMI Manager	35-10
35.6.	Object List	35-12

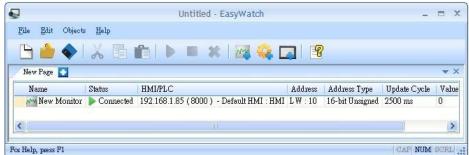


## 35.1. Overview

EasyWatch allows users to monitor values in HMI / PLC addresses via Ethernet from a PC, and it can be used for macro debugging and remote monitoring.

As shown in the example below, In EasyBuilder Pro, after creating a Numeric Input Object, you can set its address to LW-10, and set the same address in EasyWatch. The value of LW-10 will be shown in EasyWatch when connected.







- Monitoring using EasyWatch will not be possible when the system register [LB-9044 (disable remote control)] or [System Parameter Settings] » [System Setting] » [Prohibit remote HMI connecting to this machine] is enabled.
- To connect EasyWatch from a cMT / cMT X HMI, go to [System Parameter Settings] » [Model] tab, select [Support iP/iE/XE/eMT/mTV communication protocol and EasyWatch] option, and then use the port number specified here.

## 35.2. Configuration

#### 35.2.1. Basic Functions

Item	Description
File	New: Opens a new EasyWatch file.



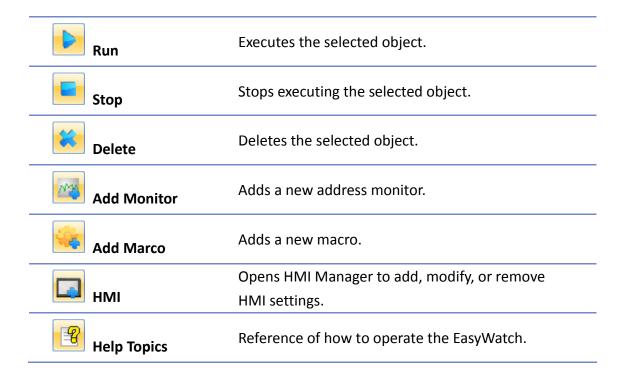
	Open: Opens an existing EasyWatch file.	
	Save: Saves an EasyWatch file.	
	Save As: Saves an EasyWatch file to .ewt format.	
	Exit: Exits EasyWatch.	
Edit	Cut: Relocates the selected items to the clipboard.	
	Copy: Copies the selected items to the clipboard.	
	Paste: Pastes the items in the clipboard at the selected location.	
Objects	jects Add Object: Adds new Monitor or Macro objects.	
	Delete Objects: Selects the objects to be deleted, a dialog box	
	appears, click [Yes] to delete.	
	Modify Object: Changes the settings of the selected object.	
	HMI Manager: Adds, modifies, or removes HMI settings.	
	Run: Executes the selected object.	
	Stop: Stops executing the selected object.	
Help	Help Topics: Reference of how to operate EasyWatch.	
	About EasyWatch: EasyWatch version information.	

## 35.2.2. Quick Selection Tools



Item	Description
New New	Opens a new EasyWatch file.
<b>Open</b>	Opens an existing EasyWatch file.
Save	Saves an EasyWatch file.
Cut	Relocates the selected items to the clipboard.
Сору	Copies the selected items to the clipboard.
	Pastes the items in the clipboard at the selected
Paste	location.





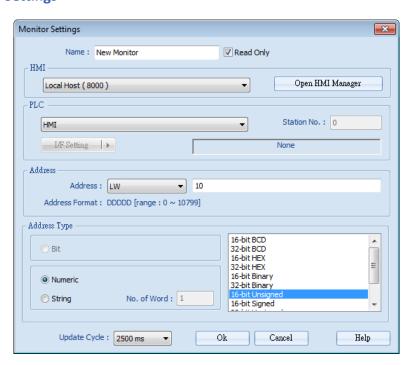
## 35.3. Monitor Settings

### 35.3.1. Adding a Monitor

There are two ways to create a Monitor Object.

- Select from the toolbar: [Objects] » [Add Object] » [Add Monitor].
- Select from the quick selection toolbar: [Add new address monitor].

### 35.3.2. Monitor Settings

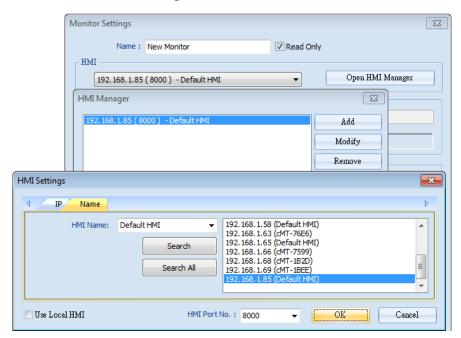




Setting	Description
Name	Enters an object name which is an unique name.  Read Only: If an object is set to read only, its address value can't be edited.
НМІ	Select a HMI to monitor.
PLC	Selects the desired PLC to monitor and sets its type, station number, and connection method.
Address	Selects the desired object address to monitor and sets its address type.
Address Type	When the address type is set, the available formats of the address can be selected. When executing, the address will bedisplayed according to the selected format.
Update Cycle	Sets the update interval of the monitoring object. If many objects are executed simultaneously, the errors or delays may appear.

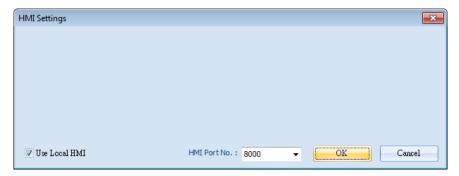
### 35.3.3. Steps to Add a New Monitor

1. Select a target HMI. If the target HMI does not exist, click [Open HMI Manager] and click [Add] to search the HMI for adding.

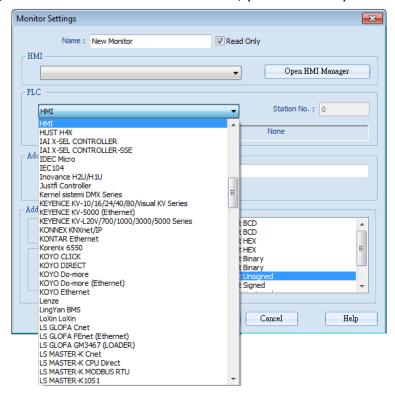


Or, select [Use Local HMI] checkbox to use the project on PC as a monitoring device.

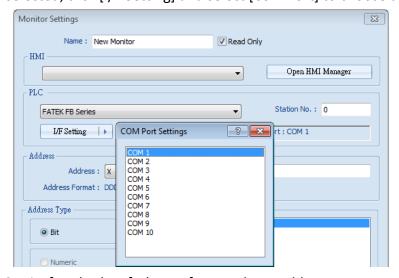




2. Select a target HMI or PLC. If one HMI is selected, you can directly control the local HMI.

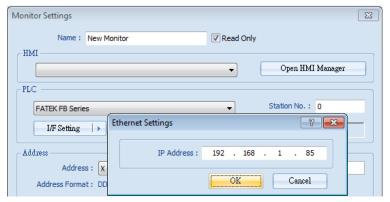


If one PLC is selected, click [I/F Setting] and select [Com Port] to choose a COM port.

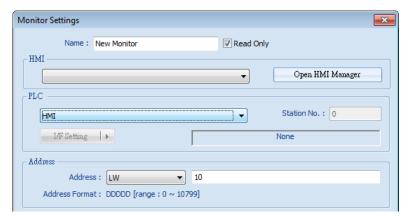


Or, click [I/F Setting] and select [Ethernet] to set the IP address.

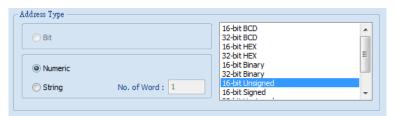




3. Set the object address and its address type for being monitored.



**4.** When a Word address is selected, set the address type to [Numeric] or [String]. [Numeric]: Select the data format of the monitor address.



[String]: Select the data format from [ANSI], [UNICODE], and [High/Reversed]. Set [No. of Word] for reading the number of WORD.



5. Set the update interval of the monitor object. The range can be set from 500ms to 5000ms.







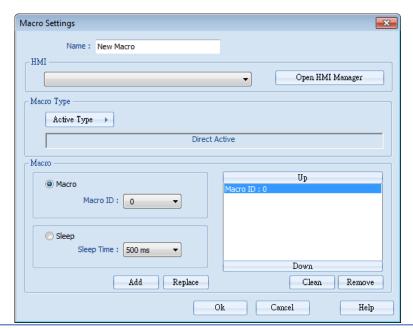
## **35.4.** Macro Settings

### 35.4.1. Adding a Macro

There are two ways to create a Macro object.

- Select from the toolbar: [Objects] » [Add Object] » [Add Macro].
- Select from the quick selection toolbar: [Add new macro].

## 35.4.2. Macro Settings

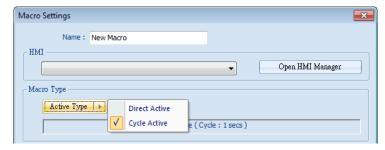


Setting	Description
Name	Enters an object name which is an unique name.
НМІ	Selects a HMI to monitor.
Macro Type	The ways to execute the Macro included Direct Active and
	Cycle Active.
Macro	Each Macro Object can execute multiple macros. The time
Macro	Each Macro Object can execute multiple macros. The time interval between the executions of two macros can be

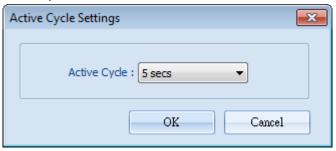
### 35.4.3. Steps to Add a New Macro

- 1. Select a target HMI. If the target HMI does not exist, add a new device, see "35.3.3 Steps to Add a New Monitor".
- 2. Set Active Type under Macro Type to [Direct Active] or [Cycle Active].
  - [Direct Active]: Directly executes Macro once.
  - [Cycle Active]: Set the interval of executing Macro.





For example, if [Cycle Active] is set to 5 seconds, when executing a macro, the next time to execute the macro object will be 5 seconds later.

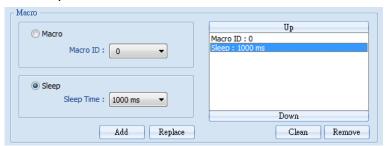


3. Set Macro to [Macro] or [Sleep].

[Macro]: Select the Macro ID for execution, and click [Add] to add the Macro to the list.



[Sleep]: Set the time interval between the executions of two Macros. Click [Add] or [Replace] to add or replace the Macros from the list.



## 35.5. HMI Manager

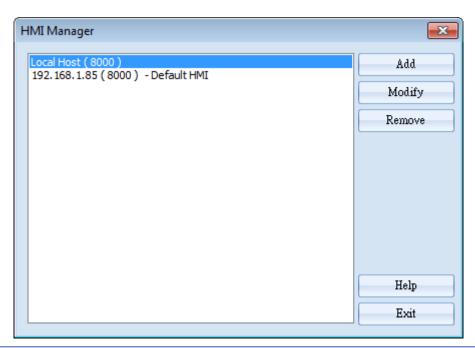
### 35.5.1. Opening HMI Setting

There are two ways to open the HMI Setting.

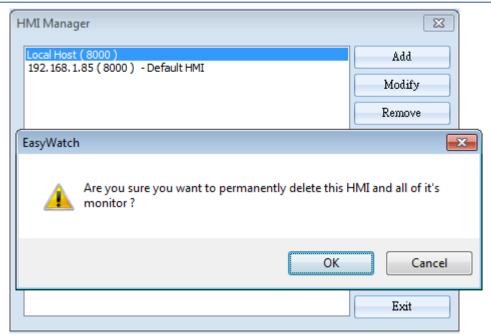
- Select from the toolbar: [Objects] » [HMI Manager].
- Select from the quick selection toolbar: [Open HMI manager].



### 35.5.2. HMI Manager



Setting	Description
Add	Select a target HMI. If the target HMI does not exist, add a
	new device, see "35.3.3 Steps to add a new monitor".
Modify	Modify the settings of the HMI.
Remove	Remove the HMI.

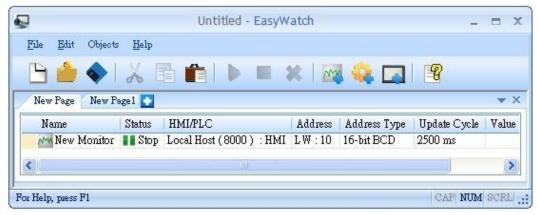




EasyWatch 35-12

# 35.6. Object List

# 35.6.1. Object List Columns



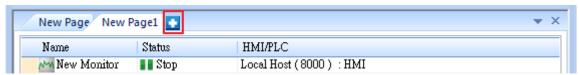
Setting	Description
Name	Displays the object name. The small icons of the names
	are for users to identify the objects.
Status	Displays the status of the objects: [Connecting],
	[Connected], and [Stop]. If HMI is not connected or Port
	No. is incorrect, the error message "HMI Not Found" will
	appear. For Monitor Objects, if the address is incorrect,
	"Address Error" message will appear.
HMI / PLC	Displays the information of HMI / PLC that is currently
	operated by the objects.
Address	For Monitor Objects, the relevant address setting is
Address Type	displayed.
Update Cycle	Set the update interval of the monitor object.
Value	For Monitor Object, if the status shows [Connected], the
	current HMI address value will be displayed. Modifying
	the value is also available when the Read-Only checkbox
	is unselected. For Macro Object, if set to [Direct Active],
	there will be an [Active] button in this column for clicking
	to directly execute a macro.



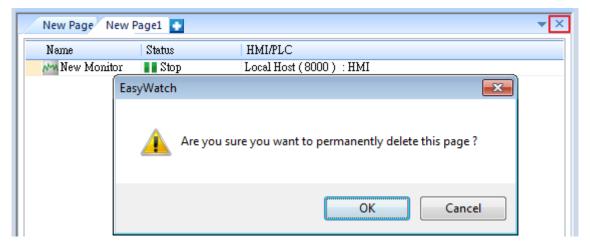
EasyWatch 35-13

### 35.6.2. Editing Object List

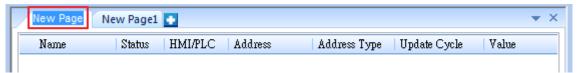
Adding a new page: Click the icon to add a new page.



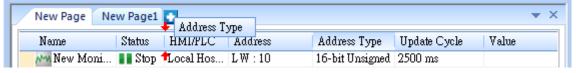
• Deleting a page: Click the icon and confirm the deletion.



Renaming the page: Double-click on the page name and enter a new name.



 Positioning the column headers: Drag and drop the column headers to the desired location.



► Click the icon to watch the demonstration film. Please confirm your internet connection before playing the film.



# 36. Administrator Tools

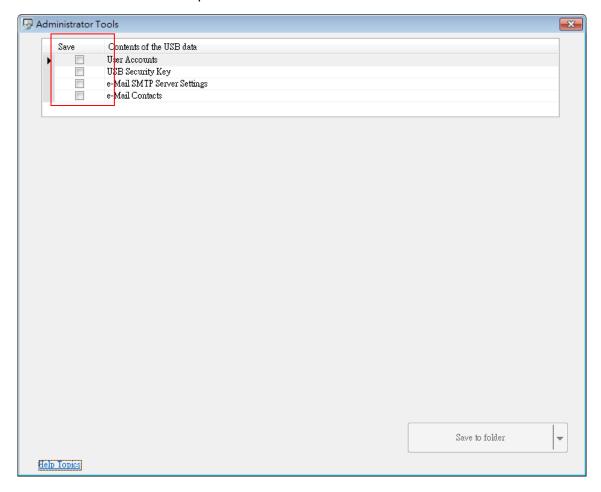
This chapter explains how to setup Administrator Tools.

36.1.	Overview	36-2
36.2.	User Accounts	36-2
36.3.	USB Security Key	36-6
36.4.	e-Mail SMTP Server Settings	36-9
36.5.	e-Mail Contacts	36-10



# 36.1. Overview

Administrator Tools allows storing the data of [User Accounts], [USB Security Key], [e-Mail SMTP Server Settings], and [e-Mail Contacts] to USB. With EasyBuilder Pro user accounts and e-Mail function, the data built can be imported to HMI by Function Key object set to "Import user data / Use [USB Security Key]". The portability and convenience is greatly improved. Launch Administrator Tools, select the check boxes in [Save] column to enable the selected functions introduced in this chapter.

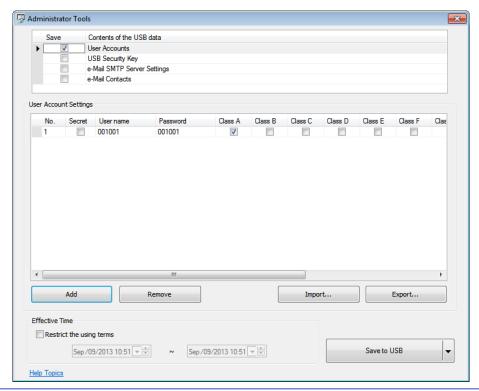


### 36.2. User Accounts

# **36.2.1.** User Accounts Settings

Select [User Accounts] check box and complete the relevant settings.





Settings	Description					
Secret	Select the check box to set secret accounts.					
User Name	Sets User Name. *Note 1					
Password	Sets User Password. *Note 1					
Class A to L	Sets user privilege.					
Add	Adds a new account. *Note 2					
Remove	Deletes an existing account.					
Import	Imports user account data.					
Export	Exports user account data.					
Effective Time	If [Restrict the using terms] is not selected, it is					
	available to import data anytime.					
	If select [Restrict the using terms] check box, and set					
	an effective time period, the importing of data to					
	HMI can only be done in the time limit specified.					
	•					
	When time expired, data cannot be imported, please					
	reset the data with this tool again.					
Save to USB	Saves data to USB. To save to a specific folder, click					
	"▼" button and select "Folder".					
	Save to USB  ✓ USB Folder					

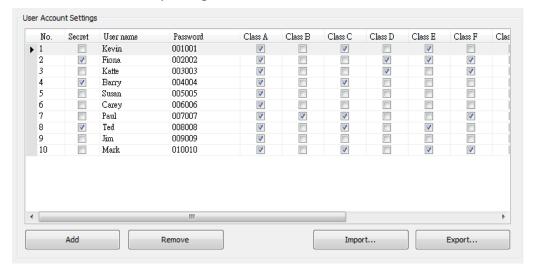




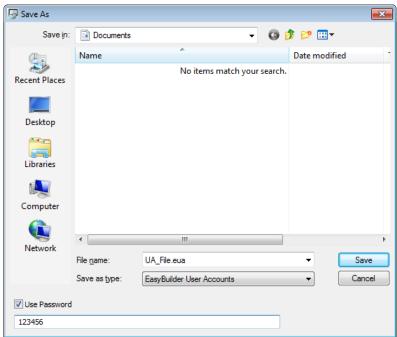
- 1. Only allows letters, numbers, "-" or "\_", case-sensitive.
- 2. A maximum of 127 user accounts can be added.

#### 36.2.2. Steps to Set User Accounts

Click [Add] to create a new account. Click [Remove] to delete the selected account. Select
[Secret] check box to define the account as a secret user. Type in [User name] and
[Password] and check the privilege from [Class A] to [Class L] check boxes.



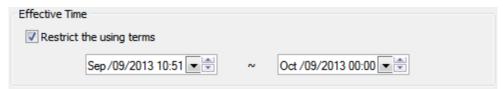
2. To back up the data, click [Export]. Click [Use Password] to protect the data, next time when click [Import] to import the backup data, a password is required.



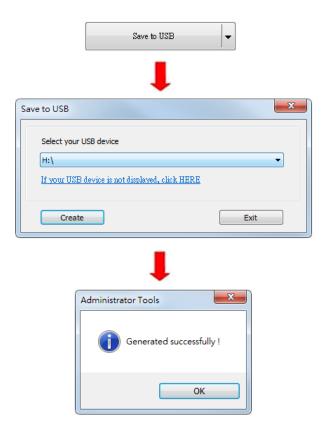
3. If under [Effective Time], the [Restrict the using terms] check box is selected, only during the specified time period can the users import account data to HMI. If not selected, users



can import data to HMI at any time.



**4.** When finished, click [Save to USB], select the location of USB and then click [Create]. If successful, the "Generated successfully!" message is shown.



#### 36.2.3. Steps to Import Accounts Using EasyBuilder Pro

The following steps explain how to create a Function Key to import data in EasyBuilder Pro.

1. Select "Import user data/Use [USB Security Key]" in Function Key setting dialog box, and then click [Settings].



2. Under [Function mode] select [Import user accounts]. Select the device that stores the data in [Data position]. Select [Overwrite] under [Account import mode]; HMI will only store the account data imported this time. Select [Append], HMI will store the accounts imported this time and those already exist. Select [Delete file after importing user accounts] check box to delete the source files after importing.



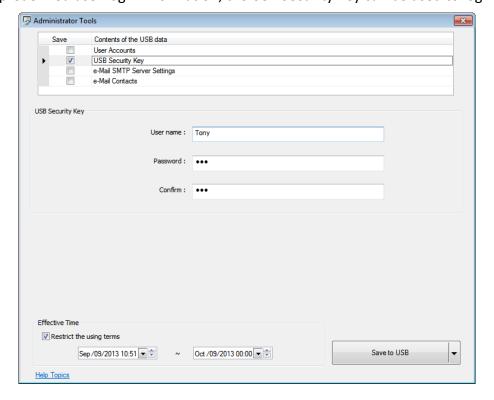


Click the icon to download the demo project that explains how to import user accounts by using Function Key. Please confirm your internet connection.

# 36.3. USB Security Key

# **36.3.1.** USB Security Key Settings

With the predefined user login information, the USB Security Key can be used to log in directly.





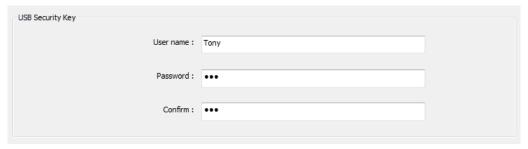
Settings	Description
User Name	Sets User Name. *Note 1
Password	Sets User Password. *Note 1
Confirm	Confirms User Password.
Effective Time	Logs in using USB Security Key during the specified
	time period. If not specifying Effective Time, log in at
	any time.
Save to USB	Saves data to USB.



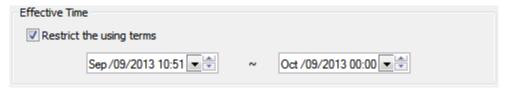
1. Only allows letters, numbers, "-" or "\_", case-sensitive.

# 36.3.2. Steps to Set USB Security Key

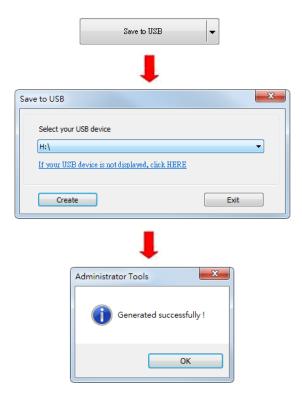
**1.** Type in the existing user name and password. Type the password again in [Confirm] field for password confirmation.



2. Under [Effective Time] if [Restrict the using terms] check box is selected, only during the specified time period can users log in using USB Security Key. If not selected, users can log in using USB Security Key at any time.



**3.** When finished, click **[Save to USB]**, select the location of USB and then click **[Create]**. If successful, the "Generated successfully!" massage is shown.



## 36.3.3. Steps to Set USB Security Key Using EasyBuilder Pro

The following steps explain how to create a Function Key to enable USB Security Key in EasyBuilder Pro. By touching the object, the USB Security Key is enabled for login.

 Select "Import user data/Use [USB Security Key]" in Function Key setting dialog box, and then click [Settings].



2. Under [Function mode] select [Use USB Security Key to Login]. Select the device that stores the data in [Data position].





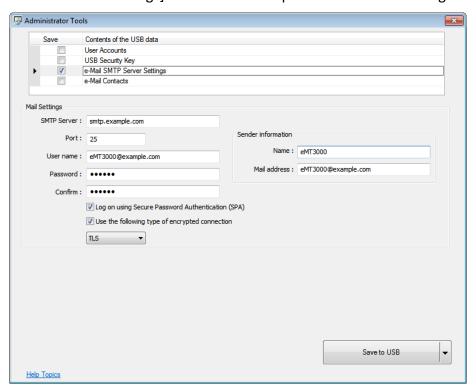


Click the icon to download the demo project that explains how to enable login using USB

Security Key by using Function Key. Please confirm your internet connection.

#### 36.4. e-Mail SMTP Server Settings

Select [e-Mail SMTP Server Settings] check box to complete the relevant settings.



Mail Settings	Description
SMTP Server	Specifies SMTP Server.
Port	Specifies SMTP Server port number.
User name	User e-mail account name.
Password	User e-mail account password.
Confirm	Confirm user e-mail account password.
Sender Information	Description
Name	The sender name displayed when mail received.
Mail address	The sender address displayed when mail received.
Save to USB	Saves data to USB.

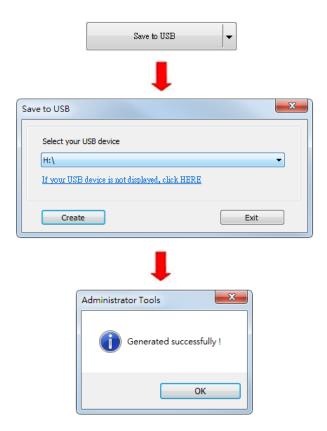
#### 36.4.1. **Steps to set e-Mail SMTP Server Settings**

Set the settings as shown in the following figure.





2. When finished, click [Save to USB], select the location of USB and then click [Create]. If successful, the "Generated successfully!" massage is shown.

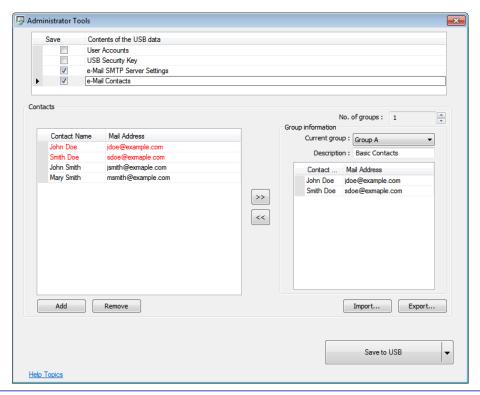


### 36.5. e-Mail Contacts

# 36.5.1. e-Mail Contacts Settings

Select [e-Mail Contacts] check box to complete the relevant settings.





Settings	Description	
Add	Adds a new contact. *Note1	
Remove	Removes a contact.	
No. of groups	The number of groups. *Note2	
Current group	The name of current group. *Note3	
Description	Group description.	
Import	Imports contact information.	
Export	Exports contact information.	
Save to USB	Saves data to USB.	

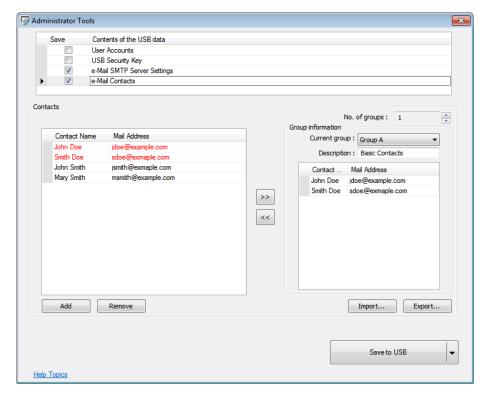


- 1. A maximum of 256 contacts can be added.
- 2. A maximum of 16 groups can be added. (Group A to Group P)
- **3.** From Group A to P, when [No. of groups] is "1", only Group A will exist, when added to "2", Group A and Group B will exist, and so on.
- 4. UTF-8 characters are allowed in contact names.

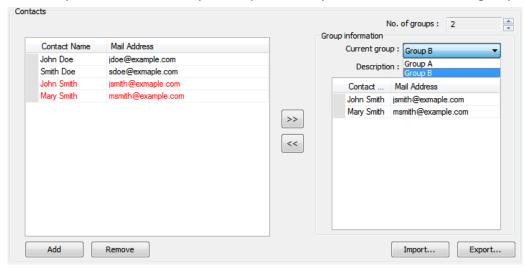
# 36.5.2. Steps to set e-Mail Contacts

- 1. Click [Add] to add in all contacts.
- 2. Add the contacts to Group A, the added contacts are displayed in red font.

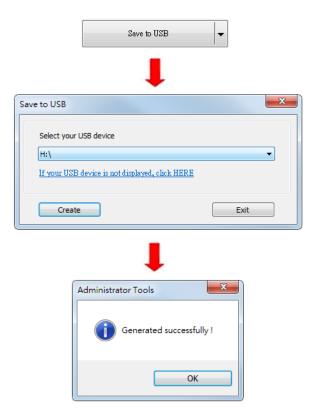




3. Press the up or down arrows of the spin box of [No. of groups] to add new groups. If add to "2", Group B can be found. Repeat step 1 and step 2 to add contacts into groups.



- **4.** After adding all the e-mail contacts, click [Export] to back up the data for future use and modification. Next time when needed, click [Import] to import the backup data.
- **5.** When finished, click [Save to USB], select the location of USB and then click [Create]. If successful, the "Generated successfully!" massage is shown.



## 36.5.3. Steps to Import e-Mail Settings and Contacts Using EasyBuilder Pro

The following steps explain how to create a Function Key to import e-Mail contacts.

- Select "Import user data/Use [USB Security Key]" in Function Key setting dialog box, and then click [Settings].
- 2. Under [Function mode] select [Import e-mail settings and contacts]. Select the device that stores the data in [Data position].



Click the icon to download the demo project that explains how to import e-mail settings and contacts by using Function Key. Please confirm your internet connection.



# 37. MODBUS Gateway

This chapter explains how to use MODBUS Gateway and configure address mapping tables.

37.1.	Overview	37-2
37.2.	Steps to Create an Address Mapping Table	37-2
37.3.	Notes about Configuring Address Mapping	37-5



# 37.1. Overview

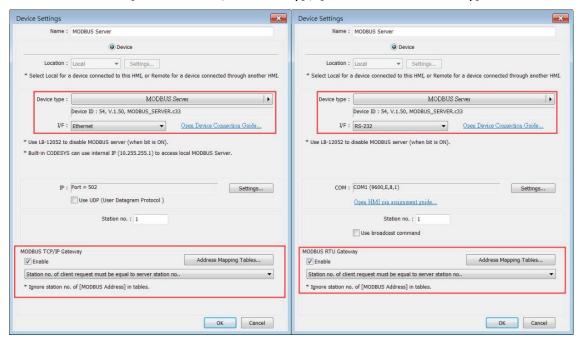
To access the data of the PLC connected to HMI with SCADA software (Supervisory Control and Data Acquisition), the former way was to transfer PLC data to the HMI's local address first, and then use MODBUS TCP/IP or MODBUS RTU protocol on PC to read HMI local address to get PLC data. Now by using MODBUS Gateway provided by EasyBuilder Pro, the mapping of MODBUS address to PLC address can be defined first, and then one can directly use MODBUS TCP/IP or MODBUS RTU protocol to access PLC data.



# 37.2. Steps to Create an Address Mapping Table

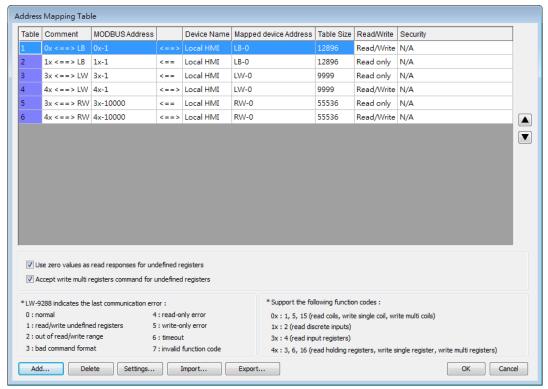
To create an Address Mapping Table, please follow the steps:

- In [System Parameter Settings] » [Device] tab, add the PLC device. (In the example FATEK FB Series is used).
- Add MODBUS Server, select Ethernet or COM port interface according to the MODBUS Client and enable [MODBUS TCP/IP Gateway] / [MODBUS RTU Gateway] as shown below.





Click [Address Mapping Tables] button and the following default tables will be displayed.Modify the tables if needed or add new tables.



4. In the example below, to access the data in the 50 consecutive registers of FATEK FB Series PLC starting from register D-0, configure the settings as shown in the following figure.





- (1) Select the address mode, in this example select [Word].
- (2) Select the access type, in this example select [Read/Write].
- (3) Set the start address of MODBUS, in this example set to "4x-1".
- (4) Set the start address of the mapped PLC, in this example set to "D-0".
- (5) Set the size of address mapping table, in this example set to "50".
- (6) Select high/low byte swap or high/low word swap if necessary.



The above figure shows that MODBUS Server  $4x-1 \sim 4x-50$  registers are mapped to FATEK FB Series PLC D-0  $\sim$  D-49 registers.

5. When finished, the data of FATEK FB Series PLC D-0 ~ D-49 registers are now accessible by using MODBUS protocol to send read / write command to 4x-1 ~ 4x-50 registers.

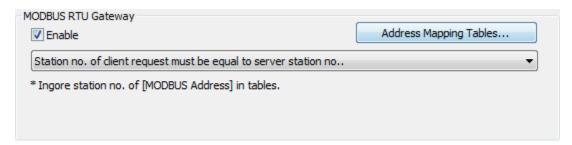


# 37.3. Notes about Configuring Address Mapping

- UDP is not supported when MODBUS TCP/IP Gateway feature is used.
- MODBUS RTU Gateway feature is only supported on cMT / cMT X Series models.
- The station number of MODBUS client request can be handled differently in the following modes, please select a mode suitable for your application:

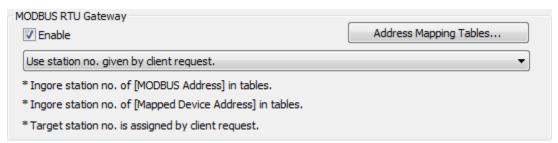
The station no. of client request must be equal to server station no.

Use the station number of MODBUS Server.



## Use station no. given by client request.

Use the station number of MODBUS Client. Only one MODBUS Client can be connected to MODBUS Server at a time, and the clients should use different station numbers.



#### Station no. of client request must meet MODBUS address setting in tables.

Use the station number of the MODBUS address in the address mapping table. Example: Two MODBUS Clients, 4x-1#100 and 4x-2#100, are connecting to MODBUS Server using station no. 1 and station no. 2. Under this mode, multiple clients can simultaneously connect to the server.

If no station number is assigned for the MODBUS address, the default station number of the device will be used.

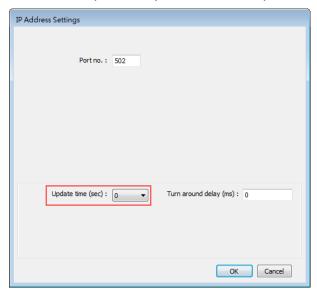


Update time (sec) can be set to enable caching for MODBUS Server when multiple clients



37-6

are frequently reading data. By default, the setting is 0 and the caching feature is not enabled. Settings greater than 0 can enable caching. At the first time the server receives a command from the client, it gets data from PLC. If the update time is set to 1 second, and the client requests for data in the same register again, within a second, the server will use the PLC data previously obtained as response.



■ When the registers of the client device are not consecutive, and the user would like to read / write all data at a time, the following two options are provided for users to decide how to handle the undefined registers in the mapping table. These options are only available on cMT / cMT X models.



- The clients are not allowed to read / write 16-bit data (high / low word) of a 32-bit register.
- System register LW-9288 is used to indicate if data transfer has been correctly executed. The following error codes represent:

<ul> <li>Value Definition</li> <li>Normal</li> <li>Read or write the register that is not defined in the Address Mapping Table.</li> <li>Read or write a range of registers that is not within the range defined in a single Address Mapping Table. (Or, read / write a register that is defined in other Address Mapping Table.)</li> <li>The command format does not follow MODBUS TCP/IP protocol.</li> </ul>		•
<ol> <li>Read or write the register that is not defined in the Address Mapping Table.</li> <li>Read or write a range of registers that is not within the range defined in a single Address Mapping Table.         <ul> <li>(Or, read / write a register that is defined in other Address Mapping Table.)</li> </ul> </li> <li>The command format does not follow MODBUS</li> </ol>	Value	Definition
Address Mapping Table.  2 Read or write a range of registers that is not within the range defined in a single Address Mapping Table.  (Or, read / write a register that is defined in other Address Mapping Table.)  3 The command format does not follow MODBUS	0	Normal
Read or write a range of registers that is not within the range defined in a single Address Mapping Table.  (Or, read / write a register that is defined in other Address Mapping Table.)  The command format does not follow MODBUS	1	Read or write the register that is not defined in the
the range defined in a single Address Mapping Table.  (Or, read / write a register that is defined in other Address Mapping Table.)  The command format does not follow MODBUS		Address Mapping Table.
(Or, read / write a register that is defined in other Address Mapping Table.)  3 The command format does not follow MODBUS	2	Read or write a range of registers that is not within
Address Mapping Table.)  The command format does not follow MODBUS		the range defined in a single Address Mapping Table.
3 The command format does not follow MODBUS		(Or, read / write a register that is defined in other
		Address Mapping Table.)
TCP/IP protocol.	3	The command format does not follow MODBUS
		TCP/IP protocol.



4	Modify a read-only register.
5	Read a write-only register.
6	Cannot get the correct reply from PLC within the specified time range.
7	Use a function code that is not supported by MODBUS Server.

- If [MODBUS Gateway] is enabled, EasyBuilder Pro will cancel the original mapping between MODBUS Server and HMI register. That includes:
  - (1) 0x, 1x mapped to LB
  - (2) 3x, 4x mapped to LW, RW

Therefore, to access data in LB or LW register via 0x, 1x, 3x, 4x, configure the Address Mapping Table again. The following figure is an example.

Table	Description	MODBUS Address		PLC Name	Mapped PLC Address	Table Size	Read/Write
1	0x <==> LB	0x-1	<==>	Local HMI	LB-0	12400 Bit(s)	Read/Write
2	1x <==> LB	1x-1	<==	Local HMI	LB-0	12400 Bit(s)	Read only
3	3x <==> LW	3x-1	<==	Local HMI	LW-0	9999 Word(s)	Read only
4	4x <==> LW	4x-1	<==>	Local HMI	LW-0	9999 Word(s)	Read/Write
5	3x <==> RW	3x-10000	<==	Local HMI	RW-0	55536 Word(s)	Read only
6	4x <==> RW	4x-10000	<==>	Local HMI	RW-0	55536 Word(s)	Read/Write



# 38. Easy Download

This chapter explains how to setup EasyDownload.

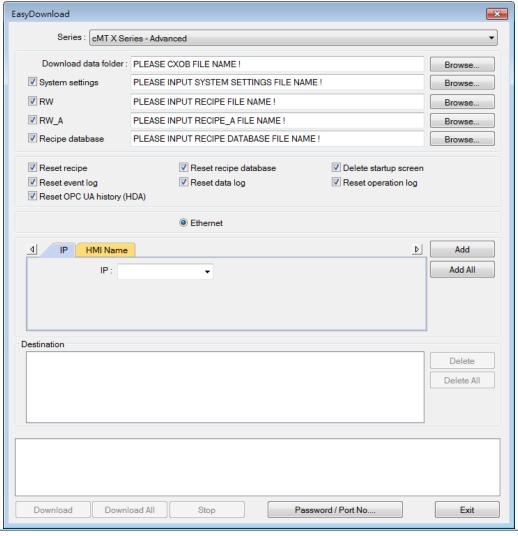
38.1.	Overview	38-2
38.2	Configuration	38-2



# 38.1. Overview

EasyDownload allows downloading the project data file built in EasyBuilder Pro via Ethernet or USB cable. In EasyBuilder Pro main menu select [Project] and then select [Build for SD card/USB disk download] to build the data file before running EasyDownload.

# 38.2. Configuration



Settings	Description	
Series	Select a Series of HMI models.	
	Browse for the project data file to download.	
Download data folder	For cMT Series / cMT X Series / IIoT Gateway Series	
Download data loider	models, select a .cxob file. For non-cMT Series models,	
	select a corresponding folder.	
RW	Browse for the recipe data (.rcp) to download.	



Browse for the recipe data (.rcp) to download.
Browse for the recipe database (.db) to download.
If selected, HMI will reboot after downloading.
The selected files will be erased before downloading.
Download the file to HMI via USB cable. Please make
sure that the USB driver is correctly installed.
Download the file to HMI via Ethernet.
Enter the target HMI IP address.
Enter the target HMI name.
Search by HMI name.
Search from all the HMI names on the same network.
Add the selected HMI in the Search field to the
Destination field.
Add all the HMI in the Search field to the Destination
field.
A list of all the HMI for download.
Delete the selected HMI in the Destination field.
Delete all the HMI in the Destination field.
Click to start download to the selected HMI in the
Destination field.
Click to start download to all the HMI in the Destination
field.
Enter the password and the port number of download
set in HMI system settings.
Non-cMT Series:
Download Password, Port No.  Password: 111111  Port no. of download: 20248 (default: 20248)  OK Cancel







■ Take eMT3000 Series as an example, the built download data directory has the following structure. Please select the parent directory of the generated file when download.

Parent directory	First subdirectory	Second subdirectory
emt3000	001	
	002	
	Pub	driver
		font

- The parent directory name changes according to the model used.
- Downloading to multiple HMI is only supported by Ethernet.
- When downloading the project to multiple HMI at a time, all the HMI must use the same password and port number.
- The downloading process goes from the top of Destination list to the bottom. Only when the downloading of one HMI is done will the downloading of next HMI start.
- To avoid long waiting time for an off-line HMI, the wait time is 3 seconds.
- EasyDownload can download project to 512 HMIs at a time; that is, the maximum allowable number of HMI that can be added into the Destination list is 512.

# 39. Data Security

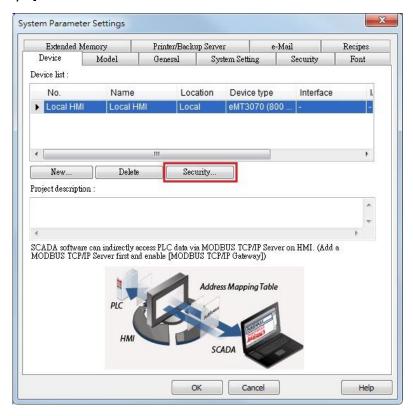
This chapter explains how to setup Data Security.

39.1.	Overview	39-2
39.2.	Configuration	39-2



# 39.1. Overview

Data Security allows setting restrictions on the write operations that modify local Word or Bit register data. To do so, open [System Parameter Settings] » [Device] tab, select [Local HMI] and then click [Security...] button.

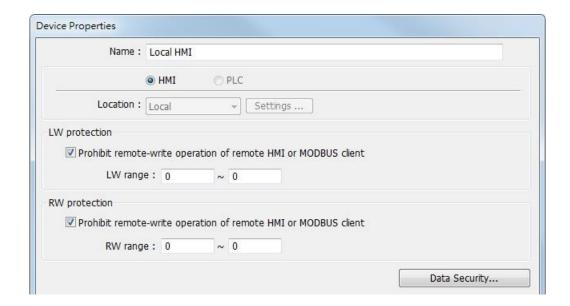


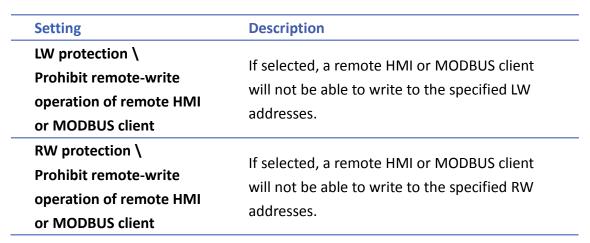
# 39.2. Configuration

The following is the settings dialog box:



Data Security 39-3





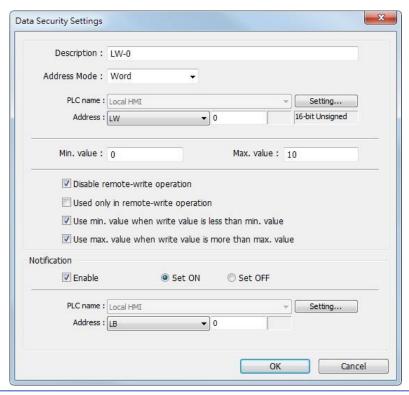
Click [Data Security] button to set the restrictions on the write operations that modify local Word or Bit register data.

# 39.2.1. Word address settings

Set the restrictions relevant to local Word addresses.



Data Security 39-4



Setting	Description
Description	Enter the description or memo about this setting.
Address Mode	Select [Word] to set the relevant attributes.
Min. value	Set the minimum value that can be written to the
	designated word address.
Max. value	Set the maximum value that can be written to the
	designated word address.
Disable remote-write	If selected, the remote HMI will not be able to
operation	write to the protected address.
Used only in	If selected, the range between [Min. value] and
remote-write	[Max. value] is only used to restrict the value
operation	written by a remote device.
Use min. value when	If selected, when the written value is less than
write value is less	[Min. value], the system will write the specified
than min. value	minimum value instead.
	If not selected, when the written value is less
	than [Min. value], the system will keep the
	original value.
Use max. value when	If selected, when the written value is greater than
write value is more	[Max. value], the system will write the specified
than max. value	maximum value instead.

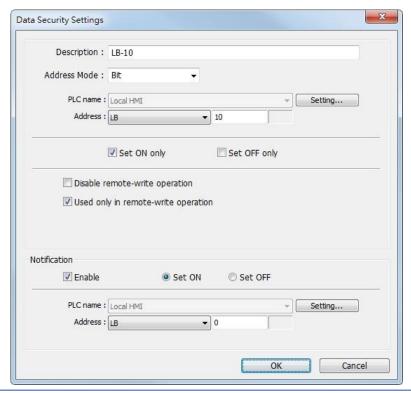


	If not selected, when the written value is greater than [Max. value], the system will keep the
	original value.
Notification	When the written value is not within the specified
	range between [Min. value] and [Max. value], the
	system will trigger the designated notification bit
	address.

As shown in the preceding figure, the remote HMI will not be able to write to LW-0, and when the value written to the local address is greater than 10, the value 10 is written instead, and the notification bit LB-0 will be set ON.

# 39.2.2. Bit address settings

Set the restrictions relevant to local Bit addresses.



Setting	Description
Description	Enter the description or memo about this setting.
Address Mode	Select [Bit] to set the relevant attributes.
Set ON only	If selected, the designated bit address can only be
	set ON.
Set OFF only	If selected, the designated bit address can only be
	set OFF.



Disable remote-write	If selected, the remote HMI will not be able to
operation	write to the protected address.
Used only in remote-write operation	If selected, the specified condition is only used to restrict the write operation by a remote device.
Notification	<ul> <li>When enabled and:</li> <li>Select [Set ON], the system will trigger the notification bit address when attempting to set OFF the protected bit address.</li> <li>Select [Set OFF], the system will trigger the notification bit address when attempting to set ON the protected bit address.</li> </ul>

As shown in the preceding figure, the remote HMI can only set ON LB-10, while the local HMI is not restricted. If the remote HMI attempts to set LB-10 OFF, the system will trigger notification bit LB-0 ON.



# 40. Web Streaming

This chapter explains how to setup Web Streaming.

40.1.	Overview	. 40-2
40.2.	Configuration	. 40-2
40.3.	Operation	. 40-2
40.4.	Applicable Models	. 40-3



Web Streaming 40-2

# 40.1. Overview

With Web Streaming function, video from the USB camera on HMI can be streamed and viewed in web browsers, and third party devices.

Click the icon to watch the demonstration film. Please confirm your internet connection before playing the film.

# 40.2. Configuration

Instead of setting an object in EasyBuilder Pro, Web Streaming is controlled by system registers. To enable Web Streaming, please set bit addresses or use macros to add the following system registers into the project file.

LB-12356: open(set on)/close(set off) web streaming server

LB-12357: web streaming server status. (on: opened / off: closed)

Set LB-12356 on to start Web Streaming, and set LB-12356 off to stop Web Streaming. LB-12357 indicates the streaming status. When LB-12357 is on, Web Streaming is enabled and running. When LB-12357 is off, Web Streaming is stopped.

Web Streaming cannot start when the USB camera is not connected.

# 40.3. Operation

First, please make sure that the Web Streaming browser is enabled and running. To stream video on a browser, enter HMI's IP address with port 8080. For example, if the IP address is 192.168.1.100, please enter:

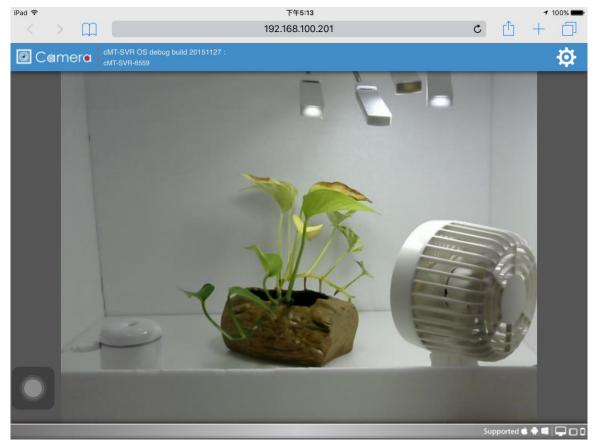
http://192.168.1.100:8080

### **Example 1**

The following is a still image of video stream on iPad's Safari of a plant monitoring application.



Web Streaming 40-3





■ When using EasyAccess 2.0, the HMI's IP address is the virtual IP address obtained in the software.

# 40.4. Applicable Models

Web streaming feature is supported on eMT/mTV/XE/cMT/cMT X Series. Please update the OS versions to those listed in the table below. Models not listed here support web streaming without the need for updating OS.

Model	OS Version
eMT Series	20150525 or later
XE Series / eMT3070B	20150225 or later
mTV	20150508 or later
cMT-SVR	20151117 or later
cMT3090	20171024 or later
cMT3151	20171129 or later



# 41. Energy

This chapter explains how to setup Energy Demand Settings to monitor and record energy consumption and calculate future energy demands.

41.1.	Energy Demand Setting	41	-2
41.2.	Energy Demand Display	41	-6



# 41.1. Energy Demand Setting

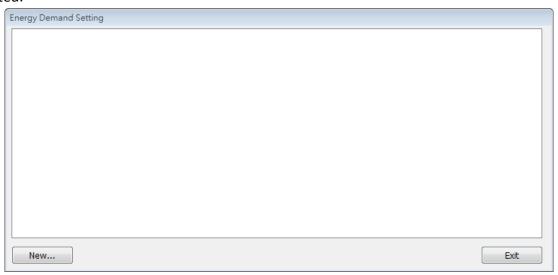
#### **41.1.1.** Overview

By monitoring the recorded energy consumption in a specified period, the Energy Demand Setting feature can calculate future energy demands, and help saving energy.

### 41.1.2. Configuration

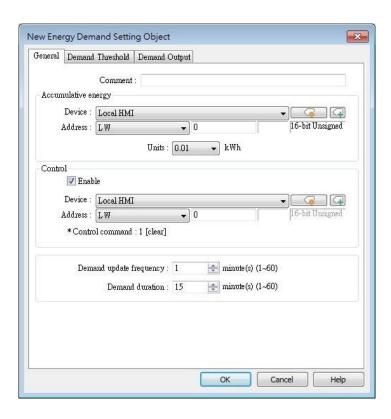


Click [Data/History] and then click [Demand Setting] to open the settings dialog box. Configure General and Demand Threshold settings and click OK; an Energy Demand Setting object will be created.





#### **General Tab**



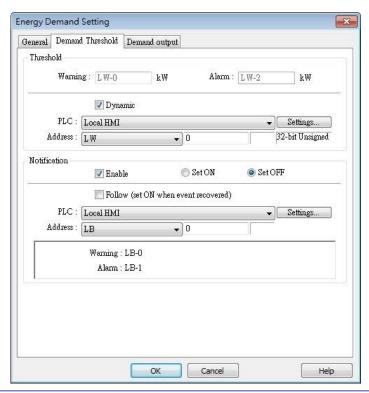
Setting	Description
Accumulative	This address records energy consumption. The unit
energy address	can be 0.1/0.01/0.001 kWh (kilowatt-hours).
Control	Giving control command 1 in the designated address
	can clear the energy consumption record.
Demand update	The frequency to record energy consumption, the
frequency	range is from 1 to 60 minutes.
Demand duration	The frequency to calculate energy demand. The
	range is from 1 to 60 minutes.



Please note that Demand Duration (T) must be an integral multiple of Demand Update Frequency (t).



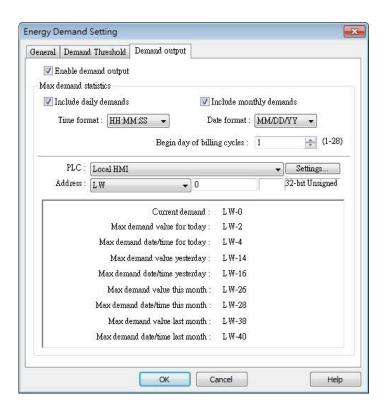
### **Demand Threshold**



Setting	Description
Threshold	When the values in the specified addresses reach
	the values specified in Warning and Alarm fields, the
	warning and alarm will be triggered. The threshold
	limits can be dynamically changed at runtime.
Notification	When the estimated energy demand reaches the
	threshold limit, the status of the specified bit
	address will change accordingly.
Follow	If selected, when the estimated energy demand falls
	less than the threshold limit, the status of the
	notification bit address will return to its original
	state.



### **Demand Output**



Setting	Description
Enable demand	Onens [May demand statistics] settings
output	Opens [Max. demand statistics] settings.
Max demand	The maximum energy demand of today/yesterday,
statistics	and current month/last month, can be recorded in
	the corresponding addresses. The time/date format,
	and the beginning day of the billing cycle, can be
	specified.



# 41.2. Energy Demand Display

#### 41.2.1. Overview

Energy Demand Display object graphs the result from Energy Demand Setting object at runtime.

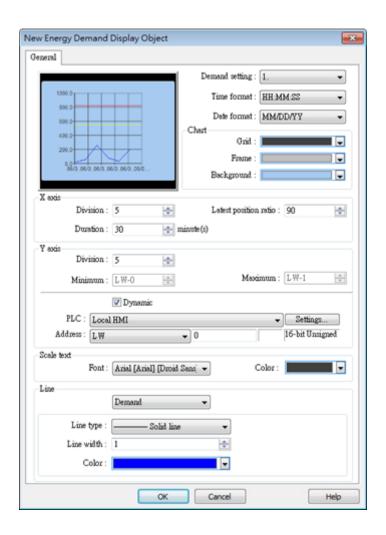
The font, grid and watch line style can be specified, and the threshold limits can be shown in the graph.

#### 41.2.2. Configuration



Click [Data/History] and then click [Demand Display] to open the settings dialog box. Configure the attributes and click OK; an Energy Demand Display object will be created.

#### **General Tab**

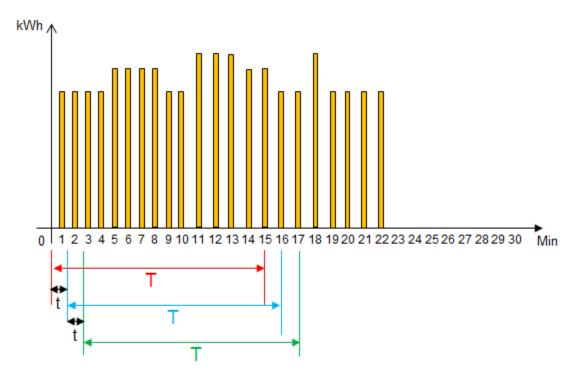




Setting	Description
Object index	Select an existing Energy Demand Setting object as
	the data source of Energy Demand Display object.
Time/Date format	Set Time and Date format.
Chart	Set the colors of Grid, Frame, and Background.
X axis	Set the number of divisions and time duration on
	the X axis. Latest position ratio: The ratio represents
	a position along the X axis, where 50% represents
	the middle and 100% represents the right end. This
	field sets the position to mark the latest data, and
	the acceptable range is: 50%~100%.
Y axis	Set the number of divisions, maximum and
	minimum scale values on the Y axis. The limits can
	be changed dynamically at runtime.
Scale text	Set the font and color of the scale text.
Line	Three watch lines marking Demand, Alarm, and
	Warning can be shown. The type, width, and color of
	the lines can be customized.

# **Example 1**

The following example illustrates the relationship between Demand Duration (T) and Demand Update Frequency (t) mentioned in Energy Demand Setting guide above.





- 1. As shown in the above figure, when t=1, the frequency to record energy consumption will be once per minute. When T=15, each 15 minutes the sum of the energy consumption measured every minute (t=1) will be calculated.
- 2. From the 1<sup>st</sup> to the 15<sup>th</sup> minute (red zone), the energy consumption measured each minute will be added up to get the total sum. The total sum times 4 (15 minutes is a quarter of an hour) to obtain a value (kWh) indicating the estimated energy demand.
- 3. From the 2<sup>nd</sup> to the 16<sup>th</sup> minute (blue zone), the energy consumption measured each minute will be added up to get the total sum. The total sum times 4 (15 minutes is a quarter of an hour) to obtain a value (kWh) indicating the estimated energy demand.
- 4. From the 3<sup>rd</sup> to the 17<sup>th</sup> minute (green zone), the energy consumption measured each minute will be added up to get the total sum. The total sum times 4 (15 minutes is a quarter of an hour) to obtain a value (kWh) indicating the estimated energy demand.
- 5. The Energy Demand Display object will graph the estimated energy demand.
- 6. If t=3 and T=15, the estimated energy demand will be: Sum of the latest 5 records (15/3=5) times 4 (15 minutes is a quarter of an hour).
- 7. If t=5 and T=30, the estimated energy demand will be: Sum of the latest 6 records (30/5=6) times 2 (30 minutes is half an hour).

Click the icon to download the demo project. Please confirm your internet connection before downloading the demo project.



42-1

# 42.**IIoT**

This chapter explains how to use IIoT protocols.

42.1.	MQTT	42-2
42.2.	OPC UA Server	42-30



## 42.1. MQTT

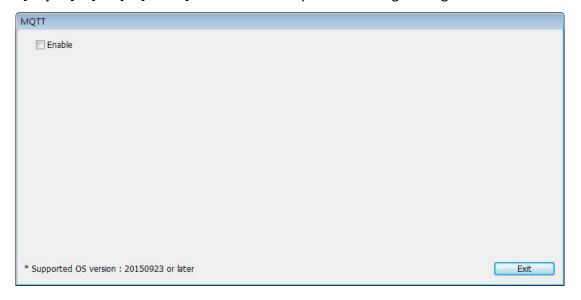
#### **42.1.1. Overview**

MQTT object can publish messages to an MQTT server, or subscribe to topics to receive messages from an MQTT server. HMI can serve as an MQTT server as well. When HMI serves as an MQTT server, it does not send message to another MQTT server.

### 42.1.2. Configuration



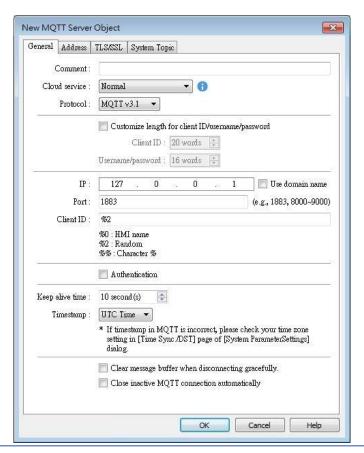
Click [Object] » [IIoT] » [MQTT] in the menu to open the settings dialog box.





#### 42.1.2.1. Server Settings

#### **General Tab**



#### Setting

#### **Description**

#### **Cloud service**

#### Normal

Use general MQTT publish-subscribe service.

#### **AWS IoT**

Use AWS IoT as a Broker, and use Thing Shadows service. For more information, please find "AWS IoT User Manual".

#### Sparkplug B

Sparkplug B is a specification designed based on the characteristic features of IoT applications. It helps define topics and messages that are not specified by standard MQTT, and allows non-MQTT terminal devices to transfer data with MQTT Server through Edge of Network, which can be HMIs in this architecture. Please see "Sparkplug B Quick Start Guide" for more information.

#### **Azure IoT Hub**

Use Microsoft Azure IoT Hub as a Broker. Using this

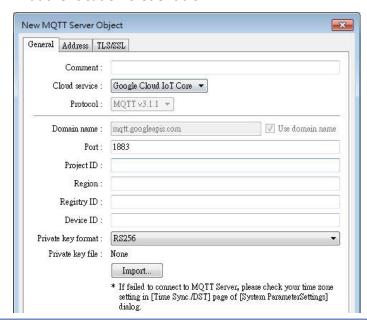


service can simplify setting step to entering a Connection String. The Connection String can be found in Microsoft Azure > IoT devices.



### **Google Cloud IoT Core**

Use Google Cloud IoT Core as a Broker. Using this service requires filling in connection parameters and authentication credentials.



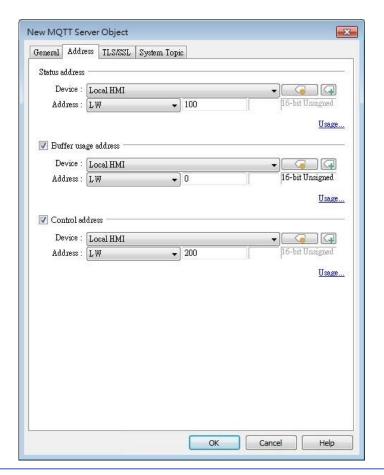
Protocol	Supports MQTT v3.1, v3.1.1, and v5. (v5 is supported only
	for cMT / cMT X Series)
Customize length for Client ID/ username/password	Client ID: The upper limit is 128 words.  Username/Password: The upper limit is 256 words.
IP	Enter the MQTT Server IP address for receiving the message. If 127.0.0.1 is entered, HMI will run a MQTT server locally.
Use domain name	A domain name can be used as MQTT server's IP address.
Port	Enter the MQTT Server port number for receiving the message.
Client ID	Enter the Client ID. Variables can be used for Client ID, for



	example, entering %0 will make the HMI Name to be the Client ID.
Authentication	If selected, connecting MQTT Server will require [Username] and [Password].
Username	Enter the username for connecting MQTT Server.
Password	Enter the password for connecting MQTT Server.
Keep alive time	When MQTT Server does not receive the message from HMI passing the specified time, the HMI will be identified as disconnected.
	Note: When running simulation, the message may be delayed, but the delay will not exceed the [Keep alive time]. The message from the HMI will be sent immediately.
Timestamp	Local time
·	Use local HMI time for timestamp.  UTC time  Use UTC+0 (coordinated universal time) for timestamp.  When the timestamp is shown incorrectly, please go to  [System Parameters] » [Time Sync. / DST] tab to set the time zone.
Clear message buffer when disconnecting gracefully	This option is selected by default. With it selected, when disconnecting gracefully (by entering 2 for the command in MQTT's control addresses), message buffer will be cleared. Messages in the buffer will be retained when this option is not selected.
Close inactive MQTT connection automatically	In this mode, the connection will be automatically terminated if there's no data update for a specified period of time. The connection will resume once any data update occurs.  The user can choose to publish initial values / topic list only at the first connection.  In this mode, the start and stop commands are disabled.



#### **Address Tab**



# **Setting**

# Description

### **Status address**

LW-n: Displays the connection status to MQTT Server.

Value	Description
0	Not attempting to connect to MQTT
	Server.
1	Disconnected and can't connect to
	MQTT Server.
2	Connection succeeded.

LW-n+1: Error indicator.

Value	Description
0	No error
1	Unknown error
2	Failed to connect
3	Access denied
4	Not allowed port number for built-in
	MQTT server



5	Unresolvable domain name
6	Buffer overflowed
32	Incorrect client ID
48	Failed to verify certificate
256	Still connecting

# Buffer usage address

Messages that have not been sent are stored in the buffer. The maximum buffer capacity is 10000 messages. The buffer capacity is measured in percentage (%), rounded up.

LW-n: Shows buffer usage.

#### **Control address**

LW-n: Controls the operation of MQTT Server.

Value	Description
0	Ready
1	Start
2	Stop
3	Update

LW-n+1: Sets the IP address of MQTT Server. LW-n+5: Sets the port number of MQTT Server. LW-n+6: Sets the Client ID for connecting MQTT Server.

LW-n+26: Enables / Disables authentication.

Value	Description
0	Disable
1	Enable

LW-n+27: Sets the username for connecting MQTT Server.

LW-n+43: Sets the password for connecting MQTT Server.

LW-n+59: Sets the domain name for connecting MQTT Server.

When Azure IoT Hub is used, the control addresses are as below:

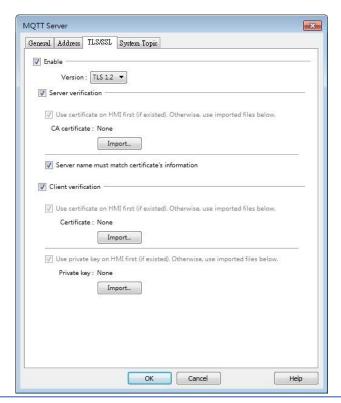
LW-n: Controls the operation of MQTT Server.

Value	Description
0	Ready
1	Start
2	Stop
3	Update



### LW-n+1: Sets the Connection String (128 words).

# **TLS/SSL Tab**



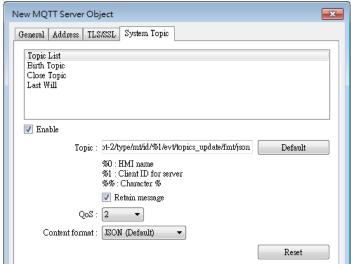
Setting	Description
Enable	Enable TLS/SSL authentication. TLS version can be
	selected from: TLS 1.0, TLS 1.1, and TLS 1.2.
	To use TLS 1.1 and TLS 1.2, HMI OS version must be
	20180323 or later.
Server verification	Enable
	Verify whether the server certificate is signed by CA
	(Certificate Authority). Server certificate is sent from
	server during connection.
	Server name must match certificate's information
	Verify whether the server's domain name or IP
	matches the records in the server certificate.
	Domain name and IP records are stored in Subject
	Alternative Name of the certificate.
Client verification	Private key and client certificate is required for
	server to authenticate the client.

# **System Topic**

Several system topics can be enabled for HMI to publish. When a system topic is enabled for an



HMI, the subscribers of that topic can view the list of available topics and connection status of that HMI.



Setting	Description
Topic List	List of topic sent from HMI to the server upon
	connection.
Birth Topic	The message sent from the HMI after it is connected
	to the server.
Close Topic	The last message sent from the HMI before it
	disconnects knowingly from the server.
Last Will	The message received by the subscriber to Last Will
	when connection between HMI and server is lost
	ungracefully. HMI updates its Last Will message
	when it connects to the server.
Topic	The actual topic name of the system topic.
Retain Message	When this checkbox is selected, the MQTT server
	will save the latest message.
QoS	MQTT provides three levels of reliability, which are
	known as quality of service (QoS). The reliability of
	the message determines the persistence of the
	message.
	QoS 0: At most once, messages are not persistent.
	QoS 1: At least once.
	QoS 2: Exactly once.
<b>Content Format</b>	JSON (Default): Use default content. The following
	are the defaults of each system topic. Actual
	context-dependent values are shown in red:



42-10

```
Topic list:
{
   "d" : {
       "topics" : [
           {
              "compression": "Compression Type",
              "nickname": "Topic Name",
              "topic": "Topic"
           },
           {
              "compression": "Compression Type",
              "nickname": "Topic Name",
              "topic": "Topic"
           }
       ]
   },
   "ts": " Current Time "
}
```

Contents in the topics vary according to the actual topic settings. The above is an example for the case of two topics.

```
Birth Topic:

{
        "d":{
            "connected":true
        },
        "ts":"Current Timestamp"
}

Close Topic:
{
        "d":{
            "connected":false
        },
        "ts":" Current Timestamp"
```



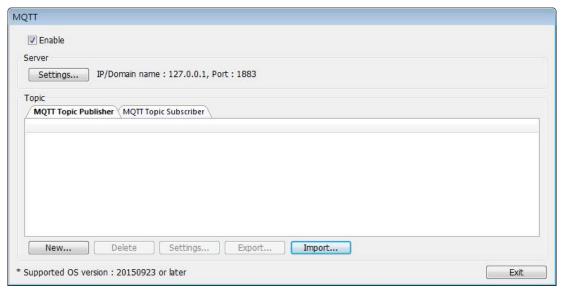
```
}
Last Will:
{
    "d":{
        "connected":false
    }
}
```

JSON (Advanced): Use user-defined content.



- Please note that System Topics tab is not supported when using Sparkplug B, Azure IoT Hub, and Google Cloud IoT Core cloud services.
- Click the icon to watch the demonstration film. Please confirm your internet connection before playing the film.

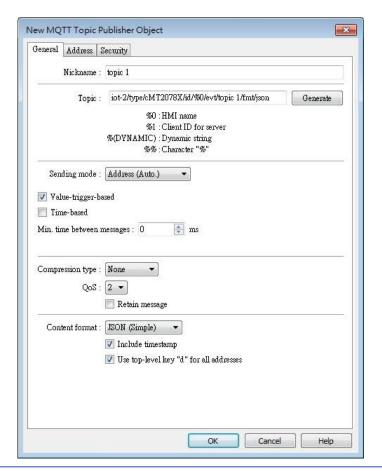
#### 42.1.2.2. MQTT Topic Publisher



Click [New] to open General and Address settings, or click [Import] / [Export] to import or export an existing \*.csv file. The maximum allowable number of topics is 255.



#### **General Tab**



#### Setting Description

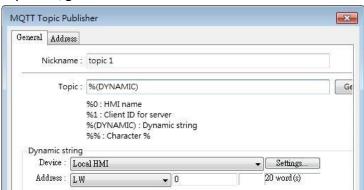
## Nickname

Enter the nickname of the MQTT Topic for easier reference.

# Topic

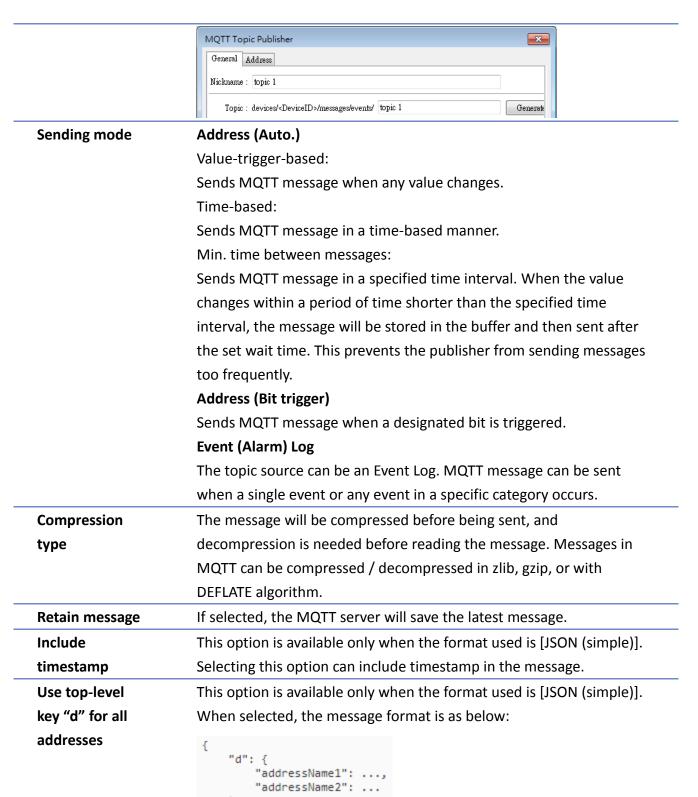
Specify the format of the message topic sent to MQTT Server.

Variables can be used for Topic. Entering %(DYNAMIC) in the Topic field opens Dyanmic String group box for designating a word address. %(DYNAMIC) can include multiple topic levels. For example: myhome/groundfloor.



When Azure IoT Hub is used, users can only specify the last topic level.





When not selected, the message format is as below:

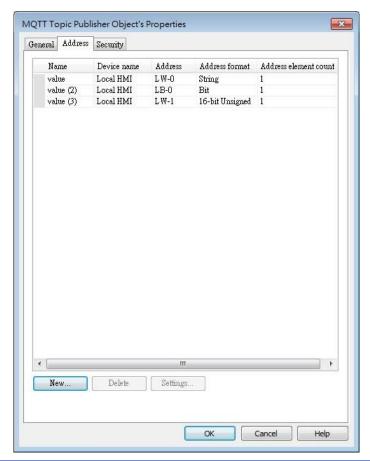


	<pre>{     "addressName1":,     "addressName2":,     "ts": }</pre>
	As shown in the above figure, when this option is not selected, ts and
	address names become keys of the same level. Therefore, please
	avoid using ts as an address name in this case.
QoS	MQTT provides three levels of reliability, which are known as quality
	of service (QoS). The reliability of the message determines the
	persistence of the message.
	0: At most once, messages are not persistent.
	1: At least once.
	2: Exactly once.
<b>Content Format</b>	The supported formats are:
	Raw Data: Data in bytes.
	JSON (Simple): JSON format with all data put in JSON member "d".
	JSON (Advanced): JSON format with flexible JSON structure.

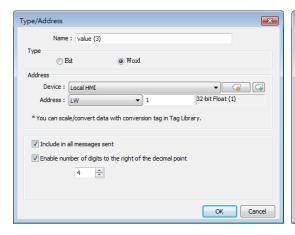
### **Address Tab**

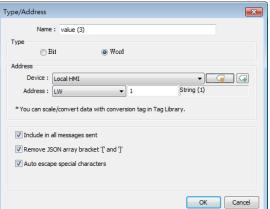
The following explains the address settings for [Raw Data] and [JSON (Simple)] content formats.





Setting	Description
New	Add the source of the topic. The length of each
	address can be specified respectively.
Delete	Delete the address.
Setting	Change the name and address.





Setting	Description
Include in all	When the value from one of the source addresses
messages sent	changes, the data in this address can be included in



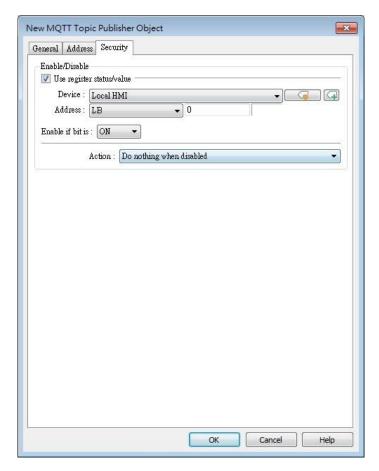
	all the messages sent. This option is available when
	the content format is [JSON (Simple)] or [JSON
	(Advanced)].
Remove JSON array	For JSON formatted messages, selecting this option
bracket "[" and "]"	can remove bracket "[" and "]". This option is
	available when the content format is [JSON
	(Simple)].
Enable number of	When data type is Float, the number of digits after
digits to the right	the decimal point can be specified. This option is
of the decimal	available when the content format is [JSON (Simple)]
point	or [JSON (Advanced)].
Auto escape special	This option is available when the data type is String,
characters (cMT /	and the content format is [JSON (Simple)]. JSON
cMT X Series)	formatted messages may contain special characters
	(e.g. " and \) which can lead to JSON parsing errors.
	With this option selected, special characters in a
	string can be escaped (e.g. change from " to $\$ " and
	change from \ to \\) for successful message parsing.



Maximum tag length: 255 words.



#### **Security Tab**

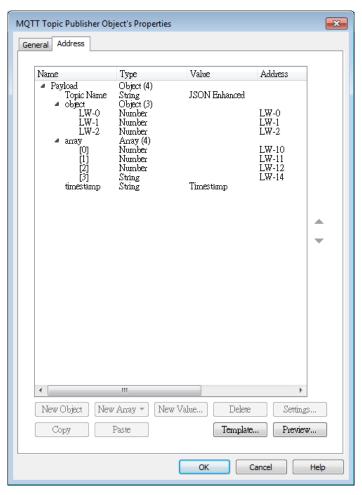


Messages will be published only when the state of the designated address meets the set condition. As shown above, the message will be published when LB-0 is ON.

### Address Tab [JSON (Advanced)]

The following explains address settings for [JSON (Advanced)] content format. This is a nested format that allows using objects or arrays, and customizing timestamp and data name. Using this format provides a more flexible way of using MQTT.





When configure the settings as shown in the above screenshot, the received MQTT message by the subscriber is as below.

```
{
   "Topic Name" : "JSON Enhanced",
   "Object" : {
     "LW-0" : [ 1 ],
     "LW-1" : [ 2 ],
     "LW-2" : [ 3 ]
   },
   "Array" : [ [ 4 ], [ 5 ], [ 6 ], [ "AABBCCDD" ] ],
   "timestamp" : "2019-02-19T06:52:13.846038"
}
```

Setting	Description
New Object	Add a new object. The name, type and value of each
	item under the object can be configured. Items
	under the object are enclosed in curly brackets { }.
New Array	Add a new array. An array may contain multiple
	items but the name of the item is automatically
	generated and is unchangeable. Items under the
	array are enclosed in square brackets [].
New Value	Add a new number, string, or timestamp. When the

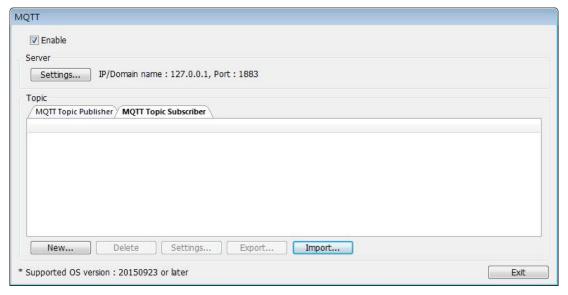


	new value is a number or a string, fixed value can be
	selected, or an address can be designated as the
	data source.
Delete	Delete the selected item.
Settings	Configure the selected item. When the selected item
	is an object or an array, the user may only change its
	name. When the selected item is contained in an
	object or an array, its parameters can be configured.
Сору	Copy the selected item.
Paste	Paste the copied item to the selected row.
Template	By pasting JSON string into the window, the system
	will automatically adjust the data structure setting
	according to JSON structure, saving time for users.
	Create from JSON Template
	Paste JSON text here.



Maximum number of nodes for a Topic is 512 (payload included). Maximum tag length is 255 words.

# 42.1.2.3. MQTT Topic Subscriber



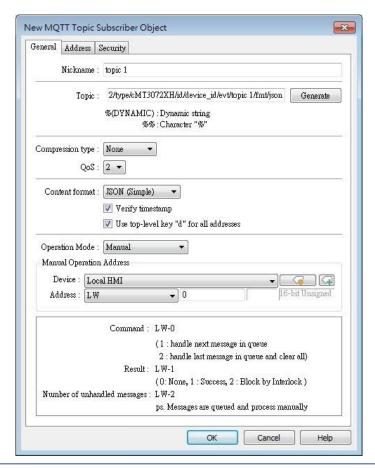
Click [New] to open General and Address settings, or click [Import] / [Export] to import or



export an existing \*.csv file. The maximum allowable number of topics is 255.

#### **General Tab**

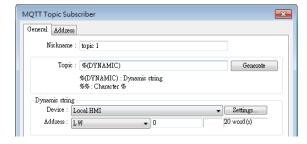
The following explains the address settings for [Raw Data] and [JSON (Simple)] content formats.



Setting	Description
Nickname	Enter the nickname of the MQTT Topic for easier
	reference.
Topic	Subscribe to a topic in MQTT Server. The topic name
	can be dynamic.
	Entering %(DYNAMIC) in the Topic field opens Dynamic
	String group box for designating a word address.
	%(DYNAMIC) can include multiple topic levels. For
	example: myhome/groundfloor.



IIOT **42-21** 



When Azure IoT Hub is used, users can only specify the last topic level, and the topic level should be the same as in MQTT Topic Publisher.



## **Compression type**

Configure with the same setting as MQTT Topic Publisher.

#### **Verify timestamp**

When timestamp is included in the message, selecting this option will verify whether the timestamp is increasing, and update will occur when the timestamp does increase; otherwise, the message will be treated as expired message and update will not occur.

# Use top-level key "d" for all addresses

When selected, the message format is as below:

```
{
    "d": {
        "addressName1": ...,
        "addressName2": ...
},
    "ts": ...
}
```

When not selected, the message format is as below:

```
{
    "addressName1": ...,
    "addressName2": ...,
    "ts": ...
}
```

Please use appropriate setting according to the data source.

#### QoS

MQTT provides three levels of reliability, which are known as qualities of service (QoS). The reliability of the message determines the persistence of the message.



	0: At most once, messages are not persistent.
	1: At least once.
	2: Exactly once.
Content Format	Raw Data: Unformatted raw data.
	JSON (Simple): Single layer JSON format.
	JSON (Advanced): JSON format with user-defined JSON
	structure.
Operation Mode	Operation mode for subscribing topics can be selected.

Operation mode for subscribing topics can be selected. Process immediately: Write the value to the designated address immediately after receiving subscribed data. Manual: Place the subscribed data in a queue before processing the data manually. The queue can hold 100 records.

# **Control address (Manual)**

LW-n: Command

Value	Description
1	Write the oldest data in the buffer to
	the designated address. If there are
	10 records in the buffer, the user can
	enter command 1 for ten times to
	write the data to the address
	sequentially.
2	Write the latest data in the buffer to
	the designated address, and then
	clear all data in the buffer.

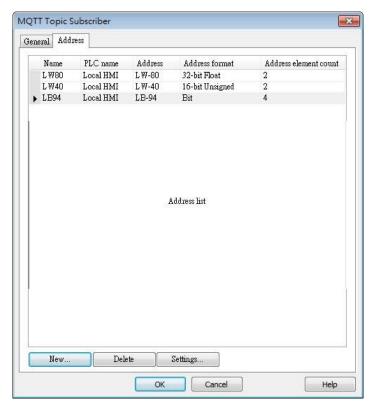
#### LW-n+1: Execution Result

Value	Description	
0	The buffer is currently empty.	
1	The command is executed	
	successfully.	
2	The topic subscription is blocked so	
	command execution failed. (See	
	Security tab in this chapter.)	

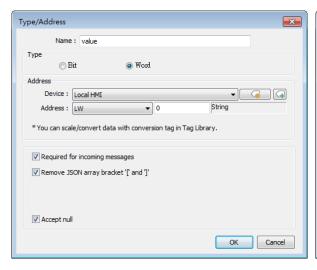
LW-n+2: Number of unhandled messages
Displays the number of messages in the buffer.

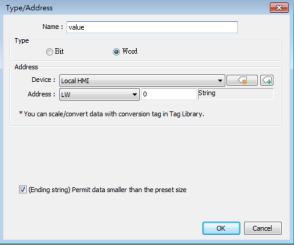


#### **Address Tab**



Setting	Description
New	Add the destination address of the subscribed topic.
	The length of each address can be specified respectively.
Delete	Delete the address.
Setting	Change the name and address.



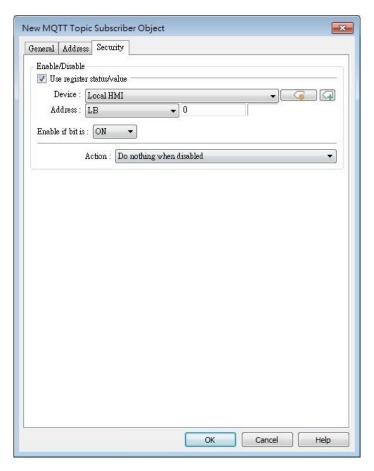




Setting	Description
Required for	When the value from one of the destination
incoming messages	addresses changes, the data in this address must be
	included in all the messages received. This option is
	available when the content format is [JSON (Simple)]
	or [JSON (Advanced)].
Remove JSON array	For JSON formatted messages, selecting this option
bracket "[" and "]"	can remove bracket "[" and "]". This option is
	available when the content format is [JSON
	(Simple)].
Accept null	Null can be accepted. This option is available when
	the content format is [JSON (Simple)] or [JSON
	(Advanced)].
(Ending string)	A string that has a length shorter than the preset
Permit data smaller	length can be accepted. This setting is effective only
than the preset size	for the ending string, and it will not be effective
	when the string is followed by other values or bit
	data. This option is available when the content
	format is [Raw data].



# **Security Tab**

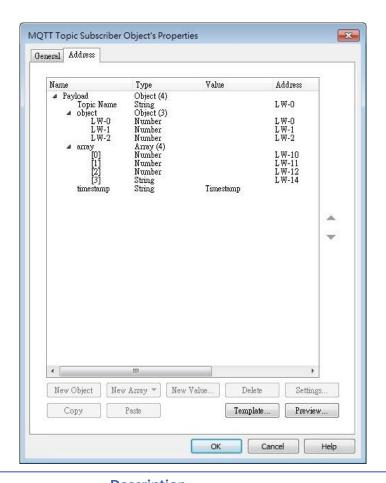


Messages will be subscribed only when the state of the designated address meets the set condition. As shown above, the message will be subscribed when LB-0 is ON.

### Address Tab [JSON (Advanced)]

The following explains address settings for [JSON (Advanced)] content format. This is a nested format that allows using objects or arrays, and customizing timestamp and data name. Using this format provides a more flexible way of using MQTT.





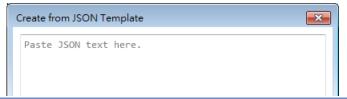
Setting	Description
New Object	Add a new object. The name, type and value of each
	item under the object can be configured. Items
	under the object are enclosed in curly brackets { }.
New Array	Add a new array. An array may contain multiple
	items but the name of the item is automatically
	generated and is unchangeable. Items under the
	array are enclosed in square brackets [].
New Value	Add a new number, string, or timestamp. When the
	new value is a number or a string, fixed value can be
	selected, or an address can be designated as the
	data source.
Delete	Delete the selected item.
Settings	Configure the selected item. When the selected item
	is an object or an array, the user may only change its
	name. When the selected item is contained in an
	object or an array, its parameters can be configured.
Сору	Copy the selected item.
Paste	Paste the copied item to the selected row.



42-27

### **Template**

By pasting JSON string into the window, the system will automatically adjust the content according to JSON structure, saving time for users.





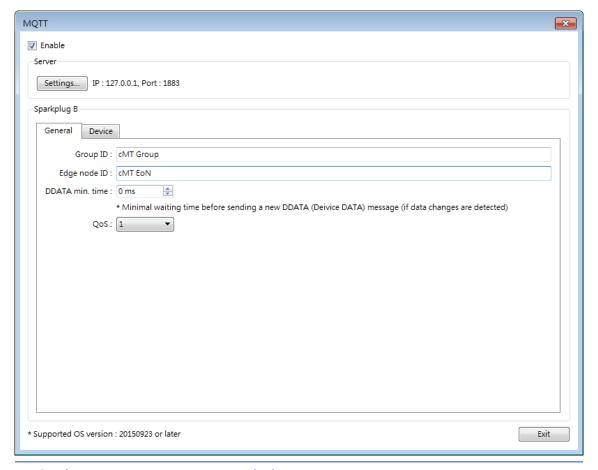
- Amazon Web Service (AWS) IoT Core supports standard MQTT protocol. However, please note the following restrictions:
  - 1. The maximum number of layers in a topic is 8 (iot-2/type equals to 2 layers).
  - 2. Authentication in General tab is not supported, please use TLS/SSL.
  - 3. Supports only Qos 0 and Qos 1.
  - 4. Retaining the latest message in MQTT server is not supported.

### 42.1.2.4. Sparkplug B

General settings and Device settings for cloud service Sparkplug B are as shown below.



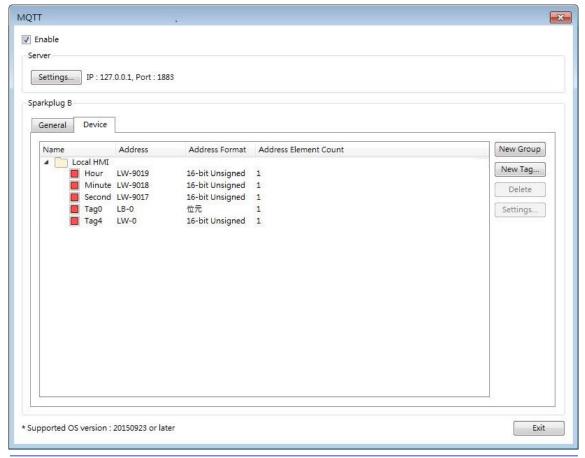
#### **General Tab**



Setting	Description
Group ID	The group ID that identifies the group in which the
	Edge of Network Nodes belong to.
Edge ID	The ID that identifies a specific Edge of Network
	Node.
DDATA min. time	The minimum-wait-time duration before a new
	DDATA (Device DATA) message is sent when data
	change is detected.
QoS	MQTT provides three levels of reliability, which are
	known as qualities of service (QoS). The reliability of
	the message determines the persistence of the
	message.
	0: At most once, messages are not persistent.
	1: At least once.
	2: Exactly once.



#### **Device Tab**



Setting	Description
New Group	Add a group to manage the tags.
New Tag	Add the tags of this EoN node monitored by MQTT engine. Please note that the Name field should not be blank.
Delete	Delete an existing group or tag.
Settings	Configure an existing group or tag.

Click the icon to download the demo project. Please confirm your internet connection before downloading the demo project.



# 42.2. OPC UA Server

#### 42.2.1. Overview

OPC UA (Unified Architecture) is a communication technology often used in industrial automation fields. OPC UA features cross-platform interoperability, unified access, standardized communication, and security. In this architecture, cMT / cMT X Series HMI models with built-in OPC UA server play a key role as Communication Gateway, and allow OPC UA clients to access HMI or PLC data by subscribing to tags to receive real-time updates. This new architecture can help you achieve vertical integration.

# Hardware & Software requirements:

- HMI Model: cMT / cMT X Series models. \*A license must be loaded for cMT-SVR / cMT-SVR-200 and cMT-HDM / cMT-FHD / cMT-FHDX.
- Software: EasyBuilder Pro V5.06.01 or later
- Recommended OPC UA Client: Unified Automation UaExpert

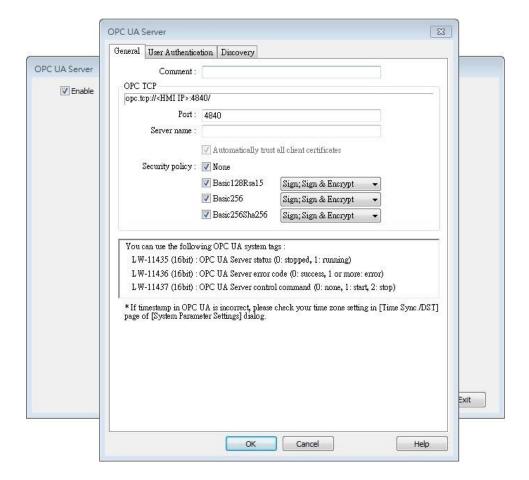
# 42.2.2. Configuration



Click [Object] » [IIoT] » [OPC UA Server] in the menu to open the settings dialog box.

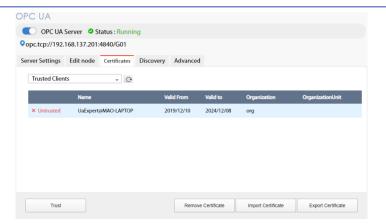


#### **General Tab**



Setting	Description
Comment	The description about the OPC UA Server.
OPC TCP	The URL of the server.
Port	The port number for the clients to connect with OPC
	UA Server. The default port number is 4840.
Server name	The server name, this field is allowed to remain blank.
	[Automatically trust all client certificates]
	This option is enabled by default, but may be toggled
	for cMT Gateway series only. When this option is
	disabled, all OPC UA clients will be refused connection
	unless their corresponding client certificates have
	been trusted in the OPC UA web interface like shown
	below:



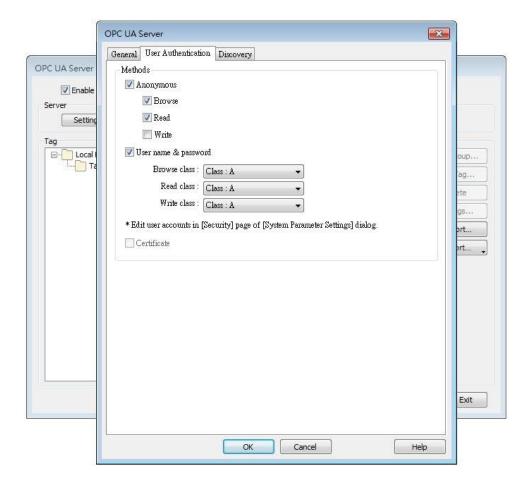


Note: According to OPC UA specification, an OPC UA client, in making a connection, will use a client certificate which will be checked by the OPC UA server for its legitimacy. The exception is if the security policy allows for the "None" option.

# **Security Policy**

Configure the security policy and available algorithms that can be used by clients.

#### **User Authentications Tab**

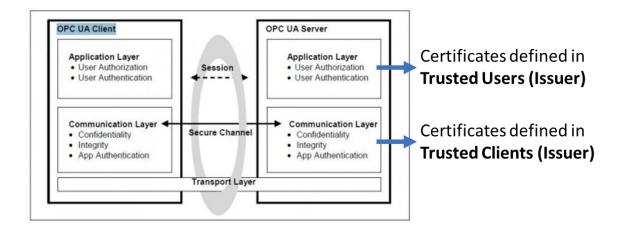




Setting	Description
Methods	Anonymous
	Grant Browse, Read, Write permissions to
	anonymous login by selecting the checkboxes.
	User name & password
	Use the same user name and password as HMI. The
	permissions are granted to the security classes
	specified in System Parameter Settings » Security.
	Certificate
	This option is available only for cMT Gateway series
	OPC UA client may use certificates as authenticatio
	method instead of username-and-password metho
	to login. Use web interface to configure
	trusted/untrusted user certificates, as shown below
	OPC UA
	OPC UA Server Status : Running Opc.tcp://192.168.137.201:4840/G01
	OPC UA Server Status : Running Opc.tcp://192.168.137.201:4840/G01 Server Settings Edit node Certificates Discovery Advanced
	• opc.tcp://192.168.137.201:4840/G01



- OPC UA security layers can be split into
  - (1) communication layer (e.g. SecurityPolicy)
  - (2) application layer, as shown in the image below:



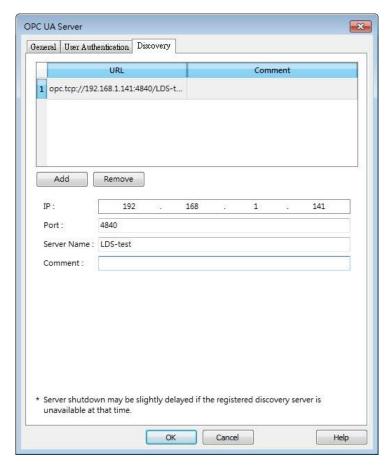


Security Layers (from <a href="http://wiki.opcfoundation.org/index.php/File:SecurityLayers.jpg">http://wiki.opcfoundation.org/index.php/File:SecurityLayers.jpg</a>)

- Client certificate is at communication layer and its use is required when using SecurityPolicy other than None.
- User certificate is at application layer and using it is one of the ways for authentication.



# **Discovery Tab**



When configured, OPC UA server will register to the Local Discovery Server (LDS).

OPC UA Discovery service is used to simplify server location maintenance when there are many
OPC UA servers in the network. An OPC UA client can access one LDS Server and obtain all

OPC UA servers in the network. An OPC UA client can access one LDS Server and obtain all registered OPC UA server.

Setting	Description
IP	IP address of the OPC UA client.
Port	Port number used by the OPC UA client.
Server Name	Server name of the OPC UA client.
Comment	A memo on the server and will not influence
	communication.

# **Example 1**

The following is an example showing how to set up Discovery service.

Install Local Discover Server (LDS) on a PC (for example, the PC name is DESKTOP-ABCD).
 Download the LDS provided by OPC Foundation from the link below:
 <a href="https://opcfoundation.org/developer-tools/developer-kits-unified-architecture/local-discovery-server-lds/">https://opcfoundation.org/developer-tools/developer-kits-unified-architecture/local-discovery-server-lds/</a>

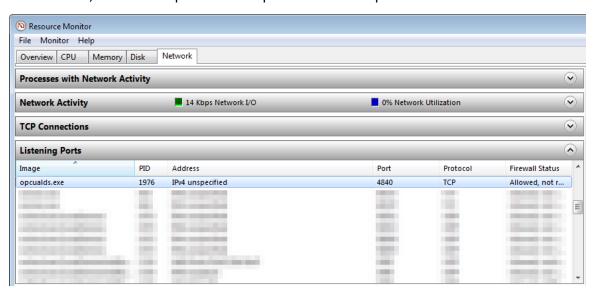


42-36

- 2. If the DNS service of router cannot resolve the HMI name to IP address, the HMI name should be changed to the IP address of the HMI. For example: If HMI IP address is 192.168.1.100, then the HMI name should be 192.168.1.100 or 0.0.0.0.
- 3. On the PC with OPC UA LDS installed, please manually copy the certificate from folder "C:\ProgramData\OPC Foundation\UA\pki\rejected\certs" (Folder for rejected certificates) to folder "C:\ProgramData\OPC Foundation\UA\pki\trusted\certs" (Folder for trusted certificates).
- 4. Launch the software of OPC UA Client, enter the name of the PC with OPC UA LDS installed or its IP address to obtain all the registered OPC UA servers.

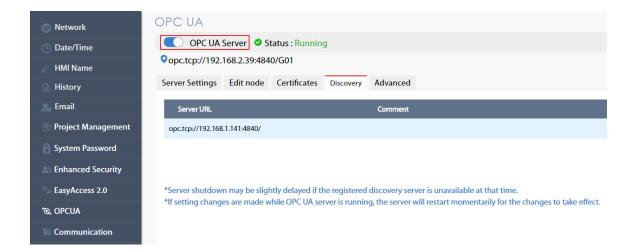
# When Discovery does not work properly, please:

 Open Windows Task Manager » Performance » Resource Monitor » Network » Listening Ports, and find the port number used by opcualds.exe. As shown in the following screenshot, in this example the PC's opcualds.exe uses port 4840.

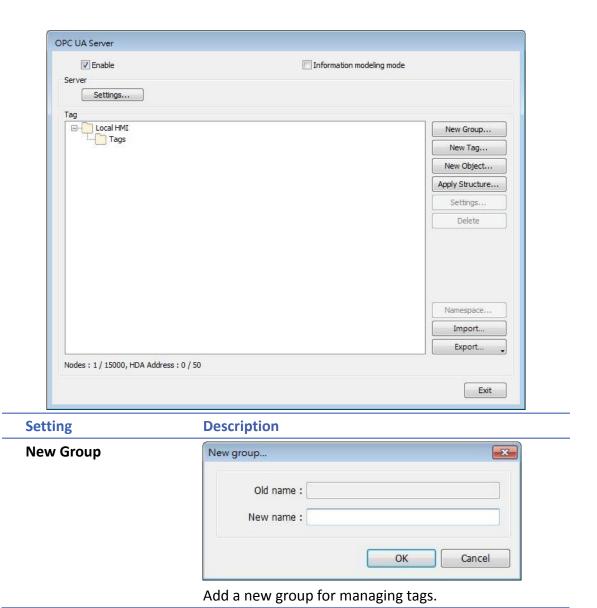


2. Enter HMI's IP address in the web browser, and enter the password to log in. Open OPC UA settings page and restart OPC UA Server. Please note that OPCUA settings tab is only supported on cMT Gateway Series models.



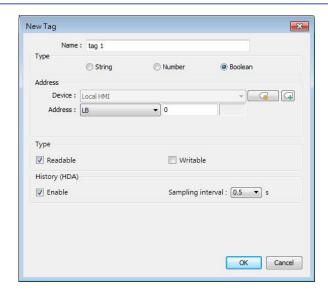


#### Tag





# **New Tag**



Add a new tag for the client to monitor or control.

The name must be specified, and the address can be Readable or Writeable.

# History(HDA)

Enable OPC UA HDA.

# **Apply Structure**



Structured node set under a device can be added, only if the device is a symbolic PLC and has structured data type defined.

After clicking OK in the Apply Structure window, a prompt window shows asking whether to create nodes that do not exist in the OPC UA node tree.

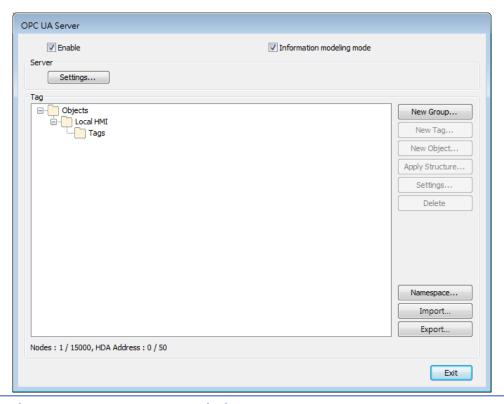


Settings	Set an existing group or tag.
Delete	Delete an existing group or tag.
Import	Import a tag file. Applicable import formats include: *.xlsx, *. xls, *.csv, *. xml
Export	Export current tags. Applicable export formats



# include: Excel format or XML format.

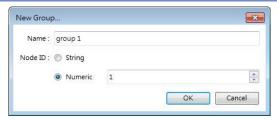
# Tag – Information Modeling Mode



# **Setting**

# Description

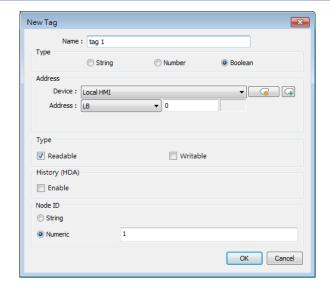
# **New Group**



Add a new group for managing tags. A Node ID can be defined.



# **New Tag**



Add a new tag for the client to monitor or control. Two types of tags can be added: Data Variable and Property.

Data Variable: The data collected by the device. New tags, either data variable or property, can be added under a data variable.

Property: The parameters of the device. No new tags can be added under a property.

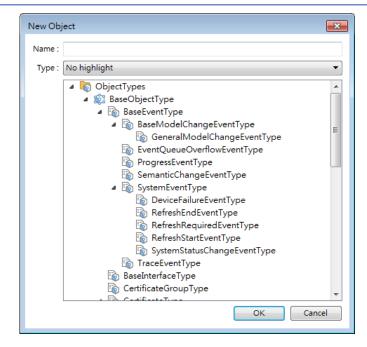
The name must be specified, the address can be Readable or Writeable, and a Node ID can be defined.

# History(HDA)

Enable OPC UA HDA.

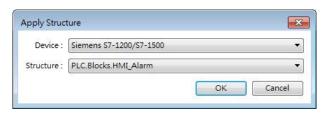


# **New Object**



Add an object in the Object Types list. The name must be specified.

# **Apply Structure**



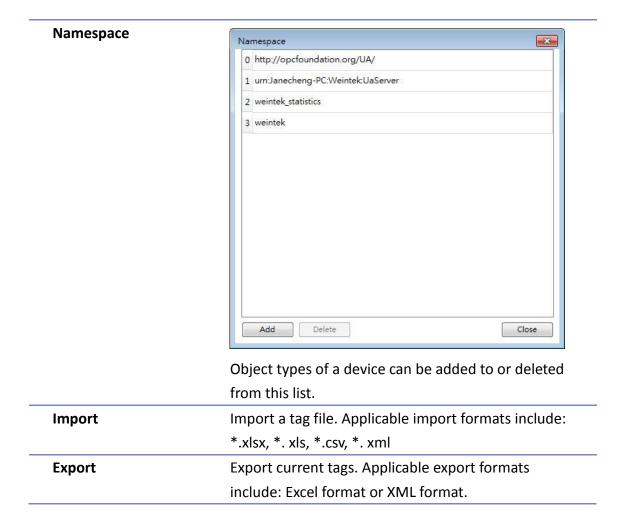
Structured node set under a device can be added, only if the device is a symbolic PLC and has structured data type defined.

After clicking OK in the Apply Structure window, a prompt window shows asking whether to create nodes that do not exist in the OPC UA node tree.



Settings	Set an existing group or tag.
Delete	Delete an existing group or tag.





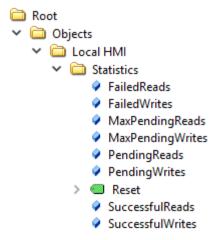


- When downloading the project file to HMI, please make sure that the HMI time and time-zone settings are correct. Otherwise, the client program may not be able to authenticate, and the communication may fail due to authentication error caused by incorrect certificate valid time.
- Changing from Information Modeling Mode back to general mode is possible but please note that the node definition will be lost by doing so.
- Click the icon to watch the demonstration film. Please confirm your internet connection before playing the film.

#### 42.2.3. Device Statistics

Device-specific statistical data can be found in "Statistics" node, as shown below:





# Meaning of each node:

Node Name	Description
FailedReads	No. of failed read commands. If it is not zero, there may
	be communication errors.
FailedWrites	No. of failed write commands. If it is not zero, there may
	be communication errors.
MaxPendingReads	Max. no. of pending read commands.
MaxPendingWrties	Max. no. of pending write commands.
PendingReads	No. of pending read commands in the queue. If the
	number stays high for a long time, it means the
	communication module is not able to process all
	commands in time. OPC UA nodes may update slower.
	Under extreme circumstances (e.g. >30), OPC UA node
	may not update in a long time.
PendingWrites	No. of pending write commands. Write commands have
	higher priority than read commands. If PendingWrites
	stays high, it will affect read commands.
Reset	Reset all statistical data.
SuccsessfulReads	No. of successful read commands.
SuccsessfulWrites	No. of successful write commands.

# 42.2.4. Limitation

The limitation of OPC UA server are listed below:

Item	Description
OPC UA Profile	UA 1.02 Standard UA Server Profile, including but not
	limited to
	* Core Server Facet



IIOT **42-44** 

	1
	* UA-TCP UA-SC UA-Binary
	* SecurityPolicy – None
	* Enhanced DataChange Subscription Server Facet
	* Standard DataChange Subscription Server Facet
	* Embedded DataChange Subscription Server Facet
	* User Token – X509 Certificate Server Facet
	* User Token – User Name Password Server Facet
	* Standard DataChange Subscription Server Facet
	* Embedded DataChange Subscription Server Facet
	See Profile Reporting Visualization Tool by OPC
	Foundation for more details.
Security policies	None
	Basic128Rsa15
	Basic256
	Basic256Sha256
Number of nodes	15 000
Max. array size	255
Read cache	100ms
	(Cache will be used for 100ms from previous read)
Max. client sessions	100
Max. subscription per	64
session	
Min. publishing interval	100ms
OPC UA HDA	Supports up to 50 node addresses with each node
	address can storing up to 10000 HDA data records.
	What constitutes a node address?
	Each HDA-enabled node is considered to take up the
	number of node addresses that is equal to the Element
	Count setting. If the data type is String, it is the No. of
	word setting instead.
	When the remaining space in HMI memory is less than
	10%, the system will delete the earliest data and store
	the latest data. The system will stop deleting data when
	the remaining space increases exceeding 10%.
Performance (Values may ch	ange for different hardware/EBPro version)
Max. Read/Subscribe	Built-in registers (e.g. LW): 27000 words/second (WPS)



Throughput	MODBUS RTU@9600bps: 500 WPS
(Security: None)	MODBUS RTU@115200bps: 4000 WPS
	MODBUS TCP/IP: 10000 WPS
	Tested Environment
	EBPro version: V6.02.02.242
	cMT-G02 OS version: 20180917
	Test uses as many as words as possible in one node
	(using array) to optimize reading.



Examples showing how to count OPC UA HDA node addresses:

If there are 50 nodes (node1, node2...node50) and each node maps to one bit only(Element Count is 1), all the nodes altogether takes up 50 node addresses.

If a node maps to a 16-bit unsigned array of size 50 (which is when Element Count is 50), every element in the array takes up a node address, so the number of node addresses taken by this node is 50.

If a node maps to a string where No. of word is set to 50, the number of node addresses taken by this node is 50.



This manual explains the usage and syntax of JS Object and JS Library.

43.1.	Overview	43-2
43.2.	JS Object	43-3
43.3.	JS Resource	43-6
43.4.	Demonstrations	43-8
43.5.	Limitations	43-21
43.6.	How a JS object operates behind the scenes	43-21



# 43.1. Overview

JS objects can be used to meet the requirements in HMI applications that may not be achieved with only built-in features in EasyBuilder Pro. By programming in JavaScript, the look and behavior of objects can be freely controlled to achieve the intended goals.

# 43.1.1. Usage Suggestions

Use the built-in features in EasyBuilder Pro where possible, and use JS objects only when the requirements are difficult or impossible to fulfill by using the built-in features.

# 43.1.2. Hardware and Software Requirements

- EasyBuilder Pro V6.05.01 or later
- Applicable JavaScript version: ECMAScript 2017 (Not including SharedArrayBuffer and Atomics)
- Eligible HMI model: cMT X Series
- JS objects are not supported on 32-bit Android devices.

# 43.1.3. Warning

JS objects provide powerful customization features, but using them incorrectly can result in system error or performance degredation. Please use JS objects carefully.

# 43.1.4. JS Object SDK

For more information on SDK supported by JS object, visit this link:

https://dl.weintek.com/public/Document/JS Object SDK/Current/index.html



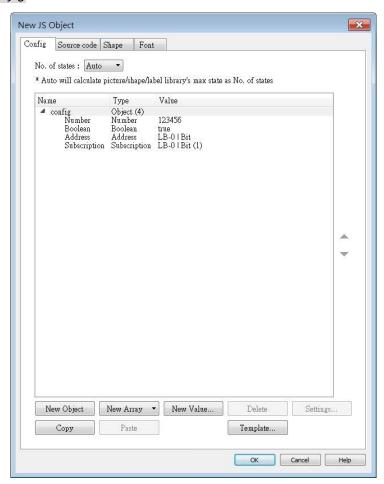
# 43.2. JS Object

# **Config Tab**

JS object property configuration may contain the following types of data:

- 1. Address
- 2. Subscription
- **3.** The parameters defined by users according to the needs to determine the runtime behavior of a JS object.

Configuration will be wrapped into a JavaScript object: 'config' and injected to the JS object at runtime  $\Rightarrow$  *this.config*.



Setting	Description
New Object	Add a new JavaScript object which can have multiple properties and each property has a name and a value.
New Array	Add a new array.
New Value	Add a new property with the following data types to choose from:



	String
	Maximum allowable size is 1000 words.
	Number
	Supports 64-bit float.
	Boolean
	May be True or False.
	Address
	The address of the device.
	Subscription
	Address subscription. Address subscription is used to monitor data
	change of designated device data. Once data changes, the system
	will notify the subscriber through the callback function registered
	in Subscription.onResponse method.
Delete	Delete a selected item.
Settings	Edit a selected item.
Сору	Copy the selected item.
Paste	Paste the copied item to the selected place.
Template	Show current configuration in JSON format in an editing window.
	After editing the JSON content and then clicking the [OK] button,
	the (JSON) content will be parsed and converted back to the
	configuration. Users who are familiar with JSON can expedite
	configuration process using this.

# **Source Code Tab**

The source code is written in JavaScript and it determines the runtime behavior of the JS object.





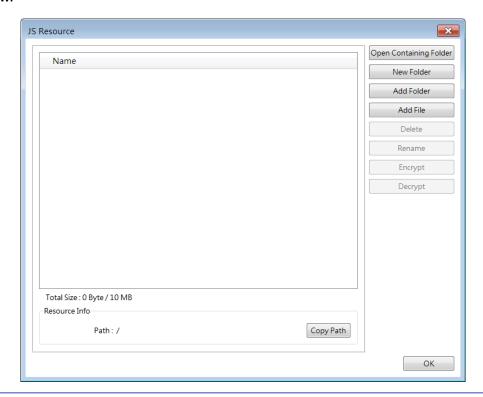
Setting	Description	
Compile 🗹	Compile the source code to check if it works properly.	
C	Edit the source code in a separate pop-up window.	
JS Object SDK	Open the JS Object SDK Documentation link, which provides	
	assistance to developers in creating and writing JS objects.	



# 43.3. JS Resource

When using external JS modules for JS objects, please add the JS modules into EasyBuilder Pro project's JS Resource first, and then the modules can be imported in the [source code] of JS objects.

The screenshot below shows an example of JS Resource, and the settings are explained in the table below.



Setting	Description
Open Containing	When opening a project, EasyBuilder Pro will create a temporary
Folder	folder and extract JS Resource content in this folder. When
	saving a project, EasyBuilder Pro will synchronize the content in
	this folder to the project.
New Folder	Create a new folder.
Add Folder	Import a folder.
Add File	Import a file.
Delete	Delete a file or a folder.
Rename	Rename the folder or JS Resource.
Encrypt	Encrypt imported .js files into .js.enc files. Opening the
	encrypted file directly will display garbled text.
Decrypt	Decrypt .js.enc files using the password set during encryption to



	restore the original content.
Copy Path	Copy a selected path of a file or a folder for use in the source
	code of JS object.

# Note

- Size limit of JS Resource: 10MB.
- The containing folder is generated automatically when opening the project, and is deleted automatically when closing the project.
- The name of the containing folder is not fixed and is randomly generated when opening the project.
- Making changes in the containing folder will turn the project into Modified state and the content in this folder will only be synchronized to the project when the user saves the project.
- The maximum password length for encryption: 32 Bytes.



# 43.4. Demonstrations

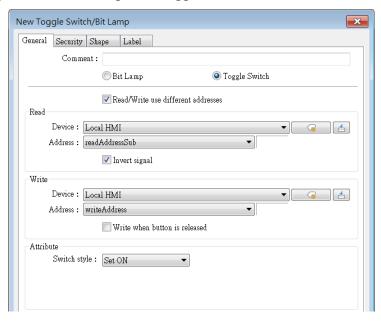
This chapter demonstrates some examples aiming to help users learn how to use JS object. For more information on the functions and classes used for the program code, please see JS Object SDK

# 43.4.1. Mimic a [Toggle Switch] object

This section aims to familiarize users with the configuration by making JS objects work as Toggle Switches. The configuration steps are as below:

- 1. Design a JS object that can read the designated address and invert signal.
- 2. Enable the ability to set the designated address ON for the JS object.
- 3. Enable the ability to set the designated address OFF for the JS object.
- 4. Enable the ability to invert the state of the designated address for the JS object.
- 5. Enable momentary control feature for the JS object.

To design a JS object to achieve the functions of a Toggle Switch, the property names of the JS object that correspond to the settings of a Toggle Switch are shown below.



# 43.4.1.1. JS Object that Reads Address and Invert Signal

This section explains how to create a JS object to read the designated address and invert signal. To achieve the goal, two properties should be added: readAddressSub and invertSignal.



# **Config Tab**

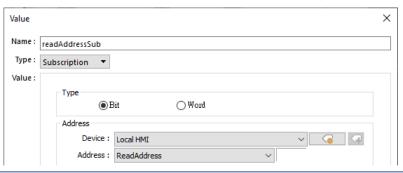


# **Setting**

# Description

# readAddressSub

Read the state of the designated bit address. Set [Type] to [Subscription], set [Value Type] to [Bit], and set address to [LB-100].



# invertSignal

Select whether or not to invert signal. Set [Type] to [Boolean], set [Value] to [false] (don't invert signal)



# **Source Code Tab**

This section explains the source code line by line.



43-10

```
this.config.readAddressSub.onResponse((err, data) => {
   if (err) {
      console.log('[response] error =', err.message);
   } else if (this.config.invertSignal) {
      this.state = (data.values[0]) ? 0 : 1;
   } else {
      this.state = (data.values[0]) ? 1 : 0;
   }
}
});
```

- Line2: 'this' is the JS object. Through 'this.config' < object > to obtain the value ('readAddressSub' and 'invertSignal') added in [Config] tab.
- Line2: Call 'onResponse' function of the 'this.config.readAddressSub' < Subscription > and register response callback to get notification when the value of the read address changes.
- Line 3~9: Act according to the response callback.
- Line 3~4: Check whether an error has occurred. Output an error message to the debugging console if an error has occurred (variable err has meaningful value).
- Line 5~8: If variable err is Null, it means that reading from the Read Address is successful and change in data has been detected. Then, set JS object state according to the data read and the 'invertSignal' property.

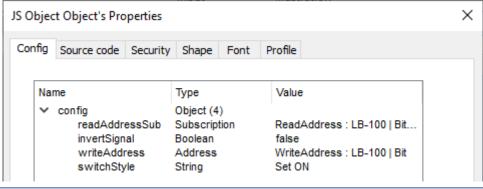
Data in Read Address	Invert Signal	JS Object State
0	False	0
1	False	1
0	True	1
1	True	0

# 43.4.1.2. Toggle Switch ON Mode

Following the preceding section, this section explains how to make a JS object work as a Toggle Switch that can set ON. To achieve the goal, another two properties should be added: writeAddress and switchStyle.



# **Config Tab**



Setting	Description	
readAddressSub	Read the state of the designated address.	
invertSignal	Invert output signal.	
writeAddress	Set the address to write to. When the user presses this object, the	
	value will be written to this address according to the value of	
	'switchStyle'.	
switchStyle	Set the switch mode and set [Value] to [Set ON].	
	Value X	
	Name: switchStyle	
	Type: String ▼	
	Value : Set ON	

#### **Source Code Tab**

```
this.config.readAddressSub.onResponse((err, data) => {
    if (err) {
        console.log('[response] error =', err.message);
    } else if (this.config.invertSignal) {
        this.state = (data.values[0]) ? 0 : 1;
    } else {
        this.state = (data.values[0]) ? 1 : 0;
    }
});
var mouseArea = new MouseArea();
this.widget.add(mouseArea);
mouseArea.on('mousedown', (mouseEvent) => {
    if (this.config.switchStyle === 'Set ON') {
        driver.setData(this.config.writeAddress, 1);
    }
});
```



Use MouseArea object to carry out write operation when the object is pressed or released.

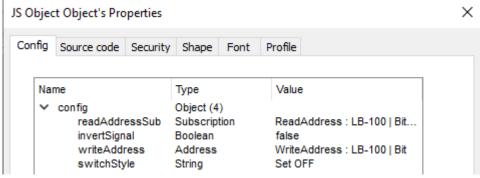
- Line 1~11: Please see Ch43.4.1.1 in this user manual.
- Line 12: Create a MouseArea object named 'mouseArea'.
- Line 13: The 'this.widget' <Container> represents the graphical widget of JS object. This widget is responsible for image display and user interaction.
- Line 13: Add 'mouseArea' to JS object.
- Line 15: Register 'mousedown' event listener with 'mouseArea'. When the user presses the object, 'mouseArea' will notify the listener with a MouseEvent object.
- Line 15~19: The listener to 'mousedown' event.
- Line 16~18: When [Switch Style] is 'Set ON', value 1 will be written into [Write address] using driver module's setData Method.



# 43.4.1.3. Toggle Switch OFF Mode

Following the preceding sections, this section explains how to make a JS object work as a Toggle Switch that can set OFF.

# **Config Tab**



Setting	Description
readAddressSub	Read the state of the designated address.
invertSignal	Invert output signal.
writeAddress	Set the address to write to. When the user presses this object, the value will be written to this address according to the value of 'switchStyle'.
switchStyle	Set the switch style and set [Value] to [Set OFF].  Value   Name:   SwitchStyle   Type:   String   Value:   Set OFF



#### **Source Code Tab**

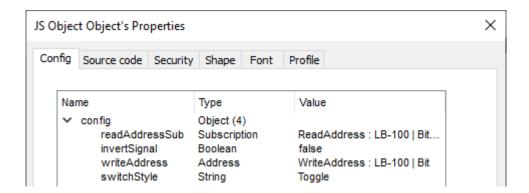
```
this.config.readAddressSub.onResponse((err, data) => {
       if (err) {
           console.log('[response] error =', err.message);
       } else if (this.config.invertSignal) {
           this.state = (data.values[0]) ? 0 : 1;
       } else {
          this.state = (data.values[0]) ? 1 : 0;
   });
   var mouseArea = new MouseArea();
   this.widget.add(mouseArea);
   mouseArea.on('mousedown', (mouseEvent) => {
       if (this.config.switchStyle === 'Set ON') {
           driver.setData(this.config.writeAddress, 1);
       } else if (this.config.switchStyle === 'Set OFF') {
           driver.setData(this.config.writeAddress, 0);
       }
   });
22
```

- Line 1~17: Please see Ch43.4.1.2 in this user manual.
- Line 18~19: When [Switch Style] is 'Set OFF', value 0 will be written into [Write address].

# 43.4.1.4. Toggle Switch Toggle Mode

Following the preceding sections, this section explains how to make a JS object work as a Toggle Switch in Toggle mode, which inverts the state of the designated address.

#### **Config Tab**



Setting	Description
readAddressSub	Read the state of the designated address.



43-15

invertSignal	Invert output signal.	
writeAddress	Set the address to write to. When the user presses this object, the	
	value will be written to this address according to the state of	
	'readAddressSub' and the value of 'switchStyle'.	
switchStyle	Set the switch style and set [Value] to [Toggle].	
	Value	
	Name : switchStyle	
	Type: String ▼	
	Value : Toggle	

# **Source Code Tab**

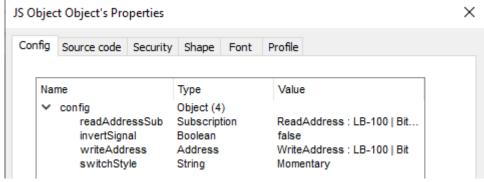
```
X
this.config.readAddressSub.onResponse((err, data) => {
   if (err) {
    console.log('[response] error =', err.message);
} else if (this.config.invertSignal) {
        this.state = (data.values[0]) ? 0 : 1;
    } else {
        this.state = (data.values[0]) ? 1 : 0;
});
var mouseArea = new MouseArea();
this.widget.add(mouseArea);
mouseArea.on('mousedown', (mouseEvent) => {
   if (this.config.switchStyle === 'Set ON') {
        driver.setData(this.config.writeAddress, 1);
    } else if (this.config.switchStyle === 'Set OFF') {
       driver.setData(this.config.writeAddress, 0);
    } else if (this.config.switchStyle === 'Toggle') {
        let currentValue = this.config.readAddressSub.latestData.values[0];
        let newValue = (currentValue) ? 0 : 1;
        driver.setData(this.config.writeAddress, newValue);
});
```

- Line 1~19: Please see Ch43.4.1.3 in this user manual.
- Line 20~23: When [Switch Style] is 'Toggle', [Write address] will be set to an inverted state.

# 43.4.1.5. Toggle Switch Momentary Mode

Following the preceding sections, this section explains how to make a JS object work as a Toggle Switch in Momentary mode.

# **Config Tab**



Setting	Description
readAddressSub	Read the state of the designated address.
invertSignal	Invert output signal.
writeAddress	Set the address to write to. When the user presses this object,
	value 1 will be written to this address and when the user releases
	this object, value 0 will be written to this address.
switchStyle	Set the switch mode and set [Value] to [Momentary].
	Value ×
	Name : switchStyle
	Type: String ▼
	Value : Momentary



#### **Source Code Tab**

```
this.config.readAddressSub.onResponse((err, data) => {
   if (err) {
        console.log('[response] error =', err.message);
   } else if (this.config.invertSignal) {
       this.state = (data.values[0]) ? 0 : 1;
    } else {
        this.state = (data.values[0]) ? 1 : 0;
});
var mouseArea = new MouseArea();
this.widget.add(mouseArea);
mouseArea.on('mousedown', (mouseEvent) => {
   if (this.config.switchStyle === 'Set ON') {
       driver.setData(this.config.writeAddress, 1);
   } else if (this.config.switchStyle === 'Set OFF') {
       driver.setData(this.config.writeAddress, 0);
   } else if (this.config.switchStyle === 'Toggle') {
       let currentValue = this.config.readAddressSub.latestData.values[0];
       let newValue = (currentValue) ? 0 : 1;
       driver.setData(this.config.writeAddress, newValue);
   } else if (this.config.switchStyle === 'Momentary') {
       driver.setData(this.config.writeAddress, 1);
});
mouseArea.on('mouseup', (mouseEvent) => {
   if (this.config.switchStyle === 'Momentary') {
        driver.setData(this.config.writeAddress, 0);
});
```

- Line 1~23: Please see Ch43.4.1.4 in this user manual.
- Line 24~25: When [Switch Style] is 'Momentary', value 1 will be written into [Write address].
- Line 29~33: When the user releases the object, value 0 will be written into [Write address].

# 43.4.2. Examples of JS Resource Usage

This section aims to familiarize users with the ways to import JS module in JS Resource using JS objects.

JS object supports the following ways to import modules:

- 1. ES6 dynamic import: Use import() function. Please note that ES6 static import is not supported by JS object.
- CommonJS: Use require() function.

# 43.4.2.1. ES6 Dynamic Import

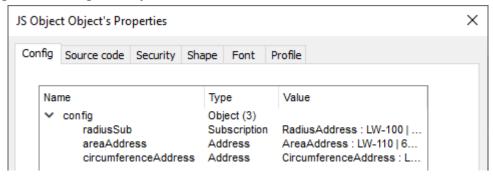
The following demonstration shows how to import JS modules using ES6 dynamic import. In the JS object, when radius changes, the area and circumference of the circle can be calculated using the *area* and *circumference* functions in JS module (*circle.js*), and the result is output to the designated addresses.



The program code of circle.js:

```
// circle.js
export function area(radius) {
  return Math.PI * radius * radius;
}
export function circumference(radius) {
  return 2 * Math.PI * radius;
}
```

1. Settings for creating a JS object are shown below:



Setting	Description
radiusSub	Obtains current radius value and monitors its changes. (Select
	LW-100, 64-bit Double)
areaAddress	The address for outputting the calculation result of the area of
	the circle. (Select LW-110, 64-bit Double)
circumferenceAddress	The address for outputting the calculation result of the
	circumference of the circle. (Select LW-120, 64-bit Double)

2. Edit the program code as shown below in [Source code] settings page:

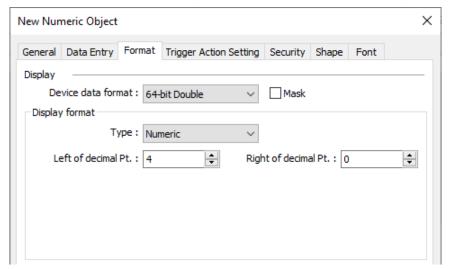


43-19

```
const circle = await import('/circle.js');

this.config.radiusSub.onResponse((err, data) => {
    if (err) {
        console.log('[response] error =', err.message);
    } else {
        let radius = data.values[0];
        let area = circle.area(radius);
        let circumference = circle.circumference(radius);
        driver.setData(this.config.areaAddress, area);
        driver.setData(this.config.circumferenceAddress, circumference);
}
}
});
```

- Line 1: Import the '/circle.js' file in JS Resource and bind the result to the circle.
- Line 3: Call *'this.config.radiusSub'* 'onResponse' function to register response callback for notification of changes in [circle radius].
- Line 8: Calculate area of the circle by calling the method in *circle.js* and store the result in *area* variable.
- Line 9: Calculate circumference of the circle by calling the method in *circle.js* and store the result in *circumference* variable.
- Line 10~11: Output the calculation result of the area and the circumference of the circle respectively to 'areaAddress' and 'circumferenceAddress'.
- 3. In the project, create three Numeric objects (64-bit Double) and set the address to LW-100 (Radius), LW-110 (Area), and LW-120 (Circumference).



4. When values are entered in LW-100 (Radius), the results are automatically updated at LW-110 (Area), and LW-120 (Circumference).



To import JS module's "default export", please refer to the code below.



43-20

```
var myModule = (await import('my-module.js')).default;
```

#### 43.4.2.2. CommonJS

The following demonstration shows how to import JS modules using require() function. This JS object behaves the same as using ES6 but in this section the external JS module is imported using CommonJS.

The program code of circle.js:

```
// circle.js
exports.area = function (radius) {
   return Math.PI * radius * radius;
};
exports.circumference = function (radius) {
   return 2 * Math.PI * radius;
}
```

- 1. Property settings are the same as explained in the preceding section.
- 2. Edit the program code as shown below in [Source code] settings page:

```
const circle = require('/circle.js');

this.config.radiusSub.onResponse((err, data) => {
    if (err) {
        console.log('[response] error =', err.message);
    } else {
        let radius = data.values[0];
        let area = circle.area(radius);
        let circumference = circle.circumference(radius);
        driver.setData(this.config.areaAddress, area);
        driver.setData(this.config.circumferenceAddress, circumference);
}
};
};
```

- Line 1: Import the '/circle.js' file in JS Resource and bind the result to the *circle*.
- Line 3~13: See Ch43.4.2.1 in this user manual.
- 3. In the project, create three Numeric objects (64-bit Double) and set the address to LW-100 (Radius), LW-110 (Area), and LW-120 (Circumference).
- 4. When values are entered in LW-100 (Radius), the results are automatically updated at LW-110 (Area), and LW-120 (Circumference).



JS Object and JS Library 43-21

### 43.5. Limitations

- 1. Size limit of a JS object's source code: 100 KB.
- 2. Size limit of a JS Resource file: 10MB
- 3. Size limit of the memory usage of a JS context(\*): 20 MB.

(\*) A JS context is a sandboxed execution context with its own set of built-in objects and functions. And, all the JS objects in the same window share one JS context, that is, share the same memory heap and global object.

### 43.6. How a JS object operates behind the scenes

- a. Create JS context.
- b. Create JS object.
- **c.** Initialize JS object 'config' (⇒ this.config).
- d. Initialize JS object 'widget' (⇒ this.widget).
- e. Wait for the reply from all Subscriptions.
- f. Wrap JS object source code into an async. function and call it.



## Appendix A.

## **Comparison of HMI Software Features**

- eMT Series: eMT3070B, eMT3105P, eMT3120A, eMT3150A
- cMT Series: cMT-SVR-100, cMT-SVR-102, cMT-SVR-200, cMT-SVR-202, cMT-iV5, cMT3151, cMT3090, cMT3071, cMT3072, cMT3103, cMT-HDM, cMT-FHD
- CMT X Series: cMT3072X, cMT3072X2, cMT3072XH, cMT3072XH2, cMT3072XHT, cMT3092X, cMT3092X (V2), cMT3102X, cMT3102X (V2), cMT3108XH, cMT3108XP, cMT3152X, cMT3161X, cMT3162X, cMT3162X (V2), cMT2078X, cMT2108X, cMT2108X2, cMT2108X2 (V2), cMT2128X, cMT2158X, cMT2158X (V2), cMT2166X, cMT1106X, cMT-FHDX-220, cMT-FHDX-820, cMT-SVRX-820, cMT-SVRX-822
- cMT Series-Gateway: cMT-G01, cMT-G02, cMT-G03, cMT-G04, cMT-CTRL01
- mTV Series: mTV-100
- iE Series: MT8050iE, MT8051iE, MT8053iE, MT6070iE, MT6071iE, MT8070iE, MT8071iE, MT8073iE, MT8100iE, MT8101iE, MT8102iE, MT8103iE
- iER Series: MT8070iER1
- XE Series: MT8090XE, MT8091XE, MT8092XE, MT8121XE, MT8150XE
- iP Series: MT6051iP, MT8051iP, MT6071iP, MT8071iP, MT8071iP2, MT6103iP, MT8102iP

Please note that the table below is for reference only and may not include all features. Some features are version-dependent, so please confirm again by cross-checking with the software or consulting Weintek service when in doubt.

### iP/iE/eMT/mTV/XE Series

Category	Model	iP	iE	eMT	mTV	XE	Note
Category	Function	ır	IL.	CIVII	1111 V	ΛL	Note
Facultuildan	Project size limit	22.5MB	22.5MB	64MB	64MB	64MB	
EasyBuilder	USB Disk Download	Υ	Υ	Υ	Υ	Υ	
	64-bit Data Type	N/A	N/A	N/A	N/A	N/A	
	3G/4G Dongle	Υ	N/A	N/A	N/A	N/A	1
	Control Token	N/A	N/A	N/A	N/A	N/A	
	Dual USB	Υ	Υ	N/A	N/A	N/A	
	e-Mail	N/A	Υ	Υ	Υ	Υ	
	Enhanced Security Mode	Υ	Υ	Υ	Υ	Υ	
	Ethernet Printer	N/A	N/A	N/A	N/A	N/A	
	LDAP	N/A	N/A	N/A	N/A	N/A	
	String Table	N/A	Υ	Υ	Υ	Υ	
Function	Time Synchronization (NTP)	N/A	Υ	Υ	Υ	Υ	
	USB Tethering	N/A	Υ	Υ	Υ	Υ	a, 2
	User-defined Startup Screen	Υ	Υ	Υ	Υ	Υ	
	VNC Server	Υ	Υ	Υ	Υ	Υ	3
	Web Streaming	N/A	N/A	Υ	Υ	Υ	4
	Web Interface	N/A	N/A	N/A	N/A	N/A	
	EasyWeb 2.0	N/A	N/A	N/A	N/A	N/A	
	WebView	N/A	N/A	N/A	N/A	N/A	
	MPI	Υ	Υ	Υ	Υ	Υ	



Category	Model	iP	iE	eMT	mTV	XE	Note
category	Function	"	"-			, AL	Note
	Audio (Speaker)	N/A	N/A	eMT3120 eMT3150	N/A	N/A	10
	Audio (Other)	N/A	N/A	N/A	HDMI	USB	
Hardware	CAN Bus	N/A	N/A	Υ	N/A	8091XE 8092XE	
	WiFi	N/A	8103iE	N/A	N/A	N/A	
	Vibration Feedback	N/A	N/A	N/A	N/A	N/A	
	Action Trigger	N/A	N/A	N/A	N/A	N/A	
	BACnet Schedule	N/A	N/A	N/A	N/A	N/A	
	Barcode Scanner (Android	NI/A	NI/A	NI/A	NI/A	NI/A	5
	Camera)	N/A	N/A	N/A	N/A	N/A	3
	Combo Button	Υ	Υ	Υ	Υ	Υ	
	Condition	N/A	N/A	N/A	N/A	N/A	
	Date/Time	Υ	Υ	Υ	Υ	Υ	
	Dynamic Drawing	Υ	Y	Υ	Υ	Υ	
	Dynamic Scale	Υ	Y	Υ	Υ	Υ	
	File Browser	Υ	Υ	Υ	Υ	Υ	
	Flow Block	Υ	Υ	Υ	Υ	Υ	
	JS Object	N/A	N/A	N/A	N/A	N/A	
Object	Media Player	N/A	N/A	eMT3105 eMT3121 eMT3150	N/A	Y	6
	PDF Reader	N/A	N/A	N/A	N/A	N/A	
	Picture View	Υ	Υ	Υ	Υ	Υ	
	Pie Chart	Υ	Υ	Υ	Υ	Υ	
	PLC Web Browser	N/A	N/A	N/A	N/A	N/A	11
	Table	Υ	Υ	Υ	Υ	Υ	
	Template Window	Υ	Υ	Υ	Υ	Υ	
	Touch Gesture	N/A	N/A	N/A	N/A	N/A	
	Video In - IP Camera	N/A	N/A	Υ	N/A	Υ	7
	Video In - USB Camera	N/A	N/A	Υ	Υ	Υ	12
	Video In - Video Input	N/A	N/A	eMT3121 eMT3150	N/A	N/A	
	VNC Viewer	N/A	Υ	Υ	Υ	Υ	8
	Demand Display	N/A	N/A	N/A	N/A	N/A	
	Demand Setting	N/A	N/A	N/A	N/A	N/A	
	MQTT	N/A	Υ	Υ	Υ	Υ	
	MQTT – Advanced JSON	N/A	N/A	N/A	N/A	N/A	
IIoT/Energy	MQTT - AWS IoT, Sparkplug B, Azure IoT Hub, Google Cloud IoT Core	N/A	N/A	N/A	N/A	N/A	
	OPC UA Client	Υ	Υ	Υ	Υ	Υ	
	OPC UA Server	N/A	N/A	N/A	N/A	N/A	
	Circular Trend Display	Υ	Υ	Υ	Υ	Υ	
	Database Server	N/A	N/A	N/A	N/A	N/A	b
Data /III-t-	Event Bar Chart	N/A	N/A	N/A	N/A	N/A	
Data/History	FTP Server	N/A	N/A	N/A	N/A	N/A	b
	Operation Log Settings	Υ	Y	Υ	Υ	Υ	
	SQL Query	N/A	N/A	N/A	N/A	N/A	



Category	Model	iP	iE	еМТ	mTV	XE	Note
	Recipe Database	Υ	Υ	Υ	Υ	Υ	
	Recipe Import / Export	Υ	Υ	Υ	Υ	Υ	
	Recipe View	Υ	Υ	Υ	Υ	Υ	
Other	CODESYS	N/A	N/A	N/A	N/A	N/A	
	cMT Viewer App	N/A	N/A	N/A	N/A	N/A	
	cMT Diagnoser	N/A	N/A	N/A	N/A	N/A	
	EasyAccess 1.0	Υ	Υ	Υ	Υ	Υ	
11122	EasyDiagnoser	Υ	Υ	Υ	Υ	Υ	
Utility	EasyPrinter	Υ	Υ	Υ	Υ	Υ	
	EasySimulator	Υ	Υ	Υ	Υ	Υ	
	EasySystemSetting	Υ	Υ	Υ	Υ	Υ	9
	EasyWatch	Υ	Υ	Υ	Υ	Υ	
	Dashboard	N/A	N/A	N/A	N/A	N/A	
	EasyAccess 2.0	Υ	Y	Υ	Y	Υ	
Weincloud	EasyAccess 2.0 Built-in License	N/A	8053iE 8073iE 8103iE	N/A	N/A	8092XE	

### **cMT Series**

	Series			cN	ЛΤ			cMT Gateway	
Category	Model Function	cMT-SVR	cMT3071 cMT3072	cMT3090	cMT3103	cMT3151	cMT-HDM cMT-FHD	cMT-G01 cMT-G02 cMT-G03 cMT-G04 cMT-CTRL01	Note
EasyBuilder	Project size limit	32MB	64MB	64MB	64MB	64MB	64MB	32MB	
Easybulluer	USB Disk Download	N/A	Υ	Υ	Υ	Υ	Υ	N/A	
	64-bit Data Type	Υ	Υ	Υ	Y	Υ	Y	Y	
	3G/4G Dongle	Υ	Υ	Υ	Y	Y	Y	N/A	1
	Control Token	Υ	Υ	Υ	Υ	Υ	Υ	N/A	
	Dual USB	N/A	N/A	N/A	N/A	N/A	N/A	N/A	
	e-Mail	Υ	Υ	Υ	Υ	Υ	Υ	Υ	
	Enhanced Security Mode	Υ	Υ	Υ	Υ	Υ	Υ	Υ	
	Ethernet Printer	N/A	Υ	Υ	Υ	Υ	Υ	N/A	
	LDAP	Υ	Υ	Υ	Υ	Υ	Υ	Υ	
Function	String Table	Υ	Υ	Υ	Υ	Υ	Υ	N/A	
Function	Time Synchronization (NTP)	Υ	Υ	Υ	Υ	Υ	Υ	Υ	
	USB Tethering	Υ	Υ	Υ	Υ	Υ	Υ	N/A	a, 2
	User-defined Startup Screen	N/A	Υ	Υ	Υ	Υ	Υ	N/A	
	VNC Server	N/A	Υ	Υ	Υ	Υ	Υ	N/A	3
	Web Streaming	Υ	Υ	Υ	Υ	Υ	Υ	N/A	4
	Web Interface	Υ	Υ	Υ	Υ	Υ	Υ	Υ	
	EasyWeb 2.0	Υ	N/A	N/A	N/A	N/A	N/A	N/A	
	WebView	N/A	N/A	N/A	N/A	N/A	N/A	N/A	
	MPI	Υ	Υ	Υ	Υ	Υ	Υ	Υ	
Hardwara	Audio (Speaker)	N/A	N/A	Υ	N/A	Υ	N/A	N/A	10
Hardware	Audio (Other)	N/A	N/A	N/A	N/A	N/A	HDMI	N/A	



	Series			cN	ИT			cMT Gateway	
				·				cMT-G01	
_	Model		cMT3071				cMT-HDM	cMT-G02	Note
Category	Function	cMT-SVR	cMT3072	cMT3090	cMT3103	cMT3151	cMT-FHD	cMT-G03	
								cMT-G04 cMT-CTRL01	
	CAN Bus	N/A	Υ	Y	Υ	Υ	N/A	N/A	
	WiFi	cMT-SVR-	NI/A	NI/A	Υ	NI/A	NI/A	cMT-G02	
	WIFI	200/202	N/A	N/A	Ť	N/A	N/A	CIVIT-GUZ	
	Vibration Feedback	N/A	N/A	N/A	N/A	N/A	N/A	N/A	
	Action Trigger	Υ	Y	Y	Υ	Υ	Υ	N/A	
	BACnet Schedule	Y	Y	Υ	Υ	Υ	Y	N/A	
	Barcode Scanner (Android	Y	Υ	Υ	Υ	Υ	Υ	N/A	5
	Camera) Combo Button	Υ	Υ	Y	Υ	Υ	Y	N/A	
	Condition	Y	Y	Y	Y	Y	Y	Y	
	Date/Time	Y	Y	Y	Y	Y	Y	N/A	
	Dynamic Drawing	Y	Y	Y	Y	Y	Y	N/A	
	Dynamic Scale	Y	Y	Y	Y	Y	Y	N/A	
	File Browser	N/A	Y	Y	Y	Y	Y	N/A	
	Flow Block	N/A Y	Y	Y	Y	Y	Y		
								N/A	
Object	JS Object	N/A	N/A	N/A	N/A	N/A	N/A	N/A	-
,	Media Player	N/A	Y	Y	Y	Y	Y	N/A	6
	PDF Reader	N/A	Y	Y	Y	Y	Y	N/A	
	Picture View	N/A	Y	Y	Y	Y	Y	N/A	
	Pie Chart	Υ	Υ	Υ	Υ	Υ	Υ	N/A	- 11
	PLC Web Browser	N/A	N/A	N/A	N/A	N/A	N/A	N/A	11
	Table	Y	Y	Y	Y	Y	Y	N/A	
	Template Window	Υ		Υ	Υ	Υ		Υ	
	Touch Gesture	N/A	N/A	N/A	N/A	N/A	N/A	N/A	
	Video In - IP Camera	N/A	Y	Y	Y	Y	Y	N/A	7
	Video In - USB Camera	N/A	Y	Υ	Υ	Y	Y	N/A	12
	Video In - Video Input	N/A	N/A	N/A	N/A		N/A	N/A	•
	VNC Viewer	N/A	Y	Y	Y	Y	Y	N/A	8
	Demand Display	Y	Y	Y	Y	Y	Y	N/A	
	Demand Setting	Y	Y	Y	Y	Y	Y	N/A	
	MQTT	Y	Y	Y	Y	Y	Y	Y	
IIoT/Energy	MQTT – Advanced JSON	Y	Y	Y	Y	Y	Y	Y	
no 17 Energy	MQTT - AWS IoT, Sparkplug B, Azure IoT Hub, Google Cloud	Y	Υ	Y	Y	Υ	Y	Υ	
	loT Core		'	'	'	'	'		
	OPC UA Client	Υ	Y	Y	Υ	Υ	Y	Υ	
	OPC UA Server	License	Υ	Υ	Υ	Υ	License	Υ	
	Circular Trend Display	Υ	Y	Y	Y	Y	Y	N/A	
	Database Server	Υ	Y	Y	Y	Y	Y	Υ	b
	Event Bar Chart	Υ	Y	Y	Y	Y	Y	N/A	
Data/History	FTP Server	Υ	Υ	Υ	Υ	Υ	Υ	N/A	b
,	Operation Log Settings	Y	Y	Y	Y	Y	Y	N/A	
	SQL Query	Υ	Υ	Υ	Υ	Υ	Υ	Y	
	Recipe Database	Y	Y	Y	Y	Y	Y	N/A	
	necipe batabase	<u>'</u>	<u>'</u>	'	!		'	IV/	



	Series			cN	ЛΤ			cMT Gateway	
Category	Model	cMT-SVR	cMT3071 cMT3072	cMT3090	cMT3103	cMT3151	cMT-HDM cMT-FHD	cMT-G01 cMT-G02 cMT-G03 cMT-G04 cMT-CTRL01	Note
	Recipe Import / Export	Υ	Υ	Υ	Υ	Υ	Υ	N/A	
	Recipe View	Υ	Υ	Υ	Υ	Υ	Υ	N/A	
Other	CODESYS	N/A	License	License	N/A	License	N/A	cMT-CTRL01	
	cMT Viewer App	Υ	Υ	Υ	Υ	Υ	Υ	N/A	
	cMT Diagnoser	Υ	Υ	Υ	Υ	Υ	Υ	Υ	
	EasyAccess 1.0	N/A	N/A	N/A	N/A	N/A	N/A	N/A	
	EasyDiagnoser	N/A	N/A	N/A	N/A	N/A	N/A	N/A	
Utility	EasyPrinter	N/A	N/A	N/A	N/A	N/A	N/A	N/A	
	EasySimulator	N/A	N/A	N/A	N/A	N/A	N/A	N/A	
	EasySystemSetting	N/A	Υ	Υ	Υ	Υ	Υ	N/A	9
	EasyWatch	Υ	Υ	Υ	Υ	Υ	Y	Υ	
	Dashboard	N/A	N/A	N/A	N/A	N/A	N/A	N/A	
	EasyAccess 2.0	Υ	Υ	Υ	Υ	Υ	Υ	Υ	
Weincloud	EasyAccess 2.0 Built-in License	cMT-SVR- 102/202	cMT3071: N/A cMT3072: Y	Y	Y	Y	N/A	N/A	

### **cMT X Series**

VII A SCIN									
Category	Model		cMT3072X cMT3072X2 cMT3072XH cMT3072XH2 cMT3072XHT	cMT2166X cMT3161X	cMT2078X cMT2108X cMT2108X2 cMT2108X2 (V2) cMT2128X cMT2158X cMT2158X (V2)	cMT1106X		cMT-SVRX-820 cMT-SVRX-822	Note
Francisco (Indian	Project size limit	64MB	64MB	64MB	64MB	64MB	64MB	64MB	
EasyBuilder	USB Disk Download	Υ	Υ	Υ	Υ	Υ	Υ	Υ	
	64-bit Data Type	Υ	Υ	Υ	Υ	Υ	Υ	Υ	
	3G/4G Dongle	Υ	Υ	Υ	Υ	Υ	Y	Υ	1
	Control Token	Υ	Υ	Υ	Υ	N/A	Y	Y	
	Dual USB	Υ	Υ	Υ	Υ	Υ	Υ	Υ	
	e-Mail	Υ	Υ	Υ	Υ	Υ	Y	Y	
	Enhanced Security Mode	Υ	Υ	Υ	Υ	Υ	Υ	Υ	
	Ethernet Printer	Υ	Υ	Υ	Υ	Υ	Υ	N/A	
Function	LDAP	Υ	Υ	Υ	Υ	N/A	Υ	Υ	
	String Table	Υ	Υ	Υ	Υ	Υ	Υ	Υ	
	Time Synchronization (NTP)	Υ	Υ	Υ	Υ	Υ	Υ	Υ	
	USB Tethering	Υ	Υ	Υ	Υ	Υ	Υ	Υ	a, 2
	User-defined Startup Screen	Υ	Υ	Υ	Υ	Υ	Y	N/A	
	VNC Server	Υ	Υ	Υ	Y	Υ	Y	N/A	3
	Web Streaming	Υ	Υ	Υ	Υ	N/A	Y	Υ	4
	Web Interface	Υ	Υ	Υ	Υ	Υ	Υ	Υ	



Category	Model	cMT3092X cMT3092X (V2) cMT3102X cMT3102X (V2) cMT3108XH cMT3108XP cMT3152X cMT3162X	cMT3072X cMT3072X2 cMT3072XH cMT3072XH2 cMT3072XHT	cMT2166X cMT3161X	cMT2078X cMT2108X cMT2108X2 cMT2108X2 (V2) cMT2128X cMT2158X cMT2158X (V2)	cMT1106X		cMT-SVRX-820 cMT-SVRX-822	Note
	EasyWeb 2.0	Υ	Υ	Υ	Υ	Υ	Υ	Υ	
	WebView	Υ	Υ	Υ	Υ	N/A	Υ	Υ	
	МРІ	Y	Y	cMT2166X	cMT2078X cMT2108X2(V2) cMT2128X cMT2158X(V2)	Y	Y	Y	
	Audio (Speaker)	cMT3092X cMT3108XH cMT3108XP cMT3152X cMT3162X	N/A	Y	cMT2158X	N/A	N/A	N/A	10
Hand	Audio (Other)	N/A	N/A	N/A	N/A	N/A	HDMI	N/A	
Hardware	CAN Bus	Υ	Y	N/A	N/A	N/A	N/A	N/A	
	WiFi	cMT3102X, cMT3108XH, cMT3108XP (M02 module)	N/A	N/A	cMT2108X2, cMT2108X2 (V2) (M02 module)	(M02 module)	N/A	N/A	
	Vibration Feedback	cMT3162X	N/A	N/A	N/A	N/A	N/A	N/A	
	Action Trigger	Υ	Υ	Υ	Υ	N/A	Υ	Υ	
	BACnet Schedule	Υ	Υ	Υ	Υ	Υ	Υ	Υ	
	Barcode Scanner (Android Camera)	Y	Y	N/A	N/A	N/A	Y	Y	5
	Combo Button	Υ	Υ	Υ	Υ	Υ	Υ	Υ	
	Condition	Υ	Υ	Υ	Υ	N/A	Υ	Υ	
	Date/Time	Υ	Υ	Υ	Υ	Υ	Υ	Υ	
	Dynamic Drawing	Υ	Υ	Υ	Υ	Υ	Υ	Υ	
	Dynamic Scale	Υ	Υ	Y	Υ	Υ	Υ	Υ	
	File Browser	Υ	Y	Y	Υ	Υ	Υ	N/A	
	Flow Block	Υ	Υ	Υ	Υ	Υ	Υ	Υ	
	JS Object	Υ	Υ	Y	Υ	N/A	Υ	Υ	
Object	Media Player	Υ	Υ	Υ	Υ	N/A	Υ	N/A	6
	PDF Reader	Υ	Υ	Υ	Υ	Υ	Υ	N/A	
	Picture View	Υ	Y	Y	Υ	Υ	Υ	N/A	
	Pie Chart	Υ	Y	Y	Y	Y	Y	Y	
	PLC Web Browser	Υ	Y	N/A	N/A	N/A	cMT-FHDX-820	N/A	11
	Table	Υ	Y	Y	Y	Y	Y	Y	
	Template Window	Υ	Υ	Υ	Υ	Υ	Υ	Υ	
	Touch Gesture	cMT3152X cMT3162X	N/A	Y	N/A	N/A	N/A	N/A	
	Video In - IP Camera	Υ	Υ	Υ	Υ	N/A	Υ	N/A	7
	Video In - USB Camera	Υ	Y	Y	Y	N/A	Y	N/A	12
	Video In - Video Input	N/A	N/A	N/A	N/A	N/A	N/A	N/A	
	VNC Viewer	Υ	Υ	Υ	Υ	Υ	Υ	N/A	8



	_		1				1	1	
Category	Model Function	cMT3092X cMT3092X (V2) cMT3102X cMT3102X (V2) cMT3108XH cMT3108XP cMT3152X cMT3152X	cMT3072X	cMT2166X cMT3161X	cMT2078X cMT2108X2 cMT2108X2 (V2) cMT2128X cMT2158X cMT2158X (V2)	cMT1106X	cMT-FHDX-220 cMT-FHDX-820		Note
	Demand Display	Y	Υ	N/A	N/A	N/A	Υ	Υ	
	Demand Setting	Y	Υ	N/A	N/A	N/A	Υ	Υ	
	MQTT	Υ	Υ	Υ	Υ	Υ	Υ	Υ	
	MQTT – Advanced JSON	Υ	Υ	Υ	Υ	Υ	Υ	Υ	
IIoT/Energy	MQTT - AWS IoT, Sparkplug B, Azure IoT Hub, Google Cloud IoT Core	Y	Y	Υ	Υ	N/A	Υ	Υ	
	OPC UA Client	Υ	Υ	Υ	Υ	Υ	Υ	Υ	
	OPC UA Server	Υ	Υ	N/A	N/A	N/A	License	Υ	
	Circular Trend Display	Υ	Υ	Υ	Υ	Υ	Υ	Υ	
	Database Server	Y	Υ	N/A	N/A	N/A	Y	Υ	b
	Event Bar Chart	Υ	Υ	N/A	N/A	N/A	Υ	Υ	
	FTP Server	Υ	Υ	Y	Υ	Υ	Y	Υ	b
Data/History	Operation Log Settings	Υ	Υ	Υ	Υ	Υ	Y	Υ	
	SQL Query	Υ	Υ	N/A	N/A	N/A	Y	Υ	
	Recipe Database	Y	Υ	Υ	Υ	Υ	Υ	Υ	
	Recipe Import / Export	Υ	Υ	Υ	Υ	Υ	Υ	Υ	
	Recipe View	Υ	Υ	Υ	Υ	Υ	Υ	Υ	
Other	CODESYS	License	License	N/A	License	N/A	License	License	
	cMT Viewer App	Υ	Υ	Υ	Υ	N/A	Υ	Υ	
	cMT Diagnoser	Υ	Υ	Υ	Υ	Υ	Υ	Υ	
	EasyAccess 1.0	N/A	N/A	N/A	N/A	N/A	N/A	N/A	
Utility	EasyDiagnoser	N/A	N/A	N/A	N/A	N/A	N/A	N/A	
Othlity	EasyPrinter	N/A	N/A	N/A	N/A	N/A	N/A	N/A	
ŀ	EasySimulator	N/A	N/A	N/A	N/A	N/A	N/A	N/A	
	EasySystemSetting	Υ	Υ	Υ	Υ	Υ	Y	Υ	9
	EasyWatch	Y	Υ	Υ	Υ	Υ	Υ	Υ	
	Dashboard	Y	Υ	Υ	Υ	Υ	Y	Y	
Weincloud	EasyAccess 2.0	Y	Υ	Υ	Υ	Υ	Y	Υ	
	EasyAccess 2.0 Built-in License	cMT3092X cMT3152X	N/A	N/A	N/A	N/A	N/A	cMT-SVR-822	

### **Notes**

- **a.** USB Tethering is not supported on MT6071iE. Connection to external server.

### **OS Support**

No	Function	OS Version
1	3G/4G Dongle	iP: 20201007
		cMT-SVR: 20151127
		cMT3071/3072/3090/3103/3151: 20180723
		cMT-HDM/FHD: 20190130 or later



2	USB Tethering	iE Type A: 20160707
	S	iE Type B: 20160325
		eMT: 20160601
		mTV: 20160527
		XE: 20160503
		cMT-SVR: 20160518
		cMT3090/3103/3151/HDM: 20160412 or later
3	VNC Server	cMT3090/3151: 20160412 or later
4	Web Streaming	cMT-SVR: 20151127, cMT3151:20171129 or later
5	Barcode Scanner Android	Android cMTViewer V1.7.0 or later
6	Media Player	cMT-HDM: no 1920*1080 resolution
	eaia : iaye.	cMT3072X(H): 20200929
7	Video-in IP Camera	eMT: 20160601
•		XE: 20160503
		cMT3072X(H): 20200929
8	VNC Viewer	iE Type A: 20160707
		iE Type B: 20160325
		eMT: 20160601
		mTV: 20160527
		XE: 20160503
		all cMT series: 20181211 or later
9	EasySystemSetting	all cMT series: 20180723 or later
10	Audio Output	USB Audio Output OS Support: XE 20190325
11	PLC Web Browser	cMT3072X(H):20200723, cMT3092X/3152X/3162X: 20201202
12	Video In – USB Camera	cMT3072X(H): 20200929



cMT-Viewer Limitations B-1

# **Appendix B.cMT Viewer Limitations**

A cMT / cMT X series HMI screen can be accessed locally, by physically on the HMI screen itself, or remotely, from another device running cMT Viewer or VNC viewer. However, please note that some features do not work when connecting remotely from a cMT Viewer client (iOS, Android, PC, cMT-iV5/iV6), even if they work on the local cMT / cMT X machine. Please take this into consideration when designing projects.

Features that do not work remotely on cMT Viewer:

- Enhanced Security Mode Plugin
- File Browser
- Media Player
- Touch Gesture
- Video In: USB Camera
- Video In: IP Camera \*Note 1Video In: Video Input (analog)
- Picture View
- PDF Reader
- VNC Viewer
- Selected features of Function Key: Screen hardcopy, Import user data/User [USB Security Key]
- Custom keypad: Custom keypad is not supported on an iOS device, the system keypad pops up instead.
- Selected features of PLC Control
  - i. Screen hardcopy: File are saved in the external drive on HMI
  - ii. Backlight: Backlight control of HMI screen
- Selected features of Operation Log
  - i. Operation Log printing: Logs are saved in the external drive on HMI



1. Viewing IP camera on cMT Viewer may be possible on a Windows PC, provided that appropriate third-party codecs are used. As compatibility may vary, testing with an actual device is recommended.



## **Appendix C. PC Simulation Limitations**

Running on-line or off-line simulation when designing an EasyBuilder Pro project can help users find out if the project will work as planned. However, some features only works on HMI, in which case the project should be downloaded to HMI in order to see the effects. Please take this into consideration when designing projects.

When running simulation on PC, the historical data is stored in their respective destination folder that is placed under EasyBuilder Pro installation directory:

- HMI memory: when the designated destination is HMI memory.
- SD card: when the designated destination is SD card.
- usb1: when the designated destination is USB Disk.
- usb2: when the designated destination is USB Disk2. (Applicable only for models that support two USB disks.)

Features that do not work when running on-line/off-line simulation on PC:

#### cMT/cMT X Series

- Enhanced Security Mode Plugin
- Media Player
- Video In: USB Camera
- Video In: IP Camera
- Video In: Video Input (analog)
- PDF Reader
- VNC Viewer
- PLC Web Browser

#### eMT/iE/XE/mTV Series

- Video In: USB CameraVideo In: IP Camera
- Video In: Video Input (analog)
- VNC Viewer



## Appendix D. Notes on the Use of 64-bit

## **Data Type**

cMT / cMT X Series models offer 64-bit data type support. The following explains limitations on the use of 64-bit data type.

Input ranges (Numeric object, Set Word object...etc)

i. unit64: 0 ~ 2^48
ii. int64: -2^48 ~ 2^48
iii. double: -2^48 ~ 2^48

#### • int64 / unit64

Double is the internal data type used in computation, while it stores a mantissa with 52-bit precision. As a result, 15-digits integers and a portion of 16-digits integers may be stored exactly, but storing numbers exceeding that may result in lost precision.

In EasyBuilder Pro, inputs exceeding 48-bit may result in error; therefore, the input limit is

#### double

defined as 48-bit.

In EasyBuilder Pro, the upper/lower input limit was formerly determined by the max/min of double (+/-  $1.79 * 10^308$ ), which is nearly limitless in practicality. For consistency, the upper/lower input limit is also defined as -2^48 ~ 2^48.

#### Example:

The value 144,115,188,075,855,872 (a 64-bit unsigned int. value) read from PLC may be displayed as 144,115,188,075,855,870 by Numeric as precision is lost.

#### Other circumstances:

As in the example above, the same problem may occur when using Recipe Import / SQL Query / Database (Data Sampling), where data is from an external source.

Please note that for double, as a floating-point number, precision issue is inherent. It should not be assumed that all numbers in the range  $+2^48 \sim -2^48$  is guaranteed to display exactly. Explanations above should apply to the use of int64 / uint64 only.

